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| 949 | Iron coated bit $3 / 32^{\prime \prime}$ for 1948 |  |
| 1950 | Iron coated bit $1 / 8^{\prime \prime}$ for 1948 | f0 |
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| 1931 | X25 25 watt iron. ceramic shaft and anoth shaft of stainless steel to ensure strength |  |
| 1935 | Replacement element for 1931 | £1.84 |
| 1932 | Iron coated bit $1 / 8^{\prime \prime}$ for 1931 | f0.57 |
| 1933 | Iron coated bit $2 / 16^{\prime \prime}$ for 1931 | ¢0.57 |
| 1934 | Iron coated bit $3 / 32$ " for 1931 | ¢0.57 |
| 1953 | SK1 soldering Kit - contains 15 watt sol iron with $3 / 16^{\prime \prime}$ bit plus two spare bits, a solder, heat-sink and a booklet Solder | ring el of ow to f6. 38 |
| 1939 | ST3 iron stand made from high grade bak chrom plated steel spring, suit all model includes accommodation for six bits and |  |
| 1724 | Model MLX as X25 iron but 12 volts | f5. |

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| BA100 | ¢0.11 |
| BA102 | E0.37 |
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| BA154 | c0.14 |
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| 16217 | 40 mixed $1 / 2 \mathrm{w} 100 \mathrm{ohm}$ |  |
| 16218 | 40 mixed $1 / 2 \mathrm{w} 1 \mathrm{Kohms-82K}$ |  |
| 16 | 40 mixed $1 / 2 w$ |  |
| 16220 | 40 mixe | c0.69 |
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| 16162 |  |  |
|  | $24-3$ of each value 470p 1500 pf 2200 pf 3300 pf <br> 1500 pf 2200 pf 3300 pf $24-3$ of each value 4700 pf 6800 pf 01 uf 015 fo. 69 <br> 033uf 047uf |  |
| 61 |  |  |
|  |  |  |
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| $\begin{aligned} & 16201 \\ & 16202 \\ & 16203 \end{aligned}$ | values from $47 \mathrm{mfd}-10 \mathrm{mfd}$ values from $10 \mathrm{mfd}-100 \mathrm{mfd}$ <br> values from $100 \mathrm{mfd}-680 \mathrm{~m}$ | $\begin{aligned} & \mathbf{8 0 . 6 9} \\ & \mathbf{6 0 . 6 9} \\ & \mathbf{8 0 . 6 9} \end{aligned}$ |
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$7.5 \mathrm{v}, 8 \cdot 2 \mathrm{v}, 9.1 \mathrm{v}, 10 \mathrm{v}, 11 \mathrm{v}, 12 \mathrm{v}, 13 \mathrm{v}, 15 \mathrm{v}, 16 \mathrm{v}, 18 \mathrm{v}, 20 \mathrm{v}, 22 \mathrm{v}$,
$24 \mathrm{v}, 27 \mathrm{v}, 30 \mathrm{v}, 33 \mathrm{v}, 43 \mathrm{v}, 47 \mathrm{v}, 51 \mathrm{v}, 68 \mathrm{v}, 72 \mathrm{v}, 75 \mathrm{v}, 82 \mathrm{v}, 91 \mathrm{v}$,
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| SPECIFICATIONS |  |  |
| :---: | :---: | :---: |
| PARAMETER | BECKMAN 3020 | FLUKE 8020A |
| DC Voltage Ranges Accuracy | $\begin{aligned} & 5,200 \mathrm{mV}-1500 \mathrm{~V} \\ & \pm(0.1 \% \mathrm{rdg}+1 \text { digit }) \end{aligned}$ | $\left\lvert\, \begin{aligned} & 5,200 \mathrm{mV}-1000 \mathrm{~V} \\ & \pm(0.25 \% \text { rdg }+1 \text { digit }) \end{aligned}\right.$ |
| AC Voltage <br> Ranges <br> Accuracy <br> $45 \mathrm{~Hz}-2 \mathrm{kHz}$ | $5,200 \mathrm{mV}-1000 \mathrm{~V}$ $\pm(0.6 \% \mathrm{rdg}+3$ digits $)$ | $\begin{aligned} & 5,200 \mathrm{mV}-750 \mathrm{~V} \\ & \pm(0.75 \% \mathrm{rdg}+2 \text { digits }) \\ & \text { to } \pm(1.5 \% \mathrm{rdg}+3 \text { digits }) \end{aligned}$ |
| DC Current Ranges Accuracy | $\begin{aligned} & 6,2000 \mathrm{~A}-10 \mathrm{~A} \\ & \pm(0.35 \% \text { rdg }+1 \text { digit } \\ & \text { (except } 10 \mathrm{~A}) \end{aligned}$ | $\begin{aligned} & 4,2 \mathrm{~mA}-2 \mathrm{~A} \\ & \pm(0.75 \% \mathrm{rdg}+1 \text { digit }) \end{aligned}$ |
| AC Current <br> Ranges <br> Accuracy $45 \mathrm{~Hz}-2 \mathrm{kHz}$ | $\begin{aligned} & 6,200 \mathrm{~mA}-10 \mathrm{~A} \\ & \pm(0.9 \% \mathrm{rdg}+3 \text { digits) } \\ & \text { (except } 10 \mathrm{~A}) \end{aligned}$ | $\begin{array}{\|l} 4,2 \mathrm{~mA}-2 \mathrm{~A} \\ \pm(1.5 \% \mathrm{rdg}+3 \text { digits }) \\ \text { to } \pm(2.0 \% \mathrm{rgg}+2 \text { digits }) \\ \text { (up to } \mathrm{lkHz}) \end{array}$ |
| Resistance <br> Ranges <br> Accuracy | $\begin{aligned} & 6,200 \Omega-20 \mathrm{M} \Omega \\ & \pm(0.2 \% \mathrm{rdg}+1 \text { digit }) \end{aligned}$ | $\begin{aligned} & 6,200 \Omega-20 \mathrm{M} \Omega \\ & \pm\left(0.2^{\%} \mathrm{rdg}+1 \text { digit }\right) \\ & \text { to } \pm(2.0 \% \mathrm{rdg}+1 \text { digit }) \end{aligned}$ |
| Battery Life | 2000 hrs | 200 hrs |
| Fast Continuity Check | Yes | No |

Specifications obtained from published data.

## BECKMAN

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"Sound Design" booklet

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Additional 3
3 -octave set of PCBs
Set of text phorocopies
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KIT 80-8 $\mathbf{8 9 . 4 5}$

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Set of PCBs (incl. layout charts)
KIT 38-23 KIT 38-24
287.05 "Sound Design" booklet

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Main Unit basic component kits Main Unit set of PCBs \& layout charts Keyboard Unit basic component kits Keyboard Unit set of PCBs \& layou
charts
Keyboard Unit set of text photocopie
KIT 23-27 e86.99 KIT 23-28 $\mathbf{~ E 1 4 . 8 2 ~}$ KIT 23-29

KIT 23-30 $\mathbf{2} 2.07$

## ELEKTOR FORMANT SYNTHESISER <br> A ver

who puts performance before price
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COMPONENTS SETS include all necessary resistors. capacitors, semiconductors, potentiometers and transformers. Hardware such as cases, sockets, knobs. keyboards, etc. are not included but most of these may be bought separately. Fuller details of kits, PCBs and parts are shown in our lists.

LAYOUT DIAGRAMS are supplied free with all PCBs unless 'as published'

## P.E. GUITAR EFFECTS PEDAL

Modulates the attack, decay and filter characteristics of a signal from most audio sources, producing 8 different switchable effects that can be further modified by manual controts.

Basic parts with foot switches
Basic parts with foot switches
Basic parts with panel switches
PCB \& layout chart
Text photocopy

## ELEKTOR DICITAL REVERB UNIT

A very advanced unit using sophisticated i.c. techniques instead of mechanical spring lines. The basic delay range of 24 to 90 mS can be extended up to 450 mS using the extension unit. Further delays can be obtained using more extensions

Main unit basic component kit Main unit PCB (as published) $\quad$ PCB 9913 £3.69 $\begin{array}{llr}\text { Extension unit basic component kit } & \text { KIT 78-2 } & \text { £47.69 } \\ \text { Extension unit PCB (as published) } & \text { PCB 78B } & \mathbf{8 1 . 1 6}\end{array}$ text photocopy

## elektor analogue

## REVERB UNIT

Using i.c.s instead of spring-lines the main unit has a maxium delay of up to 100 ms , and the additional set extends this up to 00 mS . May be used in either mono or stereo mode.
Main unit basic component set $\quad$ KIT 83-1 $\quad$ E29.49 $\begin{array}{lll}\text { PCB las publ.) to hold both kits } & \text { KIT 83-2 } & \mathbf{E 2 0 . 0 7} \\ & \text { PCB 9973 } & \mathbf{8 4 . 0}\end{array}$ PCB las publ.) ho hold both kits PCB 9973 24.31

## P.E. GUITAR MULTIPROCESSOR

An extremely versatile sound processing unit capable of producing, for example, flanging, vibrato, reverb, fuzz and tremolo as well as other fascinating sounds. May be used with most electronic instruments
$\begin{array}{lll}\text { Set of basic component kits } & \text { KIT 85-3 } & \text { 843.75 } \\ \text { Set of PCBs \& layout charts } & \text { KIT } & \text { 85-4 } \\ \text { 810.62 }\end{array}$ Set of text pḥotocopies $£ 2.62$

## P.E. PHASER

oscillator.
Set of basic components, incl.,
PCB \& chart
$\begin{array}{rr}\text { KIT } 88-1 \quad \mathbf{8 1 0 . 1 4} \\ & 68 p\end{array}$

## ELEKTOR PHASING \&

## VIBRATO UNIT

Includes manual and automatic control over the rate of phasing \& vibrato, and has been slightly modified to also include a 2 -input mixer stage.

| Set of basic components | KIT 70-1 | £19.11 |
| :--- | :--- | ---: |
| PCB \& layout chart | PCB 70A | E2.58 |

Text photocopy
PCB 70A

## P.E. PHASING UNIT

A simple but effective manually controlled phasing unit.
Set of basic components incl.,
PCB \& chart
KIT 25-1 $\mathbf{~} \mathbf{3 . 8 2}$

## PHASING CONTROL UNIT

For use with Phasing Kit 25 to automatically control rate of phasing.

Set of basic components incl.,
PCB \& chart
KIT 36-1 $\mathbf{~} 8.21$
Text photocopy
10p

## P.E. SWITCHED TONE

## TREBLE BOOST

Provides switched selection of 4 preset tonal responses.
Set of basic components.
$\begin{array}{lll}\text { CB \& chart } & \text { KIT 89-1 } & \mathbf{8 3 . 8 2}\end{array}$

## P.E.TREBLE BOOST UNIT

A simple treble boost unit with manual control of depth Set of basic components.
$\begin{array}{lll}\text { PCB \& chart KIT 53-1 } & \mathbf{2 . 7 6}\end{array}$

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## ELEKTOR RESONANCE FILTER

Allows a synthesiser to produce a more realistic simulation of natural musical instruments.

PCB (as publishponents KIT 82-1 18.61
Cxt photocopy
PCB 9951 \&3.29

## P.E. GUITAR OVERDRIVE

Sophisticated versatile fuzz unit including variable controls affecting the fuzz quality whilst retaining the attack and decay, and also providing filtering. Can be used with other electronic instruments.

| Set of basic components | KIT 56.1 | $\mathbf{8 7 . 5 7}$ |
| :--- | ---: | ---: |
| PCB \& layout chart | PCB $56 A$ | $\mathbf{8 1 . 7 8}$ |
| Text photocopy |  | 880 |

P.E. FUZZ UNTT

A simple fuzz unit. Slightly modified from the original.
Set of basic components,
PCB \& chart
TREMOLO UNIT
A slightly modified version of the simple P.E. unit.
$\begin{array}{llll}\text { Set of basic components. } \\ \text { PCB \& chart } & \\ \text { KIT 54-1 }\end{array}$
GUITAR FREOUENCY DOUBLER
A slightly modified and extended version of the P.E. unit. $\begin{array}{ll}\text { PCB \& chart } & \text { KIT 74-1 } \\ \text { E4.97 }\end{array}$ Text photocopy 39p

## P.E. GUITAR SUSTAIN

Maintains the natural attack whilst extending note duration
Basic components, foot switches, KIT 75-1 e5.e4
PCB \& chart
Basic components, panel switches. KIT 75-2
PCB \& chart
KIT 75-2 E4.08

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Can be controlled manually or by integral automatic control.
Set of basic components, KIT 51-1 $\mathbf{~ E 3 . 9 9}$
PCB \& chart

## P.E. AUTO-WAH UNIT

Auromatically Wah or Swell sounds with each note played.
Basic components. foot
switches, PCB \& chart KIT 58-1 EA.43
Basic components, panel
switches, PCB \& chart
Text photocopy
KIT 5B-2 E5. 31

## ELEKTOR WAVEFORM CONVERTOR

Converts a saw-tooth waveform into sinewave, mark-space sawtooth. regular triangle, or square-wave with variable mark-space ratio. Basic components, PCB \& chart.
but excl. sw's.
KIT 67-1 $\mathrm{f9.24}$

## P.E. VOLTAGE CONTROLLED FILTER

Extracted from P.E. Minisonic project.
Set of basic components.
PCB \& chart
KIT 65-1 $£ 7.88$

## P.E. RING MODULATOR

Extracted from P.E. Minisonic project
$\begin{array}{lll}\text { Set of basic components. } \\ \text { PCB \& chart } & & \\ \text { KIT 59-1 } & \text { E6.05 }\end{array}$

## ELEKTOR RING MODULATOR

Compatible with the Formant \& most other synthesisers Set of basic components KIT 87-1
PCB (as published)
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84.68
$\mathrm{c1.74}$
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PHOTOGRAPHS in this advertisement show two of our units contaning some of the $P$ E. projects buill from our kits and PCBs The cases were built by ourselves and are not for sale. though a small
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 KEYBOARDS AND CONTACTSKIMEER-ALLEN KEYBOARDS as required for many published projects. The manufacturers claim that these are the finest moulded plastic keyboards available All octaves are C to C , the keys are plastic, spring-loaded, fitted with actuators, and mounted on a robust aluminium frame 3 Octave ( 37 notes) . $\mathbf{£ 2 5 . 5 0}$ 4 Octave (49 notes)

CONTACT ASSEMBLIES (gold-clad wire) - 1 required for each KBD note: Type GJ - SPCO $25 \frac{1}{2} p$ ea. Type GA - 1 pr of contacts, normally open 24p ea. Type G8 - 2 pr N/O 2812 p ea. Type GC - 3 pr N/O $37 \frac{1}{2} p$ ea. Type GE-4 pr N/O 4efp ea. Type GH - 5 pr N/O 581p ea. Type 4PS - 3 pr N/O plus SPCO 57p ea.

## P.E. NOISE GENERATOR

Extracted from the P.E. Minisonic.
Set of basic components

## WIND \& RAIN EFFECTS UNIT

A slightly modified version of the original P.E. unit Set of basic components.
PCB \& chart
KIT 28-1

## P.E. ENVELOPE SHAPER

WITHOUT VCA
Provides full manual control over attack, decay, sustain and release functions, and is for use with an existing VCA Set of basic components. Text photocopy

KIT 44-1
e5.24

## P.E. ENVELOPE SHAPER

## WITH VCA

Has an integral Voltage Controlled Amplifier, and has full manual control over the A,D,S,R functions. Set of basic components.
PCB \& chart

## P.E. GENERATOR

An ADSR envelope shaper without VCA, and additional providing Repeat-triggering enabling a synthesiser to be programmed for mandolin or banjo effects.

Set of basic components
PCB \& layout chart
KIT 63-1
PCB 63A

## P.E. EXTERNAL-INPUT

## SYNTHESISER-INTERFACE

Allows external inputs such as guitars, microphones etc, to be processed by synthesiser circuits.

Set of basic components,
P.E. TUNING FORK

Produces 84 switch-selected frequency-accurate tones with an LED monitor clearly displaying beat-note adjustments.

Set of basic components,
PCB \& chart
Power Supply components.
Power Supply
PCB \& chart
Text photocop
P.E. TUNING INDICATOR
a simple 4-octave frequency comparitor for use with synthesisers and other instruments where the full versatility of KIT 46 is not equired.
Set of basic components,
PCB \& chart, but excl. sw
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## P.E. DYNAMIC RANGE LIMITER

Preset to automatically con PCB \& chart

## P.E.CONSTANT DISPLAY

FREQUENCY COUNTER
A 5 -digit counter for 1 Hz to 55 KHz with 1 Hz sampling rate. Meadout does not count visibly or flicker due to blanking. Set of basic components Text phos published)

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## INTEGRATED CIRCUITS

# BD1 Package KitThe Connoisseur's Budget Choice 

Connoisseur now offer their famous BD1 Kit in a package deal.

The package consists of the BD1 Kit, SAU2 pick-up arm, plinth with anti-vibration feet, acrylic cover complete with hinges and friction lid stays, a pick-up mounting board, and all necessary screws, washers, etc. The plinth, cover and pick-up mounting board are all pre-drilled and ready for assembly.
The illustration shows the package with the BD1 Kit partially assembled.


## OPPORTUNITIES ABOUND

WE ARE all, nowadays, electronics conscious. Yes, even the layman, while not conversant with the technicalities involved, has a general appreciation of the vital part played by this young but exuberant branch of electrical engineering in the complex world of today . . . and this is but the beginning.
"As we step over the threshold into a new exciting technological age, our dependence upon electronics is all too apparent: terrestrial developments centre around automation, with electronics providing the brain and guiding hand for power-operated machinery; extraterrestrial exploration relies utterly upon electronics for remote control, communications and telemetering services.
"These grand scale developments have an impact on the entire field of electronics, for in their wake come new components, new circuits, new methods and, of course, new applications."

Some might query the terms "young" and "the beginning" when applied to electronics and these are the only clues to the fact that those words were the
opening paragraphs of the PE editorial in Volume 1 No. 2-back in December 1964 ! Whilst looking back to see how far we have come over the past 15 years what is most apparent is that we are still part of a relatively young and most certainly exuberant industry.

## NO BOUNDS

The introduction of the transistor-just making a significant impact on the hobbyist market back in '64-has led us into an electronics world which knows no bounds and, while progressing at breakneck speed five years ago is now going twice as fast.

That editorial continued in the following way:
'Without a doubt the amateur enthusiast will be eager to reap his share of these benefits of technological progress, as he has been indeed in the past. For it is true that amateurs have been conducting experiments and building electronic equipment since the earliest days of radio communication; even before the thermionic valve drove the crystal diode into (temporary) oblivion, and long before the very term 'electronics' entered into general use.
'But, in more recent times, the technical revolution triggered off by the invention of the crystal triode or transistor some 16 years ago has quite dramatically transformed the situation to the advantage of the home constructor."

The crystal triode! We wonder haw many readers using microprocessors know how a triode works.

## 30 YEARS ON

Only about 30 years from the discovery of transistor action we are able to put about 100,000 semiconductor devices in the area originally required for one.

If that first 16 years progress "dramatically transformed the situation to the advantage of the home constructor" just think what the last 15 years have done. Far from putting us "out of business", as some intimated when i.c.s. became readily available, the hobby has grown in both numbers and complexity and now forms a significant market for the component industry.

We fully expect the next 15 years to be even more rewarding.

Mike Kenward

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We are unable to offer any advice on the use or purchase of commercial equipment or the incorporation or modification of designs published in Practical Electronics.

All letters requiring a reply should be accompanied by a stamped, self addressed envelope and each letter should relate to one published project only.

Components are usually available from advertisers; where we anticipate supply difficulties a source will be suggested.

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# -14 STHTE GAR INSTRUMENTS llo. 2 REV.COUITER ENTS 

 . $+$ Michael Tooley b.А. David Whitfield b.a. м.sc.The second article in a series of car instrument constructionals using the LM3914 (discussed last month), and which produce an l.e.d. bar display

MEASURING the rate at which the engine turns over is something which on first thoughts might not appear to be of much practical interest to the average motorist. In fact it is a very useful facility in both engine tuning and everyday driving situations.

In order to obtain optimum performance, it is necessary to drive at an engine speed which produces the maximum torque for that particular engine (the torque produced by an engine tends to decrease at high and low revs). The average saloon car performs best at approximately 2,000-3,000 r.p.m. and driving at this rate will produce optimum fuel consumption and acceleration for that particular gear. Indeed, one of the reasons for the increasing popularity of the 5speed gearbox is that it allows driving nearer to this optimum rev's while at higher road speeds.

Another point of interest is that the forces exerted on the engine unit vary with the square of the engine rev's, i.e. doubling the r.p.m. increases the forces on, say, the rocker gear by a factor of 4 . Hence, it is important that the maximum r.p.m. rating for a particular engine is not exceeded, irrespective of road speed.

In engine tuning, it is often necessary that certain measurements (e.g. ignition timing advance) are carried out at known engine speeds. Also the "tickover" speed should be adjusted so that the engine does not waste fuel while idling, yet moves off smoothly when required.

## MEASUREMENTOF RPM

Measuring the engine r.p.m. would seem to require some type of transducer which is connected to the engine crankshaft. A little thought, however. soon shows that there is usually one already fitted; the distributor! The distributor shaft in a 4 -stroke engine rotates at exactly half of the engine speed, and is responsible for the opening and closing of the contact breaker points. The contact breaker causes a pulsed signal to be produced across the primary (LT) winding of the ignition coil. The number of pulses produced per minute will be:

$$
\frac{1}{2} \times \text { r.p.m. } \times \text { number of cylinders }
$$

All that is now required is a circuit to count these pulses and turn the result into an analogue signal which is suitable for driving the display module input, i.e. 0 to +5 volts for the required full scale.

Pulse counting by digital methods is one obvious way of determining contact breaker rate. This approach, however, requires a minimum of three to four i.c.s and also involves a stage of digital-to-analogue conversion, see Fig. 1a for details. A simple charge pump alternative (Fig. 1b) has the advantage of simplicity, but suffers the disadvantages of additional sensitivity to both pulse width and amplitude. These problems may be overcome by the incorporation of a monostable prior to the charge pump (Fig. 1c). With a monostable pulse width which is less than the periodic time of the input pulse train, the output of this new arrangement will now only depend on the input pulse frequency. The response time and full-scale values may then be set by a suitable choice of R and $C$, and of the monostable pulse width. A derivative of this approach is used in the integrated frequency-to-voltage converter produced by National Semiconductor and used in the r.p.m. counter to be described below.

## FREQUENCY-TO-VOLTAGE CONVERTER

National Semiconductor's LM2917 is a linear monolithic i.c. which contains a frequency-to-voltage converter, together with a high gain op amp/comparator designed to operate a relay, lamp or other external load, up to 50 mA . The tachometer section uses a charge pump technique and offers frequency doubling for low ripple, input protection, and an output which falls to ground level for a zero frequency input.

One of the main aims in the design of the LM2917 was ease of use. A single RC network provides the frequency doubling (see Fig. 2), and the output is simply related to the input frequency by the following formula:

$$
\text { Vout }=\text { Fin } \times \text { Vref } \times \mathrm{Ra} \times \mathrm{Ca}
$$

The integral voltage regulator sets the value of Vref and ensures accurate, stable conversion performance.

The input stage is a differential amplifier driving a positive feedback flip-flop circuit. This arrangement allows the user to define the input switching level, while retaining the hysteresis around that level to ensure good noise rejection. Following the input stage there is a charge pump where the input frequency is converted to a d.c. voltage. This operation requires a timing capacitor (Ca), an output load resistor (Ra), and an integrating filter capacitor (Cb). The capacitor Cb determines the trade-off between output ripple voltage and response time of the circuit.


E0190
Fig. 1 (a) Measurement of r.p.m. (b) Basic diode pump (c) Frequency controlled diode pump

[60189]
Fig. 2. The LM2917 frequency-to-voltage converter


[^1]Fig. 3. Full circuit diagram of the Rev. Counter.


Fig. 4. Printed circuit layout (actual size)


Fig. 5. (above). Component layout of p.c.b. for Rev. Counter

Fig. 6. (left). Alternative stripboard layout. Note that R9 goes to collector TR 1 which will not affect operation

Fig. 7. (below). Method of calibration


This, for example, gives 200 Hz for a 4 -cylinder engine at 6,000 r.p.m. A direct method of calibration is then to use a pulse generator to apply a 200 Hz square wave (greater than three volts amplitude) to the input, and then adjust VR1 to give 5.0 V across R6. Should a pulse generator be unavailable, a suitable mains (filament-type) transformer may be used to generate a 50 Hz signal, and VR 1 is then adjusted to give an appropriate proportion of 5.0 V across R6, e.g. 1.25 V (i.e. fifty 200ths of 5.0 V ) in the case of a 6,000 r.p.m. 4-cylinder tachometer. See Fig. 7 for details.

## INSTALLATION AND USE

Connecting the tachometer to the engine ignition system is a very simple operation. Fig. 8 shows how the supply (A) and measurement input (B) leads are connected across the ignition coil; the OV connection being made to any convenient point on the vehicle chassis. In cases where the instrument is to be used as a piece of test equipment, switched values of load resistance may be provided for different ranges/numbers of cylinders, and connections brought out on flying leads with crocodile clips.

The tachometer has been successfully tried on a variety of British and foreign vehicles. Constructors should, however, be aware that for vehicles already fitted with a current pulse type of tachometer (e.g. Smiths type RVC), the readings obtained may tend to be rather misleading.

NEXT MONTH: Battery Current Indicator, Temperature Gauge, Dwell Indicator. All three car instruments form a special supplement with details on extending the displays and on providing extra warnings of high level readings



## FULL FRONTAL

These BIMDICATORS were designed to satisfy applications requiring indicators with a restricted viewing angle, long operating life, and good aesthetic qualities.

Both devices utilise red, green or amber l.e.d.s which are set back from the front of the indicator and have low current, low voltage characteristics, fast switching times, and are fully i.c. compatible.


The BIM 33 l.e.d. (left) has a nickel plated brass body and is panel mounted in a 6 mm dia. hole. The BIM 34 l.e.d. has a chromium plated brass body and is panel mounted in an 8 mm dia. hole.

Prices inc. VAT and p\&p, for either size are: Red-71p, Green or Yellow-81p.

BOSS Industrial Mouldings Ltd., Higgs Ind. Est., 2 Herne Hill Road, London SE24 0AU (01-737 2383).

## FIRST CLASS CATALOGUE

The Toolrange catalogue is excellently designed and printed. Over a hundred pages, most of them in colour, show a comprehensive range of tools which the serious constructor would be interested in knowing about. No need to send an SAE.

Toolrange supply tools and production aids for the electrical and electronic industries and their address is Toolrange Ltd., Upton Road, Reading, Berks., RG3 4JA (0734 22245).

## CSC

A new 32 page catalogue from Continental Specialties Corporation features the company's ranges of breadboarding equipment, logic testing devices, and test instrumentation. Products featured include a wide range of solderless breadboards and breadboard assemblies, test clips, instrument cases, pulse and function generators, frequency counters and accessories, logic probes, logic monitors, the CSC digital pulser, test kits and probe kits.

The catalogue is available from Continental Specialties Corporation, Shire Hill Industrial Estate, Saffron Walden, Essex CBII 3AQ


## AEROSOLS FOR ELECTRONICS

Switch cleaning aerosols by Servisol are now available from Toolrange. Other aerosols in the range are anti-static cleaners, water proofing sprays, insulating varnish sprays and chemical circuit freezers. Prices average out at 70 p per can.

Toolrange Ltd., Upton Road, Reading, Berks., RG3 4JA (0734 22245).

## MICRO-KIT CONSTRUCTION

If you would like a microprocessor system but are daunted by the assembly then Logsign may be of interest.

Logsign will obtain and build a kit: construct a kit supplied by a customer; even undertake to finish a kit which has proved problematical.

Charges start at around 10 per cent of system value for the most popular kits such as Nascom, Compukit, Newbear 77/68 etc., rising to around 25 per cent for large systems like Horizon.

Logsign Microcomputer Engineers, P.O. Box 33, Truro, Cornwall, TR3 6BZ. (0872 76205).

## LIGHT BARS

For those of you who are intending to construct the "car devices" currently being published by us, this new range of modular l.e.d.s should be of interest.


The HLMP 2300, 2400 and 2500 series of 9 to 19 mm rectangular devices can be multiplexed and are X-Y stackable. Composed of two or four in-line l.e.d.s with the light from each l.e.d. optically scattered to form an evenly illuminated light emitting surface, these devices may be strobed at high peak currents or driven from d.c. supplies. Available in red, yellow and green the HLMP 2300, 2400, and 2500 are priced from 97p exc. VAT and p\&p.

For further information contact Hewlett Packard Lid., Kings Street Lane, Winnersh, Wokingham, Berkshire RG115AR.

## HIGH SPEED DRILL

A new high speed drilling machine which is ideal for use in p.c.b. prototype workshops had just been announced by Linton Laboratories. The Junior Drillmaster which is mains operated has a motor speed of 14000 r.p.m. with a drill capacity of 206 mm dia.


The drill, which is supplied with a guard and four separate collets ( 0.5 to 3.2 mm ), is priced at $£ 65$ inc. p\&p, plus VAT.

Linton Laboratories Limited, 4 Bartlow Road, Linton, Cambridge, CBI 6LY.


## JVC STEREO RECEIVER

The photograph shows JVC's R-S7, an AM/FM receiver which delivers 50 W per channel r.m.s. with both channels driven into 8 ohms, from 20 Hz to 20 kHz . The THD is no more than 0.03 per cent and a phono equaliser ensures a signal to noise ratio of 90 dB .

The R-S7 has a protection circuit which prevents power on/off noise from reaching the speakers, disconnects the speakers electronically if an abnormal d.c. voltage appears at the terminals and protects the power transistors from short circuits, low speaker impedances, etc. Retail price is around $£ 203$ (inc. VAT).

## AM/FM/CB RECEIVER

A Hong Kong manufactured receiver labelled Bristal has been under appraisal at the office recently. It is said to comply, as of date of manufacture, with FCC rules and regulations part 15 subpart $C$.

As well as receiving legal transmissions from the British Broadcasting Corporation it is rumoured that if you switch the Bristal to CB you might hear French, Spanish and Italian CBers as clear as next door, probably a combination of skip and spaghetti burners.

The set measures $185 \times 90 \times 50 \mathrm{~mm}$, has a telescopic aerial one metre long, and has been seen for sale at $£ 18.95$ plus VAT.

## 10MHzScope

The 3106 C oscilloscope is a general purpose single trace instrument which has been designed for college labs, service shop repair and production line testing.


The instrument features a 5 in flat c.r.t., d.c. to 10 MHz bandwidth, vertical amplifier with a sensitivity of 10 mV to $50 \mathrm{~V} / \mathrm{cm}$ in 12 calibrated steps, $0.5 \mu \mathrm{~s}$ to $0.01 \mathrm{sec} / \mathrm{cm}$ sweep range and a times five magnifier. The price of the 3106 C is $£ 159.95$ including VAT, carriage is $£ 2.50$.

Kramer \& Co., 9 October Place, Holders Hill Road, London NW4 IEJ (01-203 2473).

## 3rd HAND

The 3rd Hand is a rather aptly named p.c.b. holder which can be clamped on the edge of a bench, table or worktop. The p.c.b. is held in position by an open ended clamp which allows any size of board to be held. When in

position the board can be flipped over to allow access for soldering and clipping.

The cost is $£ 8.95$ including VAT and p\&p.
Para Sales, 1 Hook Road, Kingsclere, Newbury, Berks. RG15 8PD.

## P.C.B.s ACCEPTED

This diecast aluminium box incorporates slots on all four sides for quick housing and removal of 1.8 mm thick p.c.b.s. Dimensions of the box are $121 \times 95 \times 61 \mathrm{~mm}$. Grey hammertone is a shortly to be introduced optional finish.


BOSS Industrial Mouldings make a range of this type of box called BIMBOXES. This size is $£ 3.45$ inc. p\&p and VAT.

BOSS Industrial Mouldings Ltd., Higgs Ind. Est., 2 Herne Hill Road, London SE24 OAU (01-737 2383).

## CRYSTALS MADETO ORDER

Golledge Electronics stock a very good range of crystals for microprocessors, markers, clocks, marine VHF, radio control, etc. They can supply crystals made to order, normal delivery six weeks.

Golledge are also designers of a range of "building block" modules which require only simple external connections and can be made to work well by anyone with little or no experience of radio construction.

Leaflets on the crystals and the modules are available from Golledge Electronics, G3EDW, Merriott, Somerset TA 16 5NS (0460 73718).


This is Ingersoll's latest clock radio waker upper. It has a 12 hour l.e.d. display and will wake you with the three band radio or a nine minute repeating buzzer. For the listener who falls off to sleep it has a 60 minute shut off timer. It is mains operated, has a power failure indicator, and is finished in either teak or satin silver. The price is $£ 30.65$ inc. VAT.


B$A B Y C O M$ is a two unit monitoring system for the nursery. It consists of a control unit with a microphone, which should be placed near the cot and an alarm unit which can be placed anywhere else in the house. The two units are joined together via a 3 core flex.

The alarm is triggered by sound, the microphone picks up the baby's cries and the control unit of the system which contains a 5 -bit shift register records the noise as a " 1 ". After 10 secs the contents of each register (A, B, C, D and $E$ ) are shifted along ( $A$ to $B, B$ to $C$ etc.) with any new noises being entered into register $A$ whilst the information in register $E$ is erased.

For the alarm to sound the baby must trigger it twice (two registers at 1) within a 50 sec. period. When triggered the alarm will sound for one period and then stop unless the baby makes any further noises in which case it will continue to sound until the baby settles down and one or less of the registers is at " 1 ". When the alarm sounds you can listen in to the baby by pressing the switch S 3 on the alarm unit.

## CONTROLUNIT

The circuit diagram of the power supply and the control unit is shown in Fig. 1. The circuit is powered via transformer T1, rectifier diodes D1 and D2, smoothing capacitors C1 and C2 and a regulator circuit formed by TR1, R1 and Zener diode D3.

Any noise picked up by the microphone via JK1 is amplified by IC1 and then fed to the detector circuit of which TR2 and TR3 form a high gain amplifier. If the output of IC1 is above a certain level (when a loud enough sound is detected) the collector of TR3 is switched "high". The output level of IC1 at which this will occur is determined by the setting of VR 1 , the sensitivity control.

The two timers of IC2 are connected as two astable multivibrators. One timer runs at approximately 1 Hz , with 2:1 mark-space ratio and the other runs at approximately 0.1 Hz , its output waveform being "high" with very short clocking "lows" every 10 secs. The frequencies are nominal and the clocks can be set accurately enough by suitable choice of timing capacitors and resistors; there is no need for variable preset timing resistors. The logic circuit comprises the 74965 -bit shift register and the 7425 dual 4 -input NOR gate with a strobe input. The output from the detector circuit (collector TR3) is fed to the preset input of register

A (IC3 pin 2). The common preset input (pin 8) is held high by Vcc so that the output of register A (pin 15) goes "high" immediately register A receives a "high" input. Preset inputs of the other registers (pins 3, 4, 6 and 7) are grounded, so that these registers have a "low" output at switch-on.

If any noise is detected during a 10 sec . period the output of register A goes "high" and remains high until the end of that period. Then the clock pulse steps the data through the registers.

The NOR function of IC4 operates only if the strobe input (pin 3) is "high". If the input is "low" the gate output is "low" whatever the state of its four inputs. The first NOR gate receives its strobe input from register $A$ and its four inputs from registers $B$ to $E$. If register $A$ is low (no noise during the 10 sec. period), the gate output is low, irrespective of the other registers. But if register A goes "high" what happens next depends on the state of the other registers. If these are all "low" (no noise during previous four periods), the output remains "low" (no alarm). If any one or more of these are "high", the gate output goes "high", switching on TR4. At the end of the period TR4 is switched off as the output of register $A$ goes low, unless of course baby makes further noises.

The second NOR gate of IC4 has its strobe input (pin 11) permanently wired to Vcc and is wired to function as an


The control unit

[66 155]
Fig. 1. Circuit diagram of the power supply and the control unit
ordinary 2 -input NOR gate. This receives inputs from the first NOR gate ("high" = alarm) and from the 1 Hz clock. In the "no alarm" state the output of this gate is continuously "low". In the alarm condition, the output of this gate is the inverse of the clock output. The output is used to turn TR4 on and off regularly.

## ALARM UNIT

The alarm unit (Fig. 2) incorporates an oscillator and amplifier to produce the audio alarm tone. The frequency at which the oscillator operates can be varied by changing the value of C14. As TR4 is turned on the red lead of the alarm unit is connected to OV switching on lamp LP2, the oscillator and therefore the alarm. Switching TR4 on and off via the second NOR gate of IC4 causes the lamp to flash and the alarm to bleep.


EO183]
Fig. 2. Circuit diagram of the alarm unit

## FAILSAFE

The unit incorporates a number of features to ensure that "no alarm" really does mean "no noise" and is not the result of a failure in the system.

1) There is no volume on the alarm unit, so this cannot be turned down and then forgotten. Similarly, the lamp cannot be switched off.
2) In the "no alarm" condition a small current flows through R16, bypassing TR4. This current is insufficient to activate the AF oscillator but does cause LP2 to glow. If the unit is operating correctly the lamp should be either flashing brightly or glowing dimly.
3) One side of the microphone jack socket (JK1b) is used as switch 1 which is wired in series with R15 to TR3 so as to connect the base of TR3 to ground when the microphone jack is not in its socket. Thus if the microphone has not been plugged in, or its plug partly pulled out of the socket, TR3 is turned off, its collector potential goes "high" and a "high" will appear at register A triggering the alarm.

## CONSTRUCTION

In the prototype, the control unit of the Babycom was housed in a $175 \times 95 \times 70 \mathrm{~mm}$ case. The front panel should be drilled and the panel components mounted into position. The Veroboard layout shown in Fig. 3 should be soldered next and then carefully checked to ensure there are no solder bridges or incomplete track breaks to short out the board. After the board has been checked it can be fitted as close to the back and one side of the case as possible using 6BA screws and spacers. Note that only one Veroboard is needed instead of the two used in the prototype

Transformer T1, the smoothing capacitor C1 and the "L" shaped heat-sink for TR1 should be fitted alongside the Veroboard with the transformer at the back of the case. The rest of the power supply circuit should then be mounted on a piece of tagboard (Fig. 4) and fitted to the clip holding



50186
Fig. 4. Tagboard layout of the p.s.u.


Internal view of the control unit
capacitor C1. Care should be taken that the upper end of the tag strip does not touch against the top cover of the case.

After all the components have been fitted into the case the wiring between the components should be carried out. R16 is mounted between the terminals of S2 and a short length of co-ax cable should be used to link JK1 to the

## COMPONENTS . . .

| Resistors |  |
| :--- | :--- |
| R1 | 2 k 7 |
| R2 | 100 k |
| R3 | 180 |
| R4 | $27 \frac{1}{2} \mathrm{~W}$ |
| R5, R6, R7, R9, R20 | $1 \mathrm{k}(5$ off $)$ |
| R8 | 10 k |
| R10, R11 | $2 \mathrm{M} 2(2$ off $)$ |
| R12 | 470 k |
| R13 | $1 \mathrm{k5}$ |
| R14 | 560 |
| R15 | 2 k 2 |
| R16, R19 | $82(2$ off) |
| R17 | 15 k |
| R18 | 330 |
| R21 | 1 k 8 |

All resistors $\frac{1}{4}$ W 5\% unless otherwise stated

## Potentiometers <br> VR1 1 k linear

| Capacitors |  |
| :--- | :--- |
| C1 | $2200 \mu 16 \mathrm{~V}$ elect. |
| C2, CB | $1000 \mu 10 \mathrm{~V}$ elect. (2 off) |
| C3, C4, C15 | $100 \mu 10 \mathrm{~V}$ elect. (3 off) |
| C5 | 220 n polyester |
| C6 | $47 \mu 10 \mathrm{~V}$ elect. |
| C7 | $470 p$ ceramic |


| C9. C14 | 100n polvester (2 off) |
| :--- | :--- |
| C10 | 10 n ceramic disc |
| C11 | 470 n polyester |
| C12 | 10n ceramic disc |
| C13 | $47 \mu 16 \mathrm{~V}$ tant |

Semiconductors

| D1, D2 | 1N4004 (2 off) |
| :--- | :--- |
| D3 | BZY 886 V 2 |
| TR1 | BD131 |
| TR2, TR3 | 2N2926 (2 off) |
| TR4 | 2XT 300 |
| TR5 | 2N2646 |
| TR6 | 2N3704 |
| IC1 | TBA 820 |
| IC2 | NE 556 |
| IC3 | 7496 |
| IC4 | 7425 |

## Miscellaneous

| T1 | 9-0-9V secondary 100mA mains transformer |
| :--- | :--- |
| S1 | Push button, push to make push to break |
| S2 | Push button, push to make |
| S3 | S.p.s.t. biased |
| LP1 | 240 V neon |
| LP2 | 6 V 60 mA MES filament lamp |
| LS1 | Miniature speaker $8 \Omega$ |
| JK1 | Min jack socket |
| JK2 | Stereo jack socket |
| MIC1 | High impedance crystal microphone |



Fig. 5. Veroboard layout of the alarm unit
amplifier on the Veroboard layout.
The prototype alarm unit of the Babycom was housed in a $130 \times 100 \times 50 \mathrm{~mm}$ case. The Veroboard layout of the alarm circuit is shown in Fig. 5. After the board has been


## The complete Babycom system

soldered and checked it should be fitted into the case with the loudspeaker, indicator lamp and switch S3 fitted into the front panel. The alarm unit is joined to the control unit via 3 core cable and PL1.


## INTELLIGENCE PRINTS BACKWARDS

SOMETHING of a price breakthrough is the Trendcom 100 Intelligent Printer from Personal Computers Ltd. A high performance serial printer capable of 40 char's $/ \mathrm{sec}$, the Trendcom 100 has a 96 character set and is controlled by its own internal microprocessor.

To speed things up, each line of characters is stored ready to be printed, and when summoned, may be printed from left-to-right or right-to-left, so that in effect the print head is quietly zig-zagging its way down the paper (known as bidirectional look-ahead printing).

Print-out is aesthetically pleasing ( 10 char's/inch) based on a $5 \times 7$ dot matrix onto low cost thermal paper. High reliability is inherent with only two d.c. stepping motors to control the print head and paper roller, and everything is powered from its own mains supply.

Interfacing to most microcomputers should be easy with TTL compatible inputs, and interface cards are available for PET, Apple II, TRS80 and RS232 ports. Signals available from Trendcom 100 are $\overline{\text { STROBE }}$ and BUSY. A Test input activates a self test message.

You may have seen printers with this kind of specification before, but here is the difference: Trendcom 100 costs $£ 241$.

Personal Computers Ltd., 194-200 Bishopsgate, London, EC2M 4NR.


## ONE-CHIP COLOUR TV SYSTEM

Motorola Semiconductors announce a European designed, multistandard TV colour system, the TDA 3300 , Chroma III, one-chip colour system.

This third generation system accepts a colour TV signal in the form of composite video and gives an output ready for application to the c.r.t. cathode, via a simple output stage.

Included on-chip are a number of features which, Motorola believes, will make the TDA 3300 one of the most sophisticated integrated TV systems yet available. Key features of the system are:

User Controls-The device includes a full range of user controls, saturation, contrast and brilliance, which have been designed with a high input impedance, in the order of $1 \mathrm{M} \Omega$, and an operating range of 0 to 5 V . This makes them compatible with Motorola and other Remote Control systems via a simple RC network.

Beam Limiting-An on-chip beam limiter automatically adjusts the output drive to prevent blooming of the picture detail highlights.

Reference Generation-For simplicity the system uses the easily obtainable 4.43 MHz crystal for the reference frequency generation. Further, the $90^{\circ}$ phase shift is accomplished on-chip by an unique self correcting circuit which will keep phase errors down to a minimum.

Automatic Black Level Setup-By sampling the c.r.t. cathode current the system is able to adjust dynamically the tube black level throughout its life, thus eliminating three complex adjustments during the set manufacture.

Full Multi-standard Capability is available as PAL and NTSC, the latter being aimed at the video recorder user. However, this is extended to SECAM with the soon to be announced TDA 3030 SECAM decoder.

On-Screen-Display-In order to take full advantage of the range of facilities available to the current and coming generation of TV sets, Teletext, games, camera, etc., the TDA 3300 includes on-chip, RGB on-screen-display inputs and the associated fast blanking inputs.

In spite of all these facilities the TDA 3300 requires a single 12 V power supply and has low current drain of 50 mA .

## Polints arising

AUTORANGING MULTIMETER
(April-May 1979)
The diodes D2 and D3 (BAV 47) may be replaced by BAV
45 s which are avallable from Ace Mallironix. Lud, Tootal
Street, Wakefied, West Yorkshire.
CONSTANTDISPLAY FREGUENCY METER
(August 1978)
A link should be made between the centre pin of IC17 and
C4-ve.


## CONCLUSION OF SERIES

$\mathrm{A}^{\mathrm{s}}$S INDICATED in the previous articles, the Compukit is hardware expandable in many ways. Expansions to the machine are in the process of being produced and include a Colour Graphics Board, and a large memory board which will bring the machine nearer to its maximum addressing ability in RAM and EPROM/ROM. By the time this article appears, these boards should be available.

Software expansions include a sophisticated Machine Code Monitor, disassembler and assembler which is included with the machine. Many programs, including games, already exist and it is hoped that others will become available in the near future from those software houses which have shown interest in the machine.

The hobbyist who wishes to expand the hardware of the machine himself may be interested in two useful and important methods of doing so. These are described below. Firstly, it is essential to bear in mind a picture of the machine's memory map:

When expanding the system or adding I/O ports, certain addresses are used for specific functions and must not be overlapped. It is also important to allow for future expansions by keeping clear of memory space which may eventually house extra RAM. In general, later expansion boards will add memory consecutively with the 8 K of on-board RAM, so that the BASIC interpreter will find it during the usual memory test when $C$ is pressed after Reset.

To decide on suitable addresses, the Address Map shown in Table 4.1 should be consulted. The addresses given are in hexadecimal notation and, as can be seen, BASIC workspace can be as large as 40,191 bytes ( 0300 to 9FFF) before overlapping with the BASIC ROMs. There is plenty of space

Table 4.1. Memory map.

Address
0130
01 CO
0000-02FF
0300
1 FFF
AOOO-BFFF
D000-D3FF
DFOO
F000, F001
F800-FFFF

Function
NMI vector
IRQ vector
Scratchpad RAM for operating system Start of BASIC workspace
End of on-board RAM ( 8 K ) BASIC interpreter
Video RAM
Polled keyboard
ACIA serial port
MONITOR ROM
from C000 to CFFF (4096 bytes), and from D400 up to F7FF, apart from the keyboard and ACIA. It is in this last portion that parallel or serial I/O ports can be neatly added with less danger of interfering with later additions

In order to expand the Compukit, therefore, a certain amount of address decoding is necessary to locate any peripherals at the right place in the machine's memory. There are two main ways in which this may be achieved. The top 1 K of the 8 K of RAM (ICs 38 and 52) may be left unused and its address decoded output (RS7) supplied to the expansion as an ENABLE signal. A more general method is to add an expansion board to the system containing its own address decoding. Both of these are described.

## PARALLELI/O PORTS

Suppose we wish to add $16 \mathrm{I} / \mathrm{O}$ ports to the machine in the most straightforward manner possible for some control purpose. A 6820 or 6821 (with greater drive) is most suitable for the job. This chip is the famous PIA or Peripheral Interface Adapter containing a number of $1 / O$ drivers and latches as well as several control lines.

A couple of d.i.l. plugs will allow the circuit in Fig. 4.1 to be connected to the Compukit with minimum effort to control almost anything. The circuit shown includes some lights and switches-just imagine the l.e.d.s to be relays and the switches to be sensors of some kind.
To use Fig. 4.1 and appreciate the circuit's full potential, the data sheet for the device must be obtained and studied. This is a very useful chip and each of its sixteen I/O lines (PBO-PB7 and PAO-PA7) may act as either input or output. There are four external control lines for various purposes (CB1, CB2, CA1, CA2), and interrupts, via IRQ, may be generated by external devices. In order to use the chip, which looks life four memory locations (here decoded as 1 COO, 1, 2, 3) internal registers must be set to a pattern of bits which informs the device of those lines which are to be inputs, and which are outputs. Data to be written to outputs is sent to the appropriate location within the PIA which subsequently clocks it through to the output latches. Similarly, incoming information is stored in a register and may be retrieved by reading the correct memory location in the PIA at the program's convenience. The Interrupt structure may be used to force the MPU to "look" at the PIA when an external device sends its information through.


Fig. 4.1. Switches and lamps interface
An interesting feature of such a device is that the time taken to change an input line to an output is similar to the instruction speed of the MPU system driving it. This allows the possibility of swopping between input and output very fast to make any given line (or lines) appear to the operator as if it is performing both functions simultaneously. Handshaking between microcomputers can be arranged in this way, and parallel processing by a set of machines may be envisaged.

The interface in Fig. 4.1 may, of course, be adapted to run many other devices including UARTs, USARTs or just tristate buffers and TTL latches. In fact, by using the lower ten address lines from IC38 and IC52, any 1 K (or less) memory mapped device may be attached to the Compukit. So far, the author has successfully driven the PE VDU and the coming EPROM Programmer. The advantages of using BASIC to control these devices are enormous. Tasks which appear most daunting when a machine code microcomputer is used, become almost trivial in the high level language.

Several extra terminals may be added to the basic machine in this way, adding considerably to the system's viability in small business applications.

However, the above expansion method, though quick and easy to implement, does tie up 1 K of on-board RAM for each expansion used, and as such may be regarded as


E6 180
Fig. 4.2. Expansion connector
wasteful in the long run. This should lead the user to attach his peripherals to the machine via the 40-pin d.i.l. socket J1. The specifications for this socket are given in Fig. 4.2. All bus lines are brought out to the socket, and they allow external memory mapped devices to communicate with the MPU directly. The BD lines are buffered data lines, with direction controlled by the DD signal which selects Read or Write through ICs 6 and 7 as shown in Fig. 4.2.

All sixteen address lines are present, as is R/W, IRQ, NMI and $\emptyset 2$. For correct memory timing this last signal should be fed to an active high enable line from all external devices. There is also one spare line not connected to anything, but brought out to a pad next to the socket. The rest of the pins are Ground connections.

To use this socket, each external device must generate its own address decoding, the details of which depend upon the amount of memory each expansion takes up. Any such device should occupy a unique address position and hence each address line must be involved in its "fetching".

For devices taking up 8 bytes of memory, for instance, Fig. 4.3 gives a straightforward method of decoding. Here, the 8 bytes are arranged to lie at F400 to F407.

This particular circuit is, of course, purely a functional suggestion to highlight the fact that NAND gates decode 1 's and NOR gates decode O's, and that all address lines play some part in decoding the base address of F400.

Thus, small memory requirements are easily catered for using the simplest logic devices. It is usually a good idea to use CMOS or LS i.c.s to reduce bus loading.


56185
Fig. 4.3. Address decoder for 8 bytes
For large memory requirements, the $n$ to $2^{n}$ line decoders such as 74LS138,9 and 74154 are extremely useful. A 24 K memory board, for instance, will need its own internal pageselect logic to enable different banks of memory i.c.s, just as the Compukit itself does, via some of the above decoders.

For general hardware control purposes, the Compukit may be operated in either BASIC or machine code. The latter can be considerably faster as it deals fundamentally with electrical steps. From BASIC, an 1/O port can be controlled by the WAIT statement or using PEEK and POKE. This has the advantage of extreme ease of programming. Imagine controlling a home-security system. The program could continually PEEK a number of I/O ports (PIA perhaps) connected to remote sensors. When a change occurs, an IF statement would decide whether to act, and a few subroutines would decide which action to take. Some other sensors could be PEEKed nearby and, in a short time, an alarm could be sounded or a stream of appropriate invective produced via a speech synthesis unit!

Extremely complex programs with feedback and analysis could be constructed using the powerful BASIC involved, which, though not as fast as machine code, would act many orders faster than any human activity involved.

The speed problem becomes important, for example, in controlling high speed machines or processes. Then, a hybrid program using the USR function could swop back and forth between BASIC and machine code for instant response to requirements.

As the IRQ and NMI interrupts are fully available to the user, an even more sophisticated system is possible whereby the external process takes control of the computer, when needed, via an interrupt.

The potential is exciting and to some extent already being exploited. Anyone interested could do worse than construct an "I.e.d. and Switch" I/O expansion as in Fig. 4.1 and learn to use it! The next step would be to add a $D / A$ or $A / D$ converter and learn to control and receive analogue data in real time.

## SPECIALKEYBOARD FUNCTIONS

Referring to the keyboard matrix circuit diagram and hardware description, it has already been stated that the keyboard is polled in software for key closures except during program execution (unless waiting for an INPUT).
There are two important routines associated with the polling sequence. One determines which key has been pressed, and the other is a routine for detecting CONTROL C. The latter is not in general disabled during program execution, and may be used to BREAK a program for examining variables, etc. The routine involved may, however, be disabled or enabled by the user via the following statements:

## POKE 530,1 disables POKE 530,0 enables

The first of these may be placed before a part of the program whose execution it is important not to be able to interrupt. If the second statement is placed at the end of the protected region, then CONTROL C will never intrude on that region if pressed.


| Table 4.2. <br> COLUMN <br> C0 |  |  |
| :---: | :---: | :---: |
| ROW | RO | CA/RA |
| C1 | R1 | 254 |
| C2 | R2 | 253 |
| C3 | R3 | 251 |
| C4 | R4 | 247 |
| C5 | R5 | 239 |
| C6 | R6 | 223 |
| C7 | R7 | 191 |
|  |  | 127 |

The keyboard matrix may be used in special applications during the execution of a program, by treating it as an ordinary read/write memory location (57088 decimal or DFOO hexadecimal). To do this, it is often important to disable the CONTROL C routine to prevent it from interfering.

An example of the keyboard's use for special functions could be to allow the keys to be reprogrammed to return graphics characters. A program would be written to allow, say, all the "block" characters to be called from a section of the keyboard when SHIFT LOCK is up.

To perform any special programming of the keyboard, the following statements are used:

```
POKE 57088, RA
IF PEEK(57088) = CA THEN (statement)
```

RA is the address of the row being tested for key-closures according to Table 4.2. This POKE statement may be thought of as "setting" the appropriate row to the "on" condition. CA, column address, is the value which location 57088 takes on when a key in the row RA is pressed. Thus if 57088 is POKEd to have value 254, and 57088 is then read (via PEEK) and found to have value 254 then the program knows that SHIFT LOCK is down (see the keyboard matrix diagram).


Fig. 4.4. (left) Asynchronous I/O and RS232. (right) Serial data buffers

The following program changes the keys 1 to 7 to graphic characters when SHIFT LOCK is up. When down, the words SHIFT LOCK roll up the screen until SHIFT LOCK is pressed. Then the keys 1 to 7 are active and each gives a different character until 7 is pressed when the program terminates.

```
10 POKE 530,1
20 POKE 57088,254
30 IF PEEK(57088) = 254 THEN PRINT ''SHIFT-
LOCK DOWN': GOTO 20
40 POKE 57088,127
50 IF PEEK(57088) = 255 THEN 40
60 PRINT CHR$( PEEK(57088) );
70 IF PEEK(57088) = 253 THEN END
80 GOTO 10
```

The program, though rather simple, is meant to illustrate how information can be gathered from the keyboard and used to control execution. Note that in line 50 the keyboard location is assumed to have value 255 unless a key is pressed, as R1-R8 pull up the inputs to IC4 and IC5 and force them to "see" 1 's until an active key is pressed.

The applications of the above are manifold, not least in the execution of games or simulation exercises; two areas which in many ways are very similar!

In order to use this keyboard polling easily, it is a good idea to label the keyboard matrix diagram, published in Part 1 , with the CA and RA addresses corresponding to the
columns and rows. For instance, CO and RO should be labelled 254, C1 and R1 253, etc.

This concludes the description of the Compukit UK 101. By the time this article appears, many readers will have had the opportunity of operating the basic machine. The applications are enormous and stretch across the full gamut of endeavour. It is hoped that through the pages of Practical Electronics, future developments can be described as they occur and thus keep readers up to date with a machine considered to be ahead of its time.
It only remains for us to wish you all good luck with the project.


## MOREI

Next month we will publish Part 1 of an EPROM programmer designed to plug into Compukit-it will also function with other computers. We also expect to be able to publish another exciting computer peripheral in the near future-we do not believe this has previous/y been published as a hobby design-more details in future issues.

## Honnidnun

Satellite Communications (conference)-Oct. 30, 31, London Press Centre. Will "tele conferencing" replace business travel? Who will finance this expanding technology, and how should outer space be shared between the nations? Details Online Conferences Lid. $b$ Uxbridge (0895) 39262.
Personal Computer World Show--Nov. 1-3, West Centre Hotel, London.
Compec-Nov. 6-8. Grand Hall, Olympia, London. Details: Iliffe Promotions Ltd. © 01-261 8437/8.
Professional Viewdata Exhibition '79—Nov. 7 \& 8. West Centre Hotel, London.
Technical Innovation In The Service Of The Elderly and Disabled-Markets And Needs (symposium)-Nov. 19-21. Berlin. Details: H. S. Wolff, Clinical Research Centre, Watford Road, Harrow, Middlesex.
Integrated Telecommunications For The 80s--Nov. 20, 21. Carlton Tower, London. Details: Online.
Electronics 79-Nov. 20-23. Olympia, London. $\zeta 0217056707$.
Video Rights 79 (conference)-Nov. 26, 27. Cafe Royal, London. Details: Nord Media 『 01-629 9381.
Breadboard 79-Dec 4-8. Royal Horticultural Halls, Westminster. Details: Trident International Exhibitions. $/ 008224671$.
IBM Hardware Selection-Dec. 5, 6. Skyline Hotel, London Airport. Details: Online.
IEA/Electrex-Feb. $25-29,1980$. National Exhibition Centre, Bir mingham. Details: Industrial and Trade Fairs Ltd. 6 021-7056707.
Viewdata '80-March 26-28. Wembley Conference Centre, London. Conference and exhibition. Details: Online Conferences Ltd. $\wp$ Uxbridge (0895) 39262.

Computer-Aided Design (conference and exhibition)-March 31-April 2, 1980. Metropole, Brighton. Details: Organisers, CAD 80.0483 31261.

Communications '80-April 14-18. National Exhibition Centre, Birmingham. Details: ITF Exhibitions. / 021-7056707.
Electronic Test and Measuring Instrumentation-April 22-24, 1980. Wythenshaw Forum, Manchester. Details: Trident.
International Conference On The Electronic Office-April 22-25, 1980. London Penta Hotel. Organised principally by the Institute of Electronic and Radio Engineers. 99 Gower St., London WC1E 6AZ.
All-Electronics Show (1980)-April 29-May 1, Grosvenor House, London. 6 0799-22612.
The Mersey Micro Show-April 30. May 1, 2, 1980. Adelphi Hotel, Liverpool. Exhibition and seminars, with the co-operation of Liverpool University. Details: Online.
The 1980 Microcomputer Show-July 10-12. Royal Lancaster Hotel, London. Details: Online.
IBC 80-Sept. 20-24. Metropole Centre, Brighton. Details: Secretariat, IEE. Savoy Place, London WC 2R OBL.

## WE NEED YOU

A. vácancy lias arisen for a production editor, en Pé If: you have some knowledge of magazline or: newspaper Itho production andfor subbing pius an interest in electronics we may be able to offer you an interesting and rewarding position:

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Wiften appilcations wih full ev:to Mike Kenward The Editor, Fractical Electronics. Westover Wouse, West Duay Road, Poole, Dorset:
|NTRODUCTION of the slide dissolve unit has been a most exciting development for the enthusiast in colour slide photography. Two projectors are used with the slides stored alternately in each and smooth dissolves from one picture to the next are made by dimming one bulb whilst brightening the other. Not only does this technique stop that annoying sudden darkness between slides but it also gives a now freedom to the photographer to produce creative sequences of images which suit the changing moods of an accompanying soundtrack. Photographic clubs all over the world have established specialist groups for audio-visual work and some outstanding work has been shown at exhibitions and competitions.

But not all work has to be at this level; even the most ordinary collection of holiday snapshots will benefit from the professional touch given by pictures which automatically dissolve from one to the next in synchronism with a recording of music or commentary. Equipment to operate two projectors and to record the control and soundtrack signals on tape is available commercially but a basic unit will cost over $£ 150$ and advanced systems can cost far more.

This series of articles describes a dissolve control unit which is easy to build and adjust yet costs in the region of £40 to make putting it well within the reach of many amateur photographers. Cross-fading between the two projectors is controlled by a knob which allows the user to fade at any speed to suit the mood of the occasion. To change the slide a single button is pressed which automatically changes the slide in the dark projector-very useful in the heat of the moment when it is all too easy to press the wrong button and upset the whole sequence. Two additional buttons provide "twinkle" (rapid switching between two projectors) and automatic superimposition of two images-features not always found on commercial machines. Operation of the controls produces an audio signal which can be recorded on one track of any domestic cassette or reel-to-reel tape recorder and subsequently replayed to reproduce exactly the sequence of fades and changes that were originally recorded.

The control is designed to handle two remote-control projectors having 24 V 150 W lamps although it is easily modified to handle 250 watt lamps. Each projector needs a simple modification to interrupt the wires carrying current to the bulb and to bring them out at a socket for connection to the control box. Additional connections to each projector operate the slide change mechanism and provide the power to drive the electronics so that no separate connection to the mains is needed.



Fig. 1. Block diagram


Fig. 2. (a) Mains input (b) late trigger pulses (c) small voltage across load (d) early trigger pulses (e) large voltage across load

## BRIGHTNESS CONTROL

A triac is used to control the brightness of each projector lamp. When the device is connected in series with a circuit it behaves like a switch which is turned on by the brief application of a pulse to its trigger contact. Provided that the current through the triac stays above a certain sustaining level it will remain conducting, but it will turn off as soon as the current falls below this critical level. These features make the triac a useful device for regulating the power applied to a load which is driven from an alternating current supply.

The block diagram of the unit (Fig. 1) shows that a triac is connected in series with the lamp circuit of each projector and Fig. 2 shows how the circuit works. In (c) the triac is turned on late in every half cycle and turns off automatically as the alternating current reverses in direction producing a small average voltage across the lamp. More light is produced in (e) where the triac conducts for the larger part of each half cycle causing almost the full rated current to flow in the lamp. Trigger pulses are applied to each triac via a pulse transformer which isolates the driving electronics from the alternating voltage applied to the load.

In order to exercise precise control over the current flowing in the lamp we need to be able to vary the position of the trigger pulses within each mains half-cycle smoothly and accurately.

## SAWTOOTH

As the block diagram shows a 100 Hz sawtooth signal derived from the full-wave rectified mains frequency is compared in a high gain comparator circuit with a d.c.
control voltage, producing the results shown in Fig. 3. Increasing the control voltage (b) causes the comparator positive-going transition (c) to occur later and later in the mains half-cycle. This transition is differentiated to form the triac trigger pulse so the triac conducts for a shorter period and the average current in the load therefore decreases. Finally the control voltage exceeds the peak of the sawtooth, no trigger pulses are produced, and the light remains off.

As the control voltage is reduced (d) the trigger pulse occurs earlier in each half-cycle so increasing the lamp brightness. Notice the negative-going pulses that are added to the sawtooth at the end of each period. If these pulses are not added to the sawtooth no trigger pulses are produced when the control voltage falls below the lowest point of the waveform and the lamp abruptly changes from full-on to off. With the pulses added the control voltage can fall well below the base of the sawtooth while still producing a narrow trigger pulse at the beginning of each half-cycle to keep the lamp on.

The control voltage is connected directly to one comparator (projector $A$ ) and to the second via an inverter (projector B). As the input voltage to comparator A rises the input to comparator $B$ falls and vice-versa producing a smooth cross-fade (dissolve) between the two projectors.

## SLIDE CHANGE

The slide in a projector is only changed when its lamp is dark. At this time the control voltage for that projector is very close to the peak of the sawtooth and slide change is


Fig. 3. Comparator waveforms (a) full wave rectified signal (b) sawtooth (c) comparator output (dim) (d) sawtooth (e) comparator output (bright)
initiated by momentarily increasing the voltage to cross a further threshold just above the peak level. This momentary increase is detected by the comparator and relay driver (see the block diagram) and the relay operates, closing a pair of contacts which are connected to the projector slide change solenoid in parallel with the normal remote control contacts.

As the control voltage for the dark projector rises to cross the slide change threshold the control voltage for the bright projector falls below the lowest point of its sawtooth comparison signal. If it were not for the negative-going pulses added to the sawtooth (Fig. 3) the bright projector would turn off momentarily each time a slide is changed.

Fig. 4 summarises the relationship between the control yoltage levels and the actions of the two projectors.


Fig. 4. Control voltage relationship

## RECORD AND REPLAY

When recording a sequence of dissolves, switch S4 (Fig. 1 ) is placed in the "record" position placing the projectors under manual control. The voltage derived from the front panel controls is also used to vary the frequency of a voltage controlled oscillator (VCO) whose output varies in the band 1 kHz to 3 kHz as the projectors are cross-faded and makes a jump to either 500 Hz or 4 kHz when the slide in the dark projector is changed. This varying frequency is sent to the tape recorder after filtering to remove unwanted higher harmonics from the square wave signal.

On replay S 4 is moved to the "play" position to form a phase-locked loop whose input signal is derived, after buffering, from the tape recorder. The output of the phase detector and low pass filter now copies the control voltage that was derived from the front panel controls during recording and the original sequence of events is reproduced exactly.
A special signal loss detector in the input buffer stage ensures that the projectors behave predictably when the replay signal is lost during tape editing. Both projectors illuminate at half brightness until the signal returns when the sequence continues from where it was interrupted.

## CONNECTIONS TO THE PROJECTORS

The electrical connections to the projectors are shown in Fig. 1. A triac is connected in series with the bulb circuit and trigger pulses are applied to the gate via a pulse transformer which isolates the projector circuits from the remainder of the electronics. Currents of up to 7A will flow in the lamp circuit so the connections to the triac must be

made with stout wire and the triac itself must be in firm contact with a good heatsink-more about this in the construction information.

Both sides of the low voltage secondary winding of the mains transformer are brought out from the projector to provide power for the unit so that a separate mains connection to the unit is avoided. The slide change button of each projector remote control is duplicated by a relay contact in the unit which closes momentarily to set the slide change mechanism in motion.


Fig. 5. Power supply

## POWER SUPPLY

D3-D6 together with C2 (Fig. 5) form a conventional fullwave bridge rectifier which is fed from the mains transformer of one of the projectors and provides a smoothed output of about 36 V . The rectifier output is connected via a dropper resistor to the pair of Zener diodes to generate stabilised supplies of $\pm 6.2 \mathrm{~V}$ and a 0 V rail which power the electronics. The unstabilised output is available to operate the three relays in the unit. A separate unsmoothed full-wave rectified supply to drive the triac trigger control circuits is provided by D1, 2 and R3. R1, 2 and C1 form a low pass filter which prevents transients caused by the switching of the projector triac from disturbing the control circuits.

## FRONT PANELCONTROLS

In Fig. 6 a resistive divider chain derives the voltage to control the brightness of the projector lamps during a crossfade. VR2, the fader potentiometer, produces a control voltage which varies between limits of approximately $\pm 2 \mathrm{~V}$, set by presets VR1, 3 when making the initial adjustments. Careful selection of VR2 is important. The component specified was chosen because it behaves in a linear fashion immediately the spindle moves away from either end stop.

Fig. 6. Circuitry associated with front panel controls.


Many potentiometers that were tested (both carbon track and wire-wound) showed little or no change in resistance during the first $20^{\circ}-30^{\circ}$ of rotation giving an unpleasant feel to the control as no change in lamp brightness occurred over this range.

Amplifier A1 serves a dual purpose. S1 is normally closed making A1 a non-inverting high impedance buffer but when S 1 is opened it becomes a comparator with threshold at OV and its output then jumps to the supply rail towards which it is already offset. When VR2 is at either end of its range one of the projectors is dark and operation of S1 causes the control voltage to cross the slide-change threshold (set at about +3 V ) for this projector. In this way the dark slide is automatically selected for change and only one change button is needed.

A1 is one of four operational amplifiers with internal compensation that are housed in a single package-the MC3403. The amplifiers in this package have sufficient slewing rate to give full output for signals of up to 4 kHz and they are used in this unit wherever an amplifier or comparator is needed. In all eleven amplifiers are used so three MC3403 packages are required. Because of the relatively low accuracy required of the d.c. amplifiers in this circuit it has not been necessary to use more expensive amplifiers with very high input impedance and low offset currents.

From A1 the output is normally connected via S2 to the lamp control and recording circuit at the record/replay switch. When S2 is operated, however, an inverted version of the control voltage (derived by A2, R6, 7, 8) is produced, inverting the states of the projectors to produce a "twinkle" effect. Operation of S2 allows rapid alternation between two slides and can be used to produce an animation effect.

S3, the superimpose button, breaks the output from S2 allowing R9, 10 to sum the control voltage (from A1) and its inverse (from A2). The opposing voltages add to give OV making both of the projectors light up equally and superimposing their images on the screen. R9, 10 also make sure that the control voltage waits respectably at OV during changeover if S2 is of the break-before-make variety.

## INTERFACE TO RECORDER

With S4 in the "record" position (Fig. 7) the control voltage derived from Fig. 6 is connected to the buffer, A5, and then to an inverter formed by A6, R22-24. The resulting pair of voltages, one of which is the inverse of the other, is used to control the two projectors, A and B .

While making a recording the control voltage is also connected to the input of a voltage controlled oscillator (VCO) which is part of IC1, an integrated phase-locked-loop circuit type MC14046. As the voltage changes the frequency


Fig. 7. Record/Replay circuits


Fig. 8. Lamp control circuits
of the oscillator varies between 500 Hz and 4 kHz . This varying frequency is filtered by a second order low pass Sallen and Key filter (A4, R17-19, C6, 7) whose break point is set at 4 kHz to remove undesirable higher harmonics from the square wave output of the VCO. The filtered tone, whose amplitude is approximately 10 V peak-to-peak, is attenuated by R20, 21 before being connected to the input of the tape recorder. The values given for the attenuator resistors result in an output signal of 100 mV peak-to-peak but the constructor can choose any suitable value by varying the resistor ratio.

On replay the output from the tape recorder is buffered and amplified by A3. This ampifier has hysteresis (determined by $\mathrm{R} 12,13$ ) of $\pm 50 \mathrm{mV}$ to ensure that no residual noise at the input is recognised as a false signal when the input is removed. If a very large input signal is available the hysteresis can be increased to give added protection by increasing R12. Reducing the hysteresis is not recommended and the input sensitivity of the unit is therefore determined by this figure. Input impedance of the amplifier is 47 k fixed by R11.

The buffered tone is fed to one input of the phase comparator (also part of IC1), the other input of which has the VCO output signal applied to it.

With S4 in the "play" position a phase locked loop is formed using R14/C4 as the low pass filter with the result that the VCO locks exactly to the frequency of the input tone. The VCO, however, is the one that was initially used to make the recording so when its frequency corresponds with that of the incoming tone the voltage at its input is
exactly equal to the control voltage that was originally applied. The recovered voltage is connected to A5 and used to control the projectors as described above.

If the received signal is lost, or if the unit is switched to "play" before the tape recorder is started, the output of the phase comparator will drop to -6 V . A control voltage of this value will turn one projector full on and the other off as well as changing its slide. To avoid this problem a loss of signal detector (described later) monitors the output of A3 and operates RLC if the signal is lost during replay. Contact RLC1 adds together the opposing voltages generated by A5, 6 producing an output to both projector brightness controllers of about OV which turns both projectors half on-a useful feature when initially aligning their images on the screen.

## LAMP CONTROL CIRCUITS

Apart from common bias components this part of the circuit (Fig. 8) is split into two identical parts, one for each projector. To avoid repetition only the components for one half will be mentioned which are numbered 101 upwards. Components for the other half are numbered 201 upwards with the same second and third digits.

The unsmoothed rectified mains voltage from the power supply circuit is used to saturate TR1, allowing it to turn off only during the short periods when the signal is close to -6.2 V . As a result narrow positive-going spikes occur at the collector coincident with the zero-crossings of the a.c. mains waveform.

## COMPONENTS . . .



## Transformers

| T101, 201 | Transformer assembly |
| :--- | :---: |
| Core | FX2238 (Mullard) 2 off per assembly |
| Bobbin | DT2281 (Mullard) 1 off per assembly |
| Ring | DT2356 (Mullard) 1 off per assembly |
| Clip | DT2357 (Mullard) 4 off per assembly |
| Board | DT2359 (Mullard) 1 off per assembly |

28 swg enamelled copper wire
36 swg enamelled copper wire

## Miscellaneous



TR1 and all the other transistors in this unit are type BC107 or its complement, the BCY71. Constructors should beware of substituting near equivalents without first checking the maximum collector to emitter voltage that the device will tolerate. In several places in the circuit the transistors have collector voltages of 30 V or more which is sufficient to damage BC108/9 devices and their equivalents.

TR102 together with R102, VR101 and the common bias supply formed by R30/D10 forms a constant current source which charges C101 causing the voltage across it to rise linearly with time. At each mains zero-crossing C101 is discharged by TR101 to $-2 \cdot 2 \mathrm{~V}$ determined by the common bias network R29/D9. The peak voltage which the ramp across C101 reaches before the discharge is determined by the charging current and can be varied between +1.5 V and +2.5 V by VR101. This adjustment, made during initial setting up, determines the value of control voltage which just extinguishes the projector lamp.

The ramp voltage is fed via R103 to the comparator A101. At the comparator input TR103 clamps the ramp signal to -6.3 V during each mains zero-crossing to produce the waveform with negative-going spikes as shown in the figure.

To the other input of the comparator is applied the projector control voltage derived from the manual controls or from the tape recorded signal. When the ramp voltage rises above the control voltage the output of the comparator makes an abrupt positive-going transition of about 10 V which is differentiated by C102/R105 and applied to the base of TR104. D101 prevents breakdown of the baseemitter junction of TR104 during the negative-going edge of the comparator output which occurs at the mains zerocrossing when C101 is discharged. TR 104 collector produces narrow 30 V pulses at the trigger instants which are coupled via the 10:1 step-down transformer T101 to the gate of the triac. R107 limits the triac gate current and prevents damage to TR104 in the event of a short circuit. D102 suppresses overshoot caused by the primary inductance of T101 when the triac is disconnected from the secondary circuit which might otherwise break down the driver transistor.
The emitter of TR104 is returned to OV rather than to -6.2 V for a particular purpose. Differentiation of the comparator output produces a steep rising edge followed by an exponential decay to -6.2 V as sketched on the circuit


Fig. 9. Slide change relay drivers


Fig. 10. Signal loss


Fig. 11. Signal regained
diagram. If the emitter were returned to -6.2 V the point at which the transistor turned off (about 0.6 V above the emitter voltage) would be on the shallow part of the exponential decay producing an ill-defined switching point and output pulse width. Furthermore, the slowly changing voltage may result in the slow turn-off of TR104 which may begin to dissipate excessive power whilst in the linear region of operation. Returning the emitter to OV ensures that both turn-on and turn-off occur at rapidly changing points on the differentiated waveform.

## SLIDE CHANGE RELAY DRIVERS

The projector control voltage is compared with a common threshold of +3 V (generated by R31, 32) in A102 as shown in Fig. 9. When the slide change button is depressed the control voltage of the dark projector jumps from approx +2 V to cross the +3 V threshold, turning on TR105 as a result. Relay RLA then operates completing the slide change circuit to the projector. D103 prevents damage to TR105 caused by overshoot across RLA when the transistor turns off.

## SIGNAL LOSS DETECTOR

If the signal from the tape recorder is lost during replay (when making an edit, for example) the output of the phase detector falls to -6.2 V at a rate determined by the low pass filter R14/C4. Fig. 10 shows what happens to the control voltage of projector $B$ (after inversion by A6) assuming that it is dark (the worst case) when the input signal is lost. We see that the projector lamp goes out and about 5 ms after the signal is lost the voltage crosses and stays across the slide change threshold. This will cause some projectors to change once, others will change repeatedly, while some will even change backwards-all undesirable effects!


Fig. 12 (above). Signal loss detector circuit. Fig. 13 (right). Showing operational waveforms of signal loss detector


Fig. 11 shows what happens when the input signal returns-it takes about 30 ms for the control voltage to stop changing the slide and to return to its correct level.

To prevent this effect it is necessary to clamp the control voltage to a value within the lamp control range before the output of the phase detector crosses the change threshold and to release the control voltage only after the phase detector output comes within this range again. This is done by means of a fast-operate slow-release signal loss detector formed by two CMOS monostables IC2a, b (Fig. 12) which is connected to the output of the signal buffer A3. CMOS devices will work over a wide range of supply voltages enabling IC1 and IC2 to be operated from the $\pm 6.2 \mathrm{~V}$ rails so that a separate power supply is not needed. Fig. 13 shows the waveforms that result from the operation of the circuit.

Shortly after the signal is lost (the time being determined by $\mathrm{R} 33 / \mathrm{C} 8$ ) the Q output of the retriggerable monostable IC2a falls making the inverting input of comparator A7 fall below the OV threshold. The comparator output rises, operating RLC via TR2, and contact RLC1 in the tape recorder interface circuit closes turning both projectors on at half power. S4b prevents RLC from clamping the control voltage when making a recording as no signal is then present at the input terminal.

On recovery of the signal the $Q$ output of IC2a rises immediately triggering IC2b whose $\overline{\mathrm{Q}}$ output falls, keeping the comparator input below OV for a period determined by R34/C9. In this way the attack and decay characteristics of the signal loss detector can be individually adjusted to prevent mis-operation of the slide change relay of projector $B$ during tape edits or before the show begins when the tape recorder is not running.

NEXT MONTH: Construction and setting up


## A Matter of Degree

There now seems to be general acceptance that both our primary and secondary educational systems have failed in respect of generating large numbers of employable people, whatever other qualities they may possess. Especially so in mathematics, physics and even English. My own contacts in industry are constantly telling me how hard it is to find good keen youngsters who can do simple arithmetic or write a sensible paragraph.

To a lesser extent but still serious is the university graduate who needs further training before being able to do any useful work in inidustry.

Now GEC-Marconi and Bath University have got together with a new $4 \frac{1}{2}$ year degree course for electrical and electronic engineers. British educational standards, savaged over the years by trendy educationists, have been thrown overboard. Instead the new standard is proudly announced as equivalent to the French Grandes Ecoles and the German Technische Hoch Schulen which, judging by results in those countries, is far more effective. I can testify, again from experience, that French and German graduates from their respective educational systems are just as 'rounded' and 'human' and 'socially responsible' as our own product. Frequently more so, as well as being better qualified and selfdisciplined.

The new Bath course, which also enjoys a support grant from the Engineering Industries Training Board, is to be a sandwich course with a difference. The difference is that individual students will be sponsored by individual GEC-Marconi companies to which they will return periodically for their industrial training sections of the course, eventually joining that company.

Emphasis is to be on real-life engineering, especially the systems approach to problem solving and design. Students will not only learn engineering fundamentals but will get
thrown in at the deep end in case studies, seminars and role-playing, reminiscent of Harvard Business School management training.

I can only spot one fault in the scheme. It doesn't start until September 1980. Anyway, this gives plenty of time for prospective Masters of Engineering to apply to the School of Electrical Engineering, Bath University.

## End of Term

Company annual reports can be compulsive reading. Often for what they leave out or the neat way that difficulties are glossed over. They are obliged to give the facts and figures of performance but beyond the balance sheet there is plenty of scope for originality in keeping the existing shareholders contented and attracting new ones. They are sometimes like end-of-term reports and none more so than that of Teradyne Inc, the Boston-based ATE manufacturer.

Their latest 'theme' company report features seventeen of their top salesmen round the world. Punchy profiles of their backgrounds, their wives, hobbies and business philosophy. And, of course, how well they are doing for Teradyne and its shareholders.

After allowing for the publicity gloss, all are clearly dedicated to their company and to personal achievement. And all are constantly on the move. Champion traveller is Tim Chan, based in Taiwan and looking after his own country, Korea, Hong Kong, Singapore, Malaysia, Thailand and Indonesia. He needs two dozen visas in his passport to get around his vast territory. Stan Fuller, based in Phoenix, pilots his own Cessna 210. Rene Verhaegen covers Benelux in his Audi, clocking up $65,000 \mathrm{~km}$ a year. And so one could go on.

This is a highly-motivated team with good products, high-priced, and sold worldwide. And the company is growing fast, now turning over $\$ 100$ million a year. Since founded it has never had a strike and has no collective bargaining contracts with its 2,000 workforce. Vice-President, sales, who heads up the global marketing is, for the record, not a high-powered tough American entrepreneur but a tough, high-powered Briton, Dennis P. O'Connell.

## Racal Breakthrough

Racal Communications Inc in the USA and Racal (Canada) Ltd were established many years ago in the hope of breaking through the 'Buy American' act which operated so unfairly against non-Americanowned companies in military procurement. Patience has now been rewarded but only with exceptional products which won the day in fierce competition. The US Air Force is initially buying $\$ 11$ million worth of a new Racal receiver, the RA 6790/GM, and the Canadian Armed Forces the RA 6778C to the tune of $\$ 5.5$ million Canadian.

The significance of the US Air Force contract is that it is the start of a replacement programme for the ageing R-390 communications receiver of which there are an estimated 40,000-plus in service round the world. The RA 6790 is a joint Racal

UK/US development. With a different front panel it made its European debut at the Racalex 79 exhibition in London as the RA 1792. It features a new frequency synthesiser based on a special LSI chip designed by Racal Microelectronics Ltd and has a 100-frequency built-in memory for instant tuning to pre-selected channels.

## Black Chips

Oil-rich Nigeria might be the first black African country to produce microcircuits. According to reports, the University of Ife has been purchasing production equipment and Nigeria could be in the business by the early or mid-1980s.

## Naval Missile

British Aerospace Dynamics Group has received a f 300 million shot-in-the-arm to develop a new sea-skimming anti-ship airlaunched guided weapon. Provisionally known as the P3T, the weapon is of the fire-and-forget type, pre-programmed by fire control computer just before launch with the on-board homing head and computer finding the target and moving in for the kill. It appears to be a further development of the Anglo-French Martel currently in service with the Royal Air Force. The only electronic subcontractor so far named is Marconi Space and Defence Systems for the active radar target seeker and homing head.

BA Dynamic Group is also looking at inhouse costs. At Stevenage a computeraided draughting and design system has been installed which is said to multiply draughtsman productivity by a factor of four. Of the 12,000 drawings a year currently produced, some 2,500 are expected to be handled by the automated system, leading to greater accuracy and consistent standards and cutting out much of the tedium of repetitive manual work. But apart from the benefits, BA Dynamics say, like others, that there is a shortage of suitably qualified design staff.

## Micro-min Laser

The latest in sophisticated micro-min is the world's smallest hand-held laser rangefinder, a little larger than a packet of 20 cigarettes and weighing, including battery, $1 \cdot 2 \mathrm{lb}$. An infantryman can easily carry it in his pocket and then has instant personal ranging up to 4,000 metres with an accuracy of $\pm 3$ metres. The pulse output is a third of a megawatt and the manufacturer, International Laser Supplies Inc., expect the cost to be as 'little' as $\$ 2,500$ each in 1,000-off quantities.

## Talking Calculator

And the latest in calculators is Sharp's desk-top development that repeats calculations with a synthesised voice as you key them in or demand the answer. This feature seems of doubtful value-but then I haven't seen the full specification. Anyway, it appears that you can choose your own language, English, French, Spanish, German or Japanese.


THIS article is directed towards those electronics enthusiasts who have sufficient hardware experience but possess little or no knowledge of programming. According to a recent survey conducted by The Amateur Computer Club, 70 per cent of computer faithfuls are in this category and they will find that few books suit their particular needs. Having your own computer, or at least access to one, means that you can learn at the keyboard and at your own speed. The choice of BASIC as the language is inevitable. It is the most readily available for the home computerist, which is due in turn to the fact that it is easy to learn, to understand and to apply. It is also surprisingly versatile.

## INPUT AND OUTPUT

From here on it will be assumed that you are sitting comfortably at the keyboard, ready to 'converse' with the computer. We will ignore, at least to start with, the usual formal classifications of 'assignments', 'declarations' etc. and jump straight in at the deep end with the first essential in any communication system, INPUT and OUTPUT. This is done with statements which may be used directly, as if we were 'commanding' the computer. At this stage we will regard all such statements as 'instructions' and refer to them in this way. On entering BASIC, the computer will respond with the usual prompt, \# flashing etc. which indicates that you are in command and may proceed with your first (or next) entry.

In order to embark on a new program however, we must erase all traces of previous entries and initialise all variables. This is done by typing NEW at the terminal. Remember to do this every time a fresh program is started. There is one other entry which must be made each time an instruction is completed. This is the typing of the CR (carriage return) key, which indicates to the computer the end of that particular instruction set. Remember then, to press the RETURN key at the end of each instruction statement: and now we are ready to start. Type,
NEW (+ RETURN key)
and on the next line, type the following

$$
\begin{gathered}
\text { PRINT } 25-(19-7) * 2+50 \\
(+ \text { RETURN })
\end{gathered}
$$

The printer will respond with the result of this calculation, which is 51 . This illustrates two features:

1. The instruction 'PRINT' means, in effect, "Evaluate this expression and PRINT the result".
2. The calculation follows the usual arithmetical sequence: brackets; powers; multiplication and division; addition and subtraction: and where two operations are in the same
category, the calculation is effected from left to right. This is more clearly shown in the next example. Try it.

$$
\text { PRINT } 25-2 * 3+(6 / 2) \uparrow 2(+ \text { RETURN })
$$

The order here would be,
(1.) $6 / 2$ ( $=3$ ) (/ signifies DIVIDE)
(2.) $3 \uparrow_{2}^{(=9)}$ ( $\uparrow$ signifies TO THE POWER)
(3.) $2 * 3(=6) \quad$ (* signifies MULTIPLY)

This leaves $25-6+9$ to be evaluated, so the last two steps would be,
4. $25-6(=19)$
5. $19+9(=28)$
which will have been printed on the next line. This, of course, is no more than any calculator can do, but it's a start. To move one step beyond the calculator stage, try this:
PRINT "A, B; C:D." (+ RETURN) (note the quotes,"")

## SPACING

You will have found that whatever appeared between the quotes, including spaces, was reproduced exactly as entered. Combining these features, we have simple control over our output. For example, try the following:
PRINT "THE SUM OF 5 AND $4=" ; 5+4 \quad(+$ RETURN) which produces,

THE SUM OF 5 AND $4=9$
Note the semicolon after the second quotes. This controls the spacing before the result of $5+4$ is printed. Try the same line again using a comma instead of a semicolon. This time a space of about 7 characters will be left before the 9 is printed. The line is automatically divided into printing zones of 14 positions (this may vary slightly in different versions of BASIC) and the comma is used to effect this separation.
Next, try
PRINT "LENGTH", "BREADTH", "AREA"
which will print these headings, suitably spaced out at 14 unit intervals, ready for the print-out of a table of dimensions as follows:

## LENGTH BREADTH AREA

Now experiment with various combinations of text, expressions and spacing, using both the semicolon and the comma.

Since each PRINT instruction produces a carriage return and line feed at the end of the statement, a PRINT used alone in a program will have the effect of skipping a line. You will have
noticed by now that spaces are ignored by BASIC (except when they appear between quotes).
The computer sees no difference between

$$
\text { PRINT } 4+5 / 3 \text { and } \ldots \text {. . . PRINT } 4+5 / 3
$$

If memory space is short, quite a bit can be saved by omitting all spaces, but it will not do your sanity any good when you have to search for errors!
To summarise so far with an example,

$$
\begin{gathered}
\text { PRINT "LENGTH }=" ; 5, \text { BREADTH }=" ; 7, \\
\text { AREA }=" ; 5 * 7
\end{gathered}
$$

which will produce,

$$
\mathrm{LENGTH}=5 \mathrm{BREADTH}=7 \mathrm{AREA}=35
$$

Note that in the print statement a space is left after each equals sign $(=)$, before the quotes are closed, so that the values 5,7 and 35 are suitably spaced away from the equality sign.

## TAB FUNCTION

There is one more convenient output control available in BASIC, the TAB function. This gives precise positioning for any part of a print-out, which you will now discover if you type the instructions,

## PRINT TAB(10);"BASIC IS BEAUTIFUL"

You will find that the first word is started in the tenth printing position. Note that the value 10 must be in parenthesis and that this in turn must be followed by a semicolon before opening the quotes. The value in brackets may be any expression, with or without variables, so the printing position can be made dependant on an earlier program routine and in the final evaluation, incorporated in the PRINT statement: all of which helps to make graph plotting much simpler.
Finally try,

$$
\begin{aligned}
& \text { PRINT TAB(5);"RESISTANCE }=" ; 25 ; \text { TAB }(25) ; \\
& \text { "VOLTAGE }=" ; 5 ; \text { TAB(40);"CURRENT }=" ; 5 / 25
\end{aligned}
$$

This gives,

$$
\text { RESISTANCE }=25 \quad \text { VOLTAGE }=5 \quad \text { CURRENT }=0.2
$$

. . . which shows that the TAB function may be used more than once in any one PRINT statement, so we have effective control over our print-out. (If the printer encounters a TAB value less than its present position, it will continue from its present position . . . it can hardly go backwards!)

## PROGRAM CONSTRUCTION

Having learned to control print-out we can now move on to program construction. The first noticeable difference is that when a program is entered, there will be no response from the computer at the end of each line, as happened previously when in the command mode. Each line should be numbered to indicate that a program is being entered, and this also determines the logical order in which the steps will be executed. The numbered steps or statements may however be entered in any order, since the computer will, under BASIC control, execute them in the correct numerical (i.e. logical) order.

Line numbers are in multiples of five or ten. By leaving gaps between, additional lines can be sandwiched in; and the need to add, delete or in other ways alter a program after apparent completion is the rule rather than the exception.

The first example for you to try follows:
NEW
$\begin{array}{ll}10 \text { LET } \mathrm{A}=5 & \text { (let the value } 5 \text { be entered in store } \mathrm{A} \text { ) } \\ 20 \text { LET } \mathrm{B}=12 & \text { (let the value } 12 \text { be entered in store } \mathrm{B} \text { ) } \\ 30 \text { LET } \mathrm{C}=\mathrm{A}+\mathrm{B} & \begin{array}{l}\text { (add the contents of } \mathrm{A} \text { and } \mathrm{B} \text { and } \\ \text { place in } \mathrm{C} \text { ) }\end{array}\end{array}$

40 LET D $=\mathrm{A}-\mathrm{B} \quad$ (subtract B from A and place the result in store D)
50 PRINT " $\mathrm{A}+\mathrm{B}=" ; \mathrm{C}, " \mathrm{~A}-\mathrm{B}=" ; \mathrm{D}$

## 60 END

The full program has now been entered and resides in memory, waiting for an instruction to start operating. The command in BASIC for this is RUN, so now type,
RUN (+ RETURN) . . . . and the immediate response will be,

$$
A+B=17 \quad A-B=-7
$$

The explanations on each line are hardly necessary, which is the beauty of BASIC; it is almost self-explanatory! Note that in some versions, the word LET is optional when in program mode, so line 30 , for example, would be acceptable as,

$$
30 \mathrm{C}=\mathrm{A}+\mathrm{B}
$$

## VARIABLES

This program also demonstrates the use of letters as variables. In fact any letter from A to $\mathbf{Z}$ may be used, either alone or with a digit ( 0 to 9 ) as a suffix. For example A, A0, A1, $\mathrm{A} 2, \mathrm{~B} 2, \mathrm{Z} 2$ are all acceptable as variables in the same program. .

You will no doubt have realised that the above program can be simplified, since the PRINT instruction will deal with more than one calculation in the same line. Enter the following,
NEW

```
10 LET A \(=5\)
20 LET B \(=12\)
30 PRINT" \(\mathrm{A}+\mathrm{B}=" ; \mathrm{A}+\mathrm{B}, " \mathrm{~A}-\mathrm{B}=" ; \mathrm{A}-\mathrm{B}\)
40 END
```

which will produce exactly the same output as before.
There is one more output control. Enter the following:
NEW

```
10 PRINT "ALL THIS TEXT ";
20 PRINT "WILL APPEAR ";
30 PRINT "ON THE SAME LINE"
40 END
```

As stated, the entire print-out will be on the one line, due to the effect of the semicolon at the end of lines 10 and 20 , which is to suppress the carriage return and line feed normally following a PRINT statement. Notice the space left before the quotes were closed in lines 10 and 20 , which prevents a 'cramming' of the words from the end of one line to the beginning of the next. One more similar example:

```
10 LET S = 1+2+3+4+5
20 PRINT "MEAN OF THE FIRST FIVE ";
30 PRINT "NATURAL NUMBERS = "; S/5
40 END
RUN
```

This will give,

## MEAN OF THE FIRST FIVE NATURAL NUMBERS $=3$

This completes the list of all output instructions and practice should provide proficiency; and now with this repertoire, plus the skeleton of a program to work on, we can proceed to INPUT.

## INPUT

Up to now, all data has been written into the program, but where the same program is used for different sets of values, it may be necessary to enter the data separately each time the program asks for a new set.

This can be done using the statement 'INPUT', which causes the program to stop and wait for the appropriate entries at the keyboard, each value separated from the next by a comma.

When the program stops because of an INPUT instruction, a 'question mark (?)' will be printed to indicate to the user that data is requested. Here is a simple example to start with:
NEW

```
10 INPUT A, B, C
20 PRINT A*A;B*B;C*C
30 END
RUN
```

After line 10 , the program stops, prints a question mark '?' and expects three values (separated by a comma) to be entered. When this is done (and followed in the usual way by RETURN), the three values are placed in stores A, B and C in that order and the rest of the program is implemented. In this way, by again entering RUN, a new set of data can be typed in and this can be continued as long as there is data available for evaluation.

Note that the order of entry of data must correspond to the order in which it has to be applied to the variables. If in the above example, we had entered 5, 7, 24 after the question mark '?', the print-out would have been,

$$
\begin{array}{lll}
25 & 49 & 576
\end{array}
$$

Now try this complete program, using your own values for $L$, $B$ and $H$.

NEW

```
10 INPUT L,B,H
20 PRINT
30 PRINT "LENGTH", "BREADTH", "HEIGHT",
        "VOLUME"
4 0 ~ P R I N T
50 PRINT L, B, H, L*B*H
60 END
RUN
```

The effect of this will firstly be a question mark '?', after which your values for $\mathrm{L}, \mathrm{B}$ and H must be entered, followed by RETURN as usual. On receiving this input from the keyboard (remember the comma between), the next output will be, (using $5,4,3$ for the data),

## LENGTH BREADTH HEIGHT VOLUME <br> $\begin{array}{llll}5 & 4 & 3 & 60\end{array}$

The double spacing is effected by the PRINT statement in line 40 and the horizontal spacing is obtained by the use of commas in lines 30 and 50.

## GOTO

One disadvantage of the above program is that if we again type RUN in order to repeat for another set of data, the print-out will still include the headings LENGTH, BREADTH etc. To avoid this and to allow tabulation of further data under the original headings, it is necessary to introduce a new instruction, GOTO, which directs the program to a specific statement number from where it will continue execution in the usual numerical (logical) sequence. To effect these improvements there is no need to reenter the whole program. Any line may be deleted by typing the line number followed by RETURN; and a line may be altered by retyping the whole line (including the line number) correctly, when the new line will replace the old one. Just make the following additional entries:

$$
\begin{aligned}
& 20 \text { GOTO } 50 \\
& 60 \text { GOTO } 10 \\
& 70 \text { END }
\end{aligned}
$$

Now type RUN, when the question mark will appear as usual, but after receiving the next set of values the program will jump
to line 50 , missing the 'print headings' line and so continue to print out these values and result, tabulated as before. At line 60 the instruction is now 'GOTO 10', so the program returns to the start and requests the next set of data. While all this may satisfy our present requirements, it firstly introduces an undesirable element and secondly presents a problem. The unwanted part of the output, you will already have noticed, is the question mark followed by the data, which intrudes on the continuous tabulation of the print-out. A remedy for the latter will be explained later.

## LOOP PROBLEMS

Since the program returns to line 10 at the end of each routine, the END statement is never reached and we are 'stuck in a loop', a well known nightmare in programming. Although it does not interfere with the execution of this particular program, it will certainly cause you trouble sooner or later and this is as good a time to deal with it as any.To escape from such a dilema, the 'panic button' is used. This may vary in different versions of BASIC, sometimes a single key labelled 'ESC' (escape), or the combination of two keys, one a control key and the other a suitable character such as ' $X$ ' (exit), ' $O$ ' (out), ' $C$ ' (cancel) etc. For our purpose we will call it the ESC key, but refer to your own version to find the appropriate replacement. It may be necessary to press the ESC key repeatedly, depending on what sequence of operations the computer is engaged in, before you succeed in interupting the loop. The ESC key can also be used to halt the execution of a program at any time, if you want to return to the 'command' status, where the keyboard is again in control. Now try a variety of tabulation programs such as,

1 Volume of a cylinder (V), given the radius ( R ) and height (H). $(\mathrm{V}=3 \cdot 1416 * \mathrm{R} * \mathrm{R} * \mathrm{H})$

2 Tax (T) payable, given rate of tax ( $\mathrm{R} \%$ ), gross income (I) and total allowances (A). (T = (I-A) * R/100)
3 Value of resistance ( R ), given three resistances ( $\mathrm{R} 1, \mathrm{R} 2$, R 3 ) in parallel. $(\mathrm{R}=1 /(1 / \mathrm{R} 1+1 / \mathrm{R} 2+1 / \mathrm{R} 3))$


The listing for program one and its execution is shown above. If your machine has $\pi$ in memory, only the actual symbol need be included. As the sign for raise to the power is $\uparrow$, statement 70 can be reduced
to $\pi \cdot R \mathbb{N} \mathbf{N} \cdot \mathrm{H}$.

## READ AND DATA

The input of data using the INPUT instruction (which is the only method available on minimum versions of BASIC) has obvious limitations, as you have already discovered. A second method which can be used requires two statements, READ and DATA, which must be programmed as a pair. The READ statement inputs data sequentially and finds its data in the corresponding order following the DATA statement. Type out the following,

5 READ A, B, C, D
10 DATA 2,3,4,5
15 PRINT ( $\mathrm{A}+\mathrm{B}$ )*(C+D)
20 STOP
. . . which produces the output, 45
Several things to note here:

1. The values $2,3,4$ and 5 will be read into stores $A, B, C$ and D in that order. Care must be taken therefore, that the values following DATA are entered in the correct sequence to correspond to that of the variables.
2. The DATA statement (or statements) may appear anywhere in the program, provided that if there is more than one, they are still kept in the proper order.
3. The above example could have been written as,

> 10 DATA 2,3
> 16 DATA 4,5
. . . with exactly the same result, since the READ statement will search for the required data sequentially, wherever it appears in the program.
4. Instead of the usual END as the last entry, STOP has been substituted which, though also halting execution, transfers control to the keyboard to allow investigation of that part of the program before the next part is implemented. Provided that no changes are made to the program at this point, typing CONT will direct the computer to continue from where it received the STOP instruction.
Now enter the following:
5 READ A, B, C, D, E, F
10 DATA $6,8,9,21,3,13 \ldots$ ( or any six integers you care to use)
15 LET T $=\mathrm{A}+\mathrm{B}+\mathrm{C}+\mathrm{D}+\mathrm{E}+\mathrm{F}$
20 PRINT "MEAN $=$ "; $T / 6$
25 STOP
which will print,
MEAN $=10 \ldots$ then the program will stop and wait for further commands. By retyping line 10 with a fresh set of values, followed by GOTO 5 (no line number, since this is a command after a STOP), the program will return to the start and operate on the new data.

## FOR . . . NEXT LOOP

Attempt to find the mean of several hundred numbers by this method and there will obviously be trouble! Fortunately, the problem is easily solved by the use of a FOR . . . NEXT loop. Enter this program and see what happens.
5 FOR I = 1 TO 6
10 READ N
15 PRINT N $* N$;
20 NEXT I
25 DATA $1,2,3,4,5,6$
30 STOP
The print-out will be,
149162536

The FOR . . . NEXT loop operates in this way: the variable I (any letter may be used) takes on successive values from 1 to 6 and for each one, that part of the program which lies between
lines 5 and 20 is executed. As each new value of $I$ is reached, a test is made to see if it has exceeded the 'TO' value ( 6 in this case), when the loop terminates and the rest of the program is completed. In effect, then, 'NEXT I' means, "Repeat this routine for the next value of $I$ ".

By changing line 5 to have a larger terminating value for $I$, and by entering the appropriate amount of data, a large number


Typical FOR . . . NEXT loop listings
of values can be accommodated. Try this method now on the earlier program to find the mean of six numbers, but this time make it sixteen-or sixty.

Then try this program, which shows how part of the loop can depend on the value of I itself, and how the incremental step need not be unity. (The latter requires the addition of 'STEP N', where N may be any value, positive or negative, integer or decimal). Can yuu visualise what the print-out will look like?

```
FOR I = 1 TO 9
10 PRINT TAB(4*I); I;
15 NEXT I
20 PRINT
25 FOR H = 18 TO 2 STEP - 2
30 PRINT TAB(2*H); H/2
35 NEXT H
4 0 ~ S T O P
```

It is sometimes helpful, when writing out your program, to offset that part which lies within the FOR . . . NEXT loop; on large programs this serves as a check on the start and finish of each loop. Some versions of BASIC will automatically produce such a print-out. This has been done in the last program at lines 10 and 30.

Before continuing with further examples of the FOR ... NEXT loop, it will be helpful to introduce a few more controls and to be more specific about the use of numbers.

Except in the minimum versions of BASIC, where only integers are acceptable, any real number may be entered, to at least eight significant figures, the range varying for different versions, but usually from $\pm 10^{-99}$ to $\pm\left(10^{100}-1\right)$. Numbers may be entered normally as integers or decimals, or in exponent form; (for example, 176, 49.75, or $314159 \mathrm{E}-5$, the latter representing $314159 * 10^{-5}$. The E stands for exponent).

You will no doubt have typed a few errors by now and will have found retyping the whole line exasperating. This can be avoided by the use of two devices, the BACKSPACE control and the DELETE. The former will cancel the last character to be entered and the latter will erase the whole line. Refer to the manual for your particular version, since these controls vary, the most likely ones for a BACKSPACE being a CONTROL C (for CANCEL), or a CONTROL $\leftarrow$.

## REM AND LIST

Finally, two facilities which will prove invaluable when 'debugging' a program, the REM (remark) statement and the LIST command.

The REM statement allows comments or explanations to be attached at intervals throughout a long program, without interfering with its operation. Anything following REM on the same line will be ignored by the program but will be printed out in any listing. This brings us to the use of LIST which, as a command, will cause the whole program, as then held in memory, to be printed in correct order; which allows an examination and check of the present state of the program. Further, by typing, for example, 'LIST 35', only line 35 will be listed; and by entering 'LIST 20, 70', all lines from 20 to 70 inclusive will be printed.

Combining some of these new facilities and using the FOR . . . NEXT loop, type out this program exactly as shown.

5 REM TO FIND THE MEAN OF ANY NUMBER OF VALUES
10 PRINT "HOW MANN $\longleftarrow$ Y NUMBERS ARE THERE?
15 INPUT N
20 FOR I = 1 TO N
25 READ X
30 LET T $=\mathrm{T}+\mathrm{X}$
35 NEXT I
8 LET T $=0$
40 PRINT "TOTAL $=$ "; T
45 PRINT "MEAN = "; T/N
50 STOP
40 (+ RETURN)
38 DATA $7,12,5 \cdot 8,2 \cdot 9 \mathrm{E} 2,99 \cdot 4 \mathrm{E}-1, \ldots$ (select your own data)
LIST

In line 10, an error was typed, so the backspace (CANCEL) character, control ${ }^{\leftarrow} \leftarrow$, was entered following the extra ' N ', which corrected the word 'MANY'. (Check that your version uses ' $\leftarrow$ '; it may be different). After line 35 was entered it was realised that the totalling store, $T$, would have to be set to zero for the first and each subsequent set of values. Line 8 was then typed in to accomplish this. It was also decided at this point that a print-out of the actual total was not required, so line 40 was erased by entering 40 followed by RETURN. It was now discovered, as sometimes happens, that the data itself had been forgotten and this was then entered as line 38. Because of these changes, a listing was requested by typing LIST (and RETURN), when the following output was obtained.

5 REM TO FIND THE MEAN OF ANY NUMBER OF VALUES
8 LET T = O
10 PRINT "HOW MANY NUMBERS ARE THERE?"
15 INPUT N
20 FOR I $=1$ TO N
25 READ X
30 LET'T $=$ T + X
35 NEXT I
38 DATA $7,12,5 \cdot 8,2 \cdot 9 \mathrm{E} 2,99 \cdot 4 \mathrm{E}-1, \ldots$
45 PRINT "MEAN = "; T/N
50 STOP
If the program is now run, the value of the mean will be printed; and if a re-run is required for a new set of values, enter line 38 again with the new data, then type
GOTO $8 \ldots$ which will return control to the program at line 8 , repeating the whole process.

This example also demonstrates how the terminating value, N , in the FOR . . . TO statement (line 20) can itself be a variable and therefore alterable for each new set of data.

## IF . . . THEN

Most versions of BASIC offer a number of functions such as $\operatorname{ABS}(\mathrm{X}), \operatorname{INT}(\mathrm{X}), \operatorname{RND}(\mathrm{X})$ and $\operatorname{SQR}(\mathrm{X})$, which will find the absolute value of $X$, the largest integer not greater than $X$, a random number derived from $X$ and the square root of $X$ respectively. The latter will almost certainly be obtained from a simple sub-routine which uses a process of iteration to obtain the square root; and this will form an ideal example with which to introduce the IF . . THEN statement. This is the decisionmaking facility in BASIC, where an expression of relativity appears between IF and THEN.
For example,
IF A > B THEN $50 \ldots$ will cause the program to branch to line 50 if the relation $\mathrm{A}>\mathrm{B}$ is true. Otherwise it will continue to the next line in the sequence. Here is the program, expanded slightly, in order to make its operation easier to follow.

```
5 REM SQUARE ROOT
10 LETE1=2
15 PRINT "ENTER NUMBER"
20 INPUT N
25 LETQ = N/E1
30 LET E2 = (Q+E1)/2
35 IF ABS(E1-E2)<0.0001 THEN }5
40 LET E1 = E2
4 5 \text { GOTO 25}
50 PRINT "SQUARE ROOT = "; E2
55 STOP
```

In line 10 , the first estimate, E 1 , is given any reasonable value, in this case, 2 . Line 25 divides the number, N, by E 1 and puts the quotient, $\mathbf{Q}$, in store $\mathbf{Q}$. Since the root of N will lie between $Q$ and $E 1$, the average of these two values is calculated in line 30 and placed in store E2. Line 35 tests to see if the absolute difference between this new improved estimate and the previous


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one is significant (you may choose your own degree of accuracy here): if not, the last calculated estimate, E2, is printed. If the absolute difference is still too great, E1 takes on the value of E2 (line 40 ) and a return is made to line 25 to repeat the loop. A calculation of this type, which may have to be undertaken frequently in a longer program, can be tucked away in a corner as a sub-routine, to be called into use when required. This is effected in BASIC by the statements GOSUB and (to get back to the main program at the exit point), RETURN. An example of this occurs in the following program, which finds the roots of a quadratic equation, $\mathrm{Ax}^{2}+\mathrm{Bx}+\mathrm{C}=\mathrm{O}$, given the values of the co-efficients, $\mathrm{A}, \mathrm{B}$ and C .

```
    5 PRINT "ENTER CO-EFFICIENTS"
10 INPUT A,B,C
15 LET D \(=\mathrm{B} * \mathrm{~B}-4 * \mathrm{~A} * \mathrm{C}\)
20 IF D < O THEN 80
GOSUB 50
LET X1 \(=(\mathrm{R}-\mathrm{B}) / 2 / \mathrm{A}\)
LET X2 \(=-(\mathrm{R}+\mathrm{B}) / 2 / \mathrm{A}\)
PRINT "ROOTS ARE "; X1; X2
GOTO 85
LET E \(=2\)
LET R \(=(\mathrm{D} / \mathrm{E}+\mathrm{E}) / 2\)
IF \(\operatorname{ABS}(\mathrm{R}-\mathrm{E})<0.0001\) THEN 75
LET \(E=R\)
GOTO 55
RETURN
PRINT "NO REAL ROOTS"
STOP
```

Line 20 tests to see if D is negative and if so, causes a branch to line 80 , which declares that there is no real solution and the program stops. If D is not negative, it proceeds to line 25 which in turn directs operations to the sub-routine at line 50 . Having obtained the square root of $\mathbf{D}$ (held in store R ) to the required accuracy, line 75 returns the sequence to line 30 , where we left the main program. Finally, line 45 directs operations past the sub-routine to the STOP statement. If required, a 'GOTO 10 ' command will return everything to the start for the next equation.

## ON . . . GOSUB, ON . . . GOTO

To complete this topic, there are two more useful statements which are used in conjunction with GOSUB and GOTO; they are ON . . GOSUB and ON . . . GOTO. Try to assess the effect of the following program before typing RUN.

```
10 PRINT "TYPE 1, 2 OR 3"
INPUT X
20 ON X GOTO 25, 35, 45,
25 PRINT "YOU ENTERED 1"
30 GOTO 50
35 PRINT "YOU ENTERED 2"
40 GOTO 50
45 PRINT "YOU ENTERED 3"
50 END
RUN
```

You will have discovered that line 20 effects a branch to either lines 25,35 or 45 , depending on the value of $X$, which may be any value or expression, greater than zero. For $\mathrm{X}=1$ the program is directed to line $25, \mathrm{X}=2$ sends it to line 35 and $X=3$ to line 45 . If $X<1$ or $X \geqslant 4$, an error message will be printed and if X is not an integer, it will first be truncated to an integer value. The statement ON . . . GOTO could be replaced by ON ... GOSUB with a similar effect, the branch going to some sub-routine within the program.

## DIM

A set of numbers arranged in a row or column, or an array of numbers held in matrix or table form can be manipulated very easily using the DIM statement in BASIC. This defines the dimension of an array, when named in the program, using any letter of the alphabet. For example, DIM Y(100) allocates memory space sufficient to deal with 100 values and reserves it for the array named Y. For a two-dimension matrix, the statement becomes DIM $Z(A, B)$, where $A$ and $B$ define the number of elements in the row and column respectively of matrix Z . A table of values consisting of 20 rows and 15 columns would therefore be entered as DIM T $(20,15)$. There is a limit set to the size of A and B, which will vary from one version to a nother, but usually at least 255 elements are allowed. Although an array having less than ten elements (or ten by ten in two dimensions) need not be defined by the DIM statement, it is advisable, in order to save memory space, to do this anyway. It is usually necessary to use a FOR . . . NEXT loop to read into or print from an array, the following program illustrating this for a one dimension set.

5 REM PRIME NUMBERS LESS THAN 1000
10 DIM A(1000)
15 FOR $\mathrm{H}=2$ TO 1000
20 IF A(H) < O THEN 50
25 PRINT H;
30 IF H > SQR (1000) THEN 50
35 FOR I $=\mathrm{H}$ to 1000 STEP H
0 LET A(I) $=-1$
45 NEXT I
50 NEXT H
55 END
Line 10 reserves space for the one-dimension array named A. This will usually set all elements to zero, but in some versions it may be necessary to do this in the program first, for example:

```
6 0 ~ F O R ~ K ~ = ~ 1 ~ T O ~ 1 0 0 0 ~
70 LET A(K) =0
80 NEXT K
```


## NESTED LOOPS

Above is the first program which has used nested loops (a loop within a loop) and this will also be required when dealing with a two-dimension array. At line 15 , the outer loop is started for the first value of H , which is then printed, line 25 . The second, inner loop starts at line 35 and is repeated for all defined values of I by the statement in line 45 . Line 50 now returns the program to the start of the outer loop for the next round. Note that all the circuits of loop I are undertaken before the next round of loop H begins. For a two-dimension array, a similar arrangement is necessary. To illustrate, the following program reads in the 20 elements of a 5 by 4 table, replacing all odd values by zero, then printing the revised table.

```
5 DIM T(5,4)
FOR I=1 TO 5
FOR H=1 TO 4
READ T(I,H)
IF T(I,H)/2 = INT(T(I,H)/2 ) THEN 35
LET T(I,H)=0
NEXT H
NEXTI
DATA
3,14,12,5,20,18,7,14,19,30,25,25,16,4,7,11,21,30,24,6
REM PRINT REVISED TABLE
FOR J = 1 TO 5
FOR K=1 TO 4
PRINT T(J,K)
NEXT K
```

75 PRINT
80 NEXT J
85 END
The print-out from this will be,

| 0 | 14 | 12 | 0 |
| :---: | :---: | :---: | :---: |
| 20 | 18 | 0 | 14 |
| 0 | 30 | 0 | 0 |
| 16 | 4 | 0 | 0 |
| 0 | 30 | 24 | 6 |

A few points to note from this last program:

1. Since the outer loop is from 1 to 5 , the values will be read in as 5 rows, the inner loop expecting 4 elements for each row. The data therefore, must be entered similarly in order, row by row. While the table may, if preferred, be read
in columns, it cannot be printed this way and of course it is necessary to have the same arrangement for both the READ and PRINT statements.
2. If an odd number is divided by two the result cannot be an integer, so line 25 uses the INT(X) function to test each element for even status. Note also the use of 'nested' brackets in this line.
3. If line 35 is now changed to . . 35 PRINT T(I,H), . . , line 36 becomes . . 36 NEXT H . . and a PRINT inserted at . . . 38 PRINT . . . , lines 50 to 80 will not be required, as the print-out will be processed while the loops are being cycled.
This by no means exhausts all the commands, functions and statements available in BASIC, but with further practice and experience it should be easy to learn the others from a BASIC manual.

## E24 PARASCAN

To assist understanding of how BASIC commands work together, the following program is explained step by step.

Should you have need of an odd value resistance, E24 Parascan will compare every possible combination of twin parallel resistors, and display those which meet your require-
ments.
The computer asks for the resistance you require (assumed to be in Ohms), and then asks for the acceptable tolerance (just enter figure).

20 DATA $1,1.1,1.2,1.3,1.5,1.6,1.8,2,2.2,2.4$, 2.7, 3

30 DATA 3.3, 3.6, 3.9, 4.3, 4.7, 5.1, 5.6, 6.2, 6.8, 7.5, 8.2, 9.1

40 DIM R(24) : FOR A = 1 TO 24 : READ R(A) : NEXT A
$100 \mathrm{X}=1: \mathrm{Y}=1:$ INPUT"RESISTANCE ";R
105 IF R $>4550000$ THEN PRINT"OUT OF RANGE": GOTO 100
110 INPUT"\% TOLERANCE ${ }^{\prime} ;$ T
$120 \mathrm{~L}=\mathrm{R}-(\mathrm{T} / 100) * \mathrm{R}: \mathrm{U}=\mathrm{R}+(\mathrm{T} / \mathbf{1 0 0}) * \mathrm{R}$
130 PRINT"FROM ";L; ${ }^{66}$ TO ";U;" OHMS" : PRINT
200 FOR Z $=1$ TO 7
230 FOR M=1 TO 24 : IF R(M)*X<R THEN 275
233 FOR W $=1$ TO 7
235 FOR N = M TO 24 : IF R(N) $\mathbf{2}$ Y $<$ R THEN 270
$240 \mathrm{P}=\mathbf{R}(\mathbf{M}) * \mathbf{X} * \mathbf{R}(\mathbf{N}) * \mathbf{Y} /((\mathbf{R}(\mathbf{M}) * \mathbf{X})+(\mathbf{R}(\mathbf{N}) * \mathbf{Y}))$
250 IF P<L OR P>U THEN 270
$255 \mathrm{~T} 1=((100 * \mathrm{P} / \mathrm{R})-100) * 1000: \mathrm{T} 1=$ INT(T1)/1000
$256 \mathrm{R} 1=\mathrm{R}(\mathrm{M}) \neq \mathrm{X}: \mathrm{K} \$={ }^{66 \%}: \mathrm{K} 1 \mathrm{~S}=69$
257 IF X>100 THEN R1=R1/1000 : K\$="K"
258 IF X>100000 THEN R1=R1/1000:K\$="M"
262 R2 $=$ R(N)*Y: IF Y>100 THEN
R2=R2/1000:K1\$="K"
263 IF Y>100000 THEN R2=R2/1000 : K1\$="M"
265 PRINT R1; K\$; TAB(6)"||"; R2; K1\$;
TAB(14);"="; P; TAB(28);T1; *\%"
270 NEXT $N: Y=Y \neq 10:$ NEXT $W: Y=1$
275 NEXT M : X=X*10

## 280 NEXT Z


(DATA statements containing the fundamental decade of the E24 range A variabie $R$ is chosen, subscripted ( $n$ ), to identify the above DATA.
To cope, $n$ must be from 1 to 24 , so $R(n)$ is DIMensioned thus. To cope, $n$ must be from 1 to 24 , so $R(n)$ is DIMensioned thus. A FOR-NEXT loop is used to READ-in the data, where A plays the part of $n$

Variables to be used later are preset. Then the machine is programmmed to ask for the required resistance, and designates it $R$. The
computer will not confuse this with $R(n)$ grammmed to ask for the required resist
computer will not confuse this with $R(n)$

The highest resistors this program will compare are: 9M1 $\|$ 9M1, so that nothing greater than 4M55 $\mathbf{4 M}$ can be found. Only when the IF condition is true will the PRINT and GOTO statements be executed

## Requests \% tolerance required, designated $T$

Algorithm calculates upper and lower (U and L) limits allowable
These limits are printed for user reference. The null PRINT statement creates a line space on the screen
Specifies instructions 230 to 275 to be executed 7 times (the number of E24 multiples to be considered for one arm of the parallel pair), eg. $\mathbf{4 . 7 , 4 7 , 4 7 0 , 4 k 7 , 4 7 \mathrm { k } , 4 7 0 \mathrm { k } \text { , and } 4 \mathrm { M } 7}$

Specifies instructions 230 to 270 to be executed 24 times (the number of E24 values to be considered for one arm of the parallel pair)
The IF statement will successively bypass to NEXT M until the sampled resistor is at least as high as the requested one. This avoidance of unnecessary processing considerably speeds up the action

Specifies instructions 235 to 270 to be executed 7 times (same as line 200, but for other arm)

Specifies instructions 235 to 270 to be executed up to 24 times (same as line 230, but for other arm). $N$ is sampled from $M$ to 24 to avoid repeat sampling of that which occurred in the $M$ loop. eg. $4 \mathrm{k} 7 \| 8 \mathrm{k} 2$ and $8 \mathrm{k} 2 \| 4 \mathrm{k} 7$ is avoided

Each time this main algorithm is executed, $\mathbf{P}$ becomes the parallel value of the resistors being tested. The "product-over-sum" equation is used on resistors $\mathbf{R}(M)$ and $\mathbf{R}(\mathbf{N})$, with $X$ and $Y$ as their respective multipliers

Checks that $P$ falls within $U$ and $L$, IF not, THEN jumps to next value

T1 becomes the percentage error of $\mathbf{P}$ to requested $\mathbf{R}$. The first statement deliberately over-calculates $T 1$ by a factor of 1000 , so that the INT statement can round-down to a manageable 3 decimal places,
by dividing by 1000 by dividing by 1000

Converts $\mathbf{R}(M)$ and $\mathbf{R}(\mathbf{N})$ to R1 and $\mathbf{R 2}$ ready for PRINT statement. The purpose of this block of instructions is to convert print-out to $\Omega$, $\mathbf{k} \Omega$, and $M \Omega$, to save screen space

The output PRINT instruction (bypassed by out-of-range parallel $\mathbf{R}$ combinations). R1 and R2 are the resistor values; K\$ and K1\$ state
the units. Quotes contain
Without graphic embellishments this program is fairly portable (will work on most machines) but the UK101 requires that READ statements precede DATA statements. The E24 resistors are assumed to be zero tolerance.

These specify that the NEXT value of $N$, or $M$, should be tried. These specify that the NEXT value of $\mathbf{N}$, or $\mathbf{M}$, should be tried.
Although two NEXTs may share the same line, NEXT $\mathbf{W}$, for example, will not be selected until all the Ns from $M$ to 24 have been tried (see,
line 235). In this example, the multiplier $Y$ will be raised to the power line 235). In this example, the multiplier $Y$ will be raised to the power
of ten in the process

## THE EVERYTHING CHIP

My first offering this month is not something that hobbyists can easily rush out and buy, but I do feel that it will interest most PE readers for two reasons: (a) It is British to the core, and (b) It is a novel device with almost unlimited potential which is sure to crop up in "hobby sockets" before long.
The device in question is the Ferranti ULA 2U000, where the ULA part stands for Uncommitted Logic Array. There isn't anything new about the ULA concept itself, Ferranti have been selling versions based on their unique Collector Diffusion Isolation (CDI) technology for several years, but their latest offering really does look a winner in a truly internationl sense. But first, a word about the ULA philosophy.

In these days of Large Scale Integration (LSI), anyone can get a complex logic system integrated as a single chipproviding they are prepared to order at least 10,000 to make it cost effective! Anyone who can't afford those sort of quantities has to make do with random logic chosen from the TTL or CMOS families for example, or perhaps a microprocessor with its attendant memory and peripheral chips. Those are the main options, and for many applications none of them fit very well. It is in these "awkward" applications where the great British ULA compromise can come to the rescue.

The ULA is an LSI chip which consists of an array of standard logic gates without interconnections. The uncommitted semiconductor chips are mass produced with all the economics of scale which that brings, and then stockpiled (unpackaged) as a standard product. When Joe Bloggs \& Co. want a washing machine controller chip, or John Smith \& Co. need a controller for an electronic camera, they draw up a logic diagram with all the necessary gates, counters, flip-flops and drivers shown, and Ferranti produce a final metallisation mask which interconnects the gates on a ULA to do the job. The fact that only the final mask is "special" means that design time is short and the resulting devices are much cheaper than a discrete logic, or microprocessor, approach.

The 20000 seems to be the ultimate device in a logical progression of ULAs from Ferranti, and in this case it can do more than the custom MOS LSI competition because it has linear circuitry on chip as well as the normal ULA logic gates. With the 20000 it is possible to build complete systems with gates, flip-flops, counters, Schmitt triggers, l.e.d. drivers, comparators, oscillators, and amplifiers, all on one chip
with any number of package pins from 14 to 40 ! The new chip can be battery powered too, sipping only about one milliamp from a one volt supply despite the 256 logic cells (each of which can be connected as two two-input gates) and the forty linear or interface cells which are arranged around the chip periphery.

You still can't get your hands on goodies like this in one-off or even ten-off quantities of course, but you don't have to order ten thousand either! If there is any justice in this world, this chip should be a real winner for Ferranti and for Britain.

## DIGI-POT

If you need an accurately set potentiometer with good resolution for an instrumentation application say, the old way to do it is to use a bulky, wire wound, helical pot with a turns counting dial. It would be expensive, the pot would wear out eventually, and reading the dial wouldn't be too easy, but it would work, and with luck you might get 1:1000 usable resolution. Soon you'll be able to do it the digital way-thanks to Analog Devices and their Multiplying Digital to Analogue Converters (MDACs).

Now I suppose everyone knows roughly what a DAC is (parallel binary in-proportional analogue signal out at the other end) but I for one always expected to see a precision d.c. reference supply used with every DAC, and that's where the $M$ comes in, to prove me wrong. A multiplying DAC can be used with any signal on its "reference" pin-even an a.c. waveform which swings above and below ground. So, instead of binary in and analogue out with the scaling set by a precision d.c. reference, we get a.c. signal in and a.c. signal out with the output related to the input by a scaling factor determined by the binary input. In effect the a.c. input is multiplied by the binary input, with the largest multiplier being unity.

Now, I have been talking about an a.c. signal input, just to show the change in emphasis in MDAC applications, but actually it can be any sort of signal, a.c., d.c. or precision reference. A classic application for an MDAC might be the control of gain or "level" in an audio channel by means of a computer or microprocessor, but there are many other occasions when an analogue signal has to be kept under precise, digital control.

So much for MDACs but how about Analog Devices and digital pots? Analog devices have a whole family of MDACs available already, but newly added is the

AD7525 which has the distinction of having b.c.d. (binary coded decimal) rather than straight binary inputs. B.c.d. is of course great for interfacing with people as every calculator knows, because it is easy to convert to and from decimal (or denary for the purists!). Team up the AD7525 with a $3 \frac{1}{2}$ digit thumbwheel switch, which can be set from 0000 to 1999 and you have got yourself the simplest, most reliable, precision potentiometer money can buy. You can use it anywhere you need a precision pot-power supply $O / P$ voltage setting, amplifier gain setting, time delay setting and so on. It will work for a.c. and d.c. signals and you can put it right in the signal path with only the non-critical b.c.d. connections brought to the front panel.

## IMPROVED DECODER

When the 7447 seven segment decoder joined the TTL family it was one of the most complex devices then available, and all those goodies like leading zero suppression and intensity modulation capability made it and its attendant filament or l.e.d. displays very attractive compared with the traditional high voltage "Nixie" tubes previously used for number indication. Time marches on however, and the 7447 has now got competition. Most of the competition up to now has had a limited area of application, but a pair of new devices from Signetics/Mullard look ready to oust the 7447 from its industry-standard position.

The devices, coded NE586 and NE587 do all that the 7447 does, including leading zero suppression and intensity modulation, but in addition they both feature an input latch and constant current output drivers which remove the usual need for a collection of current limiting resistors. The input latches make interfacing with microprocessors and other systems, like counters, where data is available only in a dynamic form, very easy. The NE586 has a fixed O/P drive current of 25 mA per segment which is suitable for a range of seven segment l.e.d. digits. The NE587 has an extra pin which allows single resistor programming of the output current up to a 50 mA maximum, making display multiplexing easier and the choice of l.e.d. digit even wider.

Ferranti Ltd., Gem Mill, Chadderton, Oldham, Lancs. OL9 8NP.

Analog Devices Ltd., Central Avenue, East Molesey, Surrey KT8 OSN.

Signetics/Mullard Ltd., Mullard House, Torrington Place, London WC1E7HD.

 original circuit ideas. It should be emphasised that these designs have not been proven by us. They will at any rate stimulate further thought. Why not submit your idea? Any idea published will be awarded payment according to its merits.

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serted in the text.
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that it has not been accepted for publication elsewhere.



## SOUND-TO- LIGHT SEQUENCER

THE circuit shows a four channel soundlight sequencer utilising full wave control.

Clock pulses are drived from half of a 7413. This is connected as an oscillator with a fast edge and a frequency which is variable between about 0.5 to 20 Hz . This clocks one half of the 7474 flip-flop organised as a divide by four counter which in turn is coupled to a decoder which interprets these four states and whose output sequences a low state at the outputs of the NAND gates. These outputs are inverted by IC4 and then are taken directly to the gates of the thyristors.

When any output of IC4 goes high, a logic 5 V is applied to the gate of the corresponding thyristor, thus triggering it into conduction. When, however, this voltage is removed, as it is on triggering by the following clock pulse, so as soon as the full wave rectified mains supply to the thyristor falls to zero, the thyristor is turned off and so the cycle repeats, turning on each thyristor in turn.

The input of the low frequency amplifier, is connected across a speaker and so can be used to sequence the lights in time to the beat of music. One point to note, is that, as the ground connection is not at earth potential, but at 240 V , the 0 V rail on the logic supply must not be earthed.
R. Scott,

Stakeford,
Northumberland.

## PARITY FOR ASCII

PParty bits are provided for computers to enable a check for errors to be made. This is done by counting the number of 0 s and 1 s , and if an odd number is counted an error has occurred.
This circuit effectively counts the Is, and adds a parity bit if the total is odd. The circuit is self-explanatory. The output of each EXCLUSIVE-OR gate is high only if one input is low and one high, i.e. a check for odd or even.
This means the gate IC2b is high only if the first seven bits have an odd number of 1 s . This output is used a the eighth bit.
M. Williams,

Hornchurch,
Essex.


## A PEAK PROGRAM INDICATOR



THIs circuit uses a single quad op-amp package to provide two stages of peak signal level indication, on a fast-attack. slow-decay basis. Full-wave rectification is used so that both positive and negative peaks are taken into account, and a special output configuration allows the power drawn from the supply to be no greater than that required for one l.e.d. indicator only.

ICla is a high input-impedance amplifier; the sensitivity of the indicator is defined by R2, which sets the gain of this stage. IC 1b acts as a unity gain inverter, and so one of the diode rectifier networks acts on positive peaks, and the other on
negative peaks, phase-inverted by this stage. Both peak rectifiers charge a common storage capacitor C6 through R8, which defines the attack time. R11 allows C6 to discharge between peaks, and sets the decay time.

IClc and ICId act as comparators, their trip points set by the voltages on their inverting inputs, derived from the resistor ladder-network that also generates the midrail voltage for biasing the linear stages. ICld, which receives the lower voltage, switches to indicate the -20 dBm level, its output going high and causing current to flow through D3. Since the output of IC Ic is still low, it sinks this current through

D6, and prevents D4 illuminating; D5 prevents any residual glow. At the -10 dBm level, IClc output also goes high, reversebiasing D6, and D4 is also allowed to illuminate. It is this series connection of l.e.d.s which halves the worst-case current consumption.

With the component values shown, the attack time-constant is 3 ms , and decay constant 470 ms .
D. R. G. Self,

Walthamstow,
London.

## DISPLAY TUBE/TTLINTERFACE



THis circuit was used to interface the high voltage indicator tubes of a counter to TTL circuitry to detect when a particular count had been reached. It shows a worthwhile economy over a system using presettable down counters and thumbwheel switches, or BCD equivalence gates.
Each cathode of the display tube is wired to a ten way one pole switch (S1). The cathodes are usually held at about 55 V by Zener diodes in the 74141 decoder/drivers when the numbers are off.

The number is illuminated when the output transistor turns on, taking the cathode to almost zero volts. The required count is selected by connecting that cathode to the op-amp. The resistor ratios are such that the output voltage goes high when the cathode voltage drops below 25 V . The inverting input resistor is high enough to limit the current to a safe value even if the cathode goes up to the supply voltage, due to an internal short, for example. R1 is a bias resistor to maintain a small current through the Zener diode to prevent proximity effects when nearby cathodes pulse.
A. Langton,

Aberdeen.


The Compukit UK 101 has
everything a one board 'superboard' should have.

- Uses ultra-powerful 6502 microprocessor
- 50 Hz Frame retresh for steady clear picture U.SA products with 60 Hz frame refresh always results in jittery displays)
- 48 chars by 16 lines - $1 K$ memory mapped video speed access to screen display nabling animated games and graphs
* Extensive 256 character set which inciudes full upper and lower case alphanumerics. Greek symbots or mathematical constants and numerous graphic characters enabling you to form almost any shape you desire anywhere on the screen
* Video output and UHF Highgrade modulator ( 8 Mz Bandwidth) which connects direct to the aerial socke your T.V. Channel 36 UHF.
of your Fully stabilised 5 V power supply including trans
former on board.
$\star$ Standard KANSAS city tape interface providing high reliability program storage - use on any 4 K user RAM expandable to 8 K on boan
* 4K user RAM expandable to 8 K on board $\$ 49$
* 40 line expansion intertace socket on board for attachment of extender card containing 24 K RAM and disk controller. (Ohio Scientific compatible).
$\star 6502$ machine code accessible through powerfu
2 K machine code monitor on board
* High quatity thru plated P.C.B. with all IC.'s mounted on sockets
- Professional 52 Key keyboard in 3 colours - soft ware polted meaning that all debouncing and key decooing done in software.
COMMANDS
CONT LIST NEW NULL RUN STATEMENTS CLEAR DATA GOTO GOSUB DEF DIM END FOR NEXT ON GOTO IF GOTO IF. THEN INPUT LET REM RESTORE RETURN STOP
EXPRESSIONS
OPERATORS VARIABLES
A.B.C. $Z$ and two letter variables

The above can all be subscripted when used in an array String variables use above names plus \$e.g.A


- 8 K Microsoft Basic means conversion to and from Pet, Apple and Sorcerer easy Many compatible programs already in print SPECIAL CHARACTERS
© Erases line being ty
carriage return, line feed.
Erases last character typed.
CR Carriage Return - must be at the end of each line.
Separates statements on a line
CONTROLC Execution or printing of a list is interrupted at the end of a line. "BREAK IN LINE XXXX" is printed, indicating line number of next statement to be executed or printed
CONTROLO No outputs occur until return made to command mode. If an Input state. ment is encountered. either another CONTROLO is typed, or an error occurs. ? Equivalent to PRINT


## EXTRAS AVAILABLE SOON

COLOUR ADD-ON enables you to choose your foreground and background colour anywhere on the screen. Flash any character on the screen at will. Full documentation and parts in kit form.

AD.A.RAM EXTENDER CARD provides up to 32 K Dynamic RAM Expansion, 8 Eprom sockets for 2708's or 2716 's. Parallel Port (centronics compatible) and an RS232C serial port.

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2) Fun and Games

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2) Any documentation that you have for the program (source listing not necessary)
3) This coupon signed by you accepting the rules and conditions of the competition.

## RULES:

1) Entries, including documentation, must be printed by computer or typed double spaced, with your name on every page.
2) Send or bring your entries to the address shown below.
3) Entries must be received by midnight on $29 / 2 / 80$, any received after this time are void.
Winners will be notified by post before 31/3/80.
4) You warrant by your signature that all programs and documentation material included is entirely your own creation, and that no rights to it have been given or sold to any other party, and you agree to allow COMPUKIT LTD. to use, publish, distribute, modify, and edit it as it sees fit
5) All entries become the property of COMPUKIT LTD. No entries will be returned nor any questions answered regarding individual entries. 6) Judging will be by a selected panel chosen by, and including representatives of COMPUKIT LTD. Judges may assign programs to any of the categories as they see fit. Decision of the judges is final. 7) Employees of COMPUKIT LTD, its dealers, distributors, advertising agencies and media are not eligible to enter.

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Address $\qquad$

I agree to abide by the above mentioned rules

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## Ohio Scientifics




#### Abstract

Full 8K basic and 4K user RAM Power supply and R.F. Converter P.O.A.

The machine can be economically expanded to assist in your business, remotely control your home, communicate with other computers and perform many of the tasks via the broadest lines of expansion accessories in the microcomputer industry. This machine is super easy to use because it communicates naturally in BASIC, an English-like programming language. So you can easily


## Built and tested (Delivery within 7 days)

instruct it or program it to do whatever you want, but you don't have to. You don't because it comes with a complete software library on cassette including programmes for each application stated above. Ohio Scientific also offers you hundreds of inexpensive programs on read-to-run cassettes. Program it yourself or just enjoy it, the choice is yours.

## Features

- Uses the ultra powerful 6502 microprocessor
- 8K Microsoft BASIC-in-ROM
- Full feature BASIC runs faster than currently available personal computers and all 8080 -based business computers.
- 4K static RAM on board expandable to 8 K
- Full 53-key keyboard with upper-lower case and user programmability
- Kansas City standard audio cassette interface for high reliability
- Full machine code monitor and I/O utilities in ROM
- Direct access video display has 1 K of dedicated memory (besides 4 K user memory), features uppercase, lower case, graphics and gaming characters for an effective screen resolution of up to 256 by 256 points. Normal TV's with overscan display about 24 rows of 24 characters, without overscan up to $30 \times 30$ characters.


## Extras

- Available expander board features 24 K static RAM (additional mini-floppy interface, port adapter for printer and modem and OSI 48 line expansion interface.
- Assembler/editor and extended machine code monitor available.


## Commands

| CONT | LIST | NEW | NULL | RUN |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
| Statements |  |  |  |  |  |
| CLEAR | DATA | DEF | DIM | END | FOR |
| GOTO | GOSUB | IF...GOTO | IF...THEN | INPUT | LET |
| NEXT | ON...GOTO | ON...GOSUB POKE | PRINT | READ |  |
| REM | RESTORE | RETURN | STOP |  |  |

Expressions
Operators
$-,+, *, l, \uparrow$, NOT, AND, OR, $>, \ll>,>=,<=$, $=$
RANGE $10^{-32}$ to $10^{+32}$

## Functions


(X\$,I,J).
VAL(X\$)
RIGHT\$(X\$,I)
STR\$(X)

Plus variables, arrays and editing facilities.
Fully built and tested. Requires only +5 V at 3 amps and a videomonitor or $T V$ and $R F$ converter to be up and running.


Additional 4k Ram $\mathbf{f 3 9 . 0 0}+$ VAT. Attractive custom built case $\mathbf{£ 2 5 . 0 0}$ + VAT.

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## RECORD FOR RUSSIA

This is the eleventh month of the year and it is fitting that what must be one of the most exciting years in space history should be recorded as such. On the threshold of the Shuttle era, where the techniques of the hardware have been undertaken by the United States with co-operation from space agencies round the world, the other side of the interface, mankind, has been developed by the Soviet Union. They turned their attention to the study of the biological problems of survival in space.

The longest stay in space and weightless conditions was concluded in August by Soviet cosmonauts Vladimir Lyakhov and Valeri Ryumin. They had been 175 days in space proving that this is also the province of mankind. The record of this year alone is unique for there were many misgivings, some are still vociferously apparent, yet once again the direct approach to a solution has proved the point.

## MAN-MACHINE INTERFACE

In some quarters a great play is made about the so-called difficulties on return to gravity. It is right that these matters should be thoroughly investigated. They have been, and it is clear that provided the exercises prescribed by the medical experts are followed no harm results. Of course in these early stages it is necessary for biological measurements to take place as soon as cosmonauts return. Therefore the maximum information must come from allowing the cosmonauts to land in the "heavy end'. The speed of their recovery is quite amazing when it is remembered that after several weeks in bed some considerable difficulties are experienced by ordinary people on Earth when they try to walk. Other biological problems have had much special attention in those countries interested. In the United States all the data is available. The Soviet Union has been able to supply the men required. So the
space frontiers are making the new world and it is gratifying that all the nations are cooperating in these activities.

The special attention that Russia has given to the testing of facilites and the direct effect of the man-machine interface has resulted in a major contribution to the space age. The other cosmonauts who showed progressive extensions of time in space have all contributed. The immediately past record holders were preceded by two other Russians, Vladimir Kovalenko and Alexander Ivanchenkov. They too carried out tasks with the ferries as well as the special activities with the Kristall furnace and the Splav (alloy) electrical smelting installation.

## CRYSTALS

Salyut-6 space station saw the active investigation of crystals synthesized from elements of the third and fifth groups of the periodic table such as gallium arsenide and indium antimonide.

Of special interest was the production of crystals of cadmium and mercury tellurides. This particular crystal is the basis of a thermovisor. This is an infra-red device which can yield valuable information on the internal condition of the human body. It is indispensible for certain medical specialists.

Experiments in melting extremely pure optical glass were very successful. Zero gravity is essential for the production of high quality crystals. The natural vacuum of space will no doubt enable crystals of the second generation to exceed the present 100,000 elements per square centimetre. Indeed it is already being forecast that by the late 1980's a million elements will be possible. This again will reduce the size of equipment.

## CIRCUMTERRESTRIALSPACE

There is no doubt that the feeling is growing that space exploration is associated with the application to the use of circumterrestrial space. It is to this end that the Soviet Union has spent so much time with the Salyut-6. The weight of this station is 19 tons. Its length is 15 metres. With two docked cargo ships it grows to 30 metres and 32 tons. The building up of stations by the simple process of joining up successive units, each a vehicle in its own right, seems to the Russians to be an efficient and safe way of dealing with the tasks of the future.

During the two years that the space station has been in orbit much work has been done. One interesting point that emerged from the working conditions in weightlessness was that as time went on the cosmonauts increased their efficiency in performing their allotted tasks. After the return of the last two cosmonauts the station continues orbiting automatically. During the period of its activity seven freight transport ships have made the journey to and from the Salyut-6.

Lyakhov and Ryumin began their record breaking trip in a Soyuz-32 spaceship on February 25 this year. On the 26 of February they commenced work aboard the Salyut-6. Materials and equipment were brought up by Progress-5, Progress-6 and Progress-7 ships. In addition the unmanned Soyuz- 34 brought
materials and equipment to the station. On June 13th the Soyuz-32 which brought the crew to the station returned with records and the two cosmonauts Kovalenko and Ivanchenkov.

## TELESCOPES

The freight ship Progress-7 had brought up the radio telescope KRT-10. This was assembled in the intermediate chamber of the space station. Progress- 7 was undocked and moved away. It was planned to use the Progress-7 as an observation point so that flight control could observe and control the telescope. The telescope was then moved out into position and the 10 metre parabola opened out. As it happened the unit did not quite get clear and the last task of Lyakhov and Ryumin before returning to earth was to execute a space walk to correct the fault.

The telescope was used in conjunction with the new 70 metre parabola at the long range radio communication centre in the Crimea. The distance between the two telescopes, one on Earth and the other in orbit, forming an interferometer. The base line was varied by the movement of the space station unit so that it was possible for this to range from 400 km apart to $10,000 \mathrm{~km}$ during the synchronous radio sessions. The effective aperture was the equivalent of a telescope the size of the Earth itself.

This opens up the possibilities for very large telescopes in space. A 10 metre parabola on Earth would weigh several tons but the space situated units would be a small fraction of this. It is therefore being planned by Russia to set up telescopes of up to 200 metres in diameter. A series of these will first be assembled in low earth orbit by a small team and then taken to a solar orbit. The total size of each unit would be from one to ten kilometres across. It would be possible in one combination to have one unit in near Earth orbit and the other at say Saturn. This would be a distance of about $1,500 \mathrm{~km}$.

This would have tremendous resolving power and might well be the means of detecting as yet unknown sources of energy and even perhaps discovering whether there were any planets round stars which might have civilisations. Also it would make it possible to set up a three dimensional picture of the universe directly.

## THREE FOR ONE

Comsat are seeking to reduce the number of antennae in use for satellite communications. The new proposal called the torus antenna will enable three satellites to be in use with one antenna station. Normally there has to be a separate antenna for each satellite, each a parabola focussed at a particular point. In the new proposal, provided the satellites are grouped to a band not more than 30 degrees apart from each other it takes the form of a line focus. The reflector appears almost flat but is in fact shaped. It looks very much like three parallel linear parabolic channels. Within the 30 degree requirements three satellites can be interrogated with one station. The economics are sound for the station costs only 1.1 million dollars against 0.8 million dollars each for the single version.


Fair adjudication for quiz contests

THIS article describes a monitor set which can be used by a referee or quizmaster to adjudicate fairly the result of a contest between individuals or teams and as such should prove popular in clubs or fund raising activities such as charity functions

Each team is provided with a button or buttons to press when an answer to a question is to be submitted. The first to reply actuates a lamp and buzzer simultaneously alerting the referee to the station answering and disabling all other contestants' units.

A competition state of readiness is resumed by the referee pressing his button, after adjudication, when all units revert to their stand-by state in readiness for the next question or throwing open the question to the other contestants in the event of a wrong answer,

This system was designed for three competitors or teams; however, there is no reason why it cannot be extended to as many contestants as required.

## CIRCUIT

In the off state the anodes of the three thyristors are at a positive potential biasing off D3 to D8. When one of the contestants' buttons is pressed it turns on the respective thyristor dropping its anode voltage to around zero volts; this in turn forward biases the other thyristors. The question master then notes which buzzer is sounding and cancels it by pressing his button removing the voltage from the circuit thus reducing the current through the thyristor below its holding level turning it off.

The type of thyristor used is not critical and any type should function perfectly as any variation in gate current is adjusted by the three presets to suit the manufacturer's data.

To adjust these presets connect an ammeter across the press switch contacts and adjust the wipers to get the right gate current ( 200 mA on the thyristor specified). Do not adjust for gate voltage as this can be very misleading.

If triggering should become a problem use OA47s as these have a lower forward voltage drop although they are more expensive.

The circuit around TR1 forms a simple voltage regulator with the base held at the Zener voltage thus holding the collector of TR1 at the Zener voltage less the forward voltage drop of the transistor junction, approximately 700 mV .

The quiz-master's button shorts out the Zener diode, grounding the base of TR1, effectively removing all the voltage from the output. The Zener voltage is not critical
and may be any voltage between 7-15V although the lights will be brighter and buzzers will be louder if the Zener voltage is towards the upper limit.

The regulator circuit may be discarded if a press to open push switch is available or even a toggle switch, but if this is done the output to the thyristors will not be stabilised and will rise to something like 22 V causing the bulbs to have a shortened life and making it necessary to have higher working voltage capacitors.

Also the lamps may be dispensed with but if this is done the thyristors will not latch as the buzzers take an intermittent current, so some other load will have to be provided to keep the holding current above the threshold level.

Diodes D3 to D8 are needed to stop interaction between the thyristors. It will be noticed that these are all mounted in the centre enclosure instead of their respective boxes. Wiring up in this way enables the use of four core cable, otherwise six core cable would be necessary (Fig. 1).

## COMPONENTS

Resistors
R1 $\quad 470$
R2-R4 $1 \mathrm{k}(3 \mathrm{off})$
All 1 W carbon

## Capacitors

C 1

$\mathrm{C} 2-\mathrm{C} 4$$\quad$| $1000 \mu$ elect 25 V |
| :--- |
| $220 \mu$ elect 16 V (3 off) |

Potentiometers
VR1-VR3 10k (3 off)
Semiconductors

| D1 | 1N4001 |
| :---: | :---: |
| D2 | B2Y88 10 V 400 mW |
| D3-08 | $1 \mathrm{N914}$ (6 off |
| CSR1-CSR3 | C103YY (6 off (R, S. 261-873) (3 off) |
|  | 2N3053 \$ |

## TR1

## Buzzers

BZ1-BZ3 12V single tone (R.S. 248-808) (3 off)

## Miscellaneous

S1 Mains on/off toggle, S2-S5 push button switches; 4 boxes Astros Grey (AST578)-West Hyde, 40 feet four core cable. Transformer-6-0-6V 0.5A malns IR.S. 196-2961, Lampholder- 22 mm dia, Bulbs-12V 2.2 W . Malns neon, FS $1=50 \mathrm{~mA}$


Fig. 2. Printed circuit board for p.s.u.

Fig. 3. Component layout

Fig. 4. Printed circuit board for individual or team boxes. Two are required

Fig. 5. Component layout. Pins and components for the duplicate box are shown bracketed


Fig. 6. Printed circuit board for individual or team box containing isolating diodes

Fig. 7. Component layout

Fig. 8. Panel cut-outs for lamp and buzzer in contestants' boxes

[60 203

## CONSTRUCTION

Construction is perfectly straight forward. The printed circuit boards are fitted upright in the slots moulded into the ends of the boxes. These slots are tapered down to the bottom of the box by approximately 1 mm each side and seeing as the printed circuit board is also used for strain relief on the cable, some care is needed in fitting them to ensure that they are a fairly firm fit. Four core cable passes through the hole in the side of the box and then through two holes in the printed circuit board, supplying strain relief of the soldered joints. DIN plugs and sockets could be used to join up the separate units but as the cost was of prime importance on the prototypes, these were not used.

If when fitting the buzzers the hole through which they protrude is made a tight fit, the only other means needed to support them is double sided sticky tape top and bottom of the large diameter end, this being held fast by the lid when this is screwed down. Failing this a nylon nut and bolt and spacer must be used to bolt the buzzer to the printed circuit board.

To make the holes for the panel light and buzzer the following procedure may be adopted. Mark the centre of the hole to be made with a punch, then using a pair of compasses
or dividers mark the outer diameter of the hole, then drill out the centre as big as you can, filing out the plastic carefully to the outer diameter mark using, if possible, a half round file to finish off with, as this gives a much rounder hole.

A word here about marks and scratches on the boxes. These may be cleaned off (if they are not too deep) using the type of cleaner that is advertised as cleaning without scratching, such as Jiff, but many other brands of the same type may be used.

The wires joining the boxes were brought out of the side and front of the boxes and are thus kept out of the way of the contestants and quizmaster so that their hands can rest comfortably on the tables while they are waiting to push their buttons.

The West Hyde boxes specified can be purchased with plastic or metal lids. The plastic type are needed for this application or the buzzers will not fit in the boxes. These enclosures are used because they have a smooth bottom with no moulding marks visible.

Rubber stick-on feet were also used on the boxes to stop the scratching of the polished table tops; they also hide the fixing screws.


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|  |  | 4024 | 40p | 4068 | 13p |
| 4001 | 13p | 4025 | 13p | 4069 | 13p |
| 4002 | 13p | 4026 | 90p | 4070 | 13p |
| 4007 | 13p | 4027 | 28p | 4071 | 13p |
| 4009 | 30p | 4028 | 45p | 4072 | 13p |
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| 4012 | 13p | 4040 | 55p | 4093 | 36p |
| 4013 | 28p | 4041 | 55p | 4510 | 60p |
| 4015 | 50p | 4042 | 550 | 4511 | 60p |
| 4016 | 28p | 4043 | 50p | 4518 | 65p |
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| 7401 | 10p | 7476 | 20p | 74150 | 55p |
| 7402 | 10 p | 7485 | 55p | 74151 | 40p |
| 7404 | 120 | 7486 | 20p | 74154 | 65p |
| 7406 | 22p | 7489 | 135p | 74157 | 40p |
| 7408 | 12 p | 7490 | 25p | 74164 | 55p |
| 7410 | 10p | 7492 | 30p | 74165 | 55p |
| 7413 | 22p | 7493 | 25p | 74170 | 100p |
| 7414 | 39 p | 7494 | 45p | 74174 | 55p |
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| 7430 | 120 | 74121 | 25p | 74191 | 50p |
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| 7442 | $38 p$ | 74123 | 38p | 74193 | 50p |
| 7447 | $45 p$ | 74125 | 35p | 74196 | 50p |
| 7448 | 50 p | 74126 | 35p | 74197 | 50p |
| 7454 | 12 p | 74132 | 45p | 74199 | $90 p$ |
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| LEO's | 0.1 | 5in. 0 |  | each | $100+$ |
| Red | Til | 209 TI | L220 | 9 p | $7.5 p$ |
| Green | TIL | 211 T | L221 | $13 p$ | $12 p$ |
| Yellow | T1L | 213 TI | L223 | 13p | 12p |
| Clips | 3p | 3 p |  |  |  |
| DISPLAYS |  |  |  |  |  |
| DL704 | 0.3 | in CC |  | $130 \rho$ | $120 p$ |
| OL707 | 03 | in CA |  | $130 \rho$ | $120 p$ |
| FND500 | 05 | in CC |  | 1009 | $80 p$ |

## Low profile by Texas

8pin $\quad 8 p \quad 18 p i n \quad 14 p \quad 24 p i n \quad 18 p$ $\begin{array}{llllll}14 p i n & 10 p & 20 p i n & 16 p & 28 p i n & 22 p \\ 16 p i n & 11 p & 22 p i n & 17 p & 40 p i n & 32 \mathrm{p}\end{array}$ 3 lead T018 or T05 socket 100 each Soidercon pins $100 \cdot 50 \mathrm{p} \quad 1000: 370 \mathrm{p}$

## PCBS

Size im. VEROBOARD
$25 \times 1 \quad 14 p$ 14p Cutter $80 p$
$\begin{array}{lll}2.5 \times 3.75 & 45 p & 45 p \\ 25 \times 5 & 54 p & 5 p\end{array}$
$\begin{array}{lrrr}2.5 \times 5 & 54 p & 54 p & \text { Pin } 155 \mu 1 \\ 3.75 \times 5 & 64 p & 64 p & \text { roo } 108 \\ 375 \times 17 & 2050 & 185 p & \end{array}$
$375 \times 17$
Single sided
pinsper $100 \quad 400 \quad 400$
Too quality fibre glass copper board Single
ded Size $203 \times 95 \mathrm{~mm} 60 \mathrm{p}$ wach
Dalo pens 750 each
DESISTORS Carbon film resist
Carbon film resist
ors. High stability ow noise $5 \%$
E12 series. 47 ohms to 10 M . Any mix $\begin{array}{llll}0.25 W & \text { each } & 100 \text { * } & 1000+ \\ 0.090 & 080\end{array}$ $\begin{array}{llll}0.5 \mathrm{~W} & 150 & 12 \mathrm{p} & 10\end{array}$ Special development packs consisting of ohm ( 650 res) $0.5 W £ 7.50 \quad 0.25 \mathrm{~W} £ 5.70$ METAL FILM RESISTORS
Vervhigh stability tow noise rated at $1 / 4 \mathrm{~W}$ Verv high stability. Low noise rated at AW E24 series. Any mix. $\begin{array}{lll}\text { each } & 100+ & 1000\end{array}$


| LNEAR |  | LF356 | 80p | NE531 | $\rho$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | LM301AN | - $26 p$ | NE555 | 23p |
| THIS IS ONLY ASELECTIONI |  | LM308 | 60p | NE556 | 600 |
|  |  | LM318N | 75p | NE567 | 100p |
|  |  | LM324 | 450 | RC4136 | 100p |
| 709 | 35p | LM339 | $45 p$ | SN76477 | 230p |
| 741 | 16p | LM378. | 230p | TBA800 | 70p |
| 747 | 45p | LM379S | $410 p$ | TBA810S | 100p |
| 748 | 30p | LM380 | 75 | TDA1022 | 620p |
| 7106 | 850p | LM3900 | 50p | TL081 | 45p |
| 7107 | 900p | LM3909 | 65p | TL084 | 1250 |
| CA3046 | 55 | LM3911 | 1000 | 2N414 | 80p |
| CA3080 | 70p | MC1458 | 32p | 2N425E | 390p |
| CA3130 | 909 | MM57160 | 590p | 2N103 | 200 |

## TRANSISTORS


$\begin{array}{lllllll} & & \text { BCY } & & 142 & \text { 2N3053 } & 18 p \\ \text { AC127 } & 17 p & \text { BD } 31 & 35 p & \text { 2N3054 } & 50 \mathrm{p}\end{array}$

$\begin{array}{llllll}\text { AC176 } & 180 & \text { BD } 139 & 35 p & \text { 2N3055 } & 50 \rho \\ \text { AN } & \text { AN4 } & 1350\end{array}$
$\begin{array}{llllll}\text { AD161 } & 38 p & \text { BD } 140 & 35 p & \text { 2N3442 } & 135 p \\ \text { AD } & \text { 2N3702 } & 8 p\end{array}$
$\begin{array}{llllll}\text { AD162 } & 38 p & \text { BD140 } & 35 p & \text { 2N3702 } & \text { BFY50 } \\ \text { A } & 15 p & 2 N 3703 & 8\end{array}$
$\begin{array}{llllll}\text { BC107 } & 8 p & \text { BFY51 } & 15 p & 2 N 3704 & 8 p\end{array}$
$\begin{array}{lrllll}\text { BC108 } & 8 p & \text { BFY52 } & 15 p & \text { 2N3705 } & 9 p \\ \text { BC108C } & 10 p & \text { PN }\end{array}$
$\begin{array}{llllll}\text { BC108C } & 10 \mathrm{p} & \text { MJ2955 } & 98 \mathrm{p} & 2 N 3706 & 9 p \\ \text { BC109 } & 8 \mathrm{p} & \mathrm{MPSAOS} & 20 \mathrm{p} & 2 N 3707 & 9 p\end{array}$
$\begin{array}{llllll}\text { BC109C } & 10 \mathrm{p} & \text { MPSA06 } & \text { 20p } & \text { 2N3707 } & 9 \mathrm{p} \\ & 10 & \text { MPSA5 } & 200 & \text { 2N3708 } & 8 \mathrm{p}\end{array}$
$\begin{array}{llllll}\mathrm{BC} 147 & 7 \mathrm{p} & \text { TIP29C } & 60 \mathrm{p} & \text { 2N3B19 } & 15 p\end{array}$
$\begin{array}{lrrrrr}\text { BC148 } & 7 \mathrm{D} & \text { TIP30C } & 70 \mathrm{p} & 2 N 3820 & 44 \mathrm{p} \\ \text { BC177 } & 14 \mathrm{D} & \text { TIP31C } & 65 \mathrm{p} & 2 N 3904 & 8 \mathrm{p}\end{array}$
$\begin{array}{llllll}\text { BC178 } & 14 p & \text { TIP32C } & 80 p & 2 N 3905 & 8 p\end{array}$
$\begin{array}{llllll}\text { BC179 } & 14 p & \text { TIP } 2955 & 65 p & 2 N 3906 & 8 p \\ B C 182 & 10 p & \text { TIP } 3055 & 55 p & 2 N 4058 & 12 p\end{array}$
$\begin{array}{llllll}\text { BC182L } & 10 p & 2 T \times 107 & 14 p & 2 N 5457 & 32 p \\ \text { BC184 } & 10 p & 2 T \times 108 & 14 p & 2 N 5459 & 32 p\end{array}$
$\begin{array}{llllll}\text { BC184 } & 10 p & \text { 2TX108 } & 14 p & \text { 2N5459 } & \text { 32p }\end{array}$
$\begin{array}{lllll}\text { BC212 } & 10 \mathrm{p} & 2 \mathrm{~T} \times 300 \quad 16 \mathrm{p} & 2 \mathrm{~N} 5777 & 50 \mathrm{p}\end{array}$
BC212L 10p
BC2
$\begin{array}{llllll}\text { BC477 } & 19 p & 1 N 914 & 3 p & 1 N 4006 & 6 p\end{array}$
$\begin{array}{llllll}\mathrm{BC} 478 & 19 p & 1 N 4001 & 4 p & 1 N 5401 & 13 p\end{array}$
BC548 10p 1 N4002 $4 \mathrm{n} \quad 82 \mathrm{Y} 88$ ser 8 n
$\begin{array}{lllllllll}\text { BCY71 } & 14 p & \text { 1N4148 } & \mathrm{f} 140 & 00 \mathrm{f} .111000\end{array}$

## CAPACITORS

TANTALUM BEAD
0.1. 0.15, 022, 0 33, 0.47, 068

| $1822 \mathrm{uF} @ 35 \mathrm{~V}$ |
| :--- |
| 4768 O |
| 1 |

$4.7 .68,10 \mathrm{uF} @ 25 \mathrm{~V}$
$22 @ 16 \mathrm{~V}, 47 @ 6 \mathrm{~V}, 100 @ 3 \mathrm{~V}$
$22 @ 16 \mathrm{~V}, 47 @ 6$
MYLAR FILM
$0.001,0.01,0.022,0.033,0047$
0068.0 .1

POLYESTER
Muliard C2BO series
$0.01,0.015,0.022,0.033,0.047,0.068,01.50$
$0.15,022,0.022,0.033 .0 .047,0.068,01.90$ $0.15,022$
033.047
068
CERAMIC
Plate type 50 V . Available in E12 series from
22 pF to 1000 pF and E6 series from 1500 pF t 0047 FF 20
RADIAL LEAD ELECTROLYTIC

| $63 V$ | $0.47 \quad 10$ | 22 | 4.7 | 10 |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  |  |  | 22 | 47 | $\qquad$


|  |  |  | 22 | 33 | 47 | 7 p |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 100 |  |  |  |  | 13p |
|  |  |  | 220 | -... |  | 20p |
| 25 V | 10 | 22 | 33 | 47 |  | 50 |
|  | 100 |  |  |  |  | 8 p |
|  |  | 220 |  |  |  | 100 |
|  |  |  |  | 470 |  | 150 |
|  | 1000 |  |  |  |  | 23p |

## CONNECTORS

JACK PLUGS AND SOCKETS

|  | screened | unscreened | socket |
| :--- | :---: | :---: | :---: |
| 2.5 mm | $9 p$ | $13 p$ | $7 p$ |
| 35 mm | $9 p$ | $14 p$ | $8 p$ |
| Standard | $16 p$ | $30 p$ | $15 p$ |
| Stereo | $23 p$ | $36 p$ | $18 p$ |

DIN PLUGS AND SOCKETS

|  | plug | chassis <br> socket | line <br> sockit |
| :--- | ---: | :---: | :---: |
| 2 pin | $7 p$ | $7 p$ | $7 p$ |
| 3 pin | $11 p$ | $9 p$ | $14 p$ |
| 50 in $180^{\circ}$ | $11 p$ | $10 p$ | $14 p$ |
| 50 in $240^{\circ}$ | $13 p$ | $10 p$ | $16 p$ |

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Suitable for low voltage circuits, Red \& black Plugs. 6p each Sockets: 7p each
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$9 p$
$13 p$ $10 p$

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ANTEX X25 (25W) or ANTEX CX (17W)
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240 p each

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56 mm dia. 8 ohms . $70 \mathrm{p} \quad 64 \mathrm{~mm}$ dia. 64 ohms . 75 p 64 mm dia. 8 ohms . $75 \mathrm{p} \quad 70 \mathrm{~mm}$ dia. 80 hms . 100 p Magnetic earpiece including 2.5 or 3.5 mm plug. 15 p each Crystal earpiece including 3.5 mm plug.

30p each

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Subminiature toggle. SPDT 70p. DPDT 80p Standard toggle. SPST 34p. DPDT 48p.


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Push to make switch. 15p. Push to break switch. 20p.
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Ideal for use on mixers etc. Push on type with black base and marked position line. Cap available in red, blue, green, grey, yellow \& black. 14 p
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Connection cable available in single or stranded packs of eight colours.
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Stranded
40 metre pack 85 p
18p
$80 p$
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Battery clips for PP3 with lead. 6p each
Battery clips for PP9 with lead. 10p each
Miniature crocodile clips in red or black. $8 p$ each.
Red or black probe clips. 20p each.
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n留
T018 push to fit heatsink
$10 p$ each.
T0220 twisted vane heatsink
each
T03 twisted vane sink
20p each. 22p each.

Murata Ultrasonic Transducers. 180p each. 350p pair.

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Quality black ABS boxes by BIM. All dimensions in mm. $100 \times 50 \times 25 \quad 90 p$ each $\quad 150 \times 80 \times 50 \quad 140 \mathrm{p}$ each $120 \times 65 \times 40125$ peach $190 \times 110 \times 60 \quad 220 p$ each

## REGULATORS



78L05 30p 7805 60p 7905 80p $\begin{array}{lllll}78 \mathrm{~L} 12 & 30 \mathrm{p} & 7812 & 60 \mathrm{p} & 791280 \mathrm{p} \\ 78 \mathrm{~L} 15 & 30 \mathrm{p} & 7815 & 60 \mathrm{p} & 7915 \\ 80 \mathrm{p}\end{array}$

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 <br> <br> Plus: INDEX FOR VOLUME 15}
## PRACTICAL




WITH the development of simple chemistry processes for colour film printing, more and more amateurs are trying their hand at producing their own colour prints in the home darkroom.

Once you get into colour processing you quickly realise that the good old days where the enlarger button was held down for a count of ten are gone, due to the higher timing accuracy required.

This project describes a simple enlarger timer, the accuracy of which is not affected by fluctuations in the mains voltage, and which fulfils the need for simple operation, as of course the unit is used in total darkness. No indicators or displays have been incorporated as even the red light from such displays is not "safe" for use with colour photography.

## RANGE

The range of the unit is from 1 to 99 seconds in one second steps but if required the timer can be modified to give a second range of 0.1 to 9.9 seconds in 0.1 second steps.

## CIRCUIT DESCRIPTION

The circuit diagram of the Darkroom Timer is shown in Fig. 1. The power supply uses a standard 7805 regulator
to provide +5 V . It also provides a 9 V a.c. line which is divided by R1 and R2 and clipped by the Zener diode D2 to provide an approximately square 50 Hz input to IC2 (pin 1).

IC2 and IC3 are connected in cascade to divide the 50 Hz input by 50 to produce a 1 Hz standard timing pulse.

This 1 Hz pulse is now fed to the input of the b.c.d. counters IC4 and IC5 which will count up the pulses from 0 to 9 .

As the counters are cascaded the total count available is 99. The b.c.d. outputs from these counters are fed to the 4 to 10 line decoders IC6 and IC7. The outputs of these decoders will remain normally high and an output will go low when the particular code for that output is presented to the i.c.

Thus by using S3 and S4 any number from 0 to 99 can be selected by feeding one of the outputs from the decoders IC6 and IC7 to a NOR gate IC8a, i.e. if the number 56 is selected S3 will look at the 6 output of IC6 and S4 will look at the 5 output of IC7, thus at the number 56 the output from S3 and S4 will be low causing the output of the NOR gate to go high.

The timing sequence is started by closing S2 which resets the counters IC4 and IC5 to zero and also sets the latch formed by the two NOR gates IC8b and IC8c. Once the


Fig. 1. Circuit diagram of the Darkroom Timer


Fig. 2. Printed circuit board design


E6200]
Fig. 3. Component overlay for p.c.b.
COMPONENTS
Resistors
R1,R2
R3
All $5 \% \frac{1}{4} W$ carbon
Capacitors

| C 1 | $1000 \mu 25 \mathrm{~V}$ elect |
| :--- | :--- |
| C 2 | $10 \mu 10 \mathrm{~V}$ elect |
| C 3 | 100 n polyester |

## Somiconductors


Miscellaneous 71
9 V 500 mA min mains transformer
S1, 55
S2
S3.54
SK1
PL1
Case
P.c.b.
Terminal block

Single pole push to make
Thumbwheel switches or two 1 pole 10 way waferswitches Min. 3 way mains socket Min. 3 way mains plug $200 \times 80 \times 130 \mathrm{~mm}$ EG 199 3 way
latch has been set the output turns on TR1 which operates the relay RLA switching on the enlarger lamp.

When the set count is reached the output of IC8a will go high, resetting the latch and switching off the enlarger lamp.


Internal view of the Darkroom Timer

## CONSTRUCTION

The prototype was constructed on a printed circuit board the design of which is shown in Fig. 2 with the component layout shown in Fig. 3. After the p.c.b. has been soldered and checked the board should be mounted into the case and the switches and sockets fitted.

Thumbwheel switches were used for the time selector as they give a quick and easy method of selecting the exposure period and provide an indication of the set time. Alternatively, standard rotary wafer switches could be used to reduce the cost of the unit.

The relay used had a 6 V 700 ohm coil but any relay with a coil voltage of about 4 to 6 volts and a coil resistance of over 200 ohms may be used, provided that the contacts are rated for the load.

## CASE

The unit was housed in a plastic case with an aluminium front panel measuring about $200 \times 80 \times 130 \mathrm{~mm}$ with all the controls mounted on the front panel and a mains input socket and a three way terminal block for the timer output mounted on the back of the case.

## USE

To use the timer once it has been connected up, all that is necessary is to set up the desired time for exposure on the thumbwheel switch and press the "expose" button. The enlarger will then switch on and after the time set has elapsed, switch off.

Resetting is not necessary as the timer is reset when the "expose" button is pressed.

If it is desired to switch on the timer for focusing purposes a "focus" switch (S5) has been provided which by-passes the timer causing the enlarger lamp to stay on indefinitely.

## ADDING ARANGE

A second range of 0.1 to 9.9 seconds in 0.1 second steps could be added by making the modifications shown in Fig. 4.

First, a single pole switch (changeover) is added to facilitate range switching. This switch will select either the output of IC2 (pin 11) or the output of IC3 (pin 11) and switch it to the input of IC4 (pin 14), thus feeding the counter with either 1 Hz or 10 Hz timing pulses.


Fig. 4. Modification for adding a second range
Next, a monostable has to be added in the start circuit to give a narrow pulse when the "expose" switch is closed.

The reason for this is that when the "expose" switch is operated the latch sets immediately, switching on the enlarger lamp, but the counters do noi start to count until the button has been released. Thus if the start switch is held down for 0.3 sec , there would be a timing error of 0.3 sec .

It is of course necessary to break the existing connections between pin 11 on IC3 and pin 14 on IC4.

A suitable monostable circuit is shown using a 74121 integrated circuit.

## THE APHEX SOUND

British patent application $10848 / 77^{\prime}$ in the name of Curt Koppel was filed in the UK in 1977 under the old patent laws and will thus remain secret until accepted, granted and published by the British Patent Office. This will probably not be for a year or so.

The corresponding USA patent 4150253 was, however, recently published in the joint names of Curt Koppel and Inter Technology Exchange Ltd., both of Los Angeles. This patent will be very interesting to anyone who has puzzled over the circuitry which is contained in the Aphex System as used by pop groups to make instrumental sounds, and the human voice, stand out and seem louder without any actual change in amplitude level.
"The formula by which the Aphex device selectively processes the audio signal has been arrived at after considerable research into the mechanisms of the ear", proclaim the Aphex ads. But so far there has been

Copies of Patents can be obtained from : the Patent Office Sales, St. Mary Cray, Orpington, Kent Price 95p each

little hard fact available on how Aphex actually works. The US patent includes block schematics and circuit diagrams with component values, for both valve and transistor designs.

The block diagram shows the source signal amplified and split into two channels. The split signal passes unaffected through one channel to a mixer 20 and in the other channel is fed to an exciter 19 and attenuator 21. The output signal is thus a controllable combination of excited and unexcited signal.

Despite the advertisement claim quoted above, the patent wording admits that "it cannot be said with absolute certainty which specific elements in the exciter circuit 19 perform which function". But empirical tests and the comparison of input and output
waveforms have shown that the exciter functions as a high pass filter, and generates low order, odd and even, phase shifted and amplitude dependent harmonics of the frequencies passed. A linear frequency dependent phase shift of about $360^{\circ}$ is produced over the audio bandwidth with the point of zero phase shift at around 2 kHz . In many respects therefore, the Aphex circult is controllably producing exactly those audio effects which circuit designers normally strive to eradicate.
(Although the British Patent Office does not publish copies of US patent specificalions, the foreign branch of the Patents Library attached to the Chancery Lane Pat ent Office holds a copy of all US specifications and will sell a photocopy at reasonable cost.)

## REAR-VIEW RADAR

Recent UK patent application 2004418 (filed under the new laws) discloses ideas from the Nissan Motor Company of Japan for equipping motor cars with radar sensors to warn the driver of an impending collision. The aim is to offer sensing of danger from either behind or the side or both, for instance when a car is changing lane on a motorway.



The optimum position for providing rear and side radar lookout is that already occupied by the rear-view wing mirrors, so Nissan propose that the mirrors should be combine with microwave reflectors operating in the range 10 GHz to 80 GHz .

As shown in Fig. 1 a conventional microwave transmitter unit 22, including an oscillator such as a Gunn diode and modulator, is installed in the wing mirror post 12 and a wave guide connected to a feeder horn 24. This horn sits at the focal point of parabolic reflector 26 . The reflector 26 is positioned in front of an ordinary wing mirror but the mirror is visible to the motorist because the parabolic reflector is lighttransmissive.

Fig. 2 shows constructions for a light transmissive micro-wave reflector 26 . One side of a curved plate of glass can be coated with a thin (few microns thick) film 30 of metal or of transparent and conductive oxide such as tin oxide. Coating is by vacuum evaporation. Alternatively a matrix of fine metal wires 34 are embedded in a curved plate of transparent glass or plastics.

Fig. 3 shows how the resultant radar lobes cover both the rear and side of the car for lane changing. Presumably Nissan intend incorporating an alarm system which will sound or light up if the driver attempts to change lanes when another vehicle is inside the radar lobes.

##  a selection from our postlbag

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## G3FYQ

Sir-I would like to take this opportunity of writing to you to give you details of the recently reformed "Pontefract \& District Radio Society".

The club was re-formed in May and the Home Office have re-issued the callsign G3FYQ. The meetings are held fortnightly at Knottingley Town Hall starting at 7.30 pm .
The programme of future meetings is:-
Oct. 18th. Slow Scan Television by G41BN/G4FBA.
Nov. 1st. Film Night.
Nov. 15th. Oscar Satellite Operating by Jack Ward, G4JJ.
Nov. 29th. David Tong, of Datong Electronics on the Up/Down Convertor.

Dec. 13th. Social Evening-venue to be announced

Further details can be obtained from address
below or telephone Pontefract 71071. All new members will be most welcome.

Phil N. Butterfield, G4AAQ, R.S.G.B. Area Representative,

Club Chairman
43, Lynwood Crescent
Pontefract
WF8 3QT,
West Yorkshire

## VLF Signals

Sir-I was very interested to read the article 'VLF Signals and the Magnetosphere' by C. R. Francis in your September, 1979 edition. I have been interested in this particular part of the electromagnetic spectrum for some time now, as a project with my sixth formers and we have amassed quite a lot of practical experience, much of the time using simple
receiving equipment
We would be very pleased if, through your columns, we could ask for other schools or individuals interested in VLF work and especially in Whistlers, to write to me at the address below, preferably enclosing a stamped addressed envelope. We could then share our knowledge, and even better, make simultaneous recordings of VLF phenomena. There is considerable scientific value in such co-operative work. Such co-operators need not have any prior experience.
You may be interested to know that we at Mayfield are supported in our work by the Royal Society, who have special arrangements for giving financial grants to schools doing research, and such help would be considered very favourably for any schools willing to join our investigations.
H. James, Head of Physics, Mayfield School, Mayfield Road, North End, Portsmouth, PO2 0RH.

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| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
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| HY50 | 30 W <br> into 8 | $0.02 \%$ | 90 dB | $-25-0-+25$ | $105 \times 50 \times 25$ | 155 | $£ 7.24$ <br> $+£ 1.09$ |
| HY120 | 60 W <br> into 8 $\Omega$ | $0.01 \%$ | 100 dB | $-35-0-+35$ | $114 \times 50 \times 85$ | 575 | $£ 15.20$ <br> $+£ 2.28$ |
| HY200 | 120 W <br> into 8 $\Omega$ | $0.01 \%$ | 100 dB | $-45-0-+45$ | $114 \times 50 \times 85$ | 575 | $£ 18.44$ <br> $+£ 2.77$ |
| HY400 | 240 W <br> into 4 $\Omega$ | $0.01 \%$ | 100 dB | $-45-0-+45$ | $114 \times 100 \times 85$ | 1.15 Kg | $£ 27.68$ <br> $+£ 4.15$ |

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E 5.50 $\begin{array}{ll}\text { L5.1 Listing listing of } 1.5 \mathrm{k} \text { monitor and } 2.5 \mathrm{k} \text { basic } & \mathbf{E 5 . 5 0} \\ \mathrm{L6} \cdot 1 \text { User documentation on } 7 \mathrm{k} \text { basic interpreter } & \mathbf{E 1 . 8 0}\end{array}$ $\begin{array}{ll}\text { L6. } 1 \text { User documentation on } 7 \mathrm{k} \text { basic interpreter } & \mathbf{8 1 . 8 0} \\ \text { Motherboard, 8k Ram and } 8 \mathrm{k} \text { Eprom constructional details } & \mathbf{8 5 . 0 0}\end{array}$ User group newsletter subscription $\mathbf{£ 4}$ per annum. Triton software send SAE for list of programs available for Triton.

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| AAA17 | 0.31 | BD 121 | 1.38 | NKT403 | 1.99 | 1 N 4004 | 0.08 | 7410 | 0.18 |
| AC 107 | 0.69 | 80123 | 1.38 | NKT404 | 1.99 | 1 N 4005 | 0.09 | 7412 | 0.30 |
| AC125 | 0.23 | 88124 | 1.50 | OA5 | 0.09 | i N 4006 | 0.09 | 7413 | 0.37 |
| ${ }^{\text {AC }} 126$ | 0.23 | BD131 | 0.40 | $\mathrm{OAF}^{0}$ | 0.63 0.74 | 1N4007 | 0.10 | 7416 | 0.37 |
| AC127 | 0.23 0.23 | BD 132 80135 | 0.44 | OA10 | 0.74 0.16 | 1 N 4009 | 0.17 | 7417 | 0.37 |
| ${ }_{\text {AC }}{ }^{\text {A }} 1$ | 0.29 | BD136 | 0.39 | OA470 | 0.35 | 1N4 1488 | 0.07 | 7420 | 0.20 0.23 |
| ${ }^{\text {AC }} 141 \mathrm{~K}$ | 0.40 | BD137 | 0.40 | OA79 | 0.35 | 1 N 5401 | 0.15 | 7423 | 0.37 |
|  | 0.23 | 8D138 | 0.46 | OA81 | 0.36 | 1544 | 0.05 | 7425 | 0.35 |
| $\begin{aligned} & A C 142 \mathrm{~K} \\ & \text { AC176 } \end{aligned}$ | 0.35 | 80139 | 0.49 | OA85 | 0.35 | 15920 | 0.08 | 7427 | 0.35 |
| ${ }_{\text {AC }} 187$ | 0.23 | BD144 | 0.51 2.30 | OA90 | 0.09 | 15921 | 0.0 | 7428 | 0.49 |
| AC 188 | 0.23 | ${ }_{\text {BD } 181}$ | 1.26 | 0 OA95 | 0.09 | 2G302 | 1.15 | 7430 | 0.20 0.35 |
| $\mathrm{ACY}^{17}$ | 0.98 | 80182 | 1.36 | OA200 | 0.10 | 2G306 | 1.27 | 7433 | 0.41 |
| ACY18 | 0.92 | 8 B 237 | 0.46 | OA202 | 0.10 | 2N404 | 1.15 | 7437 | 0.37 |
| ${ }^{\text {ACY }} 19$ | 0.86 | BD238 | 0.63 | OA21 | 1.15 | 2 N696 | 0.29 | 7438 | 0.37 |
| $\mathrm{ACY}^{\text {cho }}$ | 0.80 | $80 \times 10$ | 1.05 | OAZ200 | 1.15 | 2N697 | 0.29 | 7440 | 0.21 |
| ACY21 | 0.86 7.72 | $80 \times 32$ | 2.30 | OAZ201 | 1.15 | 2N698 | 0.35 | 7441 A | 0.97 |
| AD149 | 0.80 | 80Y60 | 1.72 | ${ }_{\text {OAZ206 }}$ | 1.15 | 2N705 | 1.38 | 7442 | 0.83 |
| AD16 | 0.52 | BF115 | 0.29 | ${ }_{0} \mathrm{Cl} 16$ | 2.30 | 2N708 |  | 7447 7450 | 1.04 |
| AD162 | 0.52 | BF152 | 0.21 | 0 O 20 | 2.88 | 2 N 930 | 0.23 | 7451 | 0.21 |
| AF 10 | 0.52 | BF153 | 0.23 | $\mathrm{O}^{\mathrm{O}} 22$ | 2.88 | $2{ }^{\text {N1 }} 131$ | 0.30 | 7453 | 0.21 |
| AF1 14 | 0.86 | $8 F 154$ | 0.20 | $\mathrm{OC}^{\text {c }}$ | 3.16 | 2 N 1132 | 0.30 | 7454 | 0.21 |
| AF115 | 0.86 | BF159 | 0.26 | $\mathrm{OC}^{\mathrm{C}} 4$ | 3.45 | 2 N 1302 | 0.40 | 7460 | 0.21 |
| AF116 | 0.86 | BF160 | 0.18 | 0 O 25 | 1.04 | 2N1303 | $0 \cdot 40$ |  | 0.40 |
| AF117 | 0.86 | BF167 8 F 173 | 0.23 | $\mathrm{OC}^{\circ} 26$ | 1.04 2.30 | 2 N 1304 | 0.52 | 7472 |  |
| AF186 | 1.38 | BF177 | ${ }_{0}^{0.28}$ | 0 O 29 | 2.30 $\mathbf{2} 3$ | 2N130 | 0.58 | 7473 | 0.41 |
| AF239 | 0.52 |  | 0.28 | $\mathrm{OC}^{\circ} \mathrm{S}$ | 1.73 | 2N1307 | 0.58 | 7475 | 0.62 |
| AFZ11 | 3.16 3.16 | 8 F 179 | 0.29 | $\mathrm{OC}^{\text {Of }}$ | 1.73 | 2 N 1308 | 0.63 | 7476 | 0.46 |
| $\begin{aligned} & \text { AFZ12 } \\ & \text { ASY2 } \end{aligned}$ | 3.16 0.46 | BF180 | 0.35 | OC41 | 0.92 | 2N13 | 0.63 | 7480 | . 63 |
| ASY27 | 0.46 | BF | 0.35 | ${ }_{0} \mathrm{C} 43$ | . 86 | 2N16 | $0 \cdot 79$ | 7482 | . 86 |
| ASZ15 | 1.44 | BF183 | 0.29 | 0 O 44 | 0.69 | 2 N 18 | 0.29 | 74 | 1.15 |
| ASZ16 | 1.44 | BF184 | 0.29 | 0 O 45 | 0.63 | 2N2147 | 2.02 | 7486 | 0.40 |
| ASZ17 | 1.44 | BF185 | 0.29 | 0 O 71 | 0.63 | 2N2148 | 1.89 | 7490 | 0.60 |
| ASZ20 | 1.72 | BF194 | 0.10 | OC72 | 0.63 | 2N2218 | 0.29 | 7491 AN | 0.92 |
| ASZ21 | 2.30 2.30 | 8F195 | 0.10 | Oc73 | 1.15 | 2 N 2219 | 0.28 | 7492 | 0.69 |
| AUI 13 | 1.96 | BF 197 | 0.14 | OC75 | 0.74 0.74 | 2N2220 | 0.21 | 7493 | 0.69 |
| AUY10 | 2.30 | BF200 | 0.31 | $0{ }^{\circ} 76$ | 0.63 | 2N2222 | 0.21 | 7495 | 0.83 |
| BA145 | 0.15 | BF224 | 0.23 | 0 C 77 | 1.38 | 2N2223 | 3.16 | 7496 | 0.92 |
| BA148 | 0.15 | BF244 | 0.32 | 0 O 81 | 0.74 | 2 N 236 | 0.20 | 7494 | 3.45 |
| 8A154 | 0.10 0.12 | BF257 | 0.28 0.30 | $\mathrm{OCBl}^{0}$ | 1.38 0.74 | 2N2369A | 0.24 | 74100 | 1.73 |
| 8 A156 | 0.10 | BF259 | 0.37 | ${ }^{0} \mathrm{CB3}$ | ${ }_{0}^{0.74}$ | 2 N 26 | 0.23 0.63 | 741 | 0.52 |
| BAW62 | 0.06 | BF336 | 0.35 | $0 \mathrm{CB4}$ | 0.74 | 2N29 | 0.29 | 74109 | 0.81 |
| BAX1 | 0.07 | BF3 | 0.35 | 0 C 122 | 1.73 | 2 N 2905 | 0.29 | 74111 | 0.81 |
| 8 8AX 1 | 0.10 | BF338 | 0.36 | OC123 | 2.02 | 2 N 2906 | 0.24 |  | 2.02 |
| BC107 | 0.14 | BFS2 | 4.55 | OC139 | 2.59 | 2 N 2 | 0.24 | 74118 | 1.15 |
| BC108 | 0.14 | BFS28 | 2.56 | OC140 | 3.16 | 2N2924 | 0.24 | 741 | 1.73 |
| BC109 | 0.15 | BFS61 | 0.23 | OC141 | 3.74 | 2 N 2925 | 0.25 | 741 | 0.95 |
| $8 \mathrm{BC113}$ | 0.14 | 8FS98 | 0.23 | OC170 | 1.15 |  | 0.1 | 74121 | 46 |
| BC114 | 0.15 | 陦W10 | 0.74 | $\mathrm{OCL}^{171}$ | 1.15 | 2 N 3053 | 0.29 | 74122 | 0.69 |
| BC115 | 0.16 | BFW11 | 0.74 | OC200 | 1.73 | 2 N 3054 | 0.58 | 74123 | 1.15 |
| ${ }_{8}^{8 C 116}$ | 0.17 | BFX84 | 0.25 | OC201 | 2.02 | 2 N 3055 | 0.81 | 74125 | 0.63 |
| BC1 BC1 18 | 0.20 0.12 | BFX85 BFX87 c | 0.26 0.24 | $\mathrm{OC2O2}$ OC 203 | 2.02 2.02 | 2N3440 | 0.69 | 74128 | 0.63 |
| BC125 | 0.18 | BFX8B | 0.24 | OC204 | 2.88 2 | 2N3441 | 1.26 | 741 | 0.69 0.81 |
| BC1 | 0.23 | BFY50 | 0.30 | 0 O | 2.88 |  |  | 74132 | 0.81 |
| BC135 | 0.16 | BFY51 | 0.30 | OC206 | 2.88 | 2N36 | 1.73 | 74141 | 0.92 |
| BC136 | 0.17 | 8FY52 | 0.30 0.30 | $\mathrm{OC2O}^{0}$ | 2.02 | 2 N 3702 | 0.13 | 74142 | $2 \cdot 65$ |
|  | 0.10 | ${ }_{\text {BFY }}$ | 1.44 | ORP12 | 1.44 | 2 N 3703 | 0.15 | 74143 | 2.88 |
| 8 C 148 | 0.09 | BSX 19 | 0.24 | R20088 | 2.02 | 2N3704 | 0.15 | 74144 | 2.88 |
| BC149 | 0.10 | BS×20 | 0.23 | R2009 | 2.59 | 2N3706 | 0.15 | 74145 |  |
| BC157 | 0.10 | BSX21 | 0.23 | R2010日 | 2.02 | 2 N 3707 | 0.15 | 74148 | 2.02 |
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|  | 0.17 | BY127 | 0.19 | T1P33A | 0.79 | 2 N 3819 | 0.4 | 74170 | 2.65 |
| ${ }^{8 C 178}$ | 0.16 | ${ }_{\text {Series }}$ | 0.21 | T1P34A | 0.84 | 2 N 3820 | 0.52 | 74172 |  |
| $\mathrm{BC1}^{82}$ | 0.13 | BZY88 | 0.15 | T1P42A | 0.82 | 2N3823 | 0.63 | 74173 | 1.61 |
| BC183 | 0.12 | Series |  | T1P2955 | 0.77 | 2N3904 | 0.15 | 74175 | 1.04 |
| BC184 | 0.13 |  |  | T1P3055 | 0.64 | 2N3905 | 0.15 | 74176 | 1.26 |
| $8 \mathrm{CC212}$ | 0.15 | CRS $1 / 40$ | 0.69 | T1543 | 0.52 | 2 N 3906 | 0.15 | 74178 | 1.44 |
| BC2 13 | 0.14 | CRS3/40 | 0.86 1.04 | zS140 | 0.29 | 2N4058 | 0.16 | 74179 | 1.44 |
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| BC301 | 0.29 | G3M | 0.86 | ZS278 | 0.65 | 2N4062 | 0.15 | 74192 | 1.55 |
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| $8 \mathrm{BC307}$ | 0.12 | GL7M | 0.86 | 2TX108 | 0.12 | 2N4126 | 0.17 | 74194 | 1.44 |
| BC308 | 0.12 | GMO378A | 2.52 | 27x109 | 0.14 | 2N4286 | 0.23 | 74195 | 1.15 |
| ${ }^{8} \mathrm{BC} 327$ | 0.23 0.21 | KS100A | 0.52 0.92 | 2Tx300 | 0.14 | 2N428B | 0.25 | 74196 | 1.38 |
| BC337 | 0.21 | MJE340 | 1.35 | $\begin{array}{r}\text { ZTX } \\ \text { ZTX } \\ \hline 10201\end{array}$ | 0.15 0.17 | 2N4289 | 0.28 0.40 | 74197 | 1.26 |
| BC338 | 0.20 | MJE371 | 0.71 | 21×303 | 0.20 | $2 N 5458$ | 0.40 | 74198 | 2.69 |
| $\mathrm{BCY}^{\mathrm{BCH}} \mathbf{}$ | 1.15 | MJE520 | 0.60 0.63 | 21 $\times 304$ | 0.22 | 2N5459 0.40 |  | 76013N 2.02 |  |
| ${ }_{\text {BCY }}$ | 1.15 | MJE521 | 1.44 | $\begin{array}{r}\text { 2T } \times 311 \\ \hline T \times 314\end{array}$ | 0.14 |  |  |  |  |
| BCY33 | 1.04 | MJE3055 | 0.86 | - | 0.23 | INTEGRATED |  |  |  |
| BCY34 | 1.04 | MPF102 | 0.35 | 2TX501 | 0.16 |  |  |  |  |
| BCY39 | 3.45 | MPF 103 | 0.35 | 21 $\times 502$ | 0.18 | 7400 | 0.18 |  |  |
| ${ }_{8 C Y}{ }_{8 C Y}$ | 1.15 0.29 | MPF104 | 0.35 | 2TX503 | 0.20 | 7401 | 0.18 | Plugs in socket - low profile <br> $\begin{array}{ll}8 \text { pin DIL } & 0.17 \\ 14 \text { pin DIL } & 0.17\end{array}$ <br> 16 pin DIL 0.20 |  |
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