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# ham radio

**magazine**

# FM

**techniques  
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## *this month*

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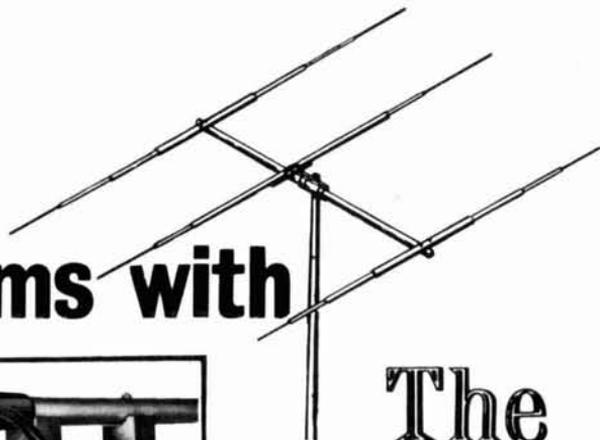
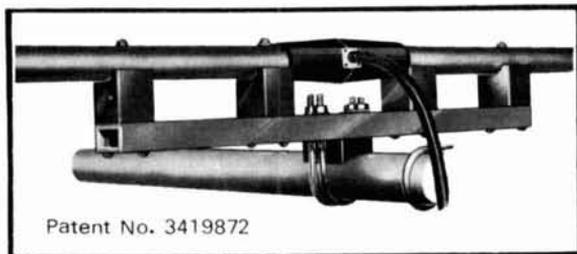
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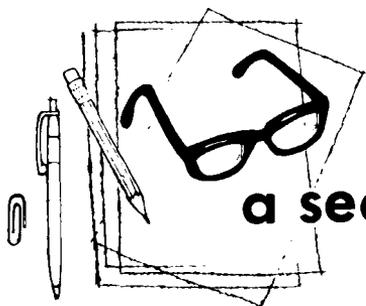
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## a second look

by Jim  
fisk

**One of the things that makes** amateur radio stand out among other recreational pursuits is the diversification it offers. Many hams like to relax after a hard day's work and talk to friends, handle traffic, or chase DX. To others, amateur radio is a means for intellectual development and personal achievement. Some fellows have a drive that makes them explore beyond the canned circuit and ready-made construction project. They like to improve, modify, innovate. These are the experimenters, and their greatest satisfaction comes from finding new ways to do things. They must know what makes things tick and why. The experimenters are truly responsible for the perpetuation of our hobby. Without them, it's doubtful if amateur radio would have existed as we know it today.

If you're a serious experimenter, ham radio can be a means of enhancing your advancement in electronics. An example is the ham who is also an engineer. When solving a design problem at work, he may remember something he's read that somehow correlates with his immediate task. He may even work on the idea at home. Often these experimenters make significant contributions to the advancement of electronics—you see their results published in the literature.

One of the many areas open to experimenters is medical electronics. Doctors working on research projects in the medical disciplines can use the help of electronic engineers and technicians. For example, a physician working in radio isotope research needed an interface between his computer and a photoelectric sensor. This would be a fairly simple task for one familiar with digital circuits. The doctor needed a buffer memory

and an analog-digital converter. He couldn't find anyone to help him, so he boned up on theory and actually built the thing himself—it worked!

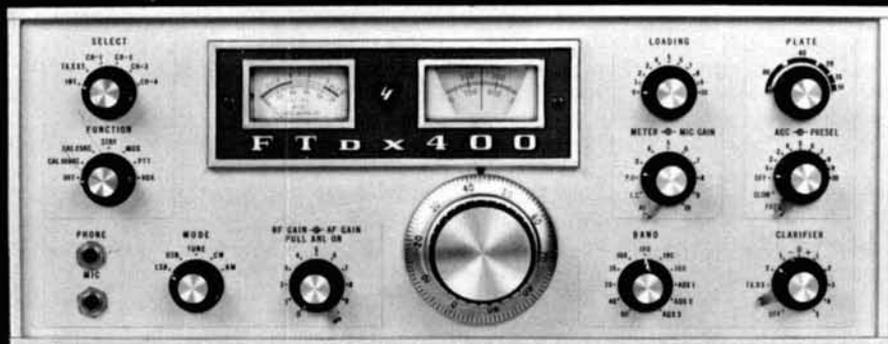
Remember the tunnel diode? Engineers in the Device Research Branch of NASA's Electronic Research Center found that pressure applied to a tunnel diode made of gallium antimonide caused the diode's band gap to vary. Apparently, pressure differential in this region changes the inflection point on the diode's characteristic current-voltage curve. The resulting change in negative resistance (and hence maximum gain) makes the device useful as a transducer.

The NASA research people built a tunnel diode transducer using these principles. The transducer was about 0.05 mm thick—small enough to pass through the eye of a needle. Power requirements were 50  $\mu$ W with 50 mV input. When inserted into the cardiovascular system, the diode reproduces minute changes in blood pressure. To the physician, these variations reveal essential data on heart activity and the circulatory system. The transducer's extremely small size allows doctors to monitor blood-pressure parameters heretofore undetectable with conventional sensors.

These are but a few things open to electronic experimentation. You probably won't come up with anything as exotic as a cardiovascular transducer, of course, but surely you must have some ideas that are worth developing in your home workshop. For example, how many different applications can you think of for the IC operational amplifier? Think about it, work up a design, then heat up your soldering iron.

**Jim Fisk, W1DTY**  
editor

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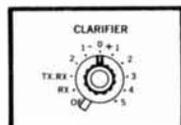
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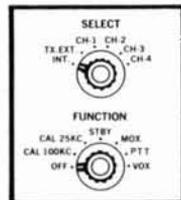
Design features include double conversion system for both transmit and receive functions resulting in, drift free operation, high sensitivity and image rejection • Switch selected metering • The FT dx 400 utilizes 18 tubes and 42 silicon semi-conductors in hybrid circuits designed to optimize the natural advantages of both tubes and transistors • Planetary gear tuning dial cover 500 KHz in 1 KHz increments • Glass-epoxy circuit boards • Final amplifier uses the popular 6KD6 tubes.

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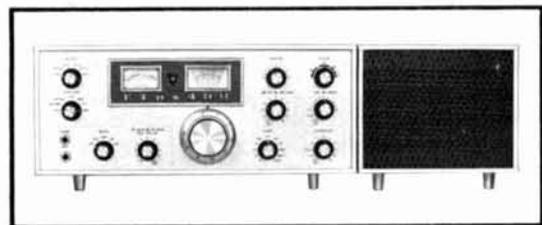


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# fm techniques and practices for vhf amateurs

In 1937 the residents along the New York and New Jersey sides of the Hudson River were awed and mystified by the appearance of a gigantic spidery structure that arose near Alpine, New Jersey. It was whispered by the local wags that this tower transmitted "secret waves," and rumors flew that the tower was used to contact inhabitants of Mars, that it was used for death-ray experiments, and that it was used for secret communications with the hereafter.

None of these wild stories, of course, were true. The appearance of the tower was the first public knowledge of a new mode of radio communication, based upon experiments of Major Edwin H. Armstrong of Columbia University, an early wireless pioneer and inventor of the regenerative receiving circuit.

## static-free radio

Major Armstrong had long realized that amplitude-modulated broadcasting suffered badly from static interference generated by electrical machinery and from crashes and noises created by natural electrical discharges in the atmosphere. It was Armstrong's belief, supported by the 1922 mathematical studies of John Carson,<sup>1</sup> that the way to avoid static was to artificially produce a radio signal differing as radically as possible from the static signals that wreaked havoc with a-m broadcast transmissions. If this could be done, a receiver could be built which would be insensitive to static interference.

Armstrong reasoned that random noise and static were amplitude variations that had no orderly variations in frequency. He proposed that a receiver be built that would be sensitive to frequency shifts but insensitive to amplitude variations. He started to work on such a receiver, plus a companion transmitter to generate a **frequency modulated** (fm) signal. During the course of his experiments in the Alpine, New Jersey laboratory, a 400-foot tower was erected. This impressive structure, with three large crossarms, was visible for miles along the banks of the Hudson River.

In 1934, before the tower was built, Armstrong conducted preliminary experimental frequency-modulated tests with a 50 watt fm transmitter atop the Empire State Building. These tests were run in conjunction with W2AG, Yonkers, New York, who operated a 50-watt fm transmitter at 120 MHz in the old 2 $\frac{1}{2}$ -meter amateur band. Voice, music, facsimile and multiplex telegraphy were transmitted by fm to W2AG.

In 1935, encouraged by the results of the tests, Armstrong applied to the FCC for an experimental fm license and was granted the call W2XMN for use in the experimental frequency region around 40 MHz. Armstrong's fm tests were soon followed by others, particularly by Connecticut State College, operating stations W1XCS and W1XPW near 43 MHz. Finally the FCC set aside four channels—200 kHz bandwidth each—for exclusive fm broadcasting in the 40-MHz band. Commercial fm broadcasting was finally launched, although it was nearly eclipsed by World War II and the advent of commercial television.

Radio amateur interest in fm techniques was aroused by the W2AG tests, and during the period from 1935 to 1940 a series of classic articles in *QST*, *Radio* and *Electronics*<sup>3-8</sup> provided practical circuitry for the

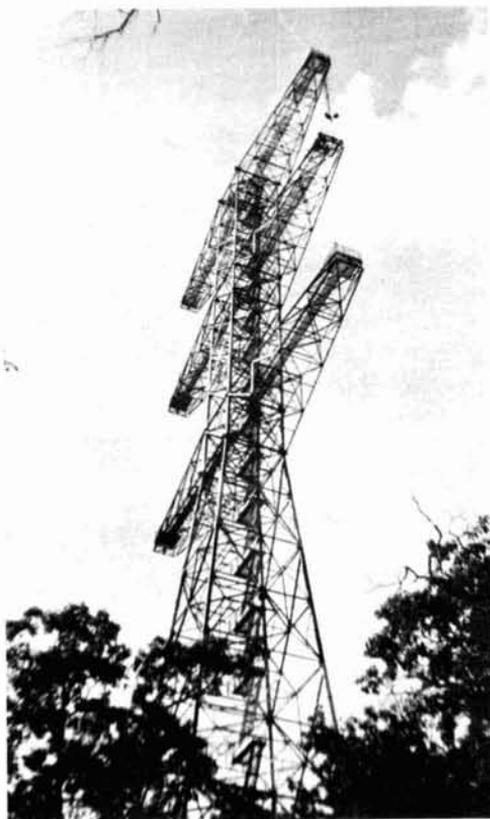
William I. Orr, W6SAI, Eimac Division of Varian, San Carlos, California 94070

transmission and reception of fm signals in the amateur 5-meter band. Amateur experiments before the war showed that fm promised excellent prospects for static-free, reliable mobile communication on the "ultra high" frequencies of  $2\frac{1}{2}$  and  $1\frac{1}{4}$  meters.

### post war fm

Frequency modulation proved its worth during World War II when it was extensively used for vhf vehicular communication and over-the-horizon military relay circuits. Unfortunately, the times were against amateur fm usage in the late 1940's. Aside from sporadic use on the higher frequencies, fm languished in the amateur bands. In the vhf bands where it would have been effective, fm was obliterated by the flood of surplus a-m gear that invaded the market.

**The tower at Alpine, New Jersey as it appeared in 1940. The man working on the 42.8-MHz turnstile antenna is supposedly Armstrong in his bucket sling.**



The SCR-522 a-m transmitter-receiver was king as far as the new 2-meter band was concerned. Aside from a few eccentrics, vhf operators restricted themselves to a-m, with a sprinkling of cw for DX work. Some narrow-band fm experiments took place on the hf amateur bands, but nbfm never proved popular except as a means for escaping broadcast interference. By 1950 or so, amateur fm was largely forgotten.

While amateurs limited their efforts to a-m in the world above 50 MHz, the mobile radio service, quick to see the advantages of fm, made a complete conversion to that mode, using 50-kHz channels and crystal-controlled transmitters and receivers. Eventually, the scarcity of channels in the mobile radio service spectrum became so acute that channel spacing was halved to 25 kHz. This released a flood of obsolete mobile fm gear to the amateur surplus market.

Amateurs soon realized the inherent advantages of this "new" form of vhf communication, and today the use of fm is increasingly popular on the higher frequency bands. Indeed, I predict that fm will eventually supplant a-m and ssb on the 144-, 220- and 432-MHz amateur bands in the metropolitan areas of the United States and Canada. The application of fm techniques in combination with stationary, remote repeater systems will bring about a revolution in the operating habits of vhf oriented amateurs during the coming decade.

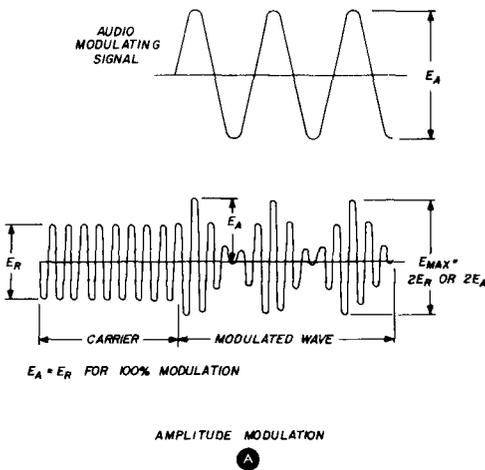
This article covers frequency modulation fundamentals and techniques and discusses the use of fm equipment and repeaters. It is hoped that it will serve as an introduction and stimulant to amateurs who have not yet experienced the thrill of using vhf fm communication as a means of reliable short range communication.

### fm: what is it?

Intelligence may be superimposed upon a steady radio signal (carrier wave) by altering the structure of the wave in some way. The amplitude of the wave may be changed as is done in amplitude modulation or ssb. Or, the frequency, or phase, of the wave may be varied. In either case, the process of altering the radio wave in accord with the transmitted

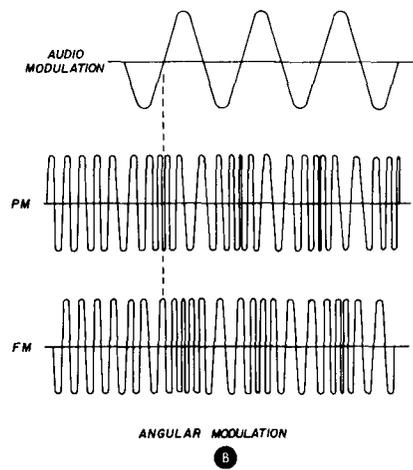
intelligence is called **modulation**. Modulation imparts a distinguishing characteristic to the radio wave which enables a properly designed receiver to convert it back into a replica of the original intelligence.

**Fig. 1A** shows an rf carrier that is amplitude modulated by a sinusoidal audio signal. The modulated rf wave varies about the zero axis at a constant rate, and the strength of the individual cycles of the wave is proportional to the amplitude of the modulating signal. The carrier is modulated 100 percent



each side of the carrier, spaced from the carrier by an interval equal to the modulation frequency. The strength of the carrier does not vary during modulation, but the strength of the sidebands depends upon the percentage of modulation. When the carrier is modulated 100 percent, the power in the sidebands is equal to one-half that of the carrier.

When an rf carrier is frequency modulated, many more than two additional side frequencies are generated. The first two are spaced from the carrier by the modulation frequency



**fig. 1. Amplitude modulation (A) and angular modulation (B) of an rf carrier by the same audio signal.**

when the peak-to-peak amplitude of the modulating signal is equal to the peak-to-peak amplitude of the unmodulated carrier.

In **fig. 1B** the rf carrier is frequency and phase modulated by the same audio signal. It can be seen that modulation voltage of one polarity causes the carrier frequency to decrease, as shown by the fact that the individual rf cycles are spaced farther apart. A modulating voltage of the opposite polarity causes the frequency to increase; this is shown by the fact that more rf cycles are completed in a given time interval. If the phase-modulated (pm) wave is shifted  $90^\circ$ , the two waves in **fig. 1B** look alike. No amplitude variation takes place in either wave.

When an rf carrier is amplitude modulated, additional side frequencies are generated. These frequencies (sidebands) are located on

each side of the carrier, spaced from each other by an amount equal to the modulating frequency. Theoretically, there are an infinite number of side frequencies; but, practically, the strength of those beyond the frequency swing of the modulated carrier is relatively low.

Unlike amplitude modulation, the strength of the carrier component of an fm wave varies widely; under certain conditions it may even disappear entirely. This variation in the strength of the carrier component is useful in measuring the modulation index, as will be discussed later.

### fm terms

There are several terms which convey considerable information about the character of

a frequency-modulated signal: deviation, swing, modulation index and deviation ratio.

**Deviation** specifies the amount of frequency shift to each side of the unmodulated carrier when the transmitter is modulated. Deviation is directly proportional to the amplitude of the modulating signal and is usually measured in kilohertz. The limits of frequency shift on either side of the carrier are known as the frequency deviation limits.

**Swing** is the total frequency range covered by an fm transmitter when modulated with a symmetrical signal (equal deviation to each side of the carrier frequency). If, for example, a transmitter operating on 50,000 kHz has its frequency shifted to 50,010 kHz, back to 50,000 kHz, then to 49,990 kHz, and back again to 50,000 kHz during one cycle of the modulating wave, the deviation is 10 kHz and the swing is 20 kHz.

**Modulation index** of an fm signal is the ratio of the maximum frequency deviation to the audio modulating frequency, when both are expressed in the same units. Thus, in the previous example, if the signal is varied from 50,000 kHz to 50,010 kHz to 49,990 kHz and back to 50,000 kHz at a rate (frequency) of 2000 times per second (modulation frequency = 2 kHz), the modulation index would be 5, since the deviation (10 kHz) is 5 times the modulating frequency (2 kHz). Expressed as a formula, the modulation index is:

$$\text{Modulation Index} = \frac{\text{Maximum Frequency Deviation}}{\text{Maximum Frequency of modulating signal}}$$

**Deviation ratio** is similar to the modulation index in that it involves the ratio between the modulating frequency and deviation. In this case, however, the deviation in question is the peak frequency shift obtained under full modulation, and the audio frequency considered is the highest one transmitted by the system. For example, if the maximum audio frequency to be transmitted is 3000 Hz, a deviation ratio of 3 would call for a peak deviation of 3 x 3000, or 9 kHz at full modulation.

The noise suppression capabilities of fm are directly related to the deviation ratio. When the deviation ratio is increased, noise suppression is better when the signal is stronger than the noise. When the noise approaches the signal in strength, however, lower deviation ratios allow communications to be maintained in many cases where high-deviation-ratio fm is incapable of giving service. This assumes that a narrow-band fm receiver is used.

For each value of received signal-to-noise ratio there is a maximum deviation ratio. Beyond this maximum deviation ratio the output audio signal-to-noise ratio decreases. Up to this critical deviation ratio, noise suppression becomes progressively better as the deviation ratio is increased.

For high-fidelity fm broadcasting, a deviation ratio of 5 is ordinarily used. The maximum audio frequency is 15 kHz and the peak deviation at full modulation is 75 kHz. For tv sound, the deviation ratio is 1.67, the maximum audio frequency is 15 kHz, and the peak deviation is 25 kHz.

Narrow-band fm has been standardized by the public services and business radio service. A maximum deviation of 5 kHz is used by these services in the vhf region with 25 kHz channel separation. In the uhf region a deviation of 15 kHz is used along with 50 kHz channel separation.

In the amateur service, the bandwidth of an fm signal on frequencies below 29 MHz and between 50.1 and 52.5 MHz cannot exceed that of an a-m signal having the same audio characteristics [Section 97.65(c)]. Thus, wideband fm can be used above 29 MHz on 10 meters, above 52.5 MHz on the 6-meter band and in all the amateur vhf and uhf bands. Most fm stations in the vhf amateur bands use deviations between 5 and 25 kHz, with a trend toward the lower values.

## fm sidebands

I mentioned earlier that additional side frequencies over and above those generated by a-m are created by frequency modulation. For distortionless transmission and bandwidth conversion a study of the spectrum of a frequency-modulated wave is useful. Mathematical studies and observation of the fm sidebands with a wave analyzer can provide

information that will allow efficient modulation under conditions of maximum deviation and minimum bandwidth.

The mathematical expressions for an fm or pm signal may be written as an infinite series having coefficients known as Bessel functions, named after a German mathematician who first studied variations of this kind. A physical representation of an fm or pm signal may be achieved by the use of a vector. The vector may be drawn as an arrow, with its

vector undergoes many rotations during each modulation cycle. As a result, the tip of the vector moves alternately inwards and outwards over a close multiturn spiral path.

Since the angular position of the vector is unaffected by amplitude modulation, the observer may ignore its rotation by considering it from the point of view of an observer who is rotating with it, and restrict his attention to its changing length. For a-m then, the representation can be reduced to a line which

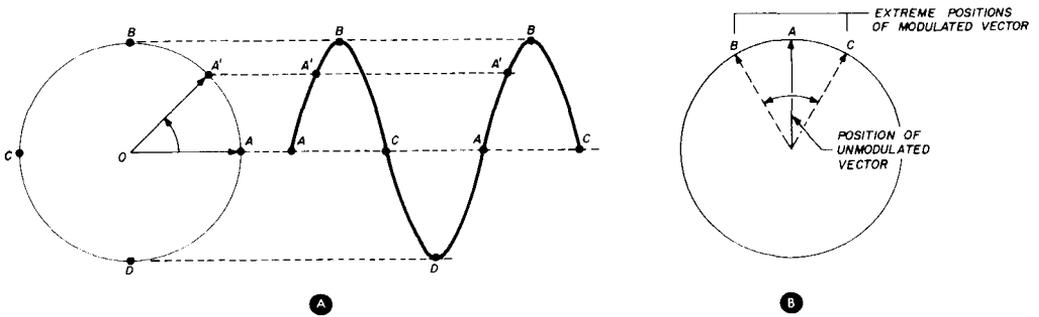


fig. 2. A rotating vector may be used to represent a sinusoidal wave (A). An fm signal may be regarded as a constant-length vector rotating with slowly varying speed; the angular displacement in advance or retard of normal is caused by angular modulation (B).

length denoting the magnitude of the voltage and the arrow indicating direction. The position of the vector with respect to various reference axes can be used to indicate angular displacement as is commonly done in vector representations of electric and magnetic fields. The frequency of an alternating voltage represented by a vector, for example, is proportional to the speed of rotation of the vector with respect to time.

The frequency-modulated carrier shown in fig. 1B may also be represented by visualizing the carrier as a vector rotating counterclockwise with time (fig. 2A). For each cycle of the sinusoidal carrier, the vector rotates one complete circle or  $360^\circ$ . This is the period of the wave; the vector rotates at a frequency equal to the wave it represents.

For the case of amplitude modulation, the vector rotates at the carrier frequency but alternately changes amplitude (at the modulation frequency) about its unmodulated value. Since the carrier frequency is much higher than the modulation frequency, the

expands and contracts at the modulation frequency and reverses its direction each time the modulation goes through zero.

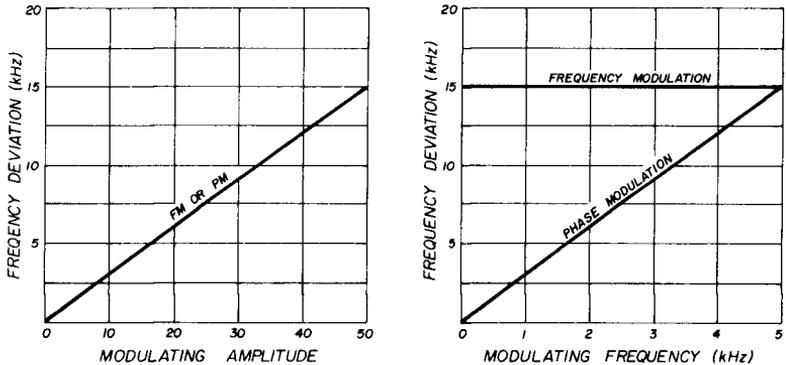
When the amplitude of the carrier vector is held constant, modulation may only be accomplished by changing the otherwise uniform rate of rotation of the vector. A constant amplitude, variable frequency signal can be represented by a vector of constant length, rotating with slowly varying speed. When the angular velocity of a vector is varied higher or lower about its mean value, its angular position is advanced or retarded from the angular position the unmodulated vector would have occupied (fig. 2B). Therefore, variations in angular velocity produce an alternate advance and retardation in the phase of the carrier.

Conversely, if it were desired to advance the angular position of the rotating vector by a certain amount it could only be done by temporarily increasing its angular velocity (frequency). Likewise, a backward shift of

the rotating vector could only be produced by reducing the frequency from the normal value. To preserve any lead or lag that was introduced, the frequency would be restored to its normal value.

Modulation based upon the advancement or retardation of the angular position of a rotating vector representing the carrier wave is called **angular modulation**. Two practical forms of angular modulation are **frequency modulation** and **phase modulation**.

fig. 3. Relationships between fm and pm. The only difference between pure fm and pm is the fact that the deviation is a function of the amplitude only of the modulating signal for fm while the frequency of the modulating signal also determines the deviation for pm.



### frequency and phase modulation

When frequency modulation is used, the phase of the carrier wave is indirectly affected. Similarly, when phase modulation is used, the carrier frequency is affected. You cannot vary frequency without changing phase and vice-versa. In view of the interrelationship between frequency and phase, with the two quantities changing together under angular modulation, the distinction between frequency and phase modulation is only a nominal one.

The only difference between pure frequency modulation and phase modulation is the fact that deviation is a function of **amplitude only** of the modulating signal for pure frequency modulation, while the **frequency** of the modulating signal **also** determines the deviation for phase modulation. A comparison of the two signal characteristics is shown in **fig. 3**.

Most modern fm transmitters use phase modulation, because frequency modulation can only be applied to an oscillator stage,

while phase modulation may be readily applied to any amplifier stage. Therefore, phase modulation is easily applied to crystal-controlled transmitters. With phase modulation, if an audio signal of 1000 Hz causes a deviation of 0.5 kHz, for example, a 2000 Hz modulating signal of the same amplitude will produce a deviation of 1 kHz, and so on. To produce an fm signal with this technique, it is only necessary to make the deviation independent of the frequency of modulation,

and proportional only to the amplitude of the modulating signal. This is accomplished by including a frequency correcting network in the transmitter.

The only disadvantage of pm, as compared to direct fm, is the fact that very little frequency deviation is produced directly by the phase modulator.\* The degree of deviation is dependent only upon the phase deviation produced on the modulation frequency:

$$F_d = M_p$$

\*This is the only obvious practical disadvantage. In reality, phase modulation suffers one other serious disadvantage. In pure fm, the spectrum width can be made nearly independent of the modulating frequency; this is not true with pure pm. The undesirable variation of bandwidth with modulating frequency in phase modulation can be corrected with a tailored audio clipper. The clipper is both pre-and post-equalized: audio with a 6-dB-per-octave rising characteristic is fed to the clipper; clipper output is then passed through a network with a 6-dB-per-octave falling characteristic. The processed audio going to the phase modulator has a flat response, but with tailored clipping which results in constant peak deviation after modulation.

where  $F_d$  is the frequency deviation one way from the mean value of the carrier, and  $M_p$  is the phase deviation accompanying modulation (expressed in radians per second). Note that the deviation is completely independent of the carrier frequency. The amount of phase shift that can be obtained with good linearity is such that the maximum practical modulation index is about 0.5.

deviation of 625 Hz at a crystal frequency of 6 MHz: this is well within the linear capability of a phase modulator. Some high-frequency fm gear designed for operation from 30 to 50 MHz uses crystals in the 200- to 500-kHz region to allow for sufficient frequency multiplication for satisfactory wide-band phase modulation at the carrier frequency.

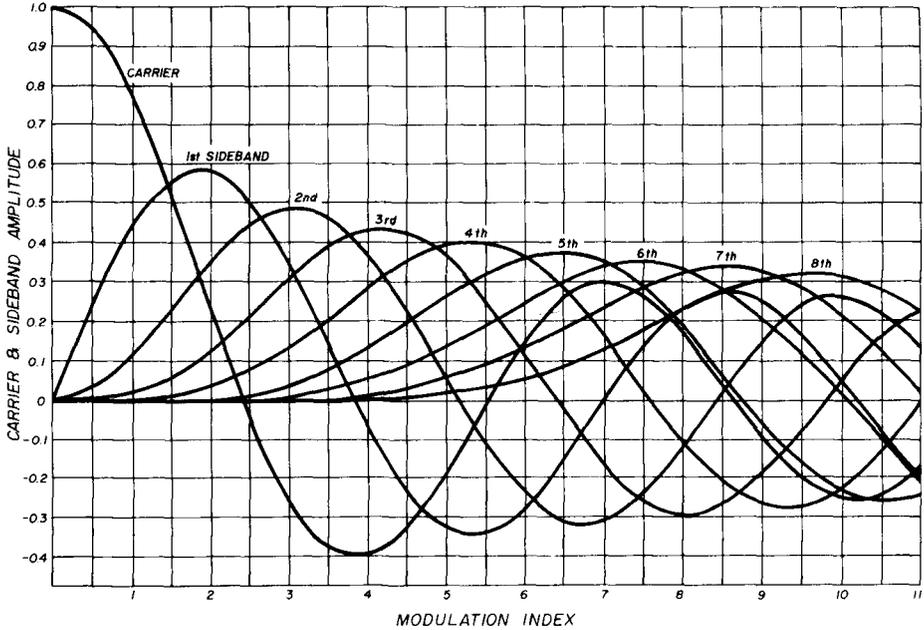


fig. 4. Bessel curves show variation in carrier and sideband amplitude with modulation index.

Zero Carrier Point	Modulation Index (m)	To Obtain Bandwidth Multiply Modulating Frequency By
1	2.40	6
2	5.52	8
3	8.65	12
4	11.79	14
5	14.93	16
6	18.07	18
7	21.21	20
8	24.35	22
9	27.49	26
10	30.64	28

The degree of frequency deviation achieved by phase modulation can be increased by multiplying the signal frequency **after** modulation. Since there are no amplitude variations in any form of angular modulation, the signal may be amplified by a nonlinear stage such as a frequency multiplier or a class-C amplifier. Modulation can take place at a low level and at a low frequency, and then be amplified by frequency multipliers or straight amplifiers. The modulation index of the signal is multiplied by the same factor by which the carrier frequency is multiplied.

Many vhf fm transmitters are crystal controlled by a crystal that is 1/24 or 1/32 of the carrier frequency. A deviation of 15 kHz at 144 MHz, for example, is equivalent to a

Odd-harmonic distortion is produced when fm is obtained by the phase modulation technique, and the amount of distortion that can be tolerated determines the amount of phase modulation that may be used. Since the audio-frequency correction network causes the lowest modulating frequency to have the greatest amplitude, maximum phase

modulation takes place at the lowest modulating frequency, and the amount of distortion that can be tolerated at this frequency determines the maximum deviation that can be obtained by the phase-modulation technique. Normally, for vhf fm, the deviation ranges from 5 kHz to 25 kHz. With a maximum audio frequency of 3000 Hz for voice operation, this represents a maximum deviation

finite number of pairs of such frequencies mathematically related to the frequency of modulation. Fortunately, only a limited number of these pairs (those nearest to the carrier frequency) are of significant amplitude for concern. However, when Armstrong first conducted his experiments with wideband fm, he used a frequency spectrum of about 250 kHz for high-fidelity transmission of music. For

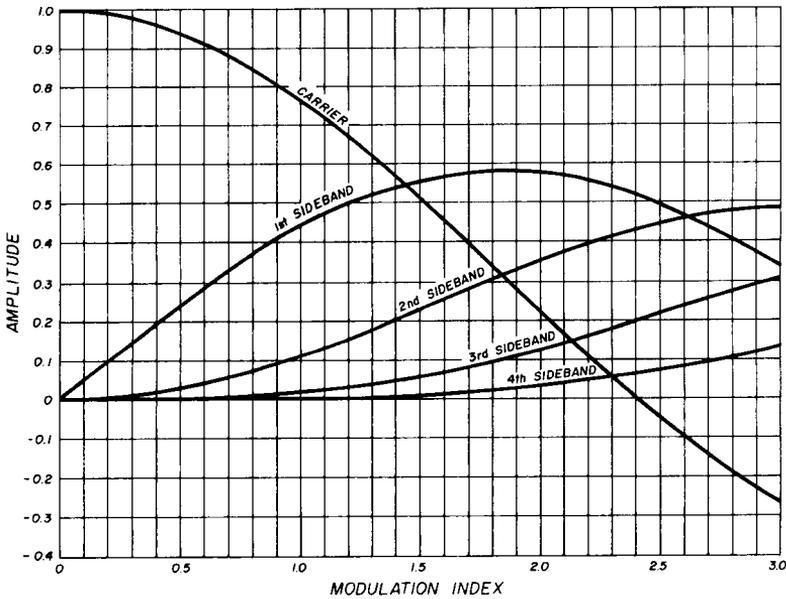


fig. 5. An expansion of the Bessel curves of fig. 4 for modulation indexes up to three.

tion of about 8. Therefore, low-frequency crystals followed by multiplier stages are mandatory for this type of service.

### fm sidebands

Until mathematical analysis proved otherwise, some people believed that varying the carrier frequency by an amount less than the actual audio frequency (for example, causing a 10-kHz modulating signal to vary the carrier frequency by plus or minus 1 kHz) would allow transmission over a frequency band smaller than that required by amplitude modulation. However, no matter how small the frequency swing in fm may be, the upper and lower sideband frequencies that are produced in a-m are also present in fm.

Moreover, not only are these two side frequencies present, but also present are an in-

this reason modern fm broadcasting must be carried out in the vhf region, since it is only here that sufficiently wide channels are available.

The sidebands generated in fm differ from those resulting from a-m in that they occur at integral multiples of the modulating frequency; in a-m a single set of sidebands is generated for each modulating frequency. A simple method of determining the amplitude of the various f-m sidebands is the family of Bessel curves shown in fig. 4. There is one curve for the carrier and one for each pair of sideband frequencies.

The Bessel curves show how the carrier and sideband frequency pairs rise and fall with increasing modulation index, and illustrate the particular values at which they disappear as they pass through zero. Since the

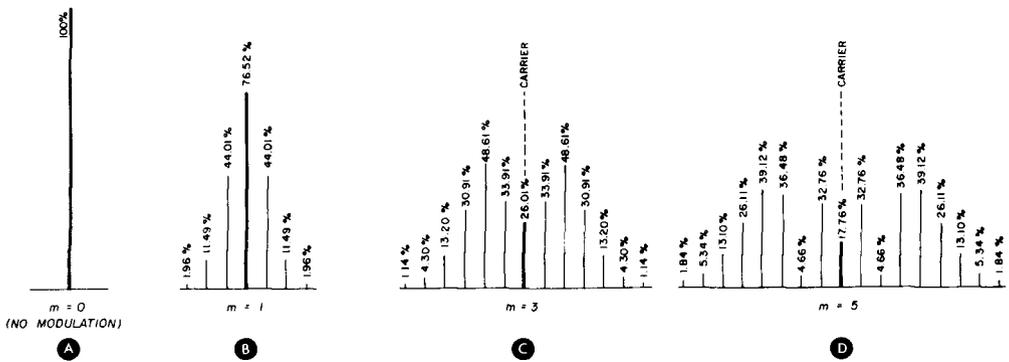


fig. 6. Effect of modulation index showing sideband frequency amplitude and distribution for modulation indexes 1, 3 and 5.

carrier drops to zero at particular values of modulation index (2.4, 5.5, 8.7, 11.8, etc.), the modulation index can be measured by noting the disappearance of the carrier. An expanded set of Bessel curves for modulation indexes up to 3 is plotted in fig. 5.

The relative amplitudes of carrier and sideband frequencies for any modulation index can be determined by finding the y-axis intercept for the particular function. Representative spectrum plots for three different values of modulation index are shown in fig. 6. The negative amplitude in the Bessel curves indicates that the phase of the particular function is reversed as compared to the phase without modulation. In fm, the energy that goes into

the sideband frequencies is taken from the carrier; the total power in the over-all composite signal remains the same regardless of the modulation index.

It should be noted that the frequency spectrum for fm is relatively constant for a given modulation depth regardless of the modulation frequency. On the other hand, the bandwidth of a pure pm signal increases with both modulation amplitude and frequency.

This situation does not occur in amplitude modulation. You might think that the large number of sideband frequencies would make the frequency spectrum produced by an fm transmitter prohibitively

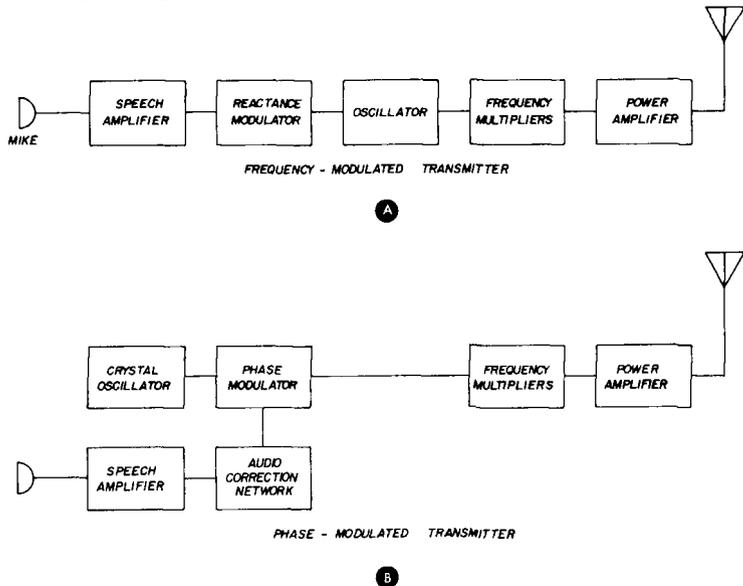


fig. 7. Block diagrams of fm and pm transmitters.

wide. However, the additional side frequencies are of small amplitude, and instead of increasing the bandwidth, modulation by a complex wave actually reduces the effective bandwidth of the fm spectrum. This is especially true when speech modulation is used, since most of the power in voice sounds is concentrated in the lower audio frequencies.

### generation of fm signals

Frequency modulation can be obtained directly by changing the frequency of an

is shown in **fig. 7A**. In the fm transmitter, the output of the speech amplifier is usually connected directly to a modulator stage, which produces an equivalent reactance that varies with the modulating signal. This causes the frequency of the oscillator to vary in the same way. The frequency-modulated signal of the oscillator is then multiplied to the desired output frequency by the multipliers; a power amplifier boosts the signal to the desired output level.

### the reactance modulator

The reactance modulator is a device that is connected across the oscillator tuned circuit to vary its resonant frequency in accord with applied modulation. A vacuum tube or transistor can be made to appear as a capacitive or inductive reactance by exciting the modulator with a voltage which either leads or lags the oscillator tank voltage. This leading or lagging input voltage causes a corresponding leading or lagging current, and the output circuit appears as a capacitive or inductive reactance across the oscillator tank circuit.

The transconductance of a vacuum-tube reactance modulator has an inverse effect on the impedance across the oscillator tank circuit. Since transconductance changes with grid voltage, the magnitude of the reactance across the tank circuit is varied with the grid signal of the reactance tube. If the impedance is complex (composed of reactance and resistance)

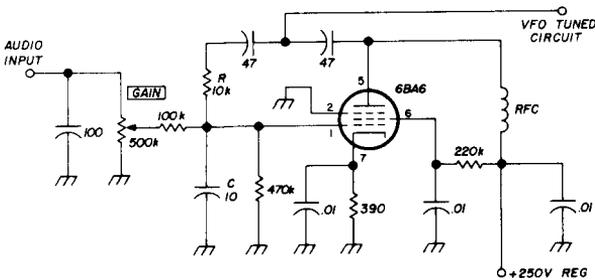


fig. 8. Simple reactance-tube modulator.

oscillator with the modulating signal, or indirectly with a phase modulator. Phase modulation circuits will be discussed later.

Simple frequency modulation of an oscillator avoids the need for phase-to-frequency-modulation conversion. In addition, it produces a large proportional frequency change, so less frequency multiplication is needed.

A block diagram of an fm transmitter

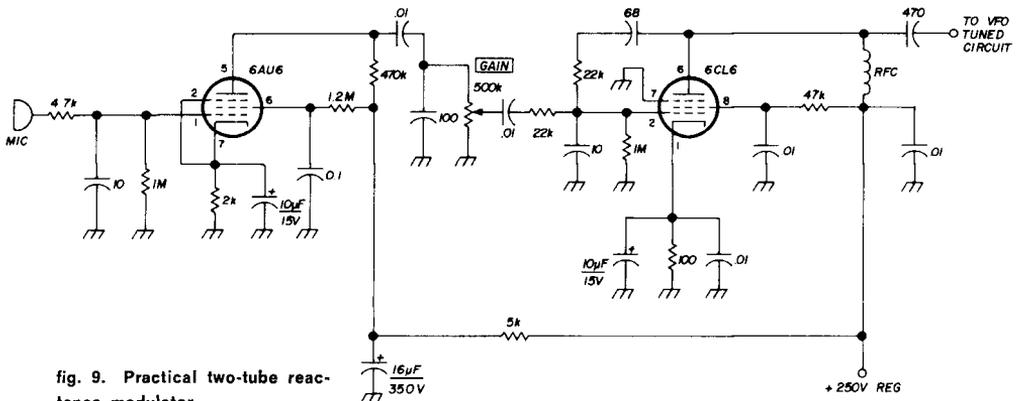


fig. 9. Practical two-tube reactance modulator.

the composite reactance will be varied about its zero-signal value when an audio signal is applied to the modulator. When properly designed and operated, the reactance modulator provides linear frequency modulation and is capable of providing large frequency deviations.

### practical reactance modulator circuits

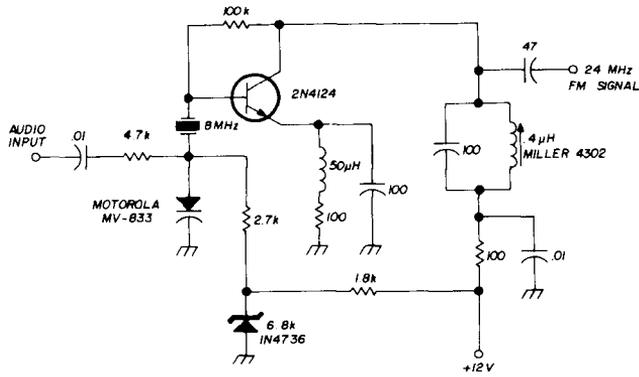
There are many possible configurations for reactance modulator circuits. The principal difference between various arrangements is the type of phase-shifting circuit that is used to produce a grid voltage which is in phase quadrature\* with the rf voltage of the modulator plate.

A practical reactance-tube modulator is shown in **fig. 8**. The modulator tube is a high-gain pentode, such as the 6BA6. The plate is coupled through a blocking capacitor to the oscillator circuit; a second capacitor couples the phase-shift network to the modulator grid circuit. If resistor R is made large in comparison to reactance C at the oscillator frequency, the current through R-C will be nearly in phase with the voltage across the tank circuit, and the voltage across C will lag the oscillator tank voltage by almost 90 degrees. The result of the 90 degree lagging voltage on the modulator grid is that its plate current lags the oscillator voltage by 90 degrees, and the reactance tube appears as an inductance in shunt with the oscillator inductance, thus raising the oscillator frequency. Capacitance C in **fig. 8** is often the grid-cathode capacitance of the reactance tube.

Two tubes are used in the practical reactance modulator circuit shown in **fig. 9**. A 6AU6 serves as a high-gain speech amplifier followed by a 6CL6 reactance modulator. The 6CL6's high transconductance permits a large value of lagging current to be drawn during the modulation swing.

A frequency-modulated crystal-controlled oscillator is shown in **fig. 10**. In this circuit a voltage-variable capacitor (varactor) is used to alter the resonant frequency

\*When two voltages are in quadrature, they are displaced 90° in phase.



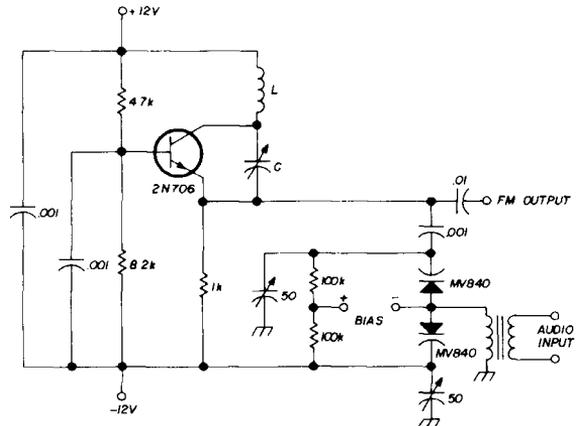
**fig. 10.** Frequency-modulated crystal oscillator uses a variable-capacitance diode across the crystal.

of the crystal by varying the shunt capacitance to ground. One or two volts of audio are sufficient to provide suitable deviation for transmitter operation at 50 MHz when 8.33-MHz crystals are used. Oscillator output is at 25 MHz.

In the circuit of **fig. 10** the audio voltage driving the varactor appears in the oscillator circuit and produces a small amount of a-m. This is eliminated by the use of two varactors in the back-to-back circuit shown in **fig. 11**. The audio signal is coupled by a high impedance transformer to the diodes through capacitors that are small in comparison with diode capacitance.

The bridge diode circuit presents only a capacitance change, and no component

**fig. 11.** Back-to-back varactors produce fm without amplitude variations. Modulation transformer should present a high impedance to the diodes.

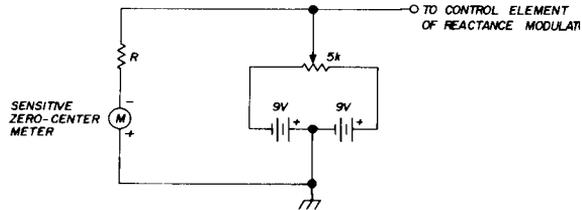


of bias or drive voltage is presented to the oscillator. Oscillator frequency is determined by L and C, plus the effect of the modulator. Bias voltage is used to adjust the center frequency of the oscillator, providing reverse bias for the diodes to place them in the linear portion of their operating curve. For best results the bias resistors and coupling capacitors should be matched.

### determining linearity

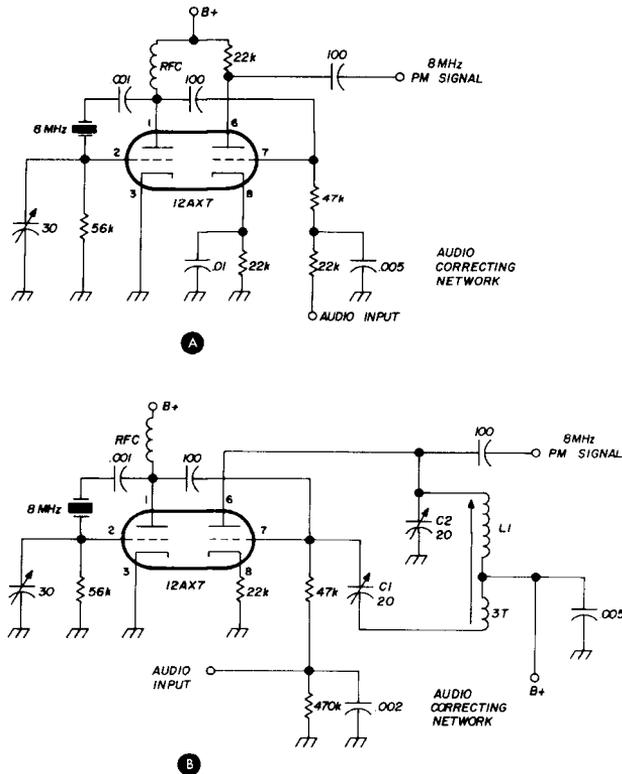
It is often desirable to run a static test on a reactance modulator to determine its linearity. A frequency-vs-control voltage curve is plotted on graph paper, and linearity is checked by comparing equal increments in control voltage—both positive and negative—against resulting changes in frequency. A circuit that pro-

vides a calibrated negative and positive control voltage is shown in **fig. 12**. The calibrated control voltage may be checked against the frequency deviation produced by the modulator stage and an appropriate graph plotted.



**fig. 12.** Linearity checking circuit provides calibrated control voltage to the reactance modulator. Resistor R is chosen for full-scale meter deflection when 5k pot is at one end of its range.

**fig. 13.** Vacuum-tube phase modulators. The circuit in B provides approximately 6 times more deviation than circuit A. Inductor L1 should be approximately 27  $\mu$ H for resonance at 8 MHz.



### generation of pm signals

To generate a phase-modulated signal, the carrier is generated in a constant frequency oscillator, and then passed through a device which introduces phase variations in time with the modulation signal.

A change in the phase of a signal can be produced by passing the signal through a network containing both a resistance and a reactance. If the series combination is considered to be the input, and the output voltage is taken across the resistor, a definite amount of phase shift is introduced, the amount depending upon the frequency of the signal and the ratio of the resistance to the reactance. If the resistance can be varied with an applied audio signal, the phase angle of the output signal changes in direct proportion to the audio signal amplitude and a phase-modulated signal is produced.

Two practical phase modulators are shown in **fig. 13**. Circuit A is an R-C phase-shift network with the phase resistance replaced by the variable plate resistance of a vacuum tube. Since the plate resistance of the triode changes with the applied audio, the phase between the input and the output changes in accord with the audio signal.

In fig. 13B phase modulation is adjusted by capacitor C1. Capacitor C2 acts as both a phase angle and magnitude control. Both capacitors are adjusted for maximum modulation. Resonance is established by inductance L1. This circuit provides about six times the deviation of the circuit in fig. 13A.

Audio and carrier signals are applied to the control grid. The rf signal reaches the plate circuit by two paths; one through the grid-plate capacitance and the other by the normal amplification action of the tube. When a large, unby-passed cathode resistor is used, tube amplification is greatly reduced, and the two signal voltages across the plate circuit are approximately equal.

The instantaneous plate voltage of the triode is 180° out of phase with the grid voltage, but the feedthrough voltage via the grid-plate capacitance is in phase with the grid voltage. Therefore, the feedthrough is out of phase with the amplified voltage. When a modulating audio voltage is applied to the grid of the modulator, amplification is varied at an audio rate, and the amplified component across the plate circuit likewise varies in amplitude. However, the feedthrough voltage does not change in either amplitude or phase. The resultant plate voltage changes in amplitude and phase in accordance with the modulating signal. The small degree of amplitude modulation introduced by this simple modulator can be eliminated in the following stages.

### the balanced modulator

Armstrong's original method of generating pm is still widely used, and a variation of the basic circuit is shown in fig. 14. Ssb fans will recognize this as a form of balanced modulator which produces a double-sideband, suppressed-carrier signal. The grids of the modulator tubes are fed through an R-C network in the output circuit of the oscillator. Out-of-phase voltages are coupled through small capacitors to a phase-shift network (R1-C3) in the grid circuit of the modulator. This network introduces a 45° phase shift between

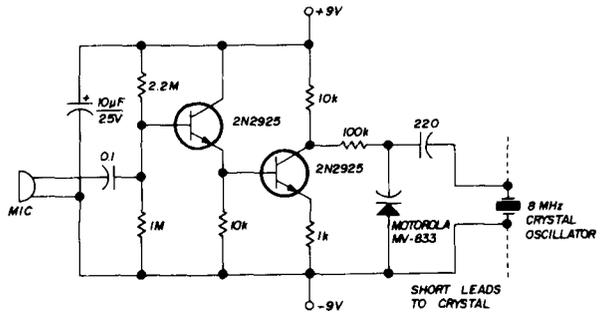
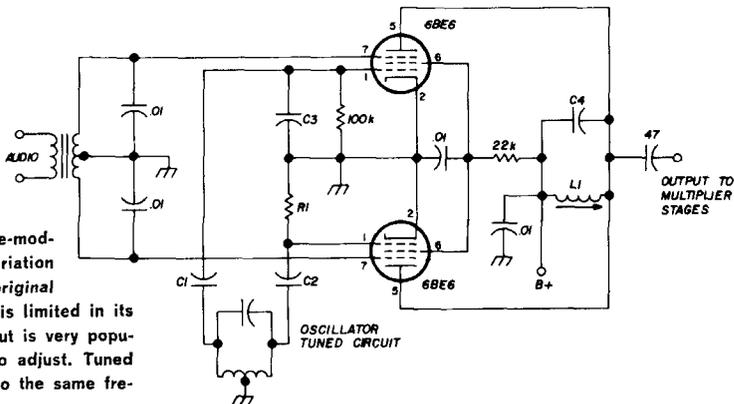


fig. 15. Compact-varactor modulator for low-frequency crystal oscillator.

the grids of the modulator with respect to the reference phase of the oscillator, and 90° with respect to each other.

The suppressor grids are fed by a push-pull audio signal, thus one tube conducts at a time. The combination of balanced modulator action with an rf carrier that

fig. 14. Balanced phase-modulator circuit is a variation of Major Armstrong's original modulator. This circuit is limited in its modulation capability but is very popular because it's easy to adjust. Tuned circuit L1-C4 is tuned to the same frequency as the oscillator.



is shifted in phase by  $90^\circ$  creates a phase-modulated output signal. Thus, amplitude modulation may be converted to phase modulation by removing the carrier, shifting the double sideband  $90^\circ$  and reinserting the carrier.

When the phase-shifted modulation is combined with the carrier, the resultant signal varies in amplitude as well as in frequency. This defect is small when the modulation amplitude is kept small in comparison with the carrier. As a result,

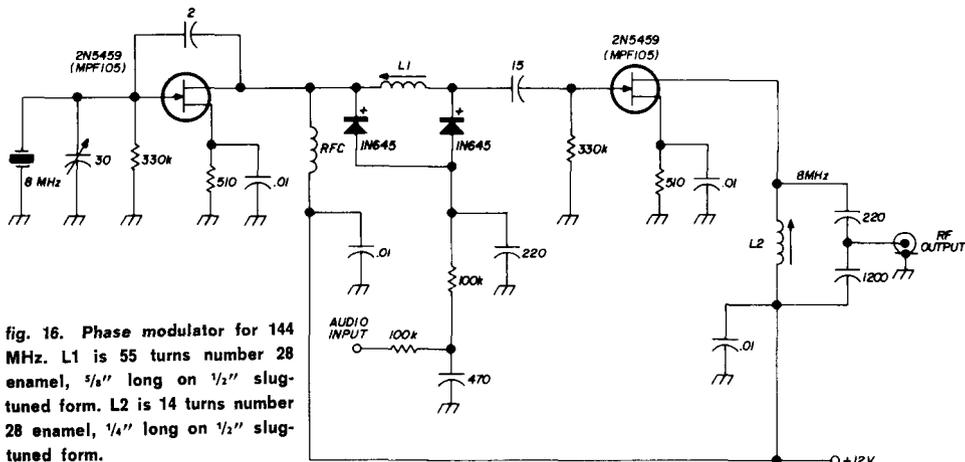


fig. 16. Phase modulator for 144 MHz. L1 is 55 turns number 28 enamel,  $\frac{5}{8}$ " long on  $\frac{1}{2}$ " slug-tuned form. L2 is 14 turns number 28 enamel,  $\frac{1}{4}$ " long on  $\frac{1}{2}$ " slug-tuned form.

this circuit is somewhat limited in modulation capability. It is, nevertheless, used in many types of commercial fm transmitters because of its ease of adjustment.

### solid-state modulators

A solid-state phase modulator that may be used with a crystal oscillator is shown in fig. 15. In this circuit a two-stage amplifier places the modulating audio voltage across a varactor which is applied as a shunt capacitance across the crystal. The degree of phase modulation is limited with this approach, and the lowest possible crystal frequency should be used so high deviation ratios can be obtained through frequency multiplication.

A phase modulator designed especially for vhf crystal-controlled fm transmitters is shown in fig. 16. The inexpensive field-effect transistor is used in a crystal oscillator operating in the 4- to 8-MHz range. A second fet is used as a phase modula-

tor, with the modulating network in the gate circuit. Two silicon diodes used as varactors across a phasing coil are driven by the modulating voltage. There is a small amount of amplitude modulation with this circuit, but it is "washed out" by the succeeding stages of the fm exciter. The audio system is designed for a high-gain carbon microphone for mobile service. Under these conditions, the rf output of the fet amplifier is about 30 milliwatts.

Bias for the diode modulator is adjusted for maximum deviation with a given amount of audio as monitored in a nearby fm receiver. Channel adjustment is accomplished by the trimmer across the crystal.

### conversion of phase modulation to frequency modulation

Phase modulation may be received on an fm receiver with no difficulty, but the modulation will sound harsh and the human voice will sound peaked and tinny. To solve this problem in early designs, the phase modulation was changed so the modulation index decreased in inverse proportion to the modulating frequency. This is accomplished by shaping the response of the transmitter speech amplifier with an audio correction network (fig. 17) so that the output voltage is inversely proportional to the modulating frequency. In current commercial practice, flat-response audio with tailored clipping

is fed to the phase modulator in the transmitter (see footnote, page 13); this results in constant peak deviation after modulation, and requires the use of post-equalization at the receiver discriminator.

### the fm transmitter

The various direct and indirect methods for producing frequency modulation involve changing either the frequency or the phase of an rf carrier in accordance with

crystals allowed sufficient frequency multiplication to obtain the desired degree of deviation at the output frequency.

Generally speaking, the circuitry used in conventional transmitters may be used for fm. In fact, aside from the modulator stage, the circuitry should be familiar to any amateur who has worked with a-m, cw or ssb.

Because the amplitude of an fm signal is constant, the signal may be amplified

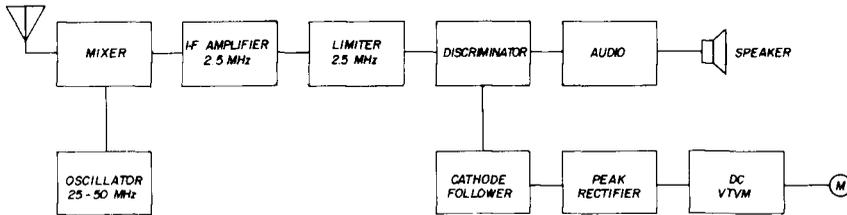


fig. 18. Fm modulation meter depends upon an increase in discriminator output with frequency deviation.

the modulating signal. The fm signal is then raised to the operating frequency by passing it through a series of frequency multipliers. When the frequency is multiplied, the frequency deviation is multiplied by a like amount.

Inexpensive, highly stable quartz crystals are available in the 3- to 10-MHz range, and many popular vhf fm transmitters use these crystals, multiplying the crystal frequency by a factor of twelve, eighteen or twenty-four. Some of the earlier military fm gear which used wideband fm in the 20- to 30-MHz region used special low-frequency crystals (type FT-241) that operated in the 250- to 500-kHz region. These

by nonlinear stages such as doublers and class-C amplifiers without introducing signal distortion. Actually, it is advantageous to pass an fm signal through nonlinear stages, since any vestige of amplitude modulation generated in the reactance modulator may be smoothed out by the inherent limiting action of a class-C amplifier.

### deviation measurement

Deviation of an fm transmitter must be limited to that bandwidth authorized for the service. When a single signal is used to modulate an fm transmitter, the relative amplitudes of the various sideband frequencies vary widely as the deviation is changed as shown in fig. 4. Since we know the relationship between the amplitude of the sideband frequencies and carrier to the modulating frequency, a simple method of measuring deviation is possible. This measurement is expressed as the modulation index (m).

The Bessel function plot of an fm signal shows that at certain values of the modulation index, carrier amplitude falls to zero and all the power is contained in the sidebands. By applying a sinusoidal audio signal of known frequency to the

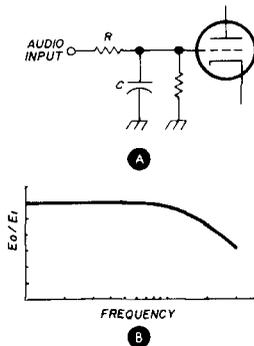
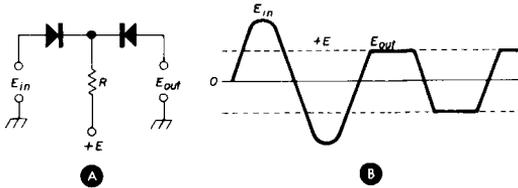


fig. 17. Audio correction network and its effect on frequency response.

transmitter, and increasing the modulation until the amplitude of the fm carrier reaches zero, deviation can be determined. The modulation index at this point may be found from a table, such as accompanies **fig. 4**.

The first point of zero carrier is reached when the modulation index is 2.405 (when the deviation is 2.405 times the modulation frequency). For example, if the transmitter is modulated by a 1000-Hz tone



**fig. 19. Simple audio clipper and its output waveform. Clipping level is determined by bias voltage E.**

and the modulation level increased until the first carrier null is obtained, the deviation will be 2.405 kHz. If the modulation frequency is 2000 Hz, the deviation at the first carrier null is 4.810 kHz. Other carrier nulls occur when the modulation index is 5.52, 8.65, 11.79, etc.

Carrier nulls may be accurately noted with a communication receiver that has a selective i-f system incorporating a crystal or mechanical filter. The output of the fm transmitter is loosely coupled to the front end of the receiver, and the unmodulated carrier is monitored with the bfo turned on and adjusted to a pleasant note, such as 800 Hz. The modulating sig-

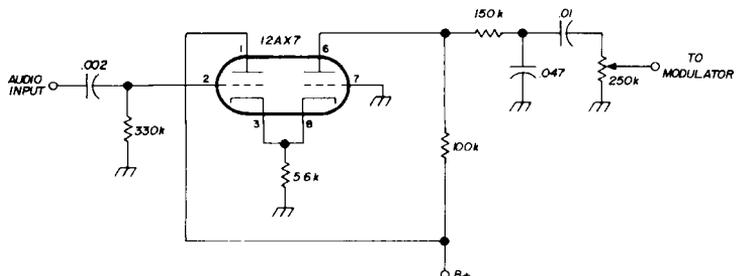
nal is turned on, and the frequency deviation is varied by increasing the amplitude of the modulating signal until the 800-Hz tone first disappears.

If an fm transmitter has a maximum frequency deviation of 15 kHz, the modulating frequency that will produce carrier disappearance at an index of 2.405 is 6237 Hz ( $f = 15,000/2.405 = 6237$ ). An audio signal of this frequency, when applied to the fm modulator and gradually increased in amplitude, will extinguish the carrier. In the measurements setup this adjustment produces a steady lessening of the beat note until it becomes inaudible.

Since 6237 Hz is above the audio range of most communications systems, it may be desirable to use the third carrier null at 8.65. For a maximum deviation of 15 kHz, the test modulating signal would be 1734 Hz ( $15,000/8.65 = 1734$ ). This test frequency is better for amateur systems since it falls within the desired speech range. For this test, the amplitude of the 1734 Hz tone is increased until the beat note disappears for the third time.

A second method of monitoring deviation is the fm modulation meter. This device consists of a simple fm receiver equipped with a vtm calibrated in kilohertz of deviation (**fig. 18**). The instrument depends upon an increase in discriminator output as frequency deviation increases. Commercial versions of this instrument will measure modulation of an fm transmitter operating in the range from 25 to 500 MHz. Harmonics of the local oscillator are used at the higher frequencies.

**fig. 20. Cathode-coupled twin-triode speech clipper.**



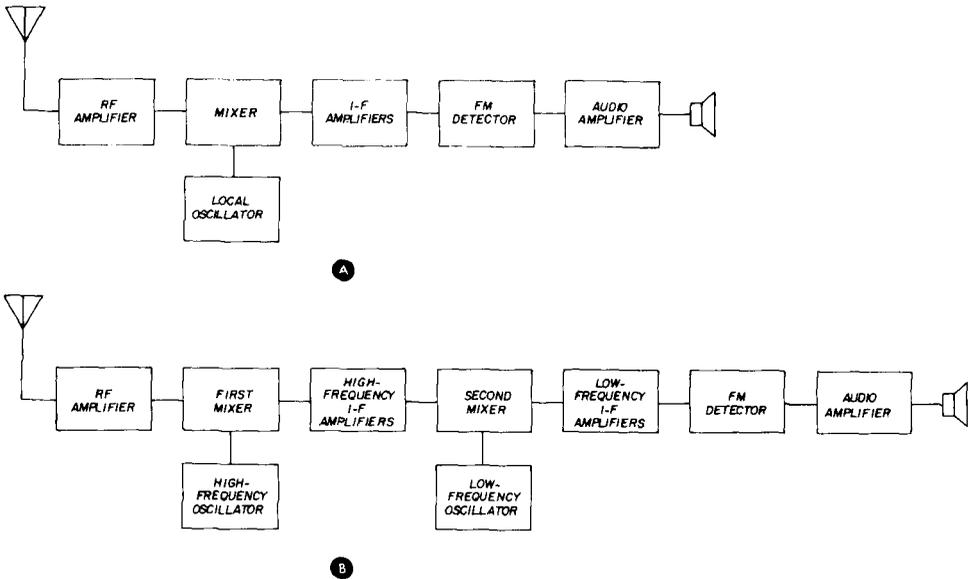
## modulation limiting

Frequency deviation in an fm transmitter can be controlled with a circuit that keeps the audio signal level within prescribed limits. Simple audio clipping circuits may be used, as well as more complex deviation control circuits that are designed for fm transmission. The audio clipping circuit shown in **fig. 19** uses two back-to-back diodes which clip each

cathode bias. Therefore, both positive and negative signal peaks are evenly clipped.

## fm reception

The fm receiver used by Major Armstrong consisted of several heavy cabinets of equipment that stretched the full length of his laboratory. In 30 years this formidable pile of gear has shrunk to the battery operated, transistorized fm im-



**fig. 21. Single- and -double-conversion fm receivers.**

half of the audio cycle at a preset level. The clipping level is determined by the bias voltage  $E$ . Normally the clipper is followed by a low-pass filter which removes the higher harmonics created by clipping action, thus greatly attenuating sidebands which could cause adjacent channel interference.

A twin-triode cathode-coupled clipping circuit (**fig. 20**) is used in some commercial fm transmitters. When the grid signal at the first triode swings too far positive, the common cathode bias resistor cuts off the second triode; on an excessively large negative driving signal, the first triode section is cut off because of the combined effect of the signal and

port selling for under ten dollars at the corner drug store.

An effective fm receiver should be insensitive to changes in signal amplitude and sensitive only to frequency changes in the received signal. By using slope detection, a conventional a-m receiver may be used to receive fm<sup>10</sup> although performance will be much poorer than with a receiver designed for this service.

## receiver requirements

There are three main requirements for a practical fm receiver:

1. Bandwidth sufficient to pass the desired fm signal while rejecting adjacent interfering signals.

2. Detector for converting frequency into audible amplitude changes.

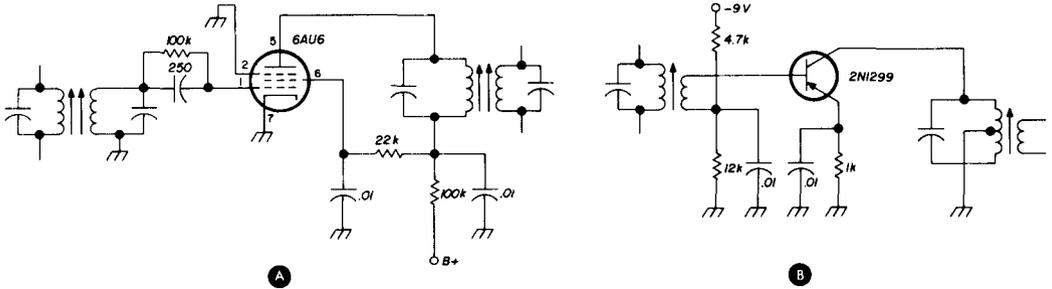
3. Limiting systems to eliminate signal amplitude variations before the detector.

A block diagram of a typical fm receiver is shown in **fig. 21A**.

Most vhf fm receivers are double conversion receivers such as **fig. 21B**. When good selectivity is necessary, a low inter-

The i-f system must provide sufficient selectivity to discriminate against stations operating on adjacent channels, and still have sufficiently broad response that the outer sidebands of the desired fm signal are not distorted.

To obtain the required selectivity consistent with the proper passband, special bandpass i-f filters are used, such as mechanical or crystal filters, or even L-C



**fig. 22. Typical i-f limiter circuits.**

mediate frequency is desirable; this, however, degrades image signal rejection. Similarly, if good image rejection is required, a high i-f should be used, but this is not compatible with good adjacent channel rejection. These difficulties may be overcome by combining the advantages of low and high i-f amplification in the double-conversion arrangement. First the received signal is mixed with a local oscillator signal to produce a high intermediate frequency; a second local oscillator signal is then mixed with the high i-f signal to produce a low frequency i-f signal.

Low noise rf amplifiers and mixers in fm receivers are the same as their counterparts in a-m receivers. Since most vhf fm receivers work on crystal-controlled channels, the local oscillators may also be crystal controlled. Channel switching is accomplished with either mechanical or electrical switching systems.

The f-m detector requires signals on the order of several volts for proper operation. Since the front end works in the microvolt region, the i-f amplifier must perform most of the voltage amplification.

filters (Motorola Permakay filter). If the transmitter deviation is changed, the filter may be replaced with one having a passband that matches that of the transmitter.

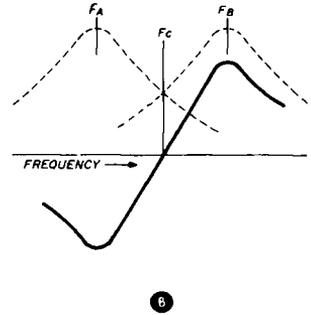
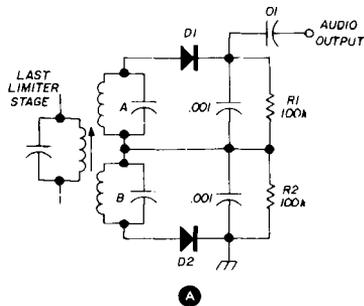
### i-f limiting

Most fm detectors are sensitive to changes in the amplitude of the received signal so they must be preceded by a limiter that removes all amplitude fluctuations from the signal. The limiting circuit may be an i-f amplifier stage having very low plate voltage and grid-resistor bias so that it overloads easily. Thus, when a certain signal level is reached, further increases in input signal produce no change in the output. If sufficient gain exists ahead of such a stage, variations in amplitude of the received signal are removed. Although a limiter may provide some amplification before the saturation point is reached, its main purpose is to limit the amplitude variations caused by fading and noise.

The limiter circuits shown in **fig. 22** are similar to conventional i-f amplifiers ex-

cept for the bias system. The R-C network produces a bias voltage that is equal to the peak rectified voltage between grid and cathode or between emitter and base. Short amplitude disturbances such as noise are longer than the time constant of the R-C circuit and are clipped off. Longer signal variations such as fading appear in the output. To take care of the slower fading, it is common practice to follow the first short-time-constant limiter with another limiter with a longer time constant.

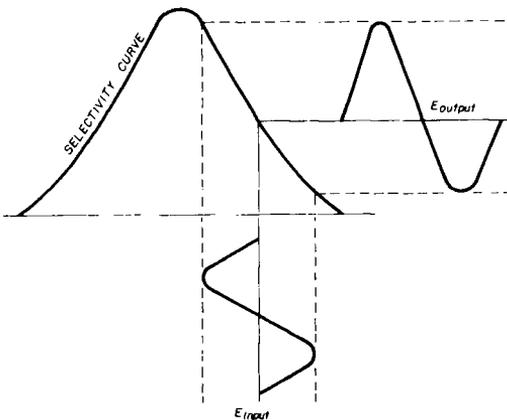
**fig. 24. Double-tuned discriminator and its a-m output characteristic.** Curves shown by dotted lines are undesirable responses of this circuit.



## fm detectors

A device that converts frequency-modulated signals into audio signals is called a discriminator. The simplest form of discriminator is an ordinary tuned circuit

**fig. 23. Slope detection using the response curve of an ordinary tuned circuit.**



that is tuned to a frequency that differs somewhat from the average frequency of the fm carrier as shown in **fig. 23**. As the carrier frequency fluctuates, the current in the detuned circuit varies, increasing as the impressed frequency approaches the resonant frequency of the circuit, and decreasing as the impressed frequency departs from the resonant frequency. The output is an a-m wave that may be demodulated by an ordinary diode detector. Since the side of the resonance curve is not linear, only a small

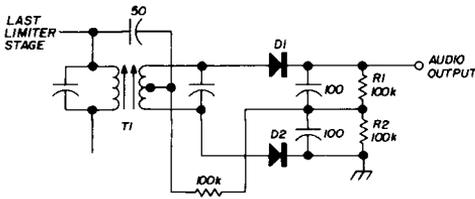
portion of the resonance curve is useful for linear conversion of frequency variations to amplitude variations.<sup>10</sup> Also, a receiver used in this manner is vulnerable to noise as well as interference from a-m signals appearing at the peak of the resonance curve and fm signals on the opposite slope.

## double-tuned discriminators

The linearity can be greatly improved by using two stagger-tuned circuits instead of one and choosing the difference between the two outputs.<sup>11</sup> A double-tuned discriminator circuit is shown in **fig. 24A**. In this circuit the input tuned circuit is resonated to the resting fm carrier frequency, and the resonant frequencies of tuned circuits A and B are spaced slightly more than maximum transmitter deviation. The audio output from this circuit is practically free of distortion because of the linear operating characteristic about the resting carrier frequency.

However, the response curve in **fig. 24B** shows that reception is possible at three points, corresponding to each outer portion of the resonant curves plus the desired linear operating region in the center.

The output from each tuned circuit is applied to a diode detector. When the fm signal is at its resting frequency, the voltages across load resistors R1 and R2 are equal and of opposite phase, and the output voltage is zero. When the fm carrier goes higher than the center fre-



**fig. 25. Foster-Seeley discriminator; output voltage vs frequency is the same as fig. 24.**

quency, more voltage is developed across one tuned circuit than the other; when the frequency swings lower than the center frequency, the voltage developed across the other tuned circuit is greater. By careful adjustment of the circuit constants the rectified audio voltage is a linear function of the impressed frequency.

Another discriminator circuit is shown in **fig. 25**. It can be shown that this circuit is essentially a double-tuned pair<sup>12</sup> and that the output vs frequency curve of **fig. 24B** also applies to this circuit.

Circuit operation is based on the phase relationships in a transformer with a tuned secondary. At the resonant frequency of the secondary the rf voltage

across each half of the winding is 90° out of phase with the primary; the voltages are 180° out of phase with each other since the winding is center tapped. When the received signal is at resonance, equal rf voltages are applied to each diode; the rectified voltages across the diode load resistors are equal but of opposite polarity so the net voltage output is zero.

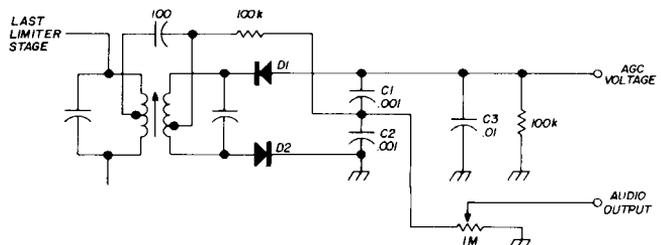
When the fm carrier shifts frequency, one diode conducts more than the other because of disturbed circuit balance. If, for example, D1 conducts more than D2, the voltage drop across R1 would be greater than the drop across R2 and the output terminal would be positive. If the carrier shifts in the other direction, D2 conducts more than D1, the voltage drop across R2 increases, that across R1 decreases, and the output terminal is negative. Thus, when the carrier deviates above and below its resting frequency, an audio voltage is developed at the output terminal—the same frequency as the original modulation and proportional to deviation.

## ratio detector

A disadvantage of the discriminator circuit of **fig. 25** is that its output is affected by amplitude variations at the input as well as frequency variations. The ratio detector in **fig. 26** was developed as an fm detector that responds only to input frequency variations because the output depends upon the ratio of the currents through the diodes rather than the voltage difference between them. Since the ratio detector is insensitive to a-m, it is not necessary to use a limiter ahead of it.

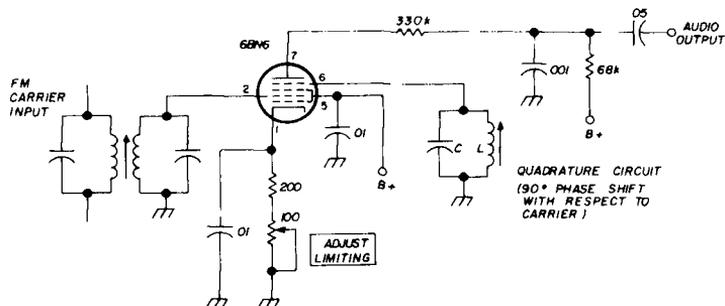
In the ratio detector in **fig. 26**, the large

**fig. 26. Ratio detector is relatively insensitive to amplitude modulation.**



value of C3 tends to maintain the voltage across C1 and C2 at a constant level. As with the two discriminator circuits discussed earlier, the relative average currents through the diodes vary with input frequency. The voltages across C1 and C2 vary correspondingly, one increasing as the other decreases, while their sum remains constant. If the two diode circuits are carefully balanced, the output voltage is practically independent of any amplitude variations on the incoming signal.

fig. 28. Gated-beam discriminator uses specially designed vacuum tube. Quadrature circuit is tuned to the same frequency as the fm carrier.



At the carrier resting frequency, C1 and C2 are charged to a constant value. When the frequency decreases, C2 acquires a greater charge than C1; when the frequency increases, C2 is charged less than C1, although the sum of the charges remains the same. The audio output at the junction of C1 and C2 follows the frequency deviation.

### cycle-counting detector

An fm detector that uses no tuned circuits is shown in fig. 27. This cycle-counting detector operates with a resistance-coupled i-f amplifier and responds directly to the number of cycles impressed up-

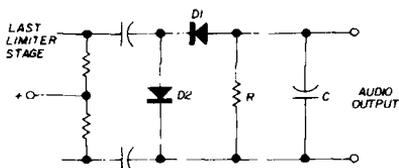


fig. 27. Cycle-counting detector charges capacitor C at rate proportional to modulation frequency.

on it. The square waves from the limiting amplifier are rectified by the diodes to negative pulses which charge the output capacitor C. As the frequency increases, the average rate of charge increases; when the frequency decreases, so does the voltage across the capacitor. The charge on the capacitor depends upon the deviation of the signal from the resting frequency. The shunt resistor lowers the time constant of the circuit so the stored charge can change fast enough to reproduce an audio signal.

Finally, mention should be made of the 6BN6 gated-beam detector shown in fig. 28. This fm demodulator is a special single-tube circuit that features excellent sensitivity and high output. With one or two volts on the input, incoming signals need little amplitude to cut the tube off for negative peaks; similarly, for positive peaks of the incoming signal, saturation is reached. Limiting action may be adjusted by a variable bias resistor in the cathode circuit.

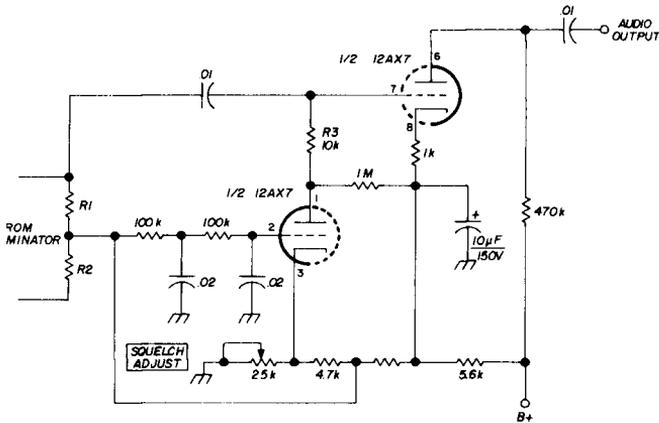
Discriminator action in the gated-beam tube takes place as a result of signal phase shift between two control grids which are 90° out of phase with each other by virtue of a quadrature circuit connected between them. When the quadrature circuit is properly tuned, the electron beam is modulated in proportion to the modulation on the incoming signal.

### squelch circuits

Squelch circuits are used to mute the audio when no signals are present. In a

high-gain receiver, speaker noise can be very annoying to operators who must monitor a channel for long periods. When the receiver is squelched, no background noise is heard; when an rf signal comes on, squelch is turned off and the audio system becomes operative.

A simple squelch circuit is shown in **fig. 29**. The squelch voltage is derived from



**fig. 29. Discriminator derived squelch circuit.**

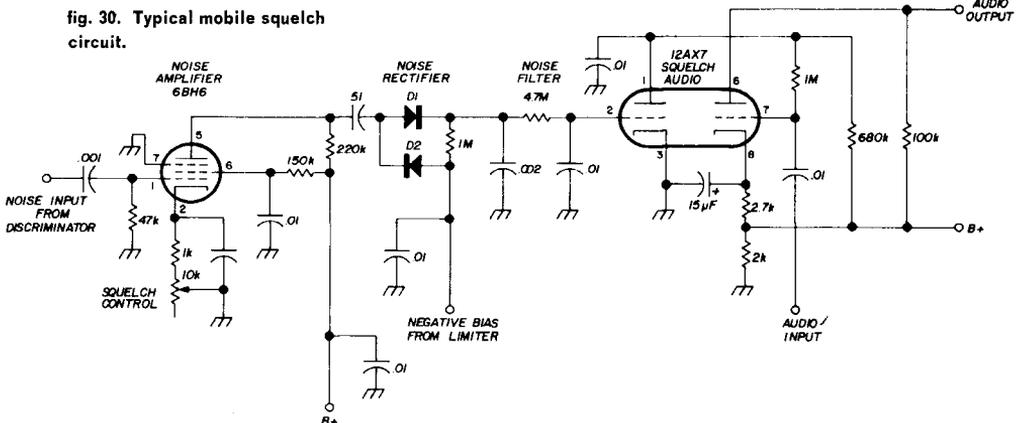
the discriminator circuit. The center of the discriminator load resistors develops a negative voltage when a signal is applied. This voltage is passed through an R-C network and is sufficient to bias the squelch tube to cutoff and permit a signal to pass through the audio amplifier.

Without an input signal, a positive bias (applied to the junction of R1 and R2) is greater than the bias applied to the cathode of the squelch tube; this causes the tube to conduct, dropping the plate voltage and cutting off the audio tube through resistor R3.

A more complex squelch circuit is shown in **fig. 30**. This circuit consists of three stages; a noise amplifier, a noise rectifier and a squelch control tube. In the absence of signal, the limiter stages of the fm receiver pass a continuous and constant level of noise voltage to the discriminator. Noise higher than the voice frequencies is amplified and passed to the noise rectifier developing positive voltage across the load resistor.

A negative bias voltage from the grid circuit of the second limiter is applied to the anode end of the load resistor. The sum of the negative limiter voltage and the positive rectified noise voltage appears across the load resistor. When a signal is received, the signal voltage overrides the noise voltage, reducing the positive noise voltage at the noise rectifier.

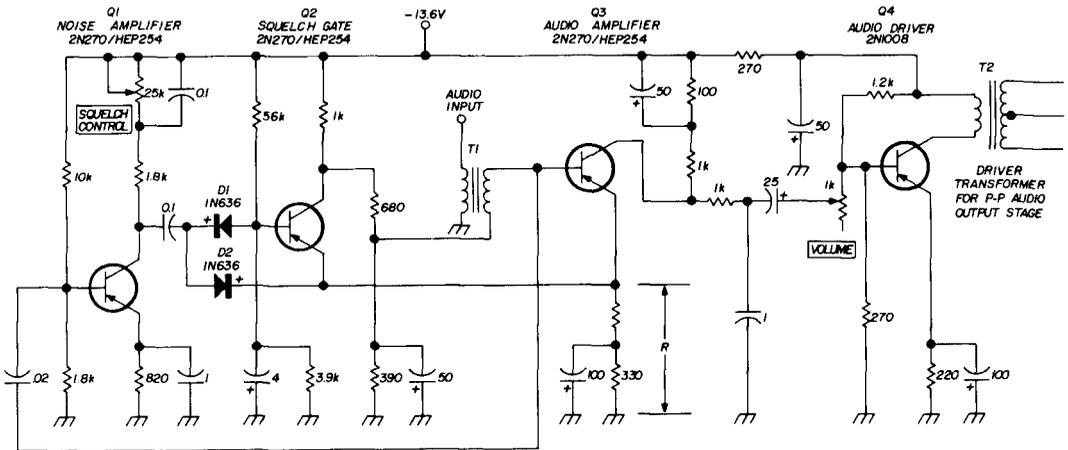
The dc amplifier is biased near cutoff, the audio stage is biased to normal operating conditions, and squelch is removed. The variable squelch level control is set to limit the gain of the noise amplifier tube, thus limiting the noise voltage to a value that will just bias the audio stage to cutoff. Hence, when even a weak carrier signal is received which quiets the noise, the squelch is opened.



**fig. 30. Typical mobile squelch circuit.**

## transistorized squelch

The transistorized squelch circuit shown in **fig. 31** consists of a noise amplifier Q1, noise detector D1, and a squelch gate (switching circuit) Q2. In the absence of an rf carrier, noise output from the discriminator is amplified by Q1. The ac output of Q1 is rectified and applied as bias to the base of Q2. With no noise signal applied, Q2 is cut off and Q3 is conducting; thus, the desired audio signals are amplified by Q3 and applied to the audio driver stage Q4.



**fig. 31.** Transistorized squelch circuit.

In the absence of carrier, noise at frequencies at 4000 Hz or higher is applied to noise amplifier Q1, rectified and applied to the base of squelch-gate transistor Q2. When this voltage reaches a predetermined level (**threshold**) determined by the squelch control, the squelch-gate transistor conducts. Since the squelch-gate and preamplifier emitters are returned to ground through a common emitter resistance (R), conduction of the squelch gate results in a more negative voltage at the emitter of the audio amplifier, Q3. This increased negative voltage cuts off the audio stage and no signal reaches the audio driver.

Most of the objectionable noise is in the frequency range above 4000 Hz, but the desired audio is in the 300- to 3000-Hz range. The squelch circuit is designed so that signals above 4000 Hz open the squelch gate and

signals below 4000 Hz do not. This is accomplished in the input circuit to the noise amplifier. The time constant is such that signals below 4000 Hz are greatly attenuated and do not provide sufficient rectified voltage to overcome the squelch threshold voltage at the base of the squelch-gate transistor.

Some squelch circuits substitute a relay in place of the blocking tube or transistor, with the relay contacts breaking the speaker circuit or activating auxiliary control circuits when the fm carrier appears.

## automatic frequency control

Some fm receivers are equipped with an automatic-frequency-control (afc) circuit which adjusts the frequency of the mixer oscillator to compensate for variations in the received signal frequency or frequency drift in the oscillator.

In an afc system, a discriminator is used to provide a dc voltage which is proportional to the frequency of the received signal. The potential at the output of the discriminator is used to control a reactance modulator shunted across the oscillator tuning circuit. Circuit constants are chosen so the tuned circuit varies the oscillator frequency to cancel out drift. The response of the system must be sufficiently slow so that variations in carrier frequency caused by modu-

lation have no effect on the afc; only slow variations in the average frequency are able to operate the reactance tube (fig. 32).

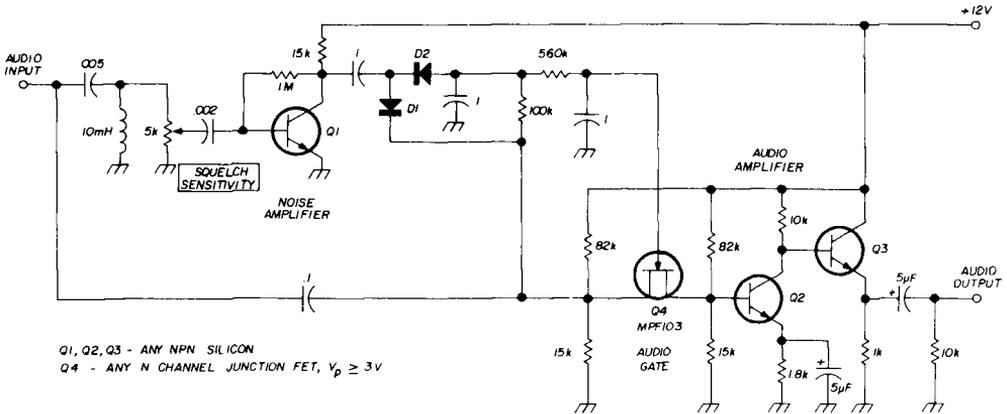
### fm repeaters

Vhf radio transmission is essentially short range, limited to line of sight unless sophisticated equipment is available to take advantage of unusual modes of propagation. A two-way radio relay station or repeater may be used to extend the communication

their own installations may cross-communicate.

The repeater receiver is normally in a standby condition, as is the transmitter section. Upon remote command a carrier-operated relay is allowed to place the repeater on the air, with receiver audio fed through a coupler to the transmitter modulator. After transmissions are complete the relay opens and the repeater is removed from the air.

**Simplex** operation refers to communica-



Solid-state squelch circuit suggested by K6HWJ uses an n-channel fet as a series audio gate.

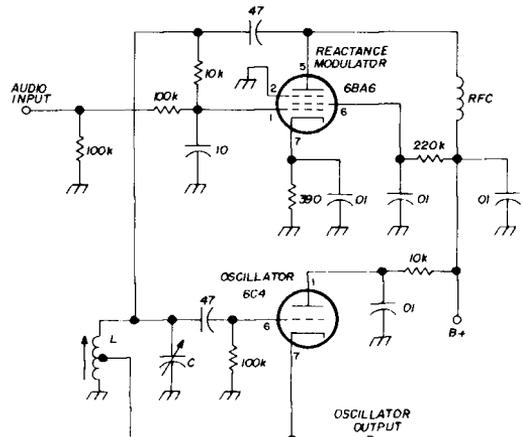
range between two or more fm stations. Various types of repeaters are in use in the United States and Canada, their operation and mode depending upon the requirements of the circuit they cover.

A repeater receives on one frequency and transmits on another. It may use separate antennas or a single antenna and diplexer so both reception and transmission can occur simultaneously. The user's transmitter is on the input frequency of the repeater, while his receiver is tuned to the output. The remote base (fig. 34) is a form of repeater whose location has a height or tactical advantage.

An unattended repeater may be operated by remote control under the provisions of Section 97.43 of the FCC Rules; control may be by wire, or by radio on an amateur frequency above 220 MHz. In some instances, remote repeaters serve on common frequencies so that individual groups operating

tion between individual units operating on a common transmit and receive frequency, which may, in turn, be interfaced with repeater operation, using either a local or re-

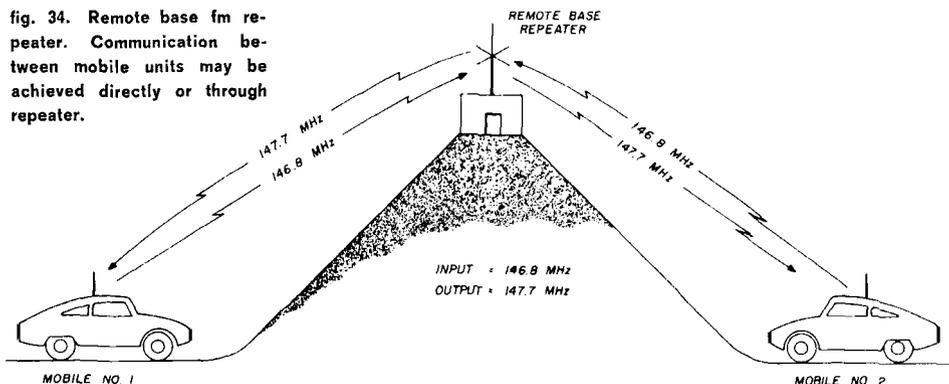
fig. 32. Automatic-frequency-control circuit.



mote base. While most repeaters are limited to a single communication channel, multiplex operation, or simultaneous transmission of two or more signals on a common carrier, is sometimes employed by means of narrow band filter techniques. For example, simultaneous voice and RTTY transmissions may occur on a single fm channel. It is also

usually 40 kHz, beginning with 52.56 MHz, in addition to the national calling channel at 52.525 MHz. Some narrow-deviation fm is used on the West Coast on 51.0, 51.1, 51.2 and 51.3 MHz, with additional channels near these frequencies for limited-access repeaters. Fm channels on the 2-meter band are usually 60 kHz apart, starting at 146.040 MHz, includ-

fig. 34. Remote base fm repeater. Communication between mobile units may be achieved directly or through repeater.



possible to insert traffic at a repeater for transmission in either or both directions. **Duplex** (simultaneous two-way) transmissions through the repeater may be achieved in many cases.

### vhf amateur fm operating standards

Generally speaking, vhf amateur fm techniques are based upon the channel concept. Transmitters and receivers are mainly crystal controlled on a given channel and random tuning techniques common to the lower frequency amateur bands are absent. Channel spacing on the 6-meter band is us-

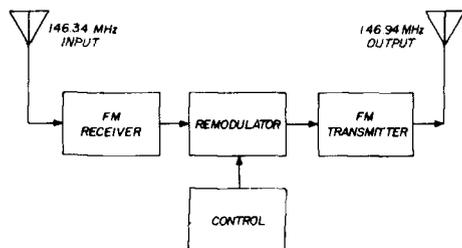
ing the national calling frequency at 146.94 MHz. A spot frequency of 29.6 MHz is often used for fm operation on 10 meters, with channel spacing of 40 kHz starting at 29.040 MHz. On the 420-MHz band, channel spacing is 50 kHz. Standard deviation for all bands is 15 kHz, with some trend towards narrower deviation of 5 kHz. Antenna polarization is vertical. In some areas where both wide- and narrow-band equipment is in use, a compromise deviation of 7.5 kHz peak is used.

### getting started

Vhf fm is an increasingly popular facet of amateur radio. The contrast in operating techniques from the QRM-filled lower frequency bands appeals to many operators. A big advantage of fm is the "quiet intercom" style of operation. Crystal-controlled transmitters and receivers eliminate tuning and missed call letters, fading is conspicuously absent, and interference is minimum.

Radio clubs and technical groups find fm perfect for club communication, and semi-private fm nets are springing up in the larger cities, as are "open" nets. Several nationwide channels have been established so that

fig. 33. Block diagram of a typical vhf fm repeater.



fm'ers from one area can quickly establish communication in another area when mobilizing across the country.

Second-hand fm equipment is available from many sources at prices ranging from ten dollars for "junkers" up to \$100 or so. A good mobile two-way fm installation should probably be available for under \$70, depending upon power, model and condition of the gear. Motorola, General Electric and RCA are some of the more popular makes of equipment, as circuit diagrams and replacement parts are readily available.

Some imported equipment for 2- and 6-meter fm is starting to show up on the American market; and other U.S. brands such as Link, DuMont, Kaar, Aerotron and Bendix are common also. Conversion of commercial gear for amateur use entails the purchase of new crystals and retuning of various stages to the amateur bands. Some vhf commercial gear (for the 148- to 170-MHz range) requires padding capacitors in the rf stages.

A gold mine of information on the latest

**This battery-operated fm handie-talkie provides one watt output on two meters and is typical of surplus gear used on the amateur bands.**



in amateur fm techniques and equipment may be found in the monthly magazine *FM*<sup>13</sup>. For additional background on fm techniques, the reader is referred to references 14 to 22.

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# using integrated circuits with single-polarity power supplies

This clears up  
the question  
of power-supply  
connections  
to linear IC's  
and presents some hints  
on lead dress  
and bypassing

John J. Schultz, W2EEY, 40 Rossie Street, Mystic, Connecticut 06355

Although an IC may specify a dual-polarity power supply, a single-polarity supply can usually be used. This applies to almost all IC's but should be of particular interest to those who read my article in the May 1968 issue of *ham radio*.<sup>1</sup>

The article showed the uses for an IC operational amplifier in amateur radio circuit applications. Apparently, however, some readers have been confused as to how the power-supply connections to the IC should be handled. Since similar confusion can develop when using an IC—not just the one shown in the article—I thought it would be worthwhile to explain in some detail how proper power supply connections to an IC can be made.

## basic mistake

Perhaps the simplest mistake was to misunderstand the power-supply voltage requirements. For instance, in **fig. 1**, which is a simple wideband rf amplifier, some builders connected a 6-volt battery between terminals 4 and 6, and others connected a 12-volt battery between the same terminals. Both connections are wrong. The IC won't function and will probably be ruined by the 12-volt battery. Note there are three reference points for the power supply connections: terminals 1 and 3, 4 and 6. Terminal 4 must be 6 volts negative with respect to terminals 1 and 3. Thus, two 6-volt batteries are required, or a power supply that will deliver a plus and minus 6-volt output. This basic dual-voltage requirement is common to most operational amplifier IC's.

## a dual-polarity supply

There should be no problem in obtaining the dual-polarity voltages. The simple circuit



figs. 3B and 4B can be connected directly to +V.

If the original circuit had terminal 1 connected in some sort of feedback or dual-input function, then R2 must be used. Its value can be best determined by experimentation, so that the original circuit function isn't disturbed. A practical rule, however, is to make R2's value equal to about the parallel combination of R1 and the feedback resistor used in a specific circuit (the 22k-ohm resistor between terminals 5 and 2 in fig. 1).

### some samples

Probably the best way to clarify the principles just mentioned is to illustrate their application to a specific circuit. Suppose you

want to operate the wideband amplifier shown in fig. 1 from a single-polarity power supply. Fig. 5 shows two ways of accomplishing this.

In fig. 5A a zener voltage divider is used to obtain 6 and 12 volts from the power supply. Terminal 6 of the IC goes to the 12-volt point. The terminal 4 dc-reference shown in fig. 1 is now connected directly to ground. The 100k-ohm resistor between terminals 1 and 2 performs the isolating function of R1 as described for fig. 3B.

Fig. 5B shows almost exactly the same connections, except that a simple resistive voltage divider, instead of a zener-diode divider, is used to obtain the 6-volt level.

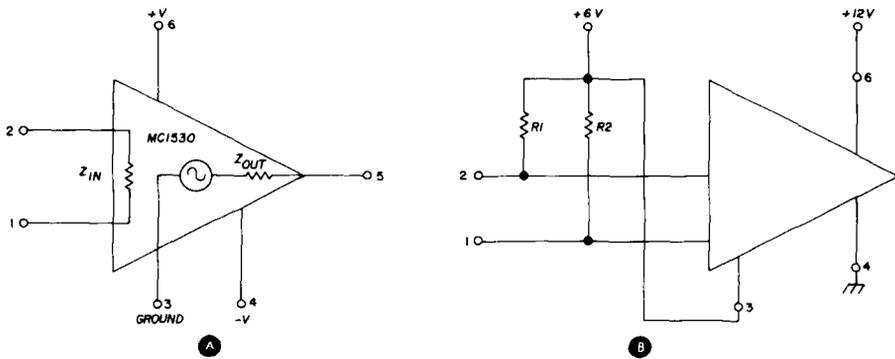


fig. 3. Equivalent circuit and signal-polarity supply connection for an IC having an external ground terminal. Signal connections are not shown.

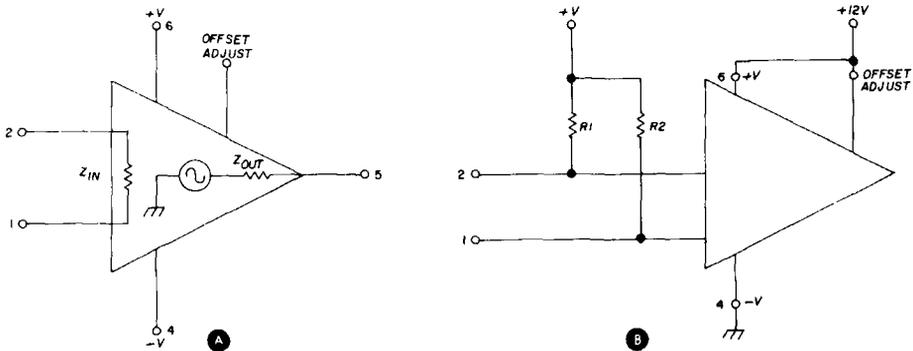


fig. 4. Equivalent circuit and single-polarity supply connection for an IC with an internal ground terminal. Terminal marked "offset adjustment" may not be present on all operation-amplifier ICs.

Either circuit can be used, depending on the components available and the regulation of the basic power supply.

Note that either circuit places a dc-bias voltage on the input and output terminals of the IC, which was not present before. Therefore, if the original circuit used direct coupling to the input and output stages, a dc-blocking capacitor will be required in the input and output leads. Normally, this won't alter circuit performance. The only exception would be if the IC were used as a dc amplifier. In this case, additional circuitry may be necessary, or it may not be feasible

to operate the IC from a single-polarity power supply.

### an exception

Almost all IC's require the techniques described. However, if a unit designed for a dual-polarity power supply is to be used properly with a single-polarity supply, you'll find that manufacturers are designing their IC's to be used with different power supplies. The IC internal circuits are arranged to avoid the necessity for biasing the IC input terminals for different power supplies.

Fig. 6 illustrates such an IC: the Motorola

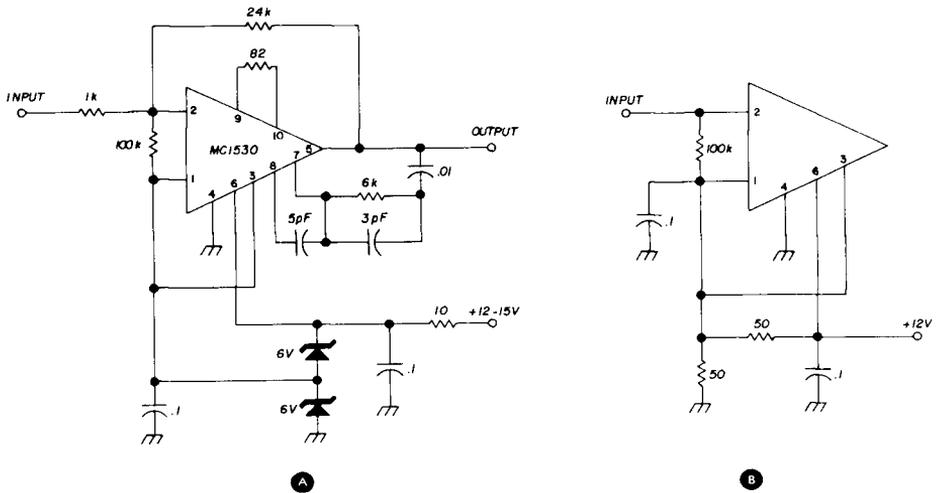


fig. 5. Two methods of providing a voltage divider. Complete circuit is shown in A; only dc-power connections are shown in B.

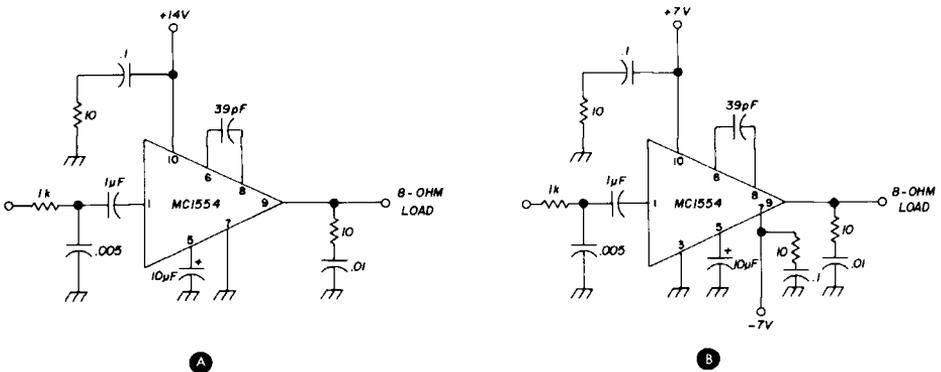


fig. 6. The Motorola MC1554 (HEP 593) audio power amplifier IC is especially designed to simplify operation from either a single- or dual-polarity supply (A and B respectively).

MC1554, which is a complete 1-watt audio power amplifier. **Fig. 6A** shows IC connections using a single-polarity power supply, and **fig. 6A** those using a dual-polarity supply. The connections are similar and involve no modification to the input circuit. Terminal 10 (V+) is connected to the positive power-supply terminal in both cases. Terminal 7 (V-) is connected either to ground or to the negative power-supply terminal. Terminal 3, called the bias-reference terminal to avoid confusion with the V-terminal (which may also be connected to ground), is either unused or grounded as shown.

### decoupling and suppression

Care must be taken in any amplifier to prevent oscillation and instability due to signal coupling via power supply or other leads. The requirements are even more stringent for IC's because (1) the IC is a concentrated package of high gain capability, and (2) it has an extremely wide frequency response. An audio-amplifier IC, for instance, may have a response up to several hundred kHz. Therefore, feedback capacitances or coupling circuits small enough not to affect a tube or transistor audio amplifier may well cause an IC amplifier to oscillate. These oscillations may not be heard because of their high frequency, but nonetheless can cause the IC to heat up and possibly be destroyed.

The 10-ohm resistor and the 0.1- $\mu$ F capacitors shown in **fig. 5A**, the 0.1- $\mu$ F capacitors shown in **fig. 5B**, and the series 10-ohm and 0.1- or 0.01- $\mu$ F networks shown in **fig. 6** are examples of decoupling or bypassing components. They should never be eliminated to simplify construction. These components are shown at various places in the schematics, but in practice they should be mounted as close as possible to the IC terminal with which they are associated. All lead lengths should be kept as short as possible to avoid the buildup of lead inductance, which can cause instability.

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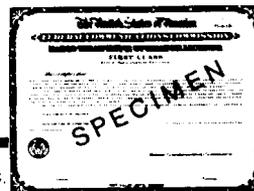
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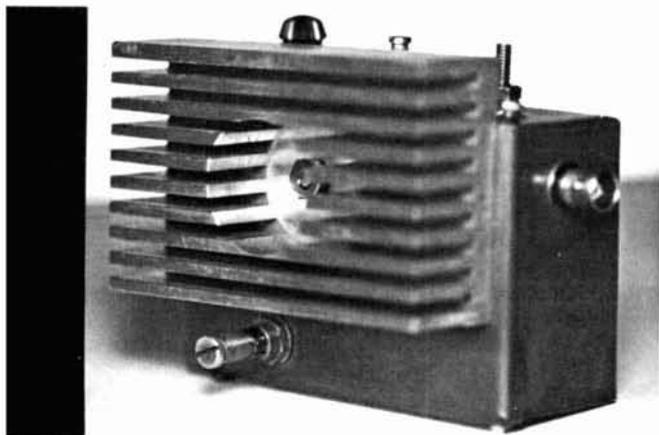
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## a frequency tripler for 1296 MHz

Introducing  
the varactor  
as an  
efficient microwave  
harmonic generator  
for  
transmitting use

Joseph J. Moraski, K4SUM, Charles E. Spitz, W4API,  
1420 S. Randolph Street, Arlington, Virginia 22204

Of the many pursuits available to experimenters in amateur radio, perhaps none offers more challenge and personal satisfaction than working in the frequency region above one gigahertz. It's challenging because tubes and components obey physical laws in a different manner than at the lower frequencies. Personal satisfaction occurs when you've mastered the techniques and special discipline required to make microwave circuits perform properly (or at all).

The objectives of this article are to encourage more amateur activity in our microwave bands and to show how we resolved one of the many problems one encounters at the "last frontier"—obtaining useful drive power in a frequency tripler at 1296 MHz through the use of a simple homemade cavity.

### some background information

An excellent discussion of the behavior of grid-controlled power tubes at the higher frequencies is contained in reference 1. One of the things the article points out is that, as frequency increases, the internal structure of the tube becomes an appreciable part of the resonant circuit. Driv-

ing voltage decreases because of the reactance presented by tube lead inductance. Because of this and other peculiarities, tubes operating at uhf and beyond are inefficient as frequency multipliers, at least in amateur work.

## the varactor

Solid-state technology has developed a device that seems, presently, to be the only answer for obtaining usable amounts of power with reasonable efficiency in multiplier circuits at the higher frequencies. The device is known as a varactor, or voltage-variable capacitance diode.

By definition a diode is a two-terminal p-n junction. Normally it operates as a rectifier (forward conduction), or as a voltage regulator (zener) conducting in the reverse direction. True, the varactor is a two-terminal p-n junction, but it's not correct to call it a diode per se. As with all p-n junctions, the varactor has a junction capacitance. This is what makes the varactor work as a frequency multiplier. The junction capacitance varies with applied voltage, which results in harmonic production.

A very readable treatment of varactor principles is contained in reference 2. Equations are derived showing the relationship of junction capacitance and applied voltage. The end result is a voltage across the varactor containing two dc components and a second component rich in harmonic content.

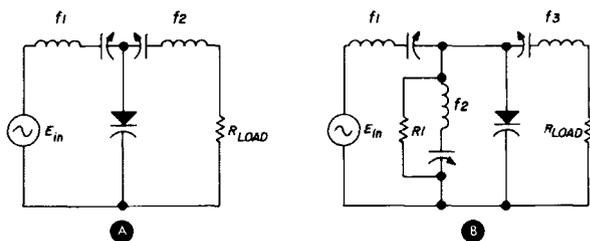
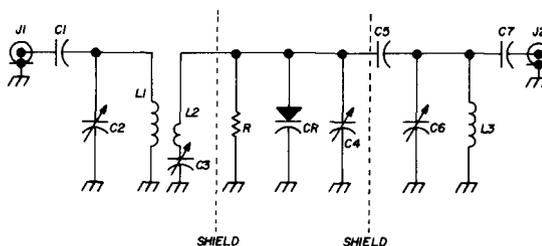


fig. 1. The varactor as a frequency multiplier. In A  $f_1$  is tuned to the fundamental and  $f_2$  to its second harmonic. Part B shows a tripler circuit with  $f_2$  tuned to the second harmonic (the so-called idler). Series circuit  $f_3$  is tuned to the third harmonic of  $f_1$ . Bias voltage is developed across  $R_1$  when the varactor is driven into conduction on peaks of the input voltage.

## higher-order harmonic generation

In varactor application if frequencies higher than the second harmonic are desired, idler circuits are used. These are tuned circuits that pass or attenuate harmonic currents to obtain the desired output frequency. Fig. 1 shows the development of a frequency multiplier varactor for generating third-order harmonics. The tuned circuits are affected by the varactor capacitance, which in turn varies as a function of the applied voltage. In a harmonic generator this voltage varies sinusoidally, so the average varactor capaci-



- C1, C5, C7** Brass or copper disc, 0.4 inch diameter
- C2, C6** Brass or copper rod, 10/32 thread
- C3** 0.6 — 30 pF piston (Johanson JMC 1901\*)
- C4** 0.6 — 5 pF piston (Johanson JMC-1375)
- L1** Brass or copper tubing, 5/16 inch diameter, 2.55 inches long
- L2** No. 14 copper wire, 3 1/2 inches long
- L3** Brass or copper tubing, 5/16 inch diameter, 1.1 inch long
- J1, J2** Single-hole-mount female BNC connectors
- R1** 100k to 1 megohm, 1/4 W (see text)

fig. 2. Schematic of the 1296-MHz tripler. The varactor can be a Motorola 1N5149, Amperex H4A (1N4885), or Microwave Associates MA-4060—all were successfully tried in this circuit.

tance is used in the design. The capacitance varies with signal power, and some circuit detuning occurs if there is a substantial change in input power. The effect is undesirable, especially in a-m ap-

\* Surplus units available from Fertik's Electronics, 5249 "D" Street, Philadelphia, Pennsylvania, 19120. The small ones are 3 for \$1.00; larger ones are \$.65 each.

plications, but is practically eliminated in step-recovery junction varactors, as discussed below.

### junction characteristics

Varactors are of two types, step junction and step recovery junction. In the former, the impurity level is constant in the p-n layers, while in the latter the impurity level is concentrated at the lead contacts and decreases toward the junction. This makes for high resistivity near the junction and low resistivity at the lead contacts.

An important parameter of varactors is the equivalent series resistance, composed of the bulk and contact resistance of the semiconductor material. This resistance is directly related to varactor efficiency, and therefore kept as low as possible. By employing a constantly decreasing impurity profile from lead contact to junction, the average series resistance remains at a desirable low value when a reverse voltage is applied. This is because the depletion layer dissipates the high resistivity region. The average series resistance is therefore kept low.

Why use step recovery junction varactors for harmonic generators? Because they provide higher power and a more linear relationship of power output to power input. What this means in terms of efficiency (power out/power in x 100) is demonstrated in **table 1**, which shows the power linearity characteristic of a typical step-recovery varactor used as a frequency doubler.

The average efficiency of this particular varactor is about 66 percent, which is typical when operating a frequency doubler. However, we were able to obtain yields of 50-percent plus, using similar varactors as **frequency triplers** with output at **1296 MHz**.

Essential to the performance of any rf generator are the tuned circuits. This is especially true at microwave frequencies for the reasons pointed out earlier. The easiest way to solve this problem is to use resonant cavities. If the procedures used in commercial practice are followed, cavities are difficult for the average amateur to build. However cavities need not be

round, as in most commercial applications. Frequencies in the 1-GHz region are high enough to permit a small rectangular chassis to be used, with divider strips acting as cavity partitions. Commercial test jigs have been made in a similar manner, but with facilities and materials beyond usual amateur resources.

If you're reasonably adept with hand

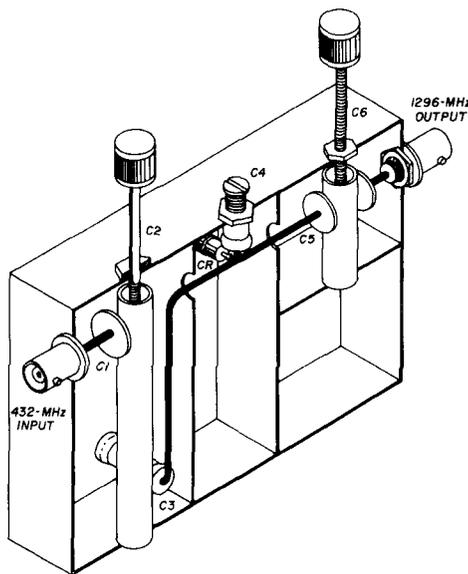


fig. 3. Assembled 1296-MHz tripler.

tools and like to work with soft metal, you should be able to duplicate the tripler described here. With an input of 20 to 25 watts on 432 MHz, we built three units that put out a respectable 10 to 15 watts on 1296 MHz. All have been operating for almost a year. The schematic is shown in **fig. 2**. Capacitors  $C_1$ ,  $C_5$ , and  $C_7$  are single discs; the other capacitor plate is formed by the tubing ( $L_1$  and  $L_3$ ).

The chassis and cavity partitions were made from 0.032-inch sheet brass. It might be possible to use a commercially available chassis of nearly the same dimensions, such as the Bud CU-341 Convertabox. The partitions could be made and added as shown. However, we haven't tried this, and for best results we recommend using the materials and dimensions shown. The tripler we built is shown in the

photo and in fig. 3. Fig. 4 shows component layout.

In fig. 3 the varactor stud protrudes through the rear wall where a heat sink was placed over the stud. A solder lug was placed at the varactor base for grounding the bias resistor. The resistor is shunted directly across the varactor.

The brass sheet is cut to the shape of fig. 5.\* Drill holes to sizes indicated. When

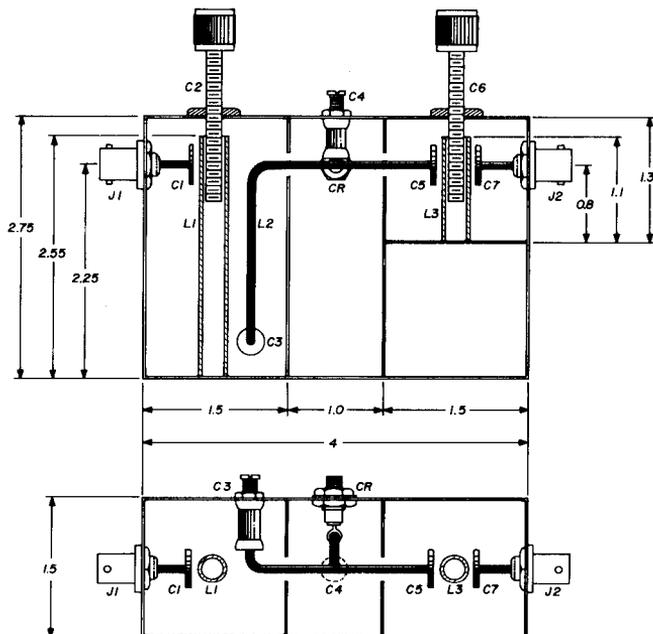


fig. 4. Plan and side views of the 1296-MHz varactor tripler.

the ends are bent, a chassis will be formed 4 inches wide x 2-3/4 inches deep x 1/2 inch high. Solder corners using a heavy iron or torch. Next, cut out the partitions and cover following the scale-size template. Insert partitions C, D and E making sure the holes D and F are drilled before soldering the partitions into place.

The cover is also shown in fig. 5. Bend the corners as indicated, solder smoothly, file, and buff. The idea is to get a good

\* Full-scale templates available from ham radio magazine for \$.25.

fit without warping the chassis.

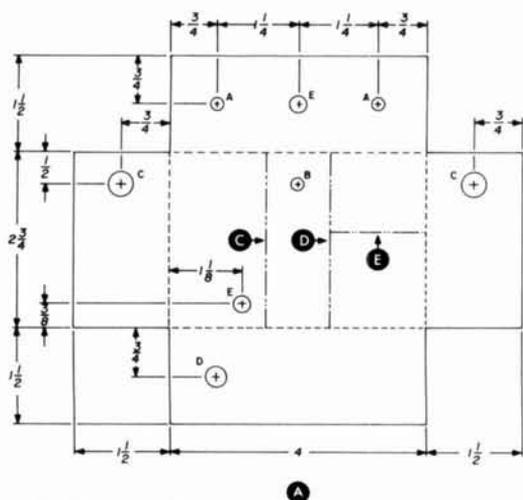
The 432-MHz and 1296-MHz cavities are capacitively tuned by turning their 10-32 threaded rods ( $C_2$  and  $C_6$ ) into tubing inductances  $L_1$  and  $L_3$ . It is important to maintain constant metal-to-metal contact between the tuning screws and the chassis. A 10-32 brass nut is soldered over holes A. It may be necessary to use a locking nut and spring between the knob and soldered nut if the threads don't mate well enough for continuous contact.

Solder the bases of the brass tubing flush with holes D. Try to make this a tight and straight fit before soldering. Screw the threaded rods through the tubing to ensure centering and alignment, then solder the base. This is where a torch works best. A teflon washer may be forced on the bottom of each threaded rod to prevent shorting or teflon spaghetti may be used.

The next step is to install BNC fittings  $J_1$  and  $J_2$  with their discs,  $C_1$  and  $C_7$ . Spacing between the discs and the brass tubing is approximately 1/32 inch. On one model we made, the BNC nuts were soldered to the outside of the chassis so these spacings could be made variable. A short wire lead will be necessary between the disc and BNC inner conductor. This dimension is not given, as the length of the center conductor may vary between different BNC chassis fittings. The critical factor is the spacing of the disc.

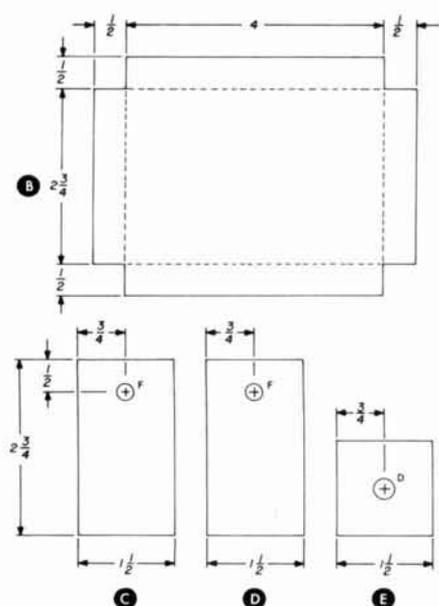
Install plunger tuning capacitors  $C_3$  and  $C_4$  with serrated washers under the nuts. Install  $L_2$  in one piece, soldering one end to  $C_3$  and the other to the  $C_5$  disc. Approximate spacing of  $C_5$  from  $L_3$  is about 1/16 inch. Be very careful to apply **minimum heat** or use heat sinks when soldering to the plunger capacitors. Too much heat can crack the glass or warp the glass-to-metal seals so the plungers won't enter the stator cups. Many plunger capacitors are ruined this way. Solder only to lugs or pins provided.

Place a solder lug on the varactor stud, then place the stud through hole I. Fasten with serrated washer and nut. If a heat sink is used, make it secure but not overly



- A NO. 9 DRILL TO CLEAR 10-32 THREADED ROD  
 B 3/16" (TO FIT VARACTOR USED)  
 C 3/8" (FOR BNC CONNECTORS)  
 D 5/16" (SHUG FIT FOR BRASS TUBING)  
 E 1/4" (TO FIT CAPACITOR USED)  
 F 1/4"

fig. 5. Chassis layout for the tripler.



tight until soldering is done, when the nut can be loosened for final placement of the heat sink. Solder the resistor to the lug as reasonably short and straight as possible so it's parallel with the varactor. Join varactor, resistor, and  $C_4$  idler capacitor at a common point on  $L_2$ , then solder. Maximum output will be obtained with a 1-megohm resistor; however if the driver is modulated greater linearity will result if 100k is used.

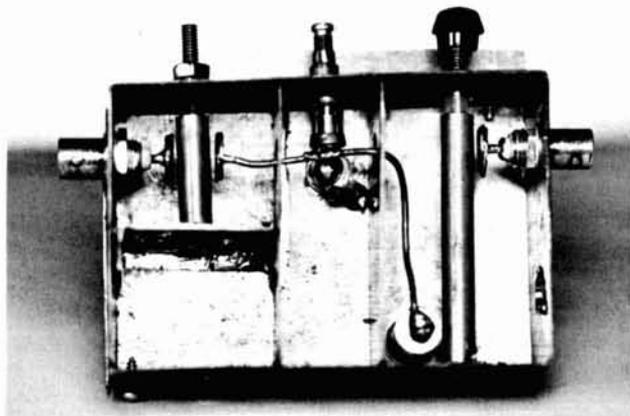
The teflon tubing may be kept from falling out by using Scotch X-1181 copper foil tape with conducting pressure-sensitive adhesive. The tape can also be used instead of finger stock to seal the compartments. "Sticky Fingers," a pressure-sensitive-backed finger stock made by Instrument Specialties Company, of Little Falls, New Jersey was also considered, but the size of the available stock was too large for use with the small cavity.

### cool it

Overheating the varactor at this power level can and does occur. The DO-5 case mounting stud, which protrudes through the chassis may be felt for heat. Another sign of overheating is a gradual decrease in output power with no change in the

input. The best preventive measure is to use a heat sink and preferably air from a fan. We used some finned aluminum heat sink stock 4 inches long x 2 1/2 inches wide x 1 inch deep. It was a piece of surplus used for power transistors and had one flat side. The varactor stud goes through a hole in the heat sink, then is fastened with its nut and washer to clamp the

**Underchassis view of the 1296-MHz tripler. Note lead dress, especially of capacity C5. Some bending might be necessary to optimize output.**



varactor, heat sink and chassis together. A Whisper fan furnished more than enough air to keep the varactor cool at extended periods with maximum power.

### operation and tuning

The input and output levels were measured and monitored using a Bird Model 43 coaxial line section, panel meter, and 400-1000-MHz element. With this element readings are about 1 dB low on 1296, but the cost was about one-third of an element with greater accuracy. Frequency readings were taken with a surplus F-26/UPR wave trap, which is calibrated from 1.25 to 6.0 GHz. Although the idler frequency is off scale at 864 MHz, it can be read. Since varactors will readily double with high efficiency, care must be taken to minimize idler output while maximizing 1296-MHz output during tuneup. The surplus TS-186 frequency meter, which has a range of 100 MHz through 10,000 MHz, with visual as well as audible output, may also be useful. While all this test gear is not absolutely necessary, it does speed things up for the initial alignment.

If the output is less than at least 7 watts with 20 watts input, and all tuning controls have been optimized, a greater yield may be possible by repositioning the disc capacitors, either in spacing or by a slight upward or downward deflection. However, each change must be accompanied by completely retuning all variable elements for maximum output at the desired frequency. A great deal of time can be saved if you can monitor the input power, output power, and output frequency during tuneup. If you do get 50 percent efficiency, leave it alone!

An input filter at 432 MHz is necessary if you use a stripline varactor tripler, a tube tripler, or grounded-grid stage as a driver, because all these circuits contain harmonic and mixing frequencies that would be seen and used by the 1296-MHz varactor tripler. On the other hand, the tripler output cavity should have about 30 dB rejection of unwanted frequencies when properly adjusted. If the output is fed directly to an antenna, a filter may be

**table 1. Power conversion in watts of the IN5150 without retuning.**

Output	Input
4	4
6	9
8	12
10	16
12	18
14	20

$$f_{in} = 0.5 \text{ GHz}, f_{out} = 1 \text{ GHz}$$

called for. If it's used to drive an amplifier with tuned input and output circuits at 1296, one may not be necessary.

The cover should be used at all times. This reduces radiation loss, prevents having to retune when the cover is placed on the chassis, isolates the compartments in the chassis, and avoids a real hazard of biological injury from radiation at these power levels. If screws are used to fasten the cover, sheet-metal screws as small as possible should be used, with two at the top and bottom of the varactor compartment, one at the center of the 432-MHz cavity, and one just below the bottom of the 1296-MHz cavity.

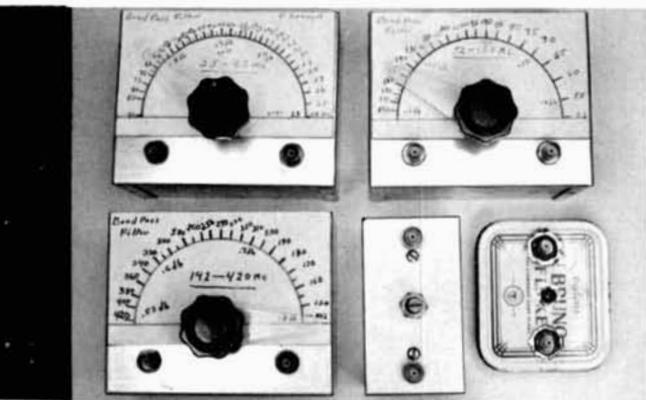
Fairly acceptable modulated signals for local use have been produced where the basic modulated transmitter was on 144 MHz and passed through two triplers. With the varactor input reduced so that a cool ICAS output of 7.5 watts was maintained on 1296 MHz, a pair of 7289's (improved 2C39A, 3CX100A5) as an amplifier produced 40 watts output with a plate voltage of 800 and plate current of 200 mA. There was no sign of creeping or overheating.

Construction and operation of the unit is simpler than it might appear from the description given, but we felt these details would be helpful since most amateur data on the subject seemed meager.

### references

1. R. I. Sutherland, W6UOV, "Vhf/uhf Effects in Gridded Tubes," *ham radio*, January, 1969, p. 8.
2. "The Semiconductor Data Book," Motorola, Inc., Semiconductor Products Division, 2nd Edition, p. 16-89.

**ham radio**



## tunable bandpass filters for 25 to 2500 mhz

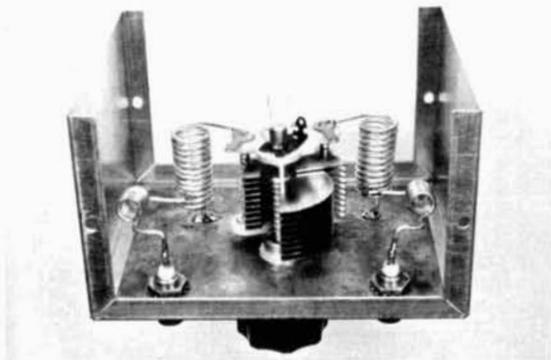
Here are  
some useful additions  
to your vhf  
and uhf  
test equipment

Del Crowell, K6RIL, 1674 Morgan Street, Mountain View, California 94040

For all their advantages, solid-state devices are not without their problems, especially when used in amplifier and multiplier circuits in the vhf and uhf regions. If you have used these devices in such applications, you've probably run into the same problems I have—is the output at the desired frequency?

The bandpass filters and accessories described here are great additions to your test equipment. They will allow you to build and adjust many circuits that would otherwise be

**Construction of a bandpass filter that covers from 25 to 85 MHz.**



Filter	Frequency Range (MHz)	L1, L4	L2, L3	C1
A	25 to 35	6 turns no. 14 1/4" diameter, 1/8" long	12 turns no. 14, 1/2" diameter, 1 1/2" long; tapped 1 1/2 turns from ground	9—140 pF (Hammarlund MC140M)
B	52 to 190	4 turns no. 16 1/4" diameter, 1/2" long	4 turns no. 16, 1/2" diameter, 3/8" long; tapped 1 1/2 turns from ground	7.7—100 pF (Hammarlund MC100M)
C	142 to 420	2 turns no. 16 3/16" diameter 1/4" long	3 1/2 turns no. 14, 3/16" diameter, 3/8" long; tapped 2 turns from ground	6.3—50 pF (Hammarlund MC50M)
D	230 to 1350	see fig. 3	see fig. 3	0.7—30 pF piston
E	2000 to 2500	see fig. 5	see fig. 5	see fig. 5

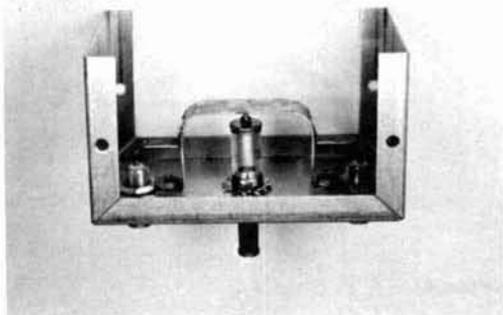
fig. 1. Bandpass filters cover the frequency range from 25 to 1350 MHz and 2.0 to 2.5 GHz.

almost impossible. An accurately calibrated, general coverage receiver with a panadaptor will give good results when making circuit adjustments using these filters.

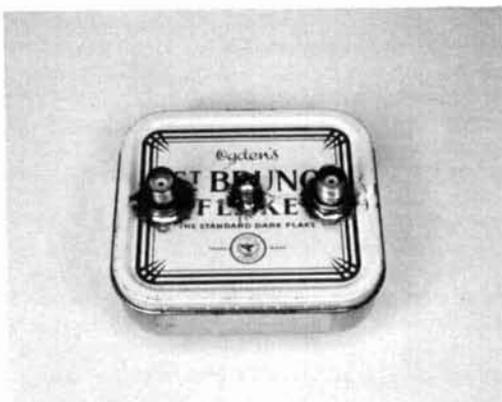
## description

Filters A through D in fig. 1 use a half-wave resonant circuit with series matching coils. This helps maintain a constant impedance and provides a balanced circuit with good operating Q. The circuit diagram and coil table show the L-C relationships. Bandwidth is primarily governed by the amount of loading, which is determined by the tap point on L2 and L3. L1 and L2 are

**Bandpass filter for 230 to 1350 MHz uses a brass-strap inductor.**



The 2.4 GHz bandpass filter is built around an old tobacco tin.



used to maintain a more constant loading with frequency; the tap points given in the table are optimum for general-purpose use. Filters with a tuning range of three to four octaves can be constructed using this principle.

## construction

Bandpass filters covering 25 to 420 MHz are basically the same, with only L and C changes required to cover the desired ranges. The filters can be duplicated by referring to fig. 1 and the photos. Filters A, B and C are constructed using a brass plate

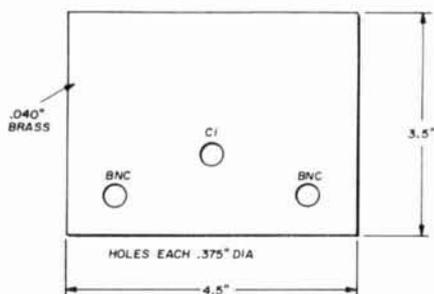


fig. 2. Brass mounting plate for filters A, B and C.

(see fig. 2) to mount the components. Coils are soldered directly to this plate. The assembly is then mounted inside an LMB779 5x4x3-inch chassis box.

The filters can be calibrated with a grid-dip oscillator; however, a good signal generator would be more accurate, of course. Referring to the circuit in fig. 1, the 3-dB bandwidth and total insertion loss can be varied by changing the points on L2 and L3. Tapping down on the coils gives greater selectivity but more insertion loss.

Filter D uses the same principle as A, B and C, except a strap inductor is used in

table 1. Bandpass filter data.

Filter	Frequency Range (MHz)	Frequency (MHz)	3 dB Bandwidth (MHz)	Loss
A	25 to 85	25	0.8	1.3
		32	0.9	1.1
		40	1.2	0.93
		60	2.0	0.80
B	52 to 190	55	6	0.40
		80	8	0.32
		110	10	0.30
		180	12	0.32
C	142 to 420	160	14	0.78
		210	20	0.70
		300	24	0.65
		380	30	0.56
D	230 to 1350	230	—	3.0
		250	—	2.5
		400	—	1.7
		432	45*	1.5
		480	—	1.4
		950	—	0.6
		1296	585*	0.35
1350	—	0.35		
E	200 to 2500	2300	400	1.0

\* 20 dB bandwidth

place of coils L2 and L3 (see fig. 3). An expensive capacitor was used in the model shown in the photo, but the simple screw-and-disc capacitor shown in fig. 4 will do the job nicely. A low minimum capacity must be used to reach above 1296 MHz.

Filter E is mounted in a discarded pipe tobacco can. I drilled holes in the ends for the input-output connectors and soldered a coupling wire from the connector to the

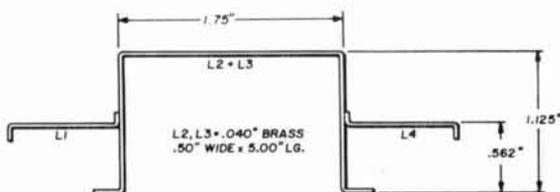
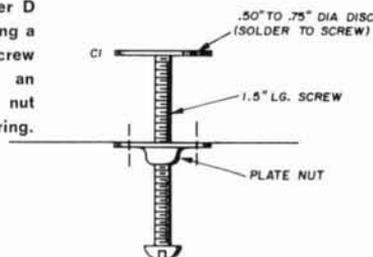
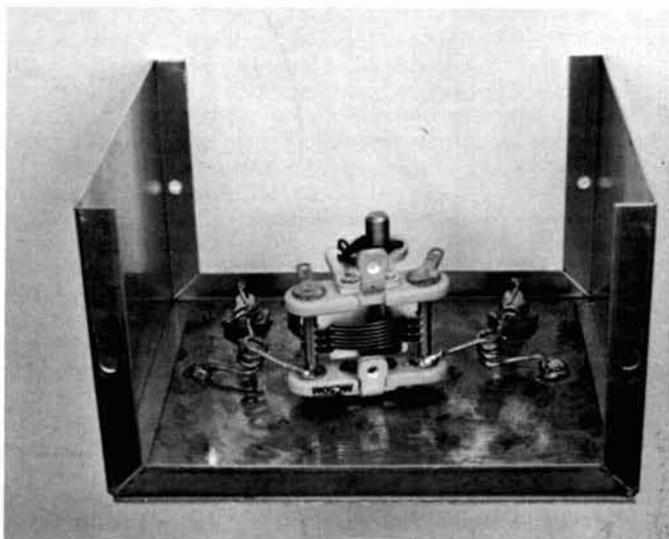


fig. 3. Inductor detail for filter D.

fig. 4. C1 for filter D is made by soldering a disc to a brass screw about 1½" long; an aircraft-type plate nut is used as a bearing.



Filter B tunes from 52 to 190 MHz.



bottom of the can (see fig. 5). Tuning is done with a threaded shaft and nut soldered in the center of the box; a friction lock nut is recommended. The last two filters don't have a calibrated dial, but once set they need be changed only slightly. A turns-counting dial with calibration chart could be used if desired.

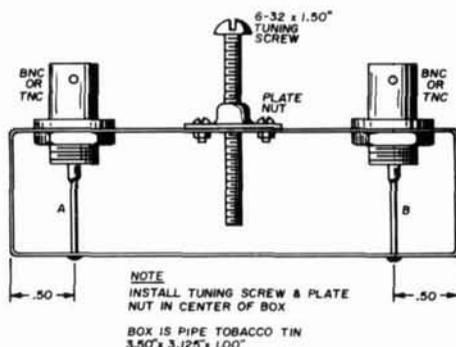


fig. 5. Bandpass filter that will tune from 2.0 to 2.5 GHz; filter will tune to 1296 MHz if a disc is attached to the end of the tuning screw. The position of the coupling probes A and B determines bandwidth and insertion loss. Space the probe  $\frac{1}{4}$ " from end of tobacco tin for less bandwidth; however, insertion loss will be slightly increased.

fig. 6. Typical test setup using the bandpass filters.



Filter C tunes from 142 to 420 MHz.

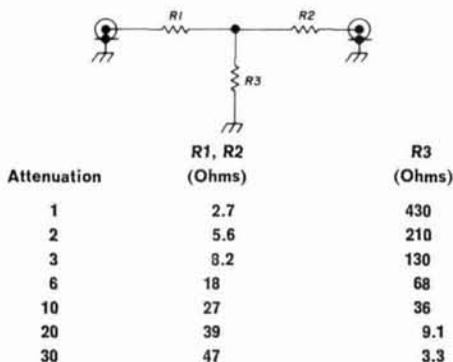
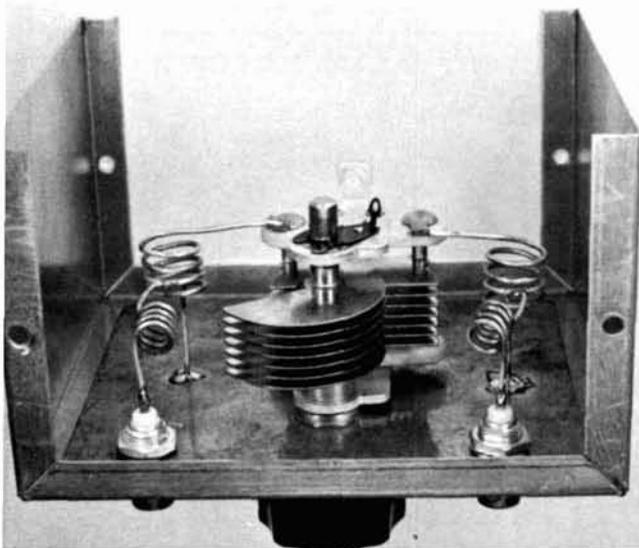


fig. 8. Attenuator circuit using standard 5% carbon resistors is not exact, but very close. Put all three half-watt resistors in a brass tube 2" long and solder BNC connectors to the ends.

## application

Using a filter at the output of a circuit will help you determine what signals are being generated. The filter will pass only the desired signal. Output level will then be the one desired; also by tuning the filter through the harmonic ranges, you can see what harmonic power is being contributed.

The output power of low-level amplifiers

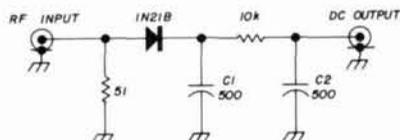


fig. 7. Sensitive rf detector probe. Capacitors C1 and C2 should be good quality ceramics.

or multipliers is sometimes only a few milliwatts, and of course most power-measuring devices won't indicate in this range. The only alternative is to use an expensive milliwatt meter or a home-made detector with a 50-ohm load. One is shown in fig. 7. I also recommend that an attenuator be used between the test circuit and the filter input as in fig. 6 because the filter inductance can upset circuit tuning.

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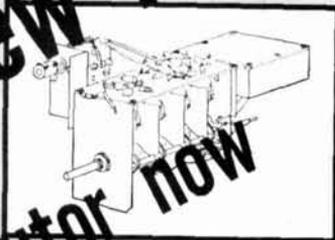
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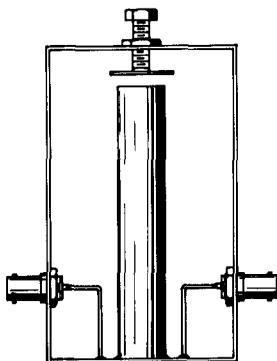
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 73-88 Hammarlund Drive, Mars Hill, North Carolina 28754

# single-pole bandpass filters

Probably the most common type of band-pass filter for amateur uhf work is the coaxial-cavity arrangement of **fig. 1**. This filter can be made to have very low insertion loss. However, the close proximity of the coupling loops results in some inductive coupling between input and output at all frequencies. The stop-band attenuation is

**fig. 1. The coaxial cavity filter commonly used at uhf.**



consequently not as high as a single-pole filter can be.

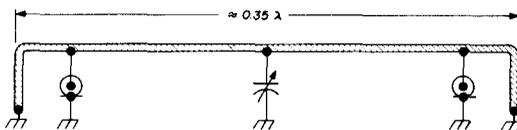
The arrangement of **fig. 2** places the input and output at opposite ends of the filter and results in better isolation. It also lends itself admirably to strip-line or trough-line construction. I built this filter to reject the usually strong, unwanted harmonics from a 432-MHz varactor tripler. Performance of the filter turned out to be quite remarkable, considering it was thrown together in twenty minutes total construction time with no attempt

to optimize anything. Attenuation vs frequency between 200 and 1000 MHz is plotted in **fig. 3**.

## construction

Construction details for the 432-MHz trough-line filter are shown in **fig. 4**. The trough is a 12-inch section of aluminum extrusion of the type used for sliding glass doors. The tuning capacitor is a miniature piston type with a range of 1.2 to 10 pF. It's a Triko 108-02M imported from West Germany. I was concerned that some of the 432-MHz insertion loss might be due to capacitor losses. To check this out I tried the filter in the output of the "big rig."

**fig. 2. This trough-line filter is not only easier to construct than the cavity type of fig. 1 but also gives superior performance.**



## performance

At high-power level the lossy components in a filter will become hot. It wasn't possible to run more than 30 watts through the filter without the tuning capacitor arcing over, but at this power level there was very little capacitor heating. It did become just perceptibly warm to the touch, but so did the number 12

Fred Brown, W6HPH, Pine Cove, Idyllwild, California 92349

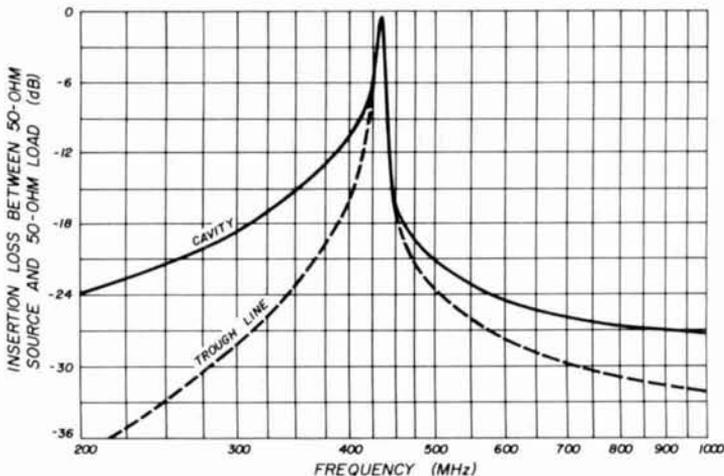


fig. 3. Comparison curves of the coaxial-cavity and trough-line 432-MHz filters. Note the superior stop-band rejection characteristics of the trough line.

copper wire center conductor. Probably the most important single factor for reducing insertion loss would be the use of a larger center conductor.

Also shown in fig. 3 is the performance of a conventional cavity filter. It, too, was designed to reject unwanted harmonics from a varactor tripler. The filter was made by K6JYO from a surplus TS1/ARR-1 gold-plated cavity.

Note that the stop-band attenuation of the trough-line filter is better throughout the entire measurement range of 200 to 1000 MHz. The cavity filter did have slightly lower insertion loss: 0.4 dB as compared to 0.8 dB for the trough line. This is to be expected because of the higher-Q construction of the cavity. Loaded Q's of both filters were comparable, as indicated by the 3-dB bandwidth of 9 MHz for the trough line and 7 MHz for the cavity.

### low-frequency version

The success of this uhf filter inspired construction of a low-frequency version using

**The aluminum trough-line filter outperforms conventional coaxial cavity below.**

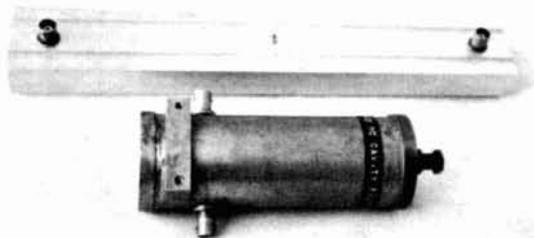
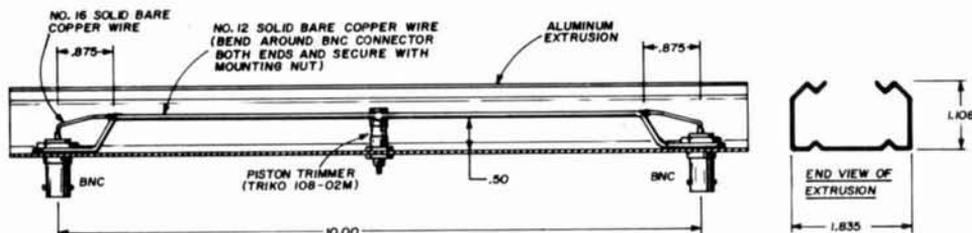


fig. 4. Construction details of the 432-MHz trough-line filter.



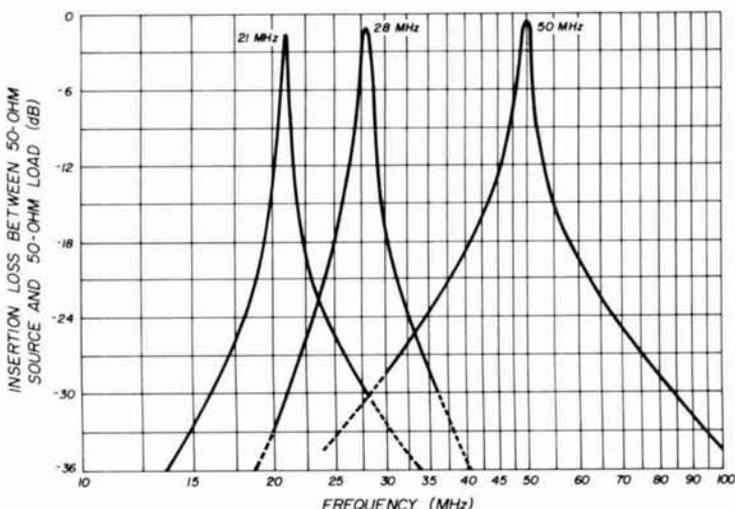
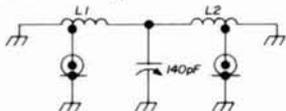


fig. 6. Performance curves of the low-frequency, lumped-constant version of the trough-line filter. Attenuation characteristics were measured with the filter tuned to three different frequencies: 21, 28 and 50 MHz.

lumped constants. It is built on a 2 x 4 x 8-inch chassis and consists merely of two coils, two BNC fittings, and one tuning capacitor. The schematic is shown in fig. 5. The LC combination gave a tuning range that covered the 15, 10 and 6 meter bands, so the filter response was measured at 21, 28 and 50 MHz.

fig. 5. Low-frequency version of the trough-line filter. L1 and L2 are 13 turns of number 16 bare copper wire, 5/8-inch diameter, 1-3/8-inch long, air wound, and tapped 1/4 turns from ground. The coils should be oriented to minimize inductive coupling.



## performance

As can be seen from the curves of fig. 6, this gadget should make an excellent tv filter if you don't mind retuning whenever you change frequency. The 3-dB bandwidth measured 2.2 MHz at 6 meters, 600 kHz at 10 meters, and 400 kHz on 15. Insertion loss was 0.7 dB at 50 MHz, 0.8 dB at 29 MHz, and 1.2 dB at 21 MHz.

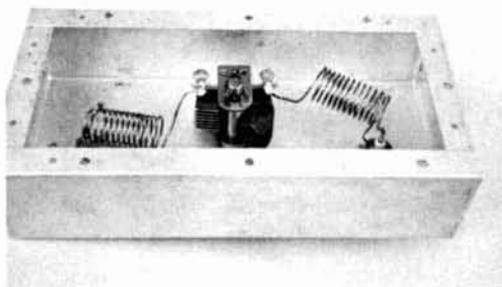
The insertion loss could have been reduced by using higher-Q coils (number 14 wire instead of number 16, for instance); or

by tapping the input and output higher up on the coils, say two turns from ground. This would also increase the 3-dB bandwidth.

Power-handling capability will be determined by the voltage breakdown point of the tuning capacitor. I've run 40 watts into this filter at 29 MHz, resulting in 35 watts delivered to the load. At this power level there is no tendency for the small variable capacitor to break down, but the coils become warm to the touch, indicating this is where the other 5 watts are being lost.

ham radio

Low-frequency lumped-constant version of the trough-line filter. This filter can be tuned to 6, 10 or 15 meters.





# standards for amateur microwave communications

This  
standard microwave  
system  
offers a practical means  
for amateur work  
above 1 GHz

Richard B. Kolbly, K6HJL, 26334 Community Boulevard, Barstow, California 92311

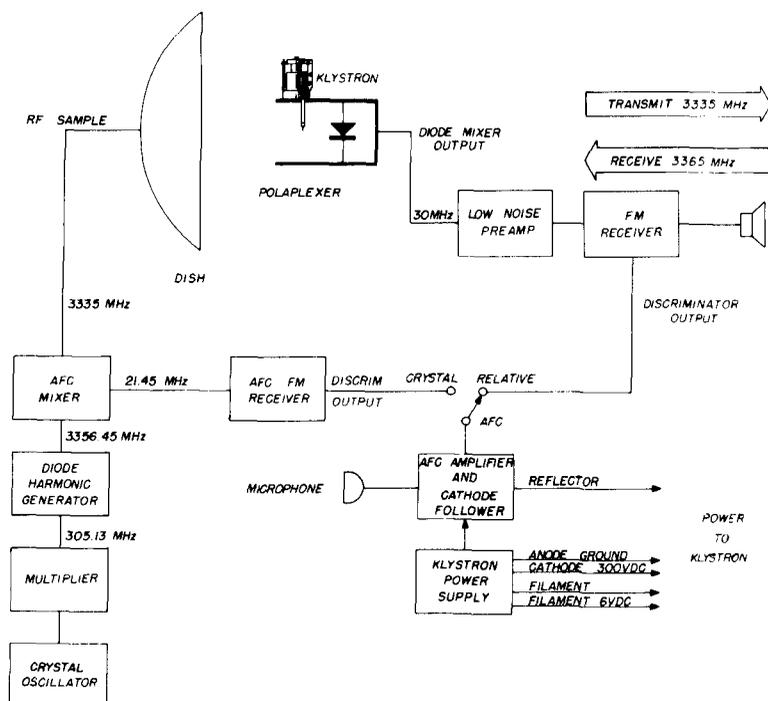
In 1956, the San Bernardino Microwave Society was incorporated to further the art of amateur communications above 1000 MHz. A prime objective of this organization has been to develop equipment and techniques for amateur operation that can be duplicated by the average amateur experimenter at moderate cost. It soon became apparent to the members that it would be necessary to develop a set of standards for amateur microwave work if the art was to be developed in other than a haphazard manner.

This article, which I hope will be first of many in amateur microwave techniques, explains the working standards that the SBMS members have evolved for their own use. These have been used by the members for a number of years and have proved to be very practical in field operation. The standards pertain to operating frequencies, polarization, modulation, power supplies and component interconnections. The standard SBMS system is full duplex, allowing simultaneous transmitting and receiving, with the transmitter frequency removed 30 MHz from the receiver frequency.

The microwave amateur bands are very large compared with the lower bands. In order to communicate effectively over long distances, it is necessary to have certain standard frequencies and operating techniques that are understood and used by the station on the other end. For example, the 3300-MHz band (high S-Band) is two-hundred megahertz wide—far too wide to

transmitter is frequency-locked to a crystal-controlled reference oscillator for stability. Fig. 1 is a block diagram of a typical SMBS microwave station. The antenna feed also acts as a receiver mixer. This system is designated ROCLOC, meaning **Relative Or Crystal Local Oscillator Control**. It was developed primarily by Don Thompson, W6IFE, and George Tillit-

fig. 1 A 3300-MHz ROCLOC station as used by members of the San Bernardino Microwave Society, Inc. (from W6OYJ).



search for a weak signal with a 1-kHz bandwidth receiver!

A large amount of surplus microwave equipment is available on the market, which is suitable for amateur work, with a wide range of possible interconnections. The members of the SBMS felt it was necessary to standardize interconnections to allow rapid replacement of system components.

### a typical station

The SBMS members operate a full-duplex system, with the transmitter also acting as the receiver local oscillator. The

son, K6MBL. This ROCLOC system has proved to be an effective and versatile ham microwave setup. Interconnections are more or less standardized to allow equipment to be easily interchanged and tested.

### frequencies

Standard operating frequencies are a necessity, as most members operate with narrowband receivers that have a limited tuning range. The selection of standard frequencies for microwave hamming was based on readily available klystrons and a safe separation from the band edges.

The selection of the frequencies listed in **table 1** was based on a 5-MHz safety factor to prevent out-of-band operation of a station accidentally tuned to the other side of an incoming signal. For example, W6IFE transmits to K6HIJ on 3335 MHz. K6HIJ is supposed to have his transmitter on 3365 MHz, 30 MHz away, but since his receiver has no image rejection, he accidentally tunes his transmitter to 30 MHz **below** W6IFE. He is on 3305 MHz, still 5 MHz inside the amateur band. All SBMS work is based on an i-f of 30 MHz.

Since the transmitter polarization is at right angles to the receiver polarization, (standard polaplexer), all SBMS members polarize transmitted and received signals 45 degrees from vertical, with the transmitted signal polarized 45° to the right of vertical in the direction of propagation.

### klystron voltages

A large number of klystrons available on the surplus market will operate satisfactorily with 300 volts of beam voltage, so the SBMS has standardized on this beam voltage, with the positive terminal (klystron body) at ground potential. Also, direct-current heater operation has been found necessary. Therefore a low-ripple, dc filament supply (5.8-6.3 V; 1.5 A), isolated from ground is required. The klystron reflector voltage (referred to the klystron cathode) will operate from -100 to -300 volts at very low current drain. Ripple, hash and noise on all power supplies should be less than ten millivolts (0.01 volt). The reflector supply is most critical in this respect.

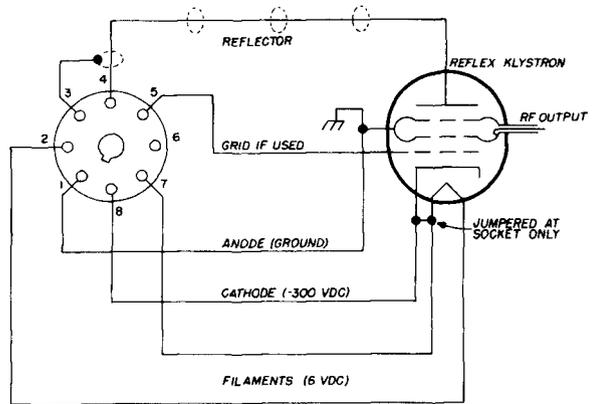


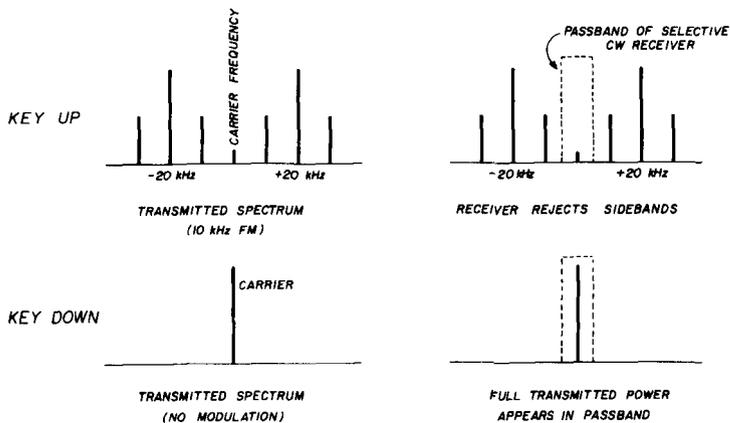
fig. 2. Typical klystron power connections.

For power connections to the klystron, standard octal plugs and sockets are used. The pin connections are shown in **fig. 2**. The supply side of the connection should be the female connector. By using these socket connections, it's possible to interchange klystrons with a minimum danger of damage to the klystron or power supply or of improper klystron operation.

### modulation modes

Amplitude modulation of a reflex klystron is difficult, so frequency modulation is used by the SBMS. For wideband operation, deviation is set to be compatible with the receiver, usually  $\pm 50$  kHz, as most of the members use BC-683 fm tank receivers as 30-MHz i-f strips. For weak signal work, it's necessary to go to narrow bandwidths and smaller deviation.

fig. 3. Principle of pseudo-cw modulation.



**table 1. Standard amateur preferred microwave frequencies.**

band	band limits (MHz)	preferred frequencies (MHz)
low S	2300-2450	2385 & 2415
high S	3300-3500	3335 & 3365
C	5650-5925	5860 & 5890
X	10,000-10,500	10,035 & 10,065
K	21,000-22,000	21,035 & 21,065 21,935 & 21,965

Usually the receiver has a bandwidth of 1 to 2 kHz, and deviation is set accordingly.

For very long-haul, weak-signal work, cw offers the best performance. To accomplish this form of modulation, the SBMS has developed "pseudo-cw" modulation. Fig. 3 illustrates the principles involved. The transmitter is frequency modulated at a high audio rate (10 kHz or so), and the deviation is adjusted to the first carrier null, with all the transmitter power in the sidebands. A narrowband receiver tuned to the carrier frequency will not receive a signal, as the sidebands are outside the receiver pass-band.

This modulation corresponds to a "key up" condition. Depressing the key ("key down") removes the modulation from the signal, and all transmitter power appears on the carrier frequency. This "pseudo-cw" signal is received exactly as a standard cw signal, with the receiver bfo on.

This technique has been as effective as standard "on-off" cw modulation for long distance work yet allows the klystron to be frequency stabilized at all times.

### conclusion

I have attempted to outline the standards for amateur microwave work used by the members of the San Bernardino Microwave Society. Using these techniques, communications have been accomplished over long, indirect paths over mountainous terrain. We've observed that a frequency change of one megahertz will result in a 20-dB change in signal strength over an indirect path. The ROCLOC system allows rapid changes in transmitter frequency with stable operation. (Any

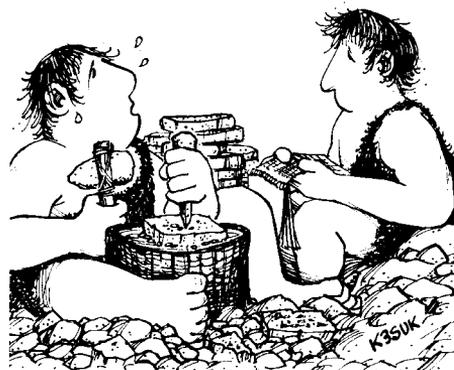
amateur system should have the capability of making frequency changes.)

In review, the standards used by the SBMS are:

operating frequencies	refer to table 1
intermediate frequency	30.0 MHz
polarization	linear, 45 degrees, transmit and receive
beam voltage	300 volts, $\pm 1\%$ , less than 10 mV ripple
fm, wide	$\pm 50$ kHz
fm, narrow	$\pm 1$ kHz
morse code	"pseudo cw" (fig. 3)
rf-tuning range	greater than $\pm 1$ MHz

If you are planning to move up to the microwave bands, I'm sure you will find these operating standards practical.

### ham radio



"I love to operate . . .  
but these QSL's are pure drudgery."



# solid-state modification of a mobile converter

An easy way  
to modernize  
a Gonset  
tube-type converter  
for mobile use



**I was thinking of installing** an old Gonset converter in my car, but the car's 12-volt system presented some problems. The converter tubes had 6-volt filaments, which would require a dropping resistor or heavy-duty zener. Also a power supply of +180 volts or more would have been necessary. Both these items would have represented considerable wasted power, more expense, installation problems, much more work, noise pickup problems, hash filtering, etc. Besides, I had a new all solid-state bc radio.

I felt that fet's and/or transistors would eliminate all these problems, and the small amount of filtered dc power required could be readily supplied by the bc set after it had been adequately filtered to eliminate input noise. Additional benefits would be instant warmup, no oscillator drift, no tube-pin noise from road shocks, and no worry over failure of tube filaments, element shorts, etc.

If mechanical redesign could be eliminated and electrical redesign limited to changing a few resistors and capacitors, the overall expense and effort would be drastically reduced even further. With this in mind, a most satisfactory modernization was achieved with equal or better performance than when the converter left the factory.

John R. Schuler, P. O. Box 37, Hanover, Maryland 21076

## construction

A most troublesome problem after removal of the tubes was finding a place to mount the transistors, since clearance was negligible between the tube socket connection ears and the bottom of the enclosing chassis. I finally decided to "spread-eagle" the short wires of the solid-state devices, use 1/4-inch pieces of spaghetti, then solder the wires directly to the socket ears where old and new com-

room on the back apron of the converter to install this switch.

Where values of components are not given on the schematic, the value is the same as originally furnished by Gonset. Of course, the filament wiring, screen-grid wiring, screen-grid bypass capacitors and dropping resistors may be cut out of the chassis; and good rid-dance. Note that the pilot lights were changed from 6-volt 47's to 12-volt types

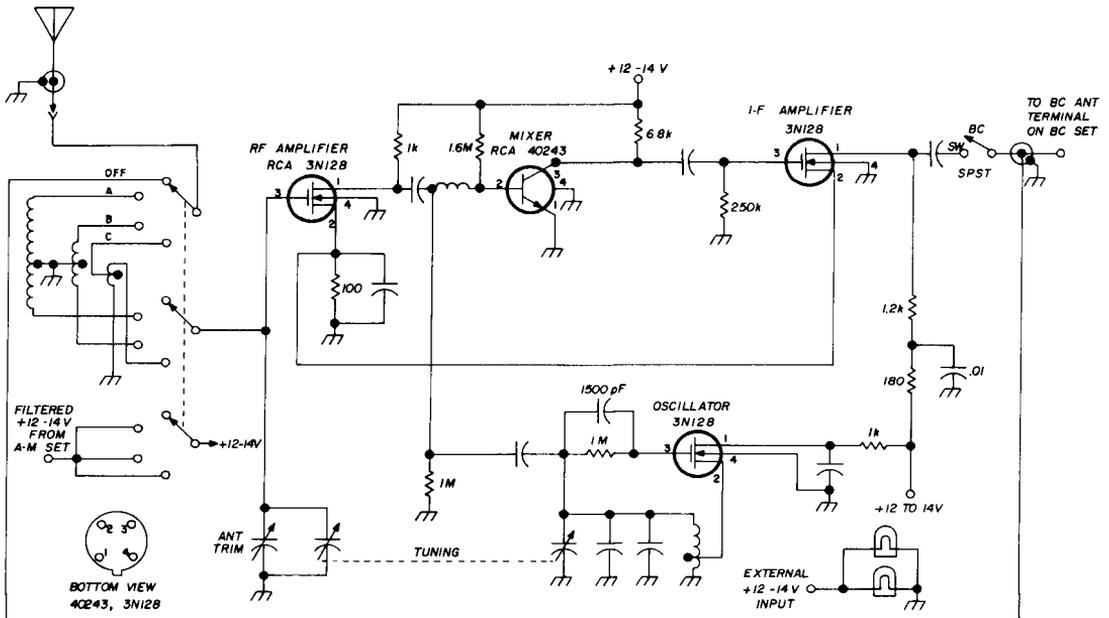


fig. 1. The solid-state Gonset converter. Mosfet's and an npn transistor eliminate tube problems of noise, drift and high power drain. Components without values are unchanged from the original converter.

ponents would also be convenient for connection. An all-fet converter was originally planned. However, the great improvement in conversion gain afforded by an npn transistor justified its use as the mixer.

The modifications are shown in fig. 1. I found it necessary to put in a slide switch to disconnect the antenna circuit from the output fet (during bc reception only), otherwise the loading effect was sufficient to ruin the Q and gain of the bc set. But this was the only mechanical change. There was plenty of

and disconnected from the line feeding the collector and drains. They may be separately fed from a battery clip and wire attached to the instrument panel light to lessen the IR drop from the bc set hash filter. In this way, when the bc set is turned off, the converter is "fail-safe" turned off too, irrespective of converter switch position. Wire from the on-off switch on the bc set should be shielded and fed to the shielded B+ line of the converter via phono pin and jack, or similar means, so each may be separated at will.

ham radio

# effect of mismatched transmitter loads

Does the character  
of the load  
affect  
power amplifier  
efficiency?

Assume, if you will, that a radio transmitter feeds a "lossless" transmission line terminated in a non-reactive load equal to the characteristic impedance of the line; the vswr will be unity, of course. Further assume that the transmitter runs 1000 watts input power and operates with an efficiency of 60%. A through-line wattmeter in the transmission line would then indicate 600 watts power output. For a final assumption, let's say that the plate of the vacuum tube in the final rf amplifier stage shows a faint trace of "color" under these operating conditions.

Now remove the non-reactive load and replace it with a complex load—partially-resistive and partially-reactive. Also, its total impedance is not equal to the characteristic impedance of the transmission line. This, of course, upsets the tuning of the transmitter; so quickly retune it to resonance and reload the final to draw 1000 watts dc input power.

## the question

Now the question: will the power amplifier plate show less, the same or more "color?"

This question will educe a lot of discussion among technical people—even a bit of argumentation. Opinion, even among well-qualified engineers, will be sharply divided. Most agree that a final solution can be reached only by setting up an experimental circuit and observing the results under carefully controlled conditions.

## the conditions

Pending such an empirical solution, however, there are several thought-provoking aspects that should be considered. First, let's

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tie down some conditions. Assume that the unloaded  $Q$  of the plate tank circuit is very high; that the tank circuit normally has a loaded  $Q$  of 12; that the inductor of the tank has low resistive losses; that a moderate change in the inductance of the tank inductor will produce no change in its total resistance; that the transmitter is operating on a relatively low frequency in the high-frequency range so that tank losses are mostly concentrated in the inductive leg of the tank; that the variable tuning element in the tank circuit is a variable inductor of the variometer type. Having assumed all this,

its resistance ( $Q = X/R$ ). This  $Q$ , in turn, determines the impedance into which the tube works. When the tank circuit is tuned to resonance it may be stated that

$$Z = \frac{X^2}{R} = XQ$$

Keep in mind that the capacitance of the tank circuit is fixed. Therefore, for a state of resonance ( $X_L = X_C$ ) at a given frequency, the effective value of inductance must be constant. This is important, for we shall be tuning the variometer to maintain a status of resonance. Now slip back a notch and con-

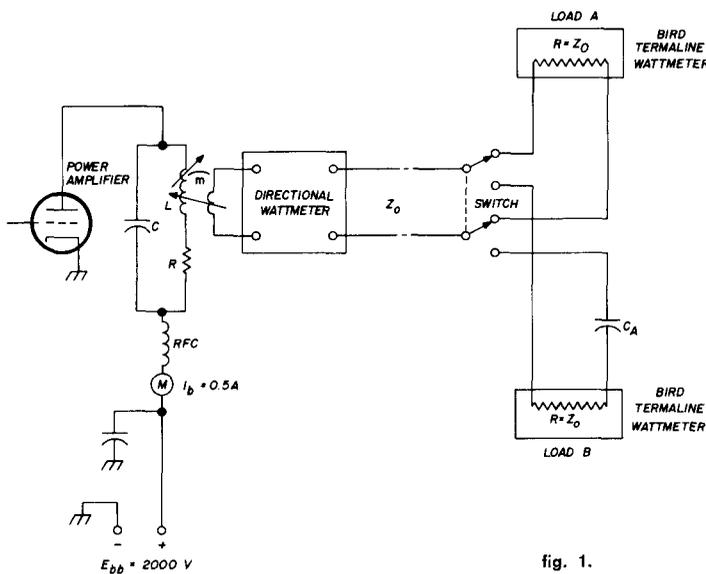


fig. 1.

we're ready to look at the schematic diagram in **fig. 1**.

You will recall that the question stipulated an over-all efficiency of 60% with a purely resistive load. The important factors determining the degree of operating efficiency are grid bias, rf excitation and the plate load. We shall assume that grid bias and rf excitation have been adjusted to optimum and will remain unchanged throughout the test. The third factor, plate load, is a variable depending upon the loaded  $Q$  of the plate tank circuit. Assuming the capacitor has negligible contributory loss, we can say that tank  $Q$  is equal to the inductor's reactance divided by

sider the matter of impedance. Look at the formula  $Z = X^2/R$ —if  $X_C$  is fixed and  $X_L$  must always equal  $X_C$ , it's evident that resistance is the only variable that can be manipulated to attain a desired value of impedance. We shall assume we have reached that desired value when the dc plate current has a value of 0.5 ampere with the tank circuit in resonance.

Since we stipulated that the unloaded  $Q$  of the tank circuit is high (same as saying that the inductor's resistance is low), the effective resistance of the tank must actually be predominantly made up of resistance reflected from the load through the mutual

coupling,  $m$ , that links the tank inductor to the transmission line pick-up coil.

## the experiment

Connect load A to the transmission line, fire up the transmitter, and adjust the plate variometer and the mutual coupling,  $m$ , so that when in resonance the dc plate current is 0.5 ampere. The directional wattmeter indicates 600 watts incident power and zero reflected; the meter on the Teraline® wattmeter used for load A also indicates 600 watts. The extent of the glow on the plate of the final amplifier tube is carefully observed and recorded. This concludes the first step.

For the second step, the transmission line is shifted from load A to load B. Load B consists of a Teraline® wattmeter in series with a capacitor. The total impedance of this load is expressed by:

$$Z = \sqrt{X_C^2 + R^2}$$

It is evident that the new load is not matched to the transmission line so there will be standing waves present on the line. To simplify matters, let's assume that the transmission line is a half-wave long (at the operating frequency). Then the capacitive reactance ( $X_C$ ) of the load will be present at the sending end of the line. It will be reflected into the inductive leg of the plate tank circuit as a value of  $X_L$ , causing the total  $X_L$  to be too great to maintain an equality with the fixed value of  $X_C$ . Therefore, the plate tank will not be in resonance. You quickly restore it to resonance by adjusting the variometer. Now total tank-circuit  $X_L$  is back to its original value.

Although the value of resistance in the load has not been changed, it is probable that  $m$  will have to be altered to maintain the tank  $R$  at a value that will permit a dc plate current of 0.5 ampere at resonance; make the necessary adjustment.

## the results

The tube now has a dc input power of 1000 watts. The directional wattmeter in the transmission line will now indicate something other than 600 watts incident power; also, it will show some reflected power. The question, though, is what has happened to

plate dissipation? The answer is short and sweet: nothing!

This is because the power generator, the tube, sees exactly the same load it saw when the transmission line was terminated with a resistive load equal to the characteristic impedance of the transmission line. This condition was established when the plate-tank variable inductor was returned to resonance and the coupling adjusted for the same dc plate current.

The plate tank circuit is the key to the situation. It performs three functions: it provides an optimum value of non-reactive load for the generator to work into, it provides frequency selection by offering this load only at the selected frequency, and it serves as a transforming device, transliterating random loads into the load that is optimum for the power generator. It is the third function that seems to be least understood.

Although a rather unusual type of tank circuit has been used in this illustration, other tank configurations work equally well and perform precisely the same service. The sending-end impedance can be (and usually is) almost anything but the 52 ohms resistive that the transmitter is designed to work into. The impedance may vary over the range from 15 to several hundred ohms—and it may be purely resistive, resistive plus inductive or resistive minus capacitive! This is what the tank circuit must cope with to perform its vital third function.

Fortunately, almost any properly designed tank circuit is capable of making this transformation. The limitations are mostly those that are built in by the designer's choice of components. There are two factors that have a lot to do with this choice: cost and ease of tuneup. The first is a matter of keeping the selling price low to compete in a highly competitive market. The other is to keep tuning procedures simple so the equipment won't be damaged during tuneup. If the tubes go out in a blinding flash or the tank circuit melts down into a sodden mess, either the designer cut too many corners or the operator lacked the skill to make the necessary corrective adjustments. Consider that before you cuss the designer!

**ham radio**

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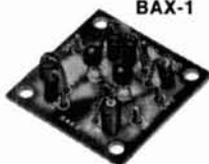
MXX-1



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BAX-1

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## putting a scope to work in ham gear

Here I am to continue with scopes. I told you last month how to fire up the scope and get displays locked into position on the screen. This month I'll give you some specific uses for it on the ham repair bench.

A scope, remember, lets you **see** the exact shape of an ac waveform. You can identify sine waves, square waves, tv sync pulses or any unusual waveshape. More than that, and often more important, you can measure peak-to-peak values of waveform voltages, whether they're nice round sine waves or crazy, misshapen oddballs.

### measurement methods vary

Probably the chief difference in various brands of service-type scopes lies in how you measure voltages with them. Yet, they're all fairly easy. There are three main ways. Each uses the scope's variable **vertical input** control, but in different ways. The **vertical input** switch is always a decade-type multiplier. And the marked graticule on the face of the scope is important to voltage measuring.

In one method, you first feed in a signal of known value and adjust the **vertical input** control to make the trace coincide with that voltage marking on the scope graticule. That

calibrates the input amplifier. You can thereafter read the voltage value more or less directly on the scope graticule.

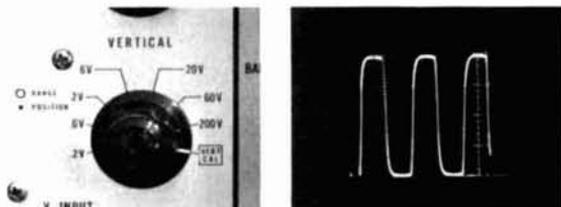
The second way of measuring peak-to-peak voltage is almost identical, except that the calibrating voltage is inside the scope. You just turn a switch to **calibrate**, and adjust the **vertical input** knob till the waveform display fits between two "calibrate" lines on the graticule. Then, you can read any signal-voltage value from where it fits on the graticule. The switch and the waveform are shown in **fig. 1**.

You've probably figured out that you can't mess with the **vertical input** knob once it's set. If the display is too small, you turn the input multiplier switch to a more sensitive position. If the display is too large (off-screen), switch to a less sensitive multiplier.

The third common method of measurement lets you read the voltage value directly from the **vertical input** knobs. **Fig. 2** illustrates the controls. You adjust the **vertical input** controls to make the waveform display exactly 2 inches high on the graticule (which is marked in inches). Then, you read the number pointed to by the variable knob and multiply it by the multiplier setting. That tells you the peak-to-peak voltage of the input waveform, no matter what its shape.

The waveforms that follow are photographed from a B&K model 1450 servicing scope. Its lighted graticule, shown in **fig. 3**, has two numbered scales: 0-2 and 0-6. The multiplier switch determines which scale

**fig. 1.** Before measurements, the vertical input amplifier must be calibrated to a standard voltage. Switching to vertical applies internal signal to deflection amplifier in this scope. Display is adjusted to fit the full-scale graticule mark.



lights up. The correct full-scale voltage is listed on each waveform photo so you can read peak-to-peak amplitude accurately. As you go along, reading voltages on a scope like this becomes second nature.

### tracing input power

A simple use for the scope, and a good one to practice with, is checking input ac voltage to a receiver or transmitter. It's the same thing you'd ordinarily do with your ac voltmeter.

The diagram in **fig. 4** shows the test points in a popular ssb transmitter. The photo below the input wiring shows the waveshape. Ac line voltage is a sine wave.

The 120 volts your voltmeter reads is a root-mean-square (rms) value, and the scope shows peak-to-peak (p-p) values. Line voltage is 335 volts peak-to-peak. The highest full-scale voltage reading on this scope is 200 volts, but its probe has a 10X switch on it. That attenuates any signal voltage by a factor of 10.

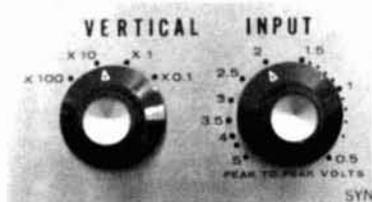
The multiplier switch for the photo in **fig. 4** is set at 60. A voltage of 600 will therefore reach all the way to the top of the 6 scale. The waveform you see goes about a subdivision and a half above the 3 mark.

The **sync** is set for **-int**, but it could just as easily be set for **line**; either would lock the line-voltage waveform in tightly.

The **sweep** control must be set for 10-50 Hz, and the **fine frequency** adjustment is turned so four cycles appear on the display. Adjust positioning controls so the bottom of the waveform is on the base line of the graticule.

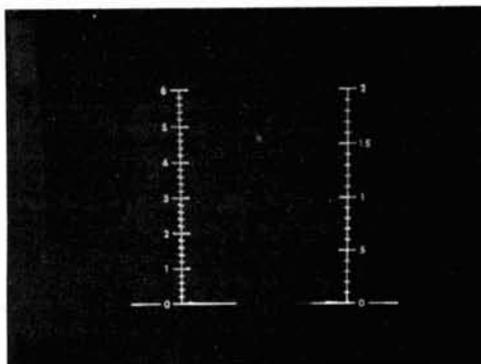
Use an isolation transformer between the

**fig. 2.** Waveform peak-to-peak amplitudes can be read directly from the knobs of this scope. The display is made exactly two inches high on the graticule by turning the knobs; then voltage is read.



plug of any chassis you're testing and the power line. Otherwise, you can blow fuses with a direct short between the scope ground lead and one side of the power line. (Not to mention the big chance of a nasty—even deadly—shock.)

Clip the ground lead of the scope to the ground side of the power cord. Then, move the test probe from point 1 to point 3 as shown. You should get the same waveform at every point. If you get a waveform when you probe the grounded end of the trans-



**fig. 3.** You read p-p voltages on scales with this scope, much like you do with a voltmeter. Either scale is used with decimal multiples chosen by the vertical input switch. Scales light one at a time.

former primary, however, it's a sign the ground is open. You can test the primary winding, too, by opening its ground connection and probing at the ground end; if you get a waveform, the primary is okay (**fig. 4** shows this test).

You can test the secondaries, too. Just probe points 4, 7, 9, 12, and 13. Remember that the **Vac** readings listed on a schematic are rms values. To know what p-p reading you should expect, multiply rms voltage by 2.8. Probing at point 10 also tests the doubler filter that couples ac voltage to the first rectifier.

### power-supply filter capacitors

A scope is a fine tool for testing power-supply filters. It lets you actually see how much ripple is left in the dc output of the supply.

Here's a good rule-of-thumb: Ripple should

not exceed 1% of the dc voltage across the filter, **with the equipment drawing full load.** Thus, in a 500-volt dc supply, output ripple under load should be no more than 5 volts. If it is, the filter capacitors aren't doing their job.

For a regulated supply, the ripple percentage should be even lower. The regulator circuit or its capacitors are faulty if the ripple at the output exceeds 0.1% of the dc value. Ripple voltages are always measured peak-to-peak.

The waveform photo in **fig. 5** is taken across the filter of a 400-volt dc power supply. The full scale is 20 volts, so the ripple waveform is 4 volts p-p. The scope **sweep** is set for 10–50, and **fine frequency** is set to display four cycles. **Sync** is -int.

### sine waves in amplifiers

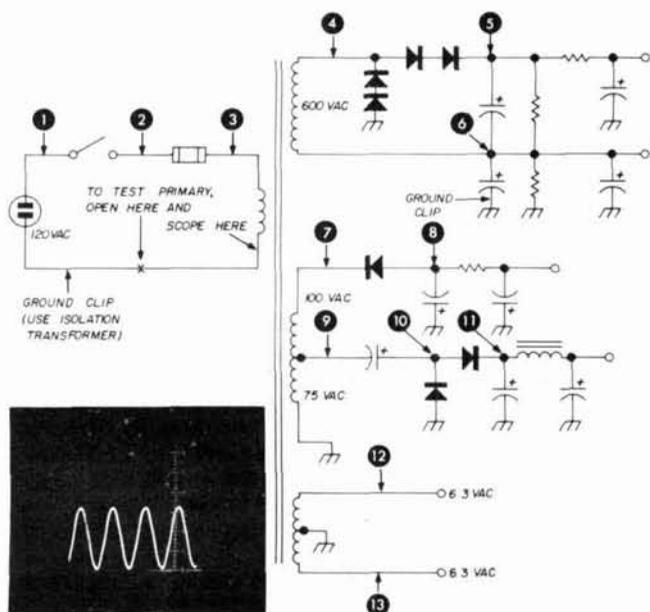
Here is where a scope begins to shine. It can show up distortion at the same time it's measuring gain in an amplifier. Suppose you suspect trouble in the speech amplifier section of a transmitter.

You feed about 50 mV of audio signal into the microphone input jack (**fig. 6**). Any frequency around 1000 Hz works fine. Then you move the scope probe from stage to stage, at inputs and outputs, all the way to the modulator. Each amplifier stage should multiply the signal voltage by at least 10 or 20.

A clipper, on the other hand, is supposed to prevent overmodulation. It limits how much audio signal reaches the modulator. You can check the clipper with a scope.

Connect the probe at the modulator grid or at the output of the clipper stage itself. Turn up the audio generator output, watching the scope as you do. When the audio signal gets strong enough to cause 100% modulation, the clipper starts acting. The sine wave begins flattening out as the second photo of **fig. 6** shows. From that point on, you should be able to turn the generator wide open without getting a higher waveform on the scope. The shape only gets flatter.

You can trace rf amplifiers with the scope, too. Just feed in a modulated rf signal, and use a demodulator probe with your scope.

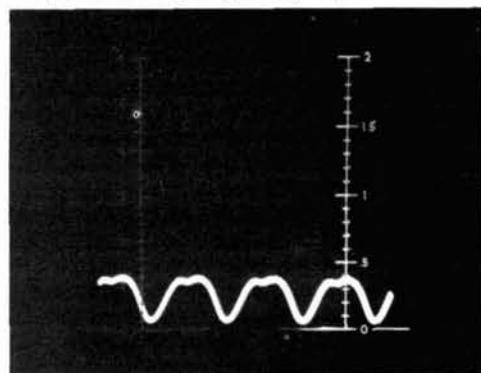


**fig. 4.** Power-supply test points. Waveform of input voltage. Full scale in this photo is 600 volts; peak-to-peak voltage therefore appears to be about 335 volts.

With amplitude-modulated signals, any circuit fault that cuts down the rf signal also cuts down the audio modulated on it.

You can even peak up receiver alignment with a scope fed by a demodulator probe. Just use the amplitude of the waveform on the scope as an indicator of peaking as you turn the adjustments. You can move the

**fig. 5.** Ripple voltage found in one fullwave power supply. Taken across input filter. Full scale of graticule is 20 volts; 4-volt p-p reading indicates filter capacitor is doing its job fairly well.



probe from stage to stage as you progress with tuning adjustments, or you can connect it following the last rf or i-f stage. If you go beyond an a-m detector, you don't need the demodulator probe. However, you can align the i-f and rf stages in an fm or ssb receiver using an a-m signal and the demodulator probe with a scope.

## ham television

In recent years, hams have found it logical to stick with the commercial tv standards. Thus, they can use standard receivers with modified tuners. Also, surplus and used transmitting equipment is more available.

For examining and measuring signal voltages in television stages, a scope is indispensable. The photos in **fig. 7** are the most common waveforms.

**Figs. 7A** and **7B** are photos of the signal voltage that contains both the video that makes the picture and the sync pulses that keep it steady. The scope probe is connected to the output of the tv set's video detector. Full scale of the graticule when these photos were taken was 6 volts p-p; the waveform is just under 5 volts p-p.

In **7A**, the scope sweep is set for about 5 kHz; that shows three cycles of the signal at the 15,750-Hz line rate. **Fig. 7B** is the same signal, but with the scope sweep set for about 20 Hz. That displays three cycles at the 60-Hz frame rate. Peak-to-peak voltage is the same, no matter what display rate is used.

From the vertical sweep section of the tv set, the signal voltage in **fig. 7C** is taken. It is

a trapezoid, displayed on the 600-volt scale. Its amplitude is 220 volts p-p. The scope sweep is set for 20 Hz.

**Fig. 7D** is also a trapezoid, this time taken in the horizontal sweep section of a television receiver. The scope is set to sweep at about 5 kHz, to display three cycles. The full-scale voltage range on the graticule is 200; the waveform is 120 volts p-p.

You'll discover that waveforms in any television receiver are viewed at either of just two scope-sweep rates. The 5-kHz sweep rate is for all waveforms that bear any relation to the horizontal line rate of the tv receiver. The 20-Hz sweep rate is for waveforms that relate to the vertical frame rate.

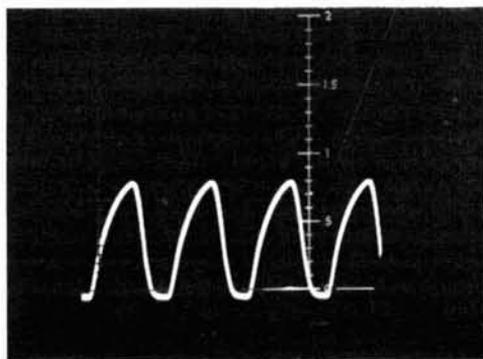
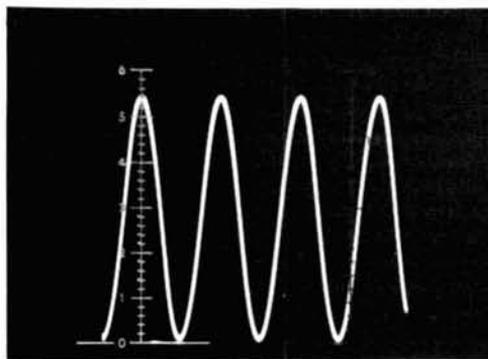
**Fig. 7E** is a special waveform found in the automatic frequency control circuit of the tv-set horizontal oscillator. The scope sweeps at the line rate. The graticule is at 200 volts full scale; the waveform is therefore 100 volts p-p in amplitude.

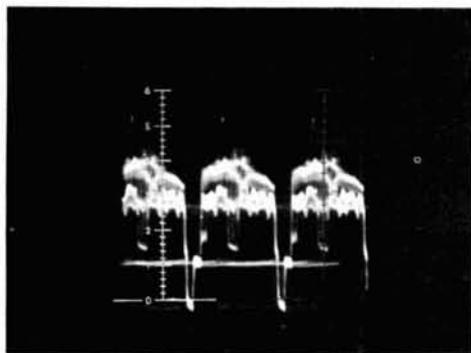
Another special circuit in TV receivers is the automatic gain control. In most modern sets, it is a keyed type. That is, a pulse is applied to it from the horizontal sweep transformer (called the flyback). The photo in **fig. 7F** is a sample of the keying signal voltage. The scope is set to display horizontal-rate signals. Peak-to-peak amplitude of the keying signal is 175 volts.

## next month

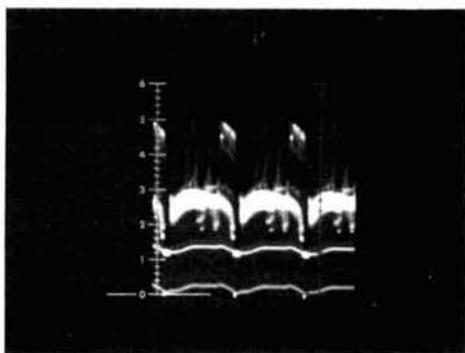
These last two installments have given you a sample of how you can use a scope on the ham repair bench. A little practice makes

**fig. 6.** Sine-wave audio signal gets flattened in clipper when too much signal is fed in. That's normal, because clipper should keep signal at modulator from exceeding voltage for 100 percent modulation.

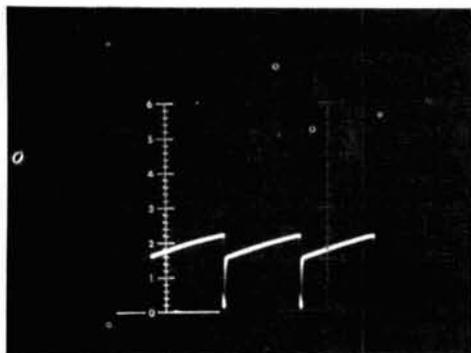




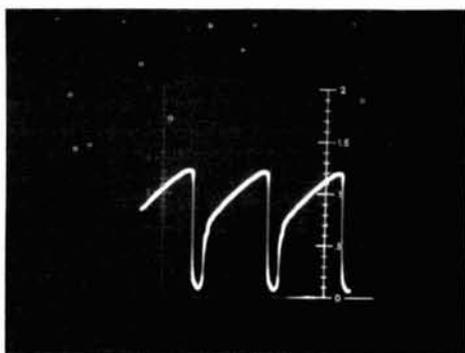
A. video waveform at line rate



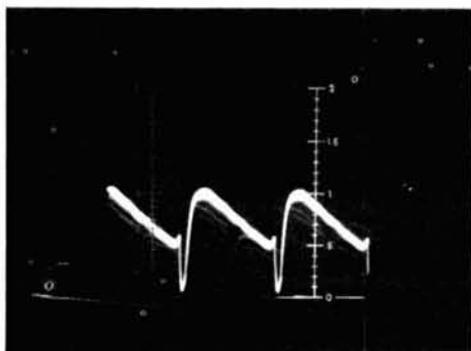
B. video waveform at frame rate



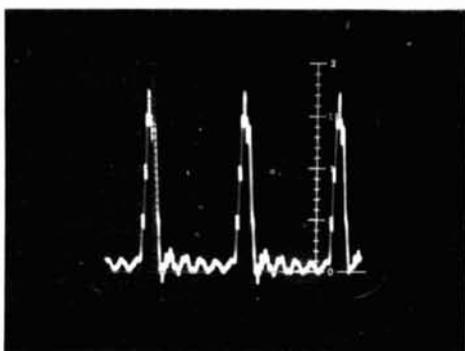
C. vertical oscillator waveform



D. horizontal drive signal



E. afc comparison signals



F. agc keying pulse

fig. 7. Typical waveforms from television receiver that can be used for amateur tv reception. Video waveform, displayed at line rate (A), video waveform, displayed at frame rate (B), vertical oscillator waveform, at frame rate (C), drive signal to horizontal output tube, displayed at line rate (D), waveform of comparison signals in afc stage, shown at line rate (E) and keying pulse for agc stage, at horizontal rate (F).

you as familiar with your scope as you are with your voltmeter. And you'll find the scope is far more versatile.

Next issue, I shift to a new topic: single-sideband. Tuning up an ssb transmitter has

some things in common with any other ham transmitter. But, there are important differences. Those are the subject of **repair bench** next month.

**ham radio**

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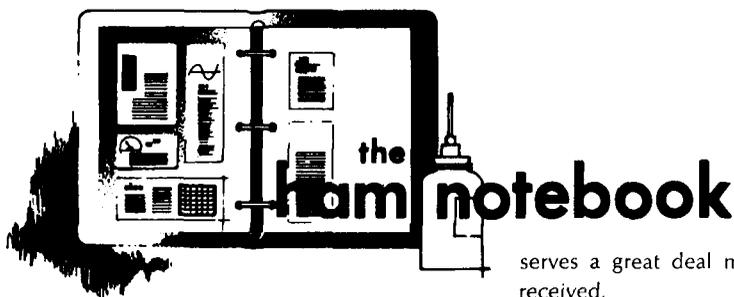
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## mono-loop antenna

Nothing new or startling is claimed for this antenna. However, like the open-wire-line fed flat top, the one-wavelength loop de-

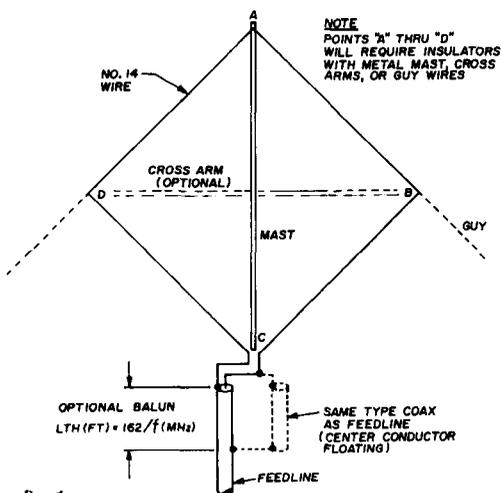


fig. 1.

f (MHz)	total length	length per side
14.0	71' 10"	17' 11½"
14.1	71' 4"	17' 10"
14.2	70' 9"	17' 8¾"
14.3	70' 3"	17' 6¾"
21.0	47' 10"	11' 11½"
21.1	47' 8"	11' 11"
21.2	47' 5"	11' 10¼"
21.3	47' 2"	11' 9½"
28.0	35' 10"	8' 11½"
28.5	35' 3"	8' 9¾"
29.0	34' 8"	8' 8"
29.5	34' 1"	8' 6½"

serves a great deal more attention than it's received.

Almost everyone using a quad parasitic array is pleased with the results. The quad has a good capture area, and for modest height above ground, a favorable low angle of radiation. A quad mono-loop has these same advantages, but with the disadvantage of being bidirectional.

My new location precluded a tower and rotary beam. As an alternative I erected thirty feet of tv mast on the chimney of the house; and from the top, some forty feet above ground, suspended a 20-meter quad loop (fig. 1)\*. Because of limitations in guying the sides at the proper height, the antenna looks like an ARRL diamond, but it works like a gem (pun intended)!

Reports broadside to the antenna are generally 6 to 12 dB higher than those received from a three-half-wave doublet (100 feet long, center fed; 40 feet high) favoring the same directions. In fact, except that the antenna is fixed, it performs just about as well as a two-element quad in a former location.

For a 20-meter loop, I suggest starting with sides 17 feet 10 inches long and trimming to optimize the swr. In my case, the regular formula length  $250/f_{MHz} =$  side in feet resulted in a resonant frequency higher than desired; probably because the sides are elongated into a diamond shape.

Hams having towers high enough to accommodate a 40-meter loop might find it would outperform a conventional inverted-V doublet, even though the bottom current loop is close to the ground.

**James A. Gundry, W8BW**

\* Editor's note: Suggestions for crossarm braces and a balun are included. The balun is recommended for optimum efficiency.

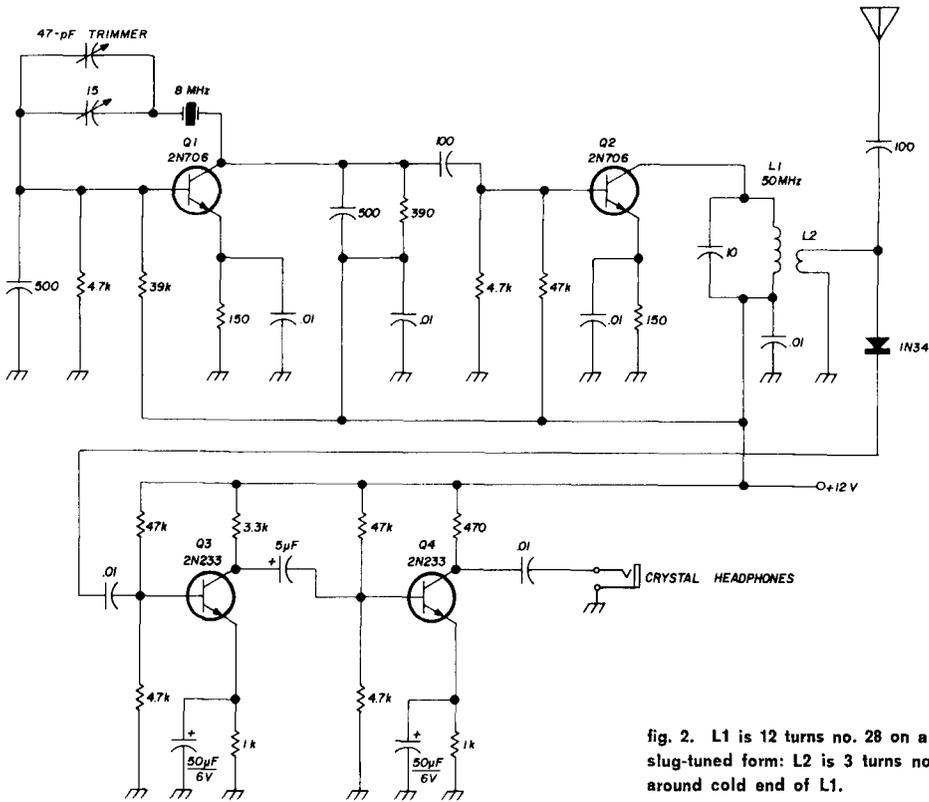


fig. 2. L1 is 12 turns no. 28 on a 1/4" slug-tuned form; L2 is 3 turns no. 28 around cold end of L1.

## crystal-controlled frequency meter

For the past couple of years amateur radio magazines have been running articles about sophisticated frequency measuring devices, mostly using integrated circuits and other solid-state components. The crystal-controlled frequency meter shown here is as simple as can be constructed and is based on the old method of zero beating one frequency against another.

The oscillator in **fig. 2** is an untuned crystal-controlled oscillator. The crystal frequency can be "pulled" from 2 to 4 kHz, depending on the crystal. I use an 8 MHz crystal and multiply it to 50 MHz; the 50 MHz signal is rectified and fed to an audio amplifier. With this carrier turned on, every time another carrier of the same frequency is fed to the amplifier a zero beat is heard. It even radiates enough to check receiver frequency.

The stability of the oscillator was checked with a digital frequency counter and only  $\pm 10$  Hz drift was observed at 8 MHz during a two-hour period. The frequency meter uses

a 12 volt battery supply; current drain is 8 mA—due chiefly to the low-level of amplifier used in the circuit.

Construction is not critical. It can be hand wired or everything can be put on printed circuit boards; I prefer printed circuit boards because it is quicker as well as compact and neat. Transistors are the four-for-\$1 type and crystals were 50¢ each. The transistors in the amplifier should be npn germanium with a beta of at least 90; the 2N233 or 2N170 will do the job fine.

Crystals from 5 to 13 MHz will work in the oscillator. Adjust the 47-pF trimmer to zero a certain frequency with the proper crystal; make sure the 15-pF capacitor is half open. You should be able to deviate the crystal frequency  $\pm 1.5$  kHz. To set a transmitter vfo, set the 15-pF capacitor to the desired frequency, plug in a crystal headphone, load the transmitter into a dummy load and vary transmitter vfo to zero beat.

John J. Sury, W5JSN

# HERE IT IS!

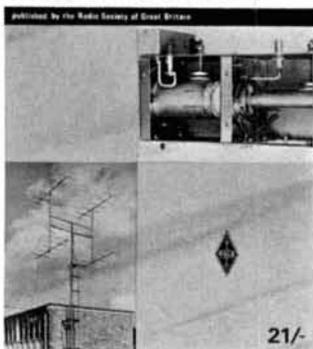
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## simple microphone stand

A microphone is usually easy and inexpensive to obtain, but getting a microphone stand is something else again. The few commercially available stands are rather expensive, often costing as much or more than the mike they support. So after looking for

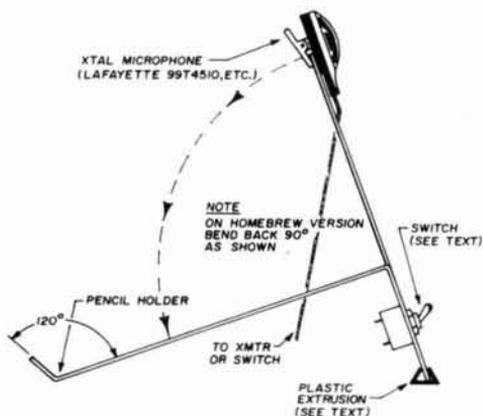


fig. 3. Simple microphone stand.

an easy method of building a stand, I got the idea of using a common, stamped steel bookend turned on its side.

The microphone is attached to the flap of the bookend. The inexpensive, Japanese crystal mikes can be clipped directly to the flap, as they are sold with a built-in clip. Other microphones will require other means of mounting. Epoxy glue should be used if a permanent microphone and stand combination is desired.

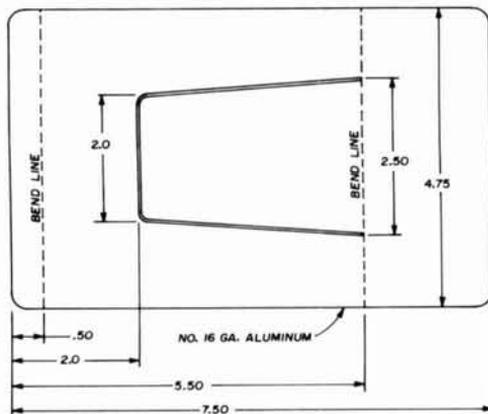
A switch may also be installed on the stand at any convenient location. Details will depend on the type of switching desired (i.e., push-to-talk, etc.).

To prevent marring the surface of your operating desk, attach a rubber or plastic moulding to the bottom of the stand. A good item for this is a piece of the triangular, extruded plastic strips sold for pennies at a stationery store. This material is used for binding loose pages into a report or cata-

\* My bookend was purchased in a book store and is made by the W. T. Rogers Company in Madison, Wisconsin.

logue. You may even want to attach a small calendar to the extrusion.

The rear end of the stand can be grooved by bending the steel as shown. This provides a handy place for pen or pencil and prevents scratches as well.



Though a bookend of the type shown\* can be bought completely finished and painted for about fifty cents, for those who prefer to make one out of aluminum or steel sheet, a suggested layout is given in fig. 3.

D. E. Hausman, VE3BUE

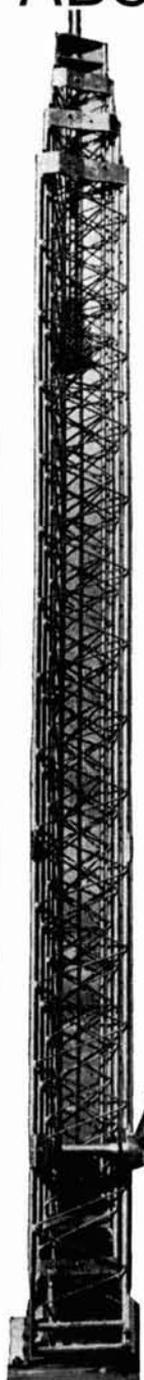
## uhf tuner tester for tv sets

Most amateurs have tv sets, so I thought this idea would appeal to **ham radio** readers. It's an adaptation of a miniature solid-state GE tuner for use as a piece of test equipment. With this tester, you can check the uhf front end of your tv set without a signal generator.

A number of surplus-type uhf tuners are available that will work nicely as signal generators. I purchased mine for \$5.20 postpaid from Arcturus Electronics.\*

\* GE transistorized tuner, catalogue number GE 85 Arcturus Electronics, 502 22nd Street, Dept. HR, Union City, New Jersey 07087.

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Remove the tuner from its cover by unhooking the securing wire. Note the junction of two resistors feeding the stator of the oscillator section of the tuning capacitor. Attach a one-half-inch piece of insulated wire to this junction. Drill a hole in the cover to accommodate the wire when the cover is replaced. Leave about one-eighth inch of bare wire at the other end. Replace the cover.

Connect a half-watt, 330-ohm resistor to the insulated stud. (This is the spot where the tuner instructions say to install the 15 kilohm resistor furnished.) Attach a few inches of wire to the other end of the resistor. Tape wire and resistor to the tuner case. Install the mounting bracket and nut according to tuner instructions, as well as the fine and coarse tuning knobs. Connect a 6-volt battery charger (must be unfiltered), with negative lead to the case and positive lead to the wire connected to the 330-ohm resistor.

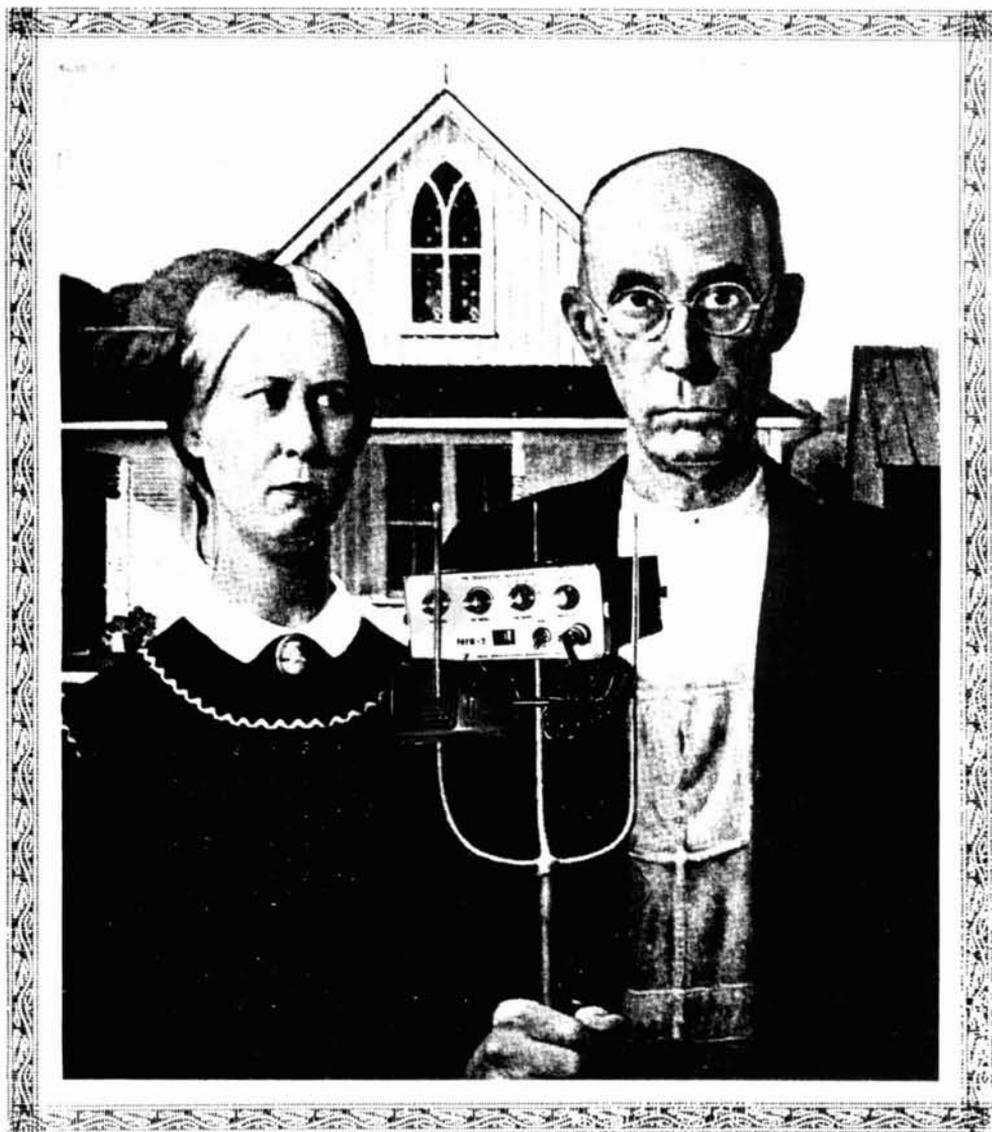
Tune the tv set to a known uhf channel. Adjust the tuner slightly so the picture just disappears. Run a jumper from the wire emerging from the oscillator section of the tester to the uhf antenna terminals of the tv set. Apply power to the tuner, and tune until two black and two white bars appear on the tv screen. (This assumes a full wave charger or rectifier circuit.) Set the tester dial to read the same as the uhf dial on the tv set minus the offset to make the picture disappear.

This completes the tune-up and tester calibration. Other modulated 6-12 volt sources may be used, providing the transistor in the tester isn't overdriven.

**John R. Schuler**

## transistors for vhf transmitters

Amplitude modulation, although popular with hams on the vhf bands, is not popular with transistors. If you really want to know how to get high quality a-m, get copies of the RCA 40290/40292 transistor data sheets. If a particular rf power transistor is not rated for a-m use, then, "10 watts out," means 2 or 3 watts of carrier power and 10 watts on a-m peaks. For a-m operation with a 12-volt power



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supply use a 28-volt transistor and modulate the last two or three stages.

For single sideband, a 10-watt rf power transistor runs 10 watts PEP—not very attractive. Since transistors heat up in thousandths of a second, they don't "average" very well. Also, there's no such thing as ICAS ratings for rf power transistors.

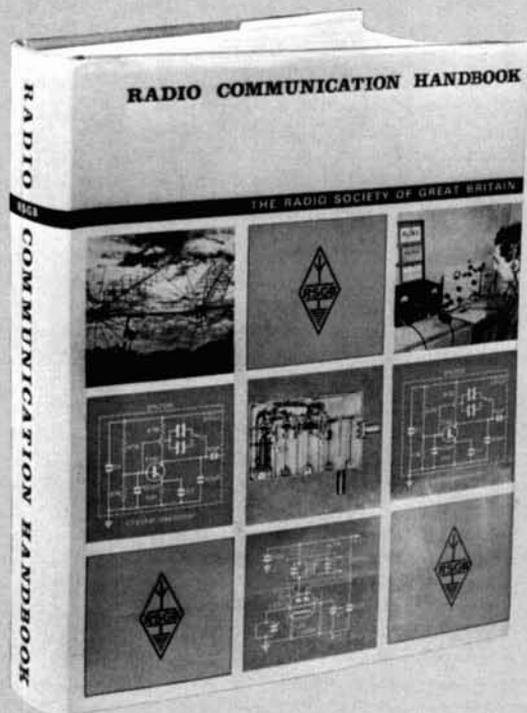
Type	Power Output (Watts)				Comment	Price
	6M	2M	220	432		
40405	0.5	0.4	0.4		12-V doubler or amplifier	\$ 1.65
2N3866	1.6	1.5	1.3	1.0	28-V driver but good with 12-V supplies	2.97
2N4073	1.0	0.6	0.3		12-V driver	2.70
40290	2.0*	2.0*			rated for 12-V a-m	2.48
40292	6.0*	6.0*	4.0		insulated collector; rated for 12-V a-m	10.45
2N2631	7.5				up to 40-V, poor with 12-V supplies	3.47
2N3553	8	5	3		TO-39 case	4.37
2N3375	10	8	6	2.0	insulated collector	10.80
2N2632	15	13	10		insulated collector	12.75
2N3733	20	20	15	8	insulated collector	15.80
2N5016		25	20			43.50

\* amplitude modulated

For fm or CW exciters, rf power transistors perform well. However, if the last stage is driven hard, it will require some sort of protection from mismatched loads—either a directional-coupler scheme or an isolator. High power rf amplifiers that are used to drive varactor frequency multipliers are especially likely to have mismatch problems.

The power gains of the transistors listed in table 1 are comparable to commonly used vacuum tubes; net efficiencies, including circuit losses, are often greater than 70%. Those listed are ones I consider best buys in terms of results.

Hank Cross, W1OOP



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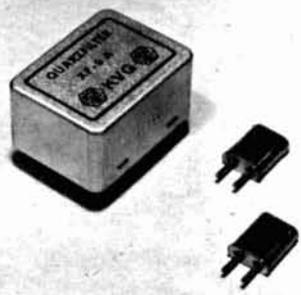
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See page 80

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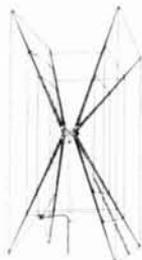
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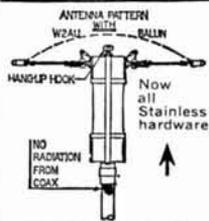
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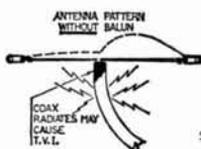


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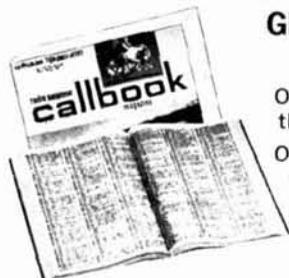
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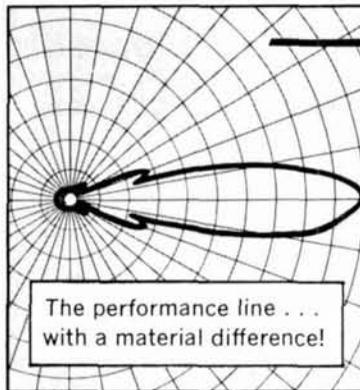
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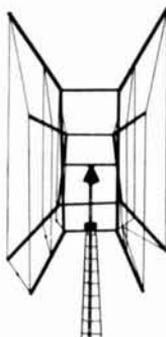
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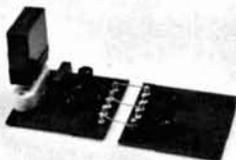


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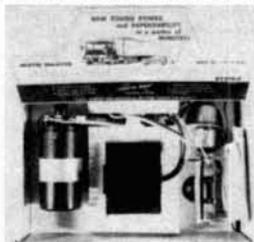
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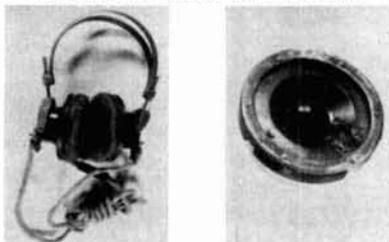
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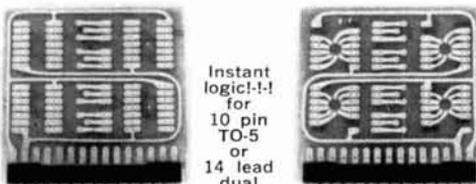
The Canadian Air Force has surplus also and we were fortunate to obtain over 500 headsets from them and are passing the savings on to you. They are unused and in the original cartons. The headphone elements are actually miniature speakers, as pictured, and this is the way Hi-Fi phones are constructed. Will give excellent fidelity with either voice or music. They have rubber pads with chamois-type covering, metal headband, cord and plug. 4 to 16 ohm impedance for use with any radio or TV, etc., by attaching to the speaker leads. May be converted to "stereo" by making connections at each ear phone. This is a real bargain for quality RCAF head sets. **RCAF HP .....\$3.00 p.p.**

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### UNIVERSAL LOGIC CIRCUIT CARDS



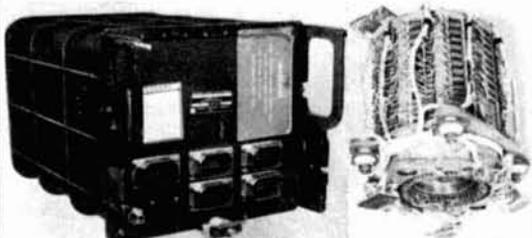
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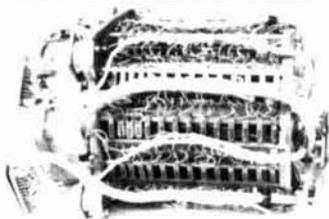


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