

## (6)RTSIS BlOl POWERTRAN (bantsis 3101 cybernetics

Hydraulic Powered Microprocessor Controlled Robots


With prices starting below $£ 1,000$ the Genesis range of general purpose robots provide a first rate introduction to robotics for both education and industry. Each has a self-contained hydraulic power source, which enables loads of several pounds to be smoothly handled. The system operates from a single phase 240 or 120V AC supply or a 12 V DC supply. The machine can be supplied with up to 6 axes each of which is fully independent but capable of simultaneous operation. Position control is achieved by means of a closed-loop feedback system based around a dedicated microprocessor. Movement sequences can be entered, stored and replayed by use of a hand held controller, alternatively the systems can also be interfaced to an external computer via a standard RS 232C link.


Example prices and specifications

## Genesis S101

Base: $19.5^{\prime \prime} \times 11^{\prime \prime} \times 7.5^{\prime \prime}$
Lifting capacity: 1500 gm
Arm lift: $6.6^{\prime \prime}$
Weight: 29 Kg
4 axis model in kit form $\mathbf{5} \mathbf{3 9 0}$
5 axis model in kit form $£ 445$
5 axis model READY BUILT $\mathbf{£} 790$

## Genesis P101

Base: $19.5^{\prime \prime} \times 11^{\prime \prime} \times 7.5^{\prime \prime}$
Lifting capacity: 2000 gm
Arm lengths between axles: $14.0^{\prime \prime}$
Weight 34 Kg
4 axis model in kit form $£ 495$
6 axis model in kit form $\mathbf{£ 5 9 5}$
6 axis model READY BUILT £950

## COMPLETE SYSTEMS AS SHOWN IN PHOTOGRAPH ABOVE

Genesis S101
4 axis system in kit form $£ 635.50$
5 axis system in kit form $\mathbf{£ 6 9 5 . 0 0}$
5 axis system READY BUILT £1355.00

Genesis P101
4 axis system in kit form $\mathbf{£ 7 4 2 . 0 0}$
6 axis system in kit form $\mathbf{£ 8 5 2 . 0 0}$
6 axis system READY BUILT $£ 1525.00$

As featured in this journal November '81-April'82 issues

For further details please contact:
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| BSX20 |
| BSX29 |









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| $2114 \mathrm{~L}-2$ |
| 2532 |
| 2716 |
| 2732 |
| 411 |
| 48 |
| 61 |
| 652 |
| 652 |
| 682 |
| EP |
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| $2114 L-2$ | $80 p$ | $75 p$ |  |
| 2532 | $365 p$ | $335 p$ |  |
| 2716 | $215 p$ | $205 p$ |  |
| 2732 | $380 p$ | $355 p$ |  |
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| 6820/6821 | $115 p$ | $105 p$ |  |
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| Printer | E489 |  |  |
| EPSON PRINTERS |  |  |  |


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| 8 pin | 8 p | 25p | A 4K Monitor Chip specially designed to |  |  |  |  |
| 14 pin | 100 | 35p |  |  |  |  |  |
| 16 pin | ${ }_{160}$ | $42 p$ 520 | produce th |  |  |  |  |
| 18 pin 20 pin | 16p | 52 p 60 p | Series I \& II, Enhanced Superboard \& |  |  |  |  |
| 22 pin | ${ }_{25}^{25}$ | 70 p | UK 101. As reviewed by Dr, A. A. Berk in |  |  |  |  |
| ${ }^{24} 88 \mathrm{pin}$ | $25 p$ $28 p$ | 70 p 80 p |  |  |  |  |  |
| 40 pin | ${ }_{30 \mathrm{p}}^{28 p}$ | 99p | Practical Electronics, June 1981Price only $£ 12.00+50 \mathrm{p}$ P\&P |  |  |  |  |
|  |  |  | IDC CONNECTORS (Speed block type) |  |  |  |  |
|  |  |  |  |  |  |  |  |
| 28 way 850 p |  |  | PCB PLUG |  | Female Header | PCB P |  |
| DIL PLUGS (Headers) |  |  |  |  |  | Strt Angle |  |
|  |  |  |  |  |  |  |  |  |  |  |  |  |
| Pint Solder 10 C |  |  | $2 \times 5$ way$2 \times 8$ way$2 \times 10$ way$2 \times 13$ way$2 \times 17$$2 \times 20$ way$2 \times 20$$2 \times 25$ way | 90 p |  | ${ }_{700}^{60 p}$ |  |
|  |  |  |  |  |  |  |  |
| $24 \quad 88 \mathrm{p} \quad 138 p$ |  |  |  |  |  | 95p |  |
| 40 195p 218p |  |  |  | ${ }^{255}$ | 169p |  | 135p |
|  |  |  | 2200 2350 |  |  |  |
|  |  |  |  |  |  |  |  |
| Way10162026344060 | Grey | Color |  | EURO CONNECTORS SOCKETS PLUGS |  |  |  |  |
|  | 12p | 22 p |  |  |  |  |  |  |  |  |
|  | ${ }_{25 p}$ | 40 p |  |  | Angle | Sim. |  |
|  | $35 p$ | 520 | DIN41612 | $2 \times 32$ way 300 p |  |  | 295p |
|  | ${ }_{55}^{48}$ | ${ }_{70}^{60 p}$ | dind 1612 | $2(3) \times 32$ way 350p | p 355p | 250 p |  |
|  | 55p 750 | \% 7150 | OiNA1612 | $3 \times 32$ way 375p | P 380p | 260p | 370p |

## 



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| :---: | :---: | :---: | :---: | :---: |
| $\begin{array}{\|c\|} \hline 30 \mathrm{va} \\ 70 \times 30 \mathrm{~mm} \\ 0.4 \mathrm{~kg} \\ \text { Reguation } \\ 18 \mathrm{zam} \end{array}$ | $\begin{array}{\|l\|} \hline 1010 \\ 10019 \\ 10012 \\ 10012 \\ 1013 \\ 1012 \\ 1015 \\ 10016 \\ 1016 \\ 10017 \end{array}$ | $\begin{aligned} & 6+6 \\ & 9+9 \\ & 12+12 \\ & 12+15 \\ & 12+18 \\ & 22+22 \\ & 25+25 \\ & 30+30 \end{aligned}$ | $\begin{aligned} & 250 \\ & 1666 \\ & 165 \\ & 100 \\ & 1083 \\ & 068 \\ & 0680 \\ & 0600 \\ & \hline 050 \\ & \hline \end{aligned}$ | $£ 5.12$ <br> －由o 50 04 －Will 92 <br>  |
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| $\left.\begin{array}{\|c\|} \hline 80 \mathrm{VA} \\ 90 \\ 90 \\ 1 \mathrm{~kg} \mathrm{mon} \\ \text { Agountiven } \\ 12 \% \end{array} \right\rvert\,$ |  | $\begin{aligned} & 6+6 \\ & 9+9 \\ & 12+12 \\ & 15+15 \\ & 18+18 \\ & 22+22 \\ & 25+25 \\ & 30+30 \\ & 110 \\ & 220 \\ & 240 \\ & \hline \end{aligned}$ | 6.64 144 3.33 2.66 2.22 181 160 1.33 0.72 0.36 0.33 |  |
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| :---: | :---: | :---: | :---: | :---: |
| $\begin{array}{\|c\|} \hline 225 \mathrm{VA} \\ 110 \mathrm{manm} \\ 2.2 \mathrm{~kg} \\ \text { Requataon } \\ 7 \% \end{array}$ |  | $\begin{aligned} & 12+12 \\ & 15+15 \\ & 18+18 \\ & 22+22 \\ & 25+25 \\ & 3+30 \\ & 35+35 \\ & 4+40 \\ & 45+45 \\ & 15+50 \\ & 110 \\ & 220 \\ & 240 \end{aligned}$ | 9.38 7.50 6.25 5.11 4.50 3.75 3.21 2.81 2.50 2.25 2.04 1.02 0.93 |  |
| $\begin{aligned} & 300 \mathrm{VA} \\ & 110 \times 50 \mathrm{~mm} \\ & 2.6 \mathrm{Kg} \\ & \text { Rogulation } \\ & 6 \% \end{aligned}$ |  | $\begin{aligned} & 15 * 15 \\ & 18 * 18 \\ & 22 * 22 \\ & 25+25 \\ & 30+30 \\ & 35+35 \\ & 40 * 40 \\ & 45 * 45 \\ & 50+50 \\ & 110 \\ & 220 \\ & 240 \end{aligned}$ | 10.00 833 682 600 5.00 1.29 3.75 3.73 3.33 2.72 1.36 1.25 1.25 | £10．17 <br> －9010 40 <br> ＋崄 5 <br> 101風 11400 |
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$\begin{aligned} & 0.1,7 p ; 0.15,0.22,90 ; 0.33,0.47,13 \mathrm{p} ; 0.68 \\ & 20 \mathrm{p}: 1,123 \rho .\end{aligned}$
$\begin{aligned} & \text { Electrolytic. Radial or axial leads. } \\ & 0.47 / 63 \mathrm{~V}, 1 / 63 \mathrm{~V}, 2 \cdot 2 / 63 \mathrm{~V}, 4.7 / 63 \mathrm{~V}, 10 / 25 \mathrm{~V} \text {. }\end{aligned}$
$\begin{aligned} & 7 \mathrm{p}, 22 / 25 \mathrm{~V},{ }^{47 / 25 \mathrm{~V}, 1 \mathrm{p}: 100 / 25 \mathrm{~V} 9 \mathrm{p} ;} 220 / 25 \mathrm{~V}, \\ & 14 \mathrm{p} ; 470 / 25 \mathrm{~V} .22 \mathrm{p}: 1000 / 25 \mathrm{~V}, 30 \mathrm{p}: 2200 / 25 \mathrm{~V} \text {, }\end{aligned}$
$\begin{aligned} & \text { S0p. } \\ & \text { Tag end Power Supoly Electrolytics. } \\ & 2200 / 40 \mathrm{~V} 110 \mathrm{p} ; 4700 / 40 \mathrm{~V} 160 \mathrm{p} ; 2200 / 63 \mathrm{~V} 140 \mathrm{p} \text {; }\end{aligned}$
$\begin{aligned} & 2200 / 63 \mathrm{~V} 2300 .\end{aligned}$
$\begin{aligned} & \text { Polyester. Miniature Siemens PCB. } \\ & \text { 1n, } 2 \mathrm{n}, 3 \mathrm{3n} 3,4 \mathrm{n7}, 6 \mathrm{n} 8,10 \mathrm{n}, 15 \mathrm{n}, 7 \mathrm{p} ; 22 \mathrm{n}, 33 \mathrm{n} \text {, }\end{aligned}$
50p.
$\begin{aligned} & 0 \cdot 1,0 \cdot 22,0 \cdot 33,0 \cdot 47,1 \cdot 0 @ 35 \mathrm{~V}, 12 \mathrm{p} ; 2 \cdot 2,4.7 \text { : } \\ & 10 \text { @ } 25 \mathrm{~V}, 20 \mathrm{p} ; 15 / 16 \mathrm{~V}, 30 \mathrm{p} ; 22 / 16 \mathrm{~V}, 27 \mathrm{p}\end{aligned}$
$\begin{aligned} & .10 @ \text { @ } 25 \mathrm{~V}, 20 \mathrm{p} ; 15 / 16 \mathrm{~V}, 30 \mathrm{p} ; 22 / 16 \mathrm{~V}, 27 \mathrm{p}: \\ & 33 / 16 \mathrm{~V}, 45 \mathrm{p}, 476 \mathrm{~V}, 27 \mathrm{p} ; 47 / 16 \mathrm{~V}, 70 \mathrm{p}, 68 / 6 \mathrm{~V} \text {. } \\ & 40 \mathrm{p}: 100 / 10 \mathrm{~V}, 50 \mathrm{p} .\end{aligned}$
$\begin{aligned} & \text { 40p: } 100 / 10 \mathrm{~V}, 90 \mathrm{p} . \\ & \text { Ceramic disc. } 22 \mathrm{p}-0.01 \mu 50 \mathrm{~V} \text {, 3p each. }\end{aligned}$
1.8 pF to 100 pF 6 p each.
Polystyrene. $5 \%$ tolerance.
$10 \mathrm{p}-1000$ p 6 p. $1500-4700$ p 8p. $6800-0.012 \mu 10$ p.
$\begin{aligned} & \text { Trimmers. Mullard } 808 \text { Series. } \\ & 2-10 \mathrm{pF} \text { 22p. 2-22pF } 30 \mathrm{p} .5 \cdot 5-65 \mathrm{pF} \text { 35p. }\end{aligned}$

## TRANSFORMERS

## BRIDGE RECTIFIERS RESISTORS

1A 50V 22 6 A 100 V so iW $5 \%$ Carbon fllm E12


serles $4 \cdot 7 \Omega$ to 4 M
$1 W 1 \% M e t a l$
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$10 \Omega$ - $6 p$ each.
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of Colchester. Telephone orders welcome with Access and VIsa. Official orders welcome trom
colleges and schools efci Exportorders no VATbut

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| full spe | REGULATORS

 $\begin{array}{llll}78 L 15 & 30 & 79 L 15 \\ 7805 & 40 & 7905 \\ 7812 & 40 & 7912 \\ 7815 & 40 & 7915\end{array}$ \begin{tabular}{ll|l|l}
7815 \& 40 \& 7915 <br>
LM309K \& 130 \& LM 723

 

LM 317 K \& 350 \& LM338K <br>
LM 317 T \& 120 \& 78 H 5 S <br>
\hline

 475 

65 \& BY 127 \& <br>
\hline
\end{tabular}

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An ideal opportunity for the beginner or the experienced constructior to obtain a
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iW
$.7 \Omega$ to $1 \mathrm{M}(650$ resistors) 480 p . 10 of each value from Ceramic Capacter KKt. Contain.
22 p to $0.014(135 \mathrm{caps}$.) 370 . $22 \mathrm{to} 0.01 \mathrm{~A}(135$ caps.) 370 p.$$
Polyester Capacitor Kit. Contai 0.01 to 1 1.F ( 65 caps.)
Preset Kit. Contains s in (total 65 presets) 425p aach Nut and Bolt Kit. Total 300 items
180p.




## CONNECTORS

## OPTO <br> $\star 3 \mathrm{~mm}$ red

 $\star 3 \mathrm{~mm}$ green $12 \pm 5 \mathrm{~mm}$ red Clips to suit 3p each Rectangular Rectantred
green green
yellow

TIL 38 2N5777 $\begin{array}{ll}40 & \text { ORP12 } \\ \text { TIL100 } \\ \text { TH } \\ \text { Dual }\end{array}$ | Com athode | Com anode |
| :--- | :--- |
| DL704 $0.3^{\prime \prime}$ | 95 |
| DL707 |  |




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 BC548
BC549
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BF200 $\begin{array}{r}10 \\ 10 \\ 10 \\ 10 \\ 18 \\ 10 \\ 30 \\ 35 \\ 35 \\ 50 \\ 50 \\ 30 \\ 30 \\ 30 \\ 35 \\ 35 \\ 110 \\ 110 \\ 85 \\ 35 \\ 35 \\ 25 \\ 25 \\ 12 \\ 12 \\ 12 \\ 12 \\ 10 \\ 18 \\ 30 \\ \hline\end{array}$
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 N以

"...the quality of the colour display is excellent.". Popular Comouting Weekly. "The graphics facilities are great fun"." Personal Computer World. "...the Spectrum is way ahead of its competitors"." Your Computer.

# "The world's best personal computer forunder $f 500$." 

## Sinclair ZX Spectrum 16K RAM $£ 125,48 K$ RAM $£ 175$.

This is the astonishing new ZX Spectrum - a powerful professional's computer in everything but price!

There are two versions -16 K or a really powerful 48 K . Both have a full 8 colours, sound generation, a full-size moving-key keyboard and high-resolution graphics. Plus established Sinclair features such as 'one-touch' keyword entry, syntax check and report codes!

## Key features of the Sinclair

## ZX Spectrum

Full colour - 8 colours plus flashing and brightness-intensity control.
Sound-BEEP command with variable pitch and duration.

Massive RAM -16 K or 48 K .
Full-size moving-key keyboard - all keys at normal typewriter pitch, with repeat facility on each key.

High resolution-256 dots horizontally $\times 192$ vertically, each individually addressable for true high-resolution graphics.

ASCII character set - with upper- and lower-case characters.

High speed LOAD \& SAVE - 16 K in 100 seconds via cassette, with VERIFY and MERGE for programs and separate data files.

The ZX Printer - available now
The printer offers $Z \times$ Spectrum owners the full ASCII character set including lower-case characters and high-resolution graphics.

Printing speed is 50 characters per second, with 32 characters per line and 9 lines per vertical inch.

## ZX Microdrive - coming soon

Each Microdrive will hold up to 100 K bytes on a single interchangeable microfloppy - with a transfer rate of 16 K bytes per second. And you'll be able to connect up to 8 ZX Microdrives to your ZX Spectrum - they're available later this year, for around $£ 50$.

How to order your $\mathbf{Z X}$ Spectrum
BY PHONE - Access, Barclaycard or Trustcard holders can call 01-200 0200 for personal attention 24 hours a day, every day.

BY FREEPOST - use the coupon below. You can pay by cheque, postal order, Access, Barclaycard or Trustcard.

EITHER WAY - please allow up to 28 days for delivery. And there's a 14 -day money-back option, of course. We want you to be satisfied beyond doubt - and we have no doubt that you will be.

## 둠디란 ZX Spectrum

Sinclair Research Ltd,
Stanhope Road, Camberley, Surrey, GU15 3PS. Tel: Camberley (0276) 685311.


## TECHNICALITIES

Our technical post bag is usually varied, very often letters pose us many problems and sometimes they can be impossible. We will always try to answer technical queries on PE projects. What we cannot do is undertake a design or general advice service. It appears that we are now often asked to design circuits to meet readers individual needs, this we simply cannot undertake, nor can we undertake the provision of modifications to PE designs or information on incorporating a PE circuit into other equipment. As we are sure many readers will be aware such data is time consuming to provide; time that PE staff simply do not have.
We sometimes get questions like "। want to start designing circuits, which computer do you suggest I buy?" or even, "I am setting up a lab what equipment do you recommend?" These are rather akin to "I'm going to start driving, which car should I buy?" The assessment must be an individual one based on various factors, e.g. price, size, accuracy required, expandibility, essential functions etc. All we can do in such a case is suggest the enquirer decides exactly what he wants to donow and in the future-then collects as
much data as possible on likely equipment, including magazine reviews etc. and makes a decision for himself, based on that data, individual preference and requirements.

## S.A.E.

We must also point out that our stamped addressed envelope, or addressed envelope and international reply coupons policy is now strictly enforced. A note about letters has been carried at the foot of this page for a number of years but it seems to be increasingly overlooked by readers. Sorry, but this means no s.a.e., no reply.

Please read all the information below so that you write to the correct department in the correct manner. This will help us to help you. Please also make sure that you write about only one project in your letter-if you have queries regarding two or more projects please write them out separately and send them with a s.a.e. each, even if they come in one envelope. Letters are often answered by designers who are not necessarily on the PE staff, so queries on different projects may be answered by different people, possibly in different parts of the world!

## BAZAAR

It seems that Bazaar has been universally welcomed and it is interesting to see the wide range of items on offer or wanted; something for everyone! However, after five months we are still getting a few ads. without the date corner, with out-of-date corners, or ads. which do not comply with our rules. We also get the odd complaint about having to cut out the whole coupon. If you want to save the issue, photostat the coupon or copy it out and send it in with a cut off corner. Sorry, but if you send a stat or a copy, you must cut off the corner, it must be posted within the specified date period and your ad. must comply with the rules. If you don't do these things we will simply not publish it. Since the service is free and the rules are explicit we will not be writing to let you know the situation.

We are pleased to help with the free ads. We are pleased Bazaar is so popular. It would also please us if everyone makes sure they get it right, so we don't have to disappoint anyone.


EDITOR Mike Kenward<br>Gordon Godbold ASSISTANT EDITOR<br>Mike Abbott TECHNICALEDITOR<br>David Shortland PROJECTS EDITOR<br>Jasper Scott PRODUCTION EDITOR

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## Letters and Queries

We are unable to offer any advice on the use or purchase of commercial equipment or the incorporation or modification of designs published in PE. All letters requiring a reply should be accompanied by a stamped, self addressed envelope, or addressed envelope and international reply coupons, and each letter should relate to one published project only.

Components and p.c.b.s are usually available from advertisers; where we anticipate difficulties a source will be suggested.

## Back Numbers

Copies of most of our recent issues are available from: Post Sales Department (Practical Electronics), IPC Magazines Ltd., Lavington House, 25 Lavington Street, London SE1 OPF, at $£ 1$ each including In land/Overseas p\&p. Please state month and year of issue required.

[^1]to UK or overseas addresses, including postage and packing, and VAT where appropriate. Orders should state the year and volume required.

## Subscriptions

Copies of PE are available by post, inland or overseas, for $£ 13.00$ per 12 issues, from: Practical Electronics, Subscription Department, Oakfield House, Perrymount Road, Haywards Heath, West Sussex RH16 3DH. Cheques and postal orders should be made payable to IPC Magazines Limited.

Technical and Editorial queries and letters (see note below to): Practical Electronics, Westover House, West Quay Road, Poole, Dorset BH15 1JG
Phone: Editorial Poole 671191
We regret that lengthy technical enquiries cannot be answered over the telephone

Queries and letters concerning advertisements to: Practical Electronics Advertisements, King's Reach Tower, King's Reach, Stamford Street, SE1 9LS Telex: 915748 MAGDIV-G

## Edited by Jasper Scott

# Distel Duta Base 

## Once again, the hobby electronics world has come up with another firstthis time in the area of customer service.

Display Electronics, well known to most readers as suppliers of components and surplus electronic equipment, now offer a new service for customers known as Distel.

Distel is a data base with a multi-port dialling system: anyone whose computer system is equipped with a 300 baud modem or acoustic coupler can dial in 24 hours a day, seven days a week to check what is currently in stock and place orders. A credit card facility is available, and schools or colleges can even use their official ordering systems.

Managing Director Dave Fisher believes that Distel is the UK's first free-of-charge public access data base-all it costs the user is his initial phone call. Distel uses European Standard CCITT modem tones, and software is fully interactive, allowing the user to search through the data base.

For anyone who would like to make use of this facility. the telephone number of Distel is $01-683 \mathrm{l} 133$. Alternatively, if you would like further details of the service, call Display Electronics on 01-689 7702.

## Fair News

It won't be fair it should be marvellous. That's the Electronic Hobbies Fair that PE, PW and EE are organising later this year for all those interested in the various aspects of electronics. As last month's Countdown stated "taking exhibitions for the amateur a bold step forward". The details are given below and our photo shows the exciting new venue at night in it's lakeside setting.

Electronic Hobbies Fair, Alexandra Pavilion, Wood Green, London. November 18th - 21 st 1982.

There will be free car parking and a special bus service to the station. The Fair will include special exhibits and demonstrations.

For further information about the show read this column next month.

## MICRO-STRIP

Micro-strip is a self adjusting wire stripper which will deal with rall p.v.c. and some thermo-resisting insulations.

A self adjusting floating cam adjusts the stripper's mechanism to the correct stripping depth and at the same time automatically sets the gripping pressure exerted on the insulation by the jaws, thereby preventing damage to the insulation.

The Micro-strip will deal with all sizes of wire up to a maximum of 1.5 mm diameter without any adjustment; for very thin or very thick insulations, an adjustment mechanism is provided.

The Micro-stripper is priced at $£ 17.85$. from $A B$ Engineering, Timber Lane, Woburn, Milton Keynes MK17 9PL.


## Briefly...

Components and p.c.b., for the PE Quasar Stereo Cassette Deck described in the April and May issues are now available as a separate package from RTVC Ltd. This kit will allow the updating of almost any tape or cassette recorder mechanism at a cost of only $£ 18.95$ including VAT plus £1.40 post and packing. Mail order only to RTVC, 21b High Street, Acton W3 6NG. Callers to 323 Edgware Road, London W2.

Not quite a new catalogue but one with a new addition is available from Semiconductor Supplies International Ltd. Their $81 / 82$ catalogue is now accompanied by a free 82/83 Eagle International catalogue which carries a very wide range of consumer products from amplifiers and intercoms to test gear and security equipment.
Semiconductor Supplies own catalogue covers a particularly good range of i.c. devices - as their name would suggest - is 88 pages whilst the Eagle catalogue is 84 pages and virtually all in full colour.

Just send $£ 1$ to Semiconductor Supplies International Ltd., Dawson House, 128/130 Carshalton Road, Sutton, Surrey SM1 4RS (01-643 1266). Incidentally $p \& p$ on the two catalogues must amount to nearly £1 anyway.

## POINTS <br> ARISING <br> AUTOMATIC SIGNAL SWITCHING (July '82)

IC1 and IC2 should both be 7805 regulators. The components list contains a misprint.

INFRA-RED TAPE CONTROL (July '82)
Transistor TR1 is a BC461, not BCY 461 !
CAR BATTERY CONDITION
INDICATOR (March '82)
In Fig. 2 the cut-out shown at G16 should be moved up to F16.

Items mentioned are available through normal retail outlets unless otherwise specified. Prices correct at time of going to press.

## CASIDTONE CT-1OIP

Casio, who must already have made other companies in the electronic musical instrument business feel positively uncomfortable have now come up with an offering that will surely have those companies' directors quaking in their boots!

The Casiotone CT-1000P, which Casio describe as a digitalised synthesiser can produce up to 1000 different sounds, all with eight-note polyphony, by

varying combinations of three elements-FOOTAGE, ENVELOPE, and MODULATION. Each element has ten different settings, thus giving 1000 possible combinations. A memory facility allows you to store up to ten settings for instant recall-a particularly useful feature if you are playing on stage.
As if this were not enough in itself, the CT-1000P also features a programmable arpeggio function which combines arpeggio patterns and can also be used as a sequencer; and a range of ten preset sounds. In addition, the CT1000P boasts sustain and various vibrato effects, a pitch control which incorporates a transposing function, and a built in speaker for home use.

Recommended retail price for the CT-1000P is an incredible $£ 375$, and we know already of one company offering a substantial discount- $£ 325$ is the all inclusive price being quoted by Tempus, 38 Burleigh Street, Cambridge, CB1 1DG (0223 312866 ).

## Toundidun

Please check dates before setting out, as we cannot guarantee the accuracy of the information presented below. Note: some exhibitions may be trade only. If you are organising any electrical/electronics, radio or scientific event, big or small, we shall be glad to include it here.

ICCC 82 (Computer Communication Conf.) Sept. 7-10. Barbican $O$ BEX Reading (Business Equipment) Sept. 8-9. Hexagon Cntr. K BEX Manchester Sept. K
Personal Computer World Show Sept. 9-12. Barbican Cntr. London M Laboratory London Sept. 14-16. Grosvenor Ho. Park Lane, London E ElectroWEST Sept. 14-16. Bristol Exhibition Cntr. Q
Two Counties Fair Sept. 15-18. Plymouth Exhibition Cntr. Millbay, Devon $\mathbf{T}$
IBC (Int. Broadcasting Convention) Sept. 18-21. Metropole, Brighton N
Microprocessors In Audiology Sept. 24 A7
Holographic Techniques Sept. 30-Nov. 28. Light Fantastic Gallery, Covent Gdn. London A8
BEX Basingstoke Oct. 6-7. Ladbroke Mercury Hotel K
BEX Cardiff Oct. K
Viewdata Oct. 12-14. Wembley Conf. Cntr. London O
Video Show Oct. 16-18. West Cntr. Hotel, London Z1
Computer Graphics Oct. 19-21. Royal Gdn. \& Bloomsbury Cntr. London 0
Testmex Oct. 26-28. Wembley Conf. Cntr. T
BEX Southampton Oct. 27-28. Polygon Hotel K

## BEX Plymouth Nov. 10-11. Holiday Inn K

Compec Nov. 16-19. Olympia Z1
Hobby Electronics Fair (is this a new concept?) Nov. 18-21. Alexandra Palace, London $\mathbf{Z 1}$
BEX Bristol Nov. 24-25. Holiday Inn K
Christmas Holography (+ items for sale) Dec. 2-Mar. (1983). Light Fantastic Gallery, London A8
ElectroNORTH Dec. 7-9. Harrogate Supercenter Q
IT82 (Information Technology Year Conf.) Dec. 8-9. Barbican 0
Continuous exhibitions at the National Microprocessor \& Electronics Cntr. (nr. Tower of London) L1
BEX Bournemouth Feb. 9-10 1983. The Pavilion K
Brighton Electronics March 1983 T
BEX Leeds Mar. 16-17. Dragonara Hotel K
INSPEX Mar. 21-25 1983. National Exhibition Cntr. Birmingham International Z1
HEVAC (Heating, Ventilation \& Air Cond.) Apr. 26-28 1983. Barbican I
Sem̄lab June 1983. Olympia, London I
A7 Institute Of Acoustics $\boldsymbol{\beta} 0312252143$
A8 Holographic Exhibitions P 01-836 6423
E Evan Steadman $\wp 079922612$
I Industrial Trade Fairs 80217056707
K Douglas Temple Studios 0020220533
L1 World Trade Cntr., Europe Ho., London E1
M Montbuild ©01-486 195
N Institute Electrical \& Electronics Engineers
O Online 60927428211
Q Exhibitions For Industry $\int 088334371$
T Trident 608224671
Z1 IPC Exhibitions / 01-643 8040.

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Portable and simple to use by non-technical staff in the REPAIR SHOP or on the PRODUCTION LINE, MD tests ROM, RAM \& $1 / O$ and prints diagnostic reports. MICRODOCTOR can be plugged into an unknown system to perform a general diagnostic and print a MEMORY-MAP. The ENGINEER may enter sequences
of CHECKSUMS and RAMTESTS.
READS and WRITES to specific MEMORY and I/O locations, SHORTING tests on DATA and ADDRESS LINES. PRINT-OUTS of memory in ASCII or HEX.
These sequences are retained in CONTINUOUS MEMORY. available always at the push of a key.

* FREE Z80 DISASSEMBLER with each MD
(other disassemblers soon to retrofit at low cost)
Get a DISASSEMBLER LISTING of ROM in any microsystem!
MICRODOCTOR - E295.00


Good tools need not be expensive. SOFTY 2 is the latest version of the engineer's favourite EPROM HANDLER. for anybody who uses $2516,2716,2532$ and 2732 EPROMS. SOFTY will program any of these EPROMS or copy any type into another. SOFTY puts out a TV picture of memory contents, with many code-manipulating and editing facilities.
There is also a fast cassette data storage system. SOFTV is also a ROMULATOR (a lead is supplied which may be inserted into a board under development to emulate the ROM using SOFTY's internal RAM. This procedure can also be used on the single-chipper piggy-back type MPU.) SOFTY is complete in itself as a PRODUCT DEVELOPMENT SYSTEM.

SOFTY 2 - £169.00

## Z80 DEVELOPMENT SYSTEM

MENTA puts out a TV PICTURE of memory in hexadecimal. The 40 key keyboard will accept inputs, both in hexadecimal and $Z 80$ mnemonics; there is a quick cassette data storage system, a powerful editor which permits program debugging by showing contents of registers and stack Also there are 24 bits of $1 / 0$ for external control. A Z80 disassembler is also available which outputs to any RS232 device such as a printer or terminal.
MENTA was designed as a low-budget device for teaching microprocessing in schools: professional course-material is available to teachers together with add-on boards for a variety of control functions and robotic applications
MENTA - £115.00
SERIAL DISASSEMBLER - £19.50
Manufactured by Dataman Designs, sold by dealers in UK, USA. France, etc. TRADE ENQUIRIES INVITED - TELEX 418442 DATAMAN


The brand-leader in Japan; gaining ground rapidly in America; this beautifully made, reliable system has all the features you could want at the right price. See it! Try it!
8001 Keyboard Unit
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(100 CPS, up to 136 columns, proportional spacing. greek and math) £399 8031 Dual Disk Drive E669 8043 Colour Monitor

All CPM software is available


## THANDAR TA2080 - £1950

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A value-for-money instrument with both TIMING and STATE capture and display and excellent triggering from 23 bits.
We are designing RS2 32 and IEEE interfaces, $Z 80$ and 8048 disassemblers for our own use, which will be available when tried and approved by Thandar. PLEASE PHONE FOR PRICES

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Prepaid or credit card orders normally shipped by return. Prices include first-class recorded post in UK
Securicor. Red Star, etc. at extra cost.
VAT should be added at current rates.


## Atlas Saga

Twenty years ago the conventional wisdom in computers was 'big is beautiful' True, second generation computers were appearing with transistors instead of thermionic valves which helped shrink physical size but the accent was on big in performance. The yardstick was not on capital cost but cost per calculation per second.
Using this formula the mammoth mainframe computer seemed justified. IBM, the world leader, set the pace with the 7030 Stretch capable of performing more than a million logical operations per second Ferranti, one of the British pioneers in association with Manchester University, went bigger and better with Atlas with a prototype installed at Manchester in 1961 described triumphantly in the Daily Telegraph as the most powerful computer in the world. It cost the then enormous sum of $£ 2$ million.

Computer industry historians record that both Stretch and Atlas were expensive flops. Performance in both cases fell short of expectations. Four years after the prototype Atlas had been installed at Manchester another Atlas at London University was still disappointing its users despite the injection of additional expertise from ICT (later to become today's ICL) who by this time had taken over Ferranti's large mainframe interests. To be fair the difficulty was not so much in the giant hardware but in software where the problem had been grossly underestimated. The thousands of tasks planned to be undertaken by the mighty number-crunching Atlas had to be clipped back to hundreds and the balance transferred to other machines.

The costly experiment didn't automatically lead to a reversal of policy to 'small is beautiful' but from then on there was a trend to smaller modular units, more manageable, which could be grouped into larger units. Later, we progressed through the mini to the micro and to distributed data processing. Over the years the
hardware/software cost ratio has also changed dramatically. The home computer hobbyist can check this for himself by charging a notional commercial rate of, say, £10 per hour for programming time compared with his once-for-all capital outlay in the low hundreds.

There are still jobs which need some mammoths although today they are described as ultra-high-powered. And, as in the battle for size two decades ago, the competitors are again IBM and ICL. And ICL, in challenging IBM, have chosen to resurrect the old name Atlas for two new systems, the Atlas 10 , Models 15 and 25.

Naturally enough after 20 years today's Atlas is very different in architecture, type of components, speed and overall capability. It is an entirely different beast owing little of its ancestry to Ferranti or Manchester University or even ICL. It is in fact made in Japan by Fujitsu, a name unheard of in computer science in the days of the original Atlas.

## Challenge

The Atlas story dramatically illustrates the changing balance of technological power. Japan has not yet achieved superiority in every field but has been successful in all that have been systematically attacked. In cameras, motorcycles, shipbuilding, cars, consumer electroncs and now, we have to assume, the drive is on to achieve market dominance in professional and capital goods electronics, perhaps to be soon followed by defence electronics, challenging the leading companies in the United States and Western Europe.

History is repeating itself. Only the geography has changed. As Japanese success in consumer electronics decimated the domestic industries of Western Europe and the United States, so Japan's own industry is under increasing threat and pressure from the torrent of consumer electronics from Hong Kong, Singapore, Korea and Taiwan. Japan today is in the same position as the UK a decade or so ago, forced to go up-market to keep factories emplyed because their original products can now be made more cheaply elsewhere.

Looking round the globe we find other nations learning fast. Space vehicle launchers are no longer exclusive to the Soviet Union, the United States and Western Europe. Japan has her own as has India and China. Indonesia put up a satellite some six years ago. The Arabs and some South American countries are also beginning to get involved in space technology. Most still depend on technical assistance from the Eastern or Western blocs but Third World countries must eventually achieve a degree of technological independence.

Happily electronics remains an expanding world industry and newcomers can still be accommodated, albeit at the risk of increasingly growing competition. With a labour-cost handicap the West's relative position can be maintained only by keeping a jump ahead in technology and, as the Atlas story shows, this is no easy challenge when a vigorous young pupil can so easily surpass an ageing tutor.

## Push-button War

All the world's military experts have been and still are evaluating, electronic sensors and weapons systems deployed in the battle of the South Atlantic. It might have been imagined that sophisticated weapons with built-in 'intelligence' operating at great range by remote control would have been the decisive factor. In the event this was no push-button war. Foot-slogging, blood-andguts discipline, courage and traditional rifle, machine-gun, mortar and artillery fire were the main components of the land battle rather than the electronic battlefield predicted and promoted by defence equipment salesmen.

The French-built Exocet anti-ship missile was the nearest thing to push-button war. Its stand-off fire-and-forget concept was effective but its hit rate was nowhere near 100 per cent although it is not yet clear whether the misses were missile malfunction or efficient defensive electronic countermeasures (ECM) by British warships. At some 200,000 US dollars each the Exocet is a cheap weapon if it sinks a ship but an expensive failure if it doesn't. Exocet is big business with over 1,000 missiles delivered to 20 countries including the UK.

Exocet first appeared in 1972. The new generation British Sea Eagle, barely yet in service, is said to have a stand-off range of 100 km compared with Exocet's 50 km . Another new British system was not available for the crisis. This was Nimrod Mk III airborne early warning and control system (AWACS) of which eleven are on order. But even had they been available it is hard to imagine how they could be maintained flying over the battle area so far from Ascension Island, their only possible base. Lack of AWACS allowed low-flying aircraft to close-in on warships with only limited warning time from shipborne radar. Thus, British casualties have to be judged taking into account the self-imposed handicaps as well as those of distance and climate.

From $3,500 \mathrm{BC}$ to the present day there have been 14,500 recorded wars and only 292 years of peace according to Francis A. Beer in his book "Peace Against War".

## Outlook

All the leaders in UK electronics turned in good half year results with defence contractors Plessey, GEC, Racal and Ferranti all showing gains in profits and turnover. This due, of course, to delivery on past orders all .pre-Falkland. Post-Falkland business is expected to be brisk following re-appraisal of future defence needs and replacement of lost equipment. But in the non-defence sector there is plenty of optimism with Cable \& Wireless, for example, nearing the $£ 100$ million pre-tax profit milestone.

Thorn-EMI have survived the worst of the recession but streamlining savaged the workforce by some 30,000 . Chairman Sir Richard Cave will be pleased to have seen a leading stockbroker forecasting substantial profit improvement for 1983 and 1984. Apart from being the biggest TV and VCR rental company in Europe the company has a number of important defence contracts.

# IIENIA Review... 

## DAVID WHITFIELD м.A. м.sc.

## MENTA-Micro Electronic mNemonic Teaching Aid

IEARNING about microprocessors is best done in a practical fashion, at machine code level on a CPU which is an accepted industry standard in its field. This was recognised in the original specification for "Auntie"s Micro" (subsequently better known as the BBC Microcomputer), which called for a Z80-based design with good support for machine code programming, as well as BASIC. Although other pressures eventually led the BBC to adopt a non-Z80 design, the exercise does give an indication of the wide degree of acceptance gained by the $\mathbf{Z 8 0}$ since its introduction by Zilog in the late 1970's.

The Z80 was developed by Zilog as a "super-8080", an 8-bit third-generation that would do everything that the then standard Intel 8080 would do, and then much more. The result was a product which has found wide acceptance in many fields of control and stand-alone applications. The 158 instructions offered by the $\mathbf{Z} 80$ include the full 78 instructions of the 8080 , thereby providing software compatibility with the 8080 , and increasing its already considerable appeal.

In the field of popular microcomputers, the $\mathbf{Z 8 0}$ is used as the CPU in the Sinclair ZX81, Tandy TRS-80 and Video Genie, to name but a few. These alone represent a user base of over a million systems. The majority of these machines, however, concentrate in the main on the support of BASIC, The Beginner's All-purpose Symbolic Instruction Code. These systems are mainly concerned with applications programming; the user is usually not even aware of the variety of CPU which lurks behind the keyboard.

The MENTA is not part of the common trend in home computing, and it does not support BASIC in any shape or form. The MENTA is dedicated to teaching how to program and use the Z 80 for control applications; it provides a unique opportunity to use a microprocessor to actually DO something. An unusually powerful in-built keyboard assembler and television display facility support a novel approach to learning and using assembly language. The facilities of the MENTA take much of the pain, in terms of both effort and cash, out of the process of learning how to use a real microprocessor in its native environment. Direct comparisons with other systems are difficult; many of the facilities are only offered on microprocessor development
systems or mini-computer systems costing upwards of 10 to 20 times the cost of the MENTA. The MENTA lays down a challenge to the user, provides the necessary facilities, and encourages the development of microprocessor based controllers for real applications.

## FIRST IMPRESSIONS

The MENTA comes securely packed in a cardboard box measuring approximately $250 \mathrm{~mm} \times 180 \mathrm{~mm} \times 100 \mathrm{~mm}$. Inside the box is a complete MENTA system, and only a mains outlet and a domestic u.h.f. television (set to the ubiquitous channel 36) are required to start programming in assembler. The package includes the MENTA itself, an a.c. mains adaptor with integral 13A plug, a television lead to suit a standard TV coaxial socket, and two manuals. The two unlabelled $\mathbf{A} 5$ sized booklets turn out, on inspection of the contents (in the absence of titles), to be the instruction manual and a listing of the monitor ROM.

The first impressions of anything new are always to be treated with care, but initial reaction to the MENTA is rather mixed. The main unit comes housed in a rather strangely contoured vacuum-formed black $A B S$ case a little larger than a Sinclair ZX81. The case is in two distinct halves, the top half of which covers approximately two-thirds of the bottom half, and the two halves are held together by four plastic fasteners (which are not easily separated). The case design seems to owe its origins to the Softy 2, also from Dataman Designs, but does nothing to enhance the appearance of the MENTA.

The keyboard is fabricated directly on the main circuit board on the part which extends beyond the limit of the top half of the case. The flat plastic keyboard is made using silver printing technology and contains 40 clearly marked keys. The keys represent the hexadecimal digits 0 to F , and the rest are used for control and editing functions. When the keyboard assembler is in use, most keys have further functions for entering assembler mnmonics; no key has more than three functions, and no shift keys are necessary. The keyboard layout is shown reproduced in Fig. 1. The plastic surface is relatively immune to dirt and dust, and can easily be cleaned with a soft cloth.

Fig. 1. MENTA keyboard layout


The great improvement of the MENTA keyboard over that of, say, the ZX81 is the audible feedback provided for the user. Each keystroke is accompanied by a short bleep, or by a squawk if that stroke represents an invalid operation. This saves much of the tiresome and continual looking up at the television screen in order to check whether the keystroke has registered or not.

At the top right of the keyboard are a seven-segment l.e.d. display, which stands proud of the board, and a 26-pin input/output connector. This connector has long exposed pins which must be susceptible to accidental damage, and which are certainly painful if encountered while trying to pick up the unit! At the rear of the unit there are sockets for connecting the power supply, television and cassette recorder. The sockets are not labelled in any way on the case, and it is necessary to refer to the manual to be sure of making a correct connection; the same comment applies to the I/O connector. From the outside therefore, the first impression is of a unit with a full range of facilities, but rather bizarre styling and inadquate labelling of connectors.

Removing the top cover from the MENTA immediately moves one to wonder why such a high quality board is hidden by such an uninspiring cover. The main circuit board is a neatly designed, well laid out, double-sided fibreglass printed circuit board. The major i.c.s are all fitted in sockets, and the top surface of the board is coated and then screen printed to simplify identification of components from the circuit diagram in the manual. The CPU, PPI and monitor ROM occupy the space immediately above the keyboard. The piezo-electric audio unit, Astec u.h.f. modulator and tape/power sockets are at the back of the unit. In the middle of the board is the quartz oscillator, counters, RAMs, and assorted logic i.c.s. One very neat feature of the board is the way in which the metal case of the television modulator is used as a heatsink for the voltage regulator i.c. All in all, a very nicely constructed board, well laid out and neatly labelled.

## SYSTEM DESCRIPTION

The overall MENTA system incorporates a Z80 CPU, 2048 bytes of read-only memory (ROM), 1024 bytes of random access memory (RAM), a programmable peripheral interface (PPI), a 40-key keyboard, and all of the circuitry necessary to drive a standard u.h.f. television receiver as a display unit. Additional features include a 7 -segment l.e.d. display to give prompts and information to the user, a cassette tape recorder interface for storing and retrieving programs, and a miniature loudspeaker. Power for the unit is provided by a separate a.c. mains adaptor which has an integral 13A plug, and which works in conjunction with the internal voltage regulator to provide power for the MENTA circuitry. The PPI also provides three 8bit input/output (I/O) ports for hardware control applications.

As with any system, the hardware provided should be considered in the light of how it is, configured, and the manner in which it performs its functions. A block diagram for the MENTA is shown in Fig. 2, showing a conventional two-bus structure. At switch on, the Z80 CPU is started up under the control of the monitor program stored in ROM. The monltor is the program to which the user "talks" in order to make the MENTA perform the functions which are required. The monitor is responsible for detecting and identifying, via the PPI, keyboard depressions, and for deciding what action is to be taken, if any. As previously mentioned any valid keyboard entry echoes a short "beep", whereas an invalid entry evokes a rather appropriate "squawk". In addition, the monitor drives the television display (doing most of its processing during the line blanking interval), and via the PPI, handles the loudspeaker, cassette tape interface, and the I/O ports.

The monitor is a program which is permanently stored in


Fig. 2. Block diagram for the MENTA system
ROM, and as such it cannot be modified by the user. In order to write applications programs, the user is provided with an area of RAM, and enlists the services of the MENTA's powerful monitor facilities to enter the necessary instruction codes into the RAM area of the memory. Once satisfied that the stored program is correct, the user instructs the monitor to pass CPU control from the monitor to the program in RAM and RUN the program. At the end of the program, or when the program is halted, control is returned to the monitor for possible further user action or modification.

## USING MENTA

Switching on the MENTA produces a display on the television screen of 256 pairs of numbers. Closer inspection shows that the numbers are in hexadecimal notation. For display purposes, the user RAM area of 10248 -bit locations starting at address $F 800$ is separated into four discrete pages each of 256 locations, identified as pages 0 to 3 . These pages, therefore, will display the contents of the 256 ( 100 HEX) locations starting from $F 800$, F90 , FA $\emptyset \emptyset$ and $F B \emptyset \emptyset$, respectively, with the addresses for each row of the display incrementing by 10 HEX . The manual advises the user that the last $3 \frac{1}{2}$ rows of page 3 (locations FBC7 to FBFF inclusive) are reserved for use by the monitor; the details provided allow the user to gain an interesting insight into the operation of the MENTA's monitor. At any time, the display shows the contents of the page which is identified by the seven-segment display; at switch-on the display comes up at page 0. Different pages are selected by the PAGE key, followed by the required page number (illegal page numbers are ignored).

The initial contents of the memory are random and the whole of the user RAM may be cleared at switch-on by operating the CLEAR key twice. This double operation is a deliberate safety feature included to prevent accidental loss of a program from memory. Similarly, the press-twice feature is provided on the RUN key. The CLEAR key actually zeroes the RAM locations from the current cursor position up to the start of the monitor RAM (FBC7). Movement of the flashing cursor is by four direction keys (UP, DOWN, LEFT, and RIGHT).

Auto-repeat is a facility provided to assist in rapid positioning of the cursor; holding the required key down will cause the cursor to move at a rate of approximately three positions per second. Full row and column wrap-around is implemented, with the next position RIGHT from the end of a row being the start

of the next row, and similarly for pages; page 0 follows page 3 in the normal wrap-around scheme. The HOME key causes the cursor to return to the start of the current page. The cursor is automatically reset to this home position whenever the PAGE key is used to move between pages.

There are two distinct methods of entering machine code instructions into the MENTA's RAM storage area. The first method will be familiar to users of many microprocessor evaluation systems and involves entering the hexadecimal instruction codes into memory directly. The second method is a significant advance over the first and it uses an in-built ROM-based keyboard assembler to allow keys representing the standard Z80 instruction mnemonics to be used to enter instructions into memory. Both entry methods are well supported by the monitor and the features of each will be considered in turn.

## PROGRAMMING IN HEX

Entering programs in hex is simply a matter of positioning the cursor at the selected memory start address, and then typing in the hex instruction codes. The cursor automatically moves on to the next location whenever two hex digits have been entered; this does, however, mean that leading zeroes must be used in entering codes. Correction of errors is simply achieved by using the LEFT cursor shift key, followed by retyping the 2 -digit code. At the end of the program, the user includes an ' FF ' to cause the program to return control to the monitor. The program is started by positioning the cursor at the start address, and then typing the RUN key twice. Should the program run out of control, it may be stopped using the INT or RESET key, which causes the monitor to resume control. The program may be stepped through one instruction at a time using the STEP key to monitor its operation in detail (the contents of the registers are displayed at the bottom of page 3, and readily accessed using the REG key).

## USING THE KEYBOARD ASSEMBLER

The keyboard assembler is started by pressing the ASMBL KEY. This causes the top bar of the l.e.d. display to be illuminated, indicating that the next keystroke will be interpreted as the instruction mnemonic printed in blue above the next key. Once the first mnemonic has been entered, the bottom bar of the l.e.d. will be illuminated, showing that the mnemonic marked in red below the next key will be entered. Some instructions will prompt for more than one red-coded mnemonic to be entered. When all of the necessary mnemonics (up to 3 ) for the instruction have been correctly entered, the instruction will be assembled and entered into memory, starting at the current cursor position. The cursor will then move on to the next available memory location and the top bar of the l.e.d. will again be illuminated, indicating that the assembler is ready for the next instruction. The instruction codes do not appear on the display screen until a particular instruction has been completed and assembled. An error during the entry of an instruction will produce a "squawk", and the instruction must be re-started.

The assembler handles 94 per cent of the Z80's instruction codes; the remaining 6 per cent must be entered in hex directly. This may be easily done by using the ASMBL key to leave the assembler, keying in the appropriate box code(s), and then using the ASMBL key again to return to the assembler mode from the direct mode. When the keyboard assembler is used to enter code, the first byte of each instruction is automatically highlighted to assist the user in identifying steps in the program.

One of the significant advantages of the MENTA is the way in which jump offsets and addresses do not need to be worked out by hand. When an address is required for a jump instruction, the user leaves the assembler, moves the cursor to the first byte of the target instruction (which will have been highlighted by the assembler), and then types the STORE key. The cursor is then
returned to its original position and the RECALL key is used to enter the jump absolute address or jump relative offset, as appropriate to the instruction selected.

The keyboard assembler puts the MENTA in a class of its own; the traditional hex entry method is retained, but programming the Z 80 in the more familiar mnemonic codes is provided with the minimum of fuss. A significantly larger and more expensive system would be required before any greatly improved facilities would become apparent to the average user.

## USER DOCUMENTATION

The manual describes the MENTA as "a product made to teach microprocessor application", and the typical user as "a trainee engineer or system designer". It is also mentioned in the introduction to the manual that the MENTA has been designed to meet the requirements of the School's Council's Project "Courses in Modular Technology".

The user documentation provided with the MENTA comprises two A5-sized manuals. The primary, and much the thicker, manual contains approximately 150 pages, of which the first half is the real user guide. This is followed by a 10 -page alphabetically ordered listing of the Z80's instruction set. Further appendices contain hex conversion and ASCII code tables. The final 40 or so pages are taken up by two data book extracts; a 19 -page data sheet on the 8255 PIA chip, and a 22 page data sheet on the Z80 CPU. The secondary manual contains a copy of the 80 -page assembler listing of the MENTA's monitor program.

The primary manual, while easily readable, is somewhat sparsely illustrated and lacks either an index or contents list. The manual does, however, contain a great deal of useful and helpful information, and even includes a complete circuit diagram. The order of presentation of the material in the manual, even allowing for the fact that the manual is not intended to be a teach yourself text, leaves much to be desired. The first sample program, for example, is introduced one-third of the way through chapter one, but it requires the user to "first read quickly through chapter 2 ", before proceeding. This first program is presented before any discussion of the Z80's CPU has occurred.

The purpose of each example in the text is well explained; the way in which the program achieves its objective, however, is not well covered. This seems a rather strange omission for such a system. The examples are presented as hex codes, with assembler listings given towards the middle of the manual. The listings, however, also err towards providing information on what the programs do, rather than how they do it. The number of examples (three) is rather low, and none are included to cover the latter part of the user text.

The latter part of the user text covers the subjects of I/O and control applications in some detail. This is really what the MENTA is all about, and this section would be excellent if it were extended to include some practical experiments for the user to try, and some sample listings. Much interesting and useful information is included on how hardware should be driven from the I/O ports; further guidance on some aspects of writing software for control applications would have been extremely useful.

In general, the individual user will probably benefit greatly by reading one of the standard Z 80 programming books in conjuction with the MENTA manual. The manual otherwise relies heavily on the user studying the Z 80 data sheet (not an idea! primary learning text even for an experienced microprocessor design engineer) for details of the Z80 instruction sheet and architecture. Such an additional text should also provide some practical examples in order to complete the picture. It should be mentioned, however, that the School's Council's Course for the

MENTA is intended to provide the complete support for the system. Course material is available which extends far beyond the scope of the standard user manual.

## CONCLUSION

The MENTA provides a well supported and cost effectiveapproach to learning assembly language programming, with particular reference to control applications. The choice of a Z 80 as the CPU makes this a particularly relevant system to the real world of microprocessor-based applications. The system encourages the adoption of a microprocessor design for roles at which they excel; the replacement of large amounts of dedicated combinational logic by a programmable controller, allowing many changes to be accommodated simply by changes in the software.

The facilities offered by MENTA have been well thought out, and then implemented in a way which minimises many of the difficulties normally associated with low-level programming teaching. The user feels encouraged to start programming, and the keyboard mnemonic assembler removes the need for continual reference to lists of hex instruction codes. The flat keyboard is well complemented by good audible feedback facilities. Program debugging is also well supported, with single stepping and the facility to examine and change registers simply at any step. The cassette tape interface allows the final program to be built up over a number of sessions, and an option is available to allow the program to be sent over a serial link to, say, a PROM programmer, if required.

The MENTA is made in the UK by Dataman Designs, Lombard House, Cornwall Road, Dorchester, Dorset, DT1 IRX; telephone 0305-68066. The one-off price is $£ 115.00$, and the dis-assemble option to produce a serial output link is $£ 19.50$; prices exclude VAT.



## SURROUND SOUND

British patent application 2067057 , from the IBA, offers a useful, and clearly worded, run down on the current state of play over broadcast surround sound. The patent application, naming Jonathan Halliday as the inventor, was filed on 19th December 1979, just two days before a press release from the IBA announcing the development of the "MSC" (Mono-Stereo-Compatible) system of surround sound. This followed a June announcement by the IBA engineers that they had reduced the number of practical options of surround sound to two "irreconcilable" approaches. These are the NRDC-Ambisonics approach (to which the BBC is closely aligned) and the IBA MSC approach. As the IBA used the MSC system to transmit from Radio Victory on September 23rd, 1979 and from Capital Radio on November 25th and December 11th, an interesting legal question is raised: does the transmission of programmes using a new technology constitute public use of the idea? If it does, then the IBA's application for a patent, made on 19th December, could be legally invalid. But valid or not, the IBA patent application makes interesting reading.

It is acknowledged that the IBA system "takes as a basis the Ambisonics B format". This provides four basic signals:

W-an omni directional signal;
$X$-a signal which, together with $W$, is indicative of front-back positions;
$Y$-a signal which, together with $W$, is indicative of side-to-side positions; and
$Z-a$ signal which, together with $W$. is indicative of height.

From these four signals linear mixing techniques provide three signals;
$\Sigma$-a sum signal equivalent to mono;
$\Delta$-a difference signal which, when taken with the $\Sigma$ signal gives stereo, and may also be decoded to give horizontal surround-sound of limited quality and;

T-a third signal which, with the other two signals, gives horizontal surroundsound of good quality.

IBA test transmissions made in 1978 left the Authority's engineers in no doubt that the phase differences between the $\Sigma$ and $\Delta$ signals, and consequently between the received stereo left and right signals, degraded the sound. The IBA engineers
then looked for a way to avoid this degradation. Starting with the same four B format signals they arrived at an encoding matrix with the following characteristic:
$\left[\begin{array}{l}\Sigma \\ \Delta \\ T\end{array}\right]=\left[\begin{array}{lll}0.9 & 0.1092 & 0 \\ 0 & 0 & 0.6897 \\ -0.3954 \mathrm{j} & 0.3954 \mathrm{j} & 0\end{array}\right]\left[\begin{array}{l}W \\ X \\ Y\end{array}\right]$
Surround-sound decoding is not possible using the $\Sigma$ and $\Delta$ signals alone. However, since there are no phase differences present between these signals, no compromise is made over normal mono and stereo reception. So the IBA signal produces perfect mono and stereo from existing mono and stereo receivers but requires a three channel receiver and decoder to produce horizontal surround-sound. Moreover the three channel receiver must have a full bandwidth capability on all three channels. This differs from the Ambisonics UHJ approach which is hierarchical. A reasonable surround-sound effect is obtainable by decoding from two signal channels and an improved effect is obtained when a third channel, of either limited or full bandwidth, is received and decoded. This is the "irreconcilable choice" to which the IBA referred in 1979.

With both approaches, the transmission of a fourth channel enables the reproduction of height information.

The decoding matrix is an inverse of the encoder, and delivers signals $W^{\prime} X^{\prime}$ and $Y^{\prime}$, which are equivalent to the original $B$ format signals. In both approaches (Ambisonics and $\mid B A$ ) the decoded $W, X$ and $Y$ signals require further processing to produce speaker feed signals for three, four, five, or even more loudspeakers around the room.

Figure 1 shows an encoding circuit for the IBA system. Linear mixer and amplifier 2 receives the $W$ and $X$ signals, eg from a microphone array, and generates two output signals. One is fed through all-pass filter 3 to produce the $\Sigma$ signal and the other is passed through all-pass filter 4 which introduces a $90^{\circ}$ phase shift to produce the T signal. The $Y$ signal from the input is fed to multiplier 5 and all-pass filter 6 (which is identical to filter 3 ) to produce the $\Delta$ signal. The three transmission signals are multiplexed at 7 and transmitted at 8.


## DRIVE UNIT IMPROVEMENT

Rank Wharfedale have filed a British patent application 2083974 on an interesting proposal for improving the performance of loudspeaker drive units. The idea is to compensate for the non-linearity which is caused by air trapped beneath the diaphragm. Under normal circumstances this air is compressed and rarified as the diaphragm moves. This produces non-linear response to a drive signal fed to the speaker coil. It's already been suggested to feed a direct current bias signal to the coil. But Rank suggests that this can create problems because of the heat generated by the continuous current flow. Instead, suggests Rank, the position of the speaker diaphragm and coil should be continually monitored and this position used to control a feedback signal.

Figure 2 shows one way of doing this. Light emitting diode 9 and photo transistor 8 are mounted on the central pole piece 4 of the speaker magnet. The internal surface of the coil former 2 is coated to make it diffusely reflective. So light from l.e.d. 9 is reflected back to the photo transistor 8 . By making the reflected beam vary in dependence on the position of the coil former, the photo transistor 8 will produce a signal which represents displacement of the coil from its rest position. The patent describes several ways of.achieving this, for instance by providing the coil former with a nonlinear pattern of reflective and nonreflective areas.

Figure 3 shows a feedback circuit which can be used with an optical sensor of this type. Operational amplifier 14 takes the output of photo transistor 8 and itself feeds another op amp 15. This applies a compensation signal to the loudspeaker coil. The gain of op amp 14 can be pre-set to give the optimum level of compensation signal relative to the audio signal being reproduced.



[^2]THE proposed legislation regarding the compulsory wearing of seat belts for people travelling in the front seats of cars becomes law in the New Year and many people who have never got into the 'clunk-click' habit could find their lapses not only dangerous but also expensive.

This project has been designed to give an audible warning to both front seat occupants to remind them to fasten their seat belts before driving off.

The system works when the ignition is on. The alarm on the driver's side is only inhibited when the seat belt is fastened or if a front door is opened. The alarm on the passenger's side which is also inhibited when the seat belt is fastened or a door opened can also be turned off by an inhibit switch. This allows the alarm to be disabled when there is no passenger in the front seat. However, the alarm will be retriggered if the passenger door is opened and then closed.

## CIRCUIT DESCRIPTION

The circuit diagram of the Seat Belt Reminder is shown in Fig. 1. The switches S2 and S3 are both proximity switches which are fitted to the seat belts and are operated by magnets fitted to the tongues of the seat belts.

When the door switches and switch S3 (on the driver's seat belt) are both open, the inputs to IC3a are both high and the output IC3a pin 12 is low as is IC3c pin 11. The output (pin 8) of IC3c is high and IC4, a 555 timer connected as an astable multivibrator, is turned on triggering the audible warning device (WD1). When either the door switches or S3 are closed (i.e. if a door is opened or the driver's seat belt fastened) the output (pin 12) of IC3a is switched high. Whether or not the output (pin 8) of IC3c is switched low and the alarm inhibited depends upon the state of the other input (pins 9 and 10) of IC3c.

If it is high then the alarm is switched off and if it is low then the alarm will continue until the passenger seat belt is fastened, a door opened or the inhibit switch S 1 pressed.

If when the ignition is first turned on, the door switch is open the two inverters IC2c and d are both high and their outputs are low. This sets the output (pin 1) of the latch circuit formed by IC2a and $b$ high. The latch circuit is reset by pressing the inhibit switch S1, IC2a pin 1 goes low, and for the output to be switched high again S2 (the door switch) must be closed or the power to the unit switched off and then on again (via the ignition switch).

If we assume S1 has not been pressed and S2 and S3 are both open the three inputs (pins 3, 4 and 5) of IC3b are all high and its output (pin 6) is low. Closing any one of the three switches (S1, S2, or the door switch) will cause the output (pin 6) of IC3b to go high. If the output of IC3b pin 6 is low the output of IC3c pin 8 is high and

## Make

 Sure You StayLegal!!


## Seat Belt Reminder David Shortland

the alarm will sound.

## TRANSPORT ACT 1981

33A.-(1) The Secretary of State may make regulations requiring, subject to such exceptions as may be prescribed, persons who are driving or riding in motor vehicles on a road to wear seat belts of such description as may be prescribed.
(2) Regulations under this section:
(a) may make different provision in relation to different classes of vehicles, different descriptions of persons and different circumstances;
(b) shall include exceptions for:
(i) the users of vehicles constructed or adapted for the delivery of goods or mail to consumers or addressees, as the case may be, while engaged in making local rounds and deliveries;
(ii) the drivers of vehicles while performing a manoeuvre which includes reversing
(iii) any person holding a valid certificate signed by a medical practitioner to the effect that it is
inadvisable on medical grounds for him to wear a seat belt.
(3) Any person who drives or rides in a motor vehicle in contravention of regulations under this section will be guilty of an offence; but notwithstanding any enactment or rule of law no person other than the person actually committing the contravention shall be guilty of an offence by reason of the contravention.

In Part I of Schedule 4 to the Road Traffic Act 1972 (prosecution and punishment of offences) after the entry relating to section 33 there shall be inserted the following entry:
33A. Driving or riding in Summarily. £50 a motor vehicle in contravention of regulations requiring wearing of seat belts.

The above extracts have been taken from Chapter 56 of the Transport Act 1981.


## CONSTRUCTION

The p.c.b. design for the Seat Belt Reminder is shown in Fig. 2 with the component layout shown in Fig. 3. The resistors should be mounted first and then the i.c. sockets followed the capacitors and the regulator. Carefully check the orientation of the electrolytic capacitors and the regulator. Also check the p.c.b. tracks to ensure there are no solder splashes.

The case should be drilled next as shown in Fig. 4 and rubber grommets fitted. The two proximity switches should then be fed through the holes in the case and soldered onto the board along with the supply wires and the door switch wire. The warning device should then be mounted in the top of the case and its two leads soldered to the board. The i.c.'s should then be fitted onto the p.c.b. and the p.c.b. mounted into the case.


Fig. 2 P.c.b. design


Fig. 3 Component layout


TABLE 1

## COMPONENTS

Resistors

| R1. R2, R3; R4 | 1 k (4 off) |
| :--- | :--- |
| R5 | 4 k 7 |
| R6 | 100 |

## Capacitors



Integrated Circuits

| IC1 | 7805 |
| :--- | ---: |
| IC2 | 7402 |
| IC3 | 7410 |
| IC4 | 555 |

Miscellaneous S1

S2. S3
WD 1
Case
$22 \mu 25 v$ elect.
10n polyester C280
$10 \mu 50 \mathrm{v}$ elect. p.c.b. mounted
470 ceramic (2 off)

7805
7402
7410
555
p.c.b. grommets

## Constructor's Note

A complete kit of parts for the Seat Belt Reminder is available from Watford Electronics, 33/35 Cardiff Road, Watford, Herts WD1 8ED (0923 40588).


Fig. 4 Case drilling details

[6931]
Fig. 5 Mounting bracket.


The actual method of mounting the proximity switches to the seat belts will depend upon the type of seat belts being used. Note: Under no circumstances should the seat belt housing be drilled in order to fix the switches into position.

It may be necessary with some seat belts to mount the switches on brackets to ensure the gap between the magnet and the switch is small onough. A suitable bracket is shown in Fig. 5.

The two unused wires on the switches should be trimmed before they are soldered to the p.c.b.

Before fitting the unit into a car connect the supply leads across the car battery. With the magnets removed from the proximity switches and with no earth on the door switch wire the alarm should sound. By following the procedure in Table 1 all the alarm facilities can be checked.

If the unit fails to operate correctly switch off and carefully check the orientation of the components. Remove IC2 and IC3 and with the supply reconnected check the supply rail is 5 volts to all the i.c.s. Next connect a link wire from pin 8 to IC3 to the supply rail this should sound the alarm. Insert IC3 and with S2 and S4 both open the alarm should sound. Finally, insert IC2 and check the output on IC2a pin 1 is high, pins 3,4 and 5 of IC3b are high and IC3b pin 6 is low.

## INSTALLATION

The unit can be sighted anywhere in the car but the following points should be taken into account.

1) The inhibit switch $S 1$ should be within easy reach of the driver.
2) The leads of the proximity switches are only 300 mm long and will need extending if the box is to be placed any distance away from the seat belts.
The proximity switches should be fitted to the seat belts using Superglue. The area on the seat belt under the switch should be smoothed before being glued. The magnet should be fitted to the seat belt tongue as shown in the photograph so that when the seat belt is engaged the gap between the magnet and the switch is less than 6 mm to ensure correct operation.

Finally the door switch wire should be connected to either front door courtesy lights switch and the unit is then ready for use.

## [Astimithe] <br> Quick, neat and easy!

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ficačy in normal gravity conditions.

## Space Watch...

## THE DRUG POTENTIAL OF SPACE

A combination of technology from a Space organisation and a large Pharmaceutical group may within a few years have achieved the object of setting up space processing of drugs. There are a number of areas where the final chemical results required cannot be reached except in zero gravity. Some tens of millions of dollars and so far six years of moving forward is not regarded by either party as an experiment but rather as the foundation of a new industry. Both are satisfied that there are profits to be had in the venture. The electrophoresis processing unit in Shuttle mission 4 launched in June 1982 carried the first processing experiments.

The process of electrophoresis involves the separation of biological materials from their surrounding medium by passing fluids between walls having a potential difference between them. Different cellis take up different charges and move in different paths as the medium is pumped. This method of separation has been in use for a very long time on Earth. However the advantages of the method cannot be fully realised under the effects of the Earth's gravity. The result is that only low grade and minute amounts of material of medical value are produced. Under zero gravity the situation is changed enormously. The convection currents and forces under normal earth conditions can prevent the necessary cell movements and changes.

Under the controlled conditions which can be found in zero gravity situations the value of the gains are 500 times the amount of the required commodity plus a bonus of an increase in purity of five times. The three types of unit devised are a production prototype for the payload bay of the shuttle, a mid-deck flight unit and a free-flying production version. A demonstration unit for verification was on Mission 4. It will also fly on Missions 6,7 and 8. This unit is 6 ft . high and can deal with 580 pounds weight having one processing chamber. The production units will have 24 chambers. By using a dye in the medium the astronauts will be able to monitor the processing. It is hoped that missions will by 1984

## BENEFITS

The planned programme will involve some forty different materials under examination for the space processing. The first of these have pren selected on the grounds that they could benefit the greatest number of patients in special classes of disability.
Naturally there is a priority for those drugs which could provide for improved chemiotherapy particularly for cancer conditions. One of these is Antitryspin products. This niaterial is able to inhibit the progress of emphysema. At the present time only small amounts are available for research purposes and are of low purity when produced in the normal gravity conditions on Earth. It is predicted that if the space processing is successful the number of patients who could benefit would be of the order of half a million.

Another substance which has already proved itself is Interferon. This fortifies the body against viral infections. It is now being developed for the treatment of cancer. Again the emphasis is on gravitational difficulties which result in low purity and small amounts. Again the estimate of purity of yield would increase the patient load to some 20 million per annum.

Growth hormone products are also in need of advanced yields in quantity and quality. This is particularly so in the case of the young where bone growth is inhibited and other deficiencies resulting in the quality and quantity of life. Another advantage is the improvement in healing of ulcers. Again only low purity material is available on Earth. The patient benefit could extend to three quarters of a million sufferers if it was available in the quantities that would be obtainable from space processing.

Beta cells are valuable for the treatment of diabetes. There is a possibility of 1-dose cure. It is thought that in excess of three million patients could be treated in a year. It has not been possible to isolate Beta cells in any quantity in normal gravity conditions. Here there is a great need for this section of the problem to be investigated.

Epidermal growth products are another useful area of research. They are important to the treatment of burns and general healing of wounds. Patient benefit could be over one million cases a year.

Finally in this short selection of the areas of interest to World Health are the Antihaemophilia products. The present products are not only low purity but also lack the beneficial by-products. The need for this product is world wide.

The two companies are to have the benefit of free space on eight shuttle missions which is an indication of NASA's attitude to the peaceful use of space technology. The funding of the research is of course to be the responsibility of the user.

After two years it will be necessary for the developing group to have their own free space vehicle. It is possible there will be further information about the final production operation for inclusion in the next SPACEWATCH.

## REACHING FOR THE STARS

In the last issue of SPACEWATCH I promised a survey of the achievements of the deep space probes Pioneer 10 and Pioneer 11. On March the 3rd this year Pioneer 10 completed the tenth year of its life. It has been a decade of success for the scientific world and was the most remote man-made device launched from its birthplace, Planet Earth. Its companion Pioneer 11 also shares in the honours.
On its birthday Pioneer 10 was at the heliocentric distance of 26.6926 astronomical units, 2.481 billion miles. It remains healthy. Its body of scientific equipment is in sound working order and it is returning data daily at the rate of 64 bits per second-collected by the 64 metre, deep space antennas of the Jet Propulsion Laboratory USA. The tragedy of this birthday was that Pioneer 10 will after this year be crying in the wilderness, unheard, its data radiating into empty space. A vehicle that has rewarded the designers and teams of researchers and maintenance engineers in a way that no human endeavour thought possible will soon be of no more use, not because it has failed; not because it is old; but because it is being cut off in its half life for the simple reason that the dollars are not to be made available. To throw away such a star performer is a tragedy of this age where everything is controlled by money. How little would be needed from each American citizen to provide the amount required. Perhaps there is a specialist organisation that could organise a "Save The Pioneer Fund". Surely this is a worthwhile cause when one considers the extra gain in facts and the employment of engineers. Is 3 Million Dollars too much to ask for such a thing?

Here is a catalogue of the achievements. Firsts.

Flying through the asteroid belt.
The first planetary spacecraft to derive power from radioactive sources independent of distance from the Sun.
Established the environmental conditions round Jupiter and provided vital information for the design of later spacecraft.
Have extended the distance over which telemetry can operate successfully.
Determination of the vast distance over which the Solar Wind has effect.
Discovery of the large scale structure of the interplanetary magnetic field.
Discovered the ring and satelite features of Saturn not previously known.
Discovery of magnetic properties of Saturn. And to this must be added what is but a short list of achievements. Major advances in the understanding of Jupiter and Saturn. The propagation of cosmic rays and solar energetic particles in the interplanetary medium. The acceleration of charged particles by interplanetary shock waves. Improved determination of the gravity fields of Jupiter and Saturn and the masses of their satellites. Improved knowledge of the hydrogen and helium abundance ratio in the atmospheres of Saturn and Jupiter.

Frank W. Hyde


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CERTAIN requirements have been laid down for ideal equipment for peacetime as well as wartime surveillance. These demanding criteria are achieved by the Searchwater Radar System. They are achieved because Searchwater was designed to those standards. Most systems for one reason or another turn out to be modifications of an equipment which had another original purpose. Searchwater was deliberately developed against specific tasks. In this alone it is unique. The system has also been brought to operational condition in a short time and at a low cost, bearing in mind that demonstrated success sets it apart from all other systems. In short it leads the world but does its job without ballyhoo and "shouting from the roof tops". However, this brief article is an opportunity to bring to the notice of as many engineers as possible that contrary to the disparagements which forever appear in the media, British endeavour still leads the world. For obvious reasons of secrecy it is not possible to provide an extensive technical review of the system.

Because all the design requirements have been met and because after exhaustive tests the first users have discovered even more extensive capabilities in practical use, Searchwater has gone into service with the Royal Air Force in Nimrod Mark 2.

## REQUIREMENTS

The main requirements for such a system are as listed below.
1 Detection and classification of surface craft in all weather conditions at ranges in excess of the radius of the effectiveness of hostile missiles.
2 To provide a measure of overlap in capability against other threats, detection ranges on submarine periscope and "snort" targets should be as great as possible in sea conditions up to the maximum in which submarines might operate.
3 The radar should have the capability to detect aircraft at long ranges although the characteristics of such targets are very different from shipping.
4 Classification performance should be as comprehensive as possible in order that in a wartime situation there could be no doubt as to whether the target is hostile and that it is a particular type of vessel before making an attack.
5 The radar must be able to operate in the presence of severe counter measures.
6 It must be possible to update methods of deception; this means active and passive deception measures.
These parameters bring out the complementary measures which are desirable such as the ability to discriminate between
real and false targets. This has to be trưc whether the deception is by way of disguising one craft to look like andther, by the adm dition of reflecting devices or by electronion synthesis of false targets.

In maritime patrols there are long mission times and therefore operator fatigue must be taken into account. It follows that the parameters outlined for this equipment must lead to a considerable increase in operator load time. Therefore a maximum of automatic operation is required if such a system is to succeed.

## PERFORMANCE

Searchwater provides, for all categories of target from periscopes to large surface vessels, a very high probability of

Searchwater operators console


## 

detoction combinet with an ary low false alarm rate in high sea states out to very long ranges. The mere increasing of sensitivity or the reduction of background noise level will not improve the target detection efficiency, especially if the sea is very rough and "clutter" return exceeds the receiver noise level. There" are a variety of techniques which can be used to attempt improvements in this area.

In this equipment the domains of space, time, frequency and nplitude are all exploited; for example the dimensions of a patch of sea illuminated at any moment are kept small in azimuth by using a narrow beam width and in range by processing a narrow pulsegren orated by using compression techniques. Frequency agility is employed and the total number of returns during the time the aerial beam takes to pass a given point is integrated. Integration of information for the whole area-over several aerial scans results in an improvement in target discrimination because the clutter characteristics change with time. In Searchwater this method of improvement is achieved by using a digital scan convertor for storage of information from scan to scan.

Immediately after the detection of the return signal a threshold is continuously adjusted using a control signal derived from the instantaneous clutter level so that, as near as possible, a constant false alarm rate is presented to the operator. The combination of all these techniques ensures that the display is virtually free of clutter and any new radar contact is immediately evident.

By using an integral real time digital computer many targets can be tracked automatically at one time. Various forms of high resolution display are available for the determination of the classification of data on targets being tracked. Integrated IFF identification, friend or foe) facilities provide another useful input. Information on the targets can be displayed readily in alpha-numeric form on a single radar display. After a short period of tracking the file on each target is so detailed that the vessels can be classified with great confidence without the need for visual confirmation.

The display is in television raster format on a black and white tube so that bright flicker-free information is shown to the operator. Radar controls, mainly push buttons, are arranged conveniently around the display and the operating routines are simple sequences of push button and roll ball movements.

No measurements are taken directly from the screen. The built-in computer takes care of many of the tasks automatically, consequently the operator can maintain a high level of efficiency
for several hours at a time. This is in contrast to the more usual long persistence radar displays where operator performance is severely affected after about 30 minutes. There is also another relief for the operator in Searchwater in that there are built-in test equipments which enables automatic detection of faults and their diagnosis during operational flying. The modular construction and the use of software control allows easy incorporation of performace improvemients and changes as may become necessary.

## WHY

Airborne surveillance using long range aircraft equipped with a wide range of sensors is accepted by the NATO countries as the most effective means of obtaining up to date information to enable vital sea lanes to be protected. Threats to naval surface forces arise from three sources: submarines, aircraft and surface vessels.

Opinion is divided as to which of these threats is the mod dangerous. Whatever the opinions the fact-remains that all the areas of threat must be taken into account if the philosophy of "sea control" is to be maintained. The matter presents problems because the characteristics of each target are different for each threat. This of course means that each is likely to need a different approach. The original intention was that Searchwater would fill the requirement for use in maritime airborne patrol. The result of this work has provided the most effective sensor system which is likely to emerge in the nextdecade.

Dealing with the maritime situation, it is clear that the major threat would come from frigates, destroyers and cruisers. Such craft are already fitted with surface to air missiles with ranges of engagement which preclude close examination and positive identification of the nature of the threat. Since development of missiles continues toward greater range and levels of operation, it becomes more important than ever to produce a system providing positive identification quickly. The same system is desirable in peacetime to reduce the flying time in identifying vessels by visual methods. Where there is a concentration of vessels it is extremely important to be able to recognise individual units from a place remote from the threat of missiles. The same criteria rule if there are many vessels strung out, for then the nearest approach must be outside the missile range of the nearest vessel.

At such ranges optical, infra-red and electro-optical systems would be inadequate. Such a situation would arise in poor visibility with low grazing angles or because the inherent resolu-



PPI and A1 display, left hand display is a silhouette of the small square


## Searchwater A-scan display

tion of such system would be incapable of making positive identification.
IFF systems are not effective in situations of caution because they can only indicate that the ship is not an ally. If it is not identified as an ally there is no way of discovering whether it is a


PPI and B display, the large square is an enlargement of the small square
neutral vessel, a civil vessel or a hostile ship. The interrogation of electronic emissions is equally difficult. Experience has shown that the only positive system is one based on radar. To this end Searchwater has transcended all others.

## ABILITY

The collaboration of EMIE and RSRE has been directed over a period of years to the identification and practical evaluation of those techniques most appropriate for the long range airborne surveillance and classification of marine targets; detection of small targets such as the snort of a submarine, its periscope or small fast patrol boats at long range in high seas.

The current state of the art is exemplified by the Searchwater which is highly flexible, based on frequency agile techniques using compression, pitch and roll stabilised scanning antennas with controllable tilt and automatic sector scan.

A Nimrod Mark 2 equipped with Searchwater and flying at $20,000 \mathrm{ft}$ can detect a submarine snort in rough seas at a range of 200 nautical miles. Since Nimrods are based on Ascension Island this could be one reason why Argentina did not risk its submarines or surface fleet in the South Atlantic.


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FAULT finding on audio circuits is not generally hard if a meter, 'scope and circuit diagram are available. Most equipment, and particularly that used for disco and P.A., is prone to failure at more inconvenient times when such aids are not available. On this note however, the lack of a circuit diagram is inexcusable, and it is good practice to glue a diagram to the inside of any equipment. The need for an audio probe arises once the equipment has failed, and on many occasions can enable the fault to be rectified with the minimum of difficulty.

In its basic form the audio probe is simply an audio amplifier which feeds an earphone. Using such a tool the path of the audio through the circuit can be followed and any breaks identified. However, such a probe will only assist in locating the faulty section, the actual fault being a chip failure, supply failure or a large d.c. offset caused by a leaky capacitor. In normal repair work the components in the faulty section are changed in order until the fault disappears, which is a tedious method, not to mention expensive in components.

The audio probe described here contains an amplifier in the conventional way, but also includes a three state l.e.d. voltage monitor. This monitor can be used to check supply rails and for any unusual d.c. offsets within a circuit, and thus narrows down the possible causes of a fault considerably.

## SPECIFICATION

The probe was designed to be used with both single and dual rail audio systems, although its major use was intended to be op-amp based systems rather than power amplifiers.

In most audio circuits the signal should sit on a d.c. level which is very close to half the supply voltage. Accordingly the probe was designed to test for this condition by generating an internal half rail voltage and comparing the probe tip voltage with this internal reference. In order to make the probe suitable for both single and dual rail systems only two supply connections are used, these being connected to the lowest supply and the highest, which, in a dual rail system, will result in the internal reference being about 0 volts.

It is obvious that the internal circuit of the probe must be related to the supplies of the circuit under test and so no conventional regulation is performed within the probe. In order to avoid accidents if the probe is connected across a power amp supply an automatic shut down circuit operates which protects the probe from damage. Under normal circumstances an input supply voltage of less than 33 volts
should be used, which is more than adequate for 30 volt opamp supplies, or $\pm 15$ volt supplies. The prototype also functioned happily with a single 5 volt supply.

The voltage display takes the form of three l.e.d.s indicating 'Low', 'Centre' and 'High'. The l.e.d. supply is individually regulated so that brightness does not vary with supply voltage.

## CIRCUIT

The circuit consists of three sections, amplifier, voltage comparator and power supply control as seen in Fig. 1.

The probe input is connected to the main circuits via R1, which together with D1 and D2 protect the following stages from excessive voltages. The amplifier itself is a.c. coupled and the input is biased to half rail by R4. The first stage serves as a buffer, which feeds a small power amplifier circuit providing drive for the earphone. The amplifier is operated in Class B, with R9, D3 and R10 providing some base bias. The feedback of this amplifier is taken right from the output which helps cut down distortion, and at the same time gives a variable gain control via VR7. C2 obviously acts as a d.c. block for the output, which should ideally be a 600R earphone, although R11 and R12 can be dropped to 68R to drive lower impedances.

The voltage detector is based on a LM339 quad open collector output comparator. A reference chain (R14, 15 and 16) gives the internally derived centre point used for the probe voltage comparison. The top and bottom comparators detect high and low probe voltages and drive the relevant l.e.d.s directly. The centre two comparators are connected identically to the outer comparators, so that when neither of the outer two outputs are low (I.e.d. on) neither of the inner outputs are low, thus TR3 switches on and the green 'Centre' l.e.d. comes on. It is worth noting that it would have been possible to design the circuit using only two comparators but this method was adopted because it was more compact in.terms of pcb space. Since only one l.e.d. can be on at one time a single current limit resistor was used from a simple regulated 5 volt supply.

R13 is used to provide a half level bias to the comparators when the probe is open circuit so that the green l.e.d. lights.

The supply control is very simple. D4 protects the probe against reverse supply connection, and TR6 provides the over voltage shutdown. Under normal circumstances D5 will not conduct, hence TR4 will be off, TR5 on, and thus TR6 will pass current to the circuit. If the input voltage exceeds

33 volts D5 will conduct, removing base drive from TR6 by means of TR4 and TR5, and the probe will shut-down. Obviously the maximum safe supply is determined by the breakdown voltage of TR6.
The supply required regulating to ensure that the l.e.d.s were visible with low voltages but did not overload the comparator output stages with high supply voltages.


Symptom: A not centre (low)
Output high
Likely: Capacitor leaky


Symptom: A not centre Likely: Feedback resistor fault


Symptom: Output d.c. level settles after switch on. Probe on non-inverting input cures problem
Likely: Non-inverting input not biased to half supply
Fig. 2. Simple faults


Showing Probe interior construction

## CONSTRUCTION

The prototype was built into a standard probe case. The small size of this case means that most of the components were mounted vertically, although the power supply control parts were mounted flat allowing alternative potentiometers to be mounted above them if required.

The prototype board was produced with an etch resist pen, so it can be done, although a commercial board would obviously ease things considerably. It is suggested that whatever board is chosen it should be fitted into the case before board assembly commences. Apart from taking care to mount the vertical components so that no wires can touch no constructional points need be noted. Fig. 4 shows the suggested preform for the l.e.d. leads.

An enclosed skeleton potentiometer was used in the prototype for VR7. Three holes were drilled in the case and the preset glued down. Wires were then soldered onto the pins protruding through the case inside.

## TESTING

It is as well to test the unit before final assembly. Connect a 15 volt supply to the unit and vary the probe voltage by means of an external potentiometer. Check that the green


Fig. 1. Audio Probe circuit


Fig. 3. Showing p.c.b. and board construction


Cross section view of Audio Probe showing earphone inserted


View of Probe top showing the three state l.e.d. voltage monitor
l.e.d. centres at 7.5 volts and that both the high and low l.e.d.s come on correctly. Remove the potentiometer from the probe and connect in a signal level audio source to check the amplifier, adjusting the volume with VR7. Finally, slowly increase the supply voltage to 36 volts. Ensure the l.e.d.s go out when the supply exceeds some 33 volts, indicating that the protection circuit functions. If it does not appear to function do not increase the supply above 36 volts or the i.c.s in the probe will fail.

The board may be placed in the case and the top fitted. The best way seems to be to insert the l.e.d.s into their holes at the front of the lid and then press the rear of the lid into place. It may be necessary to remove one or more of the plastic pillars in the case which would otherwise foul against the jack socket or one of the transistors.

## IN USE

The probe should always be used with a signal being input to the circuit under test. Firstly follow the signal using the amplifier until the problem area is located. Most frequently the output of the problem stage will have a d.c. offset present, and this can be traced back to the input, or a faulty output by means of the voltage level display. For example if the input of an inverting amplifier is biased slightly below half way and the output is high either the amplifier is suffering from high leakage current or a d.c. blocking capacitor is at fault.

## COMPONENTS ...

Resistors

| R1 | 1 k 5 |
| :--- | :--- |
| R2, 20 | 100 k |
| R3, 5 | 560 k |
| R4, 13 | 1 M |
| R6 | 56 k |
| VR7 | 1 M skeleton preset enclosed |
| R8 | $560 R$ |
| R9, 10, 14, 16 | 15 k |
| R11, 12 | $150 R$ |
| R15 | 2 k 2 |
| R17,21,24,25 | 10 k |
| R18 | $390 R$ |
| R19 | 33 k |
| R22 | 1 k |
| R23 | 3 k 3 |
| All $\frac{1}{4}$ watt |  |
| R |  |

## Capacitors

C1
C2
C3
C4,5
$0.1 \mu \mathrm{~F}$ polyester C 280
$22 \mu \mathrm{~F} 25$ volt electrolytic $0.01 \mu \mathrm{~F}$ ceramic disc $1 \mu \mathrm{~F} 35$ volt tantalum

Semiconductors

| D1,2,3 | 1N4148 |
| :--- | :--- |
| D4 | 1N4007 |
| D5 | 33 volt $1.3 W$ Zener |
| D6 | $5 \cdot 6$ volt 400 mW Zener |
| TR1,3,4,5,7 | BC184L |
| TR2 | BC412L |
| TR6 | ZTX550 |
| D7.9 | Red I.e.d. 1.25 mm |
| D8 | Green l.e.d. 1.25 mm |
| IC1 | TLO72 |
| IC2 | LM339 |

Complete probe case with probe, supply wire and fittings, printed circuit board, 3.5 mm jack socket, wire.

# SEMICONDUCTOR U-DAE R.W.Coles FEATURING MICRO/T-11 TDA 2009 TDA 2320A CDP 1871 

## PDP11 ON A CHIP

The Digital Equipment Corporation, or DEC to its friends, is probably the world's number one supplier of minicomputers. I am sure that most people will have at least heard of their major products, namely the PDP8, the PDP11 and the VAX range of minicomputers which feature 12,16 and 32 bit word lengths respectively. Of the three families, the PDP11 is undoubtedly the most popular with a model to suit the majority of applications, from the tiny PDP11-03 with twin floppies to the powerful PDP11-70 with many megabytes of hard disc storage.

The DEC PDP11 family with its common instruction set and 16 bit bus has also influenced the microprocessor scene, since many chip designers have used its architecture as a model for their own more humble offerings. The Motorala 6800, for example, was an early attempt to put as many PDP11 features as possible onto an 8 bit NMOS chip. DEC themselves saw the advantages of an LSI implementation of their popular family, and soon brought out the LSI 11 multi-chip emulation which is used in their low-end systems such as the PDP11-03. The closest design engineers could get to this chip set however, was to purchase the DEC LS $11 / 2$ or the LSI $11 / 23$ single board computers, since DEC never released the chips for sale to third parties.

With increasing competition from 16 bit microprocessors such as the intel 8086 and the Motorala 68000, DEC realised that there is a large and expanding market for 16 bit single chip processors for which the LSI. 11 boards cannot always compete, and so they went back to the drawing board and produced the MICRO/T-11 single chip PDP11 processor which looks much more like a "conventional" microprocessor than their earlier attempts. Once again, the first use of the T-11 is in a DEC single board computer called the SBC $11 / 21$ which will compete directly with the popular Intel SBCs for applications in real time control and data processing, but this time they intend to sell the chips too, and that is exciting news.

Exciting, because for the first time it is possible to build a customised system which executes the full PDP11 instruction set, exciting too, because the $\mathrm{T}-11$ is a "nice" processor with a lot of useful features which are unavailable from the competition. Perhaps most original is the user option of either a 16 bit or an 8 bit data bus; you tell the T-11 which of these you want via an external mode register during reset. A 16 bit bus is faster of course,
because one memory access gets you one data or instruction word, but it does also mean that the memory array has to be arranged as a 16 bit $\times$ nK array so you may need, for example, $2 \times 2716$ EPROMs in parallel for your program memory. The 8 bit option would allow you to use, say, a single 2732 EPROM to store the same instructions, but the chip would in this case carry out two sequential reads to get a single word and therefore it does take longer. The 8 bit mode saves chips and wire for small systems while still providing the power of the PDP11 instruction set.

Another nice feature of the $\mathrm{T}-11$ is an on-chip dynamic memory address multiplexing and refresh scheme for the simplest possible interface to 16 pin dynamic RAM chips, although once again a user option of static or dynamic memory support is provided. Add to this a comprehensive interrupt scheme with four prioritised inputs and 16 internally generated vectors, an internal clock generator which works up to 7.5 MHz , easy interface to industry standard 8 bit peripheral chips, and the usuat PDP11 feature of eight 16 bit general purpose registers, and you can see why the $\mathrm{T}-11$ is likely to be a winner!

Despite its 16 bit operation and advanced features, the $T-11$ fits in a standard 40 pin package and uses a single 5 volt supply.

## STEREO PAIR

Audio amplifier construction continues to get simpler, thanks to advanced integrated circuit technology. SGS ATES have recently introduced a pair of devices which make the assembly of a powerful stereo amplifier system an almost trivial activity.

Their TDA 2009 dual power amplifier device features two low distortion audio amplifiers in a single eleven pin MULTIWATT package. Each amplifier will provide at least 10 watts of output at $0.5 \%$. THD, and can supply output currents of up to 3.5 amps . Relatively few external components are required and the TDA 2009 can be run from a single low voltage supply rail. The diminutive MULTIWATT package comes with a substantial heat sink tab and a mercifully low thermal resistance of $3^{\circ} \mathrm{C}$ per watt so that full power can be realised with the use of a simple external heat sink.

With a super power amplifier like the TDA 2009, you will probably also need a high quality preamplifier, so SGS-ATES have brought out the TDA 2320A to match. This device lives in an 8 pin diddy-d.i.p. and yet contains a matched pair of low noise preamplifiers for stereo audio amplification. Unlike its big brother, the TDA

2320A has a very low current consumption of about 0.8 milliamps, and will work from supply rails of 3 to 36 volts. Noise figures are low at about 1 microvolt r.m.s. and there should be no complaints about the THD of typically $0.03 \%$.

At this rate, it can't be long before we find a stereo amplifier with 50 watts per channel taped to the front of Practical Electronics as a giveaway!

## LOW KEY

For many microprocessor systems, a keyboard is an essential companion. Conventional QWERTY keyboards can be obtained ready built and with an encoder built in (at a price!) but many systems need a non-standard keyboard array. In this situation the designer can either wire up the switch matrix to a couple of 8 bit parallel ports and write a software routine to scan the keyboard and encode the result, or he can buy an LSI keyboard encoder chip to do the job for him. No problem so far, because NMOS encoders are available from Intel and others and these do an admirable job. But what if the system is battery powered and uses a CMOS micro? The NMOS encoder will take more current than the rest of the circuit put together, so until recently it was necessary to use a software solution or to build up a special encoder from CMOS logic chips.

One low power CMOS microprocessor family to suffer from this shortcoming has been the 1802 series from RCA, but not any longer, because RCA have now introduced the CDP 1871 which is a fullhouse CMOS keyboard encoder drawing only about 100 microamps at 5 volts. Inside the 1871 are all the counters and scanning circuitry to interface to an array of up to 53 ASC11 coded keys and up to 32 HEX coded keys, along with $N$-key lockout logic and debounce circuitry. The 1871 can be hooked directly on to the bus of most microprocessors where it can be addressed as either an I/O device or as memory. Two output flags are provided to inform the processor of the keyboard status. EFXA goes high to indicate that data is available and an additional flag, EFXB, is used to signify that the key is still pressed after it has been read. This last facility can be used to provide the auto-repeat function if required.

The 53 ASC11 key codes assume a conventional keyboard matrix with SHIFT and CONTROL keys, but the HEX keys generate a binary pattern between 80 H and 9 FH which can be used for arbitrary user defined applications.

## all in your



## issue!



## SEMI-PROFESSIONAL

 MINTA 103रThe modular design of our mixing desk enables the number of channels to be easily expanded using a backplane motherboard which allows each complete channel to simply plug in. Channel features include Pre Fade Listen, l.e.d. peak indication and equalisation.

The system, which is ideal for demo tape work or for producing professional audio visual tapes, uses four master channels for mixing down.


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## MUGHD-PHEFESODR campeilition

## PRACTICAL



OCTOBER ISSUE ON SALE FRIDAY, SEPTEMBER 10th

# CB Scanner 

## C. F. SHORTO and M. WARD

Micro Communications Equipment and Design Ltd.

THE concept of this CB Scanner design is to provide mic. controlled channel change and full 40 channel scan facilities. This enables a transceiver to have the following advantages:

1) The ability to change channel from the mic. which most motorists will find much safer than reaching across to the rig and in doing so probably obscuring the channel display anyway.
2) The disabled can sit back at home with the mic. on their lap and use the light touch of the channel buttons to change channels which is so much easier than reaching out and twisting the channel switch, this, will be quite an advantage to people who suffer with arthritis and rheumatism.
The design, as given here, fits Uniden, Audioline and Realistic types of CB transceivers although practically all CB transceivers produced to CB 27/81 specifications can be fitted with this unit, although slight modifications will be necessary

A list of CB transceivers which can be fitted with the Scanner are detailed in Table 1. The prototype unit was designed with future modification for other CB transceivers
Harvard
Rotel
Yorks
Amstrad
Cybernet 2000/3000

Harvard
Rotel
Amstrad
Cybernet 2000/3000

Max Com Apolio 16 Midland 2001/3001/4001 Harrier CB 8 CBX
Fidelity
Radiomobile

## TABLE 1

in mind, however, it was felt that the Uniden 200 is probably the best CB transceiver on the market at this time, by virtue of its ability to withstand strong signals from adjacent channejs (bleed over and de-sensing) although this is possibly because Uniden carried a proven design from previous a.m. transceivers with minor modifications, the similarity between the a.m. Cobra 19 G.T.L. and the Uniden 100 both in looks and circuitry bears this out, whereas many manufacturers started from scratch.

Audioline and Realistic use the Uniden chassis and are, therefore, effectively covered by this article.

The full 40 channel squelch controlled pause scan facility provided by the Scanner enables the operator to monitor the entire CB bands, a single press of the scan button will set the unit in motion automatically checking each channel in succession and when it finds a signal strong enough to open the squelch, it will pause for 5 seconds or until the signal ceases whichever happens first. If the operator wishes to stop on a channel, at which the Scanner had paused, or to stop scanning.and use the manual control, a further press of the scan button or a single press of the mic. button is required, the Scanner will single step the channels up or down by repeatedly pressing the up or down buttons, however, if you
push and hold the up or down buttons the Scanner will automatically step-through the channels in that direction until the button is released, this enables fast channel change when a large amount of channels are to be bridged.

The 40 channel scan can be implemented without the use of the special microphone by simply wiring to a panel switch so that when switching to scan control the Scanner starts automatically and can be stopped by a single push of the mic. button.

## CIRCUIT DESCRIPTION

The circuit diagram of the CB Scanner; is shown in Fig. 1. In order to produce a count from 1 to 40 a trick used by CB PLL chip manufacturers has been adopted, IC6 and 8 are
 to 39 however, the code for 0 is converted into that of 40 by IC10 which adds the missing bit to make the zero appear as 4 in the most significant digit. IC7 and 9 are BCD to seven segment decoder/drivers, these i.c.s convert to output codes of the counters to drive the channel display of the CB transceiver, in the case of the Uniden chassis the PLL chip derives its channel selection code from the display drive lines and, therefore, interfaces readily with this circuit, most other makes of CB transceivers use a six bit BCD code with channel 40 represented by zero to derive their channel information, these can therefore be driven directly from the counter outputs.

It was thought reasonable that the transceivers, when under control from the Scanner, should be made to power up on the calling channel (14), the parallel load data inputs are therefore hard wired with the code for channel 14 , when power is initially applied, C13 will charge through R14, but due to the delay in doing so a short positive pulse is applied to the parallel load input, thereby latching 14 into the coun-



Fig. 1. Circuit diagram of the Scanner
ters from power up and then returning control of the counters to the clock inputs.

The two up and down buttons are gated together and fed through a short delay circuit formed by C6 and R6 and coupled via C7 and D2 to the clock inputs of the counters. If either up or down buttons are pressed a single pulse is placed on both counters, the terminal count (TC) output of IC8 will only enable IC6 to clock at the appropriate times. The up/down inputs of the counters normally reset in the up condition, however, if the down button is pressed the counters are put in the down mode until this button is released. If either the up or down buttons are held pressed for more than half a second C5 will charge through R7 and provide a logic 1 to the input of a NOR gate this, via a second NOR gate, will enable the clock oscillator formed by the IC4 to repeatedly clock the counters in the direction designated by the up/down buttons.

Two cross coupled NOR gates are used to form a simple latch, C4 ensures this latch powers up in the reset mode, if the scan button is momentarily pressed, the latch will be set
(start scan). To reset the latch (stop scan) you may either press the mic. button which will pulse the reset input of the latch or press and hold the scan button, initially this will attempt to set the latch, however, this will have no effect as it is already set, then C2 will charge via R2 and will reset the latch via R1.

The latch when set will enable the clock oscillator IC4 which will clock the counters through all 40 channels in succession, also IC5 which is a 5 second delay circuit is enabled and when the squelch of the CB transceiver is opened by a signal, this delay circuit is triggered which holds the clock oscillator for 5 seconds or until the signal ceases whichever happens first. The Scanner is powered by a 5 volt supply via the regulator IC1.

## CONSTRUCTION

The Scanner has been designed to fit into most CB transceivers, in order to do this it was necessary to design a double sided, through hole plated printed circuit board, the track patterns for which are shown in Figs. 2, and 3 with the


Fig. 2. P.c.b. design (underside)


Fig. 3. P.c.b. design (component side)


Fig. 4. Component layout
component layout shown in Fig. 4. No mounting holes have been provided although there is ample space for the constructor to include them if required, however, it is often difficult to find suitable mounting positions inside transceivers and the prototype was mounted between two pieces of $\frac{1}{2} \mathrm{in}$. thick foam rubber which provided support, insulation and some degree of shock resistance.

When assembling the components onto the p.c.b. the resistors and diodes should be fitted first followed by the i.c. sockets (if used) and then the capacitors and finally the regulator i.c. as it is the largest component. This order of assembly is not critical but fit the lowest height components first to enable the board to be turned over whilst soldering. One or two resistors will need to be stood on end and they should be left until later.

If i.c. sockets are not used the i.c.s should be inserted last, especially the 5 CMOS i.c.s which are to some extent static conscious and the normal precautions should be taken. If i.c. sockets are used the i.c.s can be left out until the board is finally wired into the transceiver and ready for testing.

## INSTRUCTIONS TO MODIFY YAESU MIC YM = $\mathbf{3 5}$ TO WORK WITH SCANNING UNIT

To modify a $Y M=35$ microphone, first undo the 3 screws at the back of the mic. to allow access. Then carefuly lift out the push to talk switch and prise the white plastic piece that covers the mic. insert and the 3 push button switches (the white plastic will be tight as it is glued in one spot). Once this is removed follow the instructions in Fig. 5

If it is required to implement the use of the Scanner without the microphone control C3 should be omitted from the p.c.b. and the switching instructions shown in Fig. 6 should be implemented. When the button wired for scan selection is pressed the Scanner will auto start and pause under the control of the squelch as usual if it is required to stop on a channel currently being monitored by the Scanner a short press of the microphone switch will achieve this.

## COMPONENTS . . .

Resistors

| R1, R3, R4, R5, R6, R8, R11, R12, |  |
| :--- | :--- |
| R14, R15 (10 off) |  |
| R2 | 68 k |
| R7 | 220 k |
| R9 | 56 k |
| R10 | 1 k |
| R13 | 100 k |

All resistors $\frac{1}{4} \mathrm{~W} 10 \%$ carbon
Capacitors
C1, C3, C4, C6, C7, C8, C10, C11
C13
C2, C5, C9, C14, C15, C16, C17 C12

100n (9 off)
$2 \mu 2$ ( 7 off) tant. bead $47 \mu$

Semiconductors

| D1-D17 | 1 N4148 (17 off) |
| :--- | :--- |
| IC1 | 7805 |
| IC2. IC3 | 4001 (2 off) |
| IC4. IC5 | $555(2$ off) |
| IC6, IC8 | $4029(2$ off) |
| IC7. IC9 | 74 LS47 (2 off) |
| IC10 | 4078 |

Constructor's Note
A complete kit of parts for the Scanner is available from Micro Communications Equipment and Design Ltd., 5 St. Patricks Avenue, Weymouth. Dorset DT4 9EO. Tel. 03057 71355. (Price £ 12.00 plus 50 p p. \&p. plus V.A.T.) The p.c.b. is available separately (price $£ 4.00$ plus 50 p p.\&p. plus V.A.T.).

A suitable microphone (YM35) is available from South Midlands Communications Ltd., SM House, Osborne Road, Totton, Southampton.

(1) REMOVE BROWN WIRE AND LINK A WIRE FROM THIS PIN 3 TO PIN 5

(3) remove the 2 White leads (large and small) and connect as shown in dtagram below. also connect brown wire, removed in step ili, to new POSITION SHOWN IN DIAGRAM BELOW.

[ [滑雨


YAESU MIC YM- 35
MIC When modified should have wires as above TO MOOFYMC AS BOUGHT FOLLOW THE FOLLOWING INSTRUCTIONS.


Fig. 5. Instructions to modify Yaesu mic.

## FITTING INSTRUCTIONS

To fit the Scanner into Uniden type transceivers it is necessary to electrically isolate the channel switch contacts from the display and PLL chip inputs, to achieve this cut all the tracks leading to the switch display drive contacts ensuring that both display current limiting resistors and PLL chip inputs remain connected together. The pin connections of the channel switch are shown in Fig. 7, the letters refer to the segments of the displays, capitals being the most significant digit (MSD) and the lower case letters being the least significant digit (LSD). The three letters shown in brackets are segments of the.least significant digit display, however when unmodified they only drive the display and the equivalent un-bracketed letters drive the PLL chip inputs. The difference between the two ' $a$ ' and ' $d$ ' contacts is that the top and bottom segments (wrap round) are displayed with 6 s and 9 s by the bracketed pins but the PLL chip will not decode this, the other contacts produce the same output with the exception of the wrap round on the 6 s and 9 s .


Fig. 6. Scan circuit without mic. control


Fig. 7. Channel switch pin connections

These are now used for both display and PLL chip drive because the 74LS47 decoder drivers also omit the wrap round (although provided wrap round was never used on early Cobra/President type transceivers). The ' $e$ ' is a complete duplicate of its counter-part and may be disregarded thereby simplifying changeover from channel switch to Scanner control. The three display segments isolated from the bracketed letters are connected to their counterparts but on the PLL input side of the track cuts. Thirteen diodes are now required to bridge the tracks cuts, the cathodes of which are connected to the channel switch side.

One of the track cuts may be implemented by moving a wire link and replacing it with a diode, Figs. 8 and 9 clearly shows where cut tracks should be made and diodes fitted,

[E9928
Fig. 8. Track cuts


Fig. 9. Diode connections


Fig. 11a. Squelch connections


Fig. 11b. PTT connections. Fig. 11a and b show the necessary connections to a Uniden 200 rig from the Scanner. For other types of rigs not listed in Table 1 see the Advice note opposite.


Fig. 10. Display connections
leads are run from the appropriate connections on the Scanner p.c.b. to the anode side of each diode thereby enabling the decoder driver i.c.s of the Scanner to drive both the display and the PLL chip. You can see from Fig. 10 which diode connects to which display segment.

As can be seen in Fig. 9 the four common connections of the channel switch are isolated from the main p.c.b. connection, this enables them to be switched to ground via an appropriate changeover switch when selecting between channel switch and Scanner control. The wiring of which is shown in Fig. 10 this also shows a connection to the Scanner to disable the outputs of the decoder drivers when in channel switch mode.

All that now remains is to connect the PTT Input, the squelch and the microphone buttons.

The connections for the squelch and PTT (Uniden 200) are shown in Figs. 11 a and b .

To connect the microphone buttons to the Scanner you must run wires from the connections labelled 'up', 'down' and 'scan' to the appropriate pins on the mike socket and a +5 V feed to the common of the buttons also on the mic. socket, details shown in Fig. 5.

## ADVICE SERVICE

If you are unsure about the Scanner connections to your particular rig, then send a photostat copy of the circuit diagram together with a stamped addressed envelope to Micro Communications Equipment and Design Ltd., 5 St. Patricks Avenue, Weymouth, Dorset DT4 9EQ. The appropriate connections will be marked on the diagram and returned.


NEW - NEW - NEW CT 1000P THE 1000 VOICE DIGITALISED POLYPHONIC SYNTH from Casiotone

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Fentures

\author{

- 1.000 Voices <br> - Polyphonic <br> - Preset and programmable arpeggios <br> 5 octave split Keyboara Real time Sequencer
}

This advanced technology synthesiser from Casiotone is without doubt the keyboard bargain of the year and has been eagerly awaited by evervone. It has ten superb basic woices plus selectable envelope, footage and modulation giving $10 \times 10 \times 10$ sound variations numbered $0-999$.
Up to ten sounds can be stored in a non-volatile memory ready for instant selec. tion while playing. The five octave eight note polyphonic keyboard can be split into two separate sections pach with a different voice. A sixteen step preset arpeggio is available in addition to programmable arpeggios with a 127 steps which can also function as a real time seduencer. Pitch is displayed digitally and a wide range pitch control, allows transposition over $1 / 2$ octaves. There is sustain and vibrato facilities plus an integral amplifier/speaker and line output and phone sockets. Dimensions $117 \times 916 \times 363 \mathrm{~mm}(4 \% \times 36 \times 14 \%$ inches) Weight 10 kgs (221bs)

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# Compiled by DJD. 

Appearing every two months, Micro-Bus presents ideas, applications, and programs for the most popular microprocessors; ones that you are unlikely to find in the manufacturers' data. The most original ideas often come from readers working on their own systems; payment will be made for any contribution featured.

THIS month's Micro-Bus looks at the sound facilities provided by the BBC Microcomputer, and shows how they can be used for electronic music synthesis. Among this month's other topics is the circuit for an analogue interface for the ZX81.

## BBC MICRO SOUND

The BBC Microcomputer provides three tone channels, and a fourth channel which can be used for noise or pulsewaves. The four channels are summed and can be played simultaneously through an internal loudspeaker. Each channel can be set to one of 16 amplitudes, and the tone channels can be set to frequencies spanning about five octaves, in steps of a quarter of semitone (where 12 semitones is one octave). Furthermore, pitch and amplitude envelopes can be set up and specified for every sound played, providing effects such as tremolo and vibrato, and allowing an approximation to different musical instruments to be achieved.

The programmer is provided with access to the sound system from BASIC by means of two statements, SOUND and ENVELOPE, each of which takes a number of parameters to control the characteristics of the sounds produced. It would obviously be undesirable for the SOUND statement to hold up further execution of a program while a note of, say, a second's duration was played. The sound system on the BBC Micro therefore has a system of queues; rather than actualiy sounding a note, the SOUND command places the parameters for that note into a queue. Up to four notes can be queued on each sound channel before program execution is suspended, and various options in the SOUND statement allow several notes to be queued separately on the different channels, but sounded together as a single chord.
The ENVELOPE statement allows up to four envelopes to be set up, for use by subsequent SOUND statements. Six of the parameters, PS1-3 and NS1-3, provide three stages of variation in the frequency of the note chosen in the SOUND statement to give effects such as tremolo, and the change in pitch of a plucked string. The remaining parameters control the ADSR (attack, decay, sustain, release) amplitude envelope of the sound.
The parameters of the SOUND and ENVELOPE statements are summarised in the diagrams of Fig. 1, and the use of these statements is illustrated in the following two music programs.

Fig. 1(a). The BBC Microcomputer's
SOUND statement enters the parameters of a sound into one of the four sound queues


Fig. 1(b). The ENVELOPE statement sets up pitch and amplitude envelopes for sounds

Envelope number 1 to 4
Step duration 1 to 127 in hundredths of a second. Add 128 to use pitch envelope once; otherwise repeats

Pitch Steps -128 to +127 , in quarter semitones, per time $s$ for each of the 3 phases of the pitch envelope

Number of Steps 0 to 255 in each phase of the pitch envelope

Attack Rate 1 to 127 Amplitude increase per time $S$ until level PL reached

Decay Rate -127 to +127 Amplitude change per time $s$ until level SL reached

Sustain Rate 0 to $\mathbf{- 1 2 8}$ Amplitude decrease per time $S$ until SOUND duration completed


20 * FX 11
40 ENVELOPE $1,4,1,-1,1,1,1,1,120,0,-1,-1,120,120$

60 REPEAT
70 AB=INSTR \{AS, GETS )
80 IFA $\mathrm{CH}=\mathrm{CH}$ :MOD $3+1$ : SOUNDCH $+16,1$, A ${ }^{2} 4,5$ 90 UNTILO

Fig. 2. Program turns the BBC Micro into an electric piano

## REM COMPOSER

1 ENVELOPE1,1,0,0,0,1,1,1, 126,-3, -3, -3,100,60
2 ENVELOPE $2,1,0,0,0,1,1,1,126,-5,-5,-5,100,60$ 3 ENVELOPE $3,1,0,0,0,1,1,1,126,-1,-1,-5,100,60$ 3 ENVELORE3, $1,0,0,0,1,1,1,126,-1,-1,-1,126,60$ 20 INPUT"DELAY , D\&:DUR $8=$
30 CH: $=0$; $I=0$ : INC $8=-1: K \&=0:$ REPEAT
IFI8>8:INC: $=-$ INC
36 IFIB<1:INC $8=-$ INC $:$ : $\mathrm{K}=(\mathrm{K} \%+7$ )MOD12
$37 \mathrm{I}=\mathrm{I}:+\mathrm{INC}$
ON(I \&MOD $4+1$ ) COTO $50,60,70,80$
$50 \quad P$ : $=12$ (IIEDIV4): GOTO90
$60 \mathrm{P} 8=3+12^{*}($ I 8 DIV 4 ): $\operatorname{GOT090}$
$70 \mathrm{Pg}=7+12$ * (ISOIVA): GOT090
$80 \mathrm{P} 8=10+12^{*}($ IBDIV 4$)$ : GOTO90
$90 \mathrm{PI}=\mathrm{P} \%+(\mathrm{INC} \%+1) / 2^{*} 7$
5 Ch
99 IFI $=1$ : SOUND $\& 13,3, \mathrm{~K}_{8} * 4+($ RND $(2)-1) * 4$ 日, 2
100 SOUND $11+$ CH \% , $1,(\mathrm{P}$ q +K ) $)$ 4, DUR
101 IFCH $=1$; SOUND $\leqslant 10,2,18 / 2 \mathrm{MOD} 3+4,10$
110 NOW=TIME:REP EATUNTILTIME-NOW>D
160 UNTILO: END
Fig. 3. Program composes music on a BBC Micro

## MICRO KEYBOARD

The surprisingly short program shown in Fig. 2 turns the BBC Microcomputer into an electronic keyboard instrument, which allows chords of up to three notes to be played. It was contributed by Tim Dobson of Warrington, and it uses the top two lines of the keyboard as a piano keyboard, as follows:


The top numeric row gives the black notes, and the row "QWERTY" gives the white notes, with " $R$ " as middle-C. The program works by first specifying an envelope for the SOUND statement (line 40) with slight tremolo, a sharp attack phase, a flat decay phase, and slowly decaying sustain and release phases to give a piano-like sound. It then reads
a key, using GET\$, and looks up the key in a string containing all the valid keys of the keyboard, AS, using the INSTR function. This sets A\% to the position of the key in the string, or 0 if the key is not found. If $\mathrm{A} \%$ is non-zero it is used to sound a note on the next sound channel (line 80). The channel number, $\mathrm{CH} \%$, is cycled through the tone channel numbers 1,2 , and 3 . The SOUND statement's first parameter sets $F=1$ to sound each note immediately.

The "FX11 call is used to turn off keyboard auto-repeat, which would otherwise cause strange effects if a key were held down. The ON ERROR statement, line 10 , allows you to exit from the program by typing ESC, and the *FX12 then turns auto-repeat back on.

## MUSIC COMPOSER

The second of the two music programs for the BBC Microcomputer actually composes music, according to a set of simple rules, to produce a tune with three parts and percussion.

The program shown in Fig. 3 begins by setting up the three envelopes used by the subsequent SOUND commands. All three envelopes have a flat pitch envelope, sharp attacks, and different decay rates in the decay, sustain, and release phases. The program next prompts for the "DELAY", which determines the speed of the tune; values of about 5 to 10 give the best results. The SOUND statements in lines 99 and 100 control the tones in the tune, and the one in line 101 gives percussive sounds using channel 0 , the noise channel.

Many varied and interesting effects can be produced by varying the parameters in the program, but the program goes only a little way in illustrating the possibilities for music composition by computer.

## ZX81 A/D INTERFACE

The addition of an analogue interface to a computer enables it to be used as a chart
recorder, a slow oscilloscope, or in real-time control and data-logging applications. The following analogue-to-digital interface for the ZX81 uses the Ferranti ZN427 in conjunction with a CMOS analogue decoder to give 8 analogue input channels which can be read by programs. The design was submitted by $D . L$. Brownlee of Hatfield, and is based on a circuit for the UK 101 published in the July 1981 Practical Electronics. What follows is based on his description.

## CIRCUIT OPERATION

"In use, one of the eight inputs is first selected by executing: POKE $11000, \mathrm{~N}$ where N is the channel number, 0 to 7 . Then the chosen input can be read by:
PRINT PEEK 11000 with readings between 0 and 255 corresponding to voltages between 0 and 5 V .
"The circuit, shown in Fig. 4, comprises 7 i.c.s and a few ancillary components. The 74 LS 04 inverters and 74LS30 gate decode a block of 256 bytes containing the address with the convenient round number 11000 . The remaining inverter, in conjunction with DI, disables the ROM when this addressed block is active. The $A / D$ inverter chip's clock is derived by dividing down the ZX81's 3.2 MHz clock, using a 74SL93, to approximately 400 kHz .
"On writing to the circuit, using a BASIC POKE statement, the lower four data lines are latched into a 74LS75 latch, and these are in turn decoded by a 4051 CMOS analogue switch to select one of 8 input channels. At the same time a latch, formed out of the two remaining NOR gates, is triggered to give a start-conversion pulse to the ZN427; the latch is reset by a pulse from the 74 LS 93 clock divider.
"On reading the $A / D$ converter, with a PEEK instruction, the latch of the $A / D$ converter is enabled by the RD signal to place the

digital value of the last analogue input onto the data bus.
"The A/D converter and analogue switch both require a negative supply rail, not available from the $\mathbf{Z X 8 1}$. As the current consumption is small this can conveniently be obtained from a 9 V battery."

If only one input channel is required, the circuit can be simplified by omitting the 4051 and 74LS75 i.c.s.

## HAWK \& SPARROW GAME

In the following game for the ZX81 you control a hawk chasing a sparrow, which tries to reach the safety of the right-hand side of the screen. The program, shown in Fig. 5, was devised by J. W. H. King of York.

On pressing "RUN N/L" the screen shows a horizintal line, representing the ground, a symbol representing the hawk near the top left-hand corner of the screen, and lower down to its right a smaller symbol representing the sparrow.

To move the hawk, key any number followed by $\mathrm{N} / \mathrm{L}$. The hawk will then move to the right by that number of spaces, and may also move up or down. Meanwhile the sparrow also moves to the right, but by a random number of positions, and up or down. To catch the sparrow you must move the hawk next to it, and both will fall to the ground with the message "CAUGHT" displayed. If, however, the sparrow manages to reach the right-hand side of the screen the message "SAFE" will be displayed, and the number of moves taken is indicated in the top left-hand corner. To restart the game type " $0 \mathrm{~N} / \mathrm{L}$ ".

## ZX8 1 ART

The following program, for a ZX81 with 16 K of RAM, will allow you to design pictures on the computer screen and print them out on the ZX printer. Ten different pictures may also be stored in memory, and then saved to tape. The program was devised by D. Wardle of Norfolk, and a picture of his house produced by the program is shown in Fig. 6.

## PROGRAM OPERATION

To use the program press RUN, enter any ZX8I character followed by NEWLINE, and the selected character will appear flashing on


Fig. 5. $\mathbf{Z X 8 1}$ Hawk and Sparrow game
the screen, indicating that the program is in "Drawing Mode". To move the character type:

1 or 2 for horizontal movement,
3 or 4 for vertical movement,
and $5,6,7$, or 8 for diagonal movement.
To change the drawing character press " 9 ", type the new character, followed by NEWLINE, and the new character will appear at the last drawing position on the screen. To erase previously drawn characters enter a SPACE or null character, or to clear the screen completely press "C".

To save a picture in memory, press " $A$ " when the program is in drawing mode; this will take about 40 seconds. The pictures are numbered in the order in which they are saved. To recall a previously saved picture press " $B$ " followed by the picture number (1 to 10), and to return to drawing mode press " 0 ".

When the program is waiting for a new drawing character, typing the function "PI" will reset the drawing counter; the next picture


Fig. 6. Art program turns a $\mathbf{2 X 8 1}$ into a sketchpad


Fig. 7. Drawing generated using the Art program of Fig. 6
saved will be number 1 . Typing the function "ARCCOS" will save the program, and all the saved pictures, on tape. To continue, press CONT and NEWLINE. When next loaded the program will be in character-entry mode.

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BACK ISSUES P.W., E.T.I., W.W., Byte from 1962. Electronic Books, LS, cases, offers, exchange for components. L. Symes, Titchborne, Redlynch, Salisbury, Wilts SP5 2JX.

UK101, 13 K , cased, $1 / 2 \mathrm{MHz}, 300 / 600$ Baud, sound and I/O, software, quick sale $£ 160$. Tony Randall, 29, Carlisle Rd, Pudsey, W/Yorks. Tel: 561967.

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CASSETTE recorders (iwo), stereo cassette mechanism, tape recorder ( 3 in . reel) $£ 5$ each. Rigonda 7 in . TV, picture unsteady $£ 10$. D. Buckley, 142A Lynton Rd, West Acton, London W3. Tel: 01-993 3123.
IBM SELECTRIC printer+magnets, overhauled manual $£ 175$. Great Dunmow (0371) 2527. D. Howard, 9 Newton Hall, Dunmow, Essex.

W/T TRANSMITTER. Type 52M, R.A.F. Serial No. 1330 (W/T Stores Depot, Kidbrooke, Kent. Ref. No. 1872). Good condition Offers? R. D. Morton, 92 Peacock Avenue, Wakefield.
MEMOPAK 64 K memory for Sinclair ZX81. As new. $£ 65$ or nearest offer. D. Smaltshire, 25 Caspian Way, Wheaton Aston, Stafford. 0785 840800.

PROFESSIONAL short-wavebands receiver kit, $1-30 \mathrm{MHz}$ unused, complete to easily construct superlative rig- $£ 13.00$; Post/Pack $£ 1.00$. David, 1 Burnhead Road, Burnfoot, Hawick, Scotland TD9 8HB.
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HEATHKIT $5^{\prime \prime}$ scope $\mathbb{C} 80$. DG6-7 scope tube £4. Wanted Wyndsor Vanguard tape recorder Belco 5A oscillator circuit. Dave Biddle. Tel: 016909697.

HOME-WORKSHOP clearance of surplus power-supplies, transformers and rack-units. Phone (0743) 59492. Mr. P. A. Hartwig, 3 Kingswood Road, Copthorne, Shrewsbury.

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WAVEFORM Digitisers, or Transient Recorders as they are otherwise known, have been available on the professional market for some time. These devices are able to store a waveform in memory and replay it at a later time, and are particularly useful for capturing transient events, e.g. musical instrument waveforms, power supply glitches, etc., so that the stored waveform can then be displayed on an oscilloscope. It is also useful for recording very low frequency events, e.g. a temperature variation throughout the day, and then displaying this at a much higher frequency on the oscilloscope.

This Waveform Digitiser has a maximum input sampling rate of 100 kilohertz and a memory capacity of one kilobyte. The total cost is approximately $£ 50$, and the design is based on a new (1982) Ferranti analogue to digital converter i.c., the ZN449.

## BASIC OPERATION

An analogue signal, either periodic or transient is converted into a digital signal and stored in memory. The stored signal can then be converted back into analogue for display on the oscilloscope. The digital signal can be stored indefinitely, unlike a conventional analogue storage scope, and be displayed on an ordinary oscilloscope.

## APPLICATIONS

The unit can be used with experiments in Physics, Chemistry, Biology and Electronics. Any signal that varies with time and which can be converted to a voltage can be stored, providing the frequency of interest is below 50 kHz . (Note that total record time=memory size/sampling time, where memory size is 1024 bytes).

The waveform can be replayed onto an oscilloscope or can be stored on paper by the use of an $X / \mathcal{Y}$ plotter. Signals that are too fast for this are recorded by the Digitiser. The stored signal could also be permanently stored on magnetic

## SPECIFICATION

Memory-Static RAM (1 kilobyte)
Sampling rate- 1 to 100 kHz
Amplitude resolution- -8 bits ( $0.4 \%$ )
Analogue to digital conversion time- $9 \mu \mathrm{~s}$
Output display - Can be step or filtered waveform
Trigger facilities-Pretrigger
Post trigger
Manual trigger
Output trigger to oscilloscope for synchronised display
L.e.d. Indicators-Mains power on Input overload Trigger threshold
Trigger armed End of memory
Input stage-Variable gain 1 to $\times 100$, a.c./d.c. $1 \mathrm{M} \Omega$ input impedance Slew rate $-13 \mathrm{~V} / \mu \mathrm{s}$ Adjustable d.c. offset Single or repeat memory record or display BNC connectors
tape, by the use of a suitable serial interface. The minimum sample frequency on the Digitiser is one sample/second, but this can easily be reduced by the addition of more dividers (CMOS 4518).

Physics applications include temperature/time plots, measurement of stress, strain, pressure, volume, acceleration. Transient events, such as shock, can be stored and replayed later.

Fast chemical reactions can be measured. Some transient reactions can have their rates measured by the change in light absorption by the reaction medium, this change in light transmission can be measured and converted into a voltage.

Electronic uses of the Digitiser include measurement of a


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Fig. 1. Cịrcuit of Waveform Digitiser

CR charge/discharge curve, power supply monitoring, switch and relay bounce, CSR turn-on time, etc.

Biomedical signals are difficult to display with an ordinary oscilloscope. Some signals have a very low frequency (less than 1 Hz ), and by recording on the Digitiser can then be replayed at a much higher frequency. By the use of artificial stimuli on muscle and nerve tissue, the resulting response action potential can be stored and displayed by the Digitiser.

## INPUTSTAGE

The input stage in Fig. 1 consists of a preamplifier, IC2 with a gain variable from $\times 0$ to $\times 100$. A high slew rate operational amplifier is used ( $13 \mathrm{~V} / \mu \mathrm{s}$ ), a TLO84, which is a BIFET opamp with an input impedance of $10^{12} \mathrm{ohms}$. The input signal to the waveform digitiser can be either a.c. or d.c. coupled as selected by S2. There is also a variable d.c. offset conţol, VR2 that can be switched in and out of the circuit by S 1, and this enables either a positive or negative level to be added to the input signal. The trigger circuit consists of a voltage comparator, IC1a, and a trigger level potentiometer, VR4. VR4 sets a threshold level for triggering the start of the counter for the memory addressing.

Overload I.e.d.s, D1 and D2, warn when the input signal to the analogue to digital converter, IC3, is either above +2.5 V or below -2.5 V .

## ANALOGUE TO DIGITAL CONVERTER

The analogue to digital converter used is the Ferranti ZN449. This gives a digital output of 8 bits, has a guaranteed conversion time of $9 \mu \mathrm{~s}$, its own clock and 2.5 V reference source. See Fig. 5 for timing diagram.

This ADC uses the successive approximation method, and the control pins are as follows. (See Fig. 2).

Pin 1 (BUSY) this is low when the ADC is converting and goes high when the conversion has ended, and is used in the Waveform Digitiser to control the write signal to memory. Pin 2 ( $\overline{R D}$ ) controls the tri-state output of the data outputs of the ADC, when this pin is low, the data can be read, i.e., enabling the tri-state outputs. Pin 3 (CLOCK) sets the frequency of the internal clock required for the successive approximation process, and is set to 1 MHz with C 1 on the Waveform Digitiser. Pin $4(\overline{W R})$ is the write signal, when low a start conversion initiates the analogue to digital conversion process, and so the $\overline{B U S Y}$ must go low. In the Waveform Digitiser, the ADC is converting at the rate set by the clock oscillator, ICs 11, 12, 13. At the end of a conversion, the $\overline{\mathrm{BUSY}}$ signal is sent to control logic to write the data into the memory.



Fig. 2. Block diagram of ZN449 ADC


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Fig. 3. Block diagram of ZN429 DAC

## VARIABLE FREQUENCY CLOCK

The clock, i.c.s $11,12,13$ sets the frequency for the number of conversions/second for the ADC in record (Write) mode, and when in the play (Read) mode, sets the output sample frequency. The maximum input conversion rate is 100 kHz .

Table 1: Clock Range
a $1-10 \mathrm{~Hz}$
b $10-100 \mathrm{~Hz}$
c $100-1 \mathrm{kHz}$
d $1 \mathrm{kHz}-10 \mathrm{kHz}$
e $10 \mathrm{kHz}-100 \mathrm{kHz}$

## MEMORY

A kilobyte static RAM is used as the memory, and consists of two, $1 \mathrm{~K} \times 4$ bit static RAMs, type 2114 . The total memory used can be expanded by using additional 2114 s and extending the counter range of the 12 bit counter, IC7. Four kilobytes of memory can be used with IC7 at present and more CMOS 4040s can be used if more memory is required to be addressed.


Fig. 4. Circuit of power supply


Fig. 5. Logic timing diagram

## CONTROL LOGIC AND ADDRESS COUNTER

The control logic allows the following functions to be performed: 'Repeat' or 'Single', 'Write' or 'Read', 'Set' and 'Reset' of counter circuit, 'Post' or 'Pre' trigger control, oscilloscope 'Trigger Out', l.e.d: indication of memory 'End', trigger 'Armed', voltage 'Trigger Level', 'Overload' to ADC.

Read (Play) or Write (Record) is selected by S7 that sets either a 1 (read) or $\overline{W E}$ (write enable) pulse to the memory. The $\overline{W E}$ is derived from the $\overline{B U S Y}$ signal from the ADC, and the data from the ADC is written into the RAM.

The Repeat/Single switch sets IC7 to either count continuously or terminate at count 1023.

The Set push switch arms the analogue trigger circuit (IC1a, IC8a, b) and when the trigger level is exceeded, the data will be loaded into memory.

Post trigger starts the addressing from count 0 . In the Pre-trigger mode the counter is running continuously until a pre-trigger signal stops the counter. The signal that occured before the trigger can thus be stored. This is useful for analysing signals such as those caused by power supply transients; the momentary glitch can be observed at leisure in the stored mode.

The oscilloscope trigger control is a 5 V CMOS compatible signal that is connected to the External Trigger input of the oscilloscope. This provides a stationary display on the 'scope.

The memory End l.e.d. is illuminated whenever the address count is at 1024 to 2048, and will light once per 1024 address counts in the Repeat mode. In the Single mode the l.e.d. will indicate that the memory is full and recording has stopped. The trigger Armed I.e.d. is lit when the analogue trigger circuit is in a waiting state, i.e. waiting to be triggered by an input signal. The voltage trigger l.e.d. will light when the threshold has been reached by the sample input, and this l.e.d. is used with the Trigger Level control to set its threshold.

| Resistors |  |  |
| :---: | :---: | :---: |
| R1 | 82k |  |
| R2, 3, 28 | 8 k 2 |  |
| R4 | 390 |  |
| R5 | 1 M |  |
| R6, 15, 16, 19, 31 | 10 k |  |
| R7 | 220k |  |
| R8, 13, 14 | 1 k |  |
| R9, 10 | 470k |  |
| R11, 12, 18, 20, 27 | 180 |  |
| R17, 25, 26 | 47k |  |
| R21 | 100k |  |
| R22 | $1 \mathrm{M5}$ |  |
| R23, 32 | 4 k 7 |  |
| R24 | 3 k 3 |  |
| R29 | 3 k 3 |  |
| R30 | 27k |  |
| All $\frac{1}{4}$ W 10\% carbon |  |  |
| Capacitors | C7, 8 | $0.1 \mu$ |
| C1 33p ceramic | C9 | $470 \mu$ elect 16 V |
| C2 $4 \mu 7$ elect 9 V | C10 | $100 \mu$ elect 16 V |
| C3 $\quad 0 \cdot 1 \mu$ polyester | C11 | 68p |
| C4. 5 8n2 10\% | C12 | 470 p polyester |
| C6 22 n polyester | C13, 14 | 100p ceramic |

Integrated Circuits

| IC1 | LM324 | IC9 | 4049B |
| :--- | :--- | :--- | :--- |
| IC2 | TL084 | IC10 | 4081B |
| IC3 | ZN449 | IC11 | 4046 B |
| IC4 | ZN429 | IC12,13 | 4518 B |
| IC5,6 | 2114 | IC14 | 78 M05 |
| IC7 | $4040 B$ | IC15 | 78 LO5 |
| IC8 | 4001 B |  |  |

Diodes
D1, 2,4,

| D3 | Green l.e.d |
| :--- | :--- |
| D5 | Amber l.e.d. |

Potentiometers VR1
VR2, 4, 6
VR3
VR5a, b
Switches

| S1,2,5,6 | S.p.d.t. |
| :--- | :--- |
| S7 | S.p.s.t. |
| S4 | S.p.s.t. |
| S3 | S.p.d.t. |
| S8 | Singe pole 6 way rotary |
| S9 | S.p.d.t. mains |

Miscellaneous
BR1, BR2-bridge rectifiers WOO5, transformer T1, 0-9V, 0-9V 9VA, BNC sockets (3 off), knobs (5 off), l.e.d. clips (5 off), cabinet (Maplin type WB6), p.c.b., Veropins ( 46 off), p.c.b. mounting pillars, stick-on rubber feet (4 off)

## D TO A CONVERTER AND OUTPUT FILTER

A Ferranti ZN429 digital to analogue converter i.c. is used to convert the stored signal back to the analogue form. This DAC has an 8 bit input, a settling time of $1 \mu$ s and uses the voltage reference of the ZN449. The analogue output can be filtered, if required, to smooth the step waveform from the DAC output, by the filter as shown.


Fig. 6. Etching detail of board topside

## POWER SUPPLY

This is a $\pm 5 \mathrm{~V}$ power supply, providing the 200 mA required by the +5 V circuits and 25 mA required for -5 V use. In the prototype two separate transformers were used for the power supply, but a transformer with two separate secondary windings is also suitable. (Fig. 4).

## CONSTRUCTION

Assemble the components onto the printed circuit board as shown in Fig. 7. The prototype p.c.b. is double sided, with pins linking the two sides of the board.

Connect up the components starting with the resistors, diodes, capacitors.


Fig. 7. Track layout and component overlay. Here the board topside is coloured and the underside tinted

The i.c.s can be soldered directly into place on the p.c.b. Take the usual precautions with CMOS i.e., earth yourself when handling and use a low leakage soldering iron. The terminal pins can now be connected to the p.c.b., these can most easily be inserted by pushing the pins gently into place and using the soldering iron to heat up the pin so it slides into position on the board.

The front panel controls are labelled as shown with any suitable dry transfer lettering. Note that the filter shown on the left hand side of the front panel is not in use any more, unless an input filter is required. The lettering can now be protected with clear laquer.

The p.c.b. can now be mounted in the box, together with the transformer, and front panel controls.


## SETTING UP

The Offset potentiometer is first set up. Connect the input of the Waveform Digitiser to ground, switch to d.c., switch Offset control to 'Off' and set the gain control to maximum. Adjust VR3 until the output of IC2b is OV.

Set the Frequency control to maximum, and measure the output at IC11, pin 4. This should be 100 kHz . Set the control to minimum, and the frequency should now be 10 kHz .

Adjust R21 if the upper limit is inaccurate and similarly R22 for the lower limit.

## TESTING

Connect a signal generator to the input of the Waveform Digitiser, with a triangle wave of frequency 100 Hz and amplitude approximately 1 V .

Set the Digitiser controls as follows; 'A.c.' on, 'Offset' off.


Fig. 9. Case mounted components and interwiring with numbered board pins
'Post' trigger, 'Trigger Level' mid point, 'Repeat', 'Write', 'Freq.' ( 100 kHz ), 'Filter' off, 'VIEW OUT' signal.

Connect Trigger out to an oscilloscope external trigger input, and connect the Output of the Waveform Digitiser to the CRO signal input. Adjust the Gain control potentiometer until the overload I.e.d.s just stop flickering. Now switch to Read, and check that the oscilloscope shows the stored triangle wave. This should be 2.5 V amplitude, linear, and have no glitches.

The analogue trigger can be tested now. Set the controls as above with the Single setting used instead of Repeat. Reduce the signal generator amplitude to minimum, and press the Set push switch. The Waveform Digitiser is now waiting for a trigger signal, as indicated by the Arm I.e.d. Increase the signal generator output and the Trigger l.e.d. should light when the trigger threshold is crossed. Switch to Read and Repeat and the stored waveform should be displayed.
The Pre-trigger control can now be tested. Set to Pretrigger, Write, Repeat, Freq. ( 1 kHz ). Set the signal generator to 100 Hz and minimum amplitude. Press the Set switch and slowly increase the input signal amplitude over a period of about a second. Switch to Read and observe the output waveform is of a stationary waveform with increasing amplitude. Approximately 10 cycles will be seen.

The operation of the filter can be checked by switching it in and adjusting the frequency control until the output waveform is smoothed and the step response is eliminated.

## FAULT FINDING

Check that the input signal is present on IC2, pins 1 and 7 and IC3, pin 6. The operation of the analogue trigger circuit can now be checked. IC1a is used as a comparator; and when the signal on pin $3, I C 1$ is above the voltage level set by VR4 then the output of pin 1, IC1 goes to logic 1 (CMOS logic 1 is 3.5 V with 5 V power supply). This signal then sets the latch IC8a,b. In the Post trigger mode, the output of IC8, pin 4 goes to C6,R19, which sends a rest pulse to the address counter IC7, so that the count starts at zero. On the negative edge of the pulse from IC8, pin 10, the data from the ADC is written into memory.

Check that the clock oscillator, IC1 1,12,13 is operating satisfactorily, pin 4 IC 11 should give an output frequency of 100 kHz with VR5 at maximum. Check that the decade dividers, IC12,13 are working.

Measure the clock frequency on pin 4, IC3 (ADC), this should be as on S8. Now test the frequency of pin 3, IC3. this should be 1 MHz . If the ADC is working, then the BUSY output (pin 1) will have an output frequency as on S 8 . Check that the $\overline{R E A D}$ pin is at logic 0 , the input waveform from the signal generator should now be seen at the output of the DAC, IC4, pin 4.

If the input waveform is seen at the DAC output, but is not stored in memory, then the following tests can be applied. Observe that the clock signal is present at pins 10 IC6/7. and that each of the address pins on IC5, 6 is correctly addressed.

Test for the $\overline{W E}$ (Write Enable) signal (pin 10, IC5, 6) from IC8 pin 10.

## CONTROL FUNCTIONS

'ON' switch-connects mains supply.

## 'ON'I.e.d. -5 V on.

AC/DC switch-a.c. coupled ( 3 Hz ) or d.c. coupled.
GAIN pot-Amplifier has unity gain bandwidth of 3 MHz .
'IN' BNC socket-input impedance $1 \mathrm{M} \Omega$, signal greater than 50 mV .
Offset 'ON/OFF'-'On', $\pm 5 \mathrm{~V}$ d.c. offset, 'Off', OV offset.
'OFFSET' pot-sets d.c. offset level.
Filter 'ON/OFF' $20-20 \mathrm{kHz}-12 \mathrm{db} /$ octave low pass filter.

## 'FILTER' pot-sets frequency of cut off.

Trigger 'PRE' or 'POST'—pretrigger records and displays the memory contents before a trigger threshold is crossed. Post-trigger records and displays the memory contents after the trigger point.
'TRIG LEVEL' pot-sets a level $0-+5 \mathrm{~V}$ as threshold.
'ARM' l.e.d.-Digitiser is waiting for a trigger level to be crossed and for recording to be commenced. This is set by Set push button. When the threshold is crossed, the signal is recorded.
'ON' l.e.d. (Trigger)-lights when trigger threshold is crossed.
'SINGLE/REPEAT'- the first is a memory count of 01023. Repeat is continuous addressing of memory for read or write. 'End' l.e.d.-count 1023 reached.
'READ/WRITE'—Read-play, Write-record.
'FREQ' sets frequency of clock for read and write.
'RANGE' of clock. Five ranges reading clockwise
a $1-10 \mathrm{~Hz}$
b $10-100 \mathrm{~Hz}$
c $100-1 \mathrm{kHz}$
d $1 \mathrm{kHz}-10 \mathrm{kHz}$
e $10 \mathrm{kHz}-100 \mathrm{kHz}$
'SET' press to set arm latch (state shown by arm l.e.d.)
'RESET'-resets addresser to count 0 .
-OVERLOAD' + ve and -ve overange to analogue to digital converter shown by l.e.d.s.
'VIEW' switch-'In' from input BNC 'Out'-digital to analogue converter output.
'TRIG OUT'-to external trigger of oscilloscope.

```
- OUT' BNC socket O-+2.5V
```



Note: The third strip controls are redundant


## OPERATION

To store a continuous waveform in the memory of the Waveform Digitiser, set the controls as follows: 'Post', 'Repeat', 'Write', 'View Out', Filter 'Off'. Set Gain and Offset as required, any overload will be indicated by the Overload l.e.d.s. Set clock rate as fast as possible, noting that:

Total time for event $=1024 /$ clock frequency
To view the stored waveform, switch to Read, and observe the waveform on an oscilloscope connected to the BNC output socket. Connect the external trigger output (Trig Out) of the Waveform Digitiser to the external trigger input of the oscilloscope, so that a stationary display is obtained.

Use of the Post trigger feature is similar to above. Set the switch to Single and adjust the trigger pot until a suitable trigger level is found. Press Set, and when the input signal crosses the threshold the signal will be stored in memory. The Post trigger is used for transient waveforms, and to view the signal, switch to Read and Repeat.

To use the Pre-trigger, switch to Pre, Repeat, Write, Set, and set a suitable trigger level. The pre-trigger event will be. recorded when the threshold is crossed. Switch to Read and Post to observe the stored waveform.

The stored waveforms can be displayed at any convenient frequency, by adjusting the Freq and Range controls as required. Hence low frequency events, e.g. less than 10 Hz can easily be displayed on the oscilloscope without flicker.

## APPLICATIONS

One possible application of the Waveform Digitiser is in the storage of musical instrument sounds. The characteristic of any part of the waveform can be stored and later analysed, e.g. the start of the sound may be of particular interest in the case of a plucked instrument. In another example, the tonal characteristics of a piano waveform five seconds from the start of the note may wished to be stored. A suitable microphone pre-amplifier circuit is shown in Fig. 10

Transient sounds such as those from percussion instruments can be stored. The highest possible input sampling frequency is chosen so that the waveform fits into the memory space and that the greatest possible time resolution is obtained. For a 100 kHz input sampling frequency, a sound of length 10 ms would fill the kilobyte memory.

Another use of the Digitiser is in the display of the amplitude envelope of a note being played. By using a precision rectifier circuit to convert the a.c. input to d.c., the envelope can be recorded.

Another application is as a sequencer to store a pattern of notes as played by a sound synthesiser. Some circuit modification would be required, but basically, the synthesiser keyboard control voltage is stored by the Digitiser. The replayed voltages are then converted into frequency by the synthesiser's voltage controlled oscillators.

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## PART TWO Fred Judd E.A. Rule

THE Power Amplifier section of the Combo Amplifier is based on the very successful Winton amplifier design published in Practical Wireless, in March 79. The circuit has been modified to give increased power.

One of the most important requirements for an amplifier is that it is reliable, for if an amplifier breaks down in the middle of a concert it can cause all sorts of repercussions, so reliability is very high on the list. For this reason the power MOS-FET is the only choice, in the writers opinion, for the output devices. Two of the advantages of using power MOSFETs are that they do not suffer from secondary break down or thermal runaway as normal bipolar transistors do, and this means that they are almost 'abuse proof'. They can be run into any type of load without fear of breaking down, and even if they are run into a load that would normally overrun the output stage, the only thing that happens is that they gradually produce less power output as they get hot until a balance is reached between the heating caused by the adverse load and the power delivered into it.

Bipolar devices subjected to the same conditions will almost certainly either suffer from secondary breakdown or thermal runaway, and even if protective circuits were used in such a design these would operate and shut the down output, which, as far as a concert is concerned would have the same effect as a failure.

Power MOS-FETs do not need protection, thus another possible cause of interruption is removed.

The circuit of the power amplifier and power supply is shown in Fig. 2.1. The signal from the control unit section is fed into TR 1 via an RF filter C2 R4. TR1 forms one half of a differential pair TR1 and TR2 using low noise transistors type BC556, which in turn drive a second differential pair TR4 and TR5 type 2SC1775e. TR3 and D1 form an active collector load (current mirror) to maintain the pushpull action. Drive to the gates of the power MOS-FETs is taken direct from the second differential pair. The power MOSFETs are protected from overdrive by diodes D2 to D5.

Because of the very low distortion obtained when using MOS-FETs, only 45dB of negative feedback is needed to obtain the required low distortion, and this is fed via R9 R8 C4 from the output back to the base of TR2. The use of less feedback means that, at the overload point the amount of distortion produced is less objectionable than would be the case with the 60 dB or more often used in bipolar amplifiers. Yet another advantage of MOS-FETs!

Only minimal phase correction is needed (due to the excellent high frequency response, full power can be obtained at 100 kHz ) in the negative feedback loop and as a result the amplifier is unconditionally stable. Electronic decoupling is used in the supplies to the early stages of the power amplifier and these enable very low distortion to be maintained at all power outputs as well as improving the overall signal to noise.

As the MOS-FETs have a negative temperature coefficient, no adjustment is needed. for setting the quiescent current, which will be around 50 mA when cold, and after prolonged high power use the current will quickly return to a low level as thermal runaway is impossible with these devices.

## HEAT SINKS

Normally, a heat sink is designed to prevent thermal runaway of the output devices and to maintain the devices used within their maximum power ratings. The requirements of heat sinks when using power MOS-FETs are different to that normally used with bipolar devices in as much as we are not concerned about thermal runaway. If fact, the design could come down to two requirements only. Will the power output required be maintained at the temperature the output devices are running at, and if the heat sink could be touched by someone, would it burn them! Of course, in practice we still want the devices to run as cool as possible for reliability and to maintain maximum power, and as commercial heat sinks are expensive it was decided to make these out of 1.2 mm thick aluminium sheet. The method used is shown in Figs. 2.2 to 2.4 , and these will enable the full power of the amplifier to be maintained under all practical conditions with a final temperature of around 60 to 80 deg $C$ above ambient with continuous drive. As the power amplifier unit is mounted in the bottom of the speaker cabinet they are unlikely to be touched. Under normal music conditions it is doubtful if they will get anywhere near the maximum temperature.

## Specification

## Power Amplifier

Power output @ 1 kHz Power bandwidth - $1 d B$ Frequency response, - 1 dB Total Harmonic Distortion, 20 Hz to 20 kHz up to rated power Slew Rate Damping Factor Signal to noise (input shorted) Stability Input voltage for maximum power

60 watts 20 Hz to 50 kHz 20 Hz to 50 kHz

Less than 0.05\% 20Volts/microsec better than 50 88dB (96dBA) Unconditional

100 millivolts

## POWER SUPPLY

To reduce the weight of the unit, and to obtain good regulation, a Toroidal type of transformer is used in the power supply. The output from this goes to a bridge rectifier REC1 and then to two $4700 \mu$ capacitors, C13 C14, which need a high ripple current rating for reliability. A Zener stabilised, $\pm 15$ volts supply is also provided for the control unit section, via R1, R2, D8, D9.

## CONSTRUCTION

The power amplifier is mounted in the bottom of the speaker cabinet, and a simple construction can be used for the chassis which consists of one sheet of aluminium bent into an $L$ shape. The dimensions are given in Fig. 2.5.

Mark out and drill all the holes with the aluminium sheet flat, and then bend as shown. Be sure you bend it the correct way. The same procedure is used for the heat sinks. Make sure that the heat sinks are free of all burrs, as these must fit flush to each other so that the heat from the transistors is transferred to the fins.

An improvement in heat dissipation of around $40 \%$ can be obtained by painting the heat sink fins matt black, although this was not done on the original prototype and no ill effects were noted.

The mains transformer and $4700 \mu$ capacitors are held in place with large cable ties RS 543-349.

The printed circuit board (Fig. 2.6) is mounted on the insulating pillars. The component layout is shown in Fig. 2.7.

## FINAL WIRING

The wiring diagram is shown in Fig. 2.8. Wiring is not critical but $16 / 0.2 \mathrm{~mm}\left(.5 \mathrm{~mm}^{2}\right)$ flex should be used and all leads to the power MOS-FETs should be kept as short as possible. It will be found that the best way to wire these is to fit the wires to the MOS-FETs first then place the p.c.b. in

Fig. 2.1. Circuit diagram of the power amplifier
Please note, there is no D7, and R13 should ideally be 18K



Fig. 2.2. Heatsink plate " $A$ " drilling and bending details


Fig. 2.3. Heatsink plate " $B$ " drilling and bending details



Fig. 2.4. Dual heatsink assembly. Heatsink compound should be used on both sides of the mica washer, and between plate $A$ and plate B



Fig. 2.5. Power amplifier support bracket dimensions


Photographs showing all aspects of the power amplifier and PSU


Fig. 2.6. Amplifier p.c.b. (actual size)


Fig. 2.7. Component layout


Fig. 2.8. How to make R21/L1 as a combined component


Fig. 2.9. Wiring diagram for this section of the Combo Amp.

## COMPONENTS . . .

## POWER AMPLIFIER

| Resistors |  |  |
| :---: | :---: | :---: |
| R1, R2 | 680R | 2.5 watt w/w (2 off) |
| R3 | 100k |  |
| R4 | 2k2 |  |
| R5, R24 | 2k7 | (2 off) |
| R6 | 39k |  |
| R7 | 150 |  |
| R8 | 15k |  |
| R9 | 12k |  |
| R10, R11 | 100 | (2 off) |
| R12 | 330 |  |
| R13 | 18k |  |
| R14 | 220 |  |
| R15, R19 | 120k | (2 off) |
| R16, R20 | 4 k 7 | (2 off) |
| R17, R18 | 560 | (2 off) |
| R21, R22 | 10 | 1 watt 5\% (2 off) |
| R23 | 10k | 0.5 watt 5\% |

All resistors $\frac{1}{4}$ W 5\% unless otherwise stated

## Diodes

D1, D2, D5
D3, D4, D8, D9
D6
REC1

1N4148 (3 off)
15 volt Zener 400 mW (4 off)
TIL 209 l.e.d.
KBL-01/02 (4 off)

## Capacitors

| C1 | $2 \mu 2$ | Elect. 63 V |
| :--- | :--- | :--- |
| C2 | 100 p | Polystyrene |
| C3 | $220 \mu$ | Elect. 16 V |
| C4 | 10 p | Polystyrene |
| C5, C8, C9 | 100 n | Polyester (3 off) |
| C6, C7 | $47 \mu$ | Elect. 63 V (2 off) |
| C10, C11 | 47 n | Polyester (3 off) |
| C12 |  |  |
| C13, C14 | $4700 \mu$ | Elect.** (2 off) |
| C15 | $200 n$ | Polyester |
| CX | $68 p$ | Polystyrene |

**7A ripple current. 63 V working.

## Transistors

TR1.TR2
TR3
TR4, TR5
TR6
TR 7
TR8
TR9

BC556b (2 off)
BC556a
2SC1775e (2 off)
BC556a or b
BC546a
2SK133
2SJ48

## Miscellaneous

Printed circuit board. Aluminium for chassis etc. wire. printed circuit stand-offs. Cable ties.
T1 Mains transformer ILP type 52018.
A complete set of semiconductors are available from Hart Electronics.
L1 See Fig. 9 for details.
S101/102 DPDT Toggle RS 316-989
F1 fuse, 2.5 amp quick-blo. 20 mm
F2 fuse 1 amp SO-blo 20 mm
Fuse holders RS 412-879
Cable clamp RS 544-263
position and wire the leads to the pins as shown, leave just enough slack wire to enable the p.c.b. to be removed and turned over for any service that may be required. When all the wiring is completed it can be held in place by the use of small cable ties. It is important to note the common connections, for example, C14 positive is the common connection for wiring from pins 2 , speaker negative, l.e.d. and centre tap of transformer secondary. They should not be wired-pin 2 to l.e.d. negative, then to C14, or any other way other than shown if the specification for distortion and signal-to-noise is to be obtained.

## TESTING

Before switching on, connect a $30 / 33$ ohm wire wound resistor in series with each of the supply rails to the power
amplifier, i.e. between pins 12,21 and their respective leads to the power supply. This is to limit the current in case of a fault condition when first switching on. Switch on and check the voltages. Note, do not connect the speaker at this stage. If the voltages are correct and there is no d.c. voltage on the output terminals (and no smoke either) switch off, connect the speaker and try the unit out with a signal.

Leave the extra resistors in circuit while testing at low power as an extra precaution in case of possible faults. Once signals which sound okay at low volume have been obtained, the two 30/33R resistors can be removed and the supply connected direct.

Next Month: The cabinet and speaker construction will be dealt with. Also, various ways of using the Combo amplifier.

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－ 6803 C
－ 8809 C
－6803C
＊ 6809
－6801
$\cdot 688$
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## － <br> I <br> ，

687
684
$\square$

| $* 65$ |
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## 8080 FAMILY

－8085A
8212
82085
8212
8216
＊8251
$* 8255$
BUFFERS
BUFFERS
$81 L \$ 95$
811596
81 LS97
$81 L S 58$
81LS 38
8126A
BT28A
BT28A
8 T95
$8797 A$
8T5
DATA
CONVERTERS
－2N425
$\cdot{ }^{-2 N 428}$
－2N433

| $2 N 447 / 8 / 9$ | 250 |
| :--- | :--- | 299

349
ctions on LPS and CMOS
UPS and CMOS
 ${ }^{*}$ WD1771 ${ }^{\text {W }} 1391{ }^{17}$ ＊WD1393 Kit 1.008 MHZ

1.8432 MH \begin{tabular}{ll}
Z \& 2 <br>
HZ <br>
HZ <br>
\hline

 

2.50 \& 26 <br>
2.20 \& 27 <br>
255 <br>
1.45 \& 28 <br>
1.45 \& 32 <br>
1.70 \& 37
\end{tabular}

WD
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| Price | Device Price |
| :---: | :---: |
|  | 74LS CONT． |
|  | 377 0．EO |
| 0.12 | 390 0．49 |
| 0.12 | $393 \quad 0.44$ |
| 0.12 |  |
| 0.12 | OLL SOCXETS |
| 0.12 | LOW PRORLE－ |
| 0.12 | TIN |
| 0.12 | 8 pin 0.07 |
| 0.12 | 14 pin 0.00 |
| 027 | 16 pin 0.09 |
| 034 | 18 pin |
| 0.14 | 20 pin 0.14 |
| 0.14 | $22 \mathrm{pin} \quad 0.17$ |
| 0.16 | $24 \mathrm{pin} \quad 0.19$ |
| 0.19 | 28 pin 025 |
| 0.17 | 40 pin 029 |
| 0.34 |  |
| 0.51 | Dil SOCKETS LOW PROFILE－ |
| 0.15 0.28 | $\begin{aligned} & \text { LOW PROFLLE - } \\ & \text { GOLD } \end{aligned}$ |
| 0.31 | 8 pin 0.22 |
| 0.25 | 14 pin 029 |
| 0.27 | 16 pin 0.37 |
| 0.35 | 18 pin 0.33 |
| 0.35 | 20 pin 0.35 |
| 0.24 | 22 pin 0.40 |
| 0.25 | 24 pin 0.2 |
| 0.30 | $28 \mathrm{pin} \quad 0.54$ |
| 0.23 | 40 pin |
| 0.31 |  |
| 0.31 | DIL．JUMPERS |
| 0.69 | Single Ended 24 |
| 0.39 | $\begin{array}{ll}14 & \text { pin } \\ 16 & 1.40 \\ 24 & 1.60\end{array}$ |
| 0.28 | 16 pin 1.60 <br> 24 pin |
| 0.34 | $\begin{array}{ll}24 \\ 40 \text { pin } & 235 \\ 425\end{array}$ |
| 0.34 | $40 \mathrm{pin} \quad 3-5$ |
| 0.25 | Doubte Ended $6^{*}$ |
| 029 | 14 pin 1.90 |
| 0.35 | 16 pin 205 |
| 0.34 | 24 pin 3.10 |
| 0.39 | 40 pin 45 |
| 0.51 |  |
| 0.68 | Double Ended 12 |
| 0.64 | 14 pin 200 |
| 0.40 | 16 pin 215 |
| 0.44 | 24 pin 3．25 |
| 0.4 | $40 \mathrm{pin} \quad 5.10$ |
| 0.4 | ＇Double Ended 1\％＇ |
| 034 | 14 pin 205 |
| 0.34 | 16 pin 225 |
| 0.54 | $24 \mathrm{pin} \quad 3.40$ |
| 0.64 | 40 pin $\quad 5.25$ |
| 0.64 |  |
| 0.64 |  |
| 0.54 | ZERO INSERTION FORCE SOCKETS |
| 0.59 |  |
| 0.69 | 24 pin |
| 0.29 | 28  <br> 40  <br> 0 pin 7.40 |
| 0.34 | 40 pin － 80 |
| 0.57 |  |
| 0.19 | 25 WAY＂D＂ |
| 0.98 | CONNECTORS |
| 0.29 | Male－Male（36＇ |
| 0.39 | cable） 10.15 |
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| 029 | cable） 10.13 |
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| CMOS |  |  |  | D Connectors |  |  |  |
| 4001 | 10.10 | 4069 | 20.15 | (Can | on |  | Hsg. |
| 4007 | ¢0.15 | 4070 | 20.15 |  |  |  |  |
| 4001 | \$0.47 | 4078 | 60.18 |  | Plugs c0.80 | ¢0.95 |  |
| 4011 | 60.11 | 4081 | 60.14 | is Way | \& 1.10 | 81.50 |  |
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| 4017 | 10.40 | 4511 | 10.45 | 9 Way | 21.17 | C1.80 |  |
| 4018 | 10.45 | 4512 | 10.50 | Is way | ¢ 1.53 | $\underline{62.32}$ |  |
| 4011 | c0.48 | 454 | 11.19 | 25 way | 62.20 | ¢3.20 |  |
| 4012 | 10.48 | 4515 | $¢ 1.20$ | 37 Way | 62.97 | 84.20 |  |
| 4023 | 10.16 | 4516 | 60.59 |  |  |  |  |
| 4024 | 10.32 | 4518 | $¢ 0.35$ | Volt |  |  |  |
| 4025 | 80.16 | 4520 | 60.59 | Regula | tors | Diodes |  |
| 4018 | 10.48 | 4528 | 60.64 | 7103 | 60.39 | W10002 | 60.05 |
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