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Internally the HY40 is based on conventional and proven circuit techniques developed over recent years.


OUTPUT POWER British Rating 40 WATTS PEAK, 20 watts RMS continuous.
LOAD IMPEDANCE 4-16 ohms INPUT IMPEDANCE 22Kohms at 1 Khz .
INPUT SENSITIVITY 300 mV for maximum output.
VOLTAGE GAIN 30 db at 1 KHz . FREQUENCY RESPONSE 5 Hz $60 \mathrm{KHz}+1 \mathrm{db}$.
TOTAL DISTORTION less than $1 \%$ (typical $0.1 \%$ ) at afl output powers.
SUPPLY VOLTAGE $\pm 22.5$ volts D.C.
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PRICE: including comprehensive manual, P.C. Board and FIVE EXTRA COMPONENTS:
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Specifically and critically designed to meet exacting $\mathrm{Hi}-\mathrm{Fi}$ standards, the HY5 combines extremely low noise with a high overload capability. When used in conjunction with the HY40 and PSU45 forms a completely integrated system.

## INPUTS

Maqnetic Pick-up (within $\pm 1$ db RIAA curve) 2 mV
Tape Replay fexternal components to suit head). 4 mV .
Microphone (flat) 10 mV
Ceramic Pick-up fequalized and compensatable) $2 \mathrm{C}-2000 \mathrm{mV}$ variable.
Tuner (flat) 250 mV .
Auxiliary 1250 mV .
Auxiliary $22-20 \mathrm{mV}$.
OUTPUTS
Main Pre-amp output 500 mV
Direct tape output 120 mV
ACTIVE TONE CONTROLS
Treble $\pm 12 \mathrm{db}$.
Bass $\mp 12 \mathrm{db}$.
INTERNAL STABILIZATION Enables the HY5 to share an unregulated supply with the Power Amplifier.
SUPPLY VOLTAGE
15-25 volt.
SUPPLY CURRENT
5 mA approx.
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better than 28 db on most sensitive input infinite on tuner and auxl.
OUTPUT NOISE VOLTAGE
0.5 mV .

PRICE
Mono $£ \mathbf{£ 6 0} \quad$ Stereo $£ \mathbf{£ 7} \mathbf{- 2 0}$

POWER SUPPLY PSU45


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| 0.80 | Q15 | . 2 N29:2 sil. epoxy trans. | 0.60 |
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|  | Q2: | $\because 0$ NKT trans. A.F. R.F. coded | 0.50 |
|  | Q23 | 10 OA202 sil, dlodes sub-ruin. | 0.50 |
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|  | Q31 | ti Sil. 8witch trans. 2 N 708 NPN | 0 |
| $50$ | Q32 |  | 0.50 |
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| 0.50 | Q34 | 7 sil. NPN trans. $2 \mathrm{~N} 2369,500 \mathrm{MHZ}$. | 0.50 |
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| :---: | :---: | :---: |
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| To.J | 8 | High Gairs OP Amp |
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& 40 \mathrm{p} \\
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& 40 p \\
& 45 \mathrm{p}
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| :---: | :---: |
| 07 | 10 |
| 20 | 1 |
| 11 |  |

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$\begin{array}{lll}z & 7 \times 6 \times 6.5 \\ 11 & 10.2 \times 8.9 \times 8.3 \\ 4 & 9.5 \times 12.7 \times 11.1 \\ 0 & 17.1 \times 11.4 \times 15.9 \\ 0 & 17.8 \times 17.1 \times 21.6 \\ 0 & 24.1 \times 21.6 \times 15.2 \\ 0 & 21.6 \times 21.6 \times 20.3\end{array}$

| (Watts) | 16 | oz |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 20 | 1 | 11 | $7 \times 6 \times 6.5$ |
| 100 | 5 | 12 | $10.2 \times 8.9 \times 8.3$ |
| 250 | 12 | 4 | $9.5 \times 12.7 \times 11.1$ |
| 500 | 27 | 0 | $17.1 \times 11.4 \times 15.9$ |
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| 220pF | 500 V | Cer. | 5 p | $0.033 \mu \mathrm{~F}$ | 400V | Poly. | $4 p$ |
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| 330 pF | 125 V | P.S. | 5 p | $0.047 \mu \mathrm{~F}$ | 400 V | Poly. | ${ }_{8}{ }^{\text {P }}$ |
| 330pF | 500 V | S/M | 8 p | 0.047, F | 500 V | Paper | 8p |
| 390 pF | 500 V | S/M | 8 p | $0.047 \mu \mathrm{~F}$ | 1.000 V | MDC | 10p |
| 470pF | 125 V | P.S. | 5 p | $0 \cdot 1 \mu \mathrm{~F}$ | 30 V | Dise | 6p |
| 470pF | 750 V | Disc | 5 p | $0.1 \mu \mathrm{~F}$ | 250 V | M.F. | 4p |
| 500pF | 500 V | S/M | 8 p | $0.1 \mu \mathrm{~F}$ | 400 V | Poly. | 5p |
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| $0.001 \mu \mathrm{~F}$ | 500 V | Cer. | 5p | $0.47 \mu \mathrm{~F}$ | 250 V | M.F. | 8 P |
| $0.001 \mu \mathrm{~F}$ | 1,000V | MDC | 6 p | $0.47 \mu \mathrm{~F}$ | 400 V | Foil | 15p |
| $0.0015 \mu \mathrm{~F}$ | 400 V | Poly. | 3p | 0.47 $\mu \mathrm{F}$ | 1.000 V | MDC | 20p |
| $0.0015 \mu \mathrm{~F}$ | 500 V | $S / M$ | 10 p | $1 \cdot 0 \mu \mathrm{~F}$ | 250 V | M.F. | 15p |
| $0.0015 \mu \mathrm{~F}$ | 500 V | Cer. | 5p |  |  |  |  |
| $0.0018 \mu \mathrm{~F}$ | 500 V | S/M | 10 p |  |  |  |  |
| $0.002 \mu \mathrm{~F}$ | 100 V | Mylar | 3p | Nore: S/M | = silve | mica | \%tol. |
| $0.002 \mu \mathrm{~F}$ | 500 V | Cer. | 5p | P. | = poly | yrene | 2\%tol. |
| $0.0022 \mu \mathrm{~F}$ | 125 V | P.S. | 6p | M | C - a.c. | rating | $=300 \mathrm{~V}$. |
| $0.0022 \mu \mathrm{~F}$ | 500 V | S/M | 10 p | M | = Mul | ard min | fail. |
| $0.0022 \mu \mathrm{~F}$ | $1,000 \mathrm{~V}$ | MDC | 6 p |  | . $=$ cer | mic. |  |

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## IN CHARACTER

THE requirement for direct readout of data at high operating speeds from a variety of equipments ranging from large computers to pocket size calculators, and from process counters to digital voltmeters, has provoked intense development work into opto-electronic devices. This month we commence an important new series dealing with alpha and numeric displays intended for such purposes.

The present day range of such devices is particularly interesting in that it includes representative examples based on all three traditional electronic processes: the glow discharge in a gas filled tube, the incandescent filament in a vacuum tube, and now the semiconductor light emitting diode. (An interesting parallel to the course of development of those fundamental active devices, the valve and semiconductor.) As for the future, this holds promise of further advancement in the form of plasma panels and liquid crystals. What has become known as optoelectronics is now perhaps the most important new frontier of advancing electronic technology.

Regarding character representation, it seems there often has to be a compromise between style and technical possibility. This is especially true in the case of the latest kind of display devices designed to operate from low voltage lines and to be driven directly from an i.c. Some ingenious arrangements have been devised in order to provide easily recognisable characters which are sufficiently bright for viewing under normal lighting conditions. But in the process, technical limitations have wrought some havoc with the graceful curved roman characters which have been long in general literary use. The resulting severely angular characters are less pleasing in an aesthetic sense, but as more and more digital instruments come into everyday use their general acceptance seems assured.

Maybe the ousting of the elegant cursive letter is somehow appropriate, in view of the reduced part now played by varying-amplitude sinusoidal waveforms. Sharp bursts of current are the prime movers in today's high speed circuits; and pulses are well typified by those partially dismembered characters built up from discrete spots or bars of light.

Sad but true, cursive copperplate writing, however beautiful to look at, belongs to the leisurely past; austere functional characters are the handwriting of this vigorous (some might say vicious) data acquiring and consuming age. If an artist had been commissioned to envoke the visual significance of digital techniques he could hardly have bettered this character style brought about through technical expedience and necessity. F.E.B.

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## SPECIAL SUPPLEMENT

PICKUPS AND TURNTABLES

Our April issue will be published on<br>Friday, March 10.

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ПIPHA

## By R.U.Coles

THE growth explosion in the electronic handling of numerical data has brought with it a great demand for simple systems to display the processed data in a readily understandable form for human interpretation. Electronic data handling in this context is a loose term which covers a wide variety of equipment from the mighty computer to the humble batch counter or digital clock, all of which have nced of a means of interfacing their data with people.
Amateur enthusiasts will have little need of the print-out facilities of the larger computers, some of which can print the results of their deliberations at the rate of several pages per second, but there is an increasing amateur application area for simple "Nixie" type displays for use in counters, measuring instruments, and, of course, clocks and calculators.

Alpha-numeric display devices available, or potentially available, to the amateur market are appearing in bewildering profusion, and now seems a good time to review the operation and application of the most useful types, along with some ideas on how to use them in complete display systems.

Six figure, seven segment L.E.D. display. Ferranti


Seven segment, L.E.D. display. Litronix (Guest International Ltd.)


Seven segment, filament indicator. Minitron, type 3015F (A. Marshall \& Son)

Cold cathode, neon filled numerical indicator Mullard, type ZM1020


Cold cathode, neon filled character indicator. Mullard, type ZM1263

Cold cathode, neon filled character indicator. Mullard

Seven segment, luminescent filament indicator. Atron (West Hyde Developments Ltd.)
(U.K. suppliers are shown in brackets)

## DATA FORMATS

There are quite a large number of technologies employed to form the heart of display devices: cold cathode tubes, incandescent filaments, fluorescent phosphors, gallium arsenide light emitting diodes (L.E.D.s), being but a few examples. Before looking into the operation of these various displays it is as well to look at the data formats available, as these are common to all device technologies.

Every type of readout is based on one of threc basic data formats, the particular form employed being governed mainly by the variety of data to be displayed, the simpler types handling only the numerals, and generally costing less in consequence.

## DISCRETE CHARACTERS

The simplest format available, and the one which potentially gives the most pleasing and casy to interpret display, employs a separate character for each display option. The character set to be displayed is "stored" in the device during manufacture. and may take the form of a set of shaped wire cathodes in a "Nixie" tube, or a set of tiny photographic transparencies to be projected onto a screen by an incandescent lamp in another type of indicator. In either case, a separate character is used for each symbol. The word symbol is used because with this system a device can be produced to display any type of alphabetic, numeric, or symbolic character, in any type of style, limited only by the designer's imagination.

While the flexibility and readability of this format are both excellent. in a practical device vocabulary is rather limited due to the space required to store the separate symbols, and for this reason this format is used only when a comparatively small repertoire is required, 0 to 9 , plus and minus or $\mathrm{kHz} / \mathrm{MHz}$ for example.

## DOT MATRIX

By constructing a display device from a matrix of dots, which may be individually illuminated if required, a very versatile indicator is formed which does not have a limited repertoire like the discrete character type.

A dot matrix can be built from separate filament lamps, light emitting diodes, gas discharges. and others, and though the readability is perhaps slightly worse than the discrete types, the wide variety of characters which can be handled by each device more than compensates.

Fig. 1.1 shows 36 characters of the A.S.C.I.I. (American Standard Code for Intormation Interface) code, which can be displayed on a group of 35 dots arranged as a $7 \times 5$ matrix. A single plane readout with such an impressive character capability can be used to handle even the most sophisticated display tasks but the crunch comes with the decoding and driving electronics required to handle the matrix.

Taking the A.S.C.I.I. code as an example, each character is defined by a six bit binary word, and it is necessary to decode this information to a form which is suitable for driving the matrix directly, for example, telling the display to light up all of rows 3 and 5 to form an equals sign. In a nutshell, the decoder has to decode the binary code to its one-ol-sixty-four decimal equivalent, which is then used to determine the state of each of 35 dots. In these days of M.O.S. large scale integrated circuits this is not such a difficult or expensive task as it may appear at first sight.

## BAR MATRIX

The two formats discussed so far represent opposite extremes of display versatility, and for some applications it is handy to have a system which bridges the gap between the two. This compromise is available in the form of bar matrix displays, which are obtainable with varying degrees of complexity, and hence a wide range of repertoires.

The simplest bar matrix display format is the "seven segment" type, which handles all the numerals, nine letters, and one or two symbols. This type of readout is competitive with the discrete


Fig. 1.1. The alphabetic and numeric characters available in the A.S.C.I.I. code from a $7 \times 5$ dot matrix


Some of the shapes and sizes of commercially available cold cathode tubes
character type, and is likely to prove more popular in the long run. Already seven segment displays are obtainable in incandescent, fluorescent, and L.E.D. technologies, and decoding/driving i.c.s are becoming very cheap, a definite area to watch for practical amateur requirements of the future.

Fig. 1.2 shows the "seven segment" format, and as can be seen, it is based on a stylised figure of eight made from seven individually illuminated bars. The character set available is quite extensive considering the simplicity of the format, though in general these devices are used only for numeric data. decoders being available for this task. The most obvious drawback of this system is that the characters are highly stylised, and not as we would normally write them, a problem which can be eased to some extent by using zero suppression to enhance readability of multi-digit arrays. We will be looking at the way zero suppression is achieved later on.

To overcome readability problems of the basic seven segment indicator, a version using a different bar format has been developed, and this type is shown in Fig. 1.3. To achicve this some of the versatility of the simple version is lost, and some may consider the numerals a bit "wonky" but in use this version gives a very easy to read display whilst retaining the simplicity of the parallel bar type, decoding being of the same nature.



Fig. 1.3. A modified seven segment display giving greater readability but no alphabetic characters

By increasing the number of bars used it is possible to build a device which will handle all the alphabet characters as well as the numerals, and in Fig. 1.4 a possible format using 14 separate bars is shown with its character set (several types of symbol or punctuation mark are also possible). With so many bars as this, the decoding/driving problem again rears its ugly head, resort being made to either M.O.S. arrays or to complex discrete gate decoders.

As we have seen, formats are available to readout manufacturers to enable them to produce a device at the right price and complexity to suit every application. Most of the technologies used can be incorporated into several of the formats, a situation which leads to the present (and very desirable) state where there are literally hundreds of devices to choose from.

## COLD CATHODE DISPLAYS

Perhaps the most well-known type of alphanumeric display and one which has been featured in


Two cold cathode character indicator tubes


Fig. 1.4. Multi-segment display showing how numeric and all alphabetic characters can be generated


Fig. 1.5. Internal construction of a side-viewing cold-cathode numeric indicator tube


A top-viewing cold cathode tube


Fig. 1.6. Calculation of the limiting resistor and power supply
several articles in this magazine in the past, is the cold cathode numerical indicator tube called variously "Nixies". "Numicators" and "Numbertrons". These tubes use the same principle of operation as standard neon indicator jamps, that is the ionisation of neon gas by the application of a suitable voltage across them.

The standard type consist of a number of discrete character shaped cathodes, mounted one behind the other, viewed through a metal grid which forms the anode, all contained in a neon filled glass envelope similar to that used for valves. (Fig. 1.5). The cathodes are insulated from one another and spaced as closely as possible to make a compact assembly with a reasonable field of view.

In operation the anode is connected to a high positive voltage through a current limiting resistor. and the required cathode is grounded by the driving circuitry (which may consist of relays, valves, transistors or an i.c.). The voltage developed across the anode-cathode system causes the neon gas to ionise, and with careful physical design a uniform glow is produced round the cathode selected.

The glow colour is a mixture of blue and orange, and if the tube is used without a colour filter reflections from the other cathodes and the anode produce a rather indistinct blurred display. With a red filter positioned in front of the tube, either as an envelope lacquer or a window material common to several digits, background glow can be cut out completely, producing a very pleasing readout. The anode voltage required is not critical, in fact the higher the better, but there is a lower limit set at about 180 to 200 V below which some tubes will be very slow to ionise, and more difficult to control.

## DRIVING CIRCUITRY

To consider the operation of these tubes in a simple circuit see Fig. 1.6. When the selected cathode is grounded by means of the switch the tube will strike, illuminating the required character. When the neon gas is ionised a current flows through it, limited
by the resistor $R_{: 1}$ and the voltage across the tube necessary to maintain conduction. If the anode voltage could fall below the maintaining value then conduction would ceatse, reducing the voltage drop across $R_{\text {: }}$ and causing the tube to strike again, in a sort of feedback action.

The operating conditions of the tube are thus set by the resistor $R_{i,}$, and the value required can cither be calculated precisely from manufacturers' data sheets, or in the absence of such information a very rough rule of thumb which suffices for the large majority of applications, can be employed. A good average value of operating current for these devices is 2 mA , this is the first assumption necessary to use the rule of thumb, and modifications to this figure can be made if desired on the grounds that a big tube will work better with a larger value, and a small one with less.

The next assumption needed concerns the anode to cathode maintaining voltage which will be present across the tube when it is struck, and a useful guess here is 150 V . Using these two figures and the known value of the H.T. voltage ( $V$ ) to be used, the resistor value can be calculated thus:

$$
R_{\mathrm{a}}=\frac{\text { H.T. voltage }- \text { maintaining voltage }}{\text { cathode current }}
$$

Using the values mentioned above this works out as

$$
R_{\mathfrak{a}}=-\frac{200-}{2}-\frac{150}{2} \text { kilohms, }
$$

giving a value of 25 kilohms for $R_{i}$, and this is likely to be adequate for most medium sized tubes. and is within a few kilohms of the values worked out from extensive calculations dealing with particular. coded tubes. It should be stressed here that if data is available it is far better to perform the calculations which take into account manufacturing spreads, tube individualities, and the bias on other cathodes, but if data is not available (ats so of ten is the amateur's lot) the rule of thumb will get those tubes burning regardless.


Fig. 1.7. Construction of a dot matrix neon-filled cold cathode tube


A Mullard "Pandicon" fourteen numeral cold cathode tube

## OTHER COLD CATHODE FORMATS

The standard Nixie is not the only format used with the cold cathode technology, and both bar and dot matrix versions are available. The bar types have cathodes which form the segments of the format, and operate in a similar fashion to the standard neon tube, identical supply voltages and drivers being required.

The dot type display uses a somewhat different physical construction, each dot in the matrix operates as an individual glow discharge light source. and the required dots are selected by an $X / Y$ addressing array of transparent, thin film, metal lines (Fig. 1.7). Note that the address lines do not come into direct contact with the gas in the recesses, the ionising potential being applied capacitively as at.c. pulses. This type of display is a recent innovaltion, and promises to be a very useful technique for displaying several lines of data at a time when it will be cheaper than using separate tubes.

Despite these other formats availability, they are not yet an economical choice for the amateur, and in the notes on decoding and driving for cold cathode tubes, we will deal specifically with the discrete character type.

## Next month: Driving and decoding circuits for cold cathode tubes



A cold cathode dot matrix display. In this type each dot can be individually illuminated (Mullard)


## IITITREMOIOD



The first of three guitar effects units which will add new dimensions to the sounds produced. By A. Russell

MANY electric guitar players will have noted the high cost of commercially available sound effects units. The tremolo unit described here was designed around cheap, easily available components. It is simple to build and economical with battery power and it will provide a potent tremulant effect for a guitar input with controls available for both tremolo rate and depth of sound produced.

## HOW IT WORKS

In the circuit diagram of Fig. 1, the multivibrator circuit comprising TR1, TR2, switches at a rate made variable by VR1, between 1 Hz and 10 Hz .

As the collector of TR2 rises and falls between 0 V and 8 V the capacitor C 3 will charge at a rate determined by the CR product of R5 and C3. As the voltage of C3 rises exponentially there comes a point when TR3 switches on. If a guitar is connected to JKI the output to JK2 which is normally developed


Fig. 1. Circuit diagram of Tremolo Unit
across VR2 and TR3 is suddenly very much reduced when TR3 does conduct. With the transistor switched off the guitar signal passes through the unit unchanged. As TR3 is being switched at a regular rate the output level will vary in depth to produce a tremolo effect.

## COMPONENTS . . .

> Resistors
> R1 $6.8 \mathrm{k} \Omega$
> $\begin{array}{ll}\text { R2, R3 } & 47 \mathrm{k} \Omega \text { (2 off) } \\ \text { R4, R5 } 6.8 \mathrm{k} \Omega \text { (2 off) }\end{array}$
> All $\frac{1}{2}$ watt, $10 \%$ carbon
> Capacitors
> $\begin{aligned} & \mathrm{C} 1, \mathrm{C} 2 \quad 1 \mu \mathrm{~F} \text { elect. 12V (2 off) iGj } \\ & \mathrm{C} 3 \quad 50 \mu \mathrm{~F} \text { elect. } 12 \mathrm{~V}\end{aligned}$
> Transistors
> TR1, TR2 OC81 (2 off)
> TR3 AC128
> $\begin{aligned} & \text { VR1 } 500 \mathrm{k} \Omega \text { dual gang carbon linear } 24 p \\ & \text { VR2 } 100 \Omega \text { carbon linear }\end{aligned}$
> VR2 $100 \Omega$ carbon linear 24 p.
> S1 on/off toggle 50 ;.
> SK1, SK2 Standard jack sockets (2 off)
> BY1-PP3 9 V
> Battery conniectors
> Veroboard 0.55 matrix 2 in $\times 2 \frac{1}{2}$ in
> Plastic angle (see text)
> Instrument case $6 \frac{1}{2}$ in $\times 4$ in $\times 4 i n$ (G. W. Smith) Control knobs (2 off)


Fig. 2. Component board layout and interwiring details

With VR2 a variable resistor the depth of effect can be altered but there is a point when multivibrator breakthrough is slightly apparent as a ticking noise. While this is not objectionable the unit can be switched off when the guitar is not being played, although if used in a group the ticking would not normally be noticeable above the other instruments.


Increasing the value of C3 may damp this a little, but there will be a maximum above which the tremolo effect will not be satisfactory.

## CONSTRUCTION

The majority of components are assembled on a 2 in $\times 2 \frac{1}{2}$ in piece of Veroboard as in Fig. 2. Also shown are the connections of this to the control panel.

A piece of $\frac{1}{2}$ in plastics angle was Araldited to the board and drilled for screw mounting to the case. For ease of operation Sl can be replaced by a footswitch connected by way of a socket at the front panel.

## TESTING

When the unit is completed the wiring st ould be checked ensuring that the electrolytic capacitors in the multivibrator are the right way round. Should the polarity of these be reversed the multivibrator will probably operate but at the wrong frequency.

Connect the unit to the amplifier and guitar and switch on. Check the operation of the rate and depth controls. If all is satisfactory the case panels can be assembled so completing the construction.

Some loss of signal should be expected when the tremolo unit is connected and if the gain of the amplitier is not sufficient to compensate for this a preamplifier may be necessary. If so, it should be* connected between the unit and the amplifier.


THE following circuit is for an automatic, lightoperated switch which offers reliability and high sensitivity to light variation but low sensitivity to component changes.

The electronic experimentalist constructing a lightoperated switch generally must contend with a variety of electronic and mechanical problems. This circuit is an all solid-state design employing a thyristor as the load current switch. Simplicity and economy are apparent with the design. The unit is either self-latching, remaining on after initial activation, or an on-off switch following light variations. The choice depends on whether the power supply is smoothed or simply half-wave rectified a.c., respectively. Load currents approaching 5 or 10 amps are allowed with a relatively inexpensive range of thyristors. In the off state, only a very low leakage current in the order of a few microamps is drawn.

## SIGNAL INPUT

The cadmium sulphide photoresistive cell, PCCI, in Fig. 1 acts as a voltage divider in conjunction with the series pair of resistors R1 and VRI. In bright light conditions, the photoresistor has a nominal resistance of approximately 500 ohms.


Fig. 1. Circuit diagram of the photocell thyristor switch

This value will hold the base bias on transistor TR1 near zero volts which corresponds to the off or non-conducting state. In low light conditions, the base bias increases (negatively) as PCCl resistance increases in the voltage divider. TR1 becomes forward biased with emitter current increasing to some maximum value.

## TRANSISTOR STAGES

The high gain transistor pair TRI and TR2 act as both voltage follower and current amplifier with respect to the photocell.

When TRI is biased off, the relative base-emitter bias of TR2 is zero. Thus negligible current will flow in the emitter-collector circuit of TR2. The direct connection between the emitter of TR1 and base of TR2 gives a high degree of current sensitivity at the collector of TR2 to variations in photocell resistance changes. Current through the voltage divider and in TR1 are in the order of microamps, whatever the state of the circuit.

As TR2 is biased on by conduction through the emitter of TR1, large current flow is possible through the circuit formed by the load, R4 and VR2 in TR2 emitter lead, and the thyristor gate-cathode junction in TR2 collector lead. Switching the thyristor on requires moderate current for approximately 50 microseconds after which the thyristor gate serves no purpose in maintaining anode to cathode conduction.
To prevent possibly destructive power dissipation in TR2, a self-biasing feature links TR2 and the thyristor.

## THYRISTOR OPERATION

The device has a pnpn construction as shown in Fig. 2a. The $p$ and $n$ material of the terminal regions are the anode and cathode, respectively. A lead from the internal p-type semiconductor material serves as the gate for switching the thyristor from the off state to conduction. The gate requires a current of roughly 25 milliamps to trigger the device on.

|  | Fig. 2a. Internal construction of the thyristor <br> (left) |
| :--- | :--- | :--- | :--- |
| Fig. 2b. A typical external view of a power <br> thyristor (right) |  |

It is recommended that the gate-cathode junction never be reverse biased, i.e. the gate should not be allowed to become more negative than the cathode.

Thyristors act as diodes when supplied with an a.c. power supply. Note here that the gate should be protected by a series diode when supplied with a.c. voltage. Thyristors are self-latching to the on state after the gate signal has been applied, but when the supply voltage falls to zero as with an a.c. supply, the thyristor switches off and remains off unless a gate signal occurs during the next cycle.

Physically, high power thyristors are encased for mounting on a heat sink. The threaded stud on one end is the anode (leading to the positive end of a power supply for conduction). The opposite end contains two tags, the larger being the cathode and the smaller being the gate, see Fig. 2b.

## SELF-BIASING ACTION

looking at the transients as the thyristor is switched on reveals an interesting circuit characteristic. As TR2 begins to conduct, current flows through the gate of the thyristor. So long as the current is insufficient to switch the thyristor on, the emitter of TR2 remains near zero volts. When the thyristor switches on, the full supply voltage rapidly appears across the load rather than the thyristor.

In the switching process, the emitter of TR2 swings to full negative potential while TR1 holds the base of TR2 at a positive voltage with respect to the negative rail. Thus TR2 is switched off by this reverse biasing process.

The sensitivity of TR1 and TR2 means that conduction to the thyristor gate occurs rapidly as the
light level crosses a threshold set by VR1. The variable resistor VR2 assists by holding small conduction currents below the gate threshold level. Once conduction begins at the thyristor, the otherwise wasted current in TR2 is limited to a duration of a few microseconds.

## CONSTRUCTION

Due to the simplicity of this circuit, wiring details can be arranged to suit the reader's own requirements. A suggested layout is shown in Fig. 3. Obviously miniaturisation can easily be achieved. R1, VR1, R2 and R3 dissipate less than $\frac{1}{8}$ watt of power. Due to the short duration of power dissipation in R4 and VR2, these resistors can be $\frac{1}{4}$ watt.

Throughout the circuit, fixed resistance values are not critical so that any reasonably close resistor should be sufficient. RI and R4 are included as safety resistors to protect the circuit from accidental zeroing of VR1 or VR2 during the setting up procedure. They should not be omitted during construction.

The selection and mounting of a thyristor should be done with the care usually given to semiconductor components.

## SETTING UP

After constructing and checking connections in the circuit, turn VR1 and VR2 to their maximum resistance setting. Set the photocell in the required light conditions for switching on, remembering that in bright light the circuit should be off. With the power on, bring the value of VR2 down until the circuit switches on. Next, adjust VR2 back to a


Fig. 3. Wiring details of the prototype
higher resistance so as to hold a test lamp off. The lead to the test lamp must be broken and re-made to switch the thyristor off (or the power supply switched off).

VR2 is a rougher control than VR1 for switching in relative darkness. They reverse their function in this respect when set to switch in brighter lighting.

Resistor RI may be increased toward 100k!? or 150 k ! ! if more sensitivity in dark conditions is needed, i.e. if the circuit is to differentiate between very dim lighting levels. These settings are moderattely sensitive to a shift in the supply voltage although the circuit was found to function readily over at $\pm 30 \%$ change from the stated 12 V supply voltage.

## MODIFICATIONS

In its present state the circuit can actuate parking lights or various detection systems. The speed of switching is controlled by the slowest element in the circuit. In this case, the photocell is the slow link for the detection of a rapid variation between lighting shades. The response time is somewhere around 50 milliseconds.

If an external voltage pulse or photodiode is used at the base of TRI, the switching time drops to roughly 50 microseconds. This is better than a relay reaction time. The transistors, even if not those suggested in the circuit diagram, generally switch in a range of fractions of a microsecond to a few microseconds, which is a negligible time.

Other signal sources may be a photo-transistor, a piezoelectric crystal giving a pressure sensing switch. or capacitive or inductive reactance giving a frequency sensitive switch.

## SUGGESTED APPLICATIONS

Applications of this simple circuit are closely related to the power rating of the thyristor selected by the constructor. The authors used in the prototype an unmarked thyristor of approximately 30 volts p.i.v. in a 5 amp case, as may be purchased from many electronics shops.

A 5 amp thyristor used with the test lamp at 2 watts was sufficient in the authors' application to switch on automobile lights which draw about 30 watts. This still represents only half the current rating of the thyristor.
The other rating to bear in mind is the peak inverse voltage which may be regarded as being roughly a measure of the forward voltage hold-off rating.
The maximum oltage is restricted to the maximum voltage allowed by the transistors.
With some imagination a voltage dropping resistor and Zener diode may be added to allow increased voltage on the thyristor, whilst the transistors are protected to below their limit values.

Besides finding convenient use of the switch for parking lights, the authors also found the circuit was ample to operate a small mechanical cycle counter. for which the input was generated by a rotating disc with al segment cut out, permitting light to fall onto the photocell. On this application full wave rectified voltage was supplied to the circuit, again referring to the thyristor, the part of each voltage cycle which dropped to zero ensured that the thyristor turned off as opposed to latching on as it is designed to do when constant d.c. voltage is the power source.

COMPONENTS...

## Resistors

R1 $56 \mathrm{k} \Omega$
R2 $12 \mathrm{k} \Omega$
R3 $2.2 \mathrm{k} \Omega$
R4 $18 \Omega \frac{1}{4}$ watt
All resistors $\underset{\sim}{=} 10 \%, \frac{1}{6} \mathrm{~W}$ unless otherwise stated
Potentiometers
VR1 $100 \mathrm{k} \Omega$ carbon skeleton preset
VR2 $500 \Omega$ wirewound linear slider
Transistors
TR1 OC71 or equivalent TR2 OC81 or equivalent

Thyristor
CSR1 5RC5 (International Rectifier Co.) 5 A 50 V p.i.v. (Gate triggers at 2 volts, 15 mA )

Light Dependent Resistor
PCC1 ORP12
Miscellaneous
Paxolin sheet or Veroboard $\operatorname{3in} \times 2$ in $\times \frac{1}{18}$ in M.E.S. Iamp and holder (see text)

A counter and parking light application have been . mentioned. The thyristor load may also be a burglar alarm set off by interrupting a light source.

The idea in each application is to replace the test lamp load with a working load. Then a thyristor is inserted which has the correct rating in terms of a sufficient value for the maximum current and voltage applied. Remember that the transistors are giving a high gain so that there appears to be a fair disparity betweeen the current drawn by the thyristor and by the rest of the circuit; a large thyristor current-say 10 amps-can be expected.

## THYRISTOR SELECTION

Either latching or non-latching action is possible and a range of load voltages and currents are possible according to the type power source, whether d.c. or rectified a.c. respectively, and the selected value of the thyristor.
If a constant d.c. power source is used then the device will be latched on without regard to the photocell until the power source is removed.

To find the correct thyristor current rating either
(a) take the value of current given for your load, or
(b) divide rated wattage by the applied volts, or
(c) divide applied voltage by the rated load resistance.
Then select the next largest thyristor so that there is a factor of safety.

Further suggestions for the load which may be developed quickly are a d.c. solenoid coil, a relay coil-the relay poles doing multiple switching or H.T. switching - or a simple resistive load such as a light. If the photoresistor were sensitive to the light from a flame, the switch could be used for flame detection.

Other suggestions are left to the reader.

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74154 lob-bit decoder/demultiplexer
74156 Dual 2 -line to 4 -line decoler/Aemultiplexer
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B Y FRANK W. HYDE

## HIGH POWER IN THE IONOSPHERE

There are a number of areas where man attempts to modify his environment to suit his needs and the latest of these would appear to have a possible future effect on communication systems.

The new experiments in this direction have been made using a radio telescope, with a 1.000 feet diameter dish. located at Arecibo. The very high powers that have been used with this radio telescope dish have resulted in the heating of the $I$-layer of the ionosphere.

The ialea that this might be possible has been talked about for a number of years. The writer was engaged in some of this work when the ITA television system was inaugurated. It was noticed then that when a high powered station was opened the tranemissions appeared to become reduced in intensity after about three months.

Although a few people accepted that this was due to ionospheric modification the work was not pursued for lack of support. Now in the intense beam that is obtained with this giant dish, it is possible to follow up carly ideas. particularly those put forward in 1970 by a team at Boulder, Colorado, using a very large aerial array.

The Arecibo dish has already established itself as a pioneer instrument. It confirmed beyond doubt the rotation period of Venus and also proved the correct rotation period of Mercury.

Since it is the largest dish in the world there have been many calls on its use by radio astronomers and the ionospheric teams have felt that they have been rather overshadowed by the astronomers. However, the dish may for a time at least revert to its original planned purpose which was the study of the ionosphere.

The ,r W. E. Gordon. .ed a preliminary report of what has been accomplished with the 100 kW transmitter, which operates in the 5 to 10 MHz band. The actual frequency of the experiments was 5.62 MHz . It is possible to use the radar equipment at the same time as the "heater" transmitter. It is, therefore, possible to observe the effects of the high power on the ionosphere.

When the transmitter is switched on the temperature of the $F$-layer increases and airglow appears together with infra-red activity. The variation in heating is measured at 430 MHz and a contour map plotted for changes of temperature. It is clear from these maps that plasma forms like a bubble some 100 km in length and 50 km across. Aligned with the magnetic field this rather cigar-shaped plasma shows a temperature rise of some $300^{\circ} \mathrm{C}$ over the normal temperature of the region which is of the order of $1.000^{\prime} \mathrm{C}$.

Naturally such an area has a direct effect on communications since the reflecting property is affected. It may become a useful tool in the propagation conditioning of the ionosphere.

## MARTIAN MOONS

Much speculation has been made about the inner Martian moonlet Phobos in the past. including a
suggestion thiat it was hollow ou an artificial body, because of the low density that it appeared to have.

Since Marincr 9 went into orbit around Mars on November 13 a raging dust storm had obscured the surface features of the planet. So scientists directed its television cameras towards one, then the other of the two martian moons. Some scientists regard Phobos and is sister moon Deimos as even more attractive research targets than Mars.

Of all the moons in the solar system. Phobos is the only one moving around its planet faster than the rotation of its parent body and no one has yet suggested a reasonable explanation for this unique behaviour, reminiscent of man-made satellites.
Both the satellites of Mars have now been photographed and the pictures of Phobos show it to be a rather miserable irregular chunk of rock. It is crater marked, with at least one huge crater, and its size is approximately 15 miles by 13 miles. The natural conclusion must follow that it is a captured asteroid.

During the journey towards Mars the probe photographed Deimos from a distance of 5,300 miles. It was described in the preliminary reports as being potato shaped, about 8 miles across and have groove like markings. The irregular shape is compatible with its small size.

Rugged surface features of the irregularly shaped Martian moonlet Phobos are visible in this computer enhanced photo. The photograph was taken by Mariner 9 during the 34th orbit of Mars.



# GHEREAI PUPROST AMPIIIIER 

## An experimenter's amplifier with input sensitivities to suit most bench requirements By F. C. JUDD

THE general purpose amplifier described in this article has inputs suitable for a wide variety of audio signal sources including those requiring special frequency correction such as magnetic pickup cartridges and tape heads. The amplifier can be split into two sections and operated (a) as a signal pre-amplifier and (b) as a small power amplifier, each being independently usable.

There are five input sockets and these can be used for the following signal sources:
(SK4) For all magnetic pick-up cartridges. Provides RIAA frequency response correction and has a nominal input sensitivity of 6 mV at 56 kilohms.
(SK3) For ceramic or crystal pick-up cartridges of high impedance and output signal. The high input impedance provides the necessary equalisation for record replay.
(JK1) Input sensitivity is approximately 2 mV . Suitable for microphones from 200 ohms impedance and upward.
(SK2) Suitable for radio tuners and/or tape record/replay units with linear output or any linear signal source of between 100 mV and 500 mV .
(SK1) Input sensitivity 5 mV . Suitable for direct connection from medium impedance tape heads and provides a compromise CCIR/NAB replay characteristic.

The sixth possible input is direct to the output amplifier via the volume control. This will permit connection of linear signal sources in excess of about 500 mV which would otherwise overload the preamplifier.

The power amplifier will deliver 3 watts r.m.s. power to any small loudspeaker of between 5 and 15 ohms and its input sensitivity via the direct input link to the volume control is 80 mV for 3 watts output. The pre-amplifier will deliver 80 mV from its link output terminal for the following input ratings:

Magnetic pick-up (SK4) 6 mV 56 kilohms
Ceramic pick-up (SK3) 100 mV 820 kilohms
Microphone (JK1) 2mV 100 kilohms
Radio (SK2) 100 mV 120 kilohms
Tape head (SK1) 5mV 100 kilohms

## THE CIRCUIT

The circuit is shown in Fig. 1. The inputs are selected by S1a and where necessary taken through suitable attenuation networks to TR1 which, with TR2, forms a direct coupled pre-amplifier. Negative feedback is used to control gain and/or equalisation and is taken from TR2 collector via the networks. and S1b to the emitter of TR1.

The pre-amplifier output is taken to the link terminal strip and then by VR1 (volume control) to the output amplifier. When the link is uncoupled the pre-amplifier output can be used to drive any other external amplifier. Alternatively, signals may be taken directly to the output amplifier by way of VRI.

The output amplifier itself is a fairly simple driver and complementary pair output arrangement and providing the specified components are used and the heatsinks are to the dimensions given, it requires no special adjustment or protection against thermal runaway.

The power supply employs a transformer with a centre tapped secondary delivering 13 V either side. Note that only 13 V are ajplied to the rectifier, that


| Resistors |  |  |  |
| :---: | :---: | :---: | :---: |
| R1 | 120k $\Omega$ | -R15 | $47 \mathrm{k} \Omega$ |
| R2 | 12kS | $\pm$ R16 | 10kS, |
| R3 | 820ks2 | -R17 | $3.2 \mathrm{k} \Omega$ |
| R4 | $220 \mathrm{k} \Omega$ | - R18 | 3.9k ${ }^{\text {² }}$ |
| R5 | $56 \mathrm{k} \Omega$ | R19 | 120k $\Omega$. |
| $=$ R6 | 1.2 k /2 | R20 | $39 \mathrm{k} \Omega$ |
| .-R7 | 220k $\Omega$ | R21 | 47 k S |
| $\cdots 88$ | 180k $\Omega$ | R22 | $390 \Omega$ |
| -R9 | $180 \mathrm{k} \Omega$ | R23 | $22 \Omega$ |
| R10 | $12 \mathrm{k} \Omega$ | R24 | $2.2 \mathrm{k} \Omega$ |
| -R11 | 1k! | R25 | $15 \Omega$ |
| -R12 | 1 kS 2 | R26 | $560 \Omega$ |
| -R13 | 390ks | R27 | $2.2 \Omega 2.5 \mathrm{~W}$ |
| =R14 | 12kS | R28 | $2 \cdot 2 \Omega 2.5 \mathrm{~W}$ |

All $\frac{10 \%}{}$ carbon except where otherwise stated

## Capacitors



Transistors

| TP1 | BC109 |
| :--- | :--- |
| TR2 | BC108 |
| TR3 | BC108 |
| TR4 | AC128 |
| TR5 | AC176 |
| TR6 | AC128 |

## Potentiometers

VR1 $10 \mathrm{k} \Omega$ carbon logarithimc


Fig. 1. Circuit diagram of amplifier and power supply

## Switches

S1 Double pole 4-way switch
S2 Mains on/off toggle switch
Transformer
T1 Mains transformer, 13-0-13V secondaries type TS2/13 (Henry's Radio)

## Sockets

SK1-SK4 Phono sockets (4 off)
JK1 Standard jack socket

## Rectifier

D1-D4 Rectifier type LT119 (Henry's Radio)

## Miscellaneous

Link terminals-4-way strip type TS64 fHAHry's Radio), 0.15 in matrix plain Veroboard $3 \frac{3}{4} \mathrm{in} \times 8 \mathrm{in},-$ heatsinks and copper transistor clips ( 3 off), 8 in $\times$ $\frac{3}{8}$ in aluminium angle. Plywood for base boardpand cabinet.


Baseboard assembly of amplifier control panel, component board and power supply. Note the use of aluminium heat sinks for mounting the output stage transistors and aluminium screening for the underside of the components board
is only one half of the winding is used. This provides 25 V d.c. to the amplifier which falls to approximately 22 V when the power stage is delivering its full output.

## CONSTRUCTION

The entire pre-amplifier and output stage can be assembled on a single circuit board as shown in Fig. 3. The input sockets, the selector switch SI , the link terminal strip and volume control, etc. are mounted on the control panel as in Fig. 2

The transistors TR4. TR5 and TR6 are mounted on aluminium heatsinks with copper transistor clips. Do not cut the transistor leads and place a piece of sleeving over each to prevent short circuits. The circuit board is plain s.r.b.p. ( $0 \cdot 15$ in matrix) which is mounted on an aluminium screen by means of stand-off spacers and 6B.A. bolts. The complete assembly is attached to the base board on a length of aluminium angle. The control panel is also mounted on the baseboard by similar means.

The lead from the common of Sla to Cl must be screened with the screen grounded at the component board.

## PERFORMANCE AND TESTING

Before connecting check the output patir and driver transistor circuitry in particular as both npn and $p n p$ transistors are used and it is quite easy to connect them wrongly with obvious results. It is


Fig. 2. Component layout and wiring of amplifier control panel. Apart from S2 all flying leads should be routed to the component board
also worth checking the power supply before connecting the positive line to the amplifier and make sure that 25 V only are available.

The quiescent current of the amplifier with no signal input should be approximately 22 mA . At maximum r.m.s. power output the current will rise to about 200 m A and the rail volts will fall to about 22 V . The amplifier is quite safe with the speaker disconnected but do not short circuit the speaker terminals whilst power is being developed.


Fig. 3. Board layout and wiring of pre-amplifier and output stage


The amplifier being used to check a record deck. One of the many bench applications of the unit

If possible the signal input sensitivities should be checked but providing the circuit has been correctly wired these should comply with the figures given.

The frequency response of the power stage is given in Fig. 4 but can be extended a little at the low frequency end by doubling the value of the output coupling capacitor C14, that is, making this $1,000 \mu \mathrm{~F}$. The same graph shows the response from


Fig. 4. Graphs of magnetic pick-up and frequency responses


Fig. 5. Tape head input frequency response
the magnetic pick-up input which is to RIAA characteristic. The response from the tape head input (Fig. 5) is between CCIR and NAB characteristics and provides a replay response more in line with that used on modern domestic tape recorders. It is suitable for tape speeds of $7 \frac{1}{2}$ and $3 \frac{3}{4}$ inches per second.
The combined response of the pre-amplifier and power amplifier for radio or microphone input is as shown in Fig. 4 although the response of the preamplifier by itself is considerably wider and extends down to 20 Hz and to well above $25,000 \mathrm{~Hz}$. The hum and noise level for the complete amplifier is better than -60 dB for all inputs.

## A SUITABLE CABINET

The cabinet size or shape is not critical and it need be only large enough to accommodate the amplifier and a loudspeaker which may be any round or eliptical type capable of handling 3 to 4 watts of audio.

## APPLICATIONS

The amplifier has many applications as a bench testing instrument for audio signal sources of all kinds and could be duplicated for stereo reproduction with the second chainnel run from the spare 13 V mains transformer secondary with an extra rectifier and smoothing capacitor. The circuit could also be used for a small record player in which case the switching and components for unwanted inputs need not be included. For example, for a mono record player with a ceramic or crystal pick-up the switch S1 is omitted, the collector of TR2 coupled back to the emitter of TRI via C6 and R15 and the input taken via R3 straight to C1 with R4 connected from R3 to earth as shown. The link terminals would not be necessary so C7 would be connected straight to the top of VR1.

One final point. It may be found worthwhile to place a screen (thin tinplate or aluminium) underneath the baseboard and connect this to common earth to prevent hum pick up particularly from bench mains wiring.

# POINIS Dils.jnt 

I.C. DIGITAL DICE (December 1971)

There should not be a connection between gate output G6 and common, that is P14 and P15 on the Veroboard layout.

## P.E. SCORPIO IGNITION SYSTEM (November, December 1971)

See letter on Readout page 248
PHOTOPRINT PROCESS CONTROL
(January 1972)
Components List page 26. TR5 should be type 2N2926G.
Fig. 2 page 24. R16 is $3 \cdot 3$ ohms or 6.8 ohms as in the Components List.
FS1 could be a 1 A anti-surge fuse for better protection.

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## Connoisseur

## S.A.U. 2 Pickup Arm



## S.C.U. 1 Stereo Cartridge




Witether you are a hiff fanatic with an ultimate desire lo reproduce recordea sound at its very best, or just an average person who likes music around the house withcut being too particular about the techniques or finesse of the result, this supplement has been devised to explain some of the mare important points about pickups and turritasle units that mosi users may meef.
*
That equipment used to rotaite a recorded disc and detect the recorded signal is sometimes called ia) a record deck; (b) a transcription unit: (c) an autochanger; (d) turntable and pickup. A record deck is the eeneral term applied without any implications of auality. A transcription anit has by convention implied high quality ofielt with the firest perfarmance currently available. An autochanger is a record deck with exira mechanisms to change the disc at the end of replay and operate the pickuron and off the disc.
Whatever class of equipinent interests you, it is fairly certain that manujarturers' litetature with offel you some or all of the important technical [eztures that you will wish to know to assess the value-for-money factor ofyour interided purchase.


Philips GA308 record deck

BEFOFE going into : haracteristics indivicually let us first consider the equipment as a whote. The sensitive element, which translates information stored in, the disc groove is a transducar-frequenly called a cartridge, ts function is to generate electrical sigrals from vibraticns of a stylis caused Dy varying patterns 2 : meculation in the groove wall. The Frincipies are the same for mono (single channel) or stereo (dual channel;


Transcription turntable Thorens TD124 Series II and SME 3709 Series II pickup arm with rest, side thrust correction waight, counterbalance weight at the tear and tracking weight on the side
recordings: The sigrificant difference is the direction on which the stylus is vibrated and the relationship between the signals derived as will be explained later.
The cartudge is fitted 0 the underside of the pickup head, which mav cr may not be detachable from the pick-up arm. A modern cartridge usually carries two holes or slois in its mounting with a "standard" pitch of $0.5: n$ for securing to the head shell.


## Garrard autochanger AT60 Mk /I

The motive power to rotate the disc is provided by a symzhronous motor driven turntable operated from an a.c. mains supply.

The trans ation of the recorded information :nto an electrical signal is loaded with meshanical and elecfrical probleras, although current encineering prastice has enatled the designer to master them. Extremely high quality reproduction from disc is now possible in two and fru: channels.

## HOW THE STEREO PICKUP WORKS

As is well known, sound signals recorded monophonically or from a centre-stage sound source causes the replay stylus to vibrate laterally. See Fig. Ia.
In the case of two-channel stereo records, the two walls of a Vshaped groove are modulated independently (Fig, 1b). The wall nearest the centre of the disc carries the left channel information; the other carries the right channel information.
Depending on the phasing between the left and right signals, the replay stylus vibrates laterally when there is only mono or centre-of-stage . stereo information (Fig. 2d), indicating in-phase conditions; and towards the vertical when the stereo information is at a maximum (Fig. 2c), indicating antiphase conditions. Intermediate phase conditions result in different angles of vibration (Figs. 2a and 2b).
Some of the latest "four channel" or quadraphonic discs carry hall ambience effects in one or two rear channels by the phasing interplay between the front left and right channels, with the rear channels being derived from antiphase information. The four channels are matrixed into the two channels of the disc, so that when
four-channel replay is required a corresponding decoding matrix is adopted, the disc replaying in normal two-channel stereo.

Another scheme is based on the front two channels being recorded almost normally, with the two rear channels introduced by frequency modulated signals with sidebands extending to some 50 kHz . This is called the "discrete" system because the four channels are handled in isolation throughout.

At the time of writing there is no quadrophonic disc standard, but ideas on both methods exist, with variations of the former.

Compatibility is one key note, which refers to the ability of the four channel system to replay in stereo or, indeed, in mono with minimal loss.

Correctly balanced mono replay from stereo discs is achieved by using a mono cartridge or a stereo type with the two channels correctly phased in parallel or series into the single replay channel. However, the stylus assembly must be endowed with adequate vertical compliance to avoid the inertia of the whole pickup from trying to follow the vertical vibrations of the stylus!


Fig. 1a. Stylus tip in a mono recording groove; first half-cycle


Fig. 1b. Stylus tip in a mono recording groove; second half-cycle


Fig. 2. Modes of stylus vibration. (a) left channel, (b) right channel, (c) equal left and right in anti-phase, (d) equal left and right in-phase


Fig. 3. Elementary features of a piezoelectric stereo cartridge

## PIEZOELECTRIC PICKUPS

The pickup transducer is most frequently an electromagnetic or piezoelectric generator, the latter using Rochelle salt or ceramic elements. Fig. 3 shows the essential features.

Rochelle salt crystal has the advantage of providing high output, having a high dielectric constant and hence high capacitance and relatively high compliance. Unfortunately it suffers the disadvantages of distortions due to moisture and temperature sensitivity.

Ceramic, on the other hand, is impervious to atmospheric conditions, is capable of a better frequency response than Rochelle salt, but has a smaller output.

Rochelle salt crystal pickups have now been largely superseded by ceramic types and are employed mostly in the mass market type of equipment. The high output, sometimes IV or more, can cut amplification costs, and in some low priced equipment the power amplifier stage is driven direct from the crystal pickup

Typical ceramic pickup output is 50 to 100 mV , and was used extensively at one time in budget price systems, but now that the better performance of magnetic pickups can be obtained for little more than the price of some ceramic types, the latter are tending to lose favour.

Since the output of a piezoelectric pickup is roughly proportional to the amplitude of moduiation, it can be used when correctly loaded without equalisation, which can reduce the cost of the amplifier.


Acos Crystal cartridge GP91-1SC for single channel (mono) replay of stereo or mono recordings


Audio-Technica AT-55 cartridge fitted into a headshell. Notice the mounting screw on the near side


The Goldring G800 induced field cartridge. Also uses the variable reluctance principle


Fig. 4. Moving magnet cartridge showing the stylus coupling


Fig. 5. Coil system of the Decca sum-and-difference pickup


Fig. 6. Showing how the left and right generators are independently operated by the $45 / 45$ stereo cut


Fig. 7. The $V$ magnet system on the end of the cantilever corresponds to the $45 / 45$ stereo cut. This is from the AT35 Audio. Technica cartridge


Most magnetic cartridges are designed so that the stylus assembly can be removed from the main body for cleaning or replacement. This is the Audio Technica AT35

## MAGNETIC PICKUPS

Magnetic pickups come in a diversity of types, although all of them exploit the basic electromagnetic principle (Fig. 4) Most common types are moving coil, moving magnet and variable reluctance, where a ferrous armature vibrates between "magnet" pole-pieces. Induced current can be excited in either a field coil (moving magnet) or armature coil (moving coil) by stylus vibrations

When the field is provided by a magnet which is not in contact with the pole-pieces, the term "induced magnet' is sometimes adopted, as
the field is coupled to the micromass armature

Magnetic pickups produce an output proportional to the velocity of the modulation. Since this modulation is recorded on a rising characteristic (i.e. bass cut and treble boost), corresponding approximately to constant amplitude characteristics, equalisation is required at the amplifier. This should be designed to correct the frequency response of the reproduced sound signal. Typical output is a little over $\operatorname{lmV}$ per cm s velocity.

## SUM-AND-DIFFERENCE PICKUP

One type of magnetic pickup is based on the variable reluctance principle, but employs a set of three coils from which the two stereo signals are obtained. The coils of the Decca sum-anddifference pickup are shown in Fig. 5
Signal em.f. in the three coils is the same when there is modulation in one channel, but the phasing of the coils is such that the sum of the signals in right vertical coil 1 and the lateral coil appears across terminals $C$ and $R$ when the right channel is modulated. There is theoretically zero output from the left channel, between $C$ and $G$, because the signal in vertical coil 2 is in phase opposition with that in the lateral coil, thus giving the difference function. In practice, however, a very small signal is obtained due to the crosstalk factor through leakage from other

## OTHER PICKUPS

Other pickups include one based on the photoelectric principle where a small lamp is focused on photoelectric diodes and the stylus vibration is caused to modulate the light on the diodes. Another is based on the strain gauge principle. where d.c. is modulated by the vibrating stylus.
One uses ribbon instead of a moving coil, as in a ribbon microphone. This, as with the moving coil type, requires a booster amplifier or step-up transformer
Other transducer principles have been adopted, and there would appear to be an increasing interest in the electrostatic principle, resulting in the capacitor pickup.
coils.
When the other wall is modulated, the right channel is quiet and the signal in coil 1 is in phase opposition to that in the lateral coil. When both left and right are modulated together, the two stereo signals are delivered with minimal interaction between them. The $Y$ terminal allows the lateral coil only to be used for mono replay. (Codings $R, G$, and $Y$ usually refer to colours of the connecting lead, i.e red, green, yellow. Common $C$ is the screen.)
Other cartridges employ a pair of generators with their motional axes in $V$ formation to correspond to the 4545 stereo cut, where each channel is recorded 45 degrees to the surface of the disc and at rightangles to each other (Fig. 6). Sometimes the moving magnet is arranged in $V$ formation, as shown in Fig. 7


Pickup head by Decca. This is based on the sum-and-difference principle

Audio Technica AT 1005/ll pickup arm


## PICKUP CHARACTERISTICS

## LOW FREQUENCY RESONANCE

One problem of arm/transducer matching is low frequency resonance (i.e. the natural tendency for vibration to be excited at a particular frequency related to the characteristics of the component). This results from the dynamic mass of the arm resonating with the compliance of the stylus assembly.

The electrical analogues of mass and compliance are inductance and capacitance, so not unnaturally the resonance frequency $\left(f_{0}\right)$ is equal to $1 /(2 \pi \sqrt{ } M C)$, where $M$ is the mass and $C$ the compliance. Thus the greater is $M$ or $C$ the lower will be $f_{0}$.

At resonance the vibrations tend to magnify, as also does the pickup output, while below $f_{0}$ a high-pass filter effect occurs, in which the bass response tends to roll-off (Fig. 8).

Thus if the MC combination results in $f_{0}$ being too high the bass response suffers, while a too low $f_{0}$ encourages unstable tracking, the stylus tending to leave the groove when the resonance is excited by external vibration, such as someone walking across the room.
Moreover, if $f_{0}$ corresponds to the


Fig. 8. Below bass resonance the output rolls off, an effect which is sometimes exploited for attenuating rumble
resonance of another connected component, such as a loudspeaker in a room, acoustic feedback can lead to howl build-up as the amplifier's volume control is advanced. If $f_{0}$ falls near the slip frequency of the drive motor ( 22.5 Hz ), turntable rumble could be aggravated. Thus it is seen that not all heads or cartridges will work with all arms without some problems arising.

Fortunately, hi fi cartridges and arms are to some extent designed for each other. Arm mass is being made as low as practicable, while stylus compliance is being made as
high as practicable. However, by going too far in these directions, other problems arise, such as inability to track properly; a proper balance between these two factors is very important.

It is known that at least one manufacturer reduced the compliance of a popular cartridge so that it could be used with budget auto-changers and decks. Consequently, high and low compliance models may be available to cater for high quality adjustable arms and medium class mass produced pickups.

In some cases l.f. resonances are tamed by arm decoupling (compliant couplings) and sometimes by viscous damping.

An $f_{0}$ between 8 and 20 Hz is fairly safe, but calculation is not easy before purchase because the manufacturer's published specification rarely includes the effective mass. Mass is not the same as weight which is counterbalanced, with just sufficient turned on to the head end for tracking the groove. Nevertheless, the majority of hi fi arms will partner the best cartridges without trouble.

## FREQUENCY RESPONSE



Fig. 9. Frequency response of topflight magnetic cartridge. The mild $5-6 \mathrm{kHz}$ droop is normal with magnetic types


Fig. 10. Cartridge with bad h.f. resonance, possibly due to the mass at the cantilever end removed from the tip resonating with the cantilever compliance

Specifications which merely give a frequency range without reference to a nominal power level deviation of undistorted signal should be treated with suspicion. Correct frequency response relates output to frequency over the audio spectrum and usually extends beyond aural sensitivity (Fig. 9). Both channels should match very closely at all frequencies for good steres listening quality. A good cartridge should be free from violent peaks in its characteristic which could signify undesirable resonances, particularly at the treble end.
One treble resonance is caused by the effective tip mass resonating with the compliance of the disc material (rather like a violin bow on a string), which has a value around $3 \times 10^{-8} \mathrm{~cm} / \mathrm{dyne}$. The lower the tip mass, therefore, the higher the resonant frequency.

A low tip mass is essential for good tracking of high acceleration modulation, and a mass of 1 mg or less would put the resonance outside the audio passband. However, the resonant frequency can be lower due to the mass at the end of the cantilever remote from the
stylus tip and the compliance of the stylus lever arm.
High frequency resonances yield significant energy which can damage the groove walls and hence the modulation; moreover, h.f. resonance also results in acute treble roll-off (Fig. 10). This characteristic is typical of the cheaper crystal pickups at one time common on mass produced equipment.
H.F. resonances also show up on the separation curves at close or corresponding frequencies. Internal damping reduces the mechanical $Q$ factor and hence diminishes the peaks, thereby resulting in a 'smoother' ' frequency response, but the intrinsic faults remain.
Many magnetic cartridges, especially those of current variable reluctance and moving magnet design, exhibit the droop around 5 to 6 kHz (Figs. 9 and 10). The effect is not significant and can be tolerated since it is gradual and not a violent resonance.
Piezoelectric cartridges in general have less smooth frequency responses than magnetic cartridges.

# AND PERFORMANCE 

## MEAN OUTPUT VOLTAGE

The output is related to velocity of modulation, usually at 1 or $5 \mathrm{~cm} / \mathrm{s}$ at 1 kHz . Each channel should yield the same output within 1 dB (even closer in top quality pickups). An average moving iron magnetic cartridge would be expected to produce about 6 mV from $5 \mathrm{~cm} / \mathrm{s}$, both r.m.s. values.
Moving coils and ribbon types will generate a mere $100 \mu \mathrm{~V}$, which is why a booster or step-up trans-
former is required. Due to this lower sensitivity and the limitations in the frequency response of small transformers, these latter types tend to lose favour.
Crystal cartridges can generate as much as IV r.m.s. from average modulation, but better class ceramic types settle for about 20 to 50 mV , with a smoother frequency response characteristic over the whole audio range.

## STEREO SEPARATION

A stereo cartridge specification should give the channel separation at 1 kHz or at two other frequencies. Good magnetic types often have a ratio as high as 25 dB at midspectrum, falling possibly to 15 or 20 dB at 100 Hz and 10 kHz .

Maximum stereo impact occurs at mid-spectrum, so the separation here must be as high as possible, but lack of stereo image stability can result if the separation ratio changes too violently in the upper treble regions.

The separation curve of a good
magnetic cartridge is given in Fig. 11, where the mid-spectrum separation is better than 25 dB . Notice the mild "ripples' at the top treble end which signify well damped resonances.
It is difficult to check cartridges with separation better than 30 dB owing to the disc replay noise in the "non-speaking" channel approaching the level of the breakthrough signal.

Piezoelectric cartridges have less exacting separation characteristics than most magnetic cartridges.

## LOADING

Correct cartridge loading is important for the best frequency response, and the optimum load is generally given in the specification. Most magnetic cartridges work best into about 47 kilohms, the treble lifting if the load impedance is too high and drooping if it is too low (Fig. 12).

Piezoelectric cartridges, on the other hand, are load sensitive at the bass end. This is because they are capacitive in source, a high pass filter effect thus occurring when the load is too low (Fig. 13).

Good ceramic types usually demand a load impedance of at least two megohms for extended bass response; to secure a reasonable overall frequency response from the RIAA recording characteristic inbuilt equalisation is ofter incorporated. The full-line curve in Fig. 14 approximates the RIAA.

recording characteristic, which is projected to the amplitude modulation characteristic in Fig. 15, this clearly revealing the need for piezoelectric type of equalisation.

A piezoelectric cartridge can be made to approximate velocity characteristics by loading with a low value resistor (about 33 kilohms), the output then being similar to that of a magnetic cartridge, allowing the normal magnetic equalisation to be used.

Care is necessary, though, to avoid the relatively high output from overloading the RIAA equalised preamplifiers and causing bad distortion on signal peaks. This is not the best way of using ceramics.

Capacitance in shunt with the load has virtually no affect on piezo cartridges, but it can affect the treble response of magnetic types, especially when the coil



An example of the parallel arm type of pickup, the Garrard Zero 100. The head is pivoted to both arms to maintain tangential tracking


Fig. 11. Separation characteristics of a good magnetic cartridge. The mild ripples at the treble end signify well controlled resonances.


Fig. 12. Effects of incorrect loading of a magnetic cartridge


Fig. 13. Effect of incorrect loading of peizoelectric cartridge
inductance (another parameter that might be specified) is high, and incite electrical resonance with the coils within the passband.

> Fig. 14 (far left). RIAA recording characteristic in full-line. The broken-line curve shows the equalisation required in the amplifier

Fig. 15 (left). The RIAA velocity recording characteristic projected in terms of amplitude. This shows the need for inbuilt equalisation of a piezoelectric cartridge.


Micro-Seiki MC 4100/5 cartridge with 0.5 thou radius diamond stylus


Artist's sectional view of the Audio and Design induced field cartridge


Magnetic cartridge which has a removable stylus assembly

## BEARING FRICTION

The lower the vertical and lateral bearing frictions the better, and to reap the full advantage from a low tracking weight cartridge they should not exceed much more than the equivalent of 50 dynes force at the stylus tip, a value which is met by most hi fi arms.

## EFFECTIVÉ ARM MASS

This is effectively the inertia reflected at the stylus after the weight of the arm and cartridge have been counterbalanced and the required tracking weight turned on; total value must include the cartridge and headshell.

When the arm is to be used with high compliance cartridges the total value should be as small as possible to avoid a too low a low frequency resonance (see under this heading).

## COMPLIANCE

Most specifications give a figure for compliance which is expressed in terms of the distance in $10^{-6} \mathrm{~cm}$ the stylus is displaced by a 1 dyne force (roughly equivalent to a weight of lmg on Earth). Modern magnetic cartridges boast up to $20 \times 10^{-6} \mathrm{~cm}$ dyne or more

Static compliance is higher than the dynamic compliance, and confusion can thus arise in resonance calculations. Low frequency tracking is governed by the compliance and, since maximum recorded amplitudes are limited to about 0.005 cm , from the tracking point alone there is no need for the compliance to exceed $5 \times 10{ }^{\circ} \mathrm{cm}$ dyne at a tracking force of 1 gramme . However, there are other factors, including mechanical damping and tip mass, that are related to compliance as explained earlier under Resonance.

Obviously the compliance cannot be increased to the extent where there is inadequate restoring force for the stylus assembly. Vertical and lateral compliances often differ, so there could be two main low frequency resonance factors.

## EFFECTIVE TIP MASS

The stylus is mechanically coupled to the transducer so the inertia of the mechanical assembly including the cantilever is reflected at the stylus tip, and is taken into account in determining the tip mass $M_{1}$. For adequate high frequency response and hence high acceleration tracking, $M$, has to be very small.
It is a difficult parameter to measure, which is why it is rarely found in published specifications. However, an approximation of performance can he found by calculating mass $M_{1} \simeq F /(2 \pi f V)$ where $V$ is the velocity in $\mathrm{cm} \mathrm{s}, f$ the frequency in Hz and $F$ is the tracking weight at the stylus for a condition of "just tracking properly". The modulus of acceleration is $2 \pi f \mathrm{~V}$.

A good frequency for estimating $M_{1}$ is 10 kHz , and if $10 \mathrm{~cm} s$ velocity puts the tracking threshold at, say. 1.5 grammes, then $M_{1}$ would equal approximately $2 \cdot 3 \mathrm{mgm}$.

The better cartridges tracking down to one or two grammes would have tip masses around 1 mg . A treble resonance well within the passband indicates a relatively high tip mass.

## MECHANICAL RESISTANCE

In any electro-mechanical device some mechanical resistance to movement is inevitable, but in pickups it is deliberately employed in conjunction with compliance and tip mass to even the tracking and to damp resonances over the audio spectrum. It takes effect more over the middle part of the spectrum,
while compliance is important at the low end and tip mass at the high end.

Again it is not a parameter that is specified, nor easily measured, but if natural resonance occurs over mid-range, it is likely that the mechanical assembly of stylus and cantilever is at fault.

## TRACKING PERFORMANCE

Few specifications carry meaningful information on the tracking performance, although Shure do give a parameter in terms of '"trackability", which indicates the ability of a cartridge to track recorded waveforms of high amplitude, velocity and acceleration at minimum tracking weights.

The information given under compliance and effective tip mass implies that given sufficient tracking weight any cartridge would track a given modulation. This is untrue, of course, because the groove wall would collapse. Tracking performance thus relates to tracking weight

Modern discs carry amplitude variations up to 0.005 cm , velocities up to 25 cm 's (sometimes more on heavily recorded "pop" discs) and accelerations sometimes exceeding $2,000 \mathrm{~g}$. Thus to track these at, say, l or even 2 grammes tracking weight, both the cartridge and
the arm must be of high quality.
In a more advanced specification the tracking performance might be given as a curve showing the mechanical impedance of the stylus tip over the spectrum in terms of $F V$, where $F$ is the threshold tracking force in milligrammes and $V$ the recorded velocity.

It is then possible to project a curve of maximum recorded velocities over the spectrum on to this curve as shown in Fig. 16 . From these curves the tracking weight required at any frequency can be determined. At 3 kHz , for example, the impedance is $50 \mathrm{mg} / \mathrm{cm} / \mathrm{s}$, while the maximum peak velocity is about 27 cm 's, which means that a tracking weight of a little under 1.4 grammes is required.

Very few impedance curves are as smooth as this illustration, and it is only the best cartridges which can boast a tip impedance of less than 50 ohms at 2 kHz .

## TRACKING WEIGHT

All specifications should give a tracking weight or maximum/ minimum limits. The maximum merely indicates the force that the stylus assembly can handle before running into mechanical nonlinearity effects (or bottoming) while the minimum is usually a very optimistic value having no relationship to real tracking performance.

Tracking force of a specific amount is demanded, of course, to counter the reaction of the stylus in the modulated groove (see under Tracking Performance), but even
running at the maximum is no indication that the pickup will track maximum velocities accurately unless the weight refers to given levels of modulation over the spectrum (see Fig. 16).

The arm and side-thrust correction are tied in with this problem, and one way that the user can determine the approximate tracking performance of his pickup at a given tracking weight is by festing with a special record. Bands are provided on the HF69 test record for this purpose and for optimising the side-thrust correction.

## VERTICAL TRACKING ANGLE

Discs are now being cut with a 15 degree vertical tracking angle, this value being given in the specification. If the angle deviates from 15 degrees there is a rise in harmonic distortion. The angle is defined in Fig. 17.

Fig. 17


## LATERAL TRACKING ERROR

When a disc is cut, the cutter head follows a line of true radius of the disc, tracking along a radial rotating lathe screw. On replay the stylus follows an arc because the arm is pivoted at one point. Tracking error results because of the departure from exact tangential alignment of the replay stylus with the groove over the whole groove length.

As high harmonic distortion and disc and stylus wear result from this error, steps are taken in the arm design to correct it or at least significantly to reduce it. They consist of offsetting the axis of the cartridge from that of the arm and arranging for the stylus tip to overhang the turntable pivot at centre swing.

In Fig. $18, \phi_{2}$ is the offset angle and $d_{3}-d_{2}$ the overhang. The tracking error is thus equal to 90 minus ( $\phi_{1}+\phi_{2}$ ), or is zero when $\phi_{1}+\phi_{2}=90$ degrees.

The following expression is useful for calculating the offset angle for zero error with overhang and effective arm length $\left(d_{3}\right)$ as parameters.
$\cos x=\frac{d_{1}^{2}-\left(d_{3}-d_{2}\right)^{2}+2 d_{3}\left(d_{3}-d_{2}\right)}{2 d_{3} d_{1}}$
whence $\phi_{2}$ for zero tracking error is $90-x$ degrees.

Clearly, many combinations of offset angle and overhang are possible for zero error, and it is the job of the designer to select that which yields minimum error at all arm positions relative to the effective length of the arm.

The overhang is commonly adjusted by the user with an alignment protractor for the least error at the inner groove diameter, since it is here, where the waveforms are compressed, where the distortion can be at its highest.

A well designed 8 in arm with an overhang of 0.55 in and an offset angle of 24 degrees would have zero error at $3 \frac{1}{2}$ in and Gin diameters and errors of about $2 \frac{1}{2}$ and 3 degrees at diameters of 9 in and 12 in . The maximum errors are less with longer arms, but then there is the disadvantage of extra arm inertia.

For optimum tracking conditions $\phi_{2}$ reduces as $d_{3}$ increases, this making $d_{4}$, called the "linear offset', a constant. It has been determined that when $d_{4}$ is 3.47 in , irrespective of arm length, the distortion due to tracking error is minimised over the swing of the disc after setting the overhang with an alignment protractor

Distortion is proportional to the ratios of tracking error/groove radius and recorded velocity/ turntable velocity. When calculations are made for the least distortion between the maximum and minimum groove diameters the parameters obtained differ slightly from those based on zero tracking error at the inner groove diameter.

Tangential arms which do not pivot in the usual way reduce the tracking error to a maximum of about $\frac{1}{2}$ degree by using a pantograph style arm with parallel arms for adjusting the offset angle during playback.


Fig. 16. Curves relating stylus tip impedance to recorded velocities

## STYLUS

Modern discs have groove dimensions suitable for styli of 0.0005 in tip radius. Earlier LPs called for 0.001 in radius styli. A compromise dimension is 0.0007 in , suitable for early and recent discs, but for the best reproduction the smallest practicable active radius is desirable. This is because the recorded high frequency waveforms, particularly at inner groove diameters where they are more compressed, can only be defined by a tip of smaller dimension than themselves.

Tracing distortion, which is a harmonic distortion resulting from the recording cutter being chiselshaped while the replay stylus is spherical, reduces as the active tip radius is reduced

A hemi-spherical tip cannot be reduced to much less than 0.0005in for fear of it bottoming in the groove and causing excessive nolse.

This, however, is overcome by the semi-ellipsoid or biradial tip, whose active minor radius is 0.0003 in or sometimes less. The major radius which falls across the width of the groove is 0.0007 in , thereby preventing bottoming. Such a tip improves replay definition at inner grooves while also minimising tracing distortion.

Diamond is the only material suitable for a hi fi stylus, although sapphire is still used for mass market equipment. The life of a sapphire stylus is shorter, being a softer substance, often of a composite mixture.

Stylus replacement nowadays demands either the return of the cartridge to the maker or the replacement of the stylus assembly which sometimes pulls from the main body.


Fig. 18. Factors involved in lateral tracking

## SIDE-THRUST CORRECTION

Fig. 19 shows that owing to the arm offset angle $\phi$ and the forward drag $t$ of the stylus in the groove, a torque results at the arm pivot, which reflects as force $F$ pulling the cartridge inwards.

Cancellation of this force at the arm is achieved by a dangling weight device spring or magnetism. Actual correction value cannot be calculated for the changing modulation conditions (e.g. changing drag) and a compromise correction
is usually established by using a suitable test record.
The previously held view that $F$ diminishes with reducing stylus-togroove velocity (such as at the inner diameters) is currently under question, some authorities claiming that the drag due to components other than modulation remains substantially constant over the disc.

Accurately corrected side-thrust can reduce the required tracking weight by as much as 20 per cent.


Fig. 19. Illustrating side-thrust, where force $F$ is equal to $f \sin \phi$ $\times \cos \phi$.

## TURNTABLE REQUIREMENTS



Detail of the Goldring-Lenco continuously variable speed control

Belt drive can ease the problem of noise coupling from the motor. With both belt and idler wheel systems speed change is provided by stepped or continuously variable diameters on the motor drive shaft, with the idler, like the belt, acting as pure transmission, and not affecting the drive ratio.

An interesting arrangement is adopted by Leak and GoldringLenco transcription units ior continuously variable speed change, where the idler wheel is made to slide along a conical motor drive shaft (see photo) to its preset speed position.

Constant speed under all normal operating conditions including stylus drag and cleaning brush friction is essential to avoid wow and flutter. Large mass and dynamically balanced turntables help with this problem, so that the motor needs only to transmit a relatively small amount of energy to keep the turntable at constant velocity.

## WOW AND FLUTTER

Wow, which is caused by turntable speed variations below 20 Hz , and flutter, which results from speed variations at a higher rate, are far more disturbing than consistent speed error.

The percentage wow and flutter is given as
wow and flutter

$$
\frac{\left(f_{\max }-f_{\min }\right) \times 100}{f_{\mathrm{av}}}
$$

per cent
where $f_{\text {max }}$ and $f_{\text {min }}$ are the maxi-
mum and mınımum frequencies and $f_{\mathrm{av}}$ is the average frequency, usually based on 3 kHz . Measurement is by a wow and flutter meter and the readout may be in peak or r.m.s. value.

The minimum DIN requirement is not greater than $\pm 0.2$ per cent peak, but to be undetectable to acute hearing the wow must not be greater than 0.3 per cent and the futter not greater than 0.15 per cent.

Drive motors are mostly a.c. mains operated and of quasisynchronous nature. They are usually adequately decoupled from the turntable bearing by rubber buffers or springs. The whole motor board, too, may be decoupled from the plinth to reduce shock excitation of the pickup.

A fairly recent idea is the use of a Wien network oscillator for driving a synchronous motor, the motor speed thus being adjustable by varying the oscillator frequency, Servo controls have been mooted. but in general the a.c. motors and turntable units of today are well compatible with the associated components of the system and do not really justify such sophistication.

## SPEED ERROR

The DIN minimum speed error tolerance of +1.5 per cent and -1 per cent is generally well met and is reasonable since an error of $0 \cdot 2$ per cent corresponds to a change in pitch of less than $1 / 30$ th of a semitone. Nevertheless, listeners blessed with perfect pitch should consider a unit with limited speed control.

## RUMBLE

Rumble is quoted relative to a given level of modulation, the greater the level the greater the signal/rumble ratio. Rumble expressed as, say, 40 dB below $5 \mathrm{~cm} / \mathrm{s}$ at 1 kHz RIAA implies that the rumble is relative to a signal of that frequency and level, with the rumble itself being measured via RIAA equalisation.
Other filters may be incorporated in the readout to weight the disturbance and to eliminate high frequency noise. For meaningful comparisons the nature of the measurement must be known, and this is not always given in the specification.


T111s is the concluding article in the present series: it is mainly concerned with a project for the detection of the decametre radiation from the planet Jupiter. but also explains how al radio map of the sky may be produced.

## RADIATION FROM JUPITER

In 1955 Burke and Franklyn in America were testing a large aerial system. With the team was F. Graham-Smith, one of the original team under Martin (now Sir Martin) Ryle at Cambridge. Graham Smith and the other members of the American team had noticed that there was a regular outburst of radiation which was very like the sun in some respects. Someone jokingly said perhaps it is Jupiter and in fact Jupiter was in the beam of the aerial when the radiation appeared. A check was made and it was indeed found that the planet was radiating on frequencies around 16 to 22 MHz .

When listening to these radiations the sound from the loudspeaker is very much like the sound of the ebb and flow of the sea on a shingle beach. It is quite distinctive and easily recognised in the midst of other radiation; it changes in level very rapidly and may vary by as much has a hundred times in the course of a few seconds.

As this particular part of the frequency band is full of activity, daytime observation is difficult even with an interferometer: thus the majority of observations of Jupiter are made at night. 'This particular problem has received a great deal of attention by Warwick and others in America but not much elsewhere, apart from the author's work in collaboration with Florida State University.

## BY F.W.HYDE • PART 10

There are a number of observatories in America juvolved names associated with the work are (Alex) G Smithpand T. D. Carr at Florida University: and recently workers at Meudon Observatory in France have taken a new approach to the problem. It is not possible to do more than give a brief account of this phenomenon of the Jupiter radiations. Various theories have been proposed over the past several years.

Obviously, there is still much to be done in the way of observation, and as the aerials and receiving equipment needed are extremely simple, Jupiter is now a worthwhile project for the amateur. Indeed. work can now be done in the back garden, because of a simple type of aerial which the author has brought into use.

Formerly. a large corner reflector was required and remembering that at 18 MHz , one of the particular frequencies used. the wavelength in physical length is some 54 ft . a corner reflector is quite large even with a half-wave dipole-being some 40 ft high and 40 ft long cone of the author's large aerials is shown in the photograph).

## EQUIPMENT REQUIRED

The requirements for the Jupiter project are a suitable yet simple aerial, a pre-amplifier, a communications receiver. a d.c. amplifier, and a recording system. The block layout is shown in Fig. 10.1

The simple aerial already alluded to is a loop which is nearly closed and it may be used in the normal way without a reflector, in which case it will have the usual figure of eight polar diagram. A reflector of mesh added gives an increase in gain


Fig. 10.1. Block diagram of Jupiter Receiving System


Fig. 10.2. A recording of radiations from Jupiter
with the loop facing the source of energy. This aterial is not unduly critical as to bandwidth so that an aerial designed for 20 MHz will operate quite well between 18 and 22 MHz . This is quite an important factor, because it may be that some radiations will appear in any part of this band. Also, if the band is somewhat crowded the tuning point can be changed to find a quiet spot.

Because of the nature of the Jupiter radiations the normal time constant of the communications receiver is used. If the pre-amplifier provides of the order of $20-30 \mathrm{~dB}$ gain, it will be possible to use the direct output from the receiver, or to feed the d.c. amplifier direct from the second detector, with no intermediate long time constant detector section.

Much of the professional work that has been done in the past has been with high-gain receiver frontends, and recordings made on low resistance recorders with an incorporated rectifier. If the recorder had no rectifier then a 1 mA bridge rectifier such as the Westinghouse meter rectifier was used. The results of such observations are shown in the recorded chart in Fig. 10.2.

Bearing in mind the description of the sound of this radiation, it will still need some practice, both aurally and visuaily, to determine that which is of Jovian origin, and that which is from man-made and extraterrestrial sources. More will be said about this at the end of this article.

## AERIAL CONSTRUCTION

Details of the loop aerial are given in Fig. 10.3.
The best material for the aerial element is halfhard aluminium tube of about one half inch
diameter. The reflector should be of 1 in to $1 \frac{1}{2}$ in square mesh of $16 \mathrm{~s} . \mathrm{w} . g$. galvanised wire with welded joints. This is a readily available item in most hardware stores.

The frame can be of timber or metal according to choice. If metal is used then make sure that all parts of metal that touch are electrically bonded.

The mounting of the aerial can be left to choice, but this is an opportunity to make up an equatorial mounting, and the diagrams in Fig. 10.4 give some suggestions in this respect. The aerial and preamplifier should be mounted on the back of the reflector. It is suggested that another additional pre-amplifier be employed at the receiver.

## PRE-AMPLIFIER

Two examples of suitable pre-amplifier circuits are shown in Fig. 10.5. The type of transistor can be changed to suit, provided the parameters are the same. Those shown are the types used in the original equipment and which have given reliable service.

A warning is perhaps advisable here about breakthrough. If attempts are made to use this radio telescope where there is much commercial operation, breakthrough may be troublesome and in some cases damaging. A check should be made with an aterial located at the receiver to observe the state of the band before connecting the main aerial and its pre-amplifier. Also, it is as well to have the aerial pre-amplifier switched off when not in use, for it too could suffer from overloading.


Fig. 10.3. Loop aerial constructional details


Fig. 10.4. Suggested mounting arrangement for loop aerial centred at 20 MHz . This provides for equatorial and altazimuth adjustment


Fig. 10.5a. A simple aerial pre-amplifier


Fig 10.5b. A two transistor aerial pre-amplifier

## FORM OF OBSERVATION

After a few trial observations and recordings, it would be possible to let the system run without direct supervision. This is of course very simple in the case of the interferometer for most of the interference will be avoided. In the case of the simple oneaerial system, as just described, attendance of the observer is necessary to ensure acceptable observations and until sufficient experience has been gained in assessing the recordings obtained. If possible, the recordings should subsequently be examined by an observer who has this experience.

This is mentioned because to be useful the observations should be made over as long a period as possible, and it is not very convenient nor desirable to spend up to eight hours on direct observations.

The important times are in fact the two hours before and the two hours after the planet passes the meridian. There are special reasons why the earlier and later observations can be useful. For example: important information about the ionosphere after sunset can be obtained; and, after say 03.00 a.m., the rise of the dawn chorus can be recorded. This latter phenomenon is quite striking when first experienced, and the effect on the recording can be seen in the example given in Fig. 10.6.

## MAKING A RADIO MAP OF THE SKY

The list of sources given in Part 7 is short and covers only the more powerful sources, though even some of these may be below the threshold of recording where the simple telescope is used. It is however a practical and useful exercise to make a radio map of the sky from the point of observation. There will be a considerable difference between the maps made in the northern hemisphere and those made in the southern hemisphere. Such maps could be useful where correlation of results is at intervals ranging over the two hemispheres.

The procedure for building up a useful map is simple and involves two requirements: (1) a setting in altitude; (2) a sufficiently spaced scanning programme. The altitude changes will depend on the beamwidth in the vertical direction and the value of the scans will depend on having a number of days at the same scanning position. This latter requirement is necessary in order to take care of the varying conditions of the ionosphere and other effects on the transmission of the radiation through the atmosphere. Usually a four to six day run at each altitude selected should give a reliable set of data. The sequence is then as follows:


Fig. 10.6. Example of a pen recording of the dawn chorus


Fig. 10.7. Radio map of sky at 200 MHz . Values in arbitrary units

Set the altitude; record the runs: carefully log the conditions; examine each day and compare it with the next: lay the records over each other with a bright light under to assess visually the changes.

Make careful notes of any unusual or odd items on the recording. From this it will be possible to learn the effects of satellites, man made interference, air radiation effects and, at the frequency chosen, the rain static effects.

As a normal programme, a month of scanning should yield sufficient data for a reasonably accurate map. When the man is completed it would look somewhat like that shown in Fig. 10.7. The contour lines are at the points of equal intensity, and the whole presents a kind of relief map of the part of the sky covered. The value of the lines are arbitrary in the case of this project. but there is a standard evaluation and this is given in the appendix for those who would like a little mathematical information.

## POLARISATION

One point that should be mentioned here is that the energy that is received from extra terrestrial sources is polarised. Since the aerials in use are horizontally polarised, only half the energy from space is received in the horizontal mode. It might be thought reception should be set up in both planes. This is, in fact, frequently done and does offer a means of roughly determining the way in which the radiation is polarised. This might be left handed or right handed.

One reason for the more common practice of using horizontal receiving elements is that mechanically they are easier to construct but there is also another reason which relates to the electrical properties.

It is a fact that there appears to be less interference on the horizontal mode compared with the vertical mode. One reason for this is the amount of reflected radiation from the ground which also seems to carry a good deal of man-made interference.

With the corner reflector aerial there is protection from this type of reflection. If the aerial is turned so that the bottom edge of the reflector is near the ground the "spill-over" of the beam will mean that radiation from the ground is picked up. It is sometimes necessary to set another horizontal reflector to overcome this. Where the sensitivity of the system is low as in the first simple project described in this
series, the ground radiation (or temperature as it is described) will dominate in any case. The appendix also deals with this aspect.

## IN CONCLUSION

If there is sufficient interest in the promotion of projects that have so far been described in this series, it could be possible to organise them on a group basis, and so make a worthwhile contribution to knowledge.

Those wishing to follow such a line of observation. whether it be solar noise and/or polarisation measurements, together with the study of the Jupiter radiations, should contact the editor. This would enable the author to arrange the correlation of data with a view to publication of the results and credits to those who take part. It could also result in an exchange of information between like minded readers.

## APPENDIX

One method of assessing the intensity of the radiations received is based on Planck's law relating to the emission of electromagnetic energy at all frequencies from a "black body". This energy is related to the temperature of the body. For radio frequencies the Rayleigh-Jeans formula can be used and this is:

$$
B=\frac{2 K T}{\lambda^{2}}
$$

This gives the brightness of the source in terms of $T$ which is the temperature in degrees Kelvin and the wavelength $\lambda$ where $K$ is Boltzman's constant and is equal to $1.38 \times 10-23$ in MKS units.

The temperature of the earth radiation is of the order of $100^{\circ}$ Kelvin and this sets the lower limit of temperature that can be measured. This is one advantage of the large dish type aerial since the aperture can be trained away from the surface of the earth and so avoid these limiting factors.

Although there are not many books on Radio Astronomy there are sufficient in most libraries for the enthusiast to pursue these theoretical considerations.



This photo shows Chay Blyth at the chart table of the boat British Steel which uses Brooks and Gatehouse eleztronic instruments, including speed, depth and wind indicators; depth transducer selection switch is at bottom right of the panel. The instrument dials are ciften duplicated in a waterproof housing on the top of the cabin as shown on the 36 ft cruiser racer below


Mini computer using medium integration with seven-segment displays

## ELECTRONORAMA



ANOTHER boat show-another year of marine electronic development. although quite often it is hard to find what has been developed by who. This is mainly due to the lack of organisation in the press office at the show and not the firms concerned.

Medium scale integration has now found its way into the sailing scene and is incorporated in a depth indicator with seven segment digital readout, by G. M. Systems Ltd. Having ranges from 0 to 99 feet and 0 to 99 metres the unit has no moving parts (except a range. on/off switch and a draught compensator control) and is very compact. Main disadvantages are: no facilities for remote readout and the possibility that it is more difficult to judge the rate of change of depth from a digital display than from a meter or graph readout.

The G1000-F chart recording echo sounder for inshore fishermen, yachtsmen and small coasters has been introduced by Ferrograph. The new sounder is unusual in that it uses a specially prepared paper that is marked electrically avoiding the need for a special pen and ink

Another new product is the 050 radar from Decca. Smaller than the 101 and less expensive this new radar should be of interest to many small boat owners. Decea tell us that no corners have been cut to get the price down.

Other developments in small boat radar were announced by Kelvin Hughes (Type 17 radar developments) and EMI (new version of the Electrascan); no price increases have been made on the developed sets by either of these firms.

Brookes and Gatehouse have this year come up with no less than five new developments, admittedly one of those is a skin fitting for the existing boat speed indicator, but the other four are significant developments in the small boat electronics field. Three new B and G equipments are a sailing performance computer to calculate speed made good to windward, a "single signal" df receiver-a development of the Homer K receiver.

The Decca 050 radar is suitable for small boats under 40 ft


The interior of the Decca 050 display unit showing all the display electronics mounted on one printed circuit board

## ATTHE EHON

and a long-range echo sounder ( 100 fathoms). The fifth development is an improved distance-off-course computer. This computer uses a "new design" master compass which we believe has only recently been released for sale for non-military applications. This electronic polar locking (EPL) compass is also used in the "autopilots" made by Space Age Electronics. The main feature is that the bearing is unaffected by the movement of the boat however violent. The command pilot from Space Age Electronics shown on the facing page has EPL unit on the raised mounting and incorporates a remote hand held steering control unit -shown fixed to the pilot under the main control panel.

A new speedo/log that does not use an impeller or straingauge, merely a small transducer, and provides seven segment digital readout is now being offered by Detronic Ltd. The transducer is formed by an electrostrictive crystal transmitting an ultrasonic signal of 500 kHz . The unit works by measuring the frequency change of the signal reflected by the water (the signal is transmitted about 9 inches) due to the doppler effect. Hence a very accurate measurement can be made -0.1 of a knot from 0-9.9 knots and 1 knot from 10-99 knots.

The Baron Squire range is new this year, the main difference from their original range seems to be the housings and sealed indicators, some of which incorporate the electronics. They had an impressive display of units working under about a foot depth of water It is a pity that they do not improve their meter face design as this tends to be complicated and not very easy to read.

All in all plenty of new developments for the boat owner to consider and, with the advance of micro-electronics, perhaps some smaller, better equipments still to come.
The waterproof glass fibre radome houses the Decca 050 aerial and transceiver. This arrangement, fitted to a mast is most suitable to small motorised sailing boats where unshielded rotating scanners are unsuitable


Fairey Marine "Huntsman 31"


A selection of readers' suggested circuits. It should be emphasised that these designs have not been proven by us. They will at any rate stimulate further thought.
This is YOUR page and any idea prublished will be awarded payment according to its merits.

## UNIJUNCTION TIMER

Al.THOUGH it might be argued that a monostable could perform the same function as the circuit shown in Fig. I, it should be borne in mind that this is true for relatively short periods only. The circuit under consideration will perform happily for tens of minutes but to achieve the same time scale with a monostable would require enormously large electrolytic capacitors.

This particular circuit is also more straightforward in operation. To obtain the proper sequence from a monostable would necessitate the reversal of the initial states, i.e. the transistor which is initially off would have to be triggered initially on.

The purpose of the circuit is to manually switch on a power supply for a pre-determined period and leave it to switch itself off automatically. The power supply may be connected to a motor or some other piece of apparatus. In my project, it was used for a high-frequency transmitting oscillator.

When push switch $S_{1}$ is pressed, TRI is brought into conduction via RI and the relay is energised. The operation of the relay closes contact RLAI across the switch to act as a self-hold. Capacitor CI begins to charge via R4.

When the voltage on Cl has risen to the triggering level of the unijunction TR3, CI discharges into R3 which produces a pulse of sufficient magnitude to turn TR2 on. The base-emitter junction of TRI now has the $V_{\text {rep }}$ saturation voltage of TR2 across it. This voltage is lower than the requisite turn-on voltage so TR! is turned off, the relay is de-energised and contact RLAI opens. The supply is thus switched off.

The main requirement in the project was to consume as little power as possible since the equipment was battery operated. An RS Components, type 15 , relay was therefore chosen because it requires only 60 mW operating power.

The unijunction transistor TR3 is the popular GEC type 2 N 2646 and the values of R2 and R3 are those recommended by the manufacturer. Capacitor C1 was chosen to be $1,000 \mu \mathrm{~F}$ so that $\mathrm{C} 1, \mathrm{R} 3$ has a time constant of 100 ms , which is twice the release time of the type 15 relay.

The value for R4 is only a guide since there is a variation in the value of $\eta$ for the 2 N 2646 and electrolytic capacitors have such a wide tolerance. R4 will have to be finally chosen by trial and error. In the circuit which was constructed, a time delay of 5 minutes was achieved by using 100 k ! for R4.

The ballast resistance for the Zener diode may conveniently be a suitable indicator lamp. For example, with a supply voltage of 36 V one may employ an S6/8 type of lamp (RS Components) at $28 \mathrm{~V}, 0 \cdot 04 \mathrm{~A}$. A current of 40 mA through the Zener diode will provide good regulation since the greatest shunt path will be the 20 mA relay current.


Fig. 1. Circuit diagram of the unijunction timer. Terminals 1 and 2 go to equipment

## RR.F. AMPLIFIER FOR CAR RADIO

By using a low noise transistor in the circuit shown in Fig. 1 the average car radio's performance is greatly enhanced and stations previously beneath noise level become reasonably clear.

The circuit, having a high output impedance. is effectively tuned by the input circuitry of the car radio.

The gain control VR1 should be advanced as far as possible consistent with absence of cross-modulation and car ignition interference.

Using a separate battery B1, eliminates earth loop problems, the need for elaborate decoupling and will last at least nine months with continuous use.
P. E. J. Lacey, Crediton, Devon.


Fig. 1. Circuit diagram of the r.f. amplifier for car radio

## 

## TONE GENERATORS

|N the new British Patent 1245714 Standard Telephones and Cables Ltd. (STC) discuss the problems inherent in constructing tone generators for telephone dialling.

Electrical oscillators can be used for this purpose but the problem in this case is that the associated switch is of necessity heavily used and its contacts may show early wear. A contact-less generator uses a reed of magnetised material which is set in vibration by plucking; but the vibration of the reed is not easily sustained and the plucking and plucked parts are also susceptible to wear.

STC have devised and patented a tone generator which uses a transducer (e.g. piezo electrical material) mounted on a reed coupled to a bowed leaf spring, Fig. 1. Once the transducer is excited a circuit keeps the reed vibrating, but this vibration is normally suppressed by a mechanical damper, see Fig. 2. As the reed is on a bowed spring, however, it can be snapped between one of two positions and it is only damped in one of these positions. In the other position it is free to vibrate and, what is more, this snapping motion serves to start the reed vibrating. Vibration is then maintained by the electric circuitry.

In Fig. 2 STC show such an arrangement in side view.
The leaf spring is snap controlled by a push button loaded by sprinas, and in its up-bowed position the leaf forces its reed and transducer aaainst a mechanical damping bar When the push button is pressed. the leaf snaps into its down-bowed position so that the transducer is brought well clear of the damper, the snapping motion mechanivally jolts the reed into vibration. This vibration is then maintained by an amplifier with two high qain transistors functionino as an oscillator by
virtue of a feedback loop, Fig. 3.
Usually the reed will be formed by a tongue cut out of the spring by a U-shaped incision and the transducer by a sandwich of piezoelectric material between metal electrode layers.

## NeUTRRLISEO AMPIIFERS

|N BP 1241285 Mullard Ltd. out line the advantages and disadvantages to date of neutralised transistor amplifiers.

According to Mullard the advantages of neutralising the basecollector capacitance of a transistor in an amplifier (to minimise unwanted feedback due to such capacitance) are increased gain and stability. Such neutralisation can be achieved by a neutralising capacitor circuit.

However, as there is frequently a spread in the value of the basecollector capacitance and as a fixed value component is normally used for neutralisation, there is clearly a problem that under some circumstances the transistor may be over-neutralised and have a tendency to oscillate, while under other circumstances the transistor may be under-neutralised and have its gain seriously reduced. Ideally the neutralising capacitor would be matched to a particular transistor for the best possible compromise, but this is hardly practical for normal use.

The Mullard solution is to use a semiconductor body which has a transistor and a neutralising capacitor incorporated in the one case, the latter having a value appropriate for neutralising the capacitance of the base-collector junction.

The neutralising capacitor is formed from the same material as the transistor, but with opposite conductivity type regions as the base-collector junction. Usually this will be by the same diffusions.


Fig. 1


Fig. 2
The collector or base region of the transistor is connected to the region of corresponding conductivity type of the capacitor and the amplifier circuits so arranged that during operation there will always be a virtually complete cancellation of signals fed back to the base of the transistor via the two junctions.

By making the neutralising capacitor in the same semiconductor body as the transistor, it becomes possible to hold the ratio of their capacitances to within 5 per cent or better even though their actual capacitance values may vary by $\pm 30$ per cent.

In Fig. 1 Mullard show how conventionally a neutralising capacitor C1 is connected between the base of a transistor and the side of a parallel LC tuned circuit away from the transistor collector. In Fig. 2 there is shown the manner in which the transistor and neutra. lising component C1 of Fig. 1 is realised as an integrated circuit.

The patent gives full details of the actual semiconductor bodies that can be used for realisation.

BP 1245714


Fig. 2



THE circuit of servo amplifier "B" is basically similar to that of servo amplifier " $A$ " and with the exception of D1, C2, VR2, VR3, D2, C3 (Fig. 5) the action is the same. In this circuit TR1 is complementary to TR2 and $V_{\text {be }}$ voltage changes with temperature are therefore eliminated. TR 10 replaces the resistor R8 of the long-tailed pair in amplifier "A" and acts as a constant current source, bias being determined by R10, R8a and R9b. Note that reducing R8b increases the dead zone.
The use of a complementary emitter pair enables R2 to have a higher value and the input impedance is high. If large values of C1 and R1 are used, R2 (approximately $10 \times \mathrm{R} 1$ ) may be fitted to swamp the leakage effects of Cl .

## DEAD ZONE OPERATION

The function of D1, C2, VR2 is as follows: if the input signal is increased, TR5 conducts more and TR3 and TR4 are turned on.

The collector of TR3 (bottomed) is approximately 0.2 V below the +6 V supply and, according to the setting, the wiper of VR2 may be at +4 V . The diode. D1 is therefore forward biased and C2 discharges to 52 V , there being a drop of 0.6 V across D1 and 0.2 V across TR3. This can be considered as being equivalent to connecting a $5 \cdot 2 \mathrm{~V}$ supply to the wiper of VR2 in place of +4 V ; the voltages associated with all sections of VRI are consequently increased.
If the input signal increase is not large the wiper of VR1 would have been initially not far from the

VR2 wiper is increased further, then another effect is involved.

If bottomed, TR3 and D1 discharge C2 relatively rapidly: thus in the example quoted, the motor is switched off prior to entering the "normal" position of the dead zone. On cut off, C2 is charged through VR2 relatively slowly; this time must elapse before the voltage at VRI is restored and the motor reverse should have traversed the dead zone.

The damping effect of C 2 can be tuned by means of VR2 to damp out persistent hunting. The components D2, C3 and VR3 have the complementary effect to D1, C2, VR2 and cause, by an amount set by VR3, the early cut-off of the motor in the reverse direction.

The fail safe operation is effected by changing the connection of R18 from 0 V when it has no significant effect to +6 V . This can be performed remotely, by using a relay. If R18 is less than R4 TR2 will cut off, and by selection the required torque unit setting can be obtained.

## CONSTRUCTION AND TESTING

The components should be assembled on a printed circuit board, the pattern and layout being similar to that of Servo A (see Figs. 6 and 7). On completion VR2 and VR3 should be set to have no action.

If hunting takes place, when testing with the decoder for a given time constant for R1-C1, then VR2 and VR3 should be adjusted to damp out the hunting.


Fig. 5. Circuit diagram of servo amplifier " $B$ ". The connection to R18 should be brought out separately if "fail safe" operation is contemplated

## COMPONENTS . .

## SERVO AMPLIFIER "B" (Fig. 5)

Resistors

| *R1 | 10ks | *R10 | 9.1kS |
| :---: | :---: | :---: | :---: |
| R2 | $100 \mathrm{k} \Omega$ | R11 | 680, |
| *R3 | 22k to 82k』 | R12 | $2.2 \mathrm{k} \Omega$ |
| R4 | $4.7 \mathrm{k} \Omega$ | R13 | $10 \mathrm{k} \Omega$ |
| R5 | 2.2k』2 | R14 | 10ks |
| R6 | 10ks | R15 | $2 \cdot 2 \mathrm{kS}$ |
| R7 | 750s2 | R16 | 18S2 |
| *R8a | and b $2 \times 2 \cdot 2 k \Omega$ | R17 | 18S |
| R9 | $750 \Omega$ | R18 | $4.7 \mathrm{k} \Omega$ |
| All | $\pm 10 \% \quad \frac{1}{6} \mathrm{~W}$ carb |  |  |

## Potentiometers

VR1 $500 \Omega$ linear, linked to servogeared motor VR2 1kS linear preset
VR3 1ks linear preset

## Capacitors

C1 $47 \mu \mathrm{~F}$ tantalum
*C2 $47 \mu \mathrm{~F}$ tantalum

* C3 $47 \mu \mathrm{~F}$ tantalum

C4 $0.1 \mu \mathrm{~F}$ polyester (mounted on motor)
C5 $15 \mu \mathrm{~F}$ tantalum
C6 $0.1 \mu \mathrm{~F}$ disc ceramic
Transistors

| TR2, TR5, TR6, TR8, TR10 | Contained in IC1 |
| :--- | :--- |
|  | CA3046 (RCA) |
| TR1, TR3, TR7 | 2N3702 |
| TR4 off) |  |
| TR4 | BFY51 |
| TR9 | OC84 |
|  |  |
| Diodes |  |
| D1, D2 OA202 | (2 off) |

Batteries
B1, B2 Two 6V dry batteries

## Miscellaneous

Printed circuit board
Solder pins
*See text


Fig. 6. Printed circuit pattern (full size) for servo amplifier "B"


Fiq. 7. Component layout tor servo amplifier "B"

## SERVO AMPLIFIER "C"

As shown in Fig. 8 the circuit is similar in form to servo amplifier " $A$ " but fewer components are used. The unit is compact and may be mounted directly on the torque unit. TR1 and TR2 (not thermally coupled) operate as a long-tailed pair with R4 adjusted to define the current so that TR3 and TR4 cannot be on simultaneously.
Changes in temperature and supply voltages markedly change the width of the dead zone which should for safety be made approximately 15 per cent of the range
TR3 is operated directly from TRI which despite
a gain of 100 may turn on slowly in relation to TR5. The selection of component values follows as for Servo amplifier "A."

## CONSTRUCTION AND TEST

The components should be assembled on a printed circuit board; the copper pattern is as in Fig. 9 and component layout Fig. 10
The unit should be tested as for servo amplifier "A" noting the absence of "fail-safe" circuitry and that the switching action of TR3 and TR5 in Fig. 8 is reversed with respect to the motor.

## COMPONENTS . . .

## SERVO AMPLIFIER "C" (Fig. 8)

Resistors

| R1 | $10 \mathrm{k} \Omega$ | *R6 | $4.7 \mathrm{k} \Omega$ |
| :--- | :--- | ---: | :--- |
| R2 | $750 \Omega$ | R7 | $10 \mathrm{k} \Omega$ |
| R3 | $750 \Omega$ | R8 | $18 \Omega$ |
| R4 | $6.2 \mathrm{k} \Omega$ | R9 | $18 \Omega$ |
| R5 | $2.2 \mathrm{k} \Omega$ | *R10 | $100 \Omega$ |

Potentiometer
VR1 $500 \Omega$ linear, linked to servogeared motor

## Capacitor

C1 $47 \mu \mathrm{~F}$ tantalum
Transistors

| TR1, TR2 | 2N3702 | (2 off) |
| :--- | :--- | :--- |
| TR3, TR4 | 2N3704 | (2 off) |
| TR5 | OC84 |  |

Batteries
B1, B2 Two 6 V dry batteries
Miscellaneous
Printed circuit board
Solder pins
*See text


Fig. 8. Circuit diagram of servo amplifier "C"


Fig. 9. Printed circuit pattern (full size) for servo amplifier " C "


Fig. 10. Component lay" C " for servo amplifier "

## FAIL SAFE SYSTEM

As shown in the servo amplifier circuits, a means is provided to preset the torque unit rotation in the event of a transmitter or system failure. This is effected by changing the connection of grouped servo amplifier leads by means of a lightweight relay.

As shown in Fig. 11, a decoder output pulse is also applied through R1 and D1 to the base of TR1. Capacitor CI charges rapidly during the period of the pulse, the source impedance being R1 and the collector resistance $R x$ of the logic unit used (approx. $4 \cdot 7$ kilohms).


Fig. 11. Circuit diagram of "fail safe" system

## COMPONENTS . . .

FAIL SAFE CIRCUIT (Fig. 11)

## Resistors

R1 $1 \mathrm{k} \Omega \quad$ R3 $2.2 \mathrm{k} \Omega$
R2 $390 \mathrm{k} \Omega$
Capacitor
R4 $10 \mathrm{k} \Omega$

C1 $47 \mu \mathrm{~F}$
Transistor
TR1 2N3702
TR2 2N697

## Diodes

D1, D2, D3, D4 OA202 (4 off)
Relay
RLA 12 V 37 mA , two sets of change over contacts (minimum resistance 240 ohms )
Miscellaneous
Printed circuit board
Solder pins
Test lamp

## CHARGE TIME CONSTANT

Diode D1 prevents discharge back through R1 and the discharge time constant is $\mathrm{C}_{1} \times \mathrm{R}_{2}$. Assuming a decoder pulse of 1 ms per cycle period of 40 ms this ratio of $40: 1$ makes an effective charging time constant which is still greater than the discharge time and C1 steadily charges. The base of TRI is 0.6 V $V_{\text {be }}+(2 \times 0.6 \mathrm{~V})(\mathrm{D} 2+\mathrm{D} 3)$ below the +6 V rail (i.e. approx. +4 V ). When Cl is charged to this value TR1 cuts off and R4 ensures that the base of TR2 goes to -6 V cutting it off and allowing the relay RLA to release to the position indicated in Fig. 11 connecting the test lamp to 0 V .

Referring to servo amplifier B , this is the normal working state; the fail safe acts as inoperative and no current is drawn by the circuit shown.

## PULSE FAILURE MODE

In the event of pulse failure, the charge on Cl falls relatively slowly to about +4 V when TR1 turns on. The base current would be $4 / R$, and, assuming a gain of 100 for TR1, the collector current is

$$
\frac{4 \times 100 \times 10^{3}}{390 \times 10^{3}} \mathrm{~mA}
$$

or approximately $\operatorname{ImA}$ base current for TR2.

Assuming a gain of 50 , the collector current of TR2 would be about 50 mA sufficient for a small relay of more than about 240 ohms. The diode D4 is normally reverse biased but conducts when the relay is switched off protecting TR2 from the inductive back e.m.f. pulse from RLA.

## CONSTRUCTION AND TEST

The components should be assembled on a printed circuit board as shown in Figs. 12 and 13 with R1 fitted and a 6 V lamp connected for test, as shown. The copper strips retained under the relay must be arranged to suit the relay used.

With the $-6,+6$ and 0 V supply lines connected, the input should be connected to +4.5 V (from a battery or from a potentiometer across 0 V and $+6 \mathrm{~V})$. The time taken for the relay to operate and release on the application of +4.5 V should be noted. If the "make" time is slow and the "release" time less than half second, then Cl should be checked for excess leakage current.

The unit should then be tested in connection with the working decoder, it being noted that any output could be used, but it is preferable to use one with a defined pulse-to-cycle time ratio, such as the ungated complex one previously described.

The unused contacts may be wired for servo amplifier " $A$ " or' used with any non-proportional model function. The resistor RI forms a means to protect the logic units from accidental shorts.

The positive going logic output is derived from Rx and in certain circumstances this may produce only about 4.2 V at C 1 .

A momentary interruption of pulses may therefore cause the fail safe device to operate after too short an interval. In this case RI should be connected as shown. In cases where an exceptionally long interval ( +5 seconds) is required before fail safe operation, D2 and D3 should be replaced by a 3.5 V Zener diode.

Fig. 12. Printed circuit pattern (full size) for 'fail safe" system


Fig. 13. Component layout for "fail safe" system


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| 5Y3GT | ． 26 | 30L1s | ． 57 | E13F89 | ． 29 | EZ40 | － 22 | PFL200 | ． 52 | UC1181 | ． 32 |
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| 6AT6 | ． 20 | 30 PL13 | 89 | ECF80 | ． 27 | KT6］ | ． 55 | PL84 | －30 | CL4． | 12．00 |
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## ELECTROPSYCHEDELIA?

Flicker phenomena, discussed by many and at some length by Dr W. Grey Walter in his book "The Living Brain", is the effect which sometimes manifests itself as the result of the pulsating nature of the light from cine projectors, or the intermittent flashing of sunlight through roadside trees during a drive in the car. This phenomena is often exploited in such places as discotheques where strobed xenon lamps are employed.

The effect is difficult to describe in purely objective terms, but. for most observers, this generally seems to evidence itself as a form of pleasant swimming sensation or a feeling of moving through time. To a large extent the degree of influence appears to be related to the flicker rate of the lamp and, in this context, probably has the greatest effect when it is synchronous with the frequency of the "alpha" waveform produced by the brain.

The amplitude of this alpha rhythm seems, in most cases, to be very much suppressed so that for many individuals the phenomenon may be either just noticeable or entirely absent.

However, a method for selecting and, even, raising the intensity of the elusive rhythm has just been rediscovered. This has resulted in the brand-new craze which is currently sweeping through the U.S.A., previously called "photic" stimulation back in the 1950's, and now enjoying the title "bio-feedback".

In reality, the concept behind this bio-feedback lark is an attempt to help people teach themselves the art of controlling their brain rhythms, with the intention of encouraging an equivalent condition of that transcendental experience. only hitherto reached by masters of deep meditation!

Basic operation of a bio-feedback set-up will be seen from Fig. 1. Electrodes, dampened in saline

solution and attached to the subject's scalp, pick up the very much attenuated signals originating in the cortex of the brain. They are then amplified several hundred thousand times and, subsequently, filtered since the required signals are almost always buried deep in either noise, or unwanted signals of greater amplitude.

The resulting output is fed to a Schmitt trigger prior to operating a simple delay circuit which either flashes a lamp into the subject's eyes. or controls an audio oscillator. In this way the flash-rate and delay can be adjusted to achieve a constant positive feedback such that the lamp flashes at the most effective point in the brain's alpha waveform.

This, essentially, instant way of "mind-travelling" could have quite exciting possibilities and, although not a therapy worthy of recommendation to epileptics, may hold some of the keys to the more arcane aspects of psi phenomena.
I notice that this rather costly form of "everyman"s electroencephalography" is already beginning to catch on in this country. Anyone for back-pocket hypnosis?

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Fig. 2. Circuit diagram for varying speech rate


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## PUBLICATIONS

The Book of Transistor Equivalents (BP.1) 40p Handbook of Tested Transistor Circuits
by H. Ness (BP.3) Radio and Electronic Colour Code and
Data Wall Chart (BP.7) Data Wall Chart (BP.7)

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Fig. 2a. Unijunction symbol and nomenclature

(b)

Fig. 2b. Equivalent circuit of UJT


Fig. 3. Static emitter characteristic of UJT

The parameter $\eta$ is a constant and is termed the intrinsic stand-ofl ratio. It is that fraction of the interbase voltage which appears as part of the peak point voltage, this important parameter is a constant for a given device and the value lies between 0.51 and 0.82 . The equivalent diode emitter voltage ( $V_{\mathrm{I}}$ ) is in the order of 0.5 volts depending on the UJT and the temperature. With an increase of temperature $V_{\mathrm{I}}$ decreases, but it is possible to overcome this variation by making use of the positive temperature coefficient of $R_{1315}$. If a resistor $R_{2}$ is used in series with base-two (see Fig. 2) the temperature variation of $R_{\text {及a }}$ will compensate for the original loss.

## TYPES OF UJT

Fig. 4 a shows the conventional type (UJT) which is a single junction device having an emitter and two dissimilar bases.

Fig. $4 b$ is called a complementary type (CUJT) and works by applying opposite current and voltage polarities to those used in the conventional UJT. A greater circuit flexibility is now obtainable and can be comparable to $p / n p$ and $n p n$ transistors. The CUJT has shown better stability, improved uniformity and closer intrinsic standoff ratio. It is more reliable over the specified temperature range allowing less compensation control.

## TABLE 1: UJT NOMENCLATURE

| SYMEOL | DEFINITION |
| :---: | :---: |
| $I_{\text {E }}$ | Emitter current |
| 1 EO | Emitter reverse current |
| $I_{P}$ | Peak point emitter currert. The total emitter current that can flow without |
|  | permitting the UJT to go into the negative resistance region. |
| IV | Valley point emitter current. Represents the current flowing in the emitter when the UJT is biased to the valley |
| $R_{\text {B13 }}$ | point. <br> Interbase resistance. Tre resistance |
| Ras | measured between base-tmo and baseone at a specified interbase voltage. |
| $V_{\text {bi }}$ | Voltage existing across base-two and base-one. |
| $V_{p}$ | Peak point emitter voltage. |
| $V_{D}$ | Forward voltage drop of the emitter junction. |
| $V_{v}$ | Valley point emitter voltage. |
|  | Intrinsic stand-off ratio. |
| $\alpha R_{B R}$ | Interbase resistance temperature coefficient. Variation of resistance between B2 and B1 over the specified temperature range. |



Fig. 4. Types of UJT. (a) conventional UJT; (b) complementary UJT; (c) programmable UJT (PUT)


Fig. 4 c illustrates a third configuration, termed a programmable type (PUT). The PUT is programmable in that a number of characteristics that are set in the conventional type (i.e. valley current, peak current and interbase resistance) can be adjusted accordingly or programmed into the PUT at the designer's discretion. With careful selection of additional resistors the designer can turn the device into any one of a large number of discrete UJT's.
The PUT is a planar passivated ponpn element and hence is not a true UJT, it is conventionally represented by a symbol similar to the SCR. The PUT's electrodes are known as the anode, gate and cathode, which cerrespond to emitter, base-two and base-one respectively.

## FLEXIBILITY

The UJT is a unique device in that it can be used for any number of applications involving oscillation. timing circuits and triggering devices for turning-on thyristors.
UJT's offer the advantage of being excellent circuit simplifiers allowing the elimination of a number of components. For example, one UJT used in the bistable mode (sec Fig. 5) can provide the function that normally would require two transistors and the associated capacitors and resistors. Outputs can be taken from any of the three electrodes: an
approximation of a sawtooth waveform from the emitter; a positive pulse from base-one and a negative pulse from base-two. A high degree of frequency stability and accuracy can be obtained by the careful selection of the timing constants RC.

## APPLICATIONS

A full-wave control circuit shown in Fig. 6a with Zener clipped rectified voltage Fig. 6b. The resistor $R_{\mathrm{d}}$ is chosen to limit the current through the diode D1 enabling this device to work within its rated specification

Fig. 7a shows a unijunction trigger circuit for a gated thyristor and its associated waveforms Fig. 7b. As capacitor Cl is being charged current ( $I_{\mathrm{FO}}$ ) flows through the interbase resistance ( $R_{\mathrm{BB}}$ ) of the unijunction. say of the order of $1 \mu \mathrm{~A}$. Resistance $R_{\mathrm{B}}$, is included in the circuit to provide a path for this current and prevent an undesirable turn-on of the thyristor through its gate. $R_{\mathrm{R}_{3}}$ is calculated so that a maximum voltage developed across it will be less than 0.2 volt. For a typical UJT the resistance of $R_{\mathrm{NB}}$ lies between 4.7 kilohms and 9.1 kilohms, so with an applied operating voltage of 20 volts, the value of $R_{\mathrm{B}}$, would be:

$$
R_{\mathrm{B}_{1}}=\frac{0.2 \times R_{\mathrm{BB}}(\mathrm{~min})}{V_{\mathrm{S}}}=\frac{0.2 \times 4.7 \mathrm{k} \Omega}{20}=47 \mathrm{ohms}
$$



Fig. 7. Relaxation oscillator trigger circuit and associated waveforms

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\end{aligned}
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To ensure the UJT remains stable during an increase of temperature an additional resistance $R_{\mathrm{n}_{2}}$ is connected in series with base-2.

A half-wave trigger circuit is shown in Fig. 8, where the thyristor is acting as a rectifier and power control device. No power is supplied to the load during the negative half cycle, but a variable power is supplied to the load during the positive half cycle.

During the positive half-cycle the gated thyristor is switched on by a time (phase angle) determined by the control current. The relative power in the load can be controlled by varying the phase angle when the thyristor is switched on.


## SHUNT TRANSISTOR CONTROL OF UJT

Phase control can be obtained by use of a pnp or npn transistor connected to shunt with the emitter capacitor of the unijunction. The amount of current in the base of the transistor will control the effective charging current to the capacitor, and hence will control the trigger angle of the UJT and the SCR.
Fig. 9 shows a phase control circuit and functions as follows. Transistor TR1 shunts some of the charging current supplied to capacitor C 1 by resistor R1 in an amount dependent on the base drive of TR1. The more TR1 is turned-on, the later the UJT will trigger, consequently lowering the output of the SCR. Depending on the value of R1 and the base drive to TR1 the diversion of charging current from Cl will advance or retard the trigger angle accordingly.

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## YEAR BS9000?

It's been a long time coming but this could be Year BS9000. Just to refresh your memory, BS9000 was the outcome of the Burghard Report or, to give its full title, '"2nd Report of the Committee on Common Standards for Electronic Parts." The Report was published by H.M.S.O. in 1965.

The following year the Report was accepted. on behalt of the electronics industry by the conference of the Electronics Industry and the British Standards Institution was given the task of implementing the recommendations: Supervision of the operation on a practical day-to-day basis is the responsibility of the Electrical Quality Assurance Directorate of the Ministry of Defence.


The BS9000 scheme set out with the finest ideal and that was to formulate a new and up-to-date set of specifications for electronic components which would ultimately supersede the rag-bag of specifications originated in the United States and Europe over the years. Clearly this would be a major operation but few people, in my opinion, realised what a mammoth task it would become. The technical problem was big enough to begin with. Add to it the democratic process involving countless committees on which were representatives not only of BSI and the Ministries but also of manufacturers and users, all trying to reach a consensus, and you get some idea of why BS9000 has been so long on the runway, so to speak, without getting airborne. But movement is now in sight.

Mr John Hinchcliff, Assistant Director (Components), Electrical Quality Assurance Directorate, Ministry of Defence, is at the centre of BS9000. At a recent dinner
organised by component distributors he revealed a few facts and figures on progress to date.

All the basic BS9000 specifications and many supplementary specifications have now been published. Almost 200 component manufacturers, distributors and test houses have applied to join the scheme and over 80 have so far been fully approved to operate it. More than 100 components (or component families) have been or are being approved and this figure is doubling every six months. About 200 military semiconductor specifications have been brought into the system and military digital integrated circuits are soon to be included. Nevertheless, stated Hinchcliff, there is still an enormous way to go. Several thousand components will eventually be drawn in.

BS9000 has been a source of irritation to the Americans. They see it as a protectionist policy under which their long established military specifications and quality assurance procedures will become obsolete and will no longer be specified in British equipment to the detriment of American exports.

Meantime, the Europeans have not been idle. In 1967 they instituted their own Harmonised System of Quality Assessment for Electronic Components under the title CENEL 1. Britain joined CENEL 1 as a full member with France, Germany and Italy with an understanding that each country would mutually recognise standards, approvals. and methods of inspection as equal to their own. Other European countries are in process of joining.

To cap it all, the International Elestrotechnical Commission (IEC) is considering a similar system to operate on a world-wide basis. Clearly, world standards would be best of all but will take many more years to achieve leaving, as one disgruntled components man remarked to me, the fall guy in the middle hacking his way through a jungle of national and international specifications as best he can.

## ABSENTEES

The British contingent at this year's Paris Components Show (April 6-11) will be one of the smallest on record, numbering little over 20 companies. Last year's show was both expensive and disappointing and this, I suspect, is why so many "regulars" of previous years have decided to stay at home this year despite our imminent entry into the Common Market.

But this doesn't explain why industry giants GEC and Plessey have decided to stay away from the big IEA Show at Olympia in May. Selectivity seems to be the answer. Publicity managers with restrizted
budgets have spent sleepless nights worrying over the optimum split of funds between direct mail shots, press advertising, exhibitions, and even the supply of book matches. And exhibitions seem to be losing out.

## TOTAL CAPABILITY

Total capability, it's a hackneyed phrase but.it still means something when attached to Decca Radar, still proudly holding the Number One Spot as world suppliers of marine radar and determined as ever to stay there in what, by any standards, is a highly competitive business.

Deeca launched the biggest radar event of the year. Not half a dozen, nor even a dozen, but a dazzling two dozen new models on show for the first time, twenty of them for coastal and open sea use and four river radars. All the new radars owe a lot to the solid state RM914, introduced just a year ago and which won the Queen's Award for tezhnological innovation.

The RM914, already topping 3,000 sales, was a runaway success. Big features were a solid state local oscillator, solid state modulator, and wide use of integrated circuits. The same modules, or derivations of them, are in all the new models which come in a huge choice of display sizes, scanner sizes, transmitter powers and optional facilities.

Decca's competence in advancing the state of the art in marine radar is perhaps most convincingly demonstrated by one simple fact. The latest 25 kW radar with a 60 mile range consumes no more power than the 3 kW , 24 mile range D202 model which Decca introduced as the first commercial marine radar to use transistors in 1963.

## DIVERSIFICATION

The high-powered "think-tank" at Frimley which we have known as E-A Space and Advanced Military Systems Ltd and more conveniently as EASAMS since 1962 has now officially become EASAMS Ltd.

Reason for the change of name is a change of emphasis although marketing manager R. M. French assures me that EASAMS still has plenty of military work. But the sort of systems analysis and engineering which made EASAMS famous is now being applied equally effectively in the civil field and not only in electronics. Examples are the design, construction and commissioning of new hospitals, the development of transport and distribution systems, and ports and harbour management.

At the same time there is plenty of electronic work such as studies for ESRO and on the MRCA project.

# Readour A SEIECTION FROM OUR POSTBAG 

Correspondents wishing to have a reply must enclose a stamped addressed envelope. We regret we are unable to guarantee a reply on matters not relating to articles published in the magazine. Technical queries cannot be dealt with on the telephone.

## Abysmal writing

Sir-As a regular subscriber to your normally excellent magazine. I feel that I must protest at what has become its present standard of presentation. You have excellent news columns, excellent features, and many highly interesting projects. hut I have now become convinced that the standard of presentation of your projects has now fallen to a level where they are intelligible only to those who are experts in your pseudo-scientific jargon.
This situation was drawn to my attention about a year ago during the course of 6th Form Electronics that d teach. I use, for this, back copies of P.E. as source material for student projects, but increasingly I have been aware that these 17 - and 18 -year-old Grammar School pupils were just unable to understand what your projects were about. Often 1 am faced with the plaintive. "What on Earth are they trying to say." My initial reaction was to blame them. but now I realise that I have been quite unjust. some of what appears is quite unintelligible unless you have prior knowledge of what the project is about.

In your December 1971 issue your article about Logical Radio Control is the most abysmal example of semi-scientific writing I have seen in many years as a professional scientist. By pooling the resources of two physics graduates. two graduate electrical engineers, the 6th Form and myself, we have worked out how this system can be used to control six channels, but it has taken us two weeks to work it out. God help those who are less adept than ourselves-they will just move on disillusioned.
How much simpler it could have been if someone had taken the trouble to explain the significance of each pulse, the significance of each pulse length and the significance of the need to transmit pulse trains. If you search, some of this material is present. mixed up with the wonders of the technicalities. But most is absent.
In the same issue your article I.C. Digital Dice reduced some of my 6th Form to glassy eyed disbelief I offer the following paragraph as an example of how this article could
be made much more intelligible to a much wider public:
"A dice generates the numbers I to 6 in a random order. This device achieves this in the following manner. A signal generator produces a series of electrical pulses, which are then counted in binary form. The counter counts from 1 to 6 . and then returns to 1 . The sequence of numbers is repeated over and over again just as tiong as pulses are fed to the counter.

To make the dice random, and cheat proof, we must be able to stop the counter when we do not know what the count is, and we must make the rate of counting very high.

The dice described generates pulses at 4.800 per second, so that each number from 1 to 6 appears 800 times a second. and each time it appears for only $1 / 4.800$ second. This is too fast for the eye and hand to see, and so when ever the counter is stopped the numbers must be in a random order.

1 am prepared to admit that many readers would not require such a simple approach to a project, hut such an approach to presentation would take all the mystery out of electronics. If you or your staff are intent on producing working diagrams that are easy to follow. even
to the non-expert. surely it is more than worth while making the description of what a device is supposed to do. and the broad principles upon which it works as clear as possible.

In conclusion may 1 pass the opinion that the now defunct Beginners Columns. and your complimentary magazine, Eviryday Electronics also have the same problem. a pre-occupation with jargon, little thought being given to clarity.

I hope my comments are of interest and assistance.
W. G. Joncs.

Lancs.

## Not logic

Sir-I have noticed with considerable interest your recent articles in P.E. on Logical Radio Conirol. It does however seem to me that you appear to have contradicted yourself on the shift-register section of the decoder.

You say that following the "clear" pulse the first signal pulse "turns on" the first flip-flop and the second signal pulse causes the second output to change to " 1 " and the first output to revert to "0" However, in Fig. 19b the waveform for the output (QI) of this flip-flop remains up for five of the signal pulses, not resetting to 0 after the first.

The way I see it is that following the clear pulse the first signal pulse will. as you say. set the first flipflop to "l". The second pulse will also set to "l" the second flip-flop. but since the input conditions to the first and sixth flip-flops have not changed neither will change state and the first flip-flop will remain in the "l" condition. So after six pulses all the flip-flops will be set which will not realfy work as a proportional system.



Ano:her point to note is that the master-slave type of flip-flop recommended triggers on the trailing edge of the clock-pulse: thus, assuming your circuit did work as you suggested. following the clear pulse the first flip-flop would not set until after the first pulse and would remain set for the interval plus the duration of the second pulse, thus the first channel would be "lost".

The enclosed circuit. Fig. 1. is my idea for the answer to the problem.

The clear pulse resets BSI, and sets BS2, the latter providing one input for Gl which. together with G2. forms an and gate. Thus the leading edge of the first pulse will enable G1 and G2, and hence set the first flip-flop in the shift register for the duration of the signal impulse. The trailing edge of the pulse will reset the first flip-flop. set the second, and will also indirectly (via the first flip-flop) se: BSI which. in turn. resets BS2. closing the AND gate, preventing the setting of the first flip-flop until the nexi clear pulse.

The second and subsequent flipflops in the chain will each set for the pulse length plus the interval. The clear pulse is applied to the first flip-flop in the register, to ensure correct triggering of BSI .

I hope my comments have been constructive, and look forward with great anticipation to your article on the Servo Motor Control. In fact. I was wondering whether, now you have gone so far, you might go the whole way and describe a suitable transmitter and receiver, possibly using integrated circuits as well?
M. C. Tiend. Chelmsford.

## Triggered

Sir-First may 1 compliment A. J. Dunn for a very interesting series on Logical Radio Control. It has created a great deal of enthusiasm amongst myself and friends, but also some queries were raised.

One of these was with regard to Mr Dunn's circuit for sync detection using a retriggerable monostable, as the majority of constıuctors seem to prefer the Texas SN74 -range of TTL i.c.s and many suppliers do not stock retriggerable monostables.
To try to alleviate this problem I have designed the following circuit. It can be used to detect long "0" or "ll" pulses as required and uses
a 5 -bit shift register as counting timer (see Fig. 2).

As shown here the clear signal to JK flip flops is produced when a "I" has existed at the input for a time set by the frequency of the multivibrator. This could be made up from Nand gates (see Digital Dicc article. December P.E.) to make this circuit exclusively TTL.
To detect " 0 "s instead of " 1 "s merely invert the input.
L. Cook. Lancs.

## P.E. Scorpio ignition system

## TACHOMETERS

A large number of constructors have enquired about the possible effects of the ignition system on electronic impulse tachometers. Unfortunately none of the cars on which the system was tested were fitted with electronic tachometers and so we have no personal experience of these. As there are a large number of different types available. differing considerably in their requirements, we obviously could not make any positive recommendations without buying a sample of every available type, which would be impracticably expensive. There are. however, two basic types and we recommend that the constructor ascertains which type he has and experiments to obtain the best results.

## CURRENT OPERATED

These contain a current transformer which is normally connected in series with the ignition coil, or else the SW lead is wrapped around a small magnetic pick-up on the tacho. It should be possible to operate this type with the Scorpio by connecting it into the lead from the coil to $\mathrm{C} 6 / 7$ (tag 5) as there is a 10 A current pulse through this lead

## VOLTAGE OPERATED

These are normally connected between the contact breaker and earth and work either on the 12 V change of d.c. level when the contact points open or on the high voltage spike produced when the points open. With the Scorpio it should be possible to operate the low voltage type from the contact breaker, as normal, but the high voltage type should be connected to terminal 5 on the unit, or the tag on the ignition coil to which terminal 5 is connected.

## CARS WITH MULTIPLE CONTACT BREAKERS

A number of constructors have asked about using the Scorpio with two-stroke, three-cylinder engines having a separate contact breaker and coil for each cylinder. Unfortunately as there is no distributor it would be necessary to use three separate units and in view of the high cost we cannot recommend the use of the Scorpio with this type of engine.
D. S. Gibbs \& I. M. Shaw

## Ferret tracker

Sir-1 would be most grateful if any reader can offer any advice. I intend to start ferreting rabbits and previously I have used a ferret on a collar and line, digging up to the ferret by means of holes every 2 to 3 ft .

Would it be possible to attach a device to the ferret collar which can be tracked above ground level by some kind of electronic detector?

The ferret's collar is leather $\frac{8}{8}$ in wide. The average depth we dig is 18 in to 24 in deep, some odd holes 36 in deep.

If such equipment can be purchased would you be kind enough to forward on any details. it would be a tremendous asset.
D. Nunn, Suffolk.


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## Project 60 Stereo F.M. Tuner



First in the world to use the phase lock loop principle

The phase lock loop principle was used for receiving signals fom space craft because of its vastly improved signal to noise ratio. Now. Sinclair have applied the principle to an F.M. tuner with fantastically good results. Other original features include varicap diode tuning. printed circuit coils, an I.C. in the specially designed stereo decoder and squelch circuit for silent tuning between stations. Good reception is possible in difficult areas, and often a few inches of wire are enough for an aerial. In terms of a high fidelity this tuner has a lower level of distortion than any other tuner we know. Stereo broadcasts are received automatically as the tuning control is rotated, a panel indicator lighting up as the stereo signal is tuned in. This tunercan also be used to advantage with ny other high fidelity system.
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