

# EII MOBILE-To Be Built By Humans Run By Computer 

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MPA 200 is a low price, high power 100W amplifier. Its smart styling, professional appearance and performance, make it one of our most popular designs. With adaptable inputs the mixer accepts a variety of sources yet straightforward construction makes it ideal for the first-time builder

CHROMATHEQUE 5000 - a 5-channel lighting system powerful enough for professional discos yet controllable for home-effects. Sound to light, strobe to music level, random or sequential effects - each channel can handle up to 500 W yet minimal wiring is needed with our unique single-board design.

ETI VOCODER - 14 channels, each with independent level control, for maximum versatility and intelligibility; Two input amplifiers - for speech/excitation - each with level control and tone control. The Vocoder is a powerful yet flexible machine that is interesting to build and thanks to our easy to follow construction manual, is within the capability of most enthusiasts.

SP2 200 twice the power with two of the reliable, durable and economic amps from the MPA200; fed by separate power supplies from a common toroidal transformer. Superb finish and quality components throughout - up to leven over!) the standard of high priced factory-built units.

DJ90 Stereo Mixer - this is a really versatile new mixer that enables the constructor $D J$ to produce a professional performance every time. There are two stereo inputs for magnetic cartridges, a stereo auxiliary input and mike input. Other 'plus' features are auto-panning for fast or slow, slider controls, multi-mixing, ducking, interrupt, input modulation, in short everything. . the whole works - AND under $£ 100$ complete! (We have illustrated the DJ90 teamed in our own console with the Chromatheque and an SP2 200 and speakers.

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- Ordering - Full ordering details, delivery service, and sales counter opening - inside back of this issue.
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TECH TIPS .34 Three pages of circuit designs submitted by our inventive readership.

## CONFIGURATIONS

 45lan Sinclair has done us proud on this one. This new series examines some of the basic transistor building blocks and gives all the design data you need to use them yourself. One to cut out and keep.

## READ/WRITE

This month's page of readers' correspondence deals with such diverse topics as lucid dreams, car control and crossword puzzles.

## DESIGNER'S NOTEBOOK

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The device under scrutiny this month is the versatile DPM200, an excellent little DVM module.

## DATA SHEET

You wanted it back and here it is! Our monthly glimpse at the manufacturers' info begins with a fast buffer amplifier.

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How would you like a clock/calendar you never have to put right? Here it is, with a whole lot more to offer besides. SOUND TRACK72

We were bored with the usual sort of hand-held DIY electronic game, so we came up with this audio version of the shoot-'em-down type.
MOBILE 2
We've enough modules designed now to
make something of them - and it's time you got involved, too.
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# NEWS:NEWS:NEWS:NEWS:NEWS:NEWS:NEWS 

# DIG <br> Beeb's Loss of Memory <br> Tf you're stuck in the waiting list 

 Lfor a BBC Microcomputer, we've done some simple arithmetic that may persuade you to cancel your order and choose an alternative. One of the major selling points of the Beeb machine has always been the high resolution graphics, but it isn't until you let high-res loose on your memory that you find out the snag. For example, the Model A is adver tised as being a 16 K machine. In fact it's only 16 K if it's turned off As soon as you switch on, the operating system automatically reserves 3328 bytes as its workspace, and a further 1 K goes to the memory-mapped screen if you're in mode 7 ( $40 \times 25$ teletext).

## Plug-in Power

$T$ These smart cases have been added to the West Hyde range and are designed to house power supplies for low-voltage equipment such as calculators, radios and TV games. Two sizes are available, both able to accommodate PSU components including the transformer, and the case may be plugged directly into a 13 A socket. You can have any colour so long as it's black or white, and the case is moulded in impact-resistant ABS. More details from West Hyde Developments Ltd, Unit 9, Park Street Industrial Estate, Aylesbury, Bucks, HP20 IET.

## Flock Of Eagles

Gagle International, the indusEtrial electronics company, have introduced three new professional public address mixer/ amplifiers. These are the TPM 40, TPM 80 and TPM 120 models which offer - surprise, surprise 40,80 and 120 W RMS output power. All three are suitable for both four-eight ohm or 100 V line speaker systems. General spec is $30 \mathrm{~Hz}-15 \mathrm{kHz}$ frequency response, priority paging over background music, master volume controls
etc, and two year guarantee Individually, the IPM 40 has battery backup for mains failure, three mike and two auxiliary inputs, plus a tone control; the TPM 80 is mains-only with a tone control, four mike, one record deck and two auxiliary inputs; and the TPM 120 has the same inputs as the 80 but with independent bass and treble controls and more versatile input controls. Further information from Eagle International Precision Centre, Heather Park Drive, Wembley, Middlesex HA0 1 SU .


## SDP Shrinks Drastically

Hot on the heels of the BICCVero Speedwire prototyping system, reviewed exclusively in the June E'TI, comes the SDP-500 range of digital panel meters. The SDP range (do we detect political overtones?) is into miniaturisation in a big way, if that's not a contradiction - they measure only $48 \times 24 \times 48 \mathrm{~mm}$. Packed into this tiny case we have the latest

LSI dual-integration A-to-D technology for high stability and excellent noise rejection (40dB at 50 Hz ), bright 9.2 mm LED display with anti-glare filter, externally programmable decimal points and external hold. The eight models cover DC voltage or current measurement from $\pm 199.9 \mathrm{mV}$ to $\pm 199.9 \mathrm{~V}$ and $\pm$ 199.9 uA to $\pm 199.9 \mathrm{~mA}$. The supply is 5 V at 100 mA maximum. For a comprehensive application guide contact Verospeed, Stansted Road, Boyatt Wood, Eastieigh, Hants SO5 4ZY.

## Cut With Comfort

Now hands that do cutting can N feel soft as your face...with these self-opening, cushion-grip hand tools. The three tools each weigh about 80 grams and comprise an angle side cutter, short fine nosed and long fine nosed pliers. Each tool costs $£ 2.90$ plus 45p P\&P and VAT, and is available by mail order from Electronic Hobbies Ltd, 17 Roxwell Road, Chelmsford, Essex, CM1 2LY.


## That's Entertainment? <br> Tt seems there's at least one jolly 1 wag at Linvar Ltd; they've sent us details of the ASAD Work Centre. ASAD? - well, that stands for All Singing All Dancing, to signify the fact that it's somewhat versatile. When


assembled the Work Centre is 5 by $2^{\prime} 6^{\prime \prime}$, but it can be packed up into its tailor-made carton for storage. The total cost is $£ 89.90$. Drawers, cupboards, shelves and a host of other accessories are available, including a paper cutting unit. This features in the Linvar Packing Bench, built from ASAD components. This more specialised work centre is designed to be the basis of a costeffective packing department. Another aspect of Linvar's involvement in small parts storage is the 'Linbin' range of polypropylene containers, one of which is shown in the second photo. Linvar can be contacted at Bark by Road, Leicester, LE4 7LL.



## NEWS:NEWS:NEWS:NEWS:NEWS:NEWS:NEWS

## Shorts

- A lot of hot air from Hellermann Electric of Plymouth; their new heat-guns, the GHM Mite and GHW-Triac are ideal for use with the "Helashrink" range of heatshrink sleeving.
- The ZN435 from Ferranti is a new multifunction eight-bit data converter. The standard 18 -pin DIL IC contains a fast DAC, an up/ down counter, a precision voltage reference and a clock generator. Uses include ramp-and-compare and tracking ADCs, low-frequency waveform generators, fader controls and radio channel selectors.
- Thorn EMI and JVC have postponed the launch of the VHD videodisc system in Japan for economic and marketing reasons. The same decision was recently taken in the USA. To achieve a coordinated launch, VHD won't now appear in the UK until 1983.
- Gulf Oil have donated an out-of-date IBM computer to the Science Museum in London. The machine was originally bought in 1978 for a quarter of a million pounds; the Science Museum hope
to have it in running order eventually.
- The first edition of the Electroware catalogue is now available and contains too much to list here; we'll just say it's good, it's free ( 30 p P\&P, though) and it's available from Electroware, Dutton Lane, Eastleigh, Hants, SO5 4AA.
- Stuck when it comes to metric conversion sums? The LC950 from Casio can switch from one system of weights and measures to another and has a split level display showing both sets of figures. RRP is $£ 18.95$.
- It seems there are people in the electronics industry who can think up even worse puns than us (is this possible, you gasp). MC Computers Ltd, of Newbury has launched a repackaged version of the Apple II personal computer, so naturally they've called it the Apple Pi.
- The 1982 edition of the IC Master (which contains details of more than 55,000 ICs) is now available in two hardback volumes from Paterson, Steadman and Partners of Saffron Walden. Price is $£ 59.00$ inclusive, which is one tenth of a penny per IC.


More For Less
7 emco's latest car computer, Lthe CompuCruise, has several new features but costs $£ 20$ less than the previous model. For $£ 130$ you get on-line fuel consumption; clock with stopwatch facility, cruising speed control, distancel time/fuel-to-arrive calculations, battery voltage indicators, inside and outside temperatures and about 15 other functions. The car freak who has everything (except a computer) can contact Zemco at 66 Earlsdon Street, Coventry, CV5 6EJ.


## Candid Cameras

Could this be a prototype TV of Cthe future, once satellite TV brings us a bewildering choice of channels? Nope - it's JUPITER, a CCTV control system from PhotoScan Ltd for multi-camera configurations. The microprocessorbased system allows cameras to be incorporated in multiples of 32, with up to 10 monitors, video recorders, remote camera controls, controls for up to four alarms per camera, and a lot of other stuff for security with a vengeance. Because the system is software-based the surveillance system can be modified to meet the needs of any customer. PhotoScan are at Dolphin Estate, Windmill Road, Sunbury-onThames, TW 16 7HG, if you want to know more - what we want to know is, why we never see security guards that look like this.


## Fax You Should Know

For a special three-month Revaluation period, ITT Business Systems will allow customers to rent a Telefax facsimile unit at virtually halfprice. At the end of the three months, they have the option to buy the unit or return it.

## Lithium Cell Clicks

K odak's new disc camera is revoMlutionary in more ways than one - it will be using a high performance lithium battery from Matsushita. The disc camera does not use conventional film pictures are taken on a flat disc of film and the camera includes automatic film advance exposure control and electronic flash. The lithium battery was chosen to power all this lot because of its high-rate pulse discharge capability (greater than 1 A), wide operating temperature range,

## Orient On Air

Here's a novel story - Pye HTelecommunications have won an order to supply mobile radio equipment for Chinese transport vehicles. It would have been nice to report that the rickshaw in the picture was being fitted with the equipment, but not

Facsimile transmission, as if you didn't know, is an electronic method of sending test, pictures, or graphics: the document is scanned, coded and send down a telephone line to be printed out as hard copy on a receiver anywhere in the world - all very clever, although the young lady looks quite bored by it all. If you're interested, IT'T Business Systems live at Diversey House, Chalk Lane, Cockfosters, Barnet, Herts EN4 0BU.


10-year shelf life and high reliability and safety. The lithium cell is expected to find increasing use in consumer products including cameras, flashguns, radios, transceivers, and telephone pocket pagers, as well as security and emergency equipment.
such luck; it's the Kew Kwan Motor Road Co. buses that are getting the two-way treatment. It'll be the first time that China has had radio-controlled vehicles, and Kee Kwan, who hold the exclusive bus tour franchise for Macau, expect that the system will improve route supervision, efficiency and safety.



## NEWS:NEWS:NEWS:NEWS:NEWS:NEWS:NEWS

## The Light Fantastic

This bizarre pic arrived at the office with an announcement that General Instrument Iamps of Bury St. Edmunds will be marketing Tokyo Minilite Ltd products in Europe. Assuming they haven't cheated with a fake flower, then Minilite definitely lives up to its name. For further information contact General Instrument Lamps Ltd, Beetons Way, Bury St. Edmunds, Suffolk IP32 6RA. Note to ad agencies: it's ingenious pix like


## At The Zenith

Regular readers of the mag will Rknow the high regard we have for Heath Electronics and the quality of their kits, so a new printer from Zenith Data Systems ( $\frac{1}{}$ Heath division) has to be good news. The Z-25 is a bi-directional printer with quad tractor feed which provides accurate forms

## AUSSAT Owzat?

Hughes Aircraft Company Mhave signed an agreement to build Australia's first communication satellite system. The three satellites, to be known as AUSSAT, will provide a variety of communication services including the first TV transmissions to many of the communities and homesteads in the remote outback regions. Other services include digital data transmissions, telephony, air traffic control and maritime radio coverage. The first of the satellites

this one that make it worthwhile ploughing through the hundreds of boring press releases we get each week.
registration, and a $9 \times 9$ dot matrix head for high quality print. The character set includes all 95 ASCII characters (upper and lower case) as well as 33 graphics characters. The high print rate (greater than 150 characters per second) results in a print speed of about 300 lines per minute for 10 column lines, and 65 lines per minute for 132 column lines. The operator can select from $10,12,13.2$ or 16.5 characters per inch, while the completely enclosed cabinet results in quiet operation. The printer interfaces to microcomputers via an RS-232C serial interface or 20 mA current loop. The printer (and other Zenith products) are marketed in the UK through Zenith Data Systems outlets.

will be launched in mid-1985, and each satellite is warranted for seven years; one hell of a trip for the service engineer, though!

## Stereo VHS

Cound quality continues to Simprove in the video recorder field; the new top-of-the-line HR7650 EK from JVC features stereo sound amongst a host of other goodies. This means that the inceasingly frequent simultaneous broadcasts on TV and FM radio can be recorded, as well as allowing playback of the fast-growing number of prerecorded stereo video tapes. Sound quality is further improved by the inclusion of a Dolby noise reduction system. There are some pretty good extras on the video side too, such as insert and assemble editing, a special effects playback for fast or slow picture search, double speed play, still
frame and frame advance. A full function $1 R$ remote control unit is also provided. Please can I have one for my birthday?

## Change Of Key

$\mathrm{T}^{\mathrm{h}}$his is a gorgeous young lady and that's her hotel key in her hand. Well, no-one would dispute the first statement, but the second probably requires a bit of explanation. The card is part of a new programmable electronic door lock system developed by the Yale Security Group for better hotel security; the system is known as Yaletronics. Each lock uses a Yale mortice lock and a microprocessor synchronised to the central computer - the locks are each battery-powered to avoid any costly hard-wiring. The present "credit-card" keys are presently made from plastic, but anything could be used; they have the advantage of being small, light and able to have the hotel's logo, room number and other information printed on them.

Each successive guest at the hotel is assigned a different code combination from the millions stored in the computer on a floppy disc with a 5000 -room capacity. The system has a printer to record such information as who made each key, the security level and the date. There are six security levels, from guest keys through maid's keys to master keys and emergency keys. The receptionist uses the system to punch a new key for a guest when he checks in, the microprocessor in the lock

cancelling the previous card. Hotel owners with security problems can obtain further information from Yale Security Products Ltd, Wood Street, Willenhall, East Midlands, W13 1EA.

Of course, it was only a matter of time before a security company caught up with the private detectives on TV, who've been opening doors with credit cards for years..


## THE MULTI-PURPOSE TIMER HAS ARRIVED

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connect it to your symem programme and sot it and torget it connect it 10 Your
clock will to the rest.
features include:

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Battery beckup zevess stored progerammes and continues time kooping during power toilures. (Bemtery not supglised). - Display bishking during power tailure to conserve bettiery pow - 18 progremme time sotes - Powerful "Everyday Function anabling output to mwitch avery dar but use only ona tima mer. - Direct zwitch control enabling output io tor ono hour immedistaly or atior a specified tima interval. 20 function keyped for procoramme entry.

R inclur
(Kit includes all components, PCB, assombly and programming instructions).

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Dimmer


MINI KITS

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 CONTMOLEMTHERMOSTAI Usee (LM3911 K. to somie tompere heater 1 KW mx.) and 1soal for owiching moto
 Suppliod with naro voltago wintching mpachenot Dusitiy Displeys an matoqua votuge on inear 10 elememt LED dienday as a
ber or mertar single dot. Ideas for thormostacheod to obtain 20 to tice May be diaplaya. Requires 5 -20V eupply. MEA PROPOMTIONAL Bemeratune CONTROUER owitch, this the may be wired to tor - "buirt firis powerr controller, onsbling the temperature of en on.
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 kit will switch amsins loed on (o) ofti)
ior a posen time from 20 mina. to 33 hro. congee or thornor periosio moy


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 Putroinfre rod surce corm
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one and lamp brightnoes. Includesitits own mains suopaby output, toggle, control of volume

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The now range consists of The CK 1010 Stereo Pre Amplifier, The CK 1040 WPC Power Amplifier, The CK 1100 WPC Power Amplifier
CK 1010
This kit contains all the necessary parts to build a complete pre-amp. The main PCB is ready assembled and tested therefore construction is simply a matter of point to point wiring and mechanical assembly of the connections and controls to the pre punched chassis
Theving coil input can be fitted to extend its versatility. (MC2K) if using a different power amplifier a PSK power supply kit. Inputs for disc, tuner and tape are provided and an optional add-on CK 1040
This is a nominal 40 watt per channel power amplifier kit which features our dual power supply and the DC output for the CK 1010. All components such as heatsinks, wire and connectors are included and protection is provided from short circuit outputs.

## CK 1100

Similar to the CK 1040 this model provides a nominal 100 watts per channel with extra heatsinking and thermal cutouts are provided as standard.
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"It would seem then that Crimson have maintained their position at the top of the commercial kit build field. There is no oriental amplifier I know of that can better the sound of this combination overall at any price and only a fow - such as the $K A-1000$ ( $£ 500+1$ - are of comparable standard. ...I can say no more than that for $£ 250$ it /CK $1010 / \mathrm{MC2K} / 1100$ ) is a bargain and one that
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## ACTIVE SPEAKER

A long time ago in a magazine far, far away (well, ETI December ' 75 to be exact), we published a design for an active crossover. The idea was to avoid the need for bulky, high current coils along with all the problems involved in high-power crossover design, and perform the filtering on the low-level signal. Each audio band was then fed to its driver via its own power amp, removing the need for any conventional crossover altogether. For some time now we've been planning to go one better by presenting a complete active speaker system, with the electronics built right into the speaker cabinet. When we tell you it's a joint design with the speakers by Badger Sound Systems and the power amplifiers by Crimson Elektrik, you'll appreciate how good it is. Don't miss the September issue of ETI if you know what's good for your ears.

## AUTO VOLUME CONTROL

We had hoped to bring you this project in the issue you're holding but lack of space at the last moment meant it had to be held over. The best laid plans of mice and men etc (you can decide for yourself which category editorial staff are part of ...). Anyway, it's well worth waiting for, because with only a four transistor circuit on a small PCB you can replace your manual volume control with a completely automatic version. Note that this is true volume control, affecting loud and soft sounds equally; not a compressor which reduces the dynamic range of the signal. It's the ideal upgrade for the mike inputs on your public address system.


## SIGNAL MEASUREMENT

Tim Orr, our man of many parts (most of them integrated circuits), is usually to be found within the pages of ETI expounding on the subject of electronic music in one form or another. Next month we have something a little different from him - an article about audio from the point of view of test gear. This is an in-depth feature about several aspects of electronic measurement techniques, including true RMS conversion, noise measurement, and an explanation of the decibel, a unit many people find a trifle confusing. Naturally there's also the usual helpful tables and circuits you've come to expect from us.

## AUDIOPHILE

Something for the (relatively) hard of wallet is the subject of our (relatively) tame hi-fi expert. The September Audiophile will contain a review of the system shown here, which will provide you with excellent sound quality for an outlay of $£ 500$. Deck by Thorens, amplifier by Trio, loudspeakers by JBL - we're not sure if it's built by robots too, but it certainly delivers as far as performance is concerned.



## MULLARD SPEAKER KIT

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# DESIGNING MICRO SYSTEMS When the chips are down, ETI delivers the goods. In this major new series, Owen Bishop takes the lid off computers and the ICs that go into them. This is the definitive treatise on hardware. 

This series is aimed at those readers who already know something about electronics, but who would like to know how electronics is being used today in perhaps its most important application of all -- the computer. The series will be concerned with only one of the two types of electronic computer, the digital computer. The other type, the analogue computer, has several important applications but in the main its work has been taken over by digital computers.

We still owe something to the analogue computer, for our trusty work-horse, the op-amp, was originally designed as its building block. Whereas the analogue computer operates with precisely determined voltages which are allowed to vary continuously over their range and are analogues of continuous physical quantities, the digital computer operates with only two discrete voltage levels. The analogue computer depends on the high precision of its op-amps, and needs an op-amp for every step in its computations.

As we shall see, the electronic requirements for the digital computer are much simpler, allowing designers to concentrate on obtaining high speeds of action. The units of the circuit are simple logic gates, thousands of which can be manufactured on a single slice of silicon, already connected to form the complex logic circuits of the computer. This allows the digital computer to have great computing power combined with flexibility of function. It also allows the computer to be mass-produced cheaply so that, today, anyone with a few tens of pounds to spend can buy one.

## The Heart Of The Matter

Figure 1 shows the heart of the computer to be its central processing unit (CPU). It is connected to a number of other devices - the peripheral devices. Input devices usually include a keyboard, so that the operator can send information to the CPU. Information may consist of instructions and data. Input devices might include sensors (eg circuits to measure


Fig. 1 Block diagram of a computer.

temperature) so that the CPU can obtain its data directly without need for intervention by a human operator. One essential part of this would be an analogue-to-digital converter sub-circuit, to convert the analogue quantity (in this case temperature), to its digital coded equivalent.

Output devices allow the CPU to communicate the results of its computations to the world outside. There is usually a monitor screen on which messages and the results of calculations are displayed. There may also be a printer or a chart plotter. Alternatively there may be direct control of a robot arm or similar device.

The memory is one place where information is stored. The instructions tell the CPU what to do (its program), and it is provided with data to work on. The computer is able to use part of the memory for storing other data which arises from its computations. Information can be transferred between CPU and memory very rapidly and in either direction. Memory is where the currently-used information is held. The store is for information that is not required urgently. The store may consist of a tape deck or disk drive, by means of which information is stored in magnetic form. Blocks of information can be transferred between CPU and store in either direction, but only relatively slowly. The amount of information which can be held in store is much greater than the amount held in memory.

## The CPU

This has the job of receiving instructions and data, eithera from input, memory or store, processing the data according
to the instructions, and then sending the results of its computation to an output device, memory, store, or possibly to more than one of these. In a main-frame computer, the CPU occupies several circuit boards, but in the personal computer the whole CPU is replaced by a single integrated circuit, the microprocessor. This article and the remainder of the series will concentrate on the personal computer, or microcomputer, using a microprocessor as its CPU.

We have been able to use very large scale integration (VLSI) to put all the logical parts of the CPU on to one slice of silicon. The CPU must include an oscillator, or clock, by means of which all its actions and the actions of other peripheral devices are synchronised. It is not possible to reduce the physical size of the components required for this, in particular the quartz crystal, so a least part of the clock circuit is external to the microprocessor. The clock circuit and microprocessor (MPU) together constitute the CPU of the microcomputer.

## We Want Information

Before we look at what goes on inside the MPU we must consider the concept of information in more detail. The unit of information is the bit. The term 'bit' is a shortened version of 'binary digit'. A bit can have one of two values, ' 0 ' or ' 1 ' but not any other value. This binary concept is widespread in thought, in logic and also in electronics. Table 1 shows pairs of opposite and mutually exclusive states. A binary digit is ' 0 ' or ' 1 '; it cannot be anything else. A statement is true or false; truth is by definition the whole truth, for half-truth is meaningless. A switch is either on or it is off; it cannot be partly on. If the circuits are made so that only two voltages (low and high) produce definite results and so that intermediate voltages give indeterminate results, then voltages are either high or low. Transistors are either fully off, or fully on (saturated). Given these binary states, the state of any one pair in Table 1 can be used to represent the state of any other pair. For example, we can stipulate that the digit ' 0 ' is represented in a computer circuit by a low voltage, and the digit ' 1 ' is represented by a high voltage; falsity by ' 0 ' or a low voltage, truth by ' 1 '. Here we have a system which allows numerical values and logical statements to be represented in terms of electrical signals. This is the basis of the digital computer.

| TABLE 1 |  |
| :--- | :--- |
| 0 | 1 |
| No | Yes |
| False | True |
| Absent | Present |
| Switch off | Switch on |
| Transistor off | Transistor on |
| Open circuit | Closed circuit |
| Low voltage | High voltage |

## Grab A Byte

In this system, the bit is the minimum quantity of information to be dealt with. Normally a computer deals with far more information than this. Bits are usually handled in groups. Some of the earlier MPUs handled bits in groups of four, but the majority of micros handle them in groups of eight. A group of eight digits is called a byte. In the computer, a byte is represented by a set of eight lines (eg tracks on the PCB), each at high $(=1)$ or low $(=0)$ voltage. Or it might be represented by a set of eight flips-flops or bistables, each one either set $(=1)$ or reset $(=0)$. According to the interpretation placed on it, the byte could represent:

- A binary value, ranging from 00000000 ( $=0$ decimal) to 11111111 ( $=255$ decimal)
- The truth or falsity of eight different logical statements.
- A coded instruction to the computer.

There is more to be said on this subject next month, but for the moment we will rest with the fact that the computer has to handle binary information represented in electronic form.

## On The Level

For most MPUs the low and high voltages are standardised at 0 V and +5 V respectively. These are the same levels as are used in the 7400 TTL series of ICs. These values are nominal; a Z80 MPU, for example, interprets any voltage between - 0V3 and 0V8 as 'low'. Any voltage between 2 V and 5 V is interpreted as 'high'. Voltages between 0V8 and 2 V produce indeterminate results and must not be allowed to occur. The lack of insistence on precise voltage levels allows computer circuits to remain relatively simple in electronic terms, yet be highly reliable in action.

## Those Important Little Places

If the CPU is the heart of the computer, the heart of the CPU is its arithmetic logic unit. The ALU is where data is manipulated according to the instructions stored in memory; we shall describe some of its operations next month. The ALU is able to operate on all eight bits of a byte in a single operation. We say that the word length is eight bits, or one byte. Some MPUs, such as the Texas 9980 A , have a 16 -bit word, but the general principles of its operation are the same as described below.

As an example of a well-known MPU we shall first consider the 6502 (Fig. 2). This successful but relatively simple MPU is used in the Apple, the PET, the BBC Microcomputer, and several other popular microcomputers. The ALU operates in close conjunction with the Accumulator. This is a set of eight flip-flops which temporarily hold a byte which is to be operated on by the ALU, or is the result of an operation performed by the ALU. The two registers known as X and Y may also be used to store one byte of data each. Data can be transferred between these registers and the Accumulator in either direction. These registers are therefore useful for storing values obtained in one stage of a calculation, ready for use at a later stage. They are also used as index registers, in which the values held in X or Y are the base addresses of selected blocks of memory. This makes it simpler to access blocks of memory; when storing a table of data, for example.

Since data has to be transferred from one register to another, or from a register to the ALU, it speeds the operation of the MPU if a whole byte is transferred in one operation, rather than bit-by-bit. This requires a set of eight lines connecting all the registers and the ALU. This is called the data bus. To distinguish it from a similar set of lines which connect the MPU with the peripheral devices, it is more precisely known as the internal data bus.

## It's Under Control

The control bus consists of several lines along which signals are sent to coordinate the actions of the various parts of the MPU. For example, if the data held in register X is to be sent to the ALU, a signal must be sent along a control line to register X , making it place the data on the data bus. Register X makes the lines go 'high' or 'low' according to the pattern of 0 s and $1 s$ held in its eight flip-flops. At the same time a signal must be sent along another control line to the ALU, making it accept the data now present on the data bus. The control lines emanate from a special part of the MPU called the Control.

Despite its impressive name, the Control is no more than a slave. It knows how to carry out the tasks it is allotted, but does not remember what it has just done, and does not know


Fig. 2 The internal structure of the popular 6502 microprocessor.
what task it must perform next. The list of tasks (the program) is stored in memory at a sequence of locations. The control simply fetches these instructions from memory, a byte at a time, and acts on each immediately it is received. For this purpose it needs the Program Counter, a register in which it records how far it has reached in the program - a sort of 'bookmark'. Since a single byte cannot store numbers greater than 255 (decimal), and since most programs have far more bytes than this, the Program Counter is a double-byte register. Its 16 bits allow any number up to 111111111111 1111 (binary) to be stored, equivalent to 65535 (decimal).

During its calculations, the MPU often has to store data in the Stack, a special section of memory set aside for this purpose. As data is added to or removed from the Stack, the position in memory of the first item in the Stack (the Top of Stack) changes. The Stack Pointer register records the current position of Top of Stack, so that the MPU knows where to go to retrieve the stacked data.

## Status Symbols

The status register should be considered as eight individual bits, arranged together for convenience as a byte. Each bit is set (made equal to 1 ), or reset (made equal to 0 ) individually as the result of a particular operation, For example, bit 7 is set whenever the result of an operation results in a negative value. Bit 1 is set when the result of an operation is zero. These bits, which indicate whether a particular event has occurred or not, are often known as flags. Bit 0 holds the 'carry' digit from additions or subtractions in the accumulator.

The remaining sections of the MPU are concerned with communicating with the peripheral circuitry. There is the data bus buffer which detects voltage levels on the external data bus and copies these on to the internal data bus. Or it


Fig. 3 Switching on any of the transistors generates an $\overline{\mathrm{NMI}}$
can operate in the reverse direction. If the data bus is carrying an instruction, this is accepted by the instruction register. From there it goes to the control which decodes it and then acts upon it. The address bus receives outputs from certain registers putting voltage levels on the 16 address lines, a subject which will be dealt with later.

## Dealing With Interruptions

The interrupt logic receives signals along any of three lines. All three lines are normally held high by pull-up resistors. The lines are thus described as 'active-low'. In other words, it requires a low level on the line to make the MPU respond. Most control lines in the computer are active-low. This makes it simple for any number of devices to bring the line to its low state. If the line is connected to open-collector transistors, for example (Fig. 3) this is equivalent to a wired-OR
configuration. Then if any one of these transistors is turned on, the voltage level on the line is made low. If a line is active-low, this fact is indicated by a line above its abbreviation (eg $\overline{\text { RST }}$ for active-low 'reset').

The reset line is used to initialize the MPU, either when the computer is first switched on or if it gets into a 'latchedup' condition, in which normal methods of controlling it do not work. There is generally a pull-up resistor holding the voltage high, with a 'Reset' press-button hidden in a fairly inaccessible place at the rear of the computer. Pressing this button temporarily grounds the reset line.

When the computer is first switched on, resetting is usually done automatically, by having a large-value capacitor to hold the line low for a short period while the rest of the system reaches its full voltage levels (Fig. 4). There is no reset button in the Sinclair ZX-81. To reset, you simply turn off the power, wait a moment or two and then reapply power. Resetting the MPU resets the program counter to zero, so that it returns to the beginning of the program stored in memory and starts again.

On receiving a low signal on one of the interrupt lines $\overline{(N M I}$ or IRQ) the MPU finishes whatever operation it is engaged in, then stores away (on the stack) any data relating to that operation. This takes only a few microseconds, after


Fig. 4 A suitable circuit for generating a power-on reset pulse. A manual reset button is also provided.
which the program counter is sent to the address in memory of a special interrupt service program. It performs whatever this program requires, then returns to its original program, recovers the data from the stack and continues with the original program as if nothing had happened. Interrupts are used by peripheral devices to gain the attention of the MPU when it is urgently required. The non-maskable interrupt (NMI) takes priority. It cannot be ignored by the MPU, and, while the MPU is performing the NMI task, it cannot be interrupted again. The Interrupt Request (IRQ) has second priority. The MPU can be pre-programmed to ignore an IRQ altogether. In the 6502, this is done by setting digit 2 of the Status Register to ' 1 '. An IRQ task can be interrupted by an NMI. After completing the NMI task, the MPU continues with the interrupted IRQ task. When this is completed (assuming there is no further $\overline{\mathrm{NMI}}$ ) it returns to its original program.

## Z80 Anatomy

Most MPUs have the same kind of organization, or architecture, as the 6502. The Z80 MPU, which is the processor for a wide range of computers including the TRS-80 Models I and II, the Research Machines 380 Z , and the Sinclair ZX-81, has a rather more elaborate set of registers. The main set comprises the accumulator ( A ), the flag register ( F , corresponding to the status register of the 6502), and registers $\mathrm{B}, \mathrm{C}, \mathrm{D}, \mathrm{E}, \mathrm{H}$, and L , which are general-purpose registers. There is also an alternate set of registers, $\mathrm{A}^{\prime}, \mathrm{F}^{\prime}, \mathrm{B}^{\prime}, \mathrm{C}^{\prime}, \mathrm{D}^{\prime}$, $\mathrm{E}^{\prime}, \mathrm{H}^{\prime}$, and $\mathrm{L}^{\prime}$. The MPU normally begins operations by using the main set, but can be switched over to use the alternate set instead, leaving the main set unaffected. It can be switched back to the main set again later.

In addition there are two index registers (IX, IY corresponding to X and Y in the 6502), a stack pointer, and a program counter. In the Z80, IX, IY, SP and PC are doublebyte registers ( 16 bits). Finally there's the interrupt vector register (I) in which instructions for a complex series of vectored interrupts can be stored, and the memory refresh register ( $R$ ) which is used in connection with refreshing the dynamic memory of the system. This topic will be dealt with in a later article.

Fig. 5 Pinout of the Z80 microprocessor, with a suitable clock circuit.

clock circuit


Fig. 6 The clock and control signals for the $\mathbf{Z 8 0}$.

## Making The Connection

The typical MPU is contained in a 40 -pin DIL package as shown in Fig. 5, which uses the Z 80 as an example. It requires a regulated 5 V DC supply, which is applied between pins 29 (system ground) and $11(+5 \mathrm{~V})$. The clock circuit supplies pulses at 2 MHz in the case of the original Z80 MPU. The newer Z80A can operate with a clock rate up to 4 MHz . The clock signal may also be taken to peripherals; for example, the circuits which control the monitor.

The eight data lines, D0 to D7, come direct from the data buffer (Fig. 2). These may act as inputs or outputs, though not in both capacities at the same time. The data bus is taken to the peripherals, to allow for transfer of data between these and the MPU. In order that the peripherals will know which one (and only one) of them is to receive or transmit data, each peripheral is also connected to the address bus. This is a set of 16 lines, A0 to A15. Address lines are outputs from the MPU. By putting various combinations of highs and lows on these lines the MPU can indicate which peripheral it is addressing. The peripheral may be a printer or a relay on a control board. It may be a single location in memory. Since there are 16 lines, there are 65536 possible combinations of highs and lows, this being the maximum number of locations which can be directly addressed. This figure is usually written in its shorter form, 64 K , where one ' $K$ ' is not 1000 , but $1024\left(=2^{10}\right)$.

## Peripheral Ptocedures

The remaining pins of the IC are connected to control lines which connect the MPU to certain of the peripherals. We will consider the input control lines first. The functions of RST, NMI and INT ( = IRQ) have already been dealt with. A low level on WAIT causes the MPU to halt its operations. It may have asked a peripheral to send data to it but the peripheral is not ready to put the data on the bus. Instead the peripheral sends the WAIT signal, and the MPU suspends action until the peripheral has had time to put the required data on the bus and let the WAIT line go high again. The bus request signal (BUSRQ) is used by certain peripherals to force the MPU to hand over control of the address bus, the data bus and certain control lines. This is used during an operation known as Direct Memory Access (DMA) in which blocks of data are transferred between memory and other peripheral devices without the intervention of the MPU. This is not usually implemented on the smaller microcomputers.

There are eight outputs in the control bus of which we shall mention only three now, dealing with the rest later as part of specific examples. The Machine Cycle One output (M1, pin 27) indicates when the MPU is fetching an instruction from memory. Two outputs of special importance are read ( $\overline{\mathrm{RD}}$ ) and write (WR). When the MPU is to receive data from a peripheral it puts the address of the peripheral on the address bus and make the $\overline{\mathrm{RD}}$ line low. This indicates to
the peripheral, which is also wired to the $\overline{\mathrm{RD}}$ line, that it is to transmit data and not to receive it. When the MPU wants to transmit data to a peripheral, it puts the address on the address bus and makes the WR line low.

## Clocking On

With so many signals being passed in several directions, and with the data bus being required for transmissions into or out of the MPU, it is essential that all these activities take place to a clearly defined schedule. Although micros and their peripherals act at fantastic speeds, these are only fast according to our human scale of appreciation. To an MPU a memory which responds in a microsecond is not particularly speedy. The MPU even has to wait a while to give it time to put the data on the bus, and for the voltages to settle to their intended levels. To keep all sections of the system operating in an orderly way, and to allow the circuits a finite (even if infinitesimal) time to react, the clock is of major importance.

As an example of the way the various parts of the system interact, let us consider what happens when the MPU goes to memory to find the instruction which it is to execute next. Figure 6 shows the voltage levels on the lines concerned. The top curve shows the regular pulsing of the system clock at, say, 2 MHz . At this frequency, each of the periods $\mathrm{T}_{\mathrm{i}}$ to $\mathrm{T}_{4}$ is 0.5 microseconds (uS). The MPU begins by making M1 low, indicating that it is about to fetch an instruction from memory. At the same time it puts on the address bus the address of the memory location in which this instruction is stored. It has obtained this address from its program counter, which has just been incremented following the execution of the previous instruction. The addressed location does not
know at this stage whether it is to be read or written to.
On the next low-going edge of clock, the Memory Request line (MREQ) indicates that this is an operation involving memory (as opposed to a printer, or monitor peripheral, for example). Immediately after this, the $\overline{\mathrm{RD}}$ line is taken low by the MPU, indicating that this is a read operation. The MREQ signal is used to enable (or 'turn on') the memory IC so that it is ready to put its data on the bus. Since many such ICs are permanently wired to the bus and since only one can be allowed to put data on to any line at any one time, memories have tri-state outputs. These can be high, low or 'high impedance'. The high impedance state means that the output is virtually isolated from the bus and not able to communicate with it. Outputs are in this state until a $\overline{\mathrm{RD}}$ signal is received by the IC. The RD signal can be fed to the memory IC so as to make its outputs change to low impedance and take the lines of the bus to high or low states.

As soon as the data has appeared on the bus the CPU reads it into its instruction register. It has until the next rising edge of the clock to do this. Then M1, MREQ and RD are made high, indicating that the operation has been completed. The total time for the whole operation is 1 uS . During the next 1 uS the CPU passes the data along its internal bus to its control, where the data is decoded as an instruction and then acted upon. While this is happending there is no need to take in further data and, since the instruction is still being decoded, the time for acting upon it has not yet arrived. In the Z80, this period is used for refreshing dynamic memories, as will be explained in a future issue.


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# PLAYMATE GUTAR EFFECTS/AMP 

## The sounds of the superstar in your own room - or in the middle of a field! The PLAYMATE will help you on your way. Design and development by Phil Walker

TThe Playmate is a small practice amplifier for use with a guitar giving a few watts output for easy listening while also providing some of the basic effects used by many musicians. It is ideally suited to those who do not carry all the various effects units around in their guitar case but would like to be able to practice at odd moments or in out-of-the-way places.

In addition to the amplifier and standard tone controls etc, various distortion and wah-wah effects are possible. As a by-product of the circuitry a sustain effect is also possible.

The sound output is provided by a small internal loudspeaker and the whole module is powered from a small mains unit or batteries. An
external foot pedal could be used with the wah effect if required. This consists of a variable resistor and a couple of other resistors to provide the necessary control current. The internal control is still active at this time and can be used to set an operating range.

## The Circuit

The circuit is in general straightforward. It consists of an input buffer with a gain of about 50 followed by a signal compression stage which reduces the dynamic range greatly in order to feed the effects circuitry at a constant level. The effects consist of a distortion-inducing stage for fuzz and a variable band-pass filter for the wah wah. After the effects stages, the

dynamic range of the signal is restored to normal before being fed to the mixer, tone controls and power output stages.

The input buffer consists of a single 3140 CMOS op-amp whose gain is set at 48 by R2, R3. The following dynamic range compressor consists of one part of a LM13600 dual transconductance amplifier. The gain of this device is a function of the amplifier bias current, the input diode current and the load resistor. The output buffer of the device is used here as a peak detecting rectifier which charges a capacitor (C3) to the peak value of the output signal less two base-emitter drops (about 1V4). If this voltage is greater than about 0 V 7 the resulting current flowing through the input linearising diodes causes the effective stage gain to decrease and keep the output level constant.

## Distorting The Facts

Distortion effects in this project are of two types. The first is mainly even harmonic generated by half-wave-rectifying the input, inverting it and then mixing it with the original signal to get from no distortion to complete frequency doubling. In addition to this, overload type distortion is provided by a high gain clipping amplifier using non-linear feedback (IC $3 \mathrm{a}, 3 \mathrm{~b}$ ).

Wah wah sound effects are produced by a current-controlled state variable filter. The control current determines the centre frequency of the pass band while a two-gang variable tesistor sets the bandwidth and compensates for inevitable gain changes.

Tone controls are of a standard type and use frequency-selective feedback networks around an op-amp. The following power amplifier has been designed to have a low quiescent


Fig. 1 Block diagram of the Playmate.


Fig. 2 Internal circuitry of the LM13600 - an operational transconductance amplifier!


If the diode current is not zero and the signal current is less than $I_{D / 2}$ then the transfer function is:-

$$
\begin{gathered}
I_{0 \mathrm{at}}=2 \times I_{a b c} \times I_{8} \\
I_{D}
\end{gathered}
$$

where
$I_{s}=$ signal current
$I_{a b c}=$ amp. bias current
$\mathrm{I}_{\mathrm{D}}=$ lin. diode current
$I_{\text {out }}=$ output current


Fig. 3 Basic voltage amplifier circuit.
current. This is important if batteries are to be used as many amps of the IC variety take 30 mA or more, or are designed for single rail working.

The LM13600
This device is used for two functions in this project. One of these is the compressor/expander while the other is the wah wah. In both of these, use is made of the fact that the
gain of the device is dependent on the amplifier bias current and the linearising diode current (provided that the input current is less than half the diode current). In fact the output resistor also determines the gain but is not so easily varied.

If the diode current is zero then the manufacturers' data sheet shows that the transfer function of the device is:-

If we use resistors for input and output, it can be seen that the voltage gain of a stage using this device can be controlled easily by use of the bias and linearising diode currents.

Figure 3 shows the basic circuit for a voltage amplifier and from it we can show that the output voltage $V_{0}$ is dependent on the bias and diode currents.


HOW IT WORKS

The gain of the input buffer IC1 is set by R2 and R3 at 48. R1 determines the input impedance while C 1 provides DC blocking. The output from this device goes to the dynamic range compressor IC2a and its buffer IC3a. This part of the circuit also provides control signals for the expander circuit and, if required, for the wah wah effect. The buffered output from the compressor then goes via C4 to the first part of the fuzz effect circuitry constructed around around IC3b. Here an inverted half-wave-rectified version of the input signal is produced by the action of DI and D2 in the feedback network of IC3b. This is applied to RV1 from which a portion is selected and mixed with a little of the original signal. As the half-wave-rectified signal at this point of the circuit is twice as great as the straight-through signal, by varying the setting of RV1, amounts of distortion varying from none to virtual frequency doubling can be selected.

The mixture of signals obtained above is now applied to IC3c where they are amplified. The amount of amplification is determined by the setting of SW1. In position 3 minimum gain is provided and in fact the whole fuzz section is bypassed. Position 2 gives the same gain, allowing the first distortion stage to be effective. The final position connects D3 and D4 via C5 and R19 into the feedback circuit of IC3c instead of R18. This has the effect of greatly increasing the small signal gain but causing the output to limit sharply, thus clipping and squaring the output. This facility is available on whatever output is coming from IC3b.

The output from the fuzz stages now passes to the wah wah. This effect is produced by the current controlled state variable filter used in a band-pass mode. The filter is realised by using a LM13600 device with a controlled bias current providing the variable centre frequency. The ' $Q$ ' factor is controlled by a dual gang potentiometer, half of which is used to control the ' $Q$ ' factor while the other half compensates for the effective gain change as this is altered. In this type of circuit the frequency range is determined by the values of C7, C8, R24 and R26, while the actual centre frequency is controlled by the amplifier bias current. If the bias current is allowed to become too small it is sometimes found that a thump is heard at the output; in order to prevent this R34, R35, D5 and R33 are used in the control circuitry to keep the current above this threshold.

SW2 selects between the control options for the wah wah circuit. The 'off' position bypasses the circuit altogether, the 'pedal' position makes access to an external foot pedal if fitted, while the 'auto' position connects to an output from the compressor stage. This control signal is a current which is proportional to the amount of signal compression being
applied to the input signal. The magnitude of this current increases as the input signal increases. The result of this is that when the input signal is loud, the wah wah centre frequency is high and as the input decays, the wah wah frequency decreases with it. The effect of this is to make a wah sound automatically whenever a string or chord is played.

The output from this section is buffered and adjusted in level by IC3d. After this the signal passes to the signal expansion stage built around IC2b. C23 provides DC isolation and R36 converts the input voltage to a suitable drive current for the IC. For this application the linearising diode current is held constant while the amplifier bias current is varied. Q1 in the compressor circuit provides the control current for this stage allowing a good match in the attenuation/gain characteristics of the two stages. SW3 selects either the output from the expander or bypasses it as required to give normal or sustain on the effects channel.

A dual gang potentiometer RV4 allows mixing between the original signal and the effect-modified signal. This is followed by a volume control RV5 to set the output sound level.

After the volume control, IC5a buffers the signal before applying it to the tone control circuit around IC5b. The configuration used here is a very common type of feedback arrangement. As an approximation, the gain of an op-amp with feedback is taken as -(feedback resistor value)/(input resistor value). If we replace the feedback and input resistors with variable impedances, we find that when the feedback impedance is greater than the input impedance then the overall gain is greater than unity, and vice versa. As impedances vary with frequency, the gain at each frequency will tend to be different. The only time the gain does not vary is when the input and feedback impedances are equal whatever their magnitude. This is the general principle on which the tone control networks operate.

The final section to be considered is the power amplifier stage. Voltage amplification is provided by IC6 and the output from it drives two complementary compound Darlington pairs, Q4/Q6 and QS/Q7. Quiescent current through the output devices is set by RV8 in conjunction with Q3, R54 and C19. R59 and R60 aid in maintaining bias stability and provide some protection to the output transistors in the event of a fault. R61 and C20 compensate for load impedance variations at high frequency and C 18 reduces the high frequency gain of the power amplifier to reduce the possibility of RF oscillation. The large capacitors C21-25 are to reduce the effects of aging batteries and prevent low frequency oscillation or intermodulation distortion.

$$
\begin{aligned}
& \mathrm{V}_{\mathrm{o}}=\frac{\mathrm{V}_{\mathrm{in}} \times 2 \times \mathrm{I}_{\mathrm{abc}} \times \mathrm{R}_{\mathrm{L}}}{\mathrm{RI} \times \mathrm{I}_{\mathrm{D}}} \\
& \mathrm{I}_{\mathrm{in}}=\mathrm{V}_{\mathrm{in} /} \mathrm{R}_{\mathrm{in}} \text { Therefore }
\end{aligned}
$$

$$
\text { and the gain } \frac{\mathrm{V}_{\mathrm{o}}}{\mathrm{~V}_{\text {in }}}=2 \times \frac{\mathrm{I}_{\text {abc }}}{\mathrm{I}_{\mathrm{D}}} \times \frac{\mathrm{R}_{\mathrm{L}}}{\mathrm{R1}}
$$



Fig. 4 The LM13600 as an expander.


Fig. 6 Circuit diagram for the Playmate.

## Compressing With The LM13600

Figure 5 shows the citcuit used in this project to compress the dynamic range of the signal input. For very small signals $I_{D}$ is virtually zero and the amplifier operates with a very high gain. As the signal increases, the output peak voltage will reach a level sufficient to charge the capacitor $C$ to about one diode drop. If the input
signal tries to increase further the resulting current into the input diodes will cause their impedence to fall, thus increasing the attenuation of the input and maintaining a constant output level.
At any time the current flowing into the diodes is:-
$I_{D}=2 \times\left(V_{0}-3 \times 0.7\right)$
R2


Fig. 5 Here the LM13600 is configured as a compressor.

The $3 \times 0.7$ represents the voltage drops associated with the base-emitter junctions of the output buffer transistors and the voltage drop of the linearising diodes. This voltage does vary with temperature and current so since another control current is required for the expander function, this is derived by using a resistor and common base transistor. The configuration gives a current output which tracks the compressor control current very closely as it has the same number of junctions in series.

## The LM13600 As An Expander

 If the current produced by the above circuit is fed into the bias current input of a virtually identical stage while the diode current is held a constant then the voltage gain equation above shows that the gain of the circuit will be increased as the current increases. Moreover the product of the two gains will be constant giving an invariant overall signal transfer function.

The construction details, parts list and overlays will appear next month. the standard in industry，overtaking the obsolete laminated type．Industry has been quick to recognise the advantages toroidals offer in size．weight，lower radiated field and， thanks to I．L．P．PRICE．
Our large standard range is complemented by our SPECIAL DESIGN section which can offer a prototype service within 7 DAYS together with a short lead time on quantity orders which 7DAYS together with a short lead ume on quantity orders which
can be programmed to your requirements with no price penalty

| IYPE | $\begin{gathered} \text { Sefites } \\ \text { No } \end{gathered}$ | secondaay Valls | $\begin{array}{\|c} \text { RMS } \\ \text { Curfent } \end{array}$ | Pf：CE |
| :---: | :---: | :---: | :---: | :---: |
| 30 va | 1x010， | $\xrightarrow{6+6}$ | 250 166 168 |  |
| 70×33mm | $\xrightarrow{2} 011$ | $\underset{\substack{9+9 \\ 12+12}}{ }$ | 125 |  |
| Regularon | ${ }^{1} \times 1,13$ | ${ }^{15}+13$ | 100 |  |
|  | $\xrightarrow{1}$ |  | － 0.938 |  |
|  | 18016 | coter | － 060 |  |
|  | $1 \times 17$ | $30+30$ | 050 |  |
| 50 va | $2{ }^{2010}$ | － 6.6 | 416 | ¢570 |
| comex | 2x011 | － $\begin{gathered}9+9 \\ 12.12\end{gathered}$ |  |  |
| \％egkg | 2， $2 \times 12$ | cotid 12 | ＋ 208 |  |
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| 1\％\％ | ${ }_{3} 3014$ | 隹 $12 \times 18$ | 222 |  |
|  | 3015 | 220．22 | － 1.61 |  |
|  | coly | 30＋30 | 133 132 0 |  |
|  |  | ${ }_{220}^{110}$ | 1072 0 0 0 |  |
|  | ${ }_{3 \times 150}$ | 240 | － 33 |  |
| 120 va | 4810 | 6 ＊ 6 | 1000 |  |
| $90 \times 40 \mathrm{~mm}$ | 4001 | $9+9$ | 665 |  |
| 12 kg | 4.012 | ${ }^{12+12}$ | 500 |  |
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| \％ |  | 22.22 | 372 | －ptoro |
|  | 4016 | $c25+253030$ | 240 200 200 | － |
|  | ${ }^{4 \times 018}$ | ${ }_{3}+135$ | 171 | тfrat sut |
|  | － | ${ }_{220}^{120}$ | 109 0 0 |  |
|  | ${ }_{40} 1230$ | 240 | O50 |  |
| 160 va | 50011 | $9 \cdot 9$ |  |  |
|  | 3，012 | 12＋12 | 666 | £7．91 |
| 8 \％9 | ${ }^{3} 813$ | $12 \cdot 15$ | 534 |  |
| Reguation | ， 30015 | $\underset{\substack{182+18 \\ 22+22}}{ }$ |  |  |
|  | $5 \times 015$ | 25.23 | 320 |  |
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|  | $\pm$ | 220 | 072 |  |

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| :---: | :---: | :---: | :---: | :---: |
| 225 va | $5 \times 012$ | $12+12$ | 938 |  |
| $110 \times 45 \mathrm{~mm}$ | 6x013 | $15+15$ | 750 |  |
| 27 kg | $6 \times 014$ | 18＋18 | 625 |  |
| Regulat | 6x015 | 22＋22 | 511 | f9 20 |
|  | 6x016 | $25+25$ | 450 | ． 20 |
|  | 6x017 | $30 \cdot 30$ | 375 |  |
|  | 6x018 | － $\begin{gathered}35+35 \\ 40+40\end{gathered}$ | 321 281 281 | －vatitibe |
|  | ${ }_{6 \times 025}$ | $15+15$ | 251 250 | romal $12{ }^{2} 8$ |
|  | 6x033 | 50.50 | 225 |  |
|  | ${ }^{6 \times 028}$ | 110 | 204 |  |
|  | 6x029 | ${ }_{2} 22$ | 102 |  |
|  | 6x030 | 240 | 093 |  |
| 300 va | 7x013 | $15 \cdot 15$ | 1000 |  |
| $110 \times 50 \mathrm{~mm}$ | $7 \times 014$ | $18 \cdot 18$ | B 33 |  |
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|  | Tx033 | 30＋50 | 300 |  |
|  | $7 \times 028$ | 110 | 272 |  |
|  | $7 \times 029$ | 220 | 136 |  |
|  | $7 \times 030$ | 240 | 125 |  |
| 500 Va | An 016 | 25， 25 | 1000 |  |
| $140 \times 60 \mathrm{~mm}$ | $8 \times 017$ | $30+30$ | 833 | ¢13 53 |
| 4 kg | $8 \times 018$ | $35+35$ | 714 | 3.53 |
| $\begin{aligned} & \text { Regulation } \\ & 4 \% \end{aligned}$ | 8x026 | $40+40$ | 625 |  |
|  | $8 \times 025$ | $45+45$ |  |  |
|  | $8 \times 033$ $8 \times 042$ | $50+50$ $55+55$ | 500 454 4 | －01Fit tal 26 |
|  | 8 8028 － | 110 | 454 |  |
|  | $8 \times 029$ | 220 | 2.27 |  |
|  | 81030 | 240 | 708 |  |
| 625 va | $9 \times 017$ | $30 \cdot 30$ | 1041 |  |
| $140 \times 15 \mathrm{~mm}$ | $9 \times 018$ | $35+35$ | 892 |  |
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|  | $9 \times 025$ | $45+45$ | 694 |  |
|  | ${ }_{9}^{9} \times 1033$ | 50＋50 | ${ }^{6} 25$ |  |
|  |  | $35+55$ 100 | 568 568 |  |
|  | $9 \times 029$ | 220 | 284 |  |
|  | $9 \times 030$ | 240 | 260 |  |

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\hline 7 Sa \& \& \(74259{ }^{1500}\) \& \({ }^{74} 4.5\) \& \({ }_{4043}^{4042}\) \& \multicolumn{3}{|c|}{LINEARICs} \& \multicolumn{4}{|r|}{COMPUTER COMPONENTS} \& MODULATORS \\
\hline 7400 \& 11p \& \({ }_{74273}{ }^{44295}\) \&  \& Prr \& ADC0808 9900 \& \& Nes534A 195\％ \& \& \& \& \& 6MHz UHF 37p 3 MHz UHF 4500 \\
\hline \& 12 \& \(\begin{array}{ll}74276 \\ 74278 \& 1100 \\ 1000\end{array}\) \& 74LL290
74509 \& ［ \({ }^{\text {P }}\) \& AN103 20 \& LM377 \&  \& CPUS \&  \& CRT \& \(\begin{array}{ll}81 \text { LS988 } \& \\ 9602 \& \\ 200 \\ 200\end{array}\) \& \\
\hline 7404 \& 12 p \& 74279 \&  \& \begin{tabular}{l|ll} 
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\hline 10 \& 4047 \& \(50 p\) \\
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\end{tabular} \& － \(\begin{aligned} \& \text { AY1．} 12126000 \\ \& \text { AY1．1313 } 6860\end{aligned}\) \& LM3801AN \({ }_{\text {L }}\) \& \({ }_{\text {RCA } 4151}\) \&  \& \& COntroller \& \& CRYSTALS \\
\hline \& \& \({ }^{74283}\) \& \(\begin{array}{ll}\text { 74LS298 } \\ \& \text { 900 }\end{array}\) \& （1） \& AY \& LM \(382{ }^{\text {20 }}\) \& \＄5668 \({ }^{\text {2500 }}\) \& 6502 400p \&  \& CRT6545 9600 \& 50， \& \\
\hline \& \& \({ }^{74284} 5175\) \& \({ }_{74} 1529292700\) \& － \(4050 \quad 240\) \& AY1－5050 \& LM386 90p \& SAA1 \& 6502 A 500 p \& ADMA 612 \& CR15027 518 \& 2Na27－8 \&  \\
\hline \& \& 742 \& 74LLS323 \({ }^{\text {175p }}\) \& 4051 45p \& AY3－1270 \& LM387 \& SAD1024AB500 \& \& \(1 / 2\) \& \({ }^{\text {5 }}\) 5780 \& ZN428E－8 500 p \& 200 KHz 2800 p \\
\hline 7408 \& \& 7429 \& 7453234 \& P 4052 \&  \& LM389 \& \({ }_{\text {LLA90 }}{ }^{\text {S }}\) \& \begin{tabular}{ll}
6802 \\
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\end{tabular} \& 9 \& P \& \& p \\
\hline 7410 \& \({ }^{140}\) \& 742 \& \({ }^{74153388}\) \& － 4053 \&  \& LM392N \& SN76477 480p \& 6809 \& \& \& teletext \& \\
\hline 7411 \& 18p \& 743 \& 74 \& 4055 90p \& AY－5－3600 fb \& LM393 100p \& SN76488 4500 \& \(68809{ }^{14}\) \& MEMORIES \& SFF96364 E88 \& DECODER \& \[
.5 \mathrm{MHz}
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\hline 7412 \& \& 74 \& \({ }^{741535656} 4\) \& ， \& 10070 \& LM394CH \& SN76489 \& \({ }^{68095}\) \& 2101 A 400p \& ［1MS9918 \& SAA5020 56.00 \& \\
\hline 7414 \& \({ }_{29} 2_{\text {P }}\) \& 74368 \& \(\begin{array}{ll}7415363 \\ \\ 745364 \& 1400 \\ 140\end{array}\) \& － \begin{tabular}{l}
4059 \\
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\end{tabular} \& CA3028 \& LM7710 \& \({ }_{\text {SP8515 }}{ }^{\text {S／20 }}\) \& \({ }_{8039}^{8035}\) \& 2102．3L 1200 \& \& SAA 5030 f9．00 \& 0 MHz 225 p \\
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74393 \& \({ }_{74 \text { LS365 }}\) \& \& CA3019 \& LM9 \& TA7120 1600 \& 80804 A 280p \& \({ }_{2111}{ }^{211}{ }^{\text {a }}\) \& Interface \& £16.00 \& \\
\hline \& 2 \& 90 \& 74. \& \& － \& LM 725 \& TA7204 \& \({ }^{80854} 4\) \& \({ }_{2112-A}\) \& Cs \& SAA \(5050 ¢ 9.00\) \& 2500 \\
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\hline 7 \& \({ }_{200}^{200}\) \& Tats series \& \& \& 360 \& LM \& TA7310 160p \& MS9980 \& \& \& DISC \& \\
\hline 7423 \& \& 74.5 \& 74L \& －\({ }_{4070}^{4069}\)\begin{tabular}{ll}
165 \\
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\end{tabular} \& CA3080E \& LM748 \& rBA64 1 AX 1 \& 280 \& \(\begin{array}{ll}4027.3 \& 3000 \\ 4044.45 \\ 450\end{array}\) \& AM25S10 3590 \& CONTROL \& \\
\hline \& \& 744501 \& 74.5 \& 16 p \& ca \& LM1014 1500 \& r8a64 18x1 \& \({ }_{780}^{780}\) \& \({ }^{4116.15}\) \& AM25LS252102 \& ICs \& 50p \\
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7429 \& \({ }_{20}^{23 p}\) \& \({ }_{741503}{ }^{4120}\) \& 74.15 \& P \({ }_{\text {P }}\) \& CA3089E 2000 \& LM1801 \& rBA64i8x \& \& 4116－20 90p \& \({ }_{\text {AM26LS322250 }}\) \& \& \％ \\
\hline 7428 \& 280 \& \({ }^{741515}\) \& \({ }^{74453393}\) \& 4075 \& CA31308 \& LM1877 \& t8a651 200p \& \& \begin{tabular}{lll}
4118.3 \& 500 p \\
4164.2 \& \\
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\end{tabular} \& COM8116 \({ }^{\text {coop }}\) \& FD1791 E30 \& 10p \\
\hline \& \& \({ }^{744 \text { LS08 }} 10\) \& 74 \& 400 \& CA3130\％ 130 \& \&  \& \& 4816 AP－3 320p \& D7002 \({ }^{\text {DAC80 }}\) \& \({ }^{\text {F01793 }}\) \& 4．9152M \\
\hline \& \& \(741509 \quad 15 \mathrm{p}\) \& 1600 \& \({ }^{\text {P }}\) \& CA33160E \& LM1889 \& tBA820 90p \& SUPPORT \& \& \&  \& \\
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\] \& \(741510 \quad 130\) \& \({ }_{74} 4154900\) \& \({ }_{4081}^{4089}\) \& CA3161E \& LM2917 \& \& SUPPORT \& \& \& \& \\
\hline \& \& 74 LSt1 13p \& 74 \& 4082 \& \& Lм3302 \& \& DEVICES \& \& \& WD2143 550p \& \\
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\] \& 74 \& 74LS54 1000 \& 4086 55p \& CA3189E 3000 \& Lм 3900 \& \& \& \& \& \& \({ }^{\text {lisep }}\) \\
\hline 7440 \& \& 74 \& 7415624150 \& － 4089 150p \& \({ }^{\text {CA3240E }}\) 1200 \& LM3909 \&  \& \({ }_{3242}^{3242}{ }^{3060}\) \& \({ }_{6810}{ }^{6514} \quad 120 \mathrm{p}\) \& \(\begin{array}{ll}\text { OS88331 } \& 140 \\ \text { OS832 }\end{array}\) \& CHARACTER \& 7．168MHz \({ }^{175 p}\) \\
\hline 744 \& 70 \& \& 74 \& \({ }^{289}\) \& CA328 \& \& \({ }_{\text {TCA940 }}\) \& \({ }_{6520}{ }^{3245}\) \& 3489 210p \& － \& generators \& \\
\hline \& 9 \& 74LS20 120 \& 74.5 \& 200 \& \({ }_{\text {DAC1 }}\) \& LM3915 2250 \& tDA 1004430 \& 6522 4500 \& 7451893050 \& \({ }_{\text {DS8836 }} 150\) \& \& \\
\hline \& \& \({ }_{74} 7\) \& 7415642 2000 \& 4096 70p \& 200p \& \& TDA 100883000 \& \({ }_{655228}^{652}\) \& \({ }_{745289}{ }^{3}\) \& DS88388 \& \& \({ }_{10.5} .5 \mathrm{MHz}_{2} 250 \mathrm{O}_{\mathrm{p}}\) \\
\hline 7445 \& \[
50
\] \& \(741526 \quad 140\) \& 7415643 \& ［4097 3400 \& HA1366 195p \& LM13600 \& \({ }^{\text {den }}\) \& \({ }^{65515}\) \& 93415 600p \& LC1488 \& 0．3－251314 \& 10．7MHz 150 p \\
\hline 744 \& \({ }_{40} 0\) \& \({ }^{741527}{ }^{168}\) \& \({ }^{74 L 5644}\) \& \({ }^{300}\) \& \({ }_{\text {H1L }}\) \& M51516L 5000 \& TDA1024 120 p \& 6821 120p \& 93425 600p \& MC1489 55p \& 74S262AN \& \begin{tabular}{l}
12.00 MHz \\
14.350 p \\
\hline 150
\end{tabular} \\
\hline 7448 \& 15 \& 74L530 150 \& 74L5668 120 \& 450 \& ICL7660 \({ }^{2} 2\) \& M83712 \& \& \({ }_{68829}^{6882}\) \& \& MC3419 98000 \& 10 \& \\
\hline 74 \& \({ }^{15 p}\) \& 74 \&  \& （ \(\begin{array}{ll}4502 \& 60 p \\ 4503 \& 50 p \\ 500\end{array}\) \&  \& \({ }_{\text {M }}^{\text {M } 373130}\) \& rDA 2002 V 3250 \& 68840 \& ROM \&  \& KEYBOARD \& \(14.756 \mathrm{MHz}_{250}\) \\
\hline \& \({ }^{150}\) \& 744533
741537 \& 74LS678 \& 4504 75 \& ICM \& MC1445 \& （tDA2006 3 300 \& \(\begin{array}{ll}6850 \\ 68850 \& 140{ }^{\text {c }} \\ 200 \mathrm{p}\end{array}\) \& Ms \&  \& ENCODER \& 15.000 MHz \\
\hline 7764 \& 50p \& 74153815 \& \(7415682{ }^{\text {400p }}\) \& \({ }^{350}\) \& \& \({ }^{\text {MC1458 }}\) \& \& 6852 370p \& \& \& \& \\
\hline \& 389 \& 74LS42 300 \& \(74 \mathrm{LS684} 4000\) \& \& \({ }^{\text {CLC7120 }}\) \& Mctas \& TL071／81 25p \& ， \& \& \&  \& \\
\hline 74 \& 220 \& \({ }^{741547}\) \& 74S SERIES \& \(1{ }^{4510}\) \& LC7130 325p \& MC1496 70 P \& rL07 \& \({ }^{68854} \quad 58\) \& \(745288{ }^{226 p}\) \& MC14412 900p \& \& \\
\hline \& \({ }^{25}\) \& \({ }^{7} 4\) \& \& \& LF347 160p \& MC3 \& T1074 1000 \& Pr \& \(\begin{array}{lll}745387 \\ 745871 \& 355\end{array}\) \& \& \& \\
\hline 7474
7474 \& 250 \& 74 L554 \& \(74502{ }^{\text {cop }}\) \& 4512 \&  \& \({ }_{\text {MC34 }}\) \& TL \& 8155 450p \& \begin{tabular}{lll}
745457 \\
74543 \\
\hline 8500 \\
\hline 850
\end{tabular} \& \& generators \& 19.968 MHz \\
\hline \& \& \& \({ }^{74504}{ }^{\text {che }}\) \& \({ }_{4515}{ }^{45124}\) \& \({ }^{\text {LfF356P }}\) \& MC3480 600 p \& Th \& \({ }^{8156}\) E5 \& 245474 \& \(75110 / 121600\) \& MC14411 700 p \& \[
20 .
\] \\
\hline \begin{tabular}{l}
7480 \\
7482 \\
\hline
\end{tabular} \& 500 \& 74LS \& \({ }_{7}^{745080} 8\) \& （ 4516 \& （lll \& \(\begin{array}{ll}\text { M150938 } \& \\ \text { ML920 } \\ \text { M00p }\end{array}\) \& TL \& \begin{tabular}{ll}
8205 \\
82225 \& \\
\hline \(160 p\)
\end{tabular} \& \(\begin{array}{ll}745570 \\ 745571 \& 650 p \\ 65500\end{array}\) \&  \& COM8116 800p \& \\
\hline \& \& 74 \& 74810 60p \& 45 \& LM10c 425 \& M 1571606200 \& ， \& 8216 \& 745573 950p \& \({ }_{751509}{ }^{140}{ }^{\text {P }}\) \& \& 26.690 MHz \\
\hline \& \& \& 74 \& \(4521 \quad 120 \mathrm{p}\) \& LM301A 2 \& \& UA2240 1500 \& \({ }^{8224}\) \& \& \({ }^{75154}\) \& UARTS \& 27.145 MHz \\
\hline \begin{tabular}{l}
7485 \\
7486 \\
\hline
\end{tabular} \& \({ }^{60 p}\) \& \& \({ }_{74530}{ }^{\text {745 }}\) \& \({ }^{4526}\)－\({ }^{\text {E5p }}\) \& LM310 \& Ne \& UAA \({ }^{\text {ULN2003 }}\) \& \({ }_{8228}\) \& EPROMs \&  \& AY－3．1015P \& \\
\hline 748 \& 210 p \&  \& \({ }^{74532}\) 7457 \({ }^{\text {90p }}\) \& 45 \& ［M318 150 \& NE556 \({ }^{\text {cesp }}\) \& ULN2004 55 \& 3243 3200 \& \& \({ }_{75361}{ }^{\text {150p }}\) \& \(3{ }^{\circ}\) \& \\
\hline \& 20 \& \({ }^{7415868}\) \& \({ }_{80} 0\) \& （ 4532 \& LM319 225 \& NE564 4200 \& ULN2068 250p \& \({ }^{8250}\) \&  \& \({ }^{75363}\) \& AY－5－10，3P \& \\
\hline \& 35 \& \& \& \& LM32 \& Ne56 \& ULN2802 \& 8251 \& \& \& \& \\
\hline 7492
7494 \& 2250 \& 744593 \& \({ }_{74566}\) \& （ 4536 \&  \& \begin{tabular}{ll} 
Ne566 \\
NE567 \& 1359 \\
140 \\
\hline
\end{tabular} \& UPC575
UPC592H
2000

200 \& $\begin{array}{ll}32535 & 3509 \\ 8250\end{array}$ \& 2564 \& 75453／4 720 \& ${ }^{\text {th8402 }}$ 450p \& （194H2 3000 <br>
\hline \& ${ }_{350}$ \& 74 \& \& \& LM339 \& Ne567 \& UPC1155H 275 \& 8256 \& 2708 \& 75491／2 70 p \& TR1602 300p \& 5．80 M <br>
\hline 7495 A \& 350 \& ${ }^{74 L 5966} \quad 50$ \& ${ }^{900}$ \& （4543 \& LM348 75p \& 375p \& Op \& 82575 \& 271 \& ${ }^{8726} \quad 1200$ \& \& <br>
\hline \& \& ${ }^{30}$ \& \& \& \& \& \& \& \& \& \& <br>
\hline 749 \& ${ }_{80}^{90}$ \& 7415112 \& 745132 \& 4556 \& VOLTAGE \& ULATORS \& ${ }_{655}$ \& ${ }_{8284}^{829} 4500$ \& \&  \& tiex Tol \& <br>

\hline 74107 \& $22^{2}$ \&  \& ${ }_{7}^{745133}$ \& － \& FiXED PL \& TIC \& 900 \& ${ }^{8288}$ f11 \& 321300 \& $$
81 L 595 \text { gop }
$$ \& pin $\quad \underset{\text { pin }}{\text { fin }}$ \& 5p <br>

\hline 74109

74110 \& 230 \& 745 \& ${ }_{7} 7451$ \& （ $\begin{array}{ll}45666 & 1700^{\prime} \\ 4568 & \\ 3000\end{array}$ \&  \& \& S0p \& ${ }^{\text {TM }}$ 899978 \& TMS2776 750 p \& $\begin{array}{ll}\text { 81LS96 } & \text { 90p } \\ \text { 81LS97 } & \text { 90p }\end{array}$ \& \& $$
\begin{aligned}
& 8 \text { way } \\
& \text { in way } \\
& \text { 90p } \\
& \hline 465 p
\end{aligned}
$$ <br>

\hline 74 \& $55 p$ \& 74L123 ${ }^{34}$ \& 745157 \& 4569 \& $6 \mathrm{~V} \quad 7806$ \& ${ }_{50 \mathrm{p}} 79065$ \& \& \& \& \& \& <br>

\hline \& $$
50
$$ \& \& 3 \& 1457230 \& BV 7808 \& 50 p 7908 600p \& ZN422 \& \& \& \& RE WRAP \& CK <br>

\hline 741 \& ${ }_{80} 8$ \& 74 LS126 250 \& ${ }^{745175} 30300$ \& －90p \& $\begin{array}{ll}12 \mathrm{~V} & 7812 \\ 158\end{array}$ \& ${ }^{50 \mathrm{p}} 79912 \mathrm{ll}$ \& ZN427E \& \& \& \& BYTEX \& <br>

\hline \& 500 \& ${ }^{744 S^{2} 1323}$ \& | 745188 |  |
| :--- | :--- |
| 745189 | 3500 |
| 350 |  | \& 4585 100p \& 18 V 7818 \&  \& ［N428E \& \& \& \& \& <br>

\hline 7412 \& \& ${ }^{74 \mathrm{LS136}}$ \& ${ }_{745194}{ }^{\text {3 }}$ \& \& $24 \mathrm{~V} \quad 782$ \& 50 p 7924 60p \& ZN1034E \& \& \& \& \& <br>
\hline 74122
74123 \& ${ }_{40 \mathrm{p}}^{40}$ \& ${ }^{\text {744 }}$ \& 745200

74500 \& ｜ll｜l｜l｜l｜ \&  \& ${ }_{30 \mathrm{p}}^{30 \mathrm{p}} 790505$ \& \begin{tabular}{lr}
ZN1040E \& 670p <br>
ZNA234 \& 850

\end{tabular} \& \& \& \& \[

22 pin 65
\] \&  <br>

\hline \& 340 \& \& ${ }_{745225}$ \& 150p \& gV 100 mA 78L08 \& \& \& \& \& \& \& <br>
\hline ${ }^{74126}$ \& \& ${ }_{7415147} 160{ }^{\text {cop }}$ \& $745241{ }_{400}^{40}$ \& ${ }^{180}$ \& 12 V 100 ma 78 L \& 30p 79L12 60p \& transistors \&  \& \& 2N3702／3 \& \& <br>
\hline 28 \& 38 \& ${ }^{74515148} 70$ \& $745250{ }^{70}$ \& ［ \& 15V 100 mA 7815 \& 30p 79L15 60p \& AD161／2 45 p \&  \&  \& 2N3794／5 \& 4041 \& PIASTIC <br>
\hline 74 \& 28 \& $\begin{array}{ll}744159 \\ 7415153 & 400 \\ 700\end{array}$ \& ${ }_{745262}$ \& 100 p \& \& \& BC10 \& ${ }_{\text {brx }} \times 89$ \& ${ }_{\text {HP35 }}$ \& 2 N 379617140 \& 40594 \& Lastic <br>
\hline 741 \& ${ }^{2000}$ \& 74． \& ${ }_{745287} 3$ \& ${ }^{2800}$ \& \& \& ${ }^{20}$ \& ${ }^{\text {BFFY0 }}$ \& \& 2N37739 \& \& $34400 V^{60 p}$ <br>

\hline 74 \& \&  \& | 745288 |  |
| :--- | :--- |
| 745333 | 3509 |
| 000 |  | \& 40174 \& \& \& 9 c \& BFY56 33p \& T1P41A \& 2 N 3819 \& \& 㖪 <br>

\hline 741 \& ${ }^{90 p}$ \& ${ }_{7415157}$ \& ${ }_{745374}{ }^{4000}$ \& 40175 \& M309\％1A 5 LV 100 p \& p 78HGKC 600p \& ${ }_{\text {BC／57／8 }}$ \& BFY90 ${ }^{\text {B0p }}$ \& ${ }_{\text {T1P42A }}$ \& （1） $\begin{array}{ll}\text { 2N3820 } \\ 2 \text { N3823 }\end{array}$ \& \& 4 <br>
\hline 74150 \& 50 \& 744L \& 745471 \& ${ }_{40244}^{40193} \begin{array}{rr}\text { 730 } \\ \text { 1800 }\end{array}$ \&  \& \％ 78 HOSCOC c50p \& ${ }^{\mathrm{BCC} 59} 5110$ \&  \& ${ }_{\text {TP42C }}$ \& （2N3833 \& DIODES \& ${ }^{35}$ <br>
\hline \％15 \& ${ }^{40}$ \& 74 \&  \& $40245 \quad 250 \mathrm{p}$ \& LM3137 T03 200 \& \％${ }^{\text {a }}$ \&  \& BU104 225 \& （11P540 \& 2N3902 \& \& ${ }_{124}{ }^{24} 500 \mathrm{~V}$ <br>
\hline \& \& 74.5 \& 14557 \& 40373 ${ }^{4800}$ \& LM3375 3.5258 \& P 79GuIC 225 p \& BC177／8 17 p \& \& T1P129 75p \& 2N3905／6 165 \& $8 \mathrm{Br} 36.300{ }^{20 \mathrm{p}}$ \& 16A 400V 1100 <br>
\hline 74 \& ${ }_{40}{ }^{\text {P }}$ \& ${ }^{74} 4$ \& $4000 \mathrm{CMO5}$ \& 14495 300p \& LM723 150mA \& 79HGKC \& ${ }^{8 C 1779}$ \& BU109 225p \& T1P122 \& ${ }^{2 N 4037} 655$ \& OA47 \& ${ }_{\text {T28000 }}$ <br>
\hline \& 400 \& ${ }_{74} 715165$ \& 保 \& 7000 \& adi 370 \& TL497 300 p \& ${ }_{\text {BC1 } 184}{ }^{\text {SCR }}$ \& \& ${ }_{\text {H1P147 }}$ \& ${ }^{2 N 4123 / 4} 827$ \& \& <br>
\hline 74159 \& ${ }_{750}$ \& 7415166 65p \& 12 p \& 2000 \& TLa94 400p \& Lm305A 250 p \& 30. \& Bu \& T1P2955 78p \& 2 Na \& \& HYRISTORS <br>
\hline \& \&  \& 4002 12 \& \％ \& 78805 \& pren \& ${ }^{\text {BC2212／3 }}$ \& $8{ }^{\text {8208 }}$ \& T1P4 \& $2{ }^{\text {N4427 }}$ \& OA202 \& <br>
\hline \& 48p \& 74 \& 4006 50p \& \& \& \& （enc \& ${ }^{\text {BU406 }} 145 \mathrm{p}$ \& H1593 \& ${ }^{2}$ \& －${ }_{\text {T }}$ \& <br>
\hline 741 \& 480 \& 744S173 700 \& $\begin{array}{ll}4007 & 18 p \\ 4008\end{array}$ \& 74S \& \& \& ${ }_{\text {BC327 }}$ \&  \& ${ }_{21 \times 300}$ \& （1） \& \& <br>
\hline \& 48 \& 74. \& ${ }_{4009}^{4008}$ \& ${ }^{74500}{ }^{\text {cosp }}$ \& OPTOELEC \& tronics \& вса37 16p \& ${ }^{5310}$ \& 452 45p \& 2N5172 ${ }^{\text {220 }}$ \& 1 N 40 \& <br>
\hline 74165 \& 48 p \& 74 \& $4010 \quad 24 \mathrm{p}$ \& ${ }^{7} 74508$ \& ${ }^{2} \mathbf{2} 5777$ \&  \& ${ }^{\text {BC338 }}$ \& м M802 ${ }_{\text {¢ } 4}$ \&  \& 2N519！90p \& 1 Na 003 \& C106 <br>
\hline \& 489 \&  \& 4011 14p \& 745 \& ${ }_{\text {ORP12 }}{ }_{\text {1200 }}^{\text {cen }}$ \&  \& BC477／8 30 \&  \& ${ }_{27 \times 504}$ \& （2N5194 \& 1N4006／7 7 p \& MCA <br>
\hline \& ${ }^{2750}$ \& 74L \&  \& 7745 \& \& Tl／31A $120{ }^{\text {a }}$ \& BC516／7 40p \& M 32955 \& 2TX552 55p \& ${ }_{\text {2N5 } 298}{ }^{\text {24，}}$ \& $1 \mathrm{~N} 5401 / 3 \mathrm{l}{ }^{14 \mathrm{P}}$ \& ${ }_{2}$ <br>
\hline 241 \& ${ }_{60}$ \& $\begin{array}{lll}7445199 & 45 p \\ 774159\end{array}$ \& ${ }_{4014}$ \&  \& \& T1481 \&  \&  \&  \& ${ }^{2 N 5401}$ 60p \& 1N540477 \& 2N4444 <br>
\hline \& \& 74.5 \& 4015 \& $765124{ }^{\text {300p }}$ \& \& TLL100 75p \& $cc$ \& MJE340 600 \& ${ }^{\text {VNV66AF }}$ \& 2N5457／8 \& \& ， <br>
\hline \& ${ }_{40} 5$ \& 7415194 3 35p \& ${ }_{4017}^{4016}$ \& ${ }^{745132}$ \& opto．iso \& Lators \& BC557kB 14p \& ${ }^{\text {MJEE2555 }}$ \& VN10KM 60p \& ${ }_{2} 2$ N5450 \& \& <br>
\hline \& 45p \& ${ }^{744} 195195$ \& 50 \& ${ }^{745138}$ \& \& \& ${ }^{8 C 5599 C}$－ 16 p \& MPFILIO2 40 P \& VN66 809 \& ${ }^{\text {2N5485 }}$ \& BRIDGE \& PCB <br>
\hline \& 80 \& ${ }^{7} 4$ \& 4019 25p \& ${ }^{745139} \quad 2250$ \& \& TK112 900 \& BCY7a
BCY71 \& MPFF103／4 ${ }^{30 \mathrm{P}}$ \&  \& ${ }^{2} \mathbf{N 5 8 7 5}$ \& RECTIFIERS \& mounting <br>
\hline 74179
74180 \& 80 \& ${ }_{7415221}{ }^{742}$ \& $\begin{array}{ll}4020 & 50 \\ 4021 & 50 \\ 40\end{array}$ \& ${ }^{745157}$ \& ${ }_{\text {MCS2400 }}$ \& \& 75 \& MPF105 ${ }^{\text {and }}$ \& 析 \& 2N \& \& <br>

\hline \& 115 \& ${ }^{74} 5240{ }^{\text {65 }}$ \& ［4022 | 4020 |
| :--- | :--- |
| 4020 |
| 50 | \& 745163 \& $1 \mathrm{LO} \mathbf{4}^{240}$ \& \& 400 \& ${ }^{\text {MP }}$ \& $3{ }^{3}$ \& ${ }^{2 N 6059}$ \&  \& RELAYS <br>

\hline 74182A \& S00 \& 74L5 \& $4023 \quad 16 \mathrm{p}$ \& ${ }^{7}$ \& LEDS \& $0.2{ }^{\prime \prime}$ \& 80139 400 \& MP \& 45 p \& 2NE107 \& \& <br>
\hline 74184 \& \& 7 \& 4024 32p \& 2451943 \& \& \& ${ }^{\text {BDO }} 40$ \& MPSA20 50p \& ${ }^{2 N 930}{ }^{\text {N }}$ \& 2N6247 190p \& IA G00V 30p \& <br>
\hline ${ }^{865}$ \& 500 \& ${ }_{7415244} 600$ \&  \& 745241 450p \& ${ }_{17132} 55$ \& T1L222 $\mathrm{Gr}^{\text {r }}$ \&  \& MPSA42 ${ }^{\text {M }}$ \&  \& 2N \& ${ }_{2}^{2 A}$ A 500 V \& ${ }^{24 V}$ <br>
\hline \& 2500 \& 745 \& $\begin{array}{ll}4027 & 24 p \\ 4029\end{array}$ \& \& 209 Rod 11 \& 228 \& ${ }^{80233}$ 75p \& MPSA56 \& ${ }^{2 N 1711}$ \& 2 SCl \& ${ }^{24} 400 \mathrm{~V}{ }^{35}$ \& Oil <br>
\hline \& 48 \& 744．5247 \& 4028 50p \& ECLs \& T12 \& Rectingular \&  \& MPSA70 50p \& ${ }_{2}^{2 N 2102}$ \& ${ }_{2 S \mathrm{SCl}}^{2060} 100 \mathrm{p}$ \& 3 A 200 V 60， \& 24 VD <br>
\hline 74191
74192 \& 4 \& ${ }^{74 \text { LS249 }}$ \& ${ }^{4029} 5$ \& \& til216 Red \& NSB \& ${ }_{80242} 60{ }^{\text {cop }}$ \& MPSA933 \& 2N2219a 250 \& ${ }^{2 S C 1307}{ }^{2 S 50 p}$ \& ${ }_{3 A}{ }^{\text {a }} 600 \mathrm{~V}$ \& 240 VAC 200 p <br>
\hline 193 \& ${ }_{48 p}$ \& 7415 \& ［4031 ${ }^{4030} 5$ \& MC4044 \& \& \& 边 \& M \& 2N2222A 250 \& ${ }_{2 \text { SC1969 }}$ \& ${ }_{4 A}^{4 A} 40$ \& <br>
\hline 74194 \& 48 \& 7415253 \& ${ }_{4032}$ \& MC10116 \& DISPLAYS \& TIL312／3 ${ }^{1000}$ \&  \& MPSU45 90p \& ${ }^{2 N 2369 A}$ 25p \& ${ }^{2 S C 2028} 950$ \& ${ }_{64} 50 \mathrm{~V}{ }^{\text {cop }}$ \& ${ }_{241}$ <br>
\hline \& ${ }^{48 p}$ \& ${ }^{7445258}$ \& ${ }^{4033} 1031250$ \& M $10231380{ }^{\text {a }}$ \& \& $\mathrm{TLL330}^{\text {che }} 140 \mathrm{p}$ \& ${ }_{8}^{80624}$ \& MPSU65 78p \& 2 \& ${ }^{2 \mathrm{SC} 2029}$ \& 6a 1000 \& 240 VAC 225 <br>
\hline \& ${ }_{480}^{489}$ \& 74LS259 \& ${ }_{4035}^{4034}$ \& COUNTERS \& DL707 Red 140 p \& 7750602009 \&  \& T1P29A \& 2N2904／5 250 \&  \& ${ }^{64} 400 \mathrm{~V}$ \& <br>
\hline 998 \& 485 \& 7415 \& ${ }_{4036}^{4035}$ \& \& FND357 120p \& DRIVERS \& ${ }_{\text {BF257／8 }}$ 32p \&  \& 2 N 2 \& 2sce \& \& <br>
\hline 199 \&  \& \& ${ }_{4038}$ \& \& \& \& BF337 30D \& ${ }^{1+1}$ \& 2N2907A 25p \& ${ }_{\text {3N128 }}^{23}$ \& 25 A 400 V 400 P \& RELAYS <br>
\hline \& ${ }_{700}^{550}$ \& 744LS273 \& 4040 ：${ }^{400}$ \& 72168 ${ }^{\text {c18 }}$ \& fNO507 90p \& 9370 300p \&  \& 111p \&  \& 3N140 120 p \& \& OOR <br>
\hline \& 70 P \& \& 4041 b0p \& \& MAN4640 200p \& \& \& ${ }_{\text {THP31C }}$ \& ${ }_{2}^{2 N 305354}$ \& 3N14） 1100 \& ENERS \& ETI <br>
\hline \& \& \& \& \& \& \& 20／1 250 \& T1P32C \& ${ }_{2 \times 3055}^{188 p}$ \& \& NER \& PROJECTS <br>

\hline \& \& \& \& \& \& \& （1896 \& | TIP33A | 70 p |
| :--- | :--- |
| TIP33C | 80 p | \&  \& $\begin{array}{ll}40290 \\ 40361 / 2 & 2800 \\ 75 p\end{array}$ \&  \& AILABLE <br>

\hline \& \& \& \& \& \& \& 278 \& \& $2 \mathrm{N3584} \quad 250 \mathrm{p}$ \& 40408 ${ }^{\text {400 }}$ \& \& Stock <br>
\hline \& \& \％ \& NL \& OAD， \& NDON NW10 \& 0 1E0 \& \& ASE AD \& 40p PGP 6 \& 15\％Vat \& xport no \& <br>
\hline \& PS \& T： 17 BU： \& \& \& \& \& \& \& \& \& \& <br>
\hline \& \& \& Ley road \& ，LoND \& NW10 \& \& \& Ver \& \& RD \& WE \& <br>
\hline \& \& （Tel： 0 \& 1500． 01 \& 1．450 6597．T \& 92 \& \& \& \& ACCESS C \& CARDS AC \& EPTED \& <br>
\hline \& \& \& \& \& \& \& \& \& PRICE L \& T ON REC \& \& <br>
\hline
\end{tabular}

## TECH TIPS



## Guitar Harmoniser

S.P. Giles, Edmonton

This is one for guitarists who cannot afford commercial units which cost at least $f 1000$ at the moment. Constructors who have built the CCD phaser will be familiar with the pitchchanging effect when it is set up in the vibrato mode, and must have noticed that the longer the delay, the greater the pitch change above and below the frequency of the input.

All that this circuit does is to silence the output for one half of the clock modulation oscillator's cycle. This is achieved using a 4416 quad CMOS switch, which is controlled by the square wave output of the clock modulation oscillator. This IC differs from the 4016 in that two switches will be on and two will be off even when the same control signal is applied to each switch. Depending on which way SW1 is connected, either the raised or the lowered frequency of the input will appear at the output, which can be

## CMOS Phaser

## S.P. Giles, Edmonton

This is an extension of the usual opamp phaser, which uses CMOS inverters instead. IC1a amplifies the input signal to compensate for some of the loss in gain through the four-stage allpass network formed by IC1b-1f and IC2a2 c . The resistance of the four resistors marked $\mathrm{R}_{\mathrm{X}}$ is altered by the enhancement FETs in IC3 and the changing voltage applied to their gates by slow oscillator IC2d,e as in the ETI audio phaser.

To set up, adjust RV2 for approximately the same level as at X , then adjust PR2 until the familiar phasing sound is heard with a smooth sweep. RV2 can then be adjusted for the best effect. These adjustments should be made with RV1 at a minimum; this is a feedback control which gives a deeper phasing effect. PR1 should be adjusted so that with RV1 full on, the feedback whistle just disappears.
adjusted by the rate control or by altering the delay of the TDA 1022 s.

There are many circuits available for TDA1022 clocks and filters so I have not bothered to include them here. Constructors must remember that there will be a slight tremulant effect as the signal in harmony with the input will only be present for the time that the clock modulation oscillator is high or low.

## Mains Remote <br> Speaker

G.M. Perry, West Kilbride

I have used the idea you recently published as the 'Ear-stretcher' com-
munication system to produce an extension speaker. The receiver unit (slightly modified) has been built into a small speaker/cabinet unit, while the transmitter is connected to the hi-fi via a 20 dB amp and mixer. (This combines the stereo channels into a mono signal). The result is a portable speaker

which can be plugged into any mains socket in the neighbourhood and produce an acceptable audio quality from the hi-fi system. In three weeks I've been asked to build four units!

The modifications are as follows. The receiver is built as in the Earstretcher except for the following; the mains input is switched and RV1 is a $220 \mathrm{k} \log$ pot (not a switched pot); the 'mure' is wired off; $\mathrm{C} 13,14$ are 100 n ; C 15 is omitted; C 19 is 3 n 3 . In the transmitter, C6, 7, IC3 and RV1 are not used and the circuit shown here is used to provide the signal input (instead of the microphone unit). This is a mixer with a high impedance input followed by a 20 dB amp. It is important to connect the positive supply of the mixer amp to the regulated side of the transmitter power supply. Screened cable has been used for all audio connections and an operating frequency of 250 kHz was chosen to minimise mains-borne RFI on Radio 4.

 Number-guessing

I wrote this program for the Casio FX-501P and FX-502P, but it could easily be adapted for other programmables. The object is to guess a threecaular To start the gane press INV P8. The display will show the number 15 , which is the number of attempts you have. To make a guess, enter the number followed by EXE. One of two numbers will come up on the display; - 1 means the guess was too low, while 2 means the guess was too high. If you解 number of attempts you made will isplayed. The changed to give a different number of attempts.

CODE
INV P9
INV RAN LOC 2

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Drawings should be as clear as possible and the text should be typed. Text and drawings must be on separate sheets. Circuits must not be subject to copyright. Items for consideration should be sent to ETI TECH-TIPS, Electronics Today

International,
145 Charing Cross Road, London WC2H 0EE.

## Intelligent Alarm Switch

S. S. Norman, Sunbury-On-Thames,

This simple circuit is built around a TCA965 window discriminator. It is a device which is given a predefined "voltage window" set by RV1 (lower limit) and RV2 (upper limit). The four outputs, which are normally high, indicate whether the input voltage (pin 8) is inside, outside, above or below the "window". Figures 1 and 2 show two possible circuits for normally open or normally closed switches.

The resistors marked * are mounted inside or fixed with epoxy to the switch to be "defended". RV1 and RV2 are set to form a window around the voltage at point $Z$. Once set, any attempt to cut the wires to the switch or short the switch out in an attempt to bypass it will pull the voltage at point $Z$ out past the window and the output to the alarm will go high. Needless to say the switch will also activate the alarm in the normal way.

The smaller the window about point $Z$ the more sensitive the circuit becomes. To set up the circuit, measure

Fig. 1


Fig. 2
the voltage at point $Z$ (with the circuit in its standby condition). Then adjust RV1 to set the voltage at point X to be

OV5 lower than point $Z$. Now adjust RV2 to set voltage at point $Y$ to be 0 V 5 higher than point $Z$.

## Current Saving Modifications For The Musical Doorbell

William Leung, Harlow

In the original Musical Doorbell circuit (ETI December '80) IC1 and IC2 can
be replaced by a single CMOS IC. This chip has four NAND Schmitt triggers. The bistable formed around IC1a,b is different from that of the original, in that it requires a negative trigger pulse. This explains why R1 and PB1 are transposed, the presence of IC1c as an inverter, and R4 being connected to the output of IC1a rather than IC1b. Next comes the astable; this is only gated into operation when IC1 pin 8 goes high.

One further current-saving modification which I have yet to try out is to replace C7, R13 and the speaker with a piezo-electric transducer (the PB-2720). To go even further, IC4 can be an ICM7555 when using TX1, although it must be stressed that TX1 only has a range between 1 kHz and 7 kHz , so R6-R10 will need some adjustment ie they should be reduced.




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# KITCHEN SCALES PaRt 2 

 The final part of this out-of-the-ordinary,state-of-the-art, nifty little gadget
describes the construction and calibration
procedures. Design and development by
Rory Holmes.

Assemble the PCB in the usual fashion, noting the IC orientation, and the polarity of ZD1 and the tantalum capacitors. Also check the BC184L pinouts; these often cause confusion. Twelve Veropins should be inserted at the points marked for external connections. Another point to watch is the hole marked beneath preset PR1; this should be drilled out to 3 mm diameter before mounting the preset, thus allowing its adjustment from either side of the board. Likewise, a 3 mm hole drilled on the other centre allows a secure 6BA mounting bolt for the board.

When complete, the board may be initially tested by inserting all the ICs into their sockets and connecting a 9 V PP7 battery to the supply terminals as indicated. If a scope is available, the


Fig. 1 Coil winding details.
digital sine wave approximation should be observed at the junction of R14 and C6; it could also be checked with a crystal earpiece, when a high pitched tone of 10 kHz should be heard. The reference supply voltage can be measured with a multi-meter across the wire link and a 0 V terminal. It should be in the region of 5 V if all is well, the exact value being unimportant. At this stage the transducer should be built and wired up before further testing of the PCB.

## Winding You Up

The LVDT is wound using 32 swg enamelled copper wire on a piece of 20 mm diameter plastic tubing of the type used for electrical conduit, and available from DIY shops. Any similar piece of tubing will suffice since the dimensions are not critical. Figure 1 shows the winding arrangements. Two separate secondaries are wound either side of the central primary winding. All the windings consist of 100 turns wound in the same direction in flat layers; four layers of 25 turns for each secondary, and two layers for the primary. The accuracy and linearity of the LDVT transducer depends upon the two secondaries being as similar as possible and symmetrically positioned about the primary winding. Care should thus be take to ensure the layers are evenly wound and tightly packed. Superglue may be used to retain each layer as it is wound. After completing the windings and finishing with a liberal coat of glue the two secondaries are then wired in series opposition to form one coil by connecting together the end of each winding.

The LVDT should now be wired up to the PCB using screened leads as illustrated on the overlay diagram. On
our prototype assembly we used a tour way 'Molex' PCB plug and socket for this connection since the transducer assembly could then be conveniently plugged in.

Figure 2 shows how the LVDT is mounted to measure displacement. As described last month the mechanics of an ordinary pointer scale are utilised to provide the linear displacement with weight via the in-built spring and pivot.

For our prototype we used a small low cost Salter scale which incorporated a ball-race slide mechanism to support the weighing pan. Practically any type of scales could be converted to a digital readout, provided these is room to mount the LVDT and its associated driver electronics.

## Scaling The Heights

Obviously, the more precise the mechanics of the original scale, the greater the degree of accuracy that can finally be achieved with the electronic transducer. The principle is to attach the main coil to a fixed part of the scale while the ferrite core is attached via some rigid element to the weighing pan movement, such that as weight is put on the scale the core moves linearly along its axis into the coil former.

In our prototype the two steel plates of the slide were used to support the transducer as represented in the diagram. Two pieces of PCB material fixed with epoxy act as brackets for the coil former and ferrite core

The mounting arrangement is not too critical but the following points should be observed. The coil must not be too close to steel or other magnetic material and likewise the ferrite core mounting should be non-magnetic and non-conductive. Remember to allow sufficient leeway on the ferrite mounting


The scale mechanics with the LVDT added. Compare with Fig. 2.


Fig. 2 An artist's impression of the sensor to help with construction.


Fig. 3 The (corrected) wiring diagram.
tor the tull displacement (about 1 cm ). The ferrite core must be central in the tube, with the axis of both coil and core parallel to the direction of weight displacement. Sufficient rigidity can be achieved using epoxy glue on the transducer, but initially the ferrite core should only be secured to its bracket with tight rubber bands until the calibration procedure.

Having completed the transducer the entire unit can now be tested by wiring up to the LCD meter-module. Wire up the module according to the connections shown in Fig 3 (this has been reprinted due to an error in last month's diagram).

The input voltage at point $B$ should then be connected to the corresponding point on the PCB; point A temporarily connects to the 2 V 5 reference terminal. After connecting the DVM supply rails to the 9 V terminals on the PCB, power can be switched on. When the ferrite core is near the middle of the coil the meter should be close to 0 V and will indicate + or - readings as the core is

## BUYLINES

The bandgap reference diode ZN423 is available from most semiconductor suppliers as are all the other more familiar semiconductors. Ferrite rods and copper wire can be supplied by Watford Electronics and 10 turn wirewound potentiometers are available from Henry's Radio.

The most expensive item in this project is the very neat LCD panel meter, a state-of-the-art CMOS module available from Verospeed Ltd (known as the DPM200, order ref. 89-25453C).

Suitable mechanical scales are available from most large department stores from about $£ 5$ upwards. The type used on our prototype conversion was a small Salter scale with a ball-race slide mechanism . (around £6). The PCB Service advert is on page 69.

Alternatively, for the mechanically ingenious with a bent to experiment, a large selection of springs can be obtained from Proops of Tottenham Court Road for about $£ 1$ !
moved to either side of the null position. The 100 mV sine wave across the primary coil can be observed on a scope along with the other waveforms illustrated last month. If all is well, the electronics can be assembled inside the scale. Figure 5 shows how we arranged the various components to fit into the existing scale box. The back of the case has now become the front to allow room for the LCD display! The 10 turn potentiometer, RV1, should also be connected up at this stage, along with the on/off switch, so completing the interwiring.

## Calibration

Once you are satisfied with your mechanical arrangement for mounting the transducer and associated electronics, the scale should be calibrated using standard or known weights. First, the offset voltage input to the DVM module, marked as ' A ' on the wiring diagram, should be temporarily connected to the 2V5 reference terminal shown on the PCB overlay. The preset PR1 should be set at roughly half travel, and the scale loaded up with about 1 kg . After switching on the supply, the ferrite core should be adjusted relative to the coil until it's approximately in the middle at the null output position (this corresponds to half scale deflection). As the null position is approached the DVM will accordingly decrease to zero reading. The ferrite core should now be fixed permanently to its mounting plate using epoxy and allowed to set. When set, the DVM reading must be brought exactly to zero by the addition of small increments of weight, sugar or salt being ideal. The known weight, which can be anywhere between $1 / 2$ and 1 kg , should be added to the scale pan, and PR1 adjusted until this weight is shown on the LCD display

## PROJECT : Scales Part 2



## PARTS LIST

| Resistors (all $1 / 4 \mathrm{~W}, 5 \%$ ) |  |
| :---: | :---: |
| R1, 11, 13 | 1 k 0 |
| R2 | 2 k 7 |
| R3 | 27 k |
| R4,28 | 100k |
| R5,8 | 33 k |
| R6,7,16 | 22k |
| R9,12,17,18, |  |
| 19,20,22,24 | 10k |
| R10 | 220k |
| R14 | 68 k |
| R15 | 5k6 |
| R21,25 | 1 ks |
| R23 | 4 4 7 |
| R26,27 | 270k |
| Potentiometers |  |
|  | 47k 10 turn wirewound potentiometer |
|  | 470k miniature horizontal preset |
| Capacitors |  |
| C1,4,10 | 22 u 16 V tantalum |
| C 2 | 220 p polystyrene |
| C3,7 | 10 n ceramic |
| C5 | 68 n ceramic |
| C6 | 2 n 2 ceramic |
| C8,9 | 1 n 5 polystyrene |
| C11,12 | 100 n polycarbonate |
| C13 | 220 u 16 V electrolytic |
| Semiconductors |  |
| ICI | LM324 |
| IC2 | 4018B |
| IC3 | 4093 B |
| IC4 | 4066 B |
| Q1 | BC184L |
| D1 | ZN423 |
| ZD1 | 2V7 400 mW zener diode |
| Miscellaneous |  |
| LVDT (see t scales (see B panel meter | ext); PCB (see Buylines); uylines); $3^{1 / 2}$ digit LCD type DPM 200 (see |

Potentiometers


Capacitors


Semiconductors


## Miscellaneous

LVDT (see text); PCB (see Buylines); scales (see Buylines); $31 / 2$ digit LCD panel meter type DPM 200 (see Buylines)

An internal view showing the arrangement of the boards.
(turning PR1 clockwise increases the reading).

Now remove the weight to check that the reading returns to zero, and adjust PR1 accordingly (a few adjustments to PR1 may be necessary to set the correct reading for the known weight).

Finally, the offset input ' A ' can be disconnected from the 2 V 5 reference and wired to the slider of RV1. Rotating RV 1 will alter the reading and the meter can now be easily zeroed for any weight measured, including the empty scale pan. You may now proceed to calibrate the larder.


The mechanics, seen from above.


ETI
Fig. 5 Artist's impression of the 'view from the top'.



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# CONFIGURATIONS 

Not ETI's answer to James Burke but a new series aimed at the designer. Ian Sinclair will be looking at some of the basic workaday circuits that often get eclipsed by the more glamorous ICs, showing you how and why they work and how and why to use them. We kick off this month with common-emitter transistor bias.

Configurations is a new series which aims to provide you with fundamental circuit design data for a number of the most commonly used circuit blocks. A very large amount of circuit work concerns these standard arrangements, so that by gathering your pages of Configurations each month, you will be able to build up a complete designer's handbook of circuits and their design data. We're starting this month with the most fundamental of all - biasing and calculating gain and bandwidth of the single-stage common-emitter amplifier, using a silicon transistor with a resistive load.

(a) TO FIND A VALUE FOR $\mathrm{R}_{\mathrm{b}}$, GIVEN A DESIRED

VALUE OF $V_{C}$ :

$$
\begin{aligned}
& R_{b}=\frac{R_{L} h R_{L} \cdot h_{f e} \cdot\left(V_{C C}-0.6\right)}{V_{C C}-V_{C}} \\
& \tilde{R}_{L} A N D R_{b} \mid N \text { KILOHMS }
\end{aligned}
$$

(b) TO FINO WHAT VALUE OF $V_{C}$ WILL BE CAUSED BY A GIVEN BIAS RESISTOR:
$v_{C}=\frac{v_{c c} \cdot R_{b}-R_{L} \cdot h_{f e}\left(v_{c C} \cdots 0.6\right)}{R_{b}}$
$R_{L}$ AND $R_{b}$ IN KILOHMS

Fig. 1 Simple singleresistor bias circuit. The value of resistance depends critically on the value of $h_{\mathrm{fe}}$ for the transistor.

The simplest bias circuit, of course, is that of Fig.1, using a single bias resistor connected between the base and the supply positive. We're not going to spend much time on this one, because it's not a very good bias method from any point of view. The reason is that the resistor value has to be spot on for this methodto work, and you have to know the current gain ( $\mathrm{h}_{\mathrm{f}}$ ) value for that particular transistor (not just the average for the type) to a fair degree of accuracy. If you need to use that method and have a box of $1 \%$ tolerance resistors handy, then the design data is illustrated in Fig. 1. One of the few things that can be said for the circuit is that a high input resistance is attainable, but more on that subject later.

## A Favourable Bias

A much more practical bias method is illustrated in Fig. 2. This makes use of DC shunt feedback between the collector and the base of the transistor, and is less likely to be upset by the changes that occur in the characteristics of the transistor as it heats up. You still have to know the $h_{t}$ value for the transistor, but the collector voltage won't be so far out if you just use an average value for the type and it happens that the one you're using is at one end of the range of values. The formula, like the previous one, assumes that the base-to-emitter voltage when the transistor is conducting will be 0 V 6 and since this is the quantity that changes most as a silicon transistor heats up, it's worth while taking a look at how this bias method is affected.

(a) TO FIND A VALUE FOR $R_{b}$, GIVEN A DESIRED VALUE OF $V_{C^{z}}$

```
R
RL}AND R R IN KILOHMS
EXAMPLE: IF R 
R
(b) TO FIND A VALUE FOR V}\mp@subsup{V}{C}{}\mathrm{ , GIVEN R}\mp@subsup{R}{b}{}\mathrm{ :
V
```

Fig. 2 Shuntfeedback bias. The value of collector voltage is less dependent on the $\mathrm{h}_{\mathrm{fe}}$ value. Note the units, with all resistances in kilohms.

Figure 3 shows two calculations of collector voltage, both assuming a supply voltage ( $\mathrm{V}_{\mathrm{cc}}$ ) of +9 V , load resistor of $2 \mathrm{k} 2, \mathrm{~h}_{\text {te }}$ value of 100 , and bias resistor $R_{b}$ of 88 . However, one uses $0 V 6$ as the $\mathrm{V}_{\text {be }}$ figure and the other uses 0 V 5 . The difference in the collector voltage is negligible, which points to this method of bias as being a very useful one when you are worried about the effect of temperature changes on the performance of the transistor.

```
ASSUME IN BOTH CASES THAT R R
```



```
WHEN V be }=0\mathrm{ V5, V V
DIFFERENCE IN V}\mp@subsup{V}{C}{}=70\textrm{mV
```

Fig. 3 Effect of temperature. The $V_{\text {be }}$ (assumed 0 V 6 for a silicon transistor) decreases as the temperature rises. The calculations show that the collector voltage value is hardly affected.

The circuit uses feedback, of course, and unless something is done to remove the feedback of $A C$, the gain of the stage and its input resistance will be reduced. The reduction in gain isn't serious for most circuits, but the input resistance problem can be more serious - it's detailed later in this article. Both can be tackled if AC is removed from the feedback path by splitting the bias resistor into two parts and decoupling it, as shown in Fig. 4.


Fig. 4 Removing AC feedback by splitting the bias resistor into two sections and decoupling.

## An Arrangement With Potential

The most-extensively used of all bias methods is our old friend in Fig. 5, which uses a potential divider to provide a constant voltage (we hope) at the base of the transistor, and DC feedback (series feedback this time) through the emitter resistor to stabilise the bias. The notable thing about the formula is that $\mathrm{h}_{\mathrm{fe}}$ doesn't appear anywhere in it, so that the bias should not be affected by the value of $\mathrm{h}_{\mathrm{f}}$. This means that the circuit is very tolerant of wide ranges of $h_{\mathrm{fe}}$ values, providing the base current of the transistor is not so large that it disturbs the base bias voltage set by the potential divider. As a rule of thumb, if the current flowing through R 1 and R 2 (equal to $\mathrm{V}_{\mathrm{cc}} /(\mathrm{R} 1+\mathrm{R} 2)$ ) is something like 100 times the base current of the transistor, then the circuit will work exactly as per design, and any transistor whose base current is within limits can be used with the same bias components. If the base current of the transistor is far from negligible then complications arise, and it's easier just to use lower values of R1 and R2 - but for the effect on input resistance, see later. For voltage amplifier stages where the collector current is only about 1 mA , values like 6 k 8 and 1 k 5 on a 9 V supply will suit the circuit very nicely.


$$
\begin{aligned}
& \text { (a) TO FIND R } \mathrm{R}_{8} \text { FOR A DESIRED } \mathrm{V}_{\mathrm{C}} \text { : } \\
& R_{B}=\frac{R_{L} \cdot\left(\frac{V_{C C} \cdot R_{2}}{R 1+R_{2}}\right)-0.6}{V_{C C}-V_{C}} \\
& \text { (b) TO FIND } V_{C} \text { FOR A GIVEN } R_{s} \text { : } \\
& v_{C}=v_{C C}-\frac{R_{L} \cdot\left(\frac{V_{C C} \cdot R_{2}}{R 1+R_{2}}\right)-0.6}{R_{B}}
\end{aligned}
$$

Fig. 5 The potential-divider bias method. This is particularly useful for mass-produced circuits, because bias does not depend on $\mathrm{h}_{\mathrm{fe}}$ values.

## Decoupling Is De Problem

One disadvantage of the circuit is that there's an emitter DC voltage so that the available voltage swing at the collector is correspondingly reduced. The other point, which is important where space is limited, is that decoupling of the emitter resistor is essential. Without decoupling the gain is low; it's given by $\mathrm{R}_{\mathrm{L}} / \mathrm{R}_{e}$ and will be around two to six times for the kind of values you are likely to end up with in a practical circuit. The decoupling capacitor operates at low voltage, so that a 3 V or 6 V type is normally adequate, but its value has to be large to avoid a noticeable loss of gain at low frequencies. It certainly isn't enough to have the reactance of the capacitor equal to the resistance value of $R_{e}$ at the lowest frequency for which the amplifier is intended to be used, because if you make this assumption for each coupling and decoupling time constant, you'll end up with practically no gain at that frequency. Aim for a capacitor reactance of about one fifth of the emitter resistance value at the lowest frequency you intend to use and the results will be more acceptable. With C in microfarads and $\mathrm{R}_{\mathrm{e}}$ in kilohms, this means a value given by the equation

$$
\mathrm{C}=\frac{5000}{2 \pi \mathrm{f} \cdot \mathrm{R}_{\mathrm{e}}}
$$

and for a 390 ohm emitter resistor, this indicates a capacitor value of around 50 uF for a 40 Hz breakpoint. Even at 3 V working, this is going to be a component that will be larger than the resistors or the transistor.

> IF $h_{i e}=$ INPUT RESISTANCE IN KILOHMS, I $\mathrm{I}=$ STEADY COLLECTOR CURRENT IN MILLIAMPS, AND $h_{\mathrm{fe}}=$ VALUE OF CURRENT GAIN, THEN $$
h_{\text {ie }}=\frac{h_{\mathrm{fe}}}{40 . i_{\mathrm{C}}}
$$ EXAMPLE: IF $\mathrm{h}_{\mathrm{fe}}=400$ AND $\mathrm{I}_{\mathrm{C}}=1 \mathrm{~mA}$, THEN $\mathrm{h}_{\mathrm{ie}}=\frac{400}{40 \times 1}=10 \mathrm{k}$

Fig. 6 Transistor input resistance, $\mathrm{h}_{\mathrm{ie}}$. Note this is for the transistor only, and assumes zero-signal conditions.

## You Know My Resistance Is Low

The input resistance of an amplifying stage is, as the name suggests, the ratio of input voltage to input current for an AC signal at a frequency in the middle of the bandwidth. The input resistance of a transistor is not constant, but if we take the value which it has at the setting of the bias current, with no signal, than this is a reasonable average to take for small signal inputs - small meaning millivolts. The value is calculated as shown in Fig. 6, and it depends on the $\mathrm{h}_{\mathrm{fe}}$ value and the bias current. In general, using transistors with high $\mathrm{h}_{\mathrm{fe}}$ values operated at low collector currents will give the highest input resistance values for the transistor, but you can usually assume values in the region of 1 k 0 to 10 k .

These are just input resistance figures for the transistor itself, however, and the total input resistance will be affected by the bias components. When we use the potential divider bias circuit, for example, both R1 and R2 (in Fig. 5) are connected between the base and a line which is at $0 \mathrm{~V}(\mathrm{AC})$. How so, you ask? Well, as far as AC voltage is concerned, the supply positive line is as much of an earth as the genuine earth line, since they are connected to each other by a whopping great electrolytic in the power supply circuit. Hence all of these bias resistors are in parallel across the base-to-earth path, considerably lowering the input resistance (Fig. 7). If you think that the shunt feedback circuit of Fig. 2 is better then think again, because the collector end of the bias resistor is connected to a voltage which is in antiphase to (and of much greater amplitude than) the base voltage, so it behaves as if its value were $R_{b} / G$ connected to earth. $G$ is the voltage gain of the stage, so that if $R_{b}=88 \mathrm{k}$ and $G=50$, then the bias resistor is effectively 1 k 76 in parallel with the input resistance of the transistor itself.

$1 / R_{\text {IN }}=1 / 5+1 / 1.5+1 / 6.8$ (ALL RESISTANCES IN KILOHMS), SO
$\mathrm{R}_{\text {IN }}=0.986 \mathrm{k}=986 \mathrm{R}$ WHERE $\mathrm{R}_{\text {IN }}$ IS TOTAL INPUT RESISTANCE
Fig. 7 The effect of bias components and $\mathbf{h}_{\text {ie }}$ on total input resistance.

## Gainful Employment

The output resistance of a single transistor amplifier consists of the output resistance of the transistor itself, usually around 30 k , in parallel with the load resistor. Since load resistor values are usually of the order of 1 k 0 to 10 k , this in practice means that we can use the load resistor value as the value for output resistance when we are dealing with resistor-capacitor coupled stages.

The crunch comes when we want to find what the gain of an amplifying stage will be. For a silicon transistor which has enough $\mathrm{h}_{\mathrm{fe}}$ to class it as being in the land of the living, the maximum voltage gain is given by $40 \times \mathrm{V}_{\mathrm{RL}}$, where $\mathrm{V}_{\mathrm{RL}}$ is the voltage across the load resistor when no signal is applied - the bias voltage in other words across $\mathrm{R}_{\mathrm{L}}$. For example, if you are using a transistor with 4 V 5 across the load resistor, then the maximum gain is 40 x 4.5, which is 180 times (we showed how to derive this figure in 'Gm Revisited', April 79), and that's the value which can be
measured if you use a low impedance signal generator, a very small signal amplitude, and a high-impedance oscilloscope to measure the output.

Practical circuits, however, use higher-resistance devices as signal sources and lower resistance devices as signal loads, so that the gain when we take into account the potential-dividing effect of all these loss-makers is a lot less. For example, if we imagine our transistor stage to be fed with a signal from another stage with an output resistance of 2 k 2 and feeding into a stage with input resistance of 1 k 0 (and with these same values itself) then its gain (Fig. 8) will be a miserable 17.5 times. It's not the gain of the transistor which has fallen, notice; it's the attenuation caused by the potential dividers which is dissipating the signal. The moral is that input and output resistances are important when you are aiming for maximum gain, and that everything you can do to raise input resistance and reduce output resistance can be useful.


IF TRANSISTOR GAIN IS 180, THEN SIGNAL INTO TRANSISTOR $=\frac{V_{I N} \times 1 \mathrm{kO}}{3 \mathrm{k} 3}$
AND SIGNAL OUT $=180 \times \frac{V_{\text {IN }} \times 1 \mathrm{kO}}{3 \mathrm{k} 3}$ SOTHAT $V_{\text {OUT }}=180 \times \frac{V_{\text {IN }} \times 1}{3.3} \times \frac{1}{3.3}$
$=17.5 \mathrm{~V}_{1 \mathrm{~N}}$
Fig. 8 The effect of input and output resistances in forming potential divider circuits with the internal resistances of source and load.


LOW-FREQUENCY GAIN IS 3dB DOWN ON MIDBAND GAIN WHEN $\frac{1000}{2 \pi \cdot \mathrm{I} . \mathrm{C}}=\mathrm{R}_{\text {IN }} \quad$ (C IN MICROFARADS R IN KILOHMS) OR $\mathrm{t}=1000$ (f IN HERTZ)
high-Frequency gain is 3dB down on midband gain when
$f=\frac{1000}{2 \pi \cdot A_{L} \cdot C_{S}} \quad \begin{gathered}\text { (C) } C_{S} \text { IN PICOFARADS, } R_{L} \text { IN KILOHMS } \\ t \text { IN MEGAHERTZ) }\end{gathered}$

Fig. 9 The time constants which affect bandwidth for a single stage.
Note the different units for the two equations.

## Strike Up The Bandwidth

The bandwidth of an amplifier stage is defined as the range of frequencies over which the gain does not drop 3 dB below its midband value. For a simple amplifier stage, the limits of bandwidth are set by the time constants of the coupling and emitterdecoupling capacitors at the low frequencies, and by the effects of stray capacitance at the high frequencies - Fig. 9 shows the details. Most modern transistors have good high-frequency gain and since stray capacitance can be made small with modern circuit layouts, frequencies into the many megahertz range can be expected. This is much more than is necessary (or desirable) in many cases, and it's a wise precaution to trim the bandwidth for the purpose you need. This can be done by introducing a time constant into the feedback network of a simple filter.

All of which brings us inexorably to the subject of feedback, and that's where we'll start next month, when we'll be looking at feedback pair circuits, their biasing and their gain.


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TECHNICAL DETAILS
The basic function of a spark ignition system is often lost among claims or longer 'burn times' and other marketing fantasies. It is only necessary o consider that, even in a small engine, the burning fuel releases over 5000 times the energy of the spark, to realise that the spark is only a trigger for the combustion. Once the fuel is ignited the spark is insignificant and has no effect on the rate of combustion. The essential function of the park is to start that combustion as quickly as possible and that requires a high power spark.

The traditional capacitive discharge system has this high power spark but, due to it's very short spark duration and consequential low spark energy, is incompatible with the weak air/fuel mixtures used in modern cars. Because of this most manufacturers have abandoned capacitive discharge in favour of the cheaper inductive system with it's low power but very long duration spark which guarantees that sooner or later the fue will ignite. However, a spark lasting $2000 \mu \mathrm{~S}$ at 2000 rev/min. spans 24 degrees and 'later' could mean the actual fuel ignition point is retarded by this amount.

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TYPICAL SPECIFICATION

SPARK POWER (PEAK)
SPARK ENERGY
(STORED ENERGY)
SPARK DURATION
OUTPUT VOLTAGE (LOAD 50pF EQUIVALENT TO CLEAN PLUGS)

TOTA
ENERGY ORDINARY DISCHARGE DISCHARGE
$140 \mathrm{~W} \quad 90 \mathrm{~W}$
$36 \mathrm{~mJ} \quad 10 \mathrm{~m}$
$135 \mathrm{~mJ} \quad 65 \mathrm{~mJ}$
$500 \mu \mathrm{~S} \quad 160 \mu \mathrm{~S}$
$38 \mathrm{KV} \quad 26 \mathrm{KV}$
OUTPUT VOLTAGE (LOAD 50pF + $500 \mathrm{~K} \Omega$ EQUIVALENT TO DIRTY PLUGS)

26 KV
17 KV
VOLTAGE RISE TIME TO 20 KV (Load 50pF)
$25 \mu \mathrm{~S} \quad 30 \mu \mathrm{~S}$

TOTAL ENERGY DISCHARGE should not be confused with low power inductive systems or hybrid so called reactive systems.

# MICROTUTOR PART 1 

# BASIC, Pascal and the like are OK but if you want to get the most out of your micro then machine code is where it's at. This machine code tutor will help you throw off your chains; you have nothing to lose but your SYNTAX ERRORS. Design and development by Tangerine Computer Systems. 

Real computing was able to escape from the lofty realms of the mainframe and into the hands of the layman because of two major developments. The first was when large-scale integration techniques enabled the production of small, versatile microprocessor chips which were adapted into small, relatively low-cost microcomputers. (The microprocessor was originally conceived for use in industrial machine control.) The second was the invention of the BASIC computing language, which allowed the complete beginner to write working computer programs easily and without any knowledge of the system hardware he was working on

Unfortunately such ease of use can only be obtained by means of a compromise, and the major drawback of the average mictocomputer is speed - or rather lack of it. BASIC is painfully slow when compared to the speed of operation of the microprocessor, because each BASIC statement requires a series of machine code subroutines to be executed. Obviously better use can be made of the system hardware if programs are written directly in the language of the microprocessor - machine code. Direct access to the processor means access to swift, versatile and efficient programming.

All Systems Go Consequently some of the most popular
micro systems haven't had BASIC as a language at all! Typical products include KIM, SYM, the latelamented MK14 and the AIM 65, still a well-known 6502 machine code development system. And now there's the ETI Microtutor, a project we're hoping will coax more of our readers away from the security of BASIC and into machine code, the real stuff of microcomputing.

The Microtutor has been designed for us by Tangerine Computer Systems, who were responsible for the highly popular Space Invasion game we published in November 1980. The monitor program for the system is based on TANBUG, as used in the Microtan 65 computer from the same company; this is a remarkably powerful monitor with many useful programming commands available to make machine code easier to manipulate. The hardware is designed around the 6503, a member of the 6502 family with the same instruction set but an address range of only 4 K as opposed to the more usual 64 K . Thus the microprocessor is more compact
(only 28 pins instead of 40), but any software written for it will also run on the Microtan 65. Furthermore, once you'te familiar with the instruction set of the 6500 family you should be able to write machine code programs for home computers based on the 6502 such as the PET, Acorn System 1. Acorn Atom, Superboard, UK101, Apple, VIC and the BBC machine, which should give you plenty of scope! (Indeed, the PET is designed so that the entire system can be reconfigured from software, but you'll have to become pretty good to attempt that!)

Give Us The Tool
The Microtutor is a very sophisticated and professional-looking piece of equipment. The hex keypad is mounted directly on the PCB, as are the power supply regulator, cassette interface, and a VDU with UHF output on channel 36 for direct connection to a domestic TV set (one up on the AIM 65!). The PCB is incredibly compact and a masterpiece of design, as you can see from the photographs.

The only external equipment required is a battery charger type power supply (supplied with the kit from Tangerine), and a domestic TV and cassette recorder for storing your programs (not supplied with the kit!). In the interests of economy of design and cost, the Microtutor has no


Fig. 1 Component overlay for the Microtutor. Note that all the ICs have pin 1 pointing upwards.
graphics and the ASCII set repeats through the entire range of 256 character codes. Only upper case is available (see Table 1).

Apart from a teaching aid for machine code programming, the Microtutor is also intended to be used for I/O experiments; thus all the bus lines and control signals are brought out to pads on the PCB so that external circuitry can be connected.

The only thing to remember about machine code is that it is very unforgiving of errors. Unlike BASIC ${ }_{2}$ a programming blunder won't produce a polite message on the screen and a chance to try again; more often than not your program and data may be corrupted, or the thing gets locked into an endless loop until it disappears up its own data bus. When developing software for a home computer there is otten little choice at this point but to switch off the machine to cure things, causing loss of program and laborious reentry. We've had some nasty experiences in the office with the PET this way! On the Microtutor things are more civilised; two buttons are

| SPECIFICATION |  |
| :---: | :---: |
| CPU: | 6503 (addresses 4K) |
| ROM: | 2 K containing monitor |
|  | program. EPROM is 2716 ( 5 V version) |
| RAM: | 1 K . Used for user pro- |
|  | gram and memory- |
| 1/0: | mapped VDU <br> 1 K space available |
| Display: | 16 rows by 32 characters, |
|  | upper case only |



The PCB is very compact and uses thin tracks, so a fine bit is essential on your soldering iron.

PARTS LIST

| Resistor (all ${ }_{\frac{1}{4} \mathrm{~W}} \mathbf{5}$ ( ${ }^{\text {) }}$ | IC11 | 74LS32 |
| :---: | :---: | :---: |
| R1 75R | IC12-14 | 74LS157 |
| R2 470R | IC15 | 6503 |
| R3 220R | IC17, 18 | 2114 |
| R4-1722 271 l 0 | IC19 | 86S64BWF |
| R18, 2410 k | IC20 | 2716 |
| R19, 23 120k | IC21 | 74 LS 374 |
| R20, 21 2k2 | IC22 | 74LS244 |
| R25, 26, 28 22k | IC 23 | LM358 |
|  | IC24 | 7805 |
| Capacitors | Q1, 2 | BC184L |
| $\mathrm{C}_{1} 100 \mathrm{u} 10 \mathrm{~V}$ PCB electrolytic | D1-3 | 1 N4148 |
| $\mathrm{C} 2,5,6,9-17100 \mathrm{n}$ ceramic | ZD1 | 6 V 8400 mW zener |
| C3, $8 \quad 10 \mathrm{n}$ ceramic | Miscellaneous |  |
| C4, $7 \quad 100 \mathrm{p}$ ceramic | XTAL1 | 6 MHz crystal 100 uH choke |
| Semiconductors | SK1 | miniature charger socket |
| IC1, 8 74LS04 |  | (PCB-mounting) |
| IC2 74LS73 | SK2 | 5 -pin DIN socket |
| IC3.9 74LS393 |  | (PCB-mounting) |
| IC4 74LS21 | PB1, 2 | push-buttons (PCB- |
| IC5, 16 74LS74 |  | mounting) |
| IC6 74LS08 | PCB (se | uylines); hex keypad; UHF |
| IC7 74LS11 | modulato | pe UM1111E36; [C sockets; |
| IC10 74LS00 | PCB-mou | g heatsink for regulator. |



Fig. 2 Complete circuit diagram for the Microtutor.

## BUYLINES

A complete kit of parts for this project, in-


## HOW IT WORKS

The CPU (IC15) and the video display share the same memory. Access to the memory is switched at the processor's $\not \not 22$ clock rate (as on the Microtan 65), using the address selector IC12-14. This alternately connects the CPU and CRT address onto the RAM chips IC17, IC18. IC16a is a R/W synchroniser to ensure the RAM chips get proper set-up and hold times on the $R / W$ line after it passes through the address selector IC12.

The master clock oscillator is built around three of the inverters in IC1; XTAL1 sets the operating frequency at 6 MHz . The clock signal enters the counter chain down the left of the circuit diagram at pin 1 of IC2a. IC3 generates all the character addresses along the video line for CRT refresh, with IC4a and IC4b/IC5a generating two of the timing signals required by the character generator IC19. The count length of IC3 is determined by the AND gate IC6a. IC7a generates the line sync pulses while IC5b/IC6b produce the line blanking. The line sync pulses also clock counter IC9, which together with IC2b generates all the line addresses. IC2b, IC7b and the associated logic controls the count length of the line counter and produces the frame sync. IC2b also produces the frame blanking directly.

IC19 is the character generator which receives data from the memory chips IC17, 18 during the time interval that the CRT refresh address is switched through. Data is latched and the character pattern is clocked out under the control of the various input signals to this chip. The chatacter data is mixed with the line and frame blanking in IC7c, while the line sync and frame sync pulses ate mixed in the AND gate IC6c to give a composite sync. The output of IC 7 c is mixed with the composite sync in the diode circuit (D1, D2 and associated resistors) to give an analogue video signal which is fed to the UHF modulator.

The modulator requires a supply of about 6 V 5 . To avoid the need for a separate PSU, this is derived using the DC-DC converter based on L1 and Q1, which is driven via R6 from the CRT counter chain.

IC20 is the 2 K EPROM containing the monitor program. For the EPROM to be enabled, A11 must be high and $R / \bar{W}$ in the read mode; these lines drive NAND gate IC10c which provides the chip select signal to pins 18 and 20 of the EPROM. Gates IC8c, IC6d, IC10d, IC8e and IC11b,c enable the I/O port, controlling the hex keypad and the cassette interface. Any location between 400 and 7FF (Hex) will address the port provided the I/O control line has not been pulled low externally. When reading, IC22 is enabled; when writing, IC21 is enabled. IC23 and associated components form the input amplifer for the cassette interface.

The only expansion the Microtutor has is for I/O experiments; the address bus, data bus, $R / \mathbf{W}, 2$ and $I / O$ control lines all come out to pads on the PCB. If the user builds an external I/O circuit then that circuit must operate the I/O control, which is active low, to disable the keypad circuits, otherwise bus contention will result. The monitor program assumes that they keypad is located at 7FF. Any location in the 1/O address space will activate the keypad port if I/O control is not pulled low, however. For further I/O experiments, all eight bits from IC21, 22 are brought out to pads. This means that users can experiment with bigger keypads or utilise the unused bits. RST and IRQ also come out to pads on the PCB.
provided, reset and interrupt. Both wil get you back into the monitor from a faulty program if it gets out of hand, without clearing the memory; interrupt will do so without losing any breakpoints you may have set (breakpoints are explained fully later).

## Construction

The PCB is double-sided but through-hole plated, so components only have to be soldered on the underside. Fit all the low profile components first, ie the link, resistors, diodes and choke, then the keypad. This is stuck to the component side of the board with double-sided sticky pads; insert the connecting wires through the holes in the PCB first first, secure the keypad in position with the pads and then solder the connections.

Now you can fit all the IC sockets and capacitors but don't insert the ICs until later. Solder the choke, crystal and transistors in place, then the UHF modulator. The voltage and its heatsink are bolted to the PCB and no insulating washers are required.

Finally mount the two sockets (power and cassette) and the large push-buttons, then insert all of the ICs paying great attention to the device type.

## Ready To Go

Once you've double-checked everything, you're ready to connect the power supply and TV set. The modulator is connected to the TV using UHF coaxial cable with a phono plug at one end and the usual coax plug at the TV end. Switch on the set and tune the TV until you get a steady black-and-white picrure - at this point the screen will contain garbage. Press the RESET button and the screen should announce TANBUG. You may now use the keypad, as described below, to enter the wonderful world of machine code.

As an example of the sort of power you've got at your fingertips, here's a direct comparison. Some time ago it was necessary for someone in the office to check all four-digit numbers for certain combinations of digits. A BASIC program on the PET took about five minutes to write and about 15 minutes to run. The same problem, when solved by the Microtutor, took somewhat longer to write the program, but checked through all 10000 numbers in three seconds!

## All About TANBUG

The TANBUG monitor program is located in 2 K bytes of read only memory ( ROM ) at the top of the address space ie pages $8-15$. It
contains facilities to enter, modify, run and debug programs. TANBUG will only operate in the memory map of the Microtan system, it is not a general purpose 6502 software package and has been specifically written for Microtan/Microtutor.
2 K ROM

Fig. 3 Memory map.
Locations $2 \emptyset \emptyset-3 \mathrm{FF}$ (pages 2 and 3) are the visual display memory TANBUG writes to these locations whenever a command is typed to the monitor. Locations in pages 4 to 7 are the addresses of the peripheral attachments, eg keyboard. Locations $10 \phi-1 \mathrm{FF}$ (page 1) are used as the stack by the microprocessor. Since the stack is of the push-down variety it follows that the whole of this will not be used as stack storage in the majority of programs. TANBUG requires to use locations $1 \mathrm{~F}(\mathrm{O}$-1FF as stack storage (only 16 locations). The rest of this area is free for user programs. Locations $4 \emptyset$ - FF are also available as user RAM, the preceding locations 0 -3F being reserved for use by TANBUG. User programs which do

| TABLE 1 |  |  |  |
| :---: | :---: | :---: | :---: |
| Hex | Character | Hex | Character |
| 20 | Space | 40 | @ |
| 21 | ! | 41 | A |
| 22 | * | 42 | B |
| 23 | \# | 43 | C |
| 24 | \$ | 44 | D |
| 25 | \% | 45 | E |
| 26 | \& | 46 | F |
| 27 |  | 47 | G |
| 28 | $($ | 48 | H |
| 29 | ) | 49 | 1 |
| 2A | * | 4 A | J |
| 2B | $\pm$ | 4 B | K |
| 2C | \% | 4 C | L |
| 2D | - | 4 D | M |
| 2E | . | 4 E | N |
| 2F | 1 | 4 F | O |
| 30 | 0 | 50 | P |
| 31 | 1 | 51 | Q |
| 32 | 2 | 52 | R |
| 33 | 3 | 53 | 5 |
| 34 | 4 | 54 | T |
| 35 | 5 | 55 | U |
| 36 | 6 | 56 | V |
| 37 | 7 | 57 | W |
| 38 | 8 | 58 | X |
| 39 | 9 | 59 | Y |
| 3A |  | 5 A | Z |
| 3B | - | 5 B | [ |
| 3 C | $<$ | ${ }_{5} \mathrm{C}$ | 1 |
| 3D | $=$ | 5D | I |
| 3 E | $>$ | 5 E | $\wedge$ |
| 3 F | ? | 5 F | - |

not use the stack may therefore be loaded anywhere in the area $4 \phi-1 \mathrm{EF}$ For user programs which do use the stack, the user must calculate how many stack locations are required and reduce the upper limit accordingly.

The keypad is used as follows, its layout being shown in Fig. 1.
TANBUG interrogates the keypad tor a depressed key, then translates the matrix encoded signal into an ASCII character which it puts up on the visual display. Because of the limited number of keys it has been necessary to incorporate a shift function on the keypad. So, to obtain the character $P$ for example, the user presses and releases SHIFT, then depresses and releases P. The SHIFT key contains a self-cancelling facility - if the user presses SHIFT twice in succession the pending shift operation is cancelled. So as an example, using the two keys SHIFT and 8 the operations SHIFT P yields $P$ on the display. SHIFT SHIFT $P$ yields 8 on the display. DEL deletes the last character typed. Repeated deletes erase characters back to the beginning of the line.

Having described some of the background to TANBUG it is now possible to describe the commands and syntax of TANBUG, ie how to use it. An example is shown later on. All numerical values of address, data and monitor command arguments are in hexadecimal. The symbol <CR> means on depression of the carriage return key, $<$ SP $>$ the space key, and $<$ LF $>$ line feed. In all examples, text to be typed by the user will be in bold type, while TANBUG responses will not. indicates the cursor. $<A D D R>$ means a hexadecimal address, $<$ ARG $>$ means hexadecimal data and $<$ TERM $>$ means one of the terminators $\langle\mathrm{CR}\rangle,\langle\mathrm{SP}\rangle$, or $<$ LF
All commands are of the form <COMMAND><TERM> or
$<C O M M A N D><A R G>$ TERM $>$ or <COMMAND $><$ ARG $>$, $<$ ARG $><$ TERM $>$ or <COMMAND > < ARG> $<$ ARG $>$, <ARG><TERM $>$ where $<$ COMMAND $>$ is one of the mnemonic commands and <ARG> is a hexadecimal argument applicable to the command. It should be noted at an early stage that the longest argument will contain four hexadecimal characters. If more are typed all but the last four are ignored. As an example consider the memory modify command M1234 $\$ \emptyset 78$ $<C R>$. In this case location $\$ \phi 78$ will be modified or examined as all but the last four characters are ignored.
$<$ TERM $>$ is one of the terminating characters $\langle\mathrm{CR}\rangle,\langle\mathrm{SP}\rangle,\langle\mathrm{LF}\rangle$ or $<\mathrm{ESC}>$ ．In fact TANBUG accepts any of the＂control＂＇characters（HEX code $(-2 \phi)$ as terminator．TANBUG will reply with a ？if an illegal com－ mand is encountered．

## Starting The Monitor

Press the reset button on the Microtutor．TANBUG will scroll the display and respond with TANBUG

Note that on initial power－up the top part of the display will be filled with spurious characters．These will disap－ pear as new commands are entered and the display scolls up．On subse－ quent resets the previous operations remain displayed to facilitate debugging．

## Memory modify／examine command M

The M command allows the user to enter and modify programs by chang－ ing the RAM locations to the desired values．The command also allows the user to inspect ROM locations，modify registers and so on．To open a location type the following

$$
\mathrm{M}<\mathrm{ADDR}><\text { TERM > }
$$

TANBUG then replies with the cur－ rent contents of that location．For ex－ ample，to examine the contents of RAM location $1 \phi \phi$ type $\mathrm{M} 1 \phi \phi<\mathrm{CR}>$ TANBUG then responds on the display with

M1中申，$\varnothing \mathrm{E}$ ，
assuming the current contents of the location were $\phi \mathrm{E}$ ．

There are now several options open to the user．If any terminator is typed the location is closed and not altered and the cursor moves to the next line scrolling up the display by one row．If however，a value is typed followed by one of the terminators $\langle\mathrm{CR}\rangle$ ，
$<\mathrm{LF}>$ or $<\mathrm{ESC}>$ the location is modified and then closed．For exam－ ple，using＜CR＞

location $1 \phi \varnothing$ will now contain FF．If however $<\mathrm{SP}>$ is typed，the location is re－opened and unmodified．

## M10＠，ゆE，FF Mゆ1ФФ．ФE，

This facility is useful if an erroneous value has been typed．The terminators $<$ LF $>$ and $<$ ESC $>$ modify the cur－ rent location being examined，then open the next and previous locations respectively ie using＜LF＞

M100， ©E，FF MD101，AB，
and using＜ESC＞
M100．（DE，
M $\phi$ FFF，56，

Using＜LF＞makes for very easy program entry，it only being necessary to type the initial address of the program followed by its data and $<$ LF $>$ ，then responding to the cursor prompt for subsequent data words．

Note that locations 1FE and 1FF should not be modified．These are the stack locations which contain the monitor return addresses．If they are corrupted TANBUG will almost certainly＂crash＂and it will be necessary to issue a reset in order to recover．

## List command L

The list command allows the user to list out sections of memory onto the display．It is possible to display the contents of a maximum of 120 consecutive memory locations simultancously．To list a series of locations type

$$
\begin{gathered}
\text { L <ADDR > },<\text { NUMBER }> \\
<T E R M>
\end{gathered}
$$

where $<A D D R=$ is the address of the first location to be printed and ＜NUMBER＞is the number of lines of eight consecutive locations to be printed．TANBUG pauses briefly between each line to allow the user to scan them．For example，to list the first 16 locations of TANBUG（which resides at C $(\downarrow$ FFF）type

## $\mathrm{LC} 00,2<\mathrm{CR}>$ ．

The display will then be
LCOQ， 2
C $\dagger \emptyset$ A2 FF 9A E8 861720 B7
C 48 FF 8D F3 BF A2 0 E BD DF
If zero lines are requested（ie $<$ NUMBER＞$=\emptyset$ ）then 256 lines will be given．

## Go command G

Having entered a program using the M command and verified it using the L command，the user can use the G command to start running his own program．The command is of the format G＜ADDR＞＜TERM＞． For example，to start a program whose first instruction is at location $1 \phi \phi$ type Gi $\phi \phi<C R>$ ．When the user program is started the cursor disappears．On a return to the monitor it re－appears．

The G command automatically sets up two of the microprocessor＇s internal registers：
a）The program counter（ PC ）is set to the start address given in the G command．
b）The stack pointer（SP）is set to location 1 FF ．
The contents of the other four internal registers，namely the status word（PSW），index X（IX），index Y （IY）and accumulator（A），are taken from the monitor pseudo registers
（described next）．Thus the user can either set up the pseudo registers before typing the G command，or use instructions within his／her program to manipulate them directly．

## Register modify／examine command $\mathbf{R}$

Locations 15 to 1 B within the RAM reserved for TANBUG are the user psuedo registers．The user can set these locations prior to issuing a $G$ command；the values are then transferred to the mictoptocessor＇s internal registers immediately before the user program is started．The pseudo register locations are also used by the monitor to save the user internal register values when a breakpoint is encountered．These values are then transferred back into the microprocessor when a P command is issued，so that to all intents and purposes the user program appears to be uninterrupted．

The R command allows the user to modify these registers in conjunction with the M command．To modify／examine registers，type R $<\mathrm{CR}>$ and the following display will apppear（location 15 containing $\phi \phi$ say）．

| TABLE 2 |  |
| :---: | :---: |
| 15 | Low order byte of program counter <br> （PCL） |
| 16 | High order byte of program counter（PCH） |
| 17 | Processor status word（PSW） |
| 18 | Stack bointer（SP） |
| 19 | Index X（IX） |
| 1A | Index Y（IY） |
| 1B | Accumulator（A） |
| R |  |

Now proceed as for the $M$ command．
Naturally the M command could be used to modify／examine location 15 without using the R command－ the R command merely saves the user the need to remember and type in the start location of the pseudo registers．Psuedo register locations are shown in Table 2．Two typical instances of the use of the R command are：－
a）Setting up PSW，IX，IY and A before starting a user program．
b）Modifying registers after a breakpoint but before proceeding with program execution（using the P command）for debugging purposes．
Note that when modifying registers in case（b）care must be taken if PCL， PCH or SP are modified，since the proceed command $P$ uses these to determine the address of the next instructions to be executed（PCL， PCH ）and the user stack pointer（SP）．ET


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# READ/WRITE 

Letters for this page should be addressed to Read $/ \overline{\text { Write }}$ at 145 Charing Cross Road, London WC2H 0EE.

## Dear Sir,

I am writing to enquire if your magazine or any of your readers have heard about or tested an electronic device for inducing dream consciousness (lucid dreams).
This bedside machine monitors the breathing rate of a sleeper by means of a sensitive thermistor attached to the nose. During a dream period, the breathing rate increases above normal; this is used to trigger a mild electric signal to the wrist of the dreamer telling him that he is dreaming and should become conscious in his dream.
Lucid dreams, being far more vivid than normal, are in full colour and three dimensional. The dreamer also has full control over his dream environment and can manipulate it at will. He can dream consciously about anything he chooses and total dream recall is normal.

This equipment was designed and developed by a Dr. Keith M. T. Hearne of Hull University and I believe manufactured and marketed by Campden Instruments (Incam Ltd) of London. But despite persistent enquiry, I have seen no test or reports on this equipment in electronic magazines. Have you or any of your readers seen anything?
I would be very grateful for any information you may have come across on this interesting device!
Yours faithfully,
Mark Botham,
Northumberland
Sorry, never heard of it. Sounds like it makes video games look a bit sick though. Control your dreams at will, eh? Interesting...very interesting...

## Dear Mr. Harris,

I am enclosing my entry for your Prize Crossword No. 3. However, I am sorry to say that I do not find this feature up to the usual standards of the rest of the magazine.
May I draw your attention to Crossword No. 1 in the January issue. Clue 24 Down was "Radiation particles are certainly not passive.' At first I chose "Active"' as the answer. However, on reflection, a radiation particle may be an ion, so I changed the answer to "Action."

You can imagine my surprise when you published the answer as "Active." The problem really lay in the fact that
the only letter crossed with this puzzle was the letter ' C ', common to both possible answers.

Now, five months later, in Crossword No. 3, the same difficulty arises. Clue 22 Across is "Timely happening." The only letter crossed with is the second letter, which I make an ' $E$ '. Hence the possible answers (all having some connection with time) are as follows: Decay, Death, Delay, Hence, Hertz, Leave, Merge, Peaky, Recur, Relay, Relic and Telex.

Many of these are also technical terms and therefore likely to be the correct answer. May I remind your Crossword compiler that the rule is: ' ${ }^{\text {lf }}$ a clue is to be made wholly or partly vague, the answer must have sufficient letter crosses to enable it to be verified as the sole answer.' The puzzle to be solved should involve ingenuity in word manipulation, not guesswork or thought transter!
Yours sincerely,
Paul M. Richardson,
Tavistock
Comments received. Passed on to our compiler, who will no doubt have a few cross words to say in reply.

Dear Sir,
I was happy to read the article in your April Birthday supplement entitled,
"Steering Wheel? - Wot Steering Wheel?''. Enclosed is a copy of a letter I sent to the Prime Minister in February this year.
Robert W. Teasdale,
Newcastle-Upon-Tyne
Letter to Prime Minister,
February 1982
On giving some thought to future cars, I thought it would be a good idea if they had some form of electronic control.

The system of flashing lights on the motorways was a good idea, but motorists tend to ignore this system, and I though that futuristic systems could be devised to electronically control the speed of cars (to prevent them going too fast under certain conditions, eg fog), with a built-in safety device for the driver to ignore these signals in an emergency: electronically controlled to respond to certain speed limits; controlled to stop or slow at traffic lights (being able to override this signal if
conditions desired it); controlled to slow at pedestrian crossings, crossroads and junctions; controlled to keep a safe distance from the car in front (with an override to overtake for a short period if necessary and an exterior signal to indicate when on override); controlled to slow at obstructions, again with an override.

Fast cars are dangerous and use a lot of energy. What is required is a safe, controlled car with power to get up hills and through adverse conditions.

I'm sure it would be better to have a safe, controlled system rather than fast dangerous cars, thus cutting down on accidents, death, disablements, and the work of all the services involved in accidents. I hope these suggestions can be put to future scientists and car manufacturers.

## Dear Sir,

As so many of us are now using electronically operated quartz crystal controlled watches, may I suggest that an article giving a detailed description of their operation would be of considerable interest.
I am, yours sincerely,
H. Vernon Kirby (Regular Reader), Hayling Island

Couldn't agree more. You wanna write it?

## Dear Sir,

I know that you are busy men, but looking through recent ETIs, I came across two speaker systems - the ETI V3 (Oct 1981) and the Wharfedale E70 kit (April 1982). I would be interested in knowing your views on them.

Do you feel that it would be of interest to ETI's readership if you reviewed all the hi-fi projects and compared them to corresponding commercial units?
Yours faithfully,
M. G. Hill,

Harrow
The V3 and E70 are designed to meet different criteria. The V3 is an 'all-rounder' primarily intended for use with a wide range of music at 'normal' (if there is such a thing) volume levels. It is designed to be as neutral as possible in its portrayal of the signal.

The E70 is a high-efficiency speaker with an exciting 'lively' sound balance. It is most at home with the type of music best suited to this method of replay.

As to reviewing ETI projects, could you believe anything anyone says about their own product? Our objectivity would have to be suspect.



# RUGBY CLOCK 

If you want to know the time, ask MSF Rugby. This accurate and versatile clock/

 calendar is packed with facilities and never needs resetting. Design and development by Stephen Makumbi.

Clock designs appear fairly regularly in hobbyist magazines, but they usually fall into one of two basic types. The first type derives clock pulses from the 50 Hz mains, and while these provide a highly accurate long-term performance, mains frequency variations in the short term can cause errors of several seconds in either direction. The second type relies on a built-in oscillator, usually crystalcontrolled which gives excellent shortterm precision but a steadily accumulating long-term error.

If only you could build your own atomic clock! This is a project slightly
outside the scope of the magazine, but fortunately it isn't necessary to go quite that far. We can all get to share the atomic clock at the National Physical Laboratory because it's used to send coded time data, 24 hours a day, on a 60 kHz radio carrier from a transmitter at Rugby. The signal is transmitted at around 50 kW RF power and can be received over most of Western Europe. Of course, a specialised receiver is required to demodulate and decode the time signals, and that's the project we're offering; a clock that displays the correct time of day, date, day of week, and plenty. more besides, with no need to ever
correct it. Even when the signal completely disappears the clock senses this and automatically switches on to its own crystal timebase back-up clock.

All the information is checked thoroughly for parity and validity. As an example, February 29 th 1983 will be rejected and dashes put into the display in place of the date.

We've included a comprehensive alarm system comprising no less than eight independent alarms. For each alarm setting there is a choice of a melody (author's 12 bar rock), altering the state of eight TTL-compatible lines, or both! The eight lines could, of course, be used


Fig. 1 Block diagram of the Rugby Clock.


Typical time display. Display format is set to 12 hour clock.


Mode 2, phase 2; alarm number 1 has been set for buzzer and port to function.
to turn on and off eight different electrical appliances (through relays).

There is also a separate timer with a unique mode of operation capable of recording up to 240 lap times without interrupting the count! All this makes is simply the best clock available for home use - or anywhere!

## General Description

There are three basic modes of operation designated 1,2 and 3 ; clock, alarm, and timer respectively. On reset the clock automatically enters mode 1 . Another switch would enter mode 2. In order to enter mode 3 (timer) you have to press reset while pressing one of the switches.

The emphasis in this system is ease of expansion and interfacing. To this end, all the important CPU lines are brought out to a dual 32 -way connector. Also, all the information that is transmitted is output to six decoded port selects (including the timer). We intend to publish useful add-on units in the future. The entire unit can be controlled by an external computer, instead of by the push-buttons.

## The Circuit

At the heart of the system is a Z80 microprocessor. Several other processors were considered including the RCA CPD 1802 for its low power consumption, Intel 8039 for its 'all-in-one' design, plus good BCD handling, and the Intel 8088 for its speed and overall superior processing power.

The $Z 80$ was chosen because a good interrupt structure was of paramount importance in this application. IC4 decodes the lower 32 K of the 64 K address space into eight blocks each 4 K long. These eight blocks are allocated to the PROM, RAM and six LCD displays. It might appear a waste for each digit in the display to take up an entire 4 K of addressing space, but this simplifies


Mode 2, phase 1; the hours have been set at 12 for alarm number 2 .


Mode 2, phase 3; bit 1 of alarm 6 will switch high when the alarm goes off.
decoding logic and reduces chip count. Furthermore, there is 32 K of memory still free!

As you may have gathered from the above text, the displays are 'memory mapped'; whenever the CPU wants to read or write to memory (in the lower 32 K ) pin 3 of IC6c goes high, MREQ goes low, and A15 is low, indicating to IC4 that a memory read or write is about to take place. If at this time the address bus contains 2XXX to 7 XXX hex ( $\mathrm{X}=$ don't care) then one of the six LCD displays will be selected. Similarly IC19 is used to decode the input/output section. This IC is active when $A 7$, $\overline{\text { IORQ }}$ and one of $\overline{\mathrm{RD}}$ or $\overline{\mathrm{WR}}$ are low; the port selected depends on the binary value that is present on A 2 to A 4 . This effectively divides the lower 128 port addresses (out of a possible 256) into eight separate ports each four addresses long and repeating 16 times.

The CPU clock signal is generated by XTAL1, IC5a, R1, C1, CV1. This is fed to IC5b and IC5c which are connected in parallel to provide a higher drive and isolation.

IC5d and IC5e together with R2, $\mathrm{R} 3, \mathrm{R} 4, \mathrm{C} 2$, SW 5 form the manual and automatic power-on reset. The RESET signal is ANDed with M1 by IC6a,
IC6b to form a hardware reset for the PIO (Zilog ran out of pins and omitted a proper reset pin). Incidentally although Zilog don't mention it, it's possible to reset the PIO by software. This method is used in this application, but the hardware alternative is there in case another application using the board requires it. (Anyway, we had a couple of NAND gates spare!)

IC9 to 14 are LCD display latchdecoders. Information available at the

Fig. 2 (Above) Coding data into one second. (a) a 0 ; (b) a 1 ; (c) time difference; (d) a second containing odd parity.

Fig. 3 (Right) The five clock faces available in Mode 1. From top to bottom they are time of day; date; day of week and master alarm indicator; time since clock switched to back-up; and BST/GMT time difference.

data pins (2-5) is latched internally when the latch input (pin 1) receives a positivegoing pulse. Since this is of opposite polarity to the signals coming from IC4, a hex inverter is used.

LCD displays require a square wave drive signal on the segments in antiphase to that on the backplane. IC8c and IC8d provide such a signal with a frequency of approximately 50 Hz .

This is fed to the backplane input of the display and also to each display driver (IC9-14). These ICs perform the phase reversal, but unfortunately they don't have decimal point and colon outputs so these have to be generated externally using PIO A0 and A1. IC8a and IC8b perform the phase reversal on these.

IC15 performs several functions; serial input port (SIO), timer, tone generation for radio data, internal timing, user timer (mode 3) and alarm tune.

IC17 also performs several functions, including inputting the state of the switches SW 1-SW4, inputting radio data, controlling the display decimal point and colon, inputting the default hour format (12/24); it's also a programmable output
port in conjunction with mode 2 !
The receiver follows an unusual design. For a start there are no cumbersome coils; instead the entire tuning section comprises two state variable filters in series (IC20, 21). They also provide the necessary gain to couple to IC22 via FET buffer Q1. The two filters provide very good selectivity which is required at these low frequencies due to interference, especially from TV timebase circuitry. When properly tuned by PR1-4 it is possible to have the receiver closer to a TV set than is possible with many current designs. IC22 is a tone decoder whose output pin goes low when a signal within its passband is present at its input (pin 3). Q2 inverts this signal to high for 'carrier on'. There are some spare inverters on the main board which could have been used instead, but the aim was to have a selfcontained receiver.

## Rugby Transmissions

The incoming radio carrier is switched off and on throughout the entire minute to convey the time information in


Fig. 4 Switch functions for Mode 2, phase 1.


Fig. 5 Switch functions for Mode 2, phase 2.


Fig. 6 Switch functions for Mode 2, phase 3.
binary-coded form. The carrier is switched off at the beginning of every second, and the point within the first half of the second that it comes on again determines whether the bit sent within - that second is a logic 1 or 0 , ie, if it switches on after 100 mS , then the bit is a 0 . Otherwise it will switch on after 200 mS in which case the bit is a 1 . Figure 2 should make this clear.

As each second transmits only one bit of a binary coded number more than one second may be needed to transmit a whole number. Each unit is allocated the minimum number of bits which will represent the maximum value of that unit; for instance. 'Day of Week' takes up three seconds (three bits) since these will contain binary combinations $0-8$ ( 8 not used).

Seconds $7-16$ contain information about the time difference between BST and GMT. An extra pulse (break in carrier) will indicate $1 / 100$ th second difference.

The total number of pulses within seconds 1-8 represent the number of hundredths of a second that BST lags behind GMT. Otherwise, those which occur in seconds 9-16 indicate BST leading GMT by their total multiplied by 10 milliseconds.

Seconds 17-51 contain the time, date, day of week, month and year. Seconds 51-59 contain a unique binary code which is used by detecting systems to synchronise; although the clock presented here uses a different system for synchronisation.

Seconds 52-58 also contain a parity checking code on the information that was received between seconds 17-51. That is to say a pulse 300 mS long indicates that the unit in question should have an odd number of 1 bits. A pulse of $30 n \mathrm{mS}$ indiratos an puen number of 1 s

The first second (0th) contains a fast serial code which also specifies the time, date and month.

Just before this code is a very short negative-going pulse (carrier off). It is the only pulse shorter than 3 mS in the entire minute. For this reason it is detected by its unique size and used for synchronisation. The fast code is then read immediately. Synchronizing on this code as opposed to the six second ident makes it possible to make another attempt within 10 mS of the previous attempt if the previous one was false. In the other case it would take at least six seconds to find out if the ident is valid or not before the subsequent trial is attempted.

## More On Modes

As mentioned earlier, there are three basic modes which the clock could be in. In order to economise on front panel switches, SW 1-4 are all multifunction and the function of each switch

## PROJECT : Rugby Clock


depends on which mode, face or phase one is in.

## Mode 1

Mode 1 is the default mode on power-on and displays the current time and related information. When the unit is first switched on a blip should be heard from the buzzer in sympathy with the incoming signal. This is useful for tuning purposes, as the receiver can be tuned until a clean blip (generally one a second) is heard.

After some time the blip will stop and the display will change from dashes to the correct time. The date information will take a further minute to appear. Now, assuming that you have waited this further minute, then pressing SW1 causes the display to change to date, month, and year. Press SW1 again and the day of week will appear on the left hand digit while the right hand digit will be either ' A ' or ' P ' ( AM or PM). The middle two digits will contain letters ' AL '. This is the master buzzer enable/disable indicator. If while on this third face you press SW4 the letters 'AL' will begin to flash, indicating that the master alarm is enabled, ie any of the eight alarm settings will sound the buzzer of the preset time. With the master alarm disabled, none of the alarm settings will ever activate. Repeatedly pressing SW4 will toggle the master alarm between 'enabled' and 'disabled'.

Pressing SW1 once more will move on to face 4 which shows the amount of time in hours and minutes since the clock has switched to automatic back-up time. Normally this face will show

> " 00.00 - "' meaning that the clock is running on Rugby Time.

Pressing SW1 once more will move on to face 5 which shows the BST/GMT time difference information. L indicates 'lagging' while ' H ' indicates 'leading'

Finally, pressing SW 1 again will wrap round to face 1 to display the time. It is possible to do a quick return to face 1 from any face except face 3 by pressing SW4 twice. Pressing SW2 while face 1 is displayed will change from 12 to 24 hour display and vice-versa.

## Mode 2

In Mode 2 any one of eight alarms may be set to sound the buzzer and/or configure the state of the eight lines on port B . Each individual alarm can be enabled/disabled to sound the buzzer or alter the settings of the eight port lines.

From Mode 1, press SW4. The display will show 'AL', indicating the alarm mode. From here you can branch in any one of three directions depending on what you want to do. Let's call this point $X$. If you want to set an alarm time, from point X press SW3. The display will show a 1 on the right hand side indicating that the current alarm is alarm 1. The rest of the display will contain dashes, and the hour position will be flashing meaning that the hours will be the next unit to be set (like a digital watch). Pressing SW1 will advance the hours. Pressing SW2 will cause the minute 'tens' to flash. Similarly pressing SW 1 will alter the minute tens. Pressing SW 2 once more will advance to minute 'ones', and then wrap round to hours. SW3 will advance through the alarm
numbers and is effective from whichever state the 'setting' procedure is in.

To exit 'alarm set' mode at any time press SW4 which will turn the display back to time display. Press SW4 again to go back to point $X$. This time we want to enable the alarm we have just set to sound, so press SW1 and then press SW3 to the desired alarm number. Now press SW 1; the 'A' will start to flash. If you also want to enable the alarm to alter the port lines, press SW2; 'P' will start flashing. Press SW4 to go to mode 1.

For the third branch from point X , press SW4 again and this time follow it by SW2. Press SW3 to advance to the desired alarm number, then press SW2 to advance to the required bit number. Pressing SW1 will cycle through - , H, L; refer to Fig. 3 for the significance of these letters. Once, again, to exit, press SW4.

When any of the set alarm times come up the buzzer should play a tune and the port lines will take up the state that was programmed. A nyone who dislikes the tune can get it changed for one of their choice by sending a good quality tape or a manuscript to the designer via Technomatic. Details of the charge for this service will be available from Technomatic.

When the tune starts playing, pressing SW4 will stop it. Pressing SW3 will start a 10 minute snooze delay after which the tune will play again. When the tune is playing SW4 and SW3 will perform these two functions no matter what mode, phase or face you happen to be in; the current meaning of those switches will be postponed for one key depression.

## Mode 3

This is the timer mode. It is entered by pressing SW5 (reset) and SW4 simultaneously, then releasing reset followed by SW4. The display will show both the colon and the decimal point. Presssing SW4 will start the count; pressing SW4 again will stop it. Pressing SW2 during the count will latch the current display. Repeated pressing of SW2 will latch (and store) up to 240 laps. Pressing SW1 will view the laps in store even while counting is in progress. Pressing SW3 will display the current count, if you happen to be viewing laps or have just latched a lap.

## Expansion

The board was built with expansion in mind, hence the 64 -way connector which carries all important signals. We hope to publish useful add-ons in the future.

Next month we continue this project with the circuit diagrams and How It Works.


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# DESIGNER'S NOTEBOOK 

# This month Rory Holmes provides you with all the design information you need to incorporate the DPM200 module into electronic measurement circuits. It requires few external components and is ideal for portable instruments. 

Amajor role of electronic equipment is very often the measurement and display of some quantity, either from the 'real world' or an electronic parameter. The new generation of digital voltmeter modules allows the inherent readout accuracy of a digital system to be simply and conveniently implemented due to their low cost, low power and very small size. The price of moving coil meters is steadily increasing while the price of the solid-state ones is naturally falling.

Although digital meters lack an indication of analogue trends, this will soon cease to be a valid criticism. Medium resolution LCD bargraphs coupled with digital readouts will have all the advantages of both, with an increasingly attractive versatility.

The DPM 200 module is described as a state-of-the-art $31 / 2$ digit LCD meter. Briefly, its features are:

- High contrast, wide angle display
- Wide range of programmable symbols
- Ultra-low current consumption
- Single rail supply (5-15 V)
- Auto-zero and auto-polarity
- $0.05 \%$ accuracy
- Built-in bandgap reference voltage
- Low battery indicator
- Programmable decimal points


Fig. 1 PCB pin connection diagram for DPM200.


Dimensions in mm
Fig. 2 Physical dimensions of the module. Panel cut-out is $68 \times$ 33 mm .

It is based around the latest dual-slope integration CMOS DVM chip, the 7126, and is certainly the best of its ilk available to the hobbiest.

Figure 3 shows the circuit diagram of the module. The great versatility of this device comes from the large number of user connections provided ( 38 in all) as shown on the connection overlay of Fig. 1.

When used in conjunction with other circuitry it offers a

|  |  | TABBLE 1 |
| :--- | :--- | :--- |



Fig. 3 Circuit diagram of the module. R1, R2 and C1 determine the integrator time constant and C 2 reduces the susceptability to noise of the auto-zero circuitry. The display is guaranteed to read zero when the analogue input is 0 V . An input filter formed by R3 and C3 assists with overload protection for the 7126 IC. The input voltage may exceed the
supply voltage provided the input current does not exceed 100 uA . The frequency of the internal oscillator is determined by R4 and C5 and provides three samples per second typically. The module is calibrated by means of VR 1 for a full scale reading of 200 mV with link LA in circuit and resistor $\mathbf{R}_{\text {c }}$ omitted.
number of unexpected bonuses for the designer. A square wave clock signal, an extra negative supply rail, a bandgap precision voltage reference, a common rail for op-amp references, plus four logic signals for autoranging meter circuits - all these signals are available for use in external circuits. Table 1 charts the pin numbers in numerical order with their symbols and basic functions.

## Supply Rails

The module can be operated from a single supply between 5 V and 15 V across pins 1 and 14 , at a current of 100 uA , using the bandgap reference. However, the internal reference can be used instead, reducing the current to 50 uA with a minimum voltage of 7 V . A low battery warning indicator is set to come on at 6V4, determined by the R8/R10 potential divider. R10 can be altered if required; 220 k gives a 7 V 2 warning.

## Legends/Annunciators

The symbols can be enabled very easily by directly connecting the XDP output on pin 18 (an inverted backplane
signal) to the required segment. This may also be done via logic or switches for automatic selection of the decimal points.

## Inputs

Pins 2 and 3 are the non-inverting and inverting inputs respectively; these analogue inputs are truly differential and may be operated to within 0V5 below the positive supply and 1 V above the negative supply. Common mode rejection ratio within this range is typically 86 dB .

## Voltage References

The Analogue Common pin is included primarily to set the common mode voltage for battery operation or for any system where the input signals are floating with respect to the power supply. The common pin sets a voltage that is approximately 2 V 8 more negative than the positive supply. This is selected to give a minimum end-of-life battery voltage of about 6 V . However, the analogue common has some of the attributes of a reference voltage. When the total supply voltage is large enough to cause the zener to regulate (greater than 7 V ) the common voltage will


Fig. 4 Measuring the ratio of two voltages. The maximum input voltage is $\pm 2 \mathrm{~V}$ with a 9 V supply.


Fig. 5 Measuring a floating voltage source with 200 mV full scale. Autopolarity indication is implemented, together with the decimal point and mV annunciation.

| TABLE 2 |  |  |  |
| :---: | :---: | :---: | :---: |
|  | REQUIRED FSD | LA | $\mathbf{R}_{\mathbf{c}}$ |
| LA | 2 V | 10 M | 1M0 |
| (NHI)-6 | 20 V | 10 M | 100k |
| ) | 200 V | 10M | 10k |
|  | 2000 V | 10 M | 1 k 0 |
|  | 200 uA | LINK | 1 k 0 |
| N 10 ) | 2 mA | LINK | 100R |
|  | 20 mA | LINK | 10R |
|  | 200 mA | LINK | 1R |

have a low voltage coefficient. ( $0.001 \%$ ), low output impedance (about 15R), and a temperature coefficient typically less than $800 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$.

The analogue-to-digital converter of the IC operates in a ratiometric mode, such that the digital display is $1000 \mathrm{~V} 2 / \mathrm{V} 1$, as shown in the diagram of Fig. 4. Here, the inverting inputs of the reference and voltage inputs are both connected to common (REF LO and IN LO). REF HI is normally connected to the 100 mV bandgap reference from REF + as shown in Fig. 5, thus giving the 200 mV full-scale deflection. Output REF + is 100 mV with respect to REF - when the latter is correctly terminated. REF BG is 1V2 with respect to REF - . REF - should normally connect to the COM terminal as the diagram indicates.

To alter the full-scale reading of the DVM module, the link LA and resistor $\mathrm{R}_{\mathrm{c}}$ shown in the circuit of Fig. 3 should be altered. Table 2 shows the values required for several ranges of current and voltage.

## Outputs

The polarity output on pin 7 is a square wave in-phase with the backplane signal when the analogue input has positive polarity and in anti-phase when the input has negative polarity. It can be connected directly to the " - "'symbol (pin 23) for normal
polarity indication. The clock on pin 16 may be used for systems timing or as an inpat to override the internal oscillator and control the sample rate. If CLK is connected to V - the display may be held at a particular value but this should not be connected for extended periods as the steady DC potential applied to the LCD may cause the segments to "burn".

The oscillator frequency is divided by four before it clocks the decade counters. It is then further divided to form the three convert-cycle phases. These are signal integrate ( 1000 counts), reference de-integrate ( 0 to 2000 counts) and auto-zero ( 1000 to 3000 counts). For signals less than full scale, auto-zero gets the unused portion of reference de-integrate. This makes a complete measure cycle of 4000 ( 16000 clock pulses) independent of input voltage.

An oscillator frequency of 48 kHz is used for three readings per second.

## Test

The test pin serves two functions. It is coupled to the internally generated digital ground through a 500 R resistor (digital ground is set at approximately 5 V below +V ). Thus when operated from a single battery supply, TEST can be used as the 0 V rail for externally generated segment drivers, such as decimal points (or any other presentation the user may want to include on the LCD display), or it may be used as a common mode reference level to ensure compatibility with most op-amps.

If TEST is connected to $\mathrm{V}+$ the LCD segments will be turned on and the display will read as shown in Fig. 6(This mode should not be used for extended periods, to avoid damage to the LCD).

## $-1688$

Fig. 6 The display when in the 'TEST' condition.

| SPECIFICATION |  |
| :---: | :---: |
| Input impedance: | $>100 \mathrm{M}$ |
| Full scale reading: | 199.9 mV |
| Accuracy: | $0.05 \%$ of reading $\pm 1$ digit |
| Power supply: | $5-15 \mathrm{VDC}$ |
| Power consumption: | 50 uA (in low power mode), typically 8,000 hours PP3 life |
| Sample rate: | 3 readings per second |
| Auto-zero: | No necessity to adjust for offsets |
| Auto-polarity: | Automatic polarity indication eliminates the need to reverse input leads to obtain correct reading. |
| Overrange warning: | 1 in leading digit with other digits suppressed |
| Bandgap reference ( $50 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ typ.) | incorporated tor excellent stability of reading |
| Digit height: | $15 \mathrm{~mm}\left(0.6^{\prime \prime}\right)$ can be read at distances up to 10 metres |
| Low battery warning: | direct display, voltage threshold easily adjusted |
| Operating temperature: | $0^{\circ} \mathrm{C}$ to $50^{\circ} \mathrm{C}$ |
| Overall dimensions: | $72 \times 36 \times 12 \mathrm{~mm}$ |
| Panel cut-out: | $68 \times 33 \mathrm{~mm}$ |
| Display annunciators: | many useful legends are built into the custom LCD which may be activated as required |
| Auto-zero | With the inputs shorted, the display should read zero, the negative sign being. displayed about $50 \%$ of the time |
| Overrange: | Inputs greater than full scale will cause suppression of the three least significant digits, i.e. only 1 or -1 will be displayed |
| Polarity | The absence of a polarity sign indicates a positive input reading. A negative input is indicated by a negative sign. |

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In addition to the PCBs for this month's projects, we are making available some of the more popular designs from our recent past. See the list below for details. Please note that NO OTHER BOARDS ARE AVAILABLE. If it's not listed, we don't have it!

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| 4 | 9 | 2 | 9 |  |  |  |  |  |  |  |  | $\square$ |

Signed
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Address

# SOUND TRACK <br> Play it again (and again, and again), SAM! 

 When you feel like working off your aggressions, try to zap the nasties as they fly past. Design and development by Phil Walker.The ETI Sound Track is an 'arcade' game you can carry in your pocket. It requires no special displays as all the cues are sounds. The object of the game is to intercept all 15 of the attackers with your own armament. In order to do this you have to judge the best moment to fire from the simulated sound of the attacker. It is made more realistic by the fact that both volume and frequency changes due to Doppler shift are included. As the game progresses the speed of the attack increases to prevent you getting too used to one pace. Also there are three levels of skill which determine how difficult it is to hit the attackers at all.

At the end of the game, if enough of the attackers have been intercepted, an LED will light up to
give an assessment of your performance. As an option, an aiming control can be fitted, if space permits, which will allow multiple shors if you are quick enough. To start the game, press the reset button and wait for the first attack. Now it's up to you. Bear in mind that your shots are effective only at the end of the shooting noise and while the target light is on,

## The Circuit

The circuit for this project uses standard op-amps, CMOS counters and gates and a special sound effects IC. This allows us to make fairly realistic sounds to simulate an object flying past, some sort of weapon being fired and an explosion if a successful interception has been

made. In order to make the completed project hand-held, the PCB is fairly crowded but quite a lot has been put onto it.

The heart of the system is a voltage controlled oscillator operating at a frequency of less than 0.2 Hz . This provides two outputs; one is an asymmetrical triangle wave which controls the attack sound effect and simulates the position of the target while the other output is a logic signal to drive the score counters. The VCO frequency is modified by the attack counter such that the attacks proceed more rapidly as the game progresses.

The fire control section of the circuit produces two signals. The first of these is a long pulse which causes the shooting sound to be made by the sound generator. The second, immediately after, is a short pulse which enables the hit detector. If at the same time the ramp from the VCO is within the limits of the window discriminator in the hit detector, then a HIT will be registered and the HIT counter updated. At the same time the sound generator will be switched to provide an explosion effect.

The sound select logic and analogue control switching (in the absence of any other demand) will
assume an attack sequence and configure the sound generator to give a mixture of white noise and a tone. As the ramp voltage from the VCO falls, simulating an attack, the volume will increase to a maximum and then decrease again. Simultaneously, as the volume reaches its peak, the pitch of the tone will decrease rapidly and stabilise at a lower level to simulate Doppler shift. While the ramp voltage returns to its starting level the sound generator is inhibited.

If either shooting or explosion effects are demanded, these will take precedence over the attack sound. The explosion is produced by envelopeshaping the white noise source in the chip while the shooting sound is given by an audio frequency VCO, frequency-modulated by a much lower frequency triangle wave.

The display given by the LEDs is to give some indication of the number of successful interceptions made in a game. The first LED will light when eight out of the 15 attacks have been stopped. The next will light at 12 , then 14 , and finally 15. There is one other LED which flashes each time a HIT is possible, but note that the shoot button usually has to be pressed before it lights.

## Construction

No major problems should be encountered in making this project; care must be taken when soldering the board as there are many places where tracks run between IC pins. Make sure that all the links are in


Fig. 1 Component overlay for the Sound track hand-held 'arcade' game. Note that some components are mounted off-board; see the photographs.
place and that diodes, ICs and polarised capacitors are the right way round. Low profile IC sockets may be used but the case we used may then be a little tight.

SW1, R6 and R7 were mounted so that they fitted beside the battery compartment on one side while PB1 and PB2 went the other side. The LEDS are mounted on the front of the box so that they poke through the panel; use a little glue to hold them in place. Some interconnection work
and components have to be put on to these (D7-10) and this should be kept as close to the panel as possible. If there is room, fit RV1 and R7 but this will only be possible if a very small potentiometer is available or a different box is used.

All interwiring should be carried out using thin flexible wire and kept as short as practicable. When fixing the loudspeaker check first that it will fit in the desired position and adjust fixing pillars etc. to ensure this. It is

## PARTS LIST


_PROJECT : Sound Track


Fig. 2 Circuit diagram for the Sound Track.
intended that it fits with part of the cone overlapping the battery compartment so a little shaving with a
 the speaker position is known, drill a series of holes in the panel and glue it into position.

The witing may now be
completed and the box assembled to
finish the project Fit a PP3 battery to
the connectors and it should be ready. the connectors and it should be ready


The on-off switch, SW2, is mounted on
the front panel at the bottom right-hand
side such that it will be over R38, 41-43.

## BUYLINES

Not too much here that's hard to find. The sound generator chip is one of the latest ones from the Texas Instruments range, so it
should be available from TI stockists such as Technomatic and Watford Electronics. The Pac-tec case is available from Watford or direct from OK Machine and Tool Ltd, 22




## HOW IT WORKS

to make it conduct) the output voltage will e the same as the input. When, however, Q6 starts to conduct, the junction of R38,
R41, and R43 will stay at a constant potenR41, and R43 will stay at a constant potenvoltage rises, more current will flow into the voltage rises, more current will flow into the
circuit via $\mathbf{R 3 8}$. A small amount of this will go through R41 to drive Q6 further into conduction, drawing the rest out via R43. This action will continue until the voltage across $Q 6$ is virtually zero again. The output from Q6 drives the volume control pin of
IC10 via IC9a.

The last effect is of a decaying explosion. While IC10 will produce the noise of
the explosion, the decay envelope has to be generated by Q3 and Q4. Most of the time the base of Q3 is held at 5 V 6 by the output of IC7d (part of the "HIT"' latch). In the event of a 'HIT'' being registered, the base
of O 3 will now be driven low. C6, which previously was held at about 5 V by Q3, will start to discharge via R35. The voltage on C6 is buffered by Q4 and fed to IC10 by
IC9c. Also for the explosion effect, R44 is IC9c. Also for the explosion effect, R44 is
connected into circuit by IC9b. This changes the noise slightly to give a more realistic sound. C11 and R48 are included in the amplifier circuit feedback to give more
 down on the hiss effect of the digital
generation of the various noises.
suitable display on the LEDs when Q5 is enabled by IC5a at the end of the game.范 only a short pulse is available at its output. The analogue control signals for the sound generator chip IC10 ae produced in three parts and switched into circuit when
required by IC9. The control signals for IC9
 AND gate made up of D6, D5, and R37. The analogue control signals are produced individually. The Doppler styie fall in frequency as each attack progresses is produced by IC2b. This device has a fairly high gain and at the start of the attack its output is driven to the positive rail by the ramp output from the VCO. As the ramp voltage
falls past the reference voltage the output of falls past the reference voltage the output of IC2b will change from positive to negative
quickly (but not instantanously). If there is quickly (but not instantanously). If there is output will modulate the oscillator in IC10 via R45.

Another effect required to simulate an object passing is that the noise produced by it will first increase and then decrease. This is accomplished by the circuit around Q6. output is low. At low voltages Q 6 will be off but the output will again be low. As the voltage applied to the circuit increases, (until the voltage on the base of Q 6 is sufficient

IC1b buffers the voltage at the junction of R1 and R2 to give a reference at half the
supply. IC1a and IC2c form a very low fresupply. voltage controlled oscillator. R20-23 make a simple D-to-A converter which varies the VCO frequency by a small amount as the game progresses. The timing VCO and provision is made by D $1-3$ to stop the circuit oscillating when the required 15 IC2a and IC2d form a window comparator whose position and width can be varied by RV1 and SW1. IC3a and IC3c are connected as a monostable and are triggered by PBI being closed. C3 ensures that the
period of the monostable is not affected by further dosures of PB1. When the monostable time ends, IC3b is enabled for a short time determined by R31 and C4. This signal is inverted by IC8b and is applied
with the outputs from the window comwith the outputs from the window com-
parator circuit to ICGa. If all the inputs to this IC are high at the same time this signifies a "HIT"' and the output of ICGa will go low. This action causes the latch formed by IC7c and IC7d to be set with IC7c output high. The resulting low on
IC4b clock input increments that counter, increasing the score, while further counting on the same attack run is prevented by the
latch action in IC7c/d. IC5b, $6 \mathrm{~b}, 7 \mathrm{~b}$ and 7 d decode the outputs from IC4b to give a


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# DATA SHEET 

The HOS-100 high speed, bipolar, voltage follower/buffer amplifier is designed to provide high current drive at frequencies from D.C. to 125 MHz . Featuring a slew rate of $1400 \mathrm{~V} / \mu \mathrm{s}$, output drive of $\pm 10 \mathrm{~mA}$ into $1 \mathrm{~K} \Omega$ loads, excellent phase linearity ( $2^{\circ}$ ) and low distortion ( $<0.1 \%$ ).
Ideal for wide range for buffer applications including high impedance input buffers for fast $A$ to $D$ convertors and comparators, coaxial cable drivers, yoke drivers in high resolution CRT displays etc.

## Features

$\square$ Wide Bandwidth - d.c. to 125 MHz
$\square$ High Slew Rate $-1400 \mathrm{~V} / \mu \mathrm{s}$
$\square$ Operating Temperature Range $-25^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
$\square$ High Output Drive $- \pm 10 \mathrm{~V}$ with $100 \Omega$ Load

## Applications

$\square$ Current Boosters
$\square$ High Speed AVD Input Buffers
$\square$ Coaxial Cable Drive
$\square$ High Speed Line Drivers
$\square$ Video Impedance Transformation

## Absolute Maximum Ratings

| ximum Continuous Output Current ximum Peak Output Current erating Temperature Range (Case) |
| :---: |
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## Electrical Characteristics

$\left(V_{S}= \pm 15 \mathrm{~V}, R_{L}=1 \mathrm{k} \Omega . T_{C}=25^{\circ} \mathrm{C}\right)$


| Parameters | Conditions | Min | Typ | Max | Units |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Input Bias Current Input Impedance | $\mathrm{V}_{\text {IN }}=1 \mathrm{~V} \mathrm{rms} . \mathfrak{f}=1 \mathrm{kHz}$ | 100 | $\begin{aligned} & 5 \\ & 200 \\ & \hline \end{aligned}$ | 25 | $\mu \mathrm{A}$ k / |
| Voltage Gain | $\mathrm{V}_{\text {IN }}=1 \mathrm{~V} \mathrm{rms} . \mathrm{f}=1 \mathrm{kHz}$ | 0.94 | 0.96 | 1.0 | VN |
| Output Offset Voltage | $R_{S}=50 \Omega$ |  | 10 | 25 | mV |
| Output Offset Voltage Tc | $R_{S}=50 \Omega$ |  | 25 | 75* | $\mu \mathrm{V} /{ }^{\circ} \mathrm{C}$ |
| Output Impedance | $\mathrm{V}_{\text {IN }}=1 \mathrm{Vrms}, \mathrm{f}=1 \mathrm{kHz}, \mathrm{R}_{\mathrm{S}}=500 \Omega$ |  | 8 | 12* | $\Omega$ |
| Output Voltage Swing | $\begin{aligned} & R_{S}=50 \Omega \\ & V_{S}= \pm 5 \mathrm{~V} \end{aligned}$ | $\pm 12^{*}$ | $\begin{aligned} & \pm 13 \\ & \hline \end{aligned}$ |  | V |
| Supply Current | $\begin{aligned} & V_{1 N}=0 V \cdot V_{S}= \pm i 5 . \\ & V_{S}= \pm 5 \end{aligned}$ |  | $\begin{aligned} & 15 \\ & 10 \\ & \hline \end{aligned}$ | 20 | mA mA |
| Power Consumption | $\mathrm{V}_{1 \mathrm{~N}}=\mathrm{OV}$ |  | 450 | 600 | mW |
| Slew Rate | $V_{1 N}= \pm 10 \mathrm{~V}, \mathrm{R}_{\mathrm{S}}=50 \Omega$ | 1000 | 1400 |  | $\mathrm{V} / \mu \mathrm{s}$ |
| Bandwidth | $\mathrm{V}_{\text {IV }}=1 \mathrm{Vrms} . \mathrm{R}_{\mathrm{S}}=50 \Omega$ | 100 | 125 |  | MHz |
| Rise Time | $\Delta V_{\text {IN }}=0.5 \mathrm{~V} . R_{S}=50 \Omega$ |  | 2 |  | ns |
| Propagation Delay | $\Delta \mathrm{V}_{1 \mathrm{~N}}=0.5 \mathrm{~V} . \mathrm{R}_{\mathrm{S}}=50 \Omega$ |  | 1.5 |  | ns |
| Phase Nonlinerearity | $\mathrm{BW}=1$ to $20 \mathrm{MHz}, \mathrm{R}_{\mathrm{S}}=50 \Omega$ |  | 2 |  | Degrees |
| Harmonic Distortion | $f>1 \mathrm{kHz}, \mathrm{R}_{\mathrm{S}}=50 \Omega$ |  | $<0.1$ |  | \% |

[^3]
## Typical Performance Curves



Figure 2: Frequency response


Figure 3: Output offset voltage vs temperature


Figure 4: output voltage vs supply voltage Supply current vs supply voltage

## Applications

## Layout Considerations

As is the case with any high-speed design, proper layout is critical to avoid the introduction of unnecessary errors due to high-frequency coupling, stray capacitance, and the like.

Large ground planes should be used whenever possible to provide a low resistance, low inductance circuit path, as well as shielding the effects of high-frequency coupling. Sockets should be avoided, as the increased inter-lead capacitance can degrade bandwidth. Input and output connections should be kept as short as practical.

## Capacitive Loading

The HOS-100 has been designed to drive capacitive loads of several thousand picofarads (such as coaxial cable) without oscillation. In these applications, peak current resulting from ( $\mathrm{C} \times \mathrm{dv} / \mathrm{dt}$ ) should be limited below the absolute maximum peak current rating of $\pm 250 \mathrm{~mA}$.

Also, power dissipation due to driving capacitive loads plus standby power should be kept below the total power rating of 1.5 W .

## Typical Applications



Figure 5: Current booster


Figure 6: Coaxial cable driver


Figure 7: High speed shield/line driver


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## ETIMOBILE 2

Regular readers will have followed our Motor Control series with (we hope!) a curious interest. It may have crossed your mind to wonder exactly what ETI is up to now. All this talk of Robot Control and no robot!

Way back in our April issue we showed the base of our Mobile 2, and since then have been steadily mounting modules into it, building up the basis of an advanced robotics project.

This month it's time to lay out the complete series and to involve the future participants and designers in the project - you! We have developed a complete mobile, with arm and
computer link which we will be presenting over the next few months. After that it's up to you, our readers. We hope to be able to continue the series with projects and features based upon your designs and programs for the Mobile 2.

## Too Mobile?

The complete ETI Mobile comprises a tracked base with servo driven arm - for which a low-cost metalwork kit is available-infra-red proximity detectors, on-board interface and control circuitry, wireless link to a home computer port and an experimental positional detection system.

Enough of this 'you and us' attitude-it's time for some reader involvement. We've been publishing robot modules thick and fast, but now it's your turn to be inventive; together we can make beautiful robots.

The home computer acts as the "brain'" and can be thus programmed to make decisions upon the information returned to it by the Mobile. The latter's motor drive system is linked via an eight-bit port arrangement to the control board, placing the tracks directly under computer control.

This means that a set of prearranged instructions can be sent to the mobile, causing it to follow a path around obstacles and obstructions, thus functioning in any environment. As the computer carries all the software, decisions upon "what to do if..."' can be modified and expanded at the touch of a cursor!

Similarly, the arm is ported onto the bi-directional data link and can be software controlled from the computer. Alternatively the arm may be used as a 'stand-alone' design, for which the interface has also been configured.

## Some Arm In it

The servo-driven manipulator we are proud of! Produced in conjunction with Remcon Electronics, it overcomes many of the complex mechanical hangups which beset earlier constructs.

It is ideal for teaching purposes, being controllable by any of:
(i) a standard radio control system, such as employed in model aircraft, etc.
(ii) a 'tele-operator' which allows direct instruction of the arm - and the pupil operating it.
(iii) a microcomputer, using our interface.


Above: The analogue PWM control board and motor driver board for the Mobile 2.

Below: The Mobile 2 with hand controller and servo manipulator.

 unit.

| MOBILE $2-$ |  |
| :---: | :---: |
| MECHANICAL |  |
| SPECIFICATTON |  |
| TRACTOR UNIT |  |
| Dimensions: | $193 / 4^{\prime \prime} \times 131 / 2^{\prime \prime} \times$ |
|  | 51/2" high (unloaded) |
| Ground Clearance: | 11/4" unladen |
| Operational Payload: | 11 lbs . |
| Will climb a 3" stepped full payload. | bstruction with |
| Ratio of drive units: | 60:1 (variable, see Buylines). |
| Drive Voltage: | 7V2 |
| Starting Current: | 9 A |
| Running current: | 3 A 5 |
| Operational Velocity: | 2.5 feet per second. |
| Smooth Incline Capability: | $30^{\circ}$ |

By varying the type of servo employed, the function and power of the arm can be selected to suit the application required.

To reduce the load placed on the servos, the arm is designed to be selfbalancing, whatever servos are used. On the standard manipulator, high resolution types are employed to improve accuracy as much as possible
while under computer control.
The mechanical set-up of these arms is critical for best performance, and for that reason we have arranged that they be supplied built and tested, as part of the mobile metalwork, or as a separate item if you prefer. Buylines has the details.

## Base Comments

The heart of the whole system is the tractor unit upon which the Mobile is constructed. The final design, although very simple in appearance, has only been arrived at after much debate and experimentation.

Tracks were used for their superior abilities with regard to climbing obstacles and coping with varying surfaces, ie. carpet, concrete, vinyl, etc. Infra-red rotation counters are fitted to both the motordrive shafts, to enable accurate control to be exercised over both the base speed and direction.

A brief spec of the capabilities of the base are given elsewhere in this article. All the metalwork is purpose built, and pre-drilled for our range of modules. After having tried out various commercial options - model tank mechanics, for example - we came to
the conclusion that not only is it the superior to have custom metalwork made - it is actually cheaper! Initially we had ruled it out purely on grounds of expected price level.

## How Close Encounters?

Mobile 2 is a fairly large beast to let loose around your living room ( $19 \times 13$ x $5^{\prime \prime}$ approx. not including arm and cover!) and so it is important that it be prevented from colliding with obstacles. Remember that so far as it is concerned anything in the way, be it your prize drinks cabinet, hi-fi speaker or granny, is simply an obstruction.

In our June 82 edition we published our 'Proximity Detector' module, of which Mobile 2 has four. They are mounted above each track corner and may be angled, such that even glancing contact is prevented. They provide adequate protection.

The control board logic is so configured that the IR detectors provide an override which halts operation of any program, so long as an obstacle is present. Unless programmed to do anything else, the mobile will halt at any obstruction large enough to register on two detectors, ie a wall.

## Well Developed Robot

Our Mobile 2 is presented as an open-ended project. We want our readers to carry it on and develop it as far as they can. The modules to come from $u s$ will be:

1) Arm Interface and control circuitry, to allow stand-alone control, or porting to main PCB of Mobile 2.
2) Main Control PCB - mounted within the mobile and will accept up to four eight-bit peripherals, with appropriate strobing, and operate in conjunction with the link.
3) Computer Link - a bi-directional data transfer system which has as a receiver a home computer system to which it connects via a standard interface.
4) Experimental Positional System - to allow the Mobile to 'map' its environment and thus function more precisely.
One future use for the Mobile which we are still working on - is that of office messenger. It would be 'called' to a particular room or desk, loaded with papers, etc, and dispatched to another location, programmed at point of departure. It will have to avoid doors, people and cats whilst doing so! That one may be a while coming if left to us,
but we'll get there! It would use the same metalwork and basic electronics.
"If left to us" is the key phrase there - what about that vast reservoir of design talent and ingenuity that goes under the name of ETI's readership? It's about time you got into robotics, too!

Once we complete the basics of this project, then its up to you to carry it on. Even now, if you have any ideas or strong feeling as to how the Mobile should grow, let's hear them. We will publish what correspondence we can on the subject and implement any ideas which are practical!

Next month, we commence construction of the Mobile with the base, motors and speed control. Past modules which will be used in the Robot were published in:-

1) ETI March 82 p. 61-63
2) ETI April 82 p. 94-97
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