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colleges, ORDERS.	Goods A quic	Dept e k call v	etc we	lcome eck sto	d. WE	SPECI	ALISE I	N CR	EDIT C	ARD	PHONE s subje	ect	U	1		U			VU		
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PRICES S	UBJE(GE		/ISA	Acces		£3.			\leq				01	-4	52 (0161	/01-4	50 0	995	5 Tlx:9	14977
RESISTORS	ELECTRO	LYTICS	7470 7472 7472	55p 49p	74LS124 74LS125	1 35p 59p	4047 4048 4049	75p 54p 45p	Z80ADAR1 Z80APIO ZN425E8	8.39p 3.45p 3.49p	2N6253 2N6254	1.63p 1.77p	BD138 BD139 BD140	39p 42p 47p	MPSL01 MPSL51 MPS405	69p 75p 89p	SCR's TRIACS	R5U G5U Y5U	42p 47p 47p	TDA2611A 2.50p TDA7000 3.45p TL061 51p	WIRE
5% HI STAB LOW NOISE	Matsu (Panaso Siem	shita nic) & ens	7474 7475 7476	55p 69p 49p	74LS120 74LS132 74LS133 74LS136	69p 59p	4050 4051 4052	49p 75p 75p	2N426E8 2N427E8 ZN428E8	3 10p 5.99p 4.55p	3N201 40361 40362	1.99p 75p 75p	BD239A BD239C BD240A	65p 69p 68p	MPSU06 MPSU07 MPSU51	99p 1.75p 1.29p	DIACS	Rectang	ular LEDs	TL062 77p TL064 1.50p TL071 47p	PRICES PER METRE Solid connecting
10 MΩ 1/4W E24 2p 1/2W E24 3p	weach uFd V	and)	7480 7481 7482	69p 1.39p 99p	74LS138 74LS139 74LS145	75p 75p 1.50p	4053 4054 4056	75p 85p 99p	VBE	GS	40363 40406 40408	3.99p 1.75p 1.75p	BD240C BD241A BD241C	79p 72p 79p	MPSU56 MPSU57 TIP29A	1.22p 1.95p 35p	THYRISTO 4 8 & 12 Amps Texas T0220	RS R5R G5R Y5R	19p 20p 22p	TL072 620 TL074 1.500 TL081 470	Wire MAINS/SPEAKER Twin 1 Amp 14p
1W E12 6p 2W E12 12p METAL FILM	.47 10 .47 35 1 6	0 9p 0 30p 3 8p	7483 7484 7485	1.19p 1.32p 1.44p	74LS147 74LS148 74LS151	1.95p 1.65p 1.09p	4059 4060 4063	4.49p 88p 89p	- Positi 100m	ve – nA	40410 40411 40673	1.99p 3.99p 1.49p	BD242A BD242C BD243A	75p 79p 85p	TIP29C TIP30A TIP30C	42p 37p 44p	$\begin{array}{l} \text{Suffix A} = 100\text{V}\\ \text{B} = 200\text{V}\\ \text{C} = 300\text{V} \end{array}$			TL082 550 TL084 1.200 UAA170 2.490	16p 3 Core 2 ¹ /2 Amp
ULTRA STABLE 0.4W EXTRA LOW NOISE	1 10 1 50 2.2 25	0 9p 0 40p 8p	7486 7489 7490	72p 2.25p 1.39p	74LS153 74LS154 74LS157	1.09p 3.49p 59p	4066 4067 4068	44p 2.79p 31p	78L05A 78L12A 78L15A	29p 29p 29p	40822 AC125 AC126	1.99p 99p 35p	BD243C BD244A BD244C	89p 88p 1.15p	TIP31A TIP31C TIP32A	39p 47p 46p	D = 400V M = 600V 4A	LIN I	99p	ULN2003 75p UPC575C2 2.00p UPC1156 2.75p	3 Core 13 Amp 66p SCREENED
1012 TO 1M12 1% E24 6p LOW OHMIC	2.2 63 2.2 10 2.2 35	9p 0 11p 0 30p	7491 7492 7493 7494	49p 69p 69p	74LS158 74LS160 74LS161 74LS161	49p 69p 69p	4009 4070 4071 4072	31p 31p 31p	1 Amp T	0202 (150	AC127 AC128 AC141K	35p 39p 39p	BD245C BD246A BD246C	1.19p 1.49p 1.39p	TIP33A TIP33C TIP34A	69p 83p	TIC106A 4 TIC106B 5 TIC106C 5	^{9p} AY38910 1p AY38912 3p CA3048	3.99p 4.95p 2.15p	UPC1156H 2.75p UPC1182 3.75p UPC1185 1.95p	Single 14p Stereo 27p Mini Single 12p
0.2212 to 8.212 E24 11p	3.3 2 3.3 4 3.3 6	5 10p 0 11p 3 12p	7495 7496 7497	89p 1.09p 2.29p	74LS163 74LS164 74LS165	85p 1.07p 1.29p	4073 4075 4076	31p 31p 85p	7812T 7815T 7824T	45p 45p 45p	AC151 AC152 AC153	77p 77p 77p 77p	BD249A BD249C BD250A	2.30p 2.57p 2.48p	TIP34C TIP35A TIP35C	1,26p 1.26p 1.39p	TIC106M 7 8A TIC116A 6	2p CA3059 CA3090AO CA3130E	3.29p 3.70p 87p	UPC2002 2.95 XR2206 3.95 ZN409 2.25	Mini Stereo 15p 4 Core 4 screens 44p
ON CERAMIC E12 SERIES 2 to 3W 0.2212	4.7 2: 4.7 4: 4.7 6:	5 9p 5 11p	74100 74104 74105	1.69p pls Ask pls Ask	74LS168 74LS169 74LS170	1.25p 1.39p 2.09p	4077 4078 4081	31p 31p 31p	- Negat 100mA	tive - TO92	AC153K AC176 AC176K	87p 39p 49p	BD250C BD529 BD530	2.75p 1.75p 1.95p	TIP36A TIP36C TIP41A	1.42p 1.49p 52p	TIC116B 7 TIC116C 7 TIC116D 7	2p CA3130T 5p CA3140E CA3140T 8p	2.35p 54p 1.40p	ZN414 1.00p ZN1034 1.99p	4 Core single screen 54p 8 Core 61p 12 Core 60p
to 33012 28p 4 to 7W 0.4712 to 6K8 33p	4_7 100 10 21 10 40	14p 5 8p 12p	74107 74109 74110	,49p 75p 1.59p	74LS173 74LS174 74LS175	1.10p 99p 72p	4085 4086 4089	59p 69p 1.25p	79L05 79L12 79L15	49p 49p 49p	AC 187 AC 188 AC 187K	39p 39p 49p	BD535 BD536 BD537	89p 89p 97p	TIP41C TIP42A TIP42C	58p 62p 65p	TIC116M 8 12A TIC126A 7	4p HA1366W HA1388 4p ICL7106 4p ICL7107	2.40p 2.54p 7.50p 9.50p	TRANS-	Heavy Duty Mike/Guitar
9 to 11W 10 to 33K 37p	10 6 10 10 10 35	3 14p 0 16p 0 55p	74116 74118 74119	1.63p 99p 1.59p	74LS181 74LS183 74LS190	1.09p 2.45p 1.09p	4093 4094 4095	65p 99p 89p	1 Amp 1 7905T	Г0220 57р	AC188K BC107 BC107A	49p 16p 17p	8D538 8D539 8D539C	97p 1.08p 1.33p	TIP49 TIP50 TIP53, TIP54	1.29p 1.52p 1.58p	TIC126B 7 TIC126C 7 TIC126D 7	5p 6p 1CL7611 9p 1CL8038 9p 1CM7555	97p 2.99p 1.10p	Post	AERIAL 50Ω RG58A 25p 75Ω UHF 29p
PRESETS	22 2 22 1 22 6	5 11p 0 14p 3 16p	74120 74121 74122 74123	55p 69p	74LS192 74LS193 74LS193	99p 1.09p	4098 4099 40103	99p 1.09p 2.59p	79121 7915T 7924T	57p 57p 57p	BC107B BC108A BC108A	16p 17p	BD540C BDX66B BDX67B	1.39p 6.35p 6.35p	TIP110 TIP112 TIP115	79p 85p 89p	TRIACS	^{9p} ICM7556 LC7120 LC7130	1.49p 3.20p 3.40p	prices cheaper 10 callers.	75Ω VHF 28p 300Ω Flat 14p RAINBOW
ROTARY POTS LOW NOISE 1/4" SPINDLES	22 10 47 2 47 4	5 14p 5 17p 3 26p	74125 74126 74128	59p 59p 1.59p	74LS195 74LS196 74LS197	79p 1,10p 1,10p	4502 4503 4505	59p 59p 3.75p	TRA	NS-	BC108C BC109 BC109B	20p 17p 18p	BDY54 BDY55 BDY56	2.28p 2.39p 1.99p	TIP117 TIP120 TIP122	1.05p 79p 85p	TO220 Case TIC206D(4A) 6 TIC225D(6A) 7	LC7137 LF347 9p LF351	3.95p 1.50p 59p	All 240V Primary Split Bobbin 100mA	RIBBON Prices per foot 10 way 25p
4K7 to 2M LIN 4K7 to 2M LOG	47 10 100 1 100 2	5 28p 5 14p 5 16p	74132 74136 74141	1.32p 49p 1.05p	74LS221 74LS240 74LS241	99p 1.39p 1.39p	4507 4508 4510	45p 1.49p 69p	ISTO 2N2219	RS 33p	BC109C BC140 BC141	21p 38p 43p	BDY57 BDY58 BF194	5.91p 6.33p 18p	TIP127 TIP130 TIP132	99p 1.06p 1.09p	TIC226D(8A) 9 TIC236D(12A) 1.2	2p LF353 LF355 5p LF356	1.05p 83p 99p	6-0-6 1.50 9-0-9 1.70 72-0-12 1.85	p 16 way 39p p 20 way 48p p 24 way 62p 30 way 75p
44p As above with DP Mains Switch	100 4 100 6 100 10	0 22p 3 25p 0 30p	74142 74143 74144	2.34p 2.79p 2.79p	74LS242 74LS243 74LS244	1.39p 1.39p 1.99p	4511 4512 4514	69p 69p 1.25p	2N2219A 2N2220 2N2221A	36p 33p 33p	BC147 BC147A BC147B	15p 16p 17p	BF195 BF196 BF197	18p 18p 18p	TIP135 TIP137 TIP140	1.16p 1.19p 1.21p	TIC246D(16A) 1.3 TIC253D(20A)	5p LF398 LM335Z LM348N	4.62p 1.60p 62p	1A as above 3.75	34 way 82p 40 way 88p 64 way 1.49p
99p As above stereo 1.30p	220 1 220 1 220 2	0 16p 6 17p 5 22p	74145 74147 74148	1.69p 1.39p	74LS245 74LS247 74LS248	1.15p 1.15p	4516 4518 4519	89p 69p 75p	2N2222 2N2222A 2N2223	29p 33p 5.85p	BC147C BC148 BC148A	27p 15p 17p	BF198 BF199 BF200 BF244A	18p 18p 79µ	TIP142 TIP145 TIP147 TIP162	1.21p 1.22p 4.99p	1.9 TIC263D(25A) 2.2	^{9p} LM349N 5p LM350K LM379S	1.09p 4.89p 5.50p	0.125A. 3.75 12.0 12V 50VA 7.95	RECHARGE
PRE-SETS PIHER (DUSTPROOF) E3 100Ω to 10MΩ	220 4 220 6 220 10	0 25p 3 30p 0 40p	74150 74151 74153 74154	79p 79p 3.49p	74LS251 74LS253 74LS253	79p 79p 79p	4520 4521 4522	75p 1.05p 89p	2N2223A 2N2368 2N2369 2N2369	6.25p 33p 34p	BC1486 BC148C BC149 BC149B	25p 16p 190	RF244B BF245A BF245B	55p 63p 66o	TIP2955 TIP3055 TIS43	81p 79p 61p	DIACS BR100 2	9p LM380N14	pis ask pis ask	12.0 12V 100VA 11.99 0 + 6 + 6 + 9 + 5	P Top quality
Mini Vert 16p Mini Horiz 16p Standard Vert	470 1 470 2 470 4 470 6	5 28p 0 33p 3 43p	74155 74156 74157	79p 49p 99p	74LS258 74LS259 74LS261	79p 1.59p 1.39p	4526 4527 4528	89p 89p 75p	2N2904A 2N2905 2N2905A	35p 35p 35p 38p	BC149C BC157 BC157A	26p 39p 41p	BF246 BF246A BF246B	77p 79p 79p	VN10KM VN46AF VN66AF	1.15p 1.09p	ZENER'S	LM381AN LM381N LM382N	2.26p 1.40p 1.22p	1.25A 5.65	these batteries away - they charge up to
Standard Horiz 19p CERMET 20	470 10 1000 1 1000 2	0 60p 6 30p 5 38p	74159 74160 74161	1.95p 1.35p 69p	74LS266 74LS273 74LS275	41p •1.80p 1.79p	4529 4532 4534	89p 89p 3.95p	2N2906 2N2907 2N2907A	35p 35p 38p	BC157B BC158A BC158B	44p 37p 39p	BF247A BF247B BF254	79p 79p 66p	ZTX107 ZTX108 ZTX109 ZTX200	12p 13p 14p	many inc	LM384N LM386N	1.40p 1.20p	0.1" COPPER	1000 timesl HP2(1.2AH) 2.39p
TURN PRECISION PRESETS	1000 4 1000 6 2000 1	0 46p 3 65p 6 40p	74162 74163 74164 74165	1.09p 1.09p 99p	74LS280 74LS280 74LS283	1.95p 95p	4538 4543 4553	2.29p 89p 99p 2.19p	2N2926 2N3053 2N3054	13p 35p 65p	BC159 BC159A BC159B	44p 45p 46p	BF255 BF256A BF256B BF256C	59p 59p	ZTX300 ZTX301 ZTX302 ZTX303	16p 17p 25p	CAT 400 to 500mV 624 Series	LM391N60 LM391N80 LM723CH	2.25p 1.65p 99p	TRACKS 2.5 × 3 75 95 2.5 × 5 1.08	HP2(4AH) 4.75p HP7(3AH) 99p HP11(1.2AH)
3/4" E3 SERIES 50µ to 500K 95p	2200 2 2200 4 2200 6 4700 1	5 53p 0 70p 3 1.34p 6 75p	74166 74170 74172	1.68p pls Ask 4.30p	74LS293 74LS295 74LS298	85p 1.25p 1.25p	4555 4556 4560	58p 58p 1.79p	2N3055H 2N3439 2N3440	1.89p 1.15p 99p	BC160 BC161 BC167	55p 59p 19p	8F257 8F258 8F259	39p 41p 45p	ZTX304 ZTX310 ZTX311	18p 39p 36p	2.4 to 47V	7p LM723CN LM725CH LM725CN	49p 3.40p 3.19p	3.75 × 5 1.23 2.5 × 17 3.27 3.75 × 17 4.29	PP3(110mAH) 4.95p Chargers
CAPS CERAMIC 100V DISC (PLATE)	4700 2 RADIAL	5 89p S (PCB	74173 74175 74176	1.35p 99p 1.05p	74LS299 74LS323 74LS324	2.20p 2.60p 1.50p	4566 4569 4584	1.99p 1.99p 49p	2N3441 2N3442 2N3638	1.49p 1.59p 62p	BC169 BC169B BC169C	19p 22p 23p	BF457 BF458 BF459	48p 59p 65p	ZTX312 ZTX313 ZTX314 ZTX314	39p 41p 27p 37p	E24 Series 3.3 to 82V	4p LM741CH LM741CN LM741CN	96p 19p 4 80p	4.79 x 17 5.99 VO Board 2.10 DIP Board 3.95	p TYPE H: p Adjusted to 6 of p any HP type
E12 MICRO MINI TYPICALLY ±5%	Wires of Matsush uFd V	he end) Ita only	74177 74178 74180 74181	1.25p 1.25p 3.19p	74LS325 74LS326 74LS327 74LS327	2.70p 2.70p 1.29p	LOG	IC	2N3702 2N3703 2N3704	16p 16p 16p	BC177 BC177A BC177B BC177B	29p 33p 36p	BFR40 BFR41 BFR79	pis ask pis ask pis ask	ZTX330 ZTX341 ZTX450	39p 31p 41p	BRIDGE	LM748CH LM748CN LM1871	1.00p 42p 3.25p	Track Cutter 1.63 Pin insertor	Above 15.59p TYPE M: As above but
1pF to 10nF 7p POLYCARB 5% SIEMENS 7.5mm	22 1 22 1 47 1	0 6p 6 7p 0 7p	74182 74184 74185	1.15p 1.59p 1.59p	74LS348 74LS352 74LS353	1 49p 1,25p 1.25p	CPU 1802 6502	s 6.49p 3.99p	2N3706 2N3707 2N3708	16p 16p 16p	BC178A BC178B BC179	33p 36p 31p	BFR80 BFR81 BFR90	pls ask pis ask 2.25p	ZTX500 ZTX501 ZTX502	15p 15p 15p	{PIV shown in brackets} 1 ¹ /2 amp typ	LM1872 LM1877 LM1886	4.39p 5.95p 7.44p	100 Pins 61 Verobloc 4 66 Vero Wiring	P 4AH 25.95p TYPE P: PP3 5.50p
250V 1nF to 6n8 7p 8n2 to 47nF 8p	47 1 100 1 100 1	6 8p 0 9p 6 10p	74190 74191 74192	1.75p 1.48p 1.35p	74LS362 74LS365 74LS366	6.89p 69p 69p	6502A 6800 6802	5.49p 2.75p 2.99p	2N3709 2N3710 2N3711	31p 34p 37p	BC179B BC179C BC182	39p 41p 15p	BFS61 BFS98 BFX29	99p 99p 44p	ZTX503 ZTX504 ZTX510 ZTX510	18p 19p 28p	W01(100) W02(200) W04(200)	28p LM1889 34p LM2907N 38p LM2907N	3.77p 2.75p 3 2.60p 2.40p	Pen & Spool 3.39 Spare Spool 75	TYPE A: HP7(Up to 4 at a p time) 5.85p
56nF to 150nF 12p 100V	220 1	0 11p 6 12p 0 17p	74193 74194 74195 74195	99p 1.25p	74LS367 74LS368 74LS373 74LS373	74p 2.20p 2.20p	6809 8035 8039	9.95p pis ask pis ask	2N3773 2N3819 2N3902	2.09p 55p 6.88p	BC182A BC182B BC182L	17p 19p 15p	BFX30 BFY53 BSX19 BSX20	46p 53p 29p 33p	ZTX650 ZTX651 ZTX652	47p 48p 49p	2 amp type Square with h	LM2917NE LM3900	2.40p 62p 1.45p	Combs 6	SOLDER
100nF to 150nF 13p 180nF to 270nF	1000 1 1000 1 2200 1	0 20p 6 24p 0 34p	74197 74198 74221	1.07p 2.37p 1.07p	74LS378 74LS386 74LS390	1.20p 50p 1.10p	8080A 8085 Z80A CPU Z80B CPU	18.00p pls ask 3.59p 9.45p	2N3904 2N3905 2N3905 2N3906	19p 19p 19p	BC182LB BC183 BC183A	19p 14p 16p	BU104 BU105	49p 2.32p 1.89p	ZTX 653 ZTX 750 ZTX 751	50p 47p 48p	S01(100) S02(200) S04(400)	6p LM3914 50p LM3915 55p LM13600	3.25p 3.25p 1.15p	FERRIC	ANTEX SOLD- ERING IRONS C250(15W) 5.20p
330nF to 390nF 25p 470nF to 560nF	2200 1 3300 1 3300 1	6 44p 0 50p 6 65p	74L	S TTL	74LS393 74LS395 74LS396	99p 1.35p 2.99p	MEMO 2114 2532/300	RIES pls ask 6.55p	2N4030 2N4031 2N4032	88p 82p 87p	BC183B BC183C BC183L	19p 25p 15p	BU108 BU109 BU126	2.49p 2.49p 1.55p	ZTX752 ZTX753	49p 50p	6 amp type	56p MF10 NE531N NE543N	3.75p 1.36p 2.50p	CHLOHIDE Ouick dissolving Enough to make	XS240(25W) 5.40p Iron Stand 1.75p
32p 680nF 38p 1µF (10mm) 40p	4700 1	0 65p 6 95p	74LS00 74LS01 74LS02	32p 24p 29p	74LS396 74LS399 74LS445 74LS445	1.50p 1.25p	2532/400 2564 2708	3 99p pls ask 3.95p	2N4036 2N4037 2N4400	72p 66p 19p	BC183LA BC183LB BC183LC	16p 18p 23p	8U204 8U205 8U206 8U206	2.49p 1.99p 2.16p	DIC	DDES	PW01(100) PW02(200) PW04(400) 1	95p NE555 99p NE556 80p NE558	22p 65p 1.89p	ETCH RESIST TRANSFERS 1 Thin lines	(State Iron) 2.05p C250 Bits No102 (Sml) 85p
POLYESTER 250V RADIAL (C280)	7400	48p 42p	74LS03 74LS04 74LS05 74LS05	24p 79p 29p 44n	74LS540 74LS541 74LS640	1.70p 1.44p 2.25p	2716 (5v) 2732 2764 4116	3.45p 4.50p 8.99	2N4402 2N4902 2N4903	37p 2.25p 2.38p	BC184B BC184C BC186	19p 24p 29p	BU226 BU326S BU406	4 45p 2.63p 1.45p	IN34A IN821	52p 70p	PW06(600) 1.	89p NE560 NE565 NE566	3 25p 1.18p 1.49p	2 Thick lines 3 Thin bends 4 Thick bends	No103 (Sml) 85p No106 (Sml) 85p XS240/X25 Bits
22nF, 33nF 47nF, 68nF	7402 7403 7404	59p 39p 78p	74LS09 74LS10 74LS11	35p 49p 29p	74LS641	2.25p	4118 4164 6116	4.65p 4.99p pls ask	2N4904 2N4905 2N4906	2.46p 2.99p 3.09p	BC187 BC212 BC212A	29p 16p 18p	BU407 BU408 BU409	1.58p 1.49p 1.65p	IN823 IN914 IN916	92p 4p 6p	Metal clad wi hole K01(100) 21	NE567 NE570 NE571	1.37p 4.07p 3.99p	5 DiL pads 6 Transistor pads 7 Dots & holes	No50 (Small) 85p No51 (Med) 85p No52 (Lge) 85p
150nF, 200nF 10p 330nF, 470nF 13p 680nF 18p	7405 7406 7407	52p 1.40p 1.40p	74LS12 74LS13 74LS14	35p 38p 75p	4000 4001	28p 28p	6810 MISC LOC AOCO804	1 95p GIC IC's pls ask	2N4907 2N4908 2N4909	3.42p 3.58p 3.15p	BC212B BC213 BC213A	21p 17p 18p	BU500 BUY18S E430	3.56p 4.33p 6.32p	IN4001 IN4002 IN4003	4p 4 ¹ /2p 5p	K02(200) 2. K04(400) 3. K06(600) 4.	25p RC4194 10p RC4195 RC4558	3.95p 2.95p 44p	o 0.1 edge connectors 9 Mixture Any sheet of	18swg 2.95p 22swg 3.10p
1μF 22p 1.5μF 39p 2.2μF 39p	7408 7409 7410 7411	59p 59p 59p	74LS20 74LS21 74LS22 74LS22	42p 33p 33p	4002 4006 4007 4008	28p 69p 25p	ADC0816 ADC0817 INS1771 R02512LC	pis ask pis ask pis ask	2N5089 2N5190 2N5191 2N5193	43p 75p 79p 99p	BC213C BC213L BC213LA	24p 15p 16p	J310 MJ802 MJ900	88p 4.25p 3.21p	IN4005 IN4006 IN4007	6p 6 ¹ /2p 7p	35A 400V 4.	50p SN76477 SN76003 SN76013	7.95p 3.45p 3.45p	above 39 GRADE ONE GLASS PC8	PLUGS& SOCKETS
InF 500V 35p HIGH VOLTAGE	7412 7413 7414	30p 35p 59p	74LS28 74LS30 74LS32	29p 29p 86p	4009 4010 4011	55p 29p 28p	RO2513U0 SAA5000 SAA5010	7.50p 4.05p 7.81p	2N5194 2N5245 2N5246	83p 46p 59p	BC213LB BC213LC BC214	19p 23p 18p	MJ901 MJ1000 MJ1001	3.39p 2.76p 3.26p	IN4009 IN4148 IN4150	20p 3p 18p	ОРТО	SN76023 SN76033 TA7204	3.45p 3.45p 1.99p	SINGLE-SIDED 178 × 240mm 1.50	D' Connectors 25 Way Solder Male 1.600
please enquire many types in stock	7416 7417 7420	1.29p 1.29p 49p	74LS33 74LS37 74LS38	28p 29p 69p	4012 4013 4015	29p 49p 65p	SAA5012 SAA5020 SAA5030	7.81p 5.95p 6.99p	2N5247 2N5248 2N5249	63p 65p 67p	BC214B BC214C BC214L	22p 27p 19p	MJ1800 MJ2500 MJ2501	3.79p 2.39p 2.63p	IN4448 IN5400 IN5401	22p 12p 13p	Specials see C CAT LED LAMPS	TA7205 TA7222 TA7227 TBA500	1.20p 1.75p 5.82p 2.97p	420 × 195mm 1.95 420 × 245mm 2.96	p Female 2.09p PCB Wire-Wrap Male 1.60p
TANT BEADS 1/35V 14p	7421 7422 7423 7425	39p 39p 39p	74LS40 74LS42 74LS47	45p 81p 99p	4016 4017 4018	45p 69p 69p	SAA5040 SAA5041 SAA5050	15.95p 15.95p 8.95p	2N5266 2N5401 2N5415 2N5416	3 25p 57p 1.36p 1.73p	BC214L8 BC214L0 BC300 BC301	21p 26p 59p 59p	MJ3000 MJ3001 MJ4502	2.39p 2.63p 4.25p	IN5404 IN5406 IN5407	16p 18p 19p	R = Red G = Green Y = Yellow	TBA5000 TBA510 TBA5100	3.11p 2.95p 3.05p	DALOETCH RESIST PEN + spare nib 1 29	Female 2.09p Covers 1.00p Phono plugs
22/35V 14p 33/35V 14p 47/35V 14p 68/35V 14p	7426 7427 7428	59p 39p 43p	74LS54 74LS55 74LS55 74LS73	25p 25p 52p	4020 4021 4022	89p 79p 79p	8T26 8T28 8T95	1.19p 1.19p 99p	2N5447 2N5448 2N5449	29p 31p 27p	BC302 BC303 BC327	59p 59p 16p	MJE340 MJE350 MJE2955	75p 1.49p 1.99p	IN5408 BA102 BA115	20p 49p 29p	Large diffused R5D G5D	1+ TBA520 10p TBA5200 16p TBA530	2.57p 2.75p 2.55p	PHOTO SENSITIVE PCE 1st Class Epoxy	Wt or Yell 15p Line Skts 15p Chas Skt x 1 16p
10/35V 14p 2.2/35V 14p 3.3/35V 18p	7430 7432 7433	59p 59p 35p	74LS74 74LS75 74LS76	68p 55p 33p	4023 4024 4026	49p 99p 89p	8T97 81LS95 81LS96	99p 2.27p 2.27p	2N5450 2N5451 2N5457	63p 66p 39p	BC327A BC327B BC327C	19p 23p 25p	MJE29551 MJE3055 MJE30551	Г 95р 1.59р Г 69р	BA133 BA138 BA142	51p 36p 25p	Y5D Small diffuse R3D	15p TBA5300 TBA540 d TBA5400 8p TBA550	2.76p 2.72p 2.74p 3.25p	results than spraying expos	Dual Skt 30p Ouad Skt 40p
4.7/16V 18p 4.7/35V 20p 6.8/25V 20p	7437 7438 7440 7441	49p 82p 45p 72p	74LS78 74LS83 74LS85 74LS85	41p 89p 1.15p	4027 4028 4029 4030	45p 53p 89p 39p	81LS97 81LS98 6522 6522	2.27p 2.27p 3.69p 5.55p	2N5458 2N5459 2N5460 2N5551	39p 31p 83p 41p	BC440 BC441 BC460 BC461	35p 37p 38p 42p	MPSA06 MPSA10 MPSA12	29p 33p 59p 49p	BA156 BA157 BA158	41p 28p 34p	G3D Y3D Micro 0.1"	13p TBA5500 13p TBA560C TBA570	3.27p 2.87p 2.37p	Single sided 100 x 160 2.10 100 x 220 2.50	ZIF SOCKET
10/16V 21p 10/16V 18p 10/35V 27p 15/10V 22m	7442 7443 7444	89p 1.49p 1.49p	74LS90 74LS92 74LS93	55p 84p 65p 65p	4031 4032 4034	1.60p 89p 1.99p	6532 6821 6840	6.45p 1.99p 3.75p	2N6121 2N6122 2N6123	91p 93p 99p	BC547 BC550C BC560C	19p 29p 29p	MPSA13 MPSA14 MPSA20	49p 49p 49p	BA159 BA182 BA201	38p 49p 23p	RIM GIM YIM	27p TBA5700 29p TDA1002 29p TDA1003	2.48p 3.39p 4.35p	203 x 114 2.40 233 x 220 5 20 Double sided	^p 28 pin 5.00p 40 pin 5.35p
15/16V 30p 15/25V 32p 22/6.3V 26p	7445	1.59p 1.59p 99p	74LS95 74LS96 74LS10	69p 1.55p 7 55p	4035 4036 4038	79p 2.69p 1.19p	6845 6847 8154	6.49p 6.49p pls ask	2N6124 2N6125 2N6126	1.01p 1.03p 1.09p	BCY70 BCY71 BCY72	31p 33p 25p	MPSA42 MPSA43 MPSA55 MPSA55	49p 48p 29p	BA202 BA316 BA317 BA218	29p 27p 28p	Large clear R5C G5C	12p TDA1004 12p TDA1005 17p TDA1005	4 35p	100 × 160 2.20 100 × 200 2.80 203 × 114 2.20 233 × 220 5 9	D TOGGLE (MIN)
22/16V 29p 33/10V 30p 47/3V 14p	7448 7450 7451 7453	1.19p 29p 29p	74LS10 74LS11 74LS11	9 42p 2 80p 3 85p	4040 4041 4042	72p 72p 72p	8155 8212 8216 8226	pis ask pis ask pis ask	2N6129 2N6130 2N6131 2N6131	99p 1.05p 1.23p	BD124 BD131 BD132 BD135	2.99p 63p 63p	MPSA56 MPSA65 MPSA66 MPSA70	33p 62p 65p	BA318 BAX13 BB105 BB1090	31p 21p 65p	Y5C Super brigh	17p TDA1022 t TDA2002 ty TDA2003	4.95p 3.25p 3.25p	Developer for above (do not use Sodium	SPST 59p SPDT 65p DPDT 74p
47/6.3V 34p 47/16V 39p 100/3V 32p	7454 7460	29p 29p 48p	74LS11 74LS12 74LS12	45p 2 75p 3 1.19p	4044 4045 4046	1.19p 89p	8224 8226 Z80ACTC	pis ask pls ask 3.49p	2N6132 2N6133 2N6134	1.15p 1.33p	BD136 BD137	38p 39p	MPSA92 MPSA93	49p 48p	BY126 BY127	12p 14p	Large (100 tim brighter)	TDA2020 TDA2030	3.15p 2.85p	Hydroxide) 500ml 2.95	DPDT C.OFF 90p 4PDT 325p





for low-cost training in real-life robotic

The advanced design of the Neptune 2 makes it the lowest cost real-life industrial robot.

It is electro-hydraulically powered, using a revolutionary water based system (no messy hydraulic oil!)

It performs 7 servo-controlled axis movements (6 on Neptune 1) - more than any other robot under £10,000.

Its program length is limited only by the memory of your computer. Think what that can do for your BASIC programming skills!

And it's British designed, British made.

Other features include:

Leakproof, frictionless rolling diaphragm seals.

Buffered and latched versatile interface for BBC VIC 20 and Spectrum computers. 12 bit control system (8 on Neptune 1).

Special circuitry for initial compensation.

Rack and pinion cylinder couplings for wide angular movements.

Automatic triple speed control on Neptune 2 for accurate 'homing in'.

Easy access for servicing and viewing of working parts.

Powerful - lifts 2.5 kg. with ease.

Hand held simulator for processing (requires ADC option).

Neptune robots are sold in kit form as follows:

Neptune 1 robot kit (inc, power supply)	£1250.00
Neptune 1 control electronics (ready built)	£295.00
Neptune 1 simulator	£45.00
Neptune 2 robot kit (inc. power supply)	£1725.00
Neptune 2 control electronics (ready built)	£475.00
Neptune 2 simulator	£52.00

All prices exclusive of VAT and valid until the end of 1984.



This compact, electrically powered training robot has 6 axes of movement, simultaneously servo-controlled. It gives smooth operation, and its rugged construction makes it ideal for use in educational establishments. Other features include long-life bronze and nylon bearings, integral control electronics and power supply, special circuitry for inertial compensation, optional on-board ADC, and hand-held simulator as the teaching pendant. Like Neptune, Mentor's program length is limited only by your computer's memory. Programming is in BASIC.

Mentor is all-British in design and manufacture and comes in kit form at an astonishingly low price

Mentor robot kit (inc. power supply)	£345.00
Mentor Control electronics (ready built)	£135.00
Mentor Simulator (requires ADC option)	£42.00
ADC option (Components fit to control electronics board)	£19.50
BBC connector lead	£12.50
Commodore VIC 20 connector lead	E 14 50
Sinclar ZX Spectrum connector lead	£14.50

All prices exclusive of VAT and valid until the end of 1984.







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Hydraulic power pack (ready assembled)	£435.00
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Optional extra three fingered gripper	£75.00
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Commodore VIC 20 connector lead and plug-in board	£14.50
Sinclair 7X Spectrum connector lead	£15.00



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4700 98 p; 10,000 320 p; 15,000 345 p. 500 Ω, 1K & 2K (LIN ONLY) Single 335 p BC149C 15 BD596A 30 WK1010 99 2N37/2 195 25C2334 TANTALUM BEAD CAPACITORS: 5K0.2M0 single gang DP switch 35p BC153/4 30 BF15 45 MPSA06 30 VK1010 99 2N37/2 210 2SC2335 2 TANTALUM BEAD CAPACITORS: 5K0.2M0 single gang DP switch 95 BC153/4 11 BF167 35 MPSA08 30 VN46AF 10 2N3820 60 2SC2547	85 00 25 40
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B Commoned: (9) pins) 1500, 1500, 2300, 150, 1800, 2700, 330, 1K, 2K2, 4K7, 100K, 240, 40671, 8 Commoned: (9) pins) 1500, 1500, 1500, 1500, 160, 25 218306 25 218306 25 218306 25 218457 30 40671/2 9 Commoned: (9) pins) 1500, 1500, 2100, 25 218457 30 40671/2 9 Commoned: (9) pins) 1500, 160, 125 11930A 35 21706A 25 218457 30 40671/2 10 Commoned:	70 90 50
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SPEAKERS 8Ω, 0 3W. 2"; 2 25", 2 5". 3" BOp	LEDS price includes Clips	AYS	1A T0220 Plastic Casing	S	SOCKETS 8 pin	by the brofile wrap 8p 25p		SPEC	TRU	M
0 3W, 2.5" 4011; 6411 or 8011 BOp	TIL209 Red 3mm 10 31 digit TIL211 Green 3mm 14 4 digit TIL212 Yellow 14 6 digit	495 530 625	5V 7805 50p 7905 12V 7812 45p 7912	50p	14 pin 16 pin 18 pin	10p 35p 10p 42p 16p 52p	32	K UP	GRA	DE
DIODES BRIDGE AA119 15 RECTFIERS AA129 20 (plastic case) AAY30 15 1A/50V 18 BA100 15 1A/400V 25	TIL220-2" Red 12 02" Yel, Gm, Amber 14 BPX25 Rectangular LEDs with BPW21 BPW21 two part dip. R, G & Y 45 BPW21 Rectang. Stackable ILD74 BL074 LEDS 18 ILC76 Triangular LEDs R&G 18 ILC76	250 320 320 145 275	15V 7815 45p 7915 18V 7818 45p 7918 24V 7824 45p 100mA T092 Plastic Casing 5V 78L05 30p 79L05 6V 78L62 30p - 8V 78L82 30p -	50p 50p	20 pin 22 pin 24 pin 28 pin 40 pin	20p 60p 22p 65p 25p 70p 28p 80p 30p 99p	Upgrad 48K wi simple	de your 16k th our RAM to fit. Fi	Spectru Upgrade tting ins	m to full Kit. Very tructions
BY100 24 1A/600V 34 BY126 12 2A/50V 30 BY127 14 2A/200V 40 CR033 250 2A/400V 46 OA9 40 2A/600V 65 OA7 12 6A/100V 83 OA70 12 6A/600V 125	02° Filashing LED Red 56 Isolator 02° Bi colour LEDs TIL 111 Red/Green 100 OCP71 Green/Yellow 80 ORP12 02° Tri colour LEDs 2N5777 Red/Green/Yellow 85 4N33	135 70 120 78 50 135	12V 78L12 30p 79L12 15V 78L15 30p 79L15 ICL7660 248 LM317K 38H05 5V/5A 550 LM317P 78H05 5V/5A 640 LM323K 19HC 640 LM323K	50p 2 50p 2 250 4 99 500 175	ZIF DIL S 24 way 28 way 40 way DIL PL	OCKET 575p 695p 845p		PCB Male with latch	d block type) Female Header	Female Card-Edge
OA79 15 10A/200V 215 OA81 20 10A/600V 298 OA85 15 25A/200V 240 OA90 8 25A/200V 240 OA91 8 25A/600V 395 OA91 8 81/164 56 OA95 8 VM18 50	Vellow 100 Vellow 100 L021 Infra Red (emit) 46 TIL32 Infra Red (emit) 52 SFH205 (detector) 118 OPTO SWIT	t er 715	124V 5A 599 LM723 79HG -2.25V to TBA625B -24V 5A 685 RC4194 LM309K 120 RC4195	30 75 375 160	Pins 14 16 24 28 40	Solder IDC 38p 95p 42p 100p 88p 138p 185p 290p 195p 218p	2 rows 10 way 16 way 20 way 26 way	Strt. Ang Pins Pin 90p 99 130p 156 145p 166 175p 200 205n 23	gle Socket 5 5 5 6 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7	Connector 120p 195p 240p 320p 340p
0A202 8 1N914 4 1N916 5 1N4001/2 5 1N4003 6 1N4004/5 6 Range 2V7 to 39V 400mW 8p each Range 3V3 to	III.38 50 Herited TIL81 82; TIL100 90 TIL139 Slottec Sogment Displays to RS TIL321 5° C.An 140 TIL322 5° C.th 140 D1704.37* C.Cth 140 D1704.37* C.Cth 140	225 d similar 186 A.BOXES 2' 100	SLIDE 250V TOGGLE 2A 1A DPDT 14 SPST 1A DPDT C/OFF 15 DPDT JA DP on/on/on 40 4 pole on off	250V 35 48 54	RIBBON (Ways 10 16 20 26	CABLE (price per foot) Grey Colour 15p 28p 25p 40p 30p 50p 40p 65p	40 way 50 way EURO CONNE Gold flat	220p 250 235p 270 CTORS shed contacts	EMALE COCKETS Strt. Angle	420p 470p MALE PLUGS Strt. Angle
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Cortex II **16-bit 16-colour Computer**

The new slimline Cortex offers constructors the speed and power of 16-bit computing for the same price as an 8-bit games machine. The standard kit has TV, cassette and RS232C interfaces – others are available as optional extras. Add disc drives, printer and monitor for a fully-fledged business system.

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LICENSING

THE Government has just published a consultative paper on the relaxation of licensing requirements for low power radio devices in the UK. The proposals cover such items as aids for the disabled, garage door openers, radio microphones and radio doppler alarm systems.

Licensing restrictions on metal locators and model control equipment were changed some time ago and this new move will allow further freedom to buy and use equipment working on approved frequencies and below specified power levels—providing of course the proposals are passed.

At the present time however you will need a licence to use the *Doppler Radar Alarm* published in this issue. We will keep you informed if the situation changes.

This alarm system with up to four transmitter/receiver units can be easily

set up to protect your home and could well be a very worthwhile investment.

MORE ROBOTICS

Maybe one or two readers are a little tired of reading about robots and robotics on this page but I make no apology for including some more on the subject. Much of the future of industry is tied up with robotics and it is now becoming a significant subject in education and of course for hobbyists with an eye on the future and possibly a career.

Next month we take an in-depth look at small robots with two articles from Tom Ivall and a buyers' guide to products available from around twenty UK companies. These items will form a Free 16-page Robotics Supplement which will also be carried by our sister publication *Everyday Electronics*.

PE is the leading publication in the area of serious use of small robots with

designs for six units now published. Back in October 1981 we published an article by Pròfessor Wilfred Heginbotham OBE, D.Sc. Director General of P.ERA (Production Engineering Research Association) which set the scene on industrial robots and the future. Readers bred on our designs may have a significant part to play in that future. PE intends to also play a part in the development of robotics and we are actively pursuing new designs and ideas in the small robot area which will continue to break new ground.

Everyday Electronics will also publish some interesting low cost educational robotics projects starting with *Alfred* next month and moving on to other *new* educational ideas in robotics.

Mike Kener

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We are unable to offer any advice on the use or purchase of commercial equipment or the incorporation or modification of designs published in PE. All letters requiring a reply should be accompanied by a stamped, self addressed envelope, or addressed envelope and international reply coupons, and each letter should relate to one published project only.

Components and p.c.b.s are usually available from advertisers; where we anticipate difficulties a source will be suggested.

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BURSE SE

Pirates caught RED handed BBC WIND TESTS

Piracy of software has reached such staggering proportions in the UK that (according to the Guild of Software Houses) for every one legitimate manufacturers' copy sold there are ten counterfeit copies sold. It is further estimated that this contraband market is depriving software houses of around £100 million per annum in lost revenue.

Many software producers are funding and/or working on systems to ensure that illegal copies cannot be made, in order to keep original programs 'original'.

One such company is Rising Edge Data Ltd., who have developed a patented protection system to prevent mass copying of computer software. The system is known as RED and can be adopted by any computer company or programmer and while preventing mass copying will still allow the originator to make back-up copies,

The secret of RED is in the digitised security card which is the same size and shape as a credit card and the reader unit which plugs into the computer. The reader unit will prevent a program being run until the unit is activated by the insertion of the magnetically encoded card. The code on the 'key' card is identical to a program code written into the software, only when the two codes match will the computer allow the program to be run. This means that without the 'key' card a user cannot run the program; RED can be used with most of the popular micros.

The system as yet is being considered by software houses and independent writers and if adopted would mean that home users would have to buy a RED reader unit in order to run protected software. Tapes could then be sold along with their 'key' cards.

RED's success will depend on the willingness of software originators to accept the concept and of course the users' willingness to buy a reader unit. Although no price has been set for a reader unit, the manufacturers accept that it will have to be very low.

Rising Edge Data is a subsidiary of Abacus Programs, Swansea. For further information contact Active Marketing, 113 Walter Road, Swansea SA1 500, (0792 472927)



An Acorn BBC Microcomputer is being used

in wind tunnel tests at Southampton University to improve the performance of aircraft, racing cars and other motor vehicles.

The wind tunnel enables engineers to measure the aerodynamic forces operating on the racing car. To simulate normal race circuit air conditions a 200 horse power fan blows air over a detailed one/third scale model of the car, while a moving belt under the wheels simulates the ground effects of travelling at speed.



The computer, a BBC Model B Micro, scales up the data gained from the model car in the tunnel tests to direct loads that the real car would encounter. This allows the racing team to study the effect of modifications to the basic design under controlled and economical conditions

A further program on the machine works out how these modifications will affect lap times. The software 'models' the Silverstone circuit and calculates lap times after the model car has undergone changes in aerofoil settings and body design. These are then adapted to the real car for 'live' testing.

BEWA MULTIMETE



An impressive range of 3¹/₂ digit handheld multimeters have been introduced into the UK by House of Instruments.

The range of 9 models in colour coded format (i.e. the Multimeter body) are in three model ranges of accuracy 0.1%; 0.25% and 0.5% each model in the 0.5% and 0.25% range offering a.c./d.c. current facilities of 2A, 10A and 20A, the 20 Amp being a new facility not hitherto available in this price range.

The BEWA multimeters conform to DIN & VDE specifications and are ruggedly conceived with side pushbutton selection. Ample protection is offered and prices start as low as £43.41 inc VAT and P & P for the 6010GS (pictured). From House of Instruments, Clifton Chambers, 62 High Street, Saffron Walden, Essex CB10 1EE. (0799 24922).

Quadriennium

The BBC has extended the agreement with Acorn Computers for the manufacture and distribution of the BBC Microcomputer for a further four year period from 1 September 1984

The BBC Computer Literacy Project is now in its third successful year. There is a growing demand for computer education, and the BBC plans to make new computer series and produce new books and software, as well as repeating existing series.

More than 350,000 BBC Microcomputers have been sold to date. Over half the micros used in education in Britain are BBC machines, and during the last year, three quarters of the computers bought by schools were BBC micros. It is against this background that the BBC has decided to renew the contract with Acorn.

MARGE BLACE Helping hand NEON DRIVER OPTION Mono Check and the safety aspects of the An electronic single-pole voltage tester.

Few DIY jobs are more frustrating than the one that needs "three hands"-two to hold the work and a third to apply solder or adhesive. The smaller the component, the more difficult it is to position it accurately and firmly.

Gripmate, produced by an innovative Sussex company, is a tiny clamp that provides not just one extra "hand" but four, able to grip small electronic components and similar items in an infinite number of positions.

A base block clamped to any bench or table top carries four semi-rigid wires, each fitted with a crocodile clip to hold the work. Alternatively, any of the wires can be replaced with one holding either a magnifying glass for close-up work, or perhaps a magnet.

The four-handed model costs £4.85 (a basic type with two arms sells for £1.00 less), and the magnifier and magnet come for £2.50 and £1.50 respectively, prices include VAT and p & p, from Kemplant Ltd, Durfold Wood, Plaistow, Billingshurst, W. Sussex RH14 OPN. (048 649344).



designed as an effective alternative to the conventional neon voltage testers, is announced by Steinel (UK) Ltd. The Mono Check will give a bright, easily visible indication in virtually any circumstances, when voltage is detected. A special electronic sensing circuit overcomes the problems of neon types which can often be very difficult to see when the user presents a very high insulation to earth.

DIY enthusiasts will appreciate the tough, high quality construction of the design. The voltage testing range is from 80V to 240V a.c. and there is a very generous overvoltage range of six times normal maximum (1500V). The Mono Check can be used in all situations in temperatures from -20 to +80 degrees C and in humidities up to 95 per cent. The battery lasts for around one year. The price of £3.99 includes the 12V battery, VAT and P & P. From J. E. M. Marketing, 180 Princess Avenue, Palmers Green, London N13 6HL. (01-889 1415).

STEINE

Briefly.

Job hunters who take TOPS computer training courses stand a 10 per cent better chance of finding employment this year than last. So far this year 59 per cent of leavers found a job within three months of completing their courses. Improved prospects in trade and industry along with curriculum changes are believed to be the main factors in this encouraging trend.

The Rt. Hon. Kenneth Baker, MP, Minister for Information Technology, announced recently that Britain will be a major participant in the European Space Agency's ERS-1 programme to develop a remote sensing satellite. The data provided will be of value to a range of users for forecasting winds, waves, seaice and weather; users will be able to receive information within three hours. Britain is one of the first countries to sign-up and will take a 14 per cent share in the £325 million project. ERS-1 is due to be launched in 1989.

Please check dates before setting out, as we cannot guarantee the ac-

curacy of the information presented below. Note: some exhibitions may be trade only. If you are organising any electrical/electronics, radio or scientific event, big or small, we shall be glad to include it here. Address details to Mike Abbott.

Computer Roadshow (Architects/surveyors) Sept. 11-13. B/ham. U2 Testmex Sept. 11-13. Grosvenor Ho. Pk. Lane, London. E

- Leeds Energy Manager Sept. 12-13. W3
- What Peripherals Sept. 13-16. Barbican. J3
- Computer Roadshow (Healthcare) Sept. 14-16. Birmingham. U2
- Personal Computer World Show Sept. 19-23. Olympia 2, London. M Computer Roadshow (Healthcare) Sept. 22-24. Manchester. U2
- Semiconductor International Sept. 25-27. NEC. T1

Computer Trade Forum Sept. 25-28. NEC, Birmingham. T1

Pemec (British Robot Assn.) Sept. 25-28. NEC. G2

Building & Home Improvement Sept. 25-30. Earls Court, London. M Computer Fair Sept. 29. Prestatyn High School. See the I.T. mobile exhibition, armed forces and Microelectronics Education Programme Centre. Competition, clubs, hardware/software. Z9

Computer Roadshow (Healthcare) Sept. 29-Oct. 1. Edinburgh. U2 Computer Graphics Oct. 9-11. Wembley Conf. Cntr., London. O Machine Intelligence Oct 9-11. Cunard Int. Hotel, London. I Software Expo Oct. 16-18. Wembley Conf. Cntr., London. O

Internepcon Oct. 16-18. Metropole, Brighton. T1 Scottish Energy Manager Oct 23-24. Skean Dhu Hotel, Glasgow. W3 Business Equipment Show Oct. 23-26. Olympia, London. Z Drives, Motors & Controls Oct. 24-26. Harrogate Exhibition Cntr. E Electron & BBC Micro User Oct. 25-28. Alexandra Palace, London. L International Test & Measurement Oct. 30-Nov. 1. Olympia. D4 Leisuretronics Nov. 8-11. Royal Horticultural Hall, London. T P.c.b. Manufacture & UV Box Construction (meeting) Nov. 17. Electronic Organ Constructors Society. Y4 Computers In The City Nov. 20-22. Barbican, London. O Data Security Nov. 20-22. Barbican, London. O

- Network & 0280 815226 **D4**
- E Evan Steadman @ 0799 26699
- 6 01-747 3131 G2
- ITF & 021-705 6707 I
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- Beta Exhibitions @ 01-405 6233 Z
- **Z9** Mr. Carson & 0244 535606

LTER SHIF

CLOCK RATE

VCE

AN ENHANCED phasing effect is produced in this unit by passing a music signal through modulated voltage controlled filter and delay line stages, then mixing this processed signal with the original at the output. The rate and depth of modulation, the v.c.f. response and mixing balance are panel controlled. The v.c.f., phase and by-pass modes are selected via electronic gates for quiet switching. It may be used with most electronic musical instruments or pre-recorded sources. A block diagram is given in Fig. 1.

CLOCK MOD

FORATE

INPUT SPLITTING

The signal to be processed is brought into the unity gain buffer stage IC1a and fed simultaneously to the final output stage IC1c, the voltage controlled filter around IC1b and IC2, and the selector gates IC3a and IC3b.

VOLTAGE CONTROLLED FILTER

The purpose of the filter is to give enhancement to a frequency bandwidth that is being constantly shifted up and down depending on the modulating control voltage applied. On its own the modified output gives a marked change to the quality of the audio signal, and when combined with phase shifting of the delay stage further interesting changes result. At a slow rate of modulation the filter effect on its own is similar to phase shifting with harmonic overtones. At a fast rate, a bubbly wah effect results. VR7 controls the frequency bandwidth emphasised, but should not be regarded as a level control, though at its lower end it behaves in a similar fashion as the bandwidth is moved out of the audio range. The circuit for the v.c.f. consists of a mixer stage IC1b, two transconductance op. amps IC2a and IC2c, and two high impedance stages IC2b and IC2d. The workings are too complex to be described here, but essentially the bandpass range as seen at pin 8 of IC2b is determined by the current flowing into C5 and C6, as set by the control voltage on R21 via VR7, with a gain factor determined by the value of R7.

GATE AND STATIC FILTER

The electronic changeover gates IC3a and IC3b are connected to allow either the original or v.c.f. processed signal to pass through, and are activated by S1. R22 maintains a small d.c. current on the output of the gates to minimise switch over noise. The output from the gates is then fed to the first static filter stage around IC4d in which C11 and C12 limit the maximum frequency to about 5kHz at unity gain. This limit is imposed to reduce harmonic distortion in the delay stage where the maximum signal frequency preferred is approximately one third of its controlling clock signal.

BECK

DELAY STAGE

IC8 is a 512-stage bucket brigade delay line chip that passes the audio signal through at a rate determined by the frequency of the controlling clock. The delay increases as the clock frequency reduces. Waveform distortion through the chip is kept to a minimum by applying an optimum bias voltage on its input via VR1. The twin outputs are summed at VR2, to produce a slightly attenuated delayed signal that inherently includes a trace of the clocking signal. This is partially balanced out by adjusting VR2. The remainder is filtered out by the second static filter stage around IC1d, where unity gain is maintained for the low pass signal as set by C17 and C18.

MIXER AND OUTPUT

From IC1d the signal may be switched through the electronic gate IC3c activated by S2. VR3 then allows the desired level to be mixed with the original signal at IC1c. Here a gain of two is given to the processed signal to allow for attenuation in the delay stage. The original signal passes through at unity gain with little insertion loss. The phasing effect is produced when the phase relationship between the two signals changes. Note that the maximum level of the





Fig. 2. Circuit diagram

combined signal can be up to twice that of the original depending on the relationship. From IC1c the combined signal can be fed to the normal amplifier system.

MODULATING OSCILLATOR

R46

The modulation voltage needed to vary the phase and v.c.f. changes is derived from the circuit around IC4a/b. The

frequency range is determined by C20 which varies its charge at a rate set by VR4. Each time the threshold trigger point of the comparator IC4b is passed, the direction of charge is reversed resulting in a triangular waveform at pin 7 of IC4a, variable by VR4 between about 7 and 2 cycles per minute. This can modulate the v.c.f. via VR7, and the delay clock generator stage via VR5, with IC4c optimising the voltage swing. C24 slightly smooths the peaks of the modulating waveform.



CLOCK GENERATOR

IC4 is a linear voltage controlled oscillator where the output frequency is determined by the relationship of the power supply voltage, R43, the total of R44 and VR6, C21 and the voltage present on its input via IC4c. With the modulation off, VR6 can vary the clock range from about 46kHz to 430kHz. With a voltage swing of about 13V from IC4c the clock sweep range becomes about 15kHz to 83kHz with VR6 at maximum resistance, and 86kHz to 840kHz with VR6 at minimum resistance. The output from IC5 is taken through the twin flip flop stage IC6, and the twin gates IC7a/b. Here the output is two antiphase square waves at half the frequency of the input clock, and without overlap to their edges thus achieving a quieter clock residual from IC8. The full signal delay range is thus about 3ms to 17ms. These calculated figures may vary with component tolerances.

POWER SUPPLY

The unit is designed for use with two 9 volt batteries supplying +9V/0V/-9V at about 10mA. If a power supply is used in place of batteries this should not be exceeded, but it can be reduced to about +5V/0V/-5V without significant detriment, though the optimum lies in the range of +6V/0V/-6V to +9V/0V/-9V.

ASSEMBLY

Be methodical and assemble the p.c.b. carefully in order of resistors, small capacitors, i.c. sockets, presets, large capacitors and finally the short link wires for which resistor off-cut leads may be used. Ritually check all solder joints with a magnifying glass, even for experienced constructors this still pays off in trouble-free testing. Only after all control wiring has been finished should the i.c.s be inserted, remembering that i.c.s 3 and 5-8 are MOS and require the usual handling precautions. Note that the jack sockets are also wired as battery on-off switches and mono jack plugs must be used for correct operation. Screened leads were not found to be necessary with the battery operated unit, though they may be needed for the signal leads to the jack sockets if a mains power supply is used in the same box. Ensure that the box is grounded. For the battery unit a link wire from a pot body to the OV line is adequate. Upon completion the box may be painted and control legends applied with letraset or similar, covering them with a clear varnish or plastic film.

SETTING UP

VR1 and 2 midway, VR3–VR7 minimum, S1 and 2 off. Apply a music signal to the input, at this time a pre-recorded source such as a cassette music track of an orchestral nature will show the best effect. Plug output into amplifier and



COMPONENTS ...

Resistors

R1–3,R5,R6,R8,R9,R13, R16,R18–20,R23,R24,R26,	
R28,R32,R33,R35,R37,R48	100k (21 off
R4,R17,R31	47k (3 off)
R7	200k
R10,R11,R14,R15,R27,R29	
R30	1k (7 off)
R12,R40,R42,R44,R45,R49	10k (6 off)
R21	18k
R22	9M1
R25,R34,R36	82k (3 off)
R38	4k7
R39	300k
R41,R47	30k (2 off)
R43	1M2
R46	62k

Potentiometers

VR3, VR5-7

VR1

10k skel. 5k skel. 100k lin. mono rota (4 off) 1M lin. mono rota

Capacitors

VR2

VR4

C1,C2,C7,C9,C14,C19,C24 C3,C4 C5,C6,C12,C17 C8,C10,C13,C15,C23 C11 C16 C18,C21,C22 C20,C25,C26

1µF/24V elect (7 dff) 33p polystyrene (2 off) 180p polystyrene (4 off) 100n (5 off) 360p polystyrene 220n 56p (3 off) 22µF/10V elect (3 off)

Integrated Circuits

IC1,IC4 IC2 IC3 IC5 IC6 IC7 IC8 324 (2 off) LM13600 4066* 4046* 4013* 4011* TDA1022*

Miscellaneous

PP3 battery clip (2 off) P.c.b. clip (8 off) Round knobs (5 off) Main Control p.c.b. Clock p.c.b. 14-pin i.c. sockets (5 off) 16-pin i.c. sockets (3 off) Stereo jack socket (2 off) S1 DPDT switch S2 SPDT switch Case—Phonosonics type BK3 Rubber stick-on feet (4 off) Connecting wire

•CAUTION—MOS devices are liable to sudden death from static electricity and are subject to special handling precautions.

Constructors' Note

Complete kit of parts available from: **Phonosonics**, 8 Finucane Drive, Orpington, Kent BR5 4ED. Price £46.00 inc. UK p&p and VAT.



Fig. 4. Main board p.c.b. layout (actual size)



Fig. 5. Main board component layout

VR3 fully and a change in signal level and quality should be apparent as the delayed and original signals are mixed without modulation. Vary VR6 and the phase shifting effect should be heard. Adjust VR1 around its midway point until minimum distortion is apparent on higher volume signals. Remove music source, return VR6 to min (slowest clock), increase amplifier volume until background hiss from the delay stage is heard, then adjust VR2 around its midway point until this minimises, at which point the twin outputs of IC8 are balanced. If no significant change is observed with the variation of VR1 and VR2, leave them midway and ignore. If an oscilloscope is used the balance points will be obvious. Return amplifier to normal volume, reapply music, maximise VR6, bring up VR4 and VR5 to about three-quarters and automatic phasing at a moderate rate should be evident. Adjusting VR6 will change the quality, VR4 the rate, and VR5 the depth. Taking VR4 and VR5 beyond the three-quarters position will introduce extreme results best reserved for producing unusual effects. Turn down VR5 so removing the automatic phasing. Switch the v.c.f. into circuit with S1 and by bringing up VR7 the filter shifting effect will come in. This affects the higher frequencies first, and as VR7 is progressively increased lower frequencies will be modified. Adjusting VR4 will vary the rate of shifting. Switching on S1 will now introduce phase shifting as well as filter shifting.

check that the signal passes through at a normal level. Switch on S2, bring up

USE

For the best signal to noise characteristics the input fevel should preferably be close to, but not greater than, 2.5V r.m.s. The final output of course must not exceed the amplifier requirements. The inherent noise output of the TDA 1022 is typically 0.2mV r.m.s. at a clock frequency of 100kHz. The quality of the phasing effect can be introduced for most music inputs, though it will be most apparent with those having higher harmonic harsher wavecontents or forms in the mid to upper octave ranges. The filter shifting effect will be apparent with practically any input music signal and will give further emphasis to the phasing effect when the filter characteristics are set for a low to mid frequency pass range. For normal use three-quarters settings of VR4-7 will usually be best, with VR3 from three-quarters upwards. With the latter much less than about half, the

AUDIO PROJECT



Fig. 6. Delay board p.c.b. (actual size)





Fig. 7. Delay board component layout

phase cancellation at the mixer stage will be less obvious. The optimum setting is the position where an antiphase signal can completely cancel the original of the same frequency at some point during the shifting cycle. The best position can be determined experimentally and marked on the front panel. By-passing of the effects is achieved by switching off S2, so allowing only the original signal to pass to the amplifier.







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Sequential Logic Techniques Part 1

M.TOOLEY BA and D.WHITFIELD MA MSc C Eng MIEE

THIS six, part series follows on from our previous series entitled "Introduction to Digital Electronics" and aims to both extend the concepts developed in that series and introduce some new material. The accompanying practical exercises have all been designed around the PE Logic, Tutor. (See PE Oct '83' for constructional details or the constructor's note at the end of this article.)

We'start,'this month, with a further look at digital counters and consider both programmable and decade types.

PROGRAMMABLE COUNTERS

The binary counters which we have previously met have all been based on simple arrangements of bistable stages. Readers will not need reminding that each bistable stage functions as a modulo-2 counter and that, where we need to increase the counting capacity (say to 8 or 16) we only need to cascade several stages together. A three-stage counter will, for example, have 2³ (=8) output states whereas a four-stage counter will-have 2⁴ (=16) output states, and so on.

For some applications it is desirable to have counters which can operate to a different number base. A modulo-10 counter would, for example, be very useful in a packing plant where items are to be packed in tens.

In other applications we may require a counter that can be programmed to count up or down. In yet other applications we may require a counter that can be pre-loaded with data rather than always starting its counting sequence at zero.



Fig. 1.1. Pin connections for the 74193

74193 PROGRAMMABLE COUNTER

We shall now consider a practical example of a programmable binary counter using the 74193. This reversible binary counter incorporates the equivalent of no less than 55 individual logic gates contained in a single 16-pin dai, I. package, the pin connections of which are shown in Fig. 1.1.

The internal logic arrangement of the 74193 is shown in Fig. 1.2. As can be seen, the device contains four bistable stages together with some sophisticated gating. Synchronous operation is provided by having all of the bistable stages clocked simultaneously so that the outputs change coincidentally with each other when so instructed by the steering logic. This mode of operation eliminates the output counting spikes which are normally associated with asynchronous fipple counters.

The four master-slave bistables of the 74193 are triggered by a low-tohigh level transition present on either of the two clock inputs. The direction of counting (up or down) is determined by which clock input is pulsed low whilst the other input remains high.

Alt four binary dividers are fully programmable and their outputs can be preset to either logical state by entering the desired data at the data inputs during the period in which the load input is low. The output will then change to agree with the data inputs independently of the clock. This feature allows the 74193 to be used as a modulo-N divider by simply modifying the count length using the preset inputs.

A clear input is provided which forces all outputs to the low level. This input is independent of the count and load inputs. The clear, count, and load inputs are all buffered to reduce the drive requirements. This is an important consideration in practical applications where several programmable counters are to be driven from comfinon clock and control lines.

The 74193 was designed to be cascaded without the need for external circuitry hence carry and borrow^o outputs are provided in order to extend the up- and down-counting functions respectively. The borrow output produces a pulse equal in width to the count-down input when the counter underflows. Similarly, the carry output produces a pulse equal in width to the count-down input when an overflow condition exists. The counters can then easily be cascaded by feeding the borrow and carry outputs to the countdown and count-up inputs respectively of the succeeding stage.

A typical timing diagram for the 74193 is shown in Fig. 1.3. 'This diagram shows how the outputs are first cleared, then pre-set to an output state of 7 (0111) by means of a low applied to the foad input. Five positive edge transitions are then applied to the upward clock and the 74193 counts through the states: 8, 9, 0, 1 and 2. At this point the upward clock goes high and five positive edge clock transitions are applied to the downward clock input. The output states then follow the progression: 1, 0, 9, 8 and 7. It should be noted that, once the desired data input has been loaded, the data outputs are unaffected by the state of the data input lines until the load input next goes low.

UP/DOWN COUNTER USING THE 74193

As a practical example of the use of the 74193, we shall consider a single stage counter in which the count can proceed in either direction as determined by a single up/down direction control input. The counter is also provided with a clear input which restores the count to zero.

The circuit of the 74193 up/down counter is shown in Fig. 1.4. The clock input is steered to the desired clock input by means of a simple gating arrangement configured around a 7400 quad two-input NAND gate. The clock input signal is derived from the Logic Tutor's own clock oscillator whereas the four-bit binary output is displayed on the four logic leyel indicators. In this particular example, use is not made of the ability to preload data and hence the active-low load input is taken to logic 1.

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C2	to D3	(D3 indicates QB)
C3	to D4	(D4 indicates QA)
C4	to F13	(clock down)
C5	to F3	(clock up)
C6	to D2	(D2 indicates QC)
C7	to D1	(D1 indicates QD)
C8	to OV	(common)
C11	to logic 1	(active-low load input)
C14	to S2	(S2 clears the counter)

PE1583G

i to +5V	(supply)
to clock	
to S3	(direction contro
to F5	
to F2	
to F14	
to OV	(common)
to F1	
to +5V	(supply)

With S3 set to give a logic 1 (count up), depress S2 to reset the counter (D1 to D4 will all become immediately extinguished indicating a count of '0000'). After releasing S2, a normal 4bit binary count will be produced with D1 indicating the most significant bit (MSB) and D4 the least significant bit





Fig, 1.4 (above). Up/down counter using a 74193

(LSB). Readers should confirm that all changes of state take place on the falling edge of the clock input.

On the second counting sequence, allow the count to proceed to, say, '1000' and then depress S3 to generate a logic 0 on the direction input. On the next falling clock pulse, the count should be decremented (to '0111') and should then continue to count down. It should also be noted that, at any time, the output can be cleared by means of S2.

DECADE COUNTERS

Counters which have ten states in their counting sequence are particularly useful in a number of applica-

tions, most obvious of which is the counting of digital pulses prior to display. Whilst decade counters can be built using standard J-K bistables together with some additional logic, several TTL devices have been designed to fulfil this need. The most common example of an asynchronous TTL decade counter is the 7490 and we shall continue by investigating a variety of decade counter stages based on this particular device.

7490 DECADE COUNTER

The 7490 is a 4-bit decade counter comprising four master-slave bistables internally connected to provide separate divide-by-two and divide-byfive sections. Each section has a separate clock input which causes a change of state on falling clock transitions. Due to internal ripple delays, state changes of the Q outputs do not occur simultaneously and thus decoded output signals are unfortunately susceptible to unwanted spikes.

An AND gated master reset is provided to clear all the bistable elements regardless of the state of the clock. A similar AND gated master set (MS1, MS2) is provided in order to set the output state to nine (binary 1001).

Since the output from the divide-bytwo section is not internally connected to the succeeding stages, the device may be operated in various counting modes. In a BCD (8421) counter, the CP1 input must be externally connected to the QO output. The CPO input receives the incoming count producing a BCD count sequence. In a symmetrical bi-quinary divide-by-ten counter, the Q3 output must be connected externally to the CPO input. The input count is then applied to the CP1 input and a divide-by-ten square wave is obtained at output QO. To operate as a divide-by-two and a divide-by-five counter, no external interconnections

SEQUENTIAL LOGIC

are required. The first bistable is used as a binary divider (\overline{CPO} as the input and QO as the output). The $\overline{CP1}$ input is then used to obtain divide-by-five operation at the Q3 output.

The internal logic and pin connections for the 7490 are shown in Figs. 1.5 and 1.6 respectively. The truth table for the master set and reset inputs is shown in Table 1.1 whilst the <u>BCD</u> counting sequence (QO linked to <u>CP1</u>) is illustrated in Table 1.2. The timing diagram for the BCD outputs of the counter is illustrated in Fig. 1.7.

The operation of a 7490 can be investigated by inserting the device into socket A of the Logic Tutor (checking, as usual, that pin-1 aligns with A1) and making the following connections:----

A1	to A14	(CP1)
A2.	to A3	-
A3	to S3	(reset)
A5	to +5∨	(supply)
A6	to A7	
A7	to S4	(set)
A10	to D2	(D2 indicates the state
		of the Q2 output)
A11	to D3	(D3 indicates the state
		of the Q1 output)
A12	to OV	(common)



PE15866





Fig. 1.5. Internal logic of the 7490

A13 to D1	(D1 indicates the state
	of the Q3 output)
A14 to D4	(D4 indicates the state
	of the QO output)

A16 to clock (A total of 12 links)

S4 and S3 should be initially adjusted to produce logic 0 inputs on the set and reset inputs respectively. The count should now cycle continuously through the states shown in Table 1.2. A logic 1 on S3 should immediately set all of the outputs to zero (an output state of '0000') whilst a logic 1 on S4 should set the count to nine (an output state of '1001').

Ma	aster R Inp	leset/: uts	Set		Out	puts	5
MR1	MR2	MS1	MS2	03	02	Q1	0.0
1	1	0	X	0	0	0	0
1	1	X	0	.0	0	0	0
Х	X	1	1	1	0	0	1
0	Х	0	1		co	unt	
X	0	Х	0		CO	unt	
0	X	X	0		CO	unt	
X	0	0	X		co	unt	

(X=don't care)

Table 1.1.Truth table for theset and reset inputs of a 7490



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Fig. 1.7. Timing diagram for the BCD outputs of a 7490



Fig. 1.8. Simple BCD counter using a 7490

COUNT STATE		Ουτ	PUTS	
(I/P clock pulse)	03	0.2	01	0.0
0	0	0	0	0
1	0	0	0	1
2	0	0	1	0
3	0	0	1	1
4	0	1	0	0
5	0	1	0	1
6	0	1	1	0
7	0	1	1	1
8	1	0	0	0
9	1	0	0	1

(QO connected to CP1)

Table1.2.BCDcountingsequence for the 7490

An obvious disadvantage of this simple decade counter is that the output stage is displayed in binary form, hence we shall now turn our attention to producing a display in conventional denary form.

SEVEN SEGMENT DISPLAYS

The normal format and pin connections for a common anode sevensegment display is shown in Fig. 1.9. It should be noted that the segments are labelled a to g and that, with a common anode display, it is necessary for these inputs to be taken low in order that the display is illuminated.

In order to illuminate a particular segment, a current of typically 20mA needs to be supplied. This is usually achieved by taking the common anode to the +5V rail, whilst the seven seqments are each connected in series with a resistor of 150 ohms or so. A typical arrangement is shown in Fig. 1.10. A logic 1 (high) applied to any particular segment line will not forward bias the l.e.d. concerned into conduction. A logic O (low), on the other hand, causes current to flow, the value of current being dependent on the forward characteristic of the l.e.d. and the value of series connected resistance.

Before proceeding further, readers may like to confirm that the sevensegment display is functional by 'hardwiring' it to produce various patterns. The display used MUST be of the common anode variety (common cathode displays are also available) and should be inserted into the d.i.l. socket marked C on the Logic Tutor. The device should be oriented so that pin-1 aligns with C1 and segment a is uppermost. (Note that pins C8 and C9 are unused).

Rather than use seven individual series connected resistors, a 14-pin



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Fig. 1.11. Typical seven-segment display output



Fig. 1.10. Typical arrangement for driving a seven-segment I.e.d. display

d.i.l. 150 ohm resistor network may be employed to limit the segment currents. This should be inserted into d.i.l. socket B, again ensuring that pin-1 aligns with B1. Where readers have difficulty in obtaining such a network, seven 0.25W 150 ohm resistors may be connected from B1 to B16, B2 to B15, B3 to B14, and so on, ending with B7 to B10.

The following links should be made on the Logic Tutor:----

-	
B16 to C1	(cathode a)
B15 to C15	(cathode b)
B14 to C12	(cathode c)
B13 to C10	(cathode d)
B12 to C7	(cathode e)
B11 to C2	(cathode f)
B10 to C13	(cathode g)
C16 to +5V	(common anode)
C3 to +5V	

(A total of 9 links)

The arrangement now conforms to the circuit shown in Fig. 1.10 in which each segment has its own 150 ohm series resistor terminated at B1 to B7 for segments a to g respectively. Now connect a link from OV to B1 and check that segment a becomes illuminated, then repeat for each of the other segments in turn.

Having checked that each individual segment of the display is operational, it

is worth demonstrating that we can use the 'hard-wiring' technique to provide any particular indication that we may require. If, for example, a '2' is required, we should arrange for segments a, b, d, e, and g to be illuminated. This is achieved by linking B1, B2, B4, B5 and B7 to OV. The resulting display should be similar to that shown in Fig. 1.11.

Hard-wiring of displays is fine if the indication is never to be changed. In most practical applications this is not, of course, the case. Usually the display is used to indicate the state of a count and we thus need some arrangement which can accept a binary coded decimal (BCD) input and provide the required decoding logic to illuminate the appropriate I.e.d. segments. Fortunately, several TTI devices are available which are designed to fulfil this particular need.

Constructor's Note

Logic Tutor Board p.c.b's, components and constructional details are available from Howard Associates, 59 Oatlands Avenue, Weybridge, Surrey KT13 9SU (0932 42376).

NEXT MONTH: Decade counters.

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PART 2

AST month we looked at the basic features of floppy disc drives. This month we continue by looking at some of the options which are often available to buyers. Most of these are not so much a feature of the drives themselves, but more of the way in which they are packaged for sale. If this seems a rather mundane point, it is worth bearing in mind that the difference in price between two 'bare' drives and a twindrive package can easily exceed £100! Before buying, therefore, it is a good idea to be sure that you are getting all that you need, but not paying for what you neither want nor need.

The 5.25" floppy disc drive packages available today usually (but not always) contain drive units of Japanese origin. High reliability and excellent value for money result from high volume production since this allows the very latest in floppy disc and manufacturing technology to be applied. Indeed, the floppy disc drive market is now so competitive that this must be done in order for the manufacturers to remain in business. Typical drive units currently on the market come from TEC, TEAC, Mitsubishi, Hitachi, Tandon, Canon and Shugart, to name but a few of the more popular makes.

When we are looking for a floppy disc unit to connect to our computer system, we usually want a little more than just the bare drives. We will begin, therefore, by looking at the additional features which may be appropriate for us to consider.

POWER SUPPLIES

Floppy disc drives are invariably designed to be operated from an external power supply, rather than directly from the mains. Modern drives typically require d.c. power at +5 volts and at +12 volts. The +12 volt supply is normally used to drive the rotational motor, the stepping motor and part of the read/write circuitry. The +5 volt supply, on the other hand, powers the remainder of the read/write circuitry and the logic circuits. Power requirements are now fairly modest; the M4853 half-height Mitsubishi drive, for example, requires 0.5 to 0.7 amps at +5 volts, and 0.5 to 1.0 amps at +12 volts. Supply current requirements, however, continue to fall with the use of more advanced technology. The latest TEAC FD-55 drives, for example, require only 4.9W when operating, and only 1.6W in standby mode.

Some computers have power supplies which are capable

of powering one or two floppy disc drives. The BBC Micro. for example, is capable of supplying external equipment with up to 1.25 amps at +5 volts and 1.25 amps at +12 volts. Thus, we can often use the internal power supply when using discs with the BBC Micro. However, even where the computer is able to supply power for the disc drives, a separate supply is often still preferred. This is because a separate supply keeps the load on the computer's power supply to a minimum, allowing it to run cooler and leaving the spare supply capacity free for other uses. Another advantage of a separate power supply is that it gives the system the greatest flexibility, since the disc unit is then selfcontained. Many computers, however, do not offer the option of using the internal power supply, and then we are left to provide an external power supply. The additional cost of a disc power supply will usually be around £30-£40.

rea

Although it is possible to build your own disc drive power supply, it is usually much easier to buy one which has been specially designed for disc drive applications. Power supply units of this type now commonly employ switched-mode designs. These are compact, efficient and light-weight, are usually installed in the case of the disc drive(s), and are almost always capable of powering two 5.25" drives. A point to check in a packaged unit is that the supply is fully wired, complete with a mains switch, fuse and 3-core lead.

If you are putting together your own disc drive package. however, it will be necessary to obtain a suitable power supply. This should preferably be a fully-shrouded unit, but an open-chassis supply may be used provided that all points at mains potential are safely protected to avoid electric shock risk. In addition to the power supply, a two-pole mains switch, warning neon and mains fuse will also be required. The mains lead should be 3-core, and secured to the case with a cable clamp (not knotted!), and protected with a grommet. You will also need to provide d.c. power leads between the power supply and the drive(s). These leads should be suitably rated for the expected maximum supply current, and it will be necessary to obtain the appropriate power connectors to suit the drive(s) being used. Typically the power connector is a 4-pin type, but unfortunately there is little or no standardisation at present. Fig. 1 shows a typical power connector as found on Mitsubishi M4852 and M4853 drives. In addition to the power leads, a further lead is required to securely bond the chassis of each drive to a common mains earth terminal; a suitable bonding point is usually provided on the drive's chassis for this putpose. Where a metal case is being used, this should also be bonded securely to the common earth terminal.

F	_				_	
q		1	2	3	4	
	1: 2: 3:	+ 12 \ OV (OV (/.d.c. +12V R +5V R	ETURN).	

Fig. 1. Mitsubishi disc drive power connector

CASES

As we have mentioned, the disc drives produced by the drive manufacturers are bare drives and nothing more. They are produced with a front panel which is usually styled and suitable for mounting in an equipment cabinet or in a case of their own. The basic drive, however, is usually of an open chassis construction, with the electrical connections (disc interface bus and power) at the rear. To prevent the intrusion of foreign bodies (biscuit crumbs, dust, electronic components, children's fingers, etc.) into the delicate workings of the drive mechanics, therefore, a case becomes an essential addition. Any power supply can then also be mounted safely out of harm's way inside the same case.

With the market now increasingly dominated by halfheight drives, we usually consider twin-drive arrangements when thinking of cases. This is usually true even if funds dictate that our initial purchase is of one rather than two drives. Adding a second drive to a case bought with this upgrade in mind will usually be neater, easier and cheaper in the long term. Thus we can start with a twin case which is fitted with a single drive (and possibly a power supply), and upgrade to a second drive at a later date.

There is usually a choice of mechanical arrangements for two half-height drives; side-by-side or vertically stacked, as shown in Fig. 2. One arrangement may be more convenient than the other, but either way, the drives themselves are usually mounted horizontally. The side-by-side arrangement can be very convenient if bench space is at a premium; the computer may be situated below a 'perch' which supports the drives, with the monitor/TV on top of the disc unit. This can have the added advantage of raising the monitor/TV to a more comfortable height. Alternatively, the computer may rest on the drives, with the monitor/TV above.



Fig. 2. Twin drive configurations

If making your own case, it is important to make sure that adequate ventilation is provided. The amount necessary will depend on the efficiency of the power supply (usually quite high with switched-mode designs, and hence there is little waste heat generated), and the power consumed by the disc drives themselves. Ventilation slots should be carefully positioned to minimise the possibility of unwanted objects falling into them, and they should be small enough to keep out even the smallest of probing fingers. One approach to the problem is to provide slots on the base of the case, with

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exit slots on the sides near the top of the case. Provided that the case is then mounted on suitable feet, this arrangement is usually more than adequate. With the very low power drives, it may be possible to dispense with ventilation slots altogether, provided that a metal case is used; waste heat is then removed by conduction. Any case should provide substantial and secure mountings for the drives and power supply. On vertically stacked units, it is usually necessary to provide a heavy gauge spacer bracket to separate the two drives to allow free air circulation.

In conclusion, the disc unit's case should be considered as the first line of defence against the attentions of dirt and the hardships of the computer workplace. It may also affect how easy the drives are to use, and consequently careful consideration should be given to the design of the disc case.

CABLES

Connecting the newly acquired disc drives to the computer can be an unexpectedly expensive and/or confusing business. If we buy a package tailored for a particular computer, then all this should already have been sorted out by the supplier, but watch out for an additional charge for the cables. Typically a twin-disc cable may cost around £10 to £15, mostly as a result of the cost of the connectors. As for the complete cables themselves, there is often quite some confusion regarding how they should be connected.

The signals on the standard disc interface bus were shown in Table 2 last month. Each of these signals is driven either from the drive to the computer, or from the computer to the drive. The disc interface bus uses open-collector gates for driving these signals, and the general arrangement for each signal is as shown in Fig. 3. The open-collector signals must each be terminated by a resistor at the receiving end (as shown in Fig. 3). If this is not done, the signal on the line swings only a few mV when changing state between logic 0 and logic 1. The bus should, however, only be terminated at one of the drives; the disc manual should indicate how to select whether a particular drive terminates the bus or not.



Each signal in the bus goes to all of the drives connected to the bus, using the so-called 'daisy-chain' arrangement, as shown in Fig. 4. The normal arrangement is to use a flat 34way ribbon cable, with the appropriate number of drive connectors (usually of the insulation displacement type) fitted at suitable intervals along the cable. The connectors then fit onto the data connectors at the rear of each drive. As already mentioned, the bus should only be terminated once, and this should be done at the drive which is furthest away from the computer, i.e. last on the lead. If buying only a single drive initially, it is worth buying a twin-drive cable, since this will be required eventually and will work just as well with only one drive connected, provided this uses the last connector on the cable.



Fig. 4. Daisy-chain disc cable arrangement

At any given instant, only the drive identified by the drive select signals (pins 6/10/12/14) takes any notice of the signals on the bus. The drives must thus each be able to identify themselves. This is normally achieved by setting up links in each drive; a procedure which should be fully described in the drive manual. Needless to say, we can expect that setting two drives to the same identity will cause all manner of problems! Drives are typically numbered starting from zero, and a twin drive unit will thus usually have its two drives set up as 0 and 1. The numbering of the drives does not need to bear any relationship to their physical order of connection on the cable, and can be done purely for our own convenience. It is a good idea, however, to label the drives after set-up, otherwise confusion may well result!

OTHER EXTRAS

There are a few remaining points which mustn't be overlooked when completing the shopping list for the disc unit 'package'. Assuming that the computer has already been upgraded, some of the other items needed are: Blank discs Manual Formatter

When buying blank discs, it is well worth buying only good quality types. There is nothing worse than losing valuable software due to unreliable discs; learning the lesson of false economy the hard way is no fun! Do not be tempted to use single-sided discs for double-sided applications; although they will usually work satisfactorily, the second side (the top) is not guaranteed to be reliable. A good start is to buy a box of ten double-sided double-density 80-track discs; this will encourage the keeping of backup copies, initially at least, and the discs will be suitable for all future applications. In addition to the discs themselves, it is also a good idea to invest in a suitable disc storage case to protect the discs when not in use.

A manual is essential for getting the maximum benefit out of your floppy disc drives. In addition, it will usually be necessary to refer to the DFS software documentation when setting up for the first time. It is always worth checking that adequate documentation is provided with the drive unit before taking delivery. There is nothing worse than having to make a second trip to collect the missing data, particularly if there is an additional charge involved.

The final item on the list is actually a piece of software; the formatting program. This is often supplied on a disc, itself already formatted, and it must be suitable for your particular computer system. In many cases, the formatter is supplied with the DFS software, but this is not always the case.

FINALLY

So, the great day has finally arrived and the floppy disc drives have come to the top of the shopping list. The discussion above and last month's article should allow you to put together a list of points to consider when choosing a drive unit for your system. It is often easier to buy a complete package, but you may prefer to build up your own, at least in part. In either case, make sure you know what you need, and then shop around for the best value. The buyer's guide should help you by providing a selection from the currently available models. The glossary summarises the meaning of some of the terms involved. Next month we shall be reviewing some of the drives mentioned in the buyer's guide.

GLOSSARY

Catalogue

The area of the disc used by the disc filing system (DFS or DOS) to record the names, locations and various status information relating to files stored on the disc. Sometimes known as the disc directory.

Disc interface

The hardware in the computer which provides the interface between the computer's CPU and the disc drives themselves.

Double density

A method of recording data which uses a higher data rate and the MFM recording technique to double the disc's data storage capacity when compared to single density recording.

FDC

The Floppy Disc Controller Chip (FDC) is the LSI integrated circuit which is usually at the heart of the disc interface in the computer. The FDC provides most of the detailed control functions in the interface.

Formatter

A program used to lay down the basic track, sector and catalogue structure on a previously blank disc.

Head load time

The time taken for the read/write head(s) to be brought into contact and settle on the disc surface. Typically around 50msec.

Motor start time

The time taken for the rotational motor to run up to full speed (300 r.p.m.) after commanded to do so by the computer. Typically around 250msec.

Sector

The basic unit of data which is read from or written to a floppy disc is a sector. All data transfers to/from a disc involve one or more complete sectors. A sector, sometimes known as a block, is usually 256 bytes.

Settling time

The time which must be allowed after a read/write head movement before data may be read or written. Typically around 15msec.

Single density

The basic method of recording data on the disc surface using FM encoding. This usually provides 2560 bytes on each track.

Step time

The time taken for the read/write head(s) to move from the current track position to an adjacent track position. Typically a figure in the range 3 to 25msec. Also known as the track-to-track seek time.

Track

A circular magnetic track laid down on the recording surface of a floppy disc, and used for the storage of data. Typically there are 40 or 80 tracks on one side of a disc.

The Teac FD55F from Viglen is one of five models in the FD55 series. They are all 5-25in., half-height drives with capacities which vary from 125K to 1.6Mbytes. The 55F is a 40/80 track switchable, doublesided, single drive unit with a 400K capacity and is priced at £225. Viglen Computer Supplies, Unit 7, Trumpers Way, London W7 20A.

The CDC 9428 and 9429 5.25in. half-height disc drives provide 500K or 1 Mbytes of storage respectively. The 9428 is a 40 track, double-sided drive (price on application), whilst the 9429 is an 80 track, double-sided, double-density drive (price on application). Control Data Ltd., 179/199 Shaftesbury Avenue, London WC2 8AR. (01-240 3400)

FRIS Vide has to drive 'HIS Buyer's Guide has been designed to show the wide range of disc drive units currently available. The important points to look for when considering which particular drive to purchase are difficult to list in order of importance because they will depend greatly upon your own personal requirements, i.e. in certain cases the physical size may be more important than the actual weight or an integral p.s.u. may be more important than whether the drive is 40 or 80 track.

However, no matter what your own personal requirements are, all the following points should be borne in mind when considering any disc drive to ensure you understand exactly what you are buying:

- 1) The size of the discs to be used in the drive, i.e. 8in., 5.25in., 3.5in. or 3in.
- 2) Whether the drive is a single or dual unit.
- 3) If the drives are dual, are they mounted side by side or one above the other?
- 4) Is a p.s.u. included or housed separately?
- 5) Can your computer's p.s.u. support the drives if a p.s.u. is not supplied?
- 6) Is the drive unit cased or not?
- 7) Is the drive half or full height?
- 8) Is a manual supplied with the drive?
- 9) Are the cables and formatter disc supplied and are they compatible with your computer?
- 10) Is the drive 40 or 80 track?
- 11) What is the capacity of the drive?
- 12) What is the physical size and weight? and, finally, what is the PRICE?

Although we cannot cover all these points in our guide we have given as much information as possible, together with addresses and phone numbers where a full specification on the drives mentioned can be obtained. (Prices include VAT).

The Hitachi HFD range from Datafax have unformatted capacities of 500K, 1M and 1.6Mbytes with the HFD510 being a 5.25in. double-sided, half-height, with 80 tracks and a 1Mbyte capacity, priced at £210. The Datafax range also includes the 3.5in. drives from Epson and the 3in. range from Hitachi. Full details from: Datafax Systems Ltd., Datafax House, Bounty Road, Basingstoke, Hants RG21 3BZ. (0256 64187)

The Teac FD35 series of 3.5in. drives from Tekdata are a condensed version of the FD55 series and are fully compatible. There are 8 models in the range offering capacities from 250K to 1Mbyte. The FD35B is a 500K capacity 80 track, double-sided drive, priced at £159. Tekdata Electronics, Federation Road, Burslem, Stoke-on-Trent ST6 4HY. (0782 813631)



The Watford Electronics disc drive range includes the CLS 100 which is a cased, single-sided, 40 track, 100K, 5.25in. drive, without a p.s.u.; the CLS 400, a double-sided, 80 track, 400K drive and the CLS 400/S a 40/80 track switchable 400K unit. All three of these units are also available as dual drives and all six units can be supplied with integral p.s.u.'s. Cables are also BBC micro with all drives.

The prices of the range vary from £115 for the CLS 100 to £395 for the

115 for the CLS
 0 £395 for the
 CDB00 which is a cased, dual drive with 800K storage, double-sided, 80 track unit.
 CDB00 which is a cased, dual drive Electronics, Dept PE, Cardiff Road, Watford, For further details: Watford Electronics, Dept PE, Cardiff Road, Watford, Herts. (0923 37774)

The Micronix range of 5.25in. drives are supplied complete with a DFS manual, formatter disc and disc drive cable. The MX150 is a 100K, 40 track, single-sided drive (£170.20), and the MX151 is a 200K, 40 track, double-sided drive (£216.20); the MX152 is a 400K, 80 track, double-sided drive (£238). Micronix Computers Ltd., Suite 2, 26 Charing Cross Road, London WC2. (01-240 0213)

Gmicronia

The Teac FD30A (shown centre in photograph) is a 3in., 100K, single-sided drive, and is fully compatible with Teac's 5-25in. drives. The actual floppy disc used in the 30A is stored in a hard case, not the soft sleeve used by other floppy discs. This makes loading more positive and reduces the disc's susceptibility to damage by handling. The FD30A is priced at £159 and is available from Viglen Computer Supplies, Unit 7, Trumpers Way, London W7 20A. (01-843 9903)

The FD55G from Tekdata is the latest addition to their range. It is a doublesided, BO track unit, with a capacity of 1.6Mbytes, and is priced at £200. **Tekdata Electronics,** Federation Road, Burslem, Stoke-on-Trent ST6 4HY. (0782 813631)





The Cumana range of disc drives include the CD200K: a 40 track, single-sided drive with 200K of memory. The CD400K: an 80 track, single-sided drive with 400K of memory. The CD400/S: a 40/80 track, single-sided drive. The CD800/S: a double-sided version of the 400/S; and the CD400/D, a 40 track, double-sided drive with 400K of memory. Prices for the drives vary from £350 to £575. Cumana Ltd., Unit 1, The Pines Industrial Estate, Broad Street, Guildford GU3 3BH. (0483 503121)

MAIL ORDER MICROS

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SS 40TK 100K

Make no mistake, these are the very latest halfheight drives from TEAC — world leaders in high performance, high reliability 51/4 inch* floppy disk technology. They come complete with Formatting Disk, User Manual, Case, and Cables for direct connection to the Model 'B' with DFS disk interface and with a FULL TWELVE MONTH GUARANTEE.

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*3 inch versions also available; please ring for details.

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Enquiries from Dealers and Educational Authorities welcomed.

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FD-55E*	SS 80TK 200K	(£198·95)	£129.95		
FD-55F*	DS 80TK 400K	(£240·35)	£158·70		
DUAL DRI	VES				
FD-55A	SS 40TK 200K	(£319·70)	£201-25		
FD-55B	DS40TK400K	(£389·85)	£241.50		
FD-55E*	SS 80TK 400K	(£374 · 90)	£241.50		
FD-55F*	DS 80TK 800K	(£458·85)	£297 85		
DUAL DRI	VES (with integra	(power supply)			
FD-55A	SS 40TK 200K	(£428 · 95)	£289 · 80		
FD-55B	DS 40TK 400K	(£499·10)	£331·20		
FD-55E*	SS 80TK 400K	(£486·45)	£332·35		
FD-55F*	DS 80TK 800K	(£569·25)	£387 · 55		
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The CD55FS from Technomatic is a 5.25in. dual drive disc unit with a maximum 800K storage (2 x 400K switchable drives), incorporating double-sided discs. Each drive is separately switchable between 40 track and 80 track via a hardware switch. This unit has a built-in p.s.u. with mains switch and is supplied with a manual, formatter disc, connector cables and a 13A mains plug. Price £483; Technomatic Ltd., 305 Edgware Road, London NW10. (01-723 0233)



The MX1350 is a single 3-5in. drive from Micronix, it will provide a capacity of 100Kbytes of storage; a dual unit, the (MX2350) is also available with a 200Kbyte storage capability. Both these units are 40 track and are single-sided, and are boxed in metal housings, supplied complete with power cable, disc drive cable, formatter disc and DFS manual. Prices respectively are £181.70 and £353.05. Micronix Computers Ltd., Suite 2, 26 Charing Cross Road, London WC2. (01-240

Internal photograph of the Cumana full-height unit with integral power supply. Cumana Ltd., Unit 1, The Pines Trading Estate, Broad Street, Guildford, Surrey GU3 3BH. (0483 50312)



Mail Order Micros supply a range of twelve disc drives for use with the BBC micro. The units are available with integral p.s.u.'s in dual stacked or dual flat versions or, without a p.s.u. in a dual stacked version. All versions are supplied with formatting/utility disc and manual. Disc capacities are from 200K, 40 track, single-sided drives to 800K, 80 track, double-sided units. Mail Order Micros, 2a Green Street, Sandbach, Cheshire CW11 9AX. (0782 811711)

> The HFD 305's from Datafax have been designed for use with the new 3in. compact floppy disc by Maxell; two units \are available in this range-the 305(S) a single drive and the 305(D) a dual drive. Storage capacity is from 125Kbytes (single density-single drive) to 500Kbytes (double density-dual drive). Supplied with formatter disc, cables and manual, these units are respectively priced at £155 and £180. Datafax Systems Ltd., Datafax House, Bounty Road, Basingstoke, Hants RG21 3BZ. (0256 64187)

The TRK1 from Tech OP Ltd is a dual 5-25in. drive unit offering 800Kbytes storage on 80 track, single-sided discs. The TRK2 will provide 1600Kbytes of storage using 80 track, double-sided discs. These half-size units are supplied with full documentation, all connectors and a formatting and utilities disc for BBC B micros. Prices respectively are £275 and £349. Tech OP Ltd., 19 Rodney Road, Cheltenham. (0242 570999)





The XLtron drive is a BBC compatible, half-height, single or doublesided drive complete with an interconnecting cable and manual. The single drive is priced at £150, and the double-sided drive at £166. **Disco Technology Ltd.,** 20 Orange Street, London WC2H 7ED. (01-930 1612)



The 3in. drives from Mail Order Micros are available in single or dual units. They are supplied with leads and connectors, formatting/utility disc and a manual. The drives can be powered from the p.s.u. of the BBC micro. The single drive has 80 tracks and a 200Kbytes capacity, whilst the dual drive has a 400Kbytes capacity. Mail Order Micros. (Address below.)





Ah internal view of a standard height disc drive showing the drive belt arrangement. (Courtesy of Cumana Ltd.)

The MX252 from Micronix is an 800K dual, 5.25in., 80 track, double-sided drive, priced at £492. It is shown alongside the MX-130 which is a 100K 3in. single-sided, 40 track unit, priced at £181.70. Both units are supplied complete with drive cables, formatter and DFS manual. **Micronix Computers Ltd.**, Suite 2, Charing Cross Road, London WC2. (01-240 0213)



The Shugart SA300 from Mail Order Micros is 3.5in., singlesided microfloppy drive with 40 tracks and 500K memory capacity. The drive is compatible with 5.25in. units and is available in either a single or dual drive configuration. A formatter, instruction manual and connecting cables are supplied. The single drive is priced at £102.35, and the dual unit at £201.28. Mail Order Micros, 2a Green Street, Sandbach, Cheshire CW11 9AX. (0782 811711)



The 350 1Mbyte floppy disc drive from Shugart is a $3 \cdot 5in$, double-density, single drive unit with 80 tracks. The drive is supplied complete with a formatter disc, manual and interconnecting leads. Mail Order Micros. (Address left.)

and MICROPROMPT

80 REM

Appearing every month, Micro-Bus now presents ideas, applications and programs for the most popular microcomputers and all micro-related projects so far published in PE. Ideas must be original, and payment will be made for any contribution featured.

SPECTRUM "CLOUSEAU"

Sir-"'Clouseau" is a cheap, reliable, extremely sensitive, acoustic burglar alarm system for the ZX Spectrum. Clouseau requires no soldering, and, in the case of the BASIC system, no knowledge of electronics. Clouseau works by taking the input from the EAR socket, and checking to see if there is any noise indicating, perhaps, a burglar.

Clouseau can also be used as a baby minding device, indicating when the baby, being monitored, makes any noise.

Clouseau is extremely sensitive, and networks of microphones can be set up, allowing more than one room to be monitored at a time.

The IN command on the Spectrum is used for reading the values at the Spectrum's I/O ports. These are not merely for the connections on the back edgeconnector of the computer, but also for reading data from the keyboard, and EAR connector.

The value from the EAR socket is read with the line.

LET A = IN 65022

The value at the EAR socket is determined by what the computer can hear at the socket. When there is no noise at the connection, a value of 255 is returned. However, if there is any noise at all, the value read will be different.

It is, by connecting a system of leads, amplifier, tape recorder, and microphones to this connector, that a simple, but very sensitive Burglar Alarm/Child Minder experiment can be constructed.

For the basic system of one monitoring station, you will need:

The set-up shown in Fig. 1, and run the program with the tape recorder in RECORD mode. To do this, without a tape in, you will need to manually press down the erase protection detector tab at the rear left hand corner of the cassette receptacie.

More microphones can be added in series or parallel, but Ohm's law must be followed. If the original resistance is 8 ohms, then the final resistance of the microphone network must be 8 ohms.

A suitable sound amplifier can be purchased from many high street outlets, or

the hi-fi system may be used.

MICRO---

The microphone with your cassette recorder will do. Most are compatible, but, just in case, check in your cassette recorder manual. The extra lead can be bought from specialist electronic shops or by mail order. The amplifier is required to make the Spectrum's BEEP loud enough to be used as an alarm.

The program gives an e.c.g. type printout of the trace from the EAR socket, on the T.V. screen. The alarm sounds when any noise is heard. A time delay is included so that you can set the alarm, and leave the room before the system activates. The sensitivity depends upon the volume setting of the cassette recorder.

	West Sussex.
IØ REM -	
20 REM	
3Ø REM	CLOUSEAU
40 REM -	
50 REM	
60 REM	Intruder Alarm V 1.0
70 REM	

David Harrison,

Burgess Hill,

90 REM © David Harrison 1983 100 REM 110 BORDER Ø: PAPER Ø: INK 7:8 **RIGHT 1: FLASH Ø: CLS** 120 GO SUB 280 130 LET A = 100140 PLOT Ø,A 150 FOR N=0 TO 252 STEP 2 160 LET EAR=(IN 65022)/2 170 DRAW 2, A-EAR 180 IF EAR <> 255/2 THEN GO SUB 2 2Ø 190 LET A=EAR 200 NEXT N 210 CLS : GO TO 130 220 REM HEARD A NOISE 230 FLASH 1: INK 2: BORDER 2: PAPER 2: INK 7: CLS 0: 240 PRINT AT 8 INTRUDE R' 250 PRINT AT 12,0; " A T " L E R 26Ø BEEP 1.5, 45 270 GO TO 260 280 REM TIME DELAY 29Ø INPUT "Time Delay in Seconds"; TD 300 PAUSE TO*50 **310 RETURN**





A DESIGN BY POWERTRAN CYBERNETICS

NTRUDER alarm systems fall into several distinct categories as far as the actual detection is concerned. These can be summarised generally as follows:

a) HARD WIRED

Hard wired systems where doors, windows and other entry points are wired to a central control unit. Magnetic switches and magnets, either surface mounting or flush mounting types, are positioned so that the contacts break as the door or window is opened. Pressure mats may also be placed at strategic points on stairs or landings. These are normally open contact devices where the pressure of a person's foot will make the contact.

b) ULTRASONIC

These sensors are usually self contained in one small box which can be conveniently mounted high on a wall covering the area to be protected. Ultrasonic sound waves are generated in one head and a similar head 'listens' to the sound pattern generated within the protected area. If he pattern remains constant no output appears from the receiver head and associated electronics. If a disturbance occurs in the protected area the received signal changes and the change is amplified and used to trigger the alarm circ ait. The ultrasonic system is very sensitive and is affected by draughts or anything causing air movement.

c) INFRA-RED

i) Active Infra-Red

An infra-red emitter is arranged within a housing for its energy to be collimated by a lens to provide a narrow beam. An infra-red detector in a similar housing is positioned to intercept the transmitter beam, thus providing a signal all the while the beam remains unbroken. The system can be made very robust and is suitable for inside or outside use. The beam is invisible and unaffected by sunlight or other outside influences and responds instantly to passage of an object through the beam. The transmitter and receiver can be mounted in the same housing with energy transfer accomplished using an optical reflector of the multi face type similar to a cycle reflector.

ii) Passive Infra-Red

POWERTRAN

DRA 100 .

The Passive infra-red detector uses a pyro-electric element of doped ceramic, sensitive to infra-red (heat) radiation. This produces an electrical output when there is a change in the amount of infra-red radiation striking the sensitive area. Physically, the detector, in its wallmounted housing, 'looks' at the area of coverage through an infra-red filter and an infra-red opaque grid which has the effect of allowing infra-red radiation from objects within 'windows' to fall on the detector. If an infra-red source (intruder) passes across these windows the detector plays 'now you see me, now you don't' with the result that the intruder causes several sudden changes in the level of radiation reaching the detector any of which are used to trigger the alarm system.

d) RADIO DETECTION

This usually takes the form of a module emitting radio energy in the 10 Giga Hertz region. The active element is a Gunn diode in a self-oscillating circuit which is tuned by the cavity in which it is located. The energy is directed to the area to be protected by the antenna and an adjacent cavity contains the detector diode. This, in a similar manner to the ultrasonic unit, reacts to movement within the protected area by producing an output from the detector at the Doppler fre-

SECURITY PROJECT



Fig. 1. Schematic diagram of the complete unit

quency caused by the movement of the intruder.

The system described here is a Doppler Radar Alarm which can be made by the home constructor from readily available components.

HOW IT WORKS

The oscillator frequency is generated on the oscillator (lower) printed circuit board and radio frequency energy is transferred to the detector (upper) board by the proximity of the two loops. One end of the upper loop is connected to the system ground (0 volts) and the other end is connected directly to the antenna. The mid point of the antenna loop is connected via the detector and diode D101, to C104. If the transmitted energy is represented by Pt and energy reflected from nearby objects back to the antenna is represented by Pr then the signal presented to the detector is the vector sum of Pt + Pr where the frequencies are the same but the relative phases are different, hence a steady d.c. level appears across C104. If a moving target enters the area an additional component within Pr appears at the detector due to the Doppler frequency shift. It is this shift which causes the d.c. level on C104 to vary at a frequency equal to the difference between the transmitted signal and the reflected signalwhich for a man size target moving at 1m,p.h. (1.5 feet per second) is about 1 cycle per second. Hence under steady state conditions the detected d.c. level will not pass through the a.c. coupled signal amplifier but the 1Hz Doppler signal will.

UHF OSCILLATOR

The critical frequency determining components of the



Fig. 2. Oscillator/Detector circuit

UHF oscillator are formed by the printed circuit wiring. The dimensions of the main centre tapped loop form the tuned circuit for the oscillator. The transistors are BFY90 devices which oscillate satisfactorily at the working frequency. The remaining components are feedback and decoupling capacitors and biasing resistors.

The antenna pick-off coil is positioned on a second p.c.b. mounted parallel to the oscillator board and spaced by nuts on the mounting screws. A tapping on the antenna loop is fed to the detector and filter circuit. The complete oscillator/detector unit is coupled to the control box using miniature 2 core screened cable. Up to four detectors can be accommodated by the control box and each detector has its own amplifier and hence the sensitivity of the system is individually controlled on the front panel of the control unit.





POWER SUPPLY

A toroidal transformer is used to derive the low voltage supply from the mains. The mains plug should be fused at 3 amps. This is the only fuse in the primary side of the transformer. The centre tapped secondary is full wave rectified by D1 and D2 and smoothed by C1. R1 is a trickle charge resistor to keep the external back up battery charged. In the event of mains failure the battery will supply the circuits via D3. IC1 provides 12 volts and IC2 provides 9 volts (adjustable by VR1). The 9 volt (nominal) powers the signal amplifiers and the oscillator detector units.

The oscillators are powered via R105 (R205 etc.) and VR1 is adjusted to give a voltage at the junction of R105 and D107 of 8 volts. At this voltage level, D107 will not conduct and D108 in the collector of TR103 will be off.

Should the 2 core cable to the detector be broken the voltage on D107 will rise above 8.2 volts and TR103 conducts to indicate a break.

RF SIGNAL

The RF signal in the antenna coil is detected and filtered to give a standing d.c. voltage at the input of the signal amplifier of about 1.5 volts. A moving object within the operating range of the detector will cause this d.c. level to change at the Doppler frequency which is of the order of 1 cycle per second. The two 741 operational amplifiers are connected as conventional non-inverting amplifiers with selective feedback giving appreciable reduction of gain above 20Hz. This reduces the problem of mains pick up whilst keeping the circuits simple. The output from IC102 is a.c. coupled via C110 to the diode pump circuit comprising D103, D104 and C111. Low leakage capacitors are required throughout the signal amplifier and tantalum bead types are satisfactory. A moving target within the range of a detector produces a low frequency signal and continued movement pumps up' the voltage of C111, this voltage in turn causes the Darlington pair TR104, TR105 to conduct and D109 lights, indicating a moving target. As TR105 collector goes low the signal level is indicated on the VU meter, ME1a.

The earthy side of the VU meter is the signal summing line from all the detectors and if any one goes low IC3a timer is triggered. This is the entry delay timer and the length of delay is controlled by VR2. When the entry timer IC3a is triggered, pin 5 goes high. The positive going edge is differentiated by C5 and D4 with no net change in the status of pin 8 IC3b. At the end of the entry delay period pin 5 goes low and the negative going edge is differentiated by C5, R3 the resulting pulse initiating the alarm time 'ON' timer IC3b. When this is triggered pin 9 IC3b goes high and turns on TR3 energising relay RL1. One pair of relay contacts connect the 12 volt supply to the noise generator circuit comprising IC5a, IC5b and TR4. A separate pair of relay contacts is available on the rear of the control unit for switching an external load such as a latching relay or contactor controlling a flood light or an electric bell. The alarm 'ON' time is controlled by VR3 on the front panel.

IC4a is the exit delay timer whose time is controlled by VR2b (VR2 is a dual gang potentiometer to ensure the exit delay is always at least equal to the entry delay thus preventing triggering of the alarm during the exit period).

The only switch on the front panel is the ALARM ON-OFF switch. When the alarm is switched to the 'OFF' position, pin 6 is grounded causing the output pin 5 to be high. This causes TR2 to conduct with the collector low. The collector is connected to the RESET pins 4 and 10 of IC3a and b thus keeping the entry timer and alarm timer inhibited during the exit period. The alarm signal from pin 9 IC3b also drives TR1 emitter follower. The emitter of TR1 is connected to pin 10 of IC4b. This is connected as an astable timer whose output drives the internal piezo electric bleeper, to give an audible indication that the alarm has been triggered.



Fig. 5. Circuit diagram of the Timing and Delay circuits





Fig. 6. The Noise Generator circuit diagram

NOISE GENERATOR

The Noise Generator uses a dual timer i.c. which produces a wailing high level sound in an 80 re-entrant horn loudspeaker. The output from pin 9 drives a pnp power transistor with the loudspeaker forming the emitter load. The main printed board has an area of copper strips at one end. This is provided to allow extra components to be added if required such as a thyristor and associated components to switch an external load.

The junction of D5 and R12 to +12V is a suitable point to insert personal attack buttons. As the system is powered all the time mains is connected, the PA button will activate the siren as soon as it is operated. If the base connection of TR3 is brought out to the rear panel, this, together with the BATT-VE terminal, forms a useful point for remotely disarming the alarm simply by shorting the base to ground via a

suitable keyswitch. It is important to use the base of TR3 rather than the PA connection on the left hand side of R12 because, if the PA button is pressed while the alarm is switched off at the remote key switch position, a short circuit will appear across the supply.

The only part of the system on the outside of the building is the siren and its enclosure. A high degree of security is obtained if the cable supplying the horn enters the enclosure through the rear of the box straight through the wall so that no cable is exposed. Further protection is afforded if 4 core cable is used with a reed switch/magnet assembly between the lid of the enclosure and the fixed part. The reed switch should be arranged to make contact if the lid containing the magnet is removed. The resulting contact pair is arranged to parallel the PA wiring as described earlier.

COMPONENTS

OSCILLATOR/DETECTOR UNIT

Oscillator/Detector unit and signal amplifier.

NOTE The 4 oscillator/detector units and the 4 signal amplifiers are all identical. The electronic components have a prefix of 100, 200, 300, 400. Only the components of channel 1 are listed.

Resistors

R101	270
R102, R106, R107, R111, R116,	
R118	1k (6 off)
R103	10k
R104	2k7
R105	100
R108	180k
R109, R115	220k (2 off)
R110	270k
R112, R113	330k (2 off)
R114, R117	2k2 (2 off)
All resistors 1W 5%	

Potentiometer

VR101 47k lin (panel mtg)

Capacitors

C101, C102	2p2 ceramic (2 off)
C103	22n
C104	10n
C105	1µ 35V tant
C106	4µ7 10V tant
C107, C109	33n 400V polycarb (2 off

C108	22µ 16V tant
C110, C111	47µ 6.3V tant (2 off)
C112	47µ 10V elect

Semiconductors

D101	OA95
D102-106	1N4148 (4 of
D107 8V2 Zener	BZX61
D108 green I.e.d.	TIL 220
D109 red I.e.d.	TIL 220
TR101, TR102 transistor	BFY90 (2 off)
TR103, TR104, TR105 transistor	BC109 (3 off)
IC101, IC102 op.amp.	741 (2 off)

Miscellaneous

off)



TO DIOI CATHODE

COMPONENTS ...

MAIN PC BOARD Timing Circuits

Resistors

680 1W **R1** R2, R3, R5, R6, R7, R12 1k (6 off) 10k (2 off) R4, R8 18k (2 off) R9, R14 120k (2 off) R10, R15 39k (2 off) R11, R13 5k6 (3 off) R16, R17, R18 270 R19 500R VR1 P.c.b. Trim Pot 100k dual gang pot VR2a,b 100k pot VR3 All resistors 1 W 5%

Capacitors

C1	220 0 µ 25∨
C2, C3	1000µ 16V (2 off)
C4, C6, C7	1000µ 16V elect (3 off)
C5, C13	47µ 16V elect
C8, C10	4µ7 25V elect (2 off)
C9	2n2 polycarb (2 off)
C11	10µ 16V elect
C12	220n 400V polycarb
C14	100µ 25V

Semiconductors

D1,2,3 D4–9 diode D10,11 diode IC1 Voltage regulator IC2 Voltage regulator IC3,4,5 timer TR1,2,3 transistor TR4 power transistor IN4002 (3 off) IN4148 (6 off) IN4002 (2 off) 7812 7805 556 (3 off) BC109 (3 off) TIP30

CONSTRUCTION

When assembling the oscillator and detector boards, the components should be kept as close to the board as possible. The case connection of the BFY90's (TR101/TR102) should be snipped off as close to the body as possible and when mounting TR101 it should be noted that the base connection will pass through the collector and emitter legs. All the component legs should be long enough to enable the components to be bent over to lie on the board.

OSCILLATOR/DETECTOR UNITS

After all the components have been mounted and soldered the assembly should continue as follows:

1) Insert the three 20mm CSK screws through the base plate and secure with nuts, then add extra nuts to support the oscillator board, copper side up. Ensure that the board is spaced to prevent components touching.

 Add three more screws and insert the antenna fixing screws through the detector board, and secure with a nut on

Miscellaneous

Speaker 8Ω re-entrant horn speaker Piezo bleeper VU meter Cabinet Relay DPCO 12V 110Ω Chassis assy P.c.b. 3 Pole jack socket (4 off) 2 Pole jack socket Knobs (2 off) DPCO Min rocker switch Terminal block 5A 6-way Grommet M3 6mm PH (7 off) M3 8mm CSK (4 off) 10mm M3 T spacer (4 off) Heatsink TV5 (3 off) M3 16mm PH (2 off)

Chassis Assy Nuts & Bolts

M3 8mm CSK (4 off) M3 washers (11 off) M3 nuts (8 off) M3 6mm PH (2 off) M3 6mm CSK (2 off) M4 Taptite \times 10mm PH (2 off) 4BA PH $\times \frac{5}{16}$

Power Supply

3 core 3 amp mains cable	3 metre
PCB Fuse holder	(2 off)
Fuse 1A	(2 off)
Toroidal transformer prim.	240V, sec. 15-0-15
6 way 5A terminal block	
4BA solder tag	

Constructors' Note

A complete kit of parts is available from: Powertran Cybernetics Ltd., West Portway, Andover, Hants. SP10 3WN. Tel: (0264) 64455.

Standard kit inc. 2 Transmitters £129.00 Pair of extra Transmitters £39.00 Special Offer: Extended kit inc. 4 Transmitters £149.50

the copper side making sure there is a good contact between the nut and the copper.

3) Place the detector board on the assembly and adjust the nuts until the boards are about 6mm apart. Connect points E on the two boards and connect the mid point of the detector loop with the cathode of the D101 to the junction of R102 and C104.

4.) Strip the two core screened cable and after passing through the grommet connect the red and blue wires to the circuit board as shown, with the screen soldered to the copper earth strip.

5) Place the cover over the boards with the grommet in place and secure the assembly with a nut, after insulating the antenna screw. The antenna should then be screwed on and the jack plug soldered to the cable. This may have to be removed after testing in order to route the cable. The connections to the jack plug are shown in Fig. 2.

NEXT MONTH: Assembly, Testing and Calibration.



Tale of Two Thorns

Speculation on the future ownership of Inmos was finally quashed with Thorn-EMI buying out the government holding for £95 million. The Inmos board was pleased. Uncertainty had disappeared and confidence restored.

Government was pleased to pass on a responsibility no longer welcome and to recover the taxpayers' investment. Opposition from the Labour left was routinely ideological but there was consolation at least in control remaining nominally in British hands.

Lofty sentiments on protecting national technological heritage are just plain silly when targeted at an electronics industry which since its earliest days has been international through cross-licensing of designs. Inmos is no exception with most of its production development having taken place in the United States and its "most secret" dynamic RAM technology being made available under licence to NMB/Minibea of Japan. As part, of the agreement Inmos will purchase a significant portion of the output of NMB.

Another gigantic "leak" of Inmos technology is the agreement for Racal-Redac to market worldwide the complete Inmos hardware/software package for designing advanced VLSI circuits including the transputer.

Of course, you don't give the information away for nothing. In both cases Inmos gains a down payment plus continuing royalties.

The other Thorn in the news is Waldo Thorn who had much to do with the early build-up of International Rectifier in its Italian and British plants. He then turned his attention to component distribution as MD of Celdis and is now MD Northern Europe for the Italian semiconductor manufacturer SGS. The company was well in the red until gripped by the throat by ex-Motorola executive Pasquale Pistorio whose shake-up resulted in turning huge losses into a small profit.

Waldo has boosted sales by 83 percent on his patch and has been setting up a £1.5 million CAD centre at his Aylesbury HQ.

Long Life

Technology advances so rapidly that this year's exciting new product can be obsolescent in a couple of years' time and obsolete in five. But Mullard's Hazel Grove factory has recently ended a 14-year long production run of SOD 38 rectifiers used mainly in TV sets and domestic appliances.

Over the period 87 million had been produced which placed end-to-end would extend to 1,370 miles, nearly as far by air from London to Moscow. But this enormous throughput generated only f12 million of revenue, peanuts by today's standards but a wonderful example of how cheaply we get our components by well-managed mass production.

Big Spenders

Well beyond the peanut bracket is the proposed £800 million investment in Britain by STC and ITT over the next five years. The development plan is interesting in that the two companies, nominally separate, made virtually a joint announcement.

The ITT investment of £196 million was announced by Daniel Weadock, president of ITT Europe, the STC investment of £600 million by STC chairman Sir Kenneth Corfield. Forecast is the creation of 5,000 new jobs, 3,000 in STC the rest in ITT although in ITT's case most will be in that company's hotel and insurance businesses.

Although the two companies were "divorced" in 1982 when ITT sold £500 million worth of its majority shareholding in STC, there is still a family connection. In fact ITT still holds about 35 percent of STC's equity and STC chairman Sir Kenneth Corfield is senior officer of ITT, UK.

On a smaller scale is the new £6 million factory for BICC-Vero at Chandler's Ford near Southampton. Vero products are well known and enthusiastically used by electronic hobbyists as well as the professionals.

Another £2 million is being spent on equipping the factory with the most up-todate design and production equipment in order, in the words of MD John Grillo, to beat the Japanese and Germans at their own game. The existing workforce will be reinforced with 150 new jobs.

Vive le Sport

Love it or hate it—it's been a great year for sport. Detractors are right to point out the blemishes, too commercialised, too political, too little decency and courtesy, general lack of purity in the old traditional sense of playing the game. There's no denying, however, that as an industry it is a vigorous growth area in both cash throughput and employment.

What's in it for the industry? Let's look at the football World Cup to be staged in Mexico in 1986 at a dozen'separate stadia. I am pleased to report that the new equipment needed is to be supplied by Pye TVT of Cambridge under a contract valued at £30 million and won against strong international competition, an industrial sporting event in its own right.

They are to supply more than 100 main and 60 portable cameras coupled into nine completely equipped OB vehicles with all the modern ancillaries such as caption generators and video effects. The overall distribution system includes hundreds of TV monitors, headsets and microphones for a thousand commentary positions. Each match will have seven fixed and three portable cameras, the latter for tunnel and touch-line shots and for on-the spot interviews.

The electronics doesn't stop at TV. Every venue of sporting importance has a powerful PA system, electronic scoreboards, electronic timekeeping. Then there are walkietalkies for security people and medical electronics to check on personal fitness and possible drug abuse. Computers are in there for instant recall of past performances and advance bookings.

It is impossible to estimate the overall fall-out to industry one way and another. All one can say is that it's huge, so perhaps we should not grumble too much about the inflated earnings of the superstars.

Antique Yet Modern

This year is the 116th since the Anglo-Mediterranean Telegraph Company was founded under the chairmanship of Lord William Hay. We know it today as Cable & Wireless.

It is still strong in tradition. The outdated "wireless" which came into the title 50 years ago has been retained, as indeed the court of directors rather than a humdrum board, now chaired by recently knighted Sir Eric Sharp, again following a procession of peers and knights.

There is, however, nothing old-fashioned in the conduct of C & W's world wide communications activities today. Privatised in 1981, the company used its new-found liberty to go for growth. Turnover has risen from £403 million to £650 million with a rise in pre-tax profit of 21 percent.

In the UK, formerly prohibited territory to preserve the old GPO (now BT) monopoly, the main business is still Mercury Communications in which the first international links were established via satellite in August. But now an agreement with Western Union has resulted in setting up Easylink, a flexible electronic mail service which, in the United States, is attracting 10,000 new subscribers a month. C & W is investing £5 million in UK's Easylink and has a 75 percent stake with Western Union holding the remainder.

C & W's involvement in the Far East was emphasised earlier this year by the first ever overseas meeting of the court of directors at the Hong Kong HQ. They visited the People's Republic of China where C & W is involved in joint ventures and also Macau to attend the opening of C & W's new satellite earth station. In all, the company expects to invest £1 billion in the Far East over the next decade.

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RICHARD B. H. BECKER — SYSTEM DESIGN AND MECHANICAL ENGINEERING.

TIM OBB — COMPUTER INTERFACE AND CONTROL ELECTRONICS.

THE ROBOTS are directly controlled by a BBC, VIC-20, or Spectrum computer, and the way that control is achieved is explained here. It involves digital-to-analog conversion, multiplexing to each of the axes; and then conversion of the position data back from analog into digital form, to be fed back to the computer for display on the TV.

THE CONTROL SYSTEM

The robot arm behaves in a very simple manner. It goes to where it is told to go! Once it has been given its instructions it is left to its own devices to proceed to the next set of position coordinates. This makes interfacing it with a remote computer extremely easy. All that the computer has to do is to WRITE the 7 axis position co-ordinates into some memory locations. These memory locations are in fact the robot's internal latches.

The position co-ordinates are 12 bits long, and so the computer sends the information in two stages, first an 8-bit byte and second a 4-bit nibble. These 12-bit words are held in the robot's internal latches, with one pair of latches per axis. Each latch has a different address in memory: the computer can alter the data

PART TWO

in any one or all of the latches, merely by writing to the appropriate addresses. The data held in each pair of latches then represents the intended axis position. The data is converted into a d.c. voltage by a 12-bit digital-to-analog converter (DAC) and then it is fed into individual axis servo units. 12-bit DACs are rather expensive, and so the cost of having one per axis would be prohibitive. To avoid this expense a single DAC together with a multiplexer is used to distribute the position voltage to each axis.

Great care has to be used when multiplexing a 12-bit signal because extraneous events in the multiplexing process could destroy the accuracy of the system. The position voltages are sent to the axes' servo units. These units compare this voltage with the position feedback voltages from the axles of the arm and wrist. The servo units open and close hydraulic valves so



Fig. 2.1. Block diagram of the NEPTUNE Robot system

ROBOTICS PROJECT

that the arm moves to a position of balance where all the feedback voltages equal the computer-generated position voltages. When this occurs, the arm has reached the position that it is told to go to.

The host computer can also measure the time-varying position of the arm: a multiplexed analog-to-digital converter (ADC) looks at the position feedback voltages. Multiplexing is used here too as 12-bit ADC's are even more expensive than 12-bit DAC's, at about 4 times their price. By performing a READ from two address locations, the axis position can be measured with 12-bit accuracy, but before performing a READ the multiplexer must be addressed to the required axis. This is done by writing a control byte into the multiplexer's latch. Also, the ADC must be told to Start Converting, which means toggling a data bit (part of the control byte) from a 1 to a 0 to a 1. This entails two more WRITE instructions, but can be over within microseconds. The ADC generates an answer in about 35 microseconds from the "Start Conversion" command. At that rate you could READ all 7 axes in about 0.5 milli-seconds.

The system also incorporates a "learn" axis input to which the simulator teaching pendant connects. This input is essentially the same as the position feedback multiplexing unit; by changing one bit in the control byte the ADC will measure d.c. voltages from the simulator. The simulator is a small mechanical model of the arm which can be manipulated by hand. By continuously READING these voltages and then WRITING to the arm, the arm will follow the movements of the simulator. All this information passes through the computer and so it is possible to record it either as a function of time or as a sequence of points in space.

The general system is shown in Fig. 2.1. Most of the hardware lives on the main p.c.b., and the external computers plug directly into this board via ribbon cable connector leads.



Fig. 2.2. The system interconnected with ribbon cable

The servo units (7 off) are directly connected to the solenoid valves which are in turn directly connected to the manifold. The power supply is on a separate p.c.b. All interconnections are made with pre-assembled ribbon cable IDC two-part connectors (Fig. 2.2).





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INTERFACES

The NEPTUNES can be driven by any one of three popular micro computers: the BBC, the Commodore VIC-20 and the Sinclair ZX Spectrum. Most micros have user-accessible interfaces and with small changes others could also be used. The NEPTUNE's requirements are a parallel data bus (8 bits), the lower address lines, the clock signal from the micro and the READ and WRITE signals. By using these basic signals it is possible to write 12-bit data words (a byte and a nibble) to the 7 axes of the robot. Also, using this simple interface, the axis position can be read (again with 12-bit resolution) by the host computer.

This enables the real time motion of the arm to be monitored and recorded. The learn axis information is first read by the computer and then written into the arm, enabling direct control of the position of the arm without writing-in software and position control data. The signal pinout for all three computers on the main NEPTUNE board is shown in Fig. 2.3. All three edgeconnectors are directly accessible to the user. Other signals from the computer are available, but are not used.

THE HARDWARE

The hardware shown in Fig. 2.4 is used to store the position co-ordinates and convert them into d.c. voltages for the servo units. IC101 is used to buffer the computer data bus. If the robot electronics were directly connected to the host computer's data bus the loading of it and the spurious signals picked up by it, would almost definitely crash the system. The same is true for the address bus, hence the buffer IC101. IC102 and IC103 decode the bottom 4 address lines, providing 16 available address locations to WRITE into.

A VALID WRITE signal is also required to activate the address decoders. This is obtained from the computer interface circuits. When one of the outputs of IC102 or 103 goes low and then high, it clocks the latch to which it is connected (IC106 to 119). Any data on the data bus at this time is then stored in the latch. This is a WRITE cycle. As the system uses 12-bit words, the writing has to be done twice. First an 8-bit byte is stored and then a 4-bit nibble at the next address location.

The data is extracted from these latches by enabling their outputs in sequence. This data is wired into the 12-bit DAC (IC120) which generates the d.c. position voltages. IC122 is used to demultiplex the DAC output voltage, the voltages being stored on sample and hold devices, IC123 to 126. A binary counter (IC130), which is clocked by the host computer's system clock, is used to generate the multiplexer addresses and output enable decodes. Great care has to be taken over the demultiplexer design, as it is very easy to corrupt the output voltages.



PE1592G

Fig. 2.5. Demultiplexer inhibit timing

The 4051 (IC122) suffers from momentary internal short circuits when the address changes on its inputs and this can seriously damage your sampled and held output voltage which would then become corrupted. An overlapped inhibit signal prevents this (Fig. 2.5). Also, when is a capacitor not a capacitor? Answer, when it is used in a sample and hold circuit. A parameter called dielectric absorption can make the voltage on a capacitor go soggy. Fortunately not all dielectric materials behave similarly and the cure is to use a capacitor constructed from polystyrene.

THE COMPUTER INTERFACE

The NEPTUNE robots were designed to interface with three popular micro-computers, the BBC, the Commodore VIC-20 and the Sinclair ZX Spectrum. All computers perform reads and writes to the robot. As far as the computers are concerned, the robot arm is just another area of memory. The three computers have significantly different internal electronics and so require different interface circuits at the robot end. See Fig. 2.6.

BBC INTERFACE

Connection to the BBC is via the 1MHz bus. This is a parallel interface with the lower 8 address lines, 1MHz system clock, R/\overline{W} and an address block decode called FRED (Hex FCØØ to FCFF). The BBC computer internally buffers the data and address lines, which makes the interfacing very easy indeed. Simple decoding (IC300 and 301) is used to generate valid read and write pulses.

VIC-20 INTERFACE

The VIC-20 is similar to the BBC in that both computers use a 6502A microprocessor. The VIC provides four 8K block decodes, one of which is to be selected by the user with link 12, that is the first position selects block 1 (Hex $2\emptyset\emptyset\emptyset$ -3FFF). Valid read and write signals are generated by IC303 and 304.

SINCLAIR ZX SPECTRUM INTERFACE

Every signal is available at the back of the Spectrum, but there are many possible problem areas and so great care was needed in the design of this interface. The Spectrum uses a Z80 processor and so some dissimilarities between this computer interface and the other two are inevitable. Also the use of the memory map varies and reading presents a few problems. In a 48K Spectrum, a PEEK read anywhere in the memory map would cause a read of either the Spectrum's ROM or the RAM and this would clash with data from the robot interface connected to the bus. An IN read is therefore used treating the robot as an I/O device instead of part of memory.

ADDRESS DECODING

Unfortunately the address lines are not decoded and are used directly for keyboard scanning and peripheral control. There are however a couple of non-conflicting addresses (hex 3F and 5F) and these are decoded by IC305–309. Writing requires more addresses than are available as I/O, however no conflict is caused by writing with a POKE to the address space $\emptyset\emptyset\emptyset\emptyset$ to 1FFF where the Spectrum ROM is resident.

Only one computer at a time must be connected to NEP-TUNE. All the data buses and address buses are directly connected to all interfaces, and so if two computers were simultaneously connected, a bus clash would occur. A selector switch is used to route the valid read and write signals and the computer clock signal to the relevant places in the control electronics. A l.e.d. near each connector indicates which computer interface has been selected.



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ANALOG TO DIGITAL CONVERTER

NEPTUNE has the ability to read in, via an ADC, the position of each of its arm joints and to transfer this information back to the host computer. See Fig. 2.7. The position feedback voltage is converted into a 12-bit binary code by the ADC IC202. This device performs a single conversion in about 25 μ s, which is fast enough for real time monitoring of all the 7 axes. A read of all 7 axes can be achieved in under 200 μ s. The ADC is an AD754 which uses an internal, successive approximation register to perform a fast conversion. The only signal needed to operate the ADC is a high-to-low Start Conversion signal, R/\overline{C} on pin 5. The ADC then performs the conversion and 25 μ s later the result is ready.

Two sources of voltages are available for selection by the system. When multiplexer IC205 is selected, feedback voltages (VFBØ to VFB7) from the robot axes can be read by the host computer. This is a very useful feature in that it enables the computer to observe the dynamics of the system and optimise future trajectories based upon past experiences. The computer can also plot out these trajectories on a printer.

When multiplexer IC208 is selected the learn axis voltages (LA \emptyset to LA7) can be read by the computer. VFB7 and LA7 are not necessary for the control of the robot but are provided to enable additional sensors to be connected to the system. The LA parameters are then fed back to the axis controllers so that the robot arm copies the real time motions and positions of the simulator. The computer memorises the movements either on a regular time basis, for example every 100ms, or when instructed by pressing the COPY key.

READ OPERATION

A typical read operation is as follows (Fig. 2.8). The multiplexer selection and multiplexer address is set up in control latch IC207. This is performed by writing a control byte to this latch (Table 1). The selected analog voltage is then connected to the ADC input. Start conversion is initiated by taking BD7 on the latch IC207 from a high to a low. This is another write to IC207. The conversion is now underway. It is best to delay resetting BD7 until after the end of conversion (EOC) so as not to risk disturbing the analog voltage. A test can be performed to see if the ADC is finished, as pin 28 of the ADC is a status bit (also called End \overline{Of} Conversion), and when this bit goes low the conversion is complete. By performing a read on bus buffer IC201, the EOC can be tested.

Alternatively the host computer could just wait a suitable length of time. This will occur automatically with programs written in BASIC. Reading is then performed in two steps. First the most significant byte is read (\overrightarrow{MSOE} IC200) and then the least significant nibble (\overrightarrow{LSOE} IC201). The conversion is now complete and the next analog voltage can be selected. The ADC provides the 10V reference signal for use on the servo potentiometers and simulator. If the ADC is not fitted then the zener diode (D210, 211) reference is used.

The axes operate independently; the voltage representing the required axis position is sent to the solenoid driver board of the appropriate axis, together with the position feedback voltage. For seven axes of movement, therefore, there are seven solenoid driver boards.

The system utilised is a closed loop servo system. When it is desired to change an axis position, the analog equivalent of the data operates the hydraulic valves, via the solenoid driver board, and the axis moves. The position feedback voltage from the potentiometer is then compared with the required position, and movement continues until the two voltages are the same.

NEXT MONTH: Details of the servo system, and the power supply requirements. READ CYCLE





Fig. 2.8. Sequence for read and conversion

Table 1. Neptune axis selector, latch IC207

-	BD7	BD6	BD5	BD4	BD3	BĎ2	BD1	BDØ	HEX	Signal
	1	x	х	x	0	0	0	0	xO	VFBØ
	/	х	х	x	0	0	0	1	x1	VFB1
	/	х	х	х	0	0	1	0	x2	VFB2
	/	х	х	х	0	0	1	1	x3	VFB3
	/	х	х	х	0	1	0	0	x4	VFB4
	/	х	х	х	0	1	0	1	x5	VFB5
	/	х	X	х	0	1	1	0	x6	VFB6
	_/	X	х	х	0	1	1	1	x7	VFB7
	1	x	x	x	1	0	0	0	x8	LAØ
	/	х	×	х	1	0	0	1	x9	LA1
	1	х	х	х	1	0	1	0	xА	LA2
	/	х	х	X	1	0	1	1	xB	LA3
	/	х	х	х	1	1	0	0	xC	LA4
	1	х	х	X	1	1	0	1	xD	LA5
	/	х	х	х	1	1	1	0	xĒ	LA6
		x	x	x	1	1	1	1	xF	LA7

x = don't care. / = start conversion bit. $1 \rightarrow 0 = start conversion.$

Readout...

Forward Looking

Sir—I read with interest and some amusement your comments on the IEE in Vernon Trent at Large in the August issue of P.E.

You accuse the Institution of living in the past. May I suggest it must be some time since you yourself visited the Institution. The statue of Faraday which you regard as 'off-putting' has now been put off and no longer dominates the entrance hall. Some of us thought that 'all that marble' really was a bit much and proposed that the floor should be carpeted. Our members would have none of it and we are now hard at work re-laying the marble floor (at some considerable expense). You say we do not hold meetings, debates and conferences but only seminars or conversaziones. Again have you seen our programme? I cannot recall when last we held a conversazione and only a limited number of seminars which are essentially tutorial are held.

One of the interesting aspects these days is the large number of younger members who have joined the Institution. The vigour with which they promote their views and their effectiveness in influencing the affairs of the Institution is most encouraging.

We believe we are a forward-looking Institution; why not come and see where we are going rather than dwell on the past.

Howard Losty (Sec), IEE, London.

It is about two years since I was last in direct contact with the IEE and at that time I did not detect any appreciable change in the atmosphere and outlook of the preceding 18 years. It seems times are a'changing with the speed of light.

The removal of the giant Faraday is a real step forward. But what has happened to this awesome example of the sculptor's art? I do hope he's not being kept on ice in the basement in case some future generation of the IEE management has a change of heart.

It's a shame about the marble. But I can't help feeling that the spirited objection of your members to its removal only goes to prove my argument that reluctance to change is still deep-seated. Of course, you could have saved a lot of money if you had broken up Faraday and used the pieces in your relaying operation.

No, I haven't seen any of your latest programmes, I'm afraid. That's remiss of me. But in fairness, I was cheered to read, sometime after my article was written, that you had taken over the Dominion Theatre for the Faraday Lecture. This is really reaching out, staging such an august event in a building to which in earlier months people were flocking to see Mary Poppins.

I stand duly rebuked over the seminars and conversaziones.

Your statement that younger people are joining the Institution in large numbers is clearly at variance with the official report on which my observations were based. But obviously I must accept what you say so far as the IEE is concerned. I only hope that the 'vigour with which they promote their views and their effectiveness in influencing the affairs of the Institution' will continue to bring that breath of fresh air, which from my viewpoint seemed to be lacking.—VT.

Interfacing VIC

Sir—With reference to your *Commodore 64 RS 232C Interface* by R.A. Penfold in the August issue of Practical Electronics. Could you please inform me whether the described interface is also appropriate to the VIC 20?

I have recently wished to couple a Tandy CGP115 printer/plotter to the VIC 20 and, of course, came up against the very problem that your article solves for the '64.

R.A. Prince, Welwyn Garden City, Herts.

I have tried the CBM64 RS232C Interface with a VIC-20, and without any software or hardware modifications it does seem to work. However, there is a slight problem in that as the electrolytics in the power supply section of the unit charge up the 20mm IA quick-blow fuse in the VIC does occasionally blow. This does not seem to affect the CBM64 which has a slower acting 1.25 inch fuse. The problem with the VIC can be overcome by replacing the quick-blow fuse with an anti-surge type, or adding current limiting resistors of about 10R in series with each 9V output of the user port would probably eliminate the problem.—R.P.

War and Peace

Sir—Isn't it enough that we have to put up with political views being pressed on us by national newspapers and TV, without our hobby magazine attempting to do the same?

I refer to *Industry Notebook* by Nexus. He's at it again (August); airing his views about Unions—one of his hobby horses—and giving his blessing to military electronics. Miners, lorry drivers etc.,—Nexus is there to give us his opinion and to lecture us. Just *what* 'industry' are you reporting on, Nexus?

There's no mistaking his allegiance, I'll give him that, but I don't think he should use his page to stir up this sort of stuff. To clarify (I hope), I mean that I am not interested in his opinions or views, only his reporting, and even that ought to be relevant to the magazine's title.

Of all the developments and news about industry there is no *need* for him to scrape the bottom of the barrel. News of rival Standards, processes, who's first with what system etc., is what I like to read.

I haven't expressed that very well, but if I can give you an example of interesting reporting on the Electronics Industry—the newspaper "Electronics Times," should give a good idea. Of course, there will be large amounts on military electronics in it, and an occasional mention of Unions (especially in relation to Telecoms)—but not in that irritating 'take it from me, sonny' style, which Nexus seems to have.

Give it a rest, Nexus, and stop using *Industry Notebook* as a platform for your political views.

D. Field, Poole, Dorset.

Bigoted Outlook

As your publication provides no forum for political answers to the highly prejudiced statements of your contributor 'Nexus' I am writing to you in order to express my opposition to some of his/her more outrageous sentiments over the past few months.

I have in mind *Industry Notebook* in the August issue. Having criticised the GCHQ Union for a "prolonged and noisy protest" the writer (wrongly) states. "with GCHQ employees surrendering their membership for immediate financial advantage" (Paragraph 2).

This is not the case—the workforce at GCHQ were faced with three alternatives—1) Drop out of the Union with a cash sweetener. 2) Be transferred (under a cloud) to regions unknown. 3) Be sacked. Equally vain is this writer's claim that it was "a lost cause"—visa-vis the recent High Court finding.

I am not an ex-employee of GCHQ nor have I been a member of a Civil Service T.U.

After a vicious attack, culled from the rightwing press, which contained all the heavy old cliches about ballots, violence, obscenities, provocation, civil war and union 'bosses', the writer dissolved the working class in eight lines of nonsense and in the next paragraph brought in the questions of "sweetheart agreements, peaceful negotiation, creation of wealth".

Where have you been keeping this character? Can he/she inform us how you create wealth in a closed coal mine after you have been sacked?

1 am aware that this letter deals with political issues but nonetheless I consider that a technical journal should confine itself to technical matters. General interest items should of course be included but please, not a column devoted to the bigoted outlook of one contributor.

I feel so strongly about this issue that it puts a severe strain on my loyalty to 'P.E.' I am certain that there are other electronics journals who do not inflict one-sided-no right of replyarticles on their readers.

> W.L. Thomas, Lydney, Glos.

Nexus replies:

Nobody has been 'attacked' by me. I did comment that the GCHQ and Miners' causes were just. The remainder of which Mr Thomas complains was fact, not opinion. The GCHQ picket was prolonged and noisy and the NUM remains split and picketing was as described. There is a movement, led by the EETPU in the new industries, to eliminate strikes as being outdated, destructive and benefiting nobody. The initiative is from the EEPTU, not from me, and deserves to be put on record. Build-up rather than smash-up seems reasonable. Why not give it a chancel—Nexus.

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OTHER SOLAR SYSTEMS?

The Infra-Red Astronomical Satellite (IRAS) was launched on 25 January 1983, as a joint Anglo-American-Dutch venture. Its orbit carried it round the Earth in a period of 103 minutes, and it stayed in sunlight for most of the time, because its path took it above the poles; its mean altitude was 560 miles.

Almost immediately after launch, the first important results started to come in, and during its active career, which lasted through most of 1983, *IRAS* sent back a stream of fascinating information. Several new comets were discovered (including one which became briefly visible with the naked eye) and one known periodical comet, Tempel 2, was found to have a dust-tail twenty million miles long. There were also "dust rings" in the Solar System itself, and *IRAS* detected a strange asteroid whose orbit carries it within 9,000,000 miles of the Sun. Yet the main work concerned the infra-red sources far beyond the Sun's realm. *IRAS* surveyed the whole sky, and detected thousands of new sources. All in all, it was possibly the most successful astronomical satellite to date.

The information was collected at the Rutherford-Appleton Laboratory at Chilton, in Oxfordshire, where the preliminary analyses were carried out. Two of the American scientists there were Dr. Hartmut Aumann of the Jet Propulsion Laboratory in California, and Dr. Fred Gillett of the Kitt Peak Observatory in Arizona.

They were using various stars as sources for calibrating the infra-red telescope on board *IRAS* when they made a startling discovery. Dr. Gillett was examining some of the records when he said, suddenly: "Hey! Alpha Lyrae has a huge infra-red excess." Alpha Lyrae is, of course, the brilliant blue Vega, 26 lightyears away and over 50 times as luminous as the Sun.

What did it mean? At first Aumann and Gillett wondered whether there could be some mistake, so they examined other bright stars, such as Altair, which is of the same type as Vega though it is less powerful. Nothing unusual was found.

There really was material associated with Vega, and the two scientists wondered whether it could be "mass flowing out" from the star, but this idea was soon abandoned. Further studies showed that the material took the form of a cloud of particles, larger than the "dust" particles found in interstellar space.

The infra-red radiation came from a region extending out to more than 7,000,000 miles from Vega. This is eight times the distance between the Sun and the Earth, so there had to be a considerable quantity of material. In fact, it was estimated that the total mass was about the same as that of all the planets in our Solar System put together.

Could it be a cloud of the same kind as the "solar nebula" from which the Earth and the other planets in the Sun's family were formed, more than 4,500 million years ago? Aumann and Gillett came to the conclusion that this was a possibility, but very small particles would have been drawn back into Vega; this would leave intermediate and larger-scale débris in orbit, and this could have condensed into planets, or at least started to do so.

Moreover, there was the question of temperature. The material was found to be about -300 degrees Fahrenheit, about the same as that of the particles making up the rings of Saturn.

All this was exciting. Surveys were continued, and one more star—Fomalhaut—was found to have a similar infra-red excess, for the same reason. There could be no doubt about it; the material was there, and planets were a real possibility. But could they be of the same type as the Earth, and could they support our kind of life?

To answer this, we must look more closely at the two stars concerned. Vega, as we have seen, is more than 50 times as powerful as the Sun; Fomalhaut, at a distance of 22 lightyears, is the equal of 13 Suns. Both are much hotter than the Sun, and both are more massive. This means that they run through their life-cycles much more quickly.

Nothing much will happen to the Sun for the next 5000 million years or so, which is fortunate for us; but Vega will not last for more than a few hundreds of millions of years before it uses up the available nuclear "fuel" which keeps it shining steadily. It will then have to change its whole structure, and there will be a period during which it will send out

THE SKY THIS MONTH

For the next fortnight or so you have a good opportunity to see the elusive little planet Mercury—provided that you get up early! It is emerging from the morning twilight, and reaches its greatest elongation (apparent distance from the Sun) on 14 September, when it will appear telescopically as a tiny half-moon. Rather surprisingly, it is then brighter than any star visible from Britain except Sirius, but this is not obvious, because Mercury is always seen against a light background.

Most of our knowledge of it comes from one spaceprobe, Mariner 10, which made three active passes of the planet and sent back pictures showing a rough, crater-scarred surface very like that of the Moon. Mercury is smaller than the Earth (its diameter is 3000 miles) and has practically no atmosphere, so that life there is out of the question.

Look for Mercury with binoculars by all means—but only when the Sun is still below the horizon. Never sweep around with binoculars after sunrise; there is always the danger of looking straight at the Sun by mistake, with tragic results for your eyesight.

The other inner planet, Venus, is visible after sunset, low in the west; it is over 90 per cent illuminated. Mars and Saturn are being lost in the evening twilight, though Jupiter is still brilliant in the south-west during evenings. The Moon is full on 10 September, and will be new on the 25th.

Now that the nights are lengthening, the stars can be seen to better advantage. The "Summer Triangle" of Vega, Altair and Deneb is still very much in evidence. The Plough or Great Bear is at its lowest, in the north, though over Britain it always remains well above the horizon. Arcturus is setting in the north-west, Capella rising in the north-east.

Also in the east, during late evening, look for the lovely star-cluster of the Pleiades or Seven Sisters, in Taurus (the Bull). The Pleiades have been recorded since very ancient times, and there are many legends about them; according to one tale they were seven beautiful girls who were chased by the hunter Orion, and were saved from a fate worse than death by being transformed into stars and placed in the sky! I always think that the first sign of the Pleiades in the evening is an indication that winter, with its fogs and snows, lies ahead.

The main autumn constellation is Pegasus. In mythology, Pegasus was a flying horse. In the sky he is marked by four reasonably bright stars forming a "Square". At present the Square is high in the south during evenings, and is not hard to locate, even though many people looking at maps imagine it to be smaller and brighter than it really is.

Follow down the line of the two western (right-hand) stars of the Square, almost to the horizon, and you will come to the bright star Fomalhaut, which is always very low down as seen from Britain—from North Scotland it is unlikely to be seen at all. It is one of two stars (Vega is the other) being studied by IRAS, the Infra-Red Astronomical Satellite, and found to be associated with material which may be planet-forming. much more energy than it does now, with disastrous results for any life-bearing planets. The same is true of Fomalhaut, though here the time-scale may be rather longer.

Therefore, it seems that Vega's system (and also Fomalhaut's) will never evolve into a Solar System like ours, because it will not have sufficient time before conditions become hopelessly hostile. We cannot expect Earthtype life, and probably no life of any kind. For this, we must look to more sedate stars which more closely resemble the Sun.

INVISIBLE BODIES

In spite of this, the *IRAS* revelations are immensely significant. It had already been suspected that some dim, relatively nearby stars are attended by planets, because they show slight "wobblings" in their slow motion across the background of more distant stars, and these "wobblings" may be produced by invisible bodies of planetary type. Now, with the news from Vega and Fomalhaut, the presence of other Solar Systems becomes even more plausible. And after all, why not? Our Sun is an ordinary star—one of 100,000 million in our Galaxy alone, and modern telescopes can record at least a thousand million galaxies. It would be absurd to suggest that in all this host, the Sun is unique in having a family of planets.

IRAS has come to the end of its active career. It will be succeeded by new infra-red satellites, which will examine other stars and will almost certainly detect material around some of them.

There is also the forthcoming space telescope (the Hubble Telescope), due to be launched within the next few years; it will have a 94-inch mirror, and will operate from above the atmosphere in free flight round the Earth, controlled from the ground. Its main investigations will be in the visible and near infra-red parts of the electromagnetic spectrum, and it will be far more effective than any telescope at ground level could hope to be.

SEARCH FOR ET

If planetary systems are common (as now seems more likely than ever), we must ask ourselves about the chances of extra-terrestrial life. Here, too, we would surely be conceited in claiming that we are unique, but as yet we have no positive information to guide us, and contact with other civilisations will be a very difficult matter—even assuming that they exist within reasonable range of us.

Meanwhile, the new findings have caused something of a change in outlook, and we may hope for more striking developments in the near future. So if you go outdoors on the next clear night and locate Vega and Fomalhaut, you will be able to realise that there is something very significant about them—even though to us they appear as nothing more than tiny points of light.

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V.T.'s views and opinions are entirely his own and not necessarily those of PE

O VER the past few months I've been looking (sometimes, as you've probably noticed, with a jaundiced eye) at the continuing impact that electronics is making on the way we live, play and work.

I've wandered into industry, agriculture, retail trading, the domestic scene, the Church, medicine, help for the blind and so on. I've even been able, in our April issue, to lift the veil on certain hush-hush developments in the United States that can only be described as revolutionary. And if you believed that report, you will—as the Duke of Wellington said to someone who asked him if his name was Simpkins—believe anything.

Until last week, however, I hadn't got around to the subject of sport, with which the visual and audio media confidently thinks every man-jack of us is besotted. It was then that I ran into an old buddy, Jerry Monk, group publicity manager of the Greyhound Racing Association. He came up with a lot of interesting facts, including the shameful revelation that his particular sport seems, by and large, to be getting along, thanks very much, with no more than a modicum of electronic intervention.

As a sporting attraction, Jerry told me, greyhound racing ranks second only to football in the UK, drawing about eight million fans through the turnstiles every year. The animal itself has a noble history. King Solomon described it as "one of the four things that are comely in going" (he didn't say what the other three were—I'm longing to find out).

Greyhound kennels existed in Anglo-Saxon times and Canute—probably still smarting under the disobedience of the waves petulantly decreed that only those of royal descent should be allowed to keep greyhounds. The regal touch was revived in 1968 when the Duke of Edinburgh's *Camira Flash* won the Greyhound Derby at White City.

Originally greyhound coursing involved a live hare. Then in 1876 there came a startling innovation at Hendon in North London. For the first time the prey was an artificial hare which ran on a live rail embedded in the turf of a 400-yard straight course.

The forerunner of modern greyhound racing came into being in Tucson, Arizona, in 1909, with dogs competing on a circular course. Belle Vue, Manchester, saw the first British meeting within this concept in July 1926.

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On-course betting on greyhound races is handled by the totalisator. Mindful that PE readers have in many cases led sheltered lives, let me explain that this is an electromechanical system in which the aggregate stake, less admin charges and tax, is paid out to winners in proportion to their stakes. It is, in essence, a jumbo-size calculator with a jumbo-size read-out.

"Many of these machines," said Jerry, "have been in use for more than 30 years and are approaching the end of their useful lives. We can't replace them because they aren't being made anymore.

"So, bowing to the march of technological time, we are just embarking on a heavy capital investment to provide the 10 stadia we own throughout the UK with fullycomputerised totes based on microprocessors. Already they have been installed at Wimbledon in SW London, Slough and Portsmouth.

"They will have the great advantage of faster operation and will make possible a much wider variety of betting combinations. And eventually the giant visual boards which have been with us for so long will be replaced by monitors set up in strategic positions round a course and giving much more information than hitherto.

"It's an expensive operation, as I say, but we believe that it will eventually more than pay its way."

Another project in hand, though it cannot accurately be described as one involving electronics, is to run the hare on a linear motor. The dividend here is vastly simplified maintenance.

"But while we naturally want to keep up with the times so as to give our patrons the advantages of modern developments," said Jerry, "you have to remember that basically our business is based on animals. Greyhounds are motivated by instinct and training, not by what electronic research and development offers.

"People often ask whether the hare is really necessary to a successful race. On the face of it, it isn't. Generally speaking, greyhounds will run because they are trained that way, whether or not they have a prey to follow.

"We've proved that by experiment. But the hare still has to be there. Should one nervous dog cotton on to its absence and falter, the rest of the field will falter too."

* * *

Greyhound racing has had a somewhat chequered career in Britain. Originally it was regarded as a cloth-cap type of sport. Indeed, at one point the totalisator was outlawed because it was thought it encouraged the working classes to fritter their money away.

Then by the early 1950s it had achieved a greater respectability. Track managements

went out of their way to build up an "havean-evening-out-with-the-wife" image. Catering facilities were improved out of all recognition.

Industry was wooed to provide sponsorship—many of the big classic races are now backed by household names. A night at the dogs became as much a feature of company-customer entertaining as a box at Goodwood.

Nevertheless, the sport has been hard-hit by the cold wind of recession and by the emergence of the betting shops which have enabled punters to back their fancies without turning out on a cold night. But the tide is turning again and attendances are on the upturn.

"... only those of royal descent should be allowed to keep greyhounds."

But however one may advocate the adoption of chip and other modern technology as a means of cutting costs, improving profits and increasing efficiency in other fields, one stark fact remains. Greyhound racing, while still hovering on the electronics periphery, manages to achieve a staggering betting turnover of more than £600 million a year.

Maybe there's some sort of moral here.

My friends at the Sutton (Surrey) "Talking Newspaper for the Blind" (see the March issue of PE) have been looking at a new type of reading machine, developed in the USA and available in this country at the bargain

price of $\pounds 25,000!$ This is how it works: The material to be read is placed face downwards on a scanner, similar to a photo-copier. A remote hand-held control panel is then activated which causes the machine to automatically locate the first line of text and begin scanning the page. Within seconds an electronic voice reproduces the material.

The machine is designed to read any printed material in book or magazine form. It will also handle documents, office memoranda or typewritten correspondence. It can speed up or slow down, repeat previous lines or spell out difficult words. And while many other facilities can be achieved via its 32 controls, it cannot, alas, cope with handwriting.

While the cost of this machine could not possibly be borne by any individual charitable organisation, efforts are being made in the USA to provide its benefits at major public libraries.

Ways and means are now being sought in Sutton for bringing this benefit to its 500 sightless persons.

Here's a thought. The cost of a reading machine is probably around the equivalent of the annual salaries of three Deputy Assistant Administrators (Class III), or whatever, whiling away their time in the Civic Offices.



detect high speed clock pulses and their direction, in addition to the d.c. logic levels of inputs and outputs. This is possible if a very expensive oscilloscope is available which can hold and stretch very short duration pulses. Many logic probe designs either omit the pulse function, or include it in association with the alternate switching of the logic level I.e.d.s. In the design presented here, a logic "O" is indicated by a green l.e.d. and a logic "1" by a red l.e.d. High speed pulses are indicated by a yellow I.e.d. in conjunction with a double pole, single throw switch, which indicates whether the pulse is positive or negative. This is not a fussy circuit. Apart from the 7404 Hex inverter and the miniature switch, the components used are values normally found in the workshop. TR1 can be any general purpose npn transistor and D1 and D2 any silicon switching diodes of 4148 or 914 type. Resistors R4 to R6 can be any value between 47 and 150 ohms, according to the brightness of the l.e.d.s available, 100 ohms being suitable for a normal guality l.e.d. and 47 ohms if using cheap pack l.e.d.s. C1 stretches a detected pulse sufficiently to illuminate the yellow l.e.d. The value and type is not critical, a 4µ7 electrolytic being chosen because it is of small physical size when laid on its side, but having sufficient capacity to hold a slow frequency pulse.

IN modern electronic circuits it is necessary to be able to

CIRCUIT DESCRIPTION

The circuit shown in Fig. 1 is powered by the host circuit which is being tested. This must be a +5V supply. With the probe in its quiescent state, i.e. not in contact with any active circuit, the input to IC1a (inverter 1) is floating—it is neither at logic "0", nor logic "1". Its output, which is connected to the input of IC1b is at logic "0". Therefore the output of IC1b is at logic "0" at the input to IC1c and logic "1" at its output disabling D4. At the same time, the input to IC1d is floating and its output is at logic "0". The input to IC1e is also at logic "0" and its output, being at logic "1", disables D5.

With a logic "0" at the tip of the probe and the input to IC1a the junction of IC1a output and IC1b input is at logic "1". The resulting logic "0" at the output of IC1b pulls the cathode of D3 to ground potential, turning it on and indicating a logic "0" at the tip of the probe. Meanwhile, TR1 remains turned off. If S1 is in the "0" position, touching a logic "0" with the tip of the probe produces a pulse at D5. Whilst there is a logic "0" at the cathode of D3 the input of IC1d which has been floating, is pulled down to logic "0" through D1. Its output goes to logic "1", charging C1, which acts as an a.c. coupling capacitor to the input of IC1e placing a logic "1" at its input and a logic "0" at its output. This pulls the cathode of D5 down, causing it to turn on. A series of high frequency pulses prevents C1 from discharging, holding D5 on.

With a logic "1" at the tip of the probe, TR1 is turned on, bringing the input to IC1c to logic, "1" and its output to logic "0". This brings the cathode of D4 low and turns it on. At the same time the input of IC1a being at logic "1" disables indicator D3. If switch 1 has been changed to the "1" position, any pulses appearing at the probe tip will be indicated by D5 turning on, as previously described.

TR1 and its associated resistors have the effect of stabilizing the inputs from the probe tip. Without it the inputs would float, causing either D3 or D4 to turn on. Similarly D2 prevents the input to IC1d from floating. R3 ties the input of IC1e to ground until pulled up by the output from IC1d.

CONSTRUCTION AND TESTING

The circuit is constructed on a p.c.b. 35×60 mm. The circuit design is shown in Fig. 2 and the component layout in Fig. 3.

The circuit is simple and could be a suitable introduction to drawing with etch resist pen. This is carried out by first taping a photocopy or tracing of the p.c.b. design over the copper side of the board and drilling the holes. Holes should





Fig. 1. Circuit diagram

be 0.8mm for IC1, the transistor, the diodes and capacitor and 1mm for the resistors, I.e.d.s and leads. After drilling, the board should be cleaned to remove any burrs. When drawing with the etch resist pen, first draw pads around the holes and use these as a guide for drawing the lines. Since the inverter at pins 11 and 10 of the i.c. are not used, there is no need to draw these pads, allowing a line to pass between them. Etch in a solution of ferric chloride. Clean off the etchresist when etching is complete.

Mount resistors, followed by diodes, i.c., with or without socket, transistor, capacitor and last of all the l.e.d.s. The l.e.d.s should stand-off from the surface of the p.c.b. so that they will locate in the holes in the case. Care should be taken with the polarisation of the diodes, the cathode being indicated by a broad band; the l.e.d.s, where the cathode is indicated by a flattened side and the capacitor, usually indicated by a + or – sign. The transistor emitter is indicated by a small lug on the metal case. S1 is a miniature d.p.s.t. type with 0.15'' space between connectors; it is soldered directly onto the edges of the p.c.b. Stranded red and black wires with miniature croc leads are used for the power leads.

After completion of the board, a probe tip made from a suitable conductive rod is first of all bent at the p.c.b. end before it is inserted, from the component side, through the 2mm hole provided and soldered to the large pad on the copper side. The probe was designed to fit into a small plastic case of the type shown. The p.c.b. basically 'clips' into position once the holes for the switch (S1), the probe and the croc leads have been made; non-conductive foam could be used to hold the board more firmly if necessary. It was found that a small piece of plastic had to be cut away from one of the securing pillars in order to seat the p.c.b. properly so that the other edge rested on the ledge on the inside of the case.

TESTING

Connect the probe to a suitable +5V source, then touch the probe tip to each of the positive and negative terminals. The l.e.d.s will then respond to the relevant logic levels.

TEST GEAR PROJECT

COMPONENTS ...

Resistors

R1	47k
R2	1k
R3	470
R4-R6	100* (3 off)

Capacitors

C1	4μ7
----	-----

Semiconductors

D1-D2	1N4148 (2 off)
D3	Green I.e.d.
D4	Red I.e.d.
D5	Yellow I.e.d.
TR1	BC108 or general purpose npn
IC1	7404

* elect. 16V

Miscellaneous

D.p.s.t. miniature slide switch (0.15") pitch; Case type 21026 (Electrovalue); 2mm dia. conductive rod (probe tip); Croc clips (2 off). *See Text

Constructor's note

Case available from, Electrovalue, 28 St Judes Road, Englefield Green, Egham, Surrey. TW20 OHB. (0784 33603).



Fig. 2. Component layout

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ENCODER/DECODER (MM53200N)

HE encoding and decoding of information is a very complex business, and is done for many different reasons. One of the most common of these is in control applications where one unit must control a number of others independently of each other, or where any given unit should respond only to instructions from one other specific unit. Under these circumstances there must be some means by which units can uniquely identify and recognise each other. This can prove difficult to implement, especially when a high degree of immunity against error is called for; for example, in security systems. This month we look at the MM53200N, a novel i.c. from National Semiconductor which provides an interesting solution to some of these problems.

PULSE CODE MODULATION

The MM53200N is an 18 pin digital MOS LSI device which can behave as both an encoder and a decoder. It works on the principle of pulse code modulation, as illustrated in Fig. 2. The basic waveform is shown in Fig. 2a, and is a continuous series of pulse codes each of which is 11.52ms long. (All durations quoted assume the nominal 100kHz clock frequency.) Between each pulse code is a reset pulse, also 11-52ms long. Each pulse code consists of 12 individual bits; Fig. 2b and Fig. 2c show the arrangement of these. For each bit, a short negative duration of pulse corresponds to a logic 0, and a long negative duration of pulse corresponds to a logic I. Since there are 12 bits in each code it follows that there are 212, or 4096, different combinations. When used as a decoder the i.c. only responds to one of these, so each encoder can control up to 4096 decoders without interaction.



BASIC OPERATION

The two different modes of operation of the i.e. are shown in Figs. 3 and 4. All the connections are identical except for the mode selector, pin 15 (high level = encode, i.e. transmit the signal, low level = decode, i.e. receive the signal), the receive input, pin 16 (connect to 0V for transmit), and pin 17 which is the transmit output or the negative pulse to indicate that a valid sequence of codes has been received, as appropriate.

The bit select inputs have internal pull-up resistors to the positive supply, so a switch being open corresponds to a logic 1, and closed to a logic 0. In the transmit mode, these 'bit select inputs' are scanned sequentially to produce the waveforms shown in Fig. 2.

There is no transmit enable facility as such, so the transmission of codes will continue for as long as power is applied, although the mode select pin (pin 15) could effectively be used to stop transmission of codes if required.

In the receive mode the incoming signal is fed into a Schmitt trigger circuit to help to 'clean up' the waveform, and is then compared to the locally programmed code at switches S1 to S12 in a sequential manner. If there is an error in the incoming code compared with the locally programmed code the system is reset

and comparison starts again on the next pulse. If all 12 bits of the code are received correctly an internal 'valid' signal is generated, which clears a 64ms timer and clocks a 3 stage counter. The 3 stage counter is used to count the number of 'valid' pulses, and after 4 pulses, i.e. 4 correct codes, have been received, the receive output goes to a low level, i.e. logic 0. Four valid codes must be received within the 64ms time window or else the system is reset without the receive output ever being allowed to go to a low level. The process must then start all over again. After the receive output goes low (signalling the correct receipt of four valid codes) the next valid code must be received within 128ms. Hence, at least 1 code in 6 received must be valid to maintain the receive output at a low level.

USING THE I.C.

The specification and pinout of the MM53200N are given in Fig. 1. Note that the supply range is only +7 to +11V, limiting its use in some applications but making it ideal for use with 9V batteries. The internal oscillator uses an external 100k resistor and 180p capacitor, as shown in Figs. 3 and 4. Oscillator stability is non-critical, so $\pm 5\%$ tolerance components can be used. As with most MOS logic families the output is much

Characteristic	Notes	Minimum value	Typically	Maximum value	Units
Supply voltage Quiescent current Temperature range Oscillator frequency	All spec's measured over the full supply range For 100k resistor & 180p capacitor (<i>exact</i> values)	7 25 87	9 100	11 12 +70 115	V mA °C kHz
Pull-up resistors	Pins 1 to 12, internally connected to pin 18	200k		1.2M	Ω
Input voltage to pin 16 (receive input) Input voltage to pins 1 to 12 & pin 15	For logic 1 level For logic 0 level For logic 1 level For logic 0 level	4.0 0 (+ve supply −0.5) 0		(+ve supply) 2.0 (+ve supply) 0.5	V V V
Output voltage at pin 17: Logic 1 level Logic 0 level	Output (source) current = 5μΑ Output (sink) current = 2mA	(+ve suppły –0∙5) 0		(+ve supply) 1.0	V V

Fig. 1. Pinout and specification



Fig. 2. Pulse code waveforms



Fig. 4a. I.c. in receive mode



Fig. 4b. Output/input receive waveforms

better at sinking current to 0V than it is at sourcing current from the supply. No maximum current specifications are available from the manufacturer, so to be safe the transmit/receive output should be used either to feed directly into a CMOS input, or to sink current only, at up to 2mA.

The i.c. is almost completely immune to false triggering, largely due to the internal timing which requires valid codes to be received within very definite time windows. Cross interference of devices, even those in very close proximity, is eliminated under almost all conceivable circumstances. However . . , there is

a penalty to be paid! The MM53200N is very critical of incoming waveforms, which must have no 'jitter' on any of the pulse edges and must have a very accurate pulse width or mark/space ratio. The low frequency component of 11.52ms in the waveform, combined with the high frequency demands of accurate pulse width, mean that a fairly wide bandwidth is necessary when communicating between i.c.s. If this communication is via lengths of wire all is well, but when resorting to more esoteric transmission media there can be potential problems! (Many of these can be overcome, of course.) Certainly other types of encoder and decoder i.c.s are more tolerant of serious waveform distortion than the MM53200N, although they cannot usually offer the same high security, high numbers of combinations, or simplicity of use.

TYPICAL APPLICATIONS

One of the main applications of this i.c. is in security based systems, acting as an electronic lock and key. This is the basis of the applications circuit this month, which also incorporates an infra-red optical link designed to overcome waveform pulse width difficulties over short transmission ranges. Although the i.c. is designed to work at 100kHz, this can easily be varied over a considerable range (assuming that both send and receive circuits are modified in the same way). No manufacturer's data is available about the limits of frequency variation; however, several different operating frequencies (spaced apart by much more than 30% to prevent the i.c.s locking to the wrong frequency) could give even more effective combinations of codes.

Consider also the use of the i.c.s in a burglar alarm system; they could pass codes over two out of the four cores used in the interwiring of sensors, and could raise the alarm if the cable was cut, shorted, or otherwise interfered with. The i.c.s could also be used as part of a simple remote control system, with up to 4096 devices actuated by one controller. This would be a fairly expensive exercise, however, since the i.c.s cost several pounds each! The bit select inputs, pins 1 to 12, need not be switch controlled, of course; they could be controlled by a logic system, enabling automatic changing of codes or even 'searching' for a specific incoming code. The i.c. could also be used as a 'transponder'. reacting to the receipt of one valid code with the transmission of another.

The MM53200N is an i.c. which offers a simple solution to a number of encoding and decoding problems, although care must be taken with the quality of code transmission. It is available from Macro Marketing, Burnham Lane, Slough, Bucks SL1 6LN.



THIS is an applications project using the MM53200N as a 'security device'. It consists of two parts: a portable 'key' and a fixed 'lock' which is used to interface with a house burglar alarm, car alarm, electrical garage doors, solenoid operated mechanical lock, or whatever else needs turning on or off. It is an optically based design, using infra-red light to carry the coded signal from the key to the lock. The range was designed to be fairly low, from a few centimetres to a metre or so, dependent on ambient light conditions. This is ideal for locking and unlocking an alarm via a window or windscreen, making the lock and the alarm less vulnerable to being tampered with.

The circuit diagram of the opto-key is shown in Fig. 5. IC1 is used in the transmit mode as already described. TR1, R2, and R3 are arranged so that the output of IC1, pin 17, only sinks current as advised in the specifications. The infra-red emitters, D2 and D3, are driven by the high gain Darlington pair TR3 and TR4. TR2 provides an inverting function between TR1 and TR3 so that the l.e.d.s are turned off when the output of IC1 is at a low



Internal view of the Opto-Key case



PE516A



TIL 38



Fig. 7. Veroboard layout of the Opto-Key

level, and on when the output of IC1 is high. This ensures that the emitters are turned on for as little time as possible, minimising power consumption. D1 protects against misconnection of the battery, and C2 and C3 provide smoothing of the supply.

RECEIVE CIRCUITRY

The receive side of the system is shown in Fig. 6, the 'opto-lock'. D3 is an infra-red detector diode reverse biased by R3. The leakage current through the diode is dependent on the infra-red radiation falling on it. A f.e.t. input amplifier, IC2, amplifies this leakage current variation. R4, R5, and C5 provide a half rail reference voltage at the non-inverting input, which necessitates the use of C3 to decouple the inverting input. R6 sets the gain of this amplifier and C4 rolls off the frequency response to optimise the waveform shape. The output of 1C2 feeds into IC3, which is connected in a non-inverting configuration. R7 biases the non-inverting input to the half rail reference voltage, and C7 decouples the feedback loop. R8 and R9 determine the gain of this stage (471x), the output of which is of sufficient amplitude (normally clipping the rails) that it can be fed directly into the receive input of IC1, which is an MM53200N connected in the receive mode.

The receive output of IC1 triggers a 7555 CMOS timer to give an output duration of a minimum of several seconds when the lock is operated. This output pulse triggers IC5, a Dtype flip flop connected as a divide-by-two counter. The first operation of the key will unlock the system, the next will lock it again, the next will unlock it, etc. The inclusion of IC6 ensures that a wait of several seconds must occur between each operation of the lock, reducing the chances of an unauthorised person quickly checking all 4096 possible combinations!

The output of IC5 turns on TR1, which illuminates the 'lock on' l.e.d. and provides an open collector for turning on a low power relay or operating other circuitry. For solenoid or higher power relay switching, extra buffer circuitry should be provided as required. C9, R10, and R11 provide a power-on reset action to ensure that the lock is always turned on when power is first applied, as a failsafe



Fig. 8. Veroboard layout of the Opto-Lock

measure. To do the reverse, and turn the lock off when power is first applied, interchange pins 8 and 10, i.e. pin 10 should go to R11, and pin 8 to 0V. Finally, because of the specific supply voltage limits of IC1, a +9V regulator circuit has been provided, using IC4 and associated components. IC4 is actually a 5V device, but the resistive divider in the common lead forces it up to a 9V output. The input to this i.e. can be from +12 to +24V d.c., and a heatsink should not normally be necessary unless a relay or other circuitry also have to be driven from the regulated supply.

CONSTRUCTION

The circuits are laid out on Veroboard as shown in Figs. 7 and 8. The opto-key has been specifically designed to fit into a plastic West Hyde 'Tinos' case, type TIN600D. This has internal p.c.b. mounting pillars, a battery compartment with a battery clip provided, and a pocket clip. A momentary action switch \$13 is mounted at the side on the top half of the case, and a space is allowed for its body on the Veroboard. (See the photograph). Holes should be drilled in the top of the case to allow the infra-red emitters to poke through. These should be left standing well clear of the Veroboard surface so that they do protrude when the case is screwed together. When testing the circuit, be aware that these emitters do not show any visible light; if necessery, temporarily replace them with ordinary l.e.d.s, which should glow with a slight flicker when S13 is operated.

8-way (octal) s.p.s.t. p.c.b. switches have been used to program IC1 in both key and lock circuits to allow for flexible code setting. If preferred, of course, these can be replaced with wire links where appropriate. Since only 12 switches, not 16, are used, the last 4 switches in one bank of 8 are unused. Note that the Veroboard tracks beneath these unused 4 switches are left uncut. Needless to say, the switch settings of lock and key should be

exactly the same! The opto-lock is shown uncased since it will usually be fitted in other equipment. Note carefully the orientation of infra-red sensor D3. The sensor tends to be susceptible to visible light as well as infra-red, and although the circuitry will work quite well without optical filters, the addition of a piece of infra-red transmitting filter in front of D3 will enhance performance considerably; use Kodak type 87 or 87c, or their equivalents, available from many photographic suppliers. A simple lens arrangement will also help to collect the available infra-red radiation most efficiently. D3 and D4 have been arranged at the edge of the board to make it easy to fit the unit into an enclosure while leaving these devices board mounted. If D3 must be taken off the Veroboard, use screened cable to connect it, of as short a length as possible. C4 may have to be changed in value to optimise the waveform shape if this is done.

The circuits are designed to work at a range of several centimetres to a metre or so. Under high ambient light conditions, especially artificial light, the range decreases. At very close proximity of key and lock amplifier IC2 saturates badly, distorting the waveform and preventing detection by IC1. If used in this way, reduce the value of R6 or place several thicknesses of paper directly in front of D3 (both on the lock board) to attenuate the signal.

For ranges greater than one metre, try adding extra stages of amplification and possibly pulse shaping. Extra infra-red emitters can be added to the opto-key, with their own driving stages. Ideally, for optimum range, a high frequency carrier should be used. Indeed, in the prototype system a 200kHz carrier was tried, with a wideband receive amplifier and a phased-locked loop i.e. to extract the modulating envelope and feed it to IC1. The range extended to many metres, but jitter on the capture time of the PLL was sufficient to cause IC1 to fail to read the input reliably.



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AUTOMATIC BILGE PUMP

tackle) made suitable probes. The relay should be totally encapsulated and after fitting inside the tube, the tube was filled with potting compound.

It is best to mount the unit close to the centre line of the boat to minimise the effects of movement. The standby current is only a few microamps, probably less than the normal loss of charge of the battery.

G. W. Coles, Polruan, Cornwall.



NE of the chores associated with small boats is the need to bail out rain water etc., often at inconvenient times. Providing a 12V supply is available a small bilge pump will take care of the pumping and the following circuit will ensure the water level is kept to a minimum without constant attention.

A probe is connected to IC1a which is biased so that its output is low, similarly IC1b is connected to a shorter probe and biased in the same way. Both outputs are gated via IC1c whose output is inverted to make TRI normally off. A third probe is connected to the negative supply to complete the circuit.

As the water level in the bilge rises and touches probe 1 the output from IC la goes high but has no effect. If the water level rises further so as to touch probe 2 then TR1 will switch on and activate the pump via RLA1. As the water level drops the pump will remain on as the bias for IClb remains low due to the volt drop at the collector of TR1. As the water level falls further the output of ICIa goes low and the circuit returns to the normal state with the pump turned off.

Obviously the circuit had to be waterproof so it was fitted into a plastic tube. The probes were connected to the circuit board via insulated mains cable. It was found that stainless steel wire (ex fishing

MICROPOWER REGULATOR

HE voltage regulator described here was designed to power a CMOS microprocessor data logger which had to run for several days from Ni-Cad cells without recharging. An ordinary low power regulator such as a 78L05 con-



sumes several milliamps and thus in a circuit with a very low quiescent current, would contribute quite significantly to the current drain of the batteries. The regulator shown here requires approximately 100µA, and thus gives a considerable saving in battery current. The common or garden low power regulator also requires an input voltage which is about 2 volts above the output voltage, whereas the design given here will work with an input only 0.5 volts above the output voltage, so fewer cells can be used to power the circuit.

The 9491 is a bandgap voltage reference which gives a very stable 1.2V and can operate from a current as low as 50µA. This reference voltage is fed to the inverting input of a CMOS op-amp where it is compared with a fraction of the output voltage. The output of the op-amp drives the base of the BC477 and this transistor increases the output current of the op-amp.

If the output voltage Vout starts to decrease due to increasing load, then the fraction of Vout at the non-inverting input of the op-amp decreases and this causes the output voltage of the op-amp to fall, and thus turn the transistor on more and so compensate for the increased load.

Pin 8 of the op-amp sets the quiescent current of the op-amp to one of three values. If it is connected to V+ then the quiescent current is 10µA, if connected to - then the quiescent current is 1mA, and if connected to a voltage between V- and +0.8V or V+ and -0.8V, then the quiescent current is 100µA. Therefore connecting pin 8 to the reference voltage gives a quiescent current of 100µA. The capacitor across the output prevents any oscillation of the circuit.

Using the component values given, the circuit performs as follows.

Vout 5.06V with I0mA load Vin minimum =5.27V with 40mA load Vin minimum = 5.57VNo load current = $112\mu A$

B. Hunter, Monifieth, Dundee.



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