

# ELECTRONICS WORLD

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## Design for Power:

- ACTIVE FILTERS FOR SUPERIOR FILTERING
- KIT-BASED APPROACH TO POWER
- PMICS FOR PORTABLE POWER

## MCU-BASED PLC: THE SERIES CONTINUES INSIDE



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MICROPROCESSORS  
ROADMAP

**ELECTRONICA 08**  
THE COUNTDOWN  
TO THE EVENT  
HAS STARTED



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ALSO IN THIS ISSUE: THE TROUBLE WITH RF @ TIPS 'N' TRICKS @ ROHS

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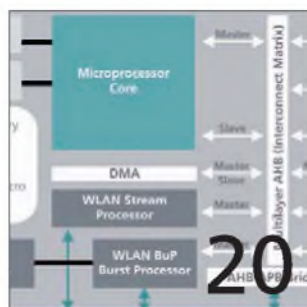


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## THE ELECTRONICA SHOWCASE

**T**wo years have gone by and Electronica – the biggest two-yearly electronics components and systems event in the world – is on again at the New Trade Fair in Munich, Germany, between 11th and 14th November.

But something feels amiss. Unlike any of the previous years, the buzz preceding the event has been somehow lacking. Previously, participant companies would start announcing new products and events or trying to organise meetings even in August. This year, things have been rather quiet. I hope it's not a reflection on how the event is going to pan out.

It'll be interesting to see what Electronica brings this year, however. As usual, I am expecting the buzz, the adrenalin, the hype, once the show opens its doors to visitors. But, it will also be a good indication of how European, American and even Asian electronics firms are doing. So far, we've seen that businesses have been cautious.

Expectations are that Electronica 2008 will be attended by some 3,000 exhibitors and 78,000 visitors. There are 14 exhibition halls in total, and this trade fair for components, systems and applications promises to present the complete spectrum of electronics, ranging from semiconductors, embedded systems, displays, sensor technology, test and measurement equipment, and electromechanics/system peripherals (previously classified at Electronica under interconnection systems/

components, switches, relays, keyboards and casing technology) through to electronic design.

According to the event organisers, this year's exhibition will focus on the growth markets of automotive and wireless. In addition to these two, other focus areas for Electronica 2008 will be on embedded systems and micro-nano systems, all of which will be presented as separate exhibition sections and a series of talks. Automotive and wireless will have their own two-day conferences.

This year, like two years ago, *Electronics World* magazine will have its own stand. We'll be in Hall A5 – more precisely A5.175/3. As last time, if you are at the Electronica 2008 event, we'd like to invite you to come by the stand, join us for a drink and share your views and announcements with us.

**Svetlana Josifovska**  
Editor

Check out Electronics World's new website by clicking on [www.electronicsworld.co.uk](http://www.electronicsworld.co.uk)



**“THIS YEAR, LIKE TWO YEARS AGO, ELECTRONICS WORLD MAGAZINE WILL HAVE ITS OWN STAND. WE’LL BE IN HALL A5 – MORE PRECISELY A5.175/3”**

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# Intel's 2009 Roadmap



At the recent San Francisco Intel Developer Forum, Pat Gelsinger, senior VP and general manager Digital Enterprise Group and Jim Brayton, Intel Nehalem project manager, are showing off the next-generation 45nm microarchitecture (codenamed Nehalem) wafer

Intel continues to march toward pervasive, higher performance and power-efficient computing, said Pat Gelsinger senior VP and general manager at the Intel Digital Enterprise Group, during his keynote speech at the recent San Francisco Developer Forum.

He detailed Intel's 2009 roadmap, disclosing a raft of new features of the next-generation processor family, including a new turbo mode that shifts the processor into a higher gear for greater performance and yet without the heat penalty.

The company's first desktop PC chips branded Core i7 processors and initial energy-efficient, high-performance server products (codenamed Nehalem-EP) will be first to production. Intel is also planning to manufacture a second server derivative designed for the expandable server market (Nehalem-EX), and desktop (Havendale and Lynnfield) and mobile (Auburndale and Clarksfield) client versions in the second half of 2009.

"Our engineers have put together an incredible processing family that will include a tremendous amount of new processor features, all centered on delivering faster computer performance and terrific energy efficiency," said Gelsinger.

The next-generation Core microarchitecture also features Intel Hyper-Threading Technology delivering

up to 8-threaded performance capability on four cores in the initial versions and best-in-class memory bandwidth, thanks to the new QuickPath Interconnect. QuickPath connects processors, chipsets and memory together, and delivers up to three times the memory bandwidth of previous generation Core microarchitecture solutions.

Gelsinger also discussed the industry's first many-core Intel Architecture (IA) based design, codenamed Larrabee. Expected in 2009 or 2010, the first product based on Larrabee will target the personal computer graphics market, support DirectX and OpenGL, and run today's games and programs. Larrabee is expected to kick-start an industry-wide effort to create and optimise software for the myriad of cores expected to power future computers.

In addition, Gelsinger said that another growth opportunity for Intel and the high-tech industry is the Internet (which Intel calls the Embedded Internet), where some 15 billion devices are expected to be connected to it in the near future. Among them will be the devices for the emerging markets in the embedded computing space such as IP networking and security, video intelligence, medical, in-vehicle infotainment and home automation, which will greatly benefit from the always-on Internet connectivity.

## IN BRIEF

- Researchers from the Hitachi Central Research Laboratory in Japan and the Advanced Technology Institute of the University of Surrey, UK, report that nano-designed transistors for the large area display and sensor application field benefit hugely from quantum size effects. The unexpected superior switching performance (low leakage current and steep sub-threshold slope) shown experimentally and analysed theoretically, demonstrate hitherto unexplored routes for improvements for transistors based on disordered silicon films.

By making the conduction channel in these disordered transistors very thin, the team has shown this technology will enable the design of low-power memory for large area electronics, based on a low-cost industry standard material processing route.

- Inside Contactless and Saetic are working together to incorporate Inside's MicroPass contactless technology into an upcoming family of contactless EMV products from Saetic that will be available in both plastic card and contactless sticker form-factors for the Spanish market.

The MicroPass platform is based on the RISC architecture and is designed to power open-standard contactless and dual-interface bank card payments along with other value-added applications.

- The Media Oriented Systems Transport (MOST) Cooperation, which standardises the MOST automotive multimedia network has demonstrated how this technology can be used as an automotive Ethernet physical layer. The multimedia demonstration showed MOST at 150Mbps bandwidth with high-speed Ethernet packet transport, multi-channel video streaming from HDD, as well as isochronous streaming of HDTV and SDTV. In addition to higher bandwidth, MOST150 features an isochronous transport mechanism to support extensive video applications, as well as an Ethernet channel for efficient seamless transport of IP-based packet data. The Ethernet channel can transport unmodified Ethernet frames as specified by IEEE 802.3. This enables software stacks and applications from the consumer and IT realms (where the speed of innovation is much faster) to be seamlessly migrated into the car.



## CONFERENCE AND EXHIBITION

4th–5th March 2009, Passenger Terminal Amsterdam (city centre), Amsterdam, Holland  
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*Gary Nevison is chairman of the AFDEC RoHS team, and Customer Support Manager, Legislation and Environmental Affairs at Premier Farnell. As such he is our industry expert who will try and answer any questions that you might have relating to the issues of RoHS, WEEE and REACH. Your questions will be published together with Gary's answers in the following issues of Electronics World.*

## BACKYARD OR ROADSIDE RECYCLING

Europe now finds itself in the centre of the contentious issue of "backyard recycling".

Organohalogen compounds are, in general, non-hazardous but a ban is being considered in an attempt to prevent uncontrolled and unsafe recycling practices that are carried out in India, China and Africa.

The fact that this happens is not in question and many people, especially the young, are harmed by the toxic chemicals that are emitted when some of these substances are burnt over open fires to recover materials such as copper, silver and aluminium from electronic waste that has reached end-of-life.

The export of WEEE (Waste Electrical and Electronic Equipment) from the European Union to countries where these practices occur is illegal as the recycling processes do not meet the requirements of the WEEE Directive, while it is also against the requirements of the Basel Convention on trans-border shipment of hazardous waste. The Basel "ban" was also based around an attempt to stop the developed world shipping e-waste to developing countries, in particular for recycling. While Europe signed up to this convention it still happens. The US has yet to ratify the agreement and still ships significant amounts of e-waste at end of life to China and India, probably as the recycling costs are one tenth of those back home.

Dr Thuppil Venkatesh, advisor to the National Referral Centre for Lead Poisoning in India states that "53% of the children under 12 have levels of lead in their blood that is causing brain damage and restricting their ability to learn". He goes on to talk about one of the contributing factors saying: "We are seeing an increased number of cases because more and more electronic waste is being handled by our people."

Dr Venkatesh, in his address to a Hazardous Materials Seminar in Bangalore earlier this year explained that the estimated cost of lead poisoning among children in India is over \$600m per year. Additional costs for adults excluded gastrointestinal disorders, anaemia, reproductive effects (including birth defects), cancer, kidney damage and cardiovascular disease (resulting from elevated blood pressure), which is 100% preventable.

While e-waste is burnt over open fires, acid baths are used to strip cable and PCBs for earnings of around \$100 to \$150 per month.

However, hazardous materials such as lead, cadmium, chromium, flame retardants and other toxins are found in e-waste. Inhaling, or regular handling of e-waste can result in damage to the brain, nervous system, lungs and kidneys, can cause cancer and even be fatal.

The raw materials in a computer for example, such as gold, copper coils, aluminium and other metals are worth money but to extract these, the motherboards are basically cooked, releasing arsenic, mercury, lead and other toxins which harm the body.

Despite the Basel Convention it is estimated that 50% of all US e-waste is "dumped" in India, China or Africa. Europe is far from blameless either, and an inspection of 18 ports around two years ago

**THE RAW MATERIALS IN A COMPUTER FOR EXAMPLE, SUCH AS GOLD, COPPER COILS, ALUMINIUM AND OTHER METALS ARE WORTH MONEY BUT TO EXTRACT THESE, THE MOTHERBOARDS ARE BASICALLY COOKED, RELEASING TOXINS**

found that 47% of e-waste destined for export was illegal.

Dr Venkatesh summed the problem up by requesting that developed countries stop sending their old computers to help with education. "Please, no charity, do not send your old computers and cell phones to us – you are killing the children", which is a sobering thought.

However, with a high demand for computers and people willing to do the painstaking work to recycle them for low pay, the industry is growing despite the dangers. Experts claim that as many as five million people work in this trade in India, often with minimal protection. Greenpeace in India, for example, is well aware of the problem and understand how dangerous the recycling is and the primitive procedures in use. Dismantling often takes place by bare hand with no protection at all, a spokesperson said. They go on to say that while the lawmakers in India are aware of the problem they are loathed to implement rules that would remove jobs for the poorest people.

The problem is not consigned to India as many countries, in particular China, receive a share of the millions of tonnes of e-waste that disappears from the developed world every year only to reappear in developing counties, despite the international bans.

In Europe, the WEEE Directive has been introduced and focuses on the funding and safe disposal of electronic equipment at end-of-life that was placed on the market after August 2005.

There are very few regulated recycling plants in the developing world. However, without the necessary investment in such facilities the e-waste problem is likely to grow, not least because of the increasing number of computers sold around the world and the attraction to the developed world of recycling a PC for \$2 rather than \$20 back home.

*Please email your questions to:*  
**[svetlana.josifovska@stjohnpatrick.com](mailto:svetlana.josifovska@stjohnpatrick.com)**  
*marking them as RoHS or WEEE.*





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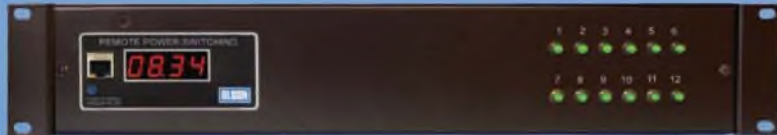
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# LOW DUTY CYCLE?

The phrase 'low' ('limited' or 'restricted') duty cycle appears in a large number of ISM band allocation descriptions, as a favourite method of allowing multiple users without calling for the complicated radio hardware that other access schemes (multiple channel, spread spectrum or listen before talk) require.

The principle behind a low duty cycle system is very simple: by restricting the duration and rate of repetition of any one user's transmissions it becomes statistically unlikely that they will coincide (collide) with those of other, similarly limited, systems.

In practice, the actual restriction is specified as a 'duty cycle', usually between 0.1% and 10%, depending on the band and the intended usage. In layman's terms this reduces to "you stab the button at random and hope like hell that you're the only one transmitting at that instant".

There are certain implications that result from this type of operation: The transmitter must be designed for efficient use of the available time. It must switch on and off cleanly (not generating AM splatter, like a GSM cellphone does) and the switching needs to be as fast as possible to maximise the time allowed for data transmission. The data coding must minimise the amount of time lost in preamble and synchronising sequences, and the overall data rate should be as high as practical (within other limitations, such as channel bandwidth).

At some point, a collision with another transmission and resulting loss of data is inevitable. The overall design of the link must allow for this.

In the simplest case, this is handled by 'user feedback re-transmission' (the light doesn't turn on, so press the button again). Although amusingly simple, this is sufficient for a large proportion of simple control systems, including almost all car radio-keys.

Where more sophisticated systems are considered, and data integrity must be maintained, then a more effective means of dealing with data loss is needed.

Sending the same data more than once will reduce (but not eliminate) the probability of completely losing a vital piece of information. In such a case, the

interval between re-transmissions must not be constant (a randomising function is required), or there is the risk of another, identical system in close proximity falling 'in step' and the re-transmissions always colliding.

Where no data loss is allowable (for example, in a data download application from a data logger), then a transmit/acknowledge protocol must be used. This requires transceivers at both ends of the link (opposed to the transmitter/receiver pair used by the simpler methods) and the transmission of a 'data received successfully' message by the destination end after each burst. The failure to receive such a message within a given time window will then cause the originating unit to re-send the same data. In this way, the transmission will be repeated until successfully received.

Additionally, once the complexity of a transceiver system has been implemented, then the user has the option of using other protocols beyond transmitting at random, as required (such as master/slave polling or master synchronised time slots), provided the



by Myk Dormer

actual transmission durations are within the spec limits.

*Myk Dormer is Senior RF Design Engineer at Radiometrix Ltd*  
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See **ERC-REC 70-03** for more information.

In addition to the duty cycle limits, this specification also states absolute transmission time limits too (otherwise a "10% duty cycle" system could transmit constantly for a year and then stay quiet for nine...!)

Maximum total time on in any hour:

3.6 seconds	0.1% duty cycle
36 seconds	1 %
360 seconds	10%

Maximum length of any given transmission:

0.72 seconds	0.1% duty cycle
3.6 seconds	1 %
36 seconds	10%

Minimum 'off' time between transmissions:

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3.6 seconds	1 %
36 seconds	10%

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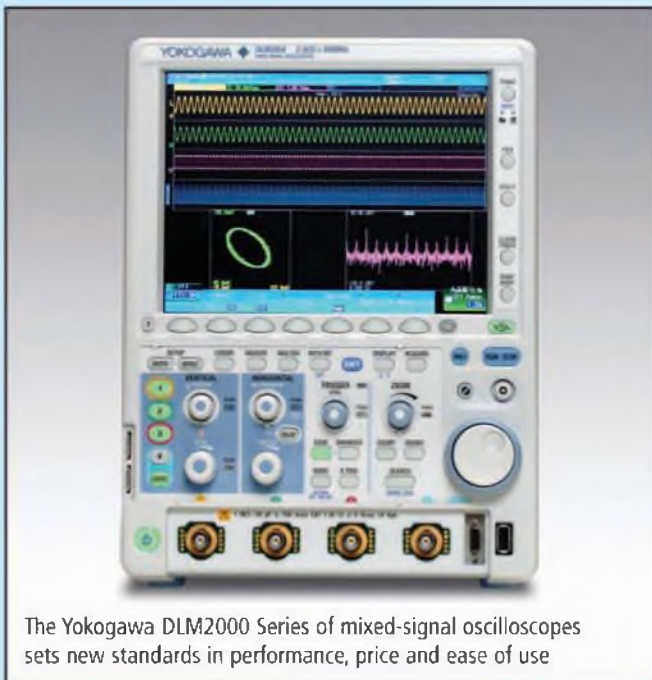
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## Yokogawa launches DLM2000 mixed-signal oscilloscope family

The new Yokogawa DLM2000 Series is a new family of mixed-signal oscilloscopes (MSOs) that represent a major step forward in terms of price/performance specification and ease of use.

With up to 500 MHz bandwidth and 2.5 GS/s sampling speed, the new oscilloscopes have the longest memory (up to 125 M points) and fastest update rate (up to 450,000 waveforms per second) in this class of instrument. In addition, the combination of flexible analogue and digital inputs, plus a large-screen display in a compact ergonomically styled body, makes the instruments exceptionally easy to use.



The Yokogawa DLM2000 Series of mixed-signal oscilloscopes sets new standards in performance, price and ease of use

In addition to the key performance specifications, the DLM2000 Series features a number of advanced measurement and analysis features, including histogram and trending functions, up to 20,000 history memories, digital filtering, zoom windows, user-defined mathematics and serial bus analysis.

The DLM2000 Series consists of six models: three with two channels and three with four, each covering the bandwidths 200, 350 and 500 MHz, respectively. Mixed-signal oscilloscope operation is enabled on the 4-channel models by converting the fourth channel of analogue input to 8-bit logic, so that the instrument then functions as a 3-channel analogue plus 8-bit logic MSO. A high-resolution mode (up to 12-bit) is also available. This logic capability is complemented by the availability of new logic probes with individual bit threshold setting and 100 kilohm input impedance at 250 MHz.

The new instruments feature a large (8.4 inch, 21.3 cm) high-resolution (XGA) display in a compact 'portrait' format package that occupies only two thirds of the area of a single A4 sheet on the benchtop. The display is enhanced by a fine grid, high luminance and viewing angle, and

on-screen markers with simultaneous display of cursors and automatic parameters. Other features include backlit buttons, additional knobs and jog shuttle, on-screen information in English, German, French, Italian and Spanish languages, two zoom windows with 80:20 or 50:50 zoom/main area split, and a choice of first-cycle or screen average mode for frequency measurement.

The combination of long memory and the history function, along with sophisticated trigger and search capabilities, means that the chances of missing elusive or intermittent waveforms are minimised. Using the /M2 option, up to 125 M points of storage capacity is available, allowing, for example, 10 kHz signals to be recorded for up to 5000 seconds. Even at a sampling rate of 1.25 GS/s, waveforms down to 0.1 sec can be captured.

With the history function, up to 20,000 previously captured waveforms can be saved in the acquisition memory, and any one or all of them can be displayed on screen with the ability to carry out cursor measurements and other analysis operations including FFT analysis and comprehensive user-defined maths. Waveforms can be displayed one at a time, in order, or automatically played back, paused, fast-forwarded or rewound.



CAN waveform of 12.5 M points (5 sec duration) showing use of the zoom window

The DLM2000 Series comes with a variety of easy-to-configure triggers combining analogue and logic inputs such as edge, enhanced and B-triggers. These include dedicated trigger functions for CAN, LIN, UART, I2C and SPI serial bus patterns as well as the ability to perform simultaneous analyses on two different buses operating at different speeds. This capability is enhanced by the extensive search facilities, allowing the user to look for specific data in the very long memory. The 4-channel models in the DLM2000 Series are also able to import the CAN DBC database and either trigger on, or decode, a physical value.

Prices for the DLM2000 Series start at €3300.

A dedicated web site has been set up for the Yokogawa DLM2000 Series at [www.dlm2000.net](http://www.dlm2000.net)

# ACTIVE FILTERING FOR LOWER LOAD CAPACITANCE IN NOISE-SENSITIVE APPLICATIONS

**CHESTER FIREK**, PRODUCT MARKETING MANAGER, AND **BOB KENT**, APPLICATIONS ENGINEER, BOTH FROM PICOR, DISCUSS A TYPICAL OFF-THE-SHELF ISOLATED DC-DC CONVERTER TO DEMONSTRATE HOW AN ACTIVE FILTER WILL PROVIDE SUPERIOR FILTERING BUT ALSO A SIMPLE SOLUTION TO MEET TRANSIENT RESPONSE REQUIREMENTS

**P**ower architects engaged in designing systems requiring low output noise and fast transient response, such as RF transmitters, power amplifiers, test systems, displays and designs supporting low voltage ASICs and laser diode transmitters, understand that when attempting to tailor power systems to meet both requirements using passive components, the two objectives become diametrically opposed. Minimising periodic and random deviations (PARD) requires filtering, whereas fast transient response is impeded by filtering.

The characteristics of the DC-DC converter, the load, the electrical characteristics of the passive components and the available PCB area all present additional design constraints that further limit the designer's options. This task becomes more difficult if the designer is unable to begin the design with an optimised DC-DC converter, to match the transient and noise requirements. This may be due to either lack of in-house design resources, a short design window, or the desire to use products already on their approved vendor list. In this instance, a high efficiency off-the-shelf DC-DC converter may be used.

This article uses a typical off-the-shelf isolated DC-DC converter to demonstrate how an active filter will not only provide superior filtering, as compared to the passive approach, but will also provide a simple turn-key solution to meet

challenging transient response requirements. This approach can either eliminate the need for load capacitance all together for noise reduction, or reduce the amount required by as much as a factor of ten for equivalent transient capability. The performance improvements demonstrated here would also apply to applications using optimised custom DC-DC converters.

## DC-DC CONVERTER CONSIDERATIONS

In order to properly understand the issues involved in optimising a "power system" for low noise and fast transient response, it is important to first establish the base-line performance of the DC-DC converter. Many of today's off-the-shelf high-density switch-mode power converters are designed to optimise for power density and efficiency, two of the most commonly used criteria for converter selection. DC-DC converters are only part of the total power system.

Although the output ripple and noise levels from some converters are adequate for the needs of today's end systems, they may not be adequate for some of the more sensitive analogue or digital systems. And as a power component, the DC-DC converter will generally provide a good current-source "engine" to support load transients, but will generally not have much internal energy storage capability.

Parameters such as low ripple and fast transient response are design trade-offs for density and efficiency and, because specific needs may vary from application to application, the DC-DC manufacturer will provide methods to further optimise these parameters with the use of external components, rather than add them internally to the converter.

The ability of the converter to be optimised (with external components) for low noise and fast transient response will depend on the converter topology, switching frequency and any limitations the converter manufacturer may impose on use of external components; i.e. maximum load capacitance.

## OPTIONS FOR REDUCING RIPPLE

The two major sources of ripple and noise on the output of a DC-DC converter are the switching noise generated by the converter and the line ripple from the

	Output Voltage		
	5 V	12 V	24 V
No Additional Filter	100 mV	150 mV	240 mV
Low ESR Cap	50 mV	75 mV	120 mV
LC Output Filter	20 mV	35 mV	50 mV
QPO and uRAM Series Active Filters	<10 mV	<10 mV	<10 mV

**Table 1:** Output ripple specifications for isolated DC-DC converters with various filter solutions

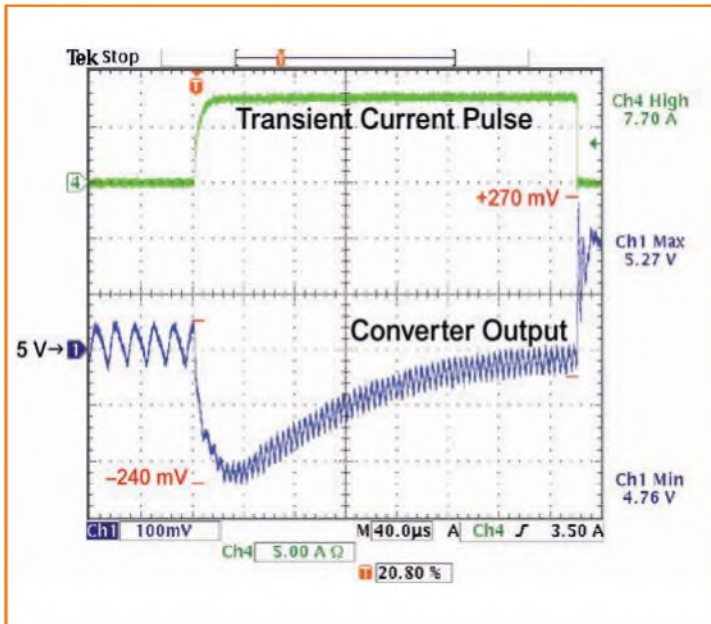


Figure 1: Transient load current with a 5V output converter

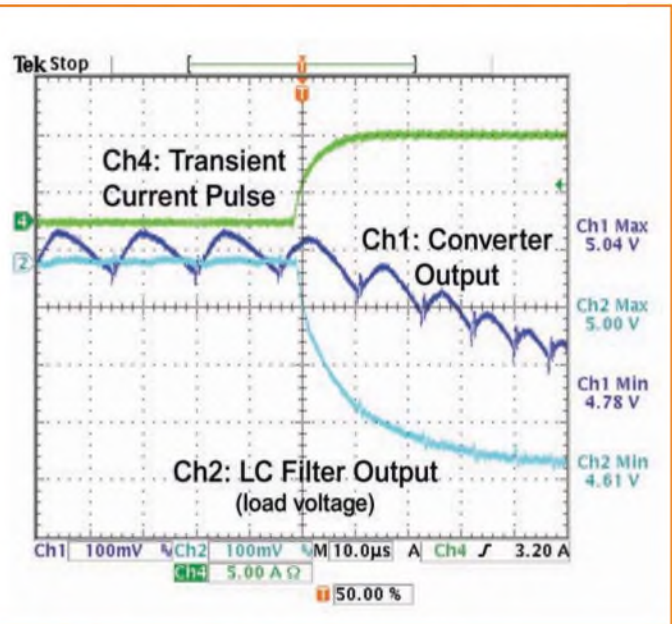


Figure 2: Test setup, DC-DC converter with LC filter

converter source (usually 120Hz if powered by an off-line source). For the line ripple, a DC-DC converter will provide some level of ripple rejection; any remaining ripple will appear at the load.

In general terms, the output ripple specification for a regulated DC-DC converter can range anywhere from 100mVp-p (5V output) to 240mVp-p (24V output) or more, depending on the converter. As a percentage of output voltage, the range could be 2% for a 5Vout converter and 1% for a 24Vout converter (see **Table 1**). The addition of low ESR (Equivalent Series Resistance) capacitors can reduce the ripple by up to 50%; using the previous examples would yield a range of 50mV to 120mVp-p.

Further reduction in ripple can be achieved by adding an inductor, with low DC resistance, in series. Adding an inductor can provide up to an additional 50-60% improvement; reducing the ripple to roughly 20mVp-p for a 5Vout converter and 50mVp-p, or more for a 24Vout converter. Although the improvement is significant, an application using a 28V RF Power Amplifier (PA) may require the ripple levels to be as low as 10mVp-p or less, to prevent sideband frequency peaks. Further improvements to reduce input line reflected ripple would require better attenuation at low frequencies, which requires the use of larger inductors and

more capacitance. For space savings, the more practical approach to attenuate the remaining lower frequency noise is to use active filtering.

### TRANSIENT RESPONSE

Noise-sensitive applications such as RF power amplifiers and laser diode transmitters also require very fast transient load response. In the case of an RF power amplifier, the system may operate steady-state at 10% load and then have the load increase to nearly 100% almost instantaneously. For the average DC-DC converter the response to a large load step can take a few hundred microseconds, where the PA may require the load to recover in less than one hundred microseconds. For an off-the-shelf isolated DC-DC converter, the response time for the control feedback loop (approximately equal to 1/5 the converter switching frequency) is far too slow to be able to recognise a transient event and respond to it in enough time to avoid a significant droop in output voltage.

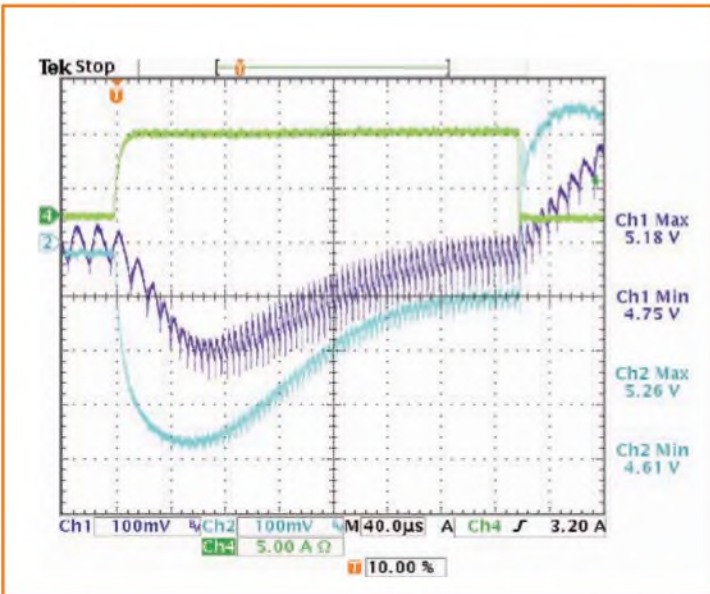
Adding passive components further slows down the converter loop response. Active filters provide a buffer between the DC-DC converter and the load as opposed to passive solutions that do not offer this capability. The load response is provided primarily by the active filter, which can provide a loop response several orders of

magnitude faster than the DC-DC converter. The waveforms in **Figure 1** depict a typical converter's response to a 7.7A transient load current with no external filtering or capacitance.

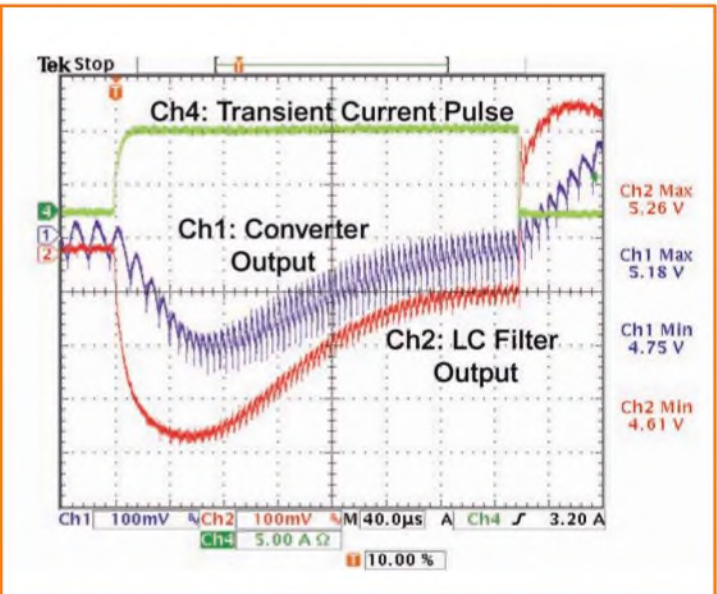
For the converter in Figure 1, the steady-state output ripple is approximately 100mVp-p, far too high for most noise-sensitive applications. However, the larger concern for system designers may be the droop in output voltage. In the example shown, the output droops when the load transient event begins and then overshoots at the end of the transient event when the load current falls creating an overall output voltage deviation of approximately  $\pm 250\text{mV}$ , which once again will be an issue in a sensitive application.

In order to provide a quicker response to load transients, additional output hold-up capacitance usually needs to be added as a source of current to satisfy the additional load. Depending on the transient requirements, this could mean that a very large amount of extra capacitance would need to be added. The drawbacks to adding extra capacitors are the cost of the components, the board space they occupy and the impact of additional capacitors on system reliability.

Furthermore, capacitors do not provide an ideal solution as there will still be an inherent transient voltage drop due to a capacitor's internal ESR. The ability of this



**Figure 3:** Ripple and load response of a 5V out converter using a LC filter on the output



**Figure 4:** Complete transient load event with a 5V out converter and LC network

configuration to maintain a clean stable output voltage during a transient is dubious.

## LC FILTER NETWORKS

The most common method of filtering output ripple is to add inductance in series and capacitance in parallel at the output of the converter, commonly referred to as an “LC network”, as shown in **Figure 2**. As illustrated in Table 1, the inductor in the LC network helps provide better ripple attenuation than the capacitor alone.

The inherent problem with adding inductance is that when a transient load occurs, the current through the inductor cannot change fast enough to provide current to the load, so all the energy must be supplied by the load capacitor(s). The amount of capacitance that is required will depend on the system requirement and change in load current versus time  $[di/dt]$ . But as the capacitors provide the necessary current, there may still be an unwanted drop in output voltage due to the non-ideal parasitic factors. It's equal to the value of the transient current multiplied by the equivalent series resistance (ESR) of the capacitor(s) and the frequency dependent drop across the electrical series inductance (ESL).

The waveforms in **Figures 3** and **4**

show the results of the LC network filtering on the converter output ripple (Ch2). Although the ripple is significantly reduced the transient drop in load voltage has increased. At the start of the transient there is a sharp drop in the output voltage from the filter. Since the current through the inductor cannot change instantaneously, the current for the transient load must come from the output capacitors. This initial voltage drop is the result of the transient current multiplied by the capacitor ESR.

To reduce the voltage drop, the overall ESR of the output capacitance would have to be reduced by either careful selection of lower ESR caps or by using more capacitors to parallel the ESR component. In this instance, the voltage at the load droops by more than 300mV before the converter starts to recover, and bring the output up to the regulation voltage.

The waveforms in **Figure 4** show the complete transient event and the resulting undershoot and overshoot of the LC filter, due to the LC filter ringing at its resonate frequency. By the end of the transient, the current through the inductor is providing the transient load current. When the load transient ends, the current through the inductor remains the same, since it cannot change instantaneously, and gets dumped into the load capacitors. Forcing this

stored energy into the capacitors raises the output voltage by about 300mV, resulting in a peak to peak variation of 600mV due to the transient load change.

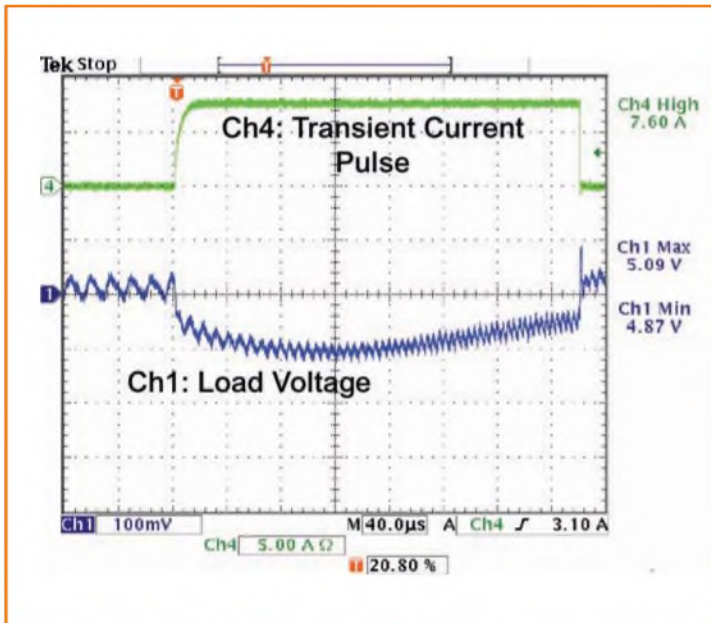
## ADDING “HOLD-UP” CAPACITANCE

To compensate for such a dramatic variation in output voltage, additional capacitance needs to be added at the load to “hold-up” the voltage at the load. To consider the affects of load capacitance, the same circuit will first be demonstrated without the inductor. The waveforms in **Figure 5** show the same converter output voltage during the transient load with an additional 8mF of capacitance on the converter output.

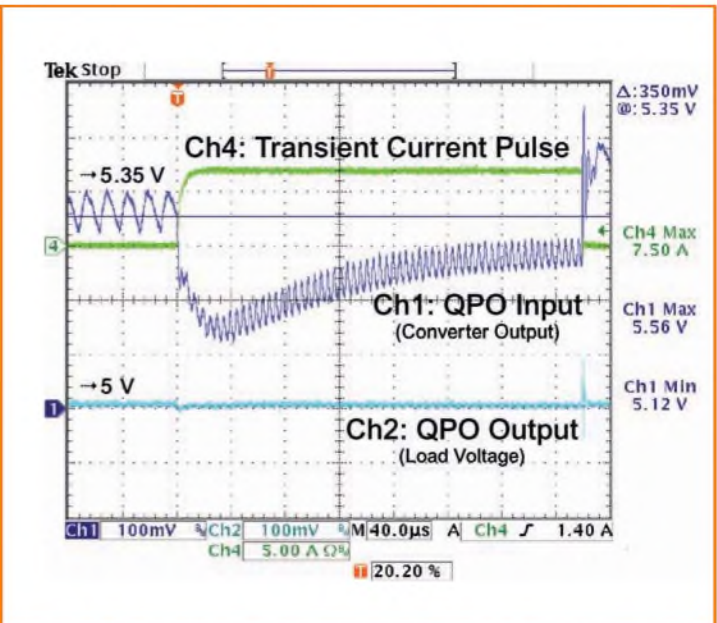
In this instance the added capacitance reduced the voltage droop to roughly 100mV, rather than 300mV with the LC filter. As expected, the amplitude of the ripple has reduced (to approximately 40mVp-p) as compared to the stand-alone DC-DC converter; even though the ripple is higher than with the LC filter.

Using this approach's results improved overall performance, but still they should be weighed against the total size of the solution, as well as any potential reliability issues relating to compatibility with the converter. (Note: Most DC-DC manufacturers place limits on the amount





**Figure 5:** Transient load current with a 5V out converter and eight parallel 1mF caps (8mF total)



**Figure 6:** Test setup, 5V out converter with 1.4μH inductor and 8mF of load capacitance

of capacitance that can be added to the output of the converter in order to avoid loop stability issues. In the example shown above the maximum capacitance value set by the converter manufacturer was exceeded in order to demonstrate an extreme case. Always refer to the manufacturer's DC-DC converter specifications to determine acceptable capacitance levels.)

### COMBINING HOLD-UP CAPACITANCE WITH INDUCTANCE

**Figure 6** shows a test circuit combining the 1.4μH inductor from the LC filter with the 8mF of hold-up capacitance from the previous example. The resultant waveforms in **Figure 7** show that the output ripple has improved but the transient response has degraded slightly. Since the resonant frequency of the LC filter is much lower with the 8mF of capacitance, it is clear that the first step in voltage is due to the capacitor's ESR and the reactance of the inductor.

In this example, the load capacitance was increased by more than ten times the amount used in the first LC filter example shown in **Figure 2**; the benefit of hold-up capacitance appears to have been maximised. Adding the inductor has, once again, reduced the ripple levels. Further

reduction in ripple may be possible with larger inductors. These nearly optimised results of a passive design can now be compared to the performance of an active filter.

### ACTIVE FILTERING AND TRANSIENT RESPONSE

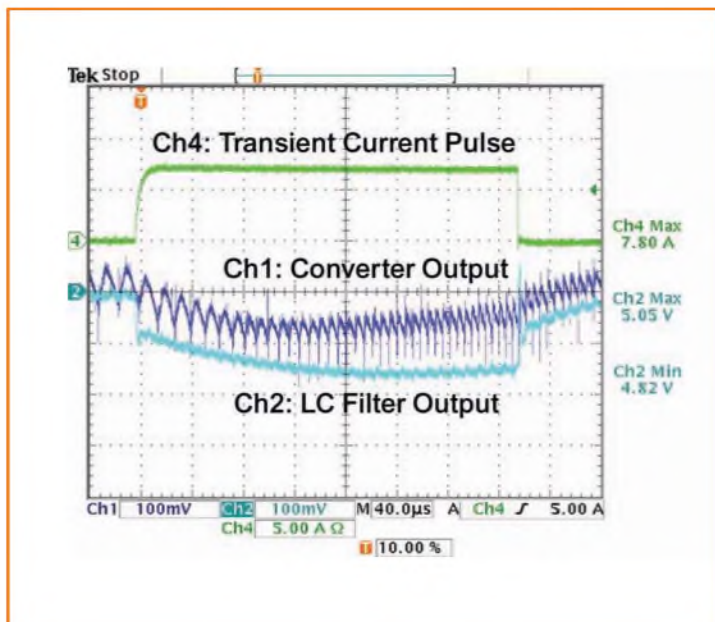
As illustrated in the previous examples, the primary drawbacks in the passive approach are the effect of the inductance on transient response, and the voltage drop across the hold-up capacitance. Active filters provide improved transient response by replacing the passive inductance, which has inherently slow di/dt, with much faster and smaller active components as shown in **Figure 8**.

In the active approach the inductor reactance is replaced by a power FET and a high speed controller device that modulates the FET to create linear resistance. During a transient condition, the loop gain of the filter increases the effect of capacitance at the input to the filter by a ratio of the change in the input voltage of the filter divided by the change in the output voltage of the filter ( $\Delta V_{in}/\Delta V_{out}$ ), drastically reducing the amount of capacitance required while decreasing transient di/dt response time.

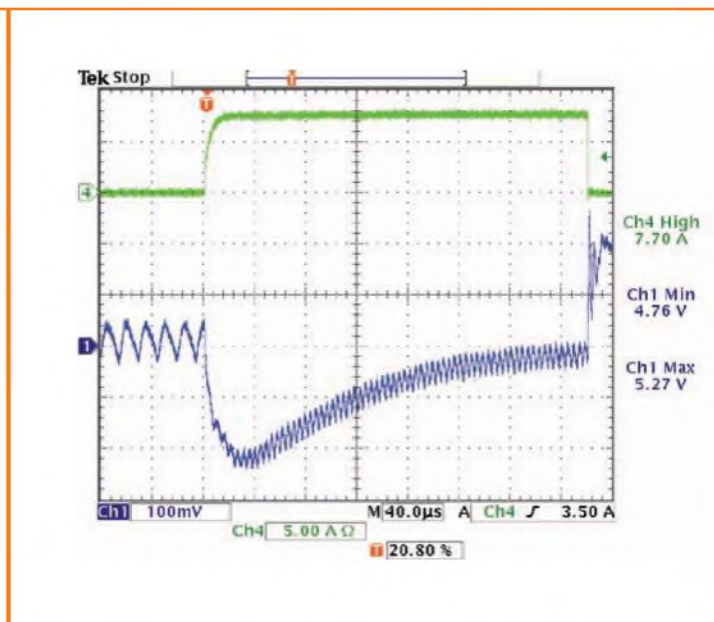
Active filters, such as Picor's QPO and uRAM models, are able to respond to transients much faster than converters by decreasing the internal resistance path between its positive input and output pins. Since the voltage is greater on the QPO input than its output, this voltage difference can be used to compensate for the additional load requirements of the transient. This voltage difference ( $\Delta V_{hr}$ ), referred to as the headroom voltage, is selected by the user, providing an output voltage on the converter that is greater than the desired load voltage. During the transient, the output of the converter will droop and the active filter will compensate by reducing the headroom voltage, to maintain a constant output voltage, provided that the voltage droop is not greater than the selected  $\Delta V_{hr}$ . The minimum voltage drop by the active loop of the QPO is based on the QPO minimum resistance.

The waveforms in **Figure 9** demonstrate the ability of the QPO to filter both the ripple voltage from the converter, as well as the voltage droop of the converter during a transient load event.

In this example the QPO test board was designed to have 350mV of headroom voltage under low-load



**Figure 7:** Transient load current with 1.4µH inductor and 8mF of load capacitance



**Figure 8:** Test set-up, 5V out converter with QPO-1 active output filter

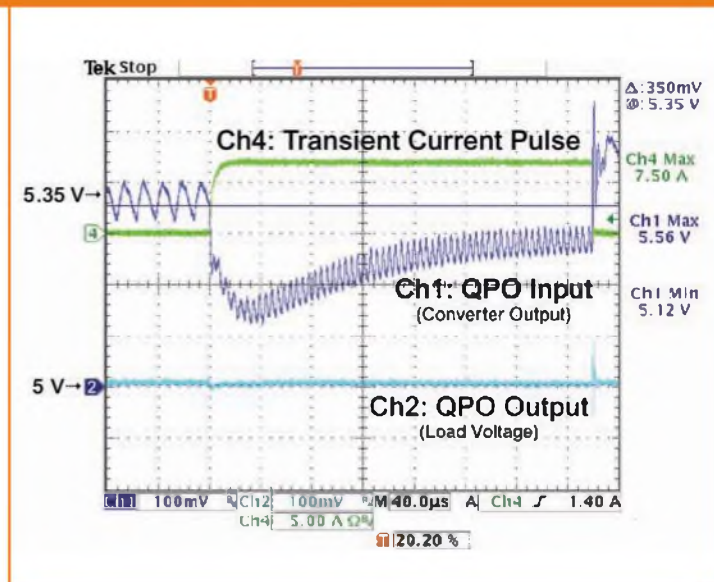
conditions, which for this test was a 1A constant load. Ch1 is the voltage seen on the QPO input; Ch2 is the QPO output voltage. Both channels are DC measurements with a 5V offset and referenced two divisions down from centre.

In Figure 9 the load step (Ch4) monitors the transient current only and does not include the static 1A load. Examining the plot, starting with the left edge of the waveforms, the average DC voltage difference between Ch1 and Ch2 is 350mV. After about 80µs, the transient current event occurs (~ 1A/µs) and the voltage from the converter (Ch1) droops. The QPO output voltage (Ch2) remains constant at 5V for the entire duration of the transient. As a result the QPO filter virtually eliminates the ripple and the load voltage drop associated with the 7.7A transient, with no additional capacitance, significantly outperforming all of the passive scenarios.

### ANALYSING THE POWER SYSTEM

When designing power systems that require low noise and fast transient response, it is important to understand the trade-offs and limitations of all the components that will make up the “power system”, i.e. the DC-DC converter, filter and hold-up capacitors. The DC-DC converter will produce the base-line from which to improve upon.

Adding passive filter components to the output of the DC-DC will reduce ripple but this will result in a negative affect on transient response and may potentially create stability issues. More capacitance will be needed to improve transient response. Depending on the amount of ripple and transient response improvement needed, the passive solution may also become very large, potentially making the solution space prohibitive.



**Figure 9:** Transient load with the same 5V out converter and a QPO active output filter

As demonstrated in the previous examples, active filtering provides better overall filtering and load transient performance than a passive approach due to faster loop response and lower resistance. In the example provided in Figures 8 and 9, the QPO-1 demonstrated a significant improvement in transient response with no additional load capacitance present. By reducing the amount of load capacitance required in low noise, high transient load systems, the power design can become optimised for both performance and size. ■

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# KIT-BASED APPROACH FOR ACCELERATED ADOPTION OF LOW-POWER TECHNIQUES

In recent years, power consumption has moved to the forefront of ASIC and system-on-chip (SoC) development concerns. The combination of higher clock speeds, greater functional integration and smaller process geometries has contributed to significant growth in power density. Furthermore, with every new process generation, leakage power consumption increases at an exponential rate.

A wide variety of low-power design techniques have been developed to address the various aspects of the power problem, including the use of clock gating, multi-switching threshold (multi-Vt) transistors, multi-supply multi-voltage (MSV), substrate biasing, dynamic voltage and frequency scaling (DVFS) and power shut-off (PSO).

## ADDRESSING LOW POWER

However, "Low power" isn't just something that can be "bolted on" at the end of the development process. Power, timing and area are overlapping and potentially conflicting goals that need to be balanced throughout the flow.

To meet aggressive design schedules, it is no longer sufficient to consider power only in the implementation phase of the design. The size and complexity of today's ICs make it imperative to consider power throughout the design process, from the chip/system architectural phase, through the implementation architecture phase, through design (including micro-architecture decisions), and all the way to implementation with power-aware synthesis, placement and routing. Similarly, to prevent functional issues from

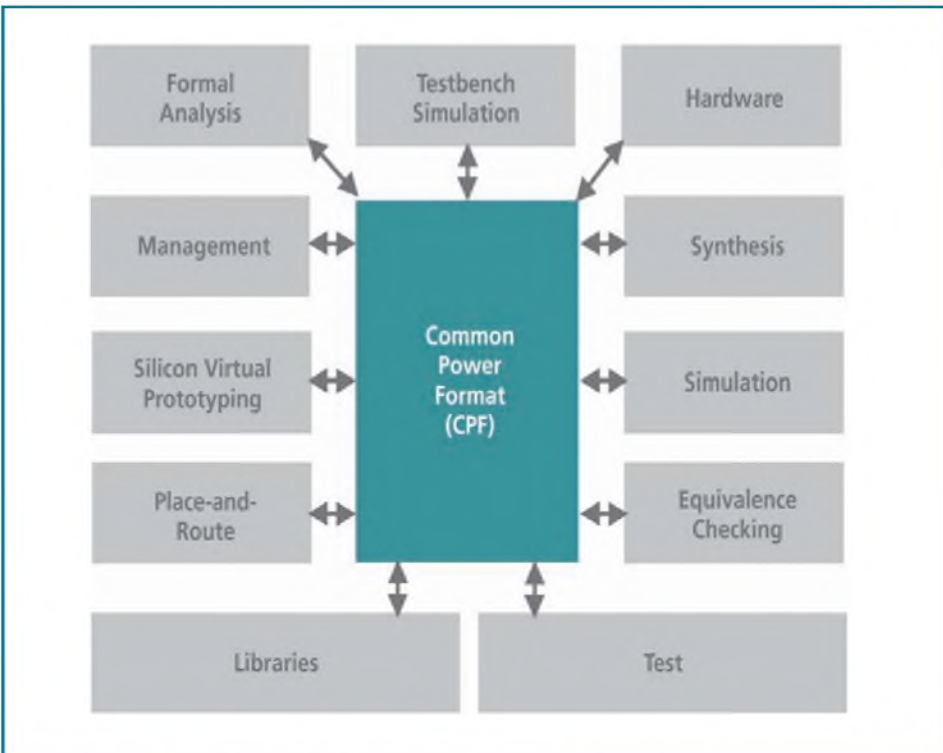
**NEIL HAND** DESCRIBES THE CONCEPT OF A "LOW-POWER KIT" THAT ENABLES DESIGNERS WITH AND WITHOUT LOW-POWER EXPERTISE TO ADOPT ADVANCED LOW-POWER TECHNIQUES EFFICIENTLY AND EFFECTIVELY

surfacing in the final silicon, power-aware verification must be performed throughout the development process.

To address low power issues, today's design environments boast a wide variety of sophisticated power-aware tools and methodologies. However, even with the high level of automation that such tools provide, applying these techniques can require substantial effort, introduce risk and can increase the complexity associated with design, implementation and verification.

In order to ensure smooth adoption of low-power techniques, we need a way to enable all team members regardless of low-power experience to utilise the capabilities at their disposal, without needing to become low-power experts, or to learn by trial and error.

This article describes the concept of a "low-power kit" that enables teams with and without low-power expertise to adopt advanced low-power techniques efficiently and effectively. A low-power kit gathers expert knowledge and best practices to: eliminate common problems, establish flows to ensure tools and technologies are applied to achieve the best results, and establish processes to ensure predictability.



**Figure 1:** CPF provides a holistic specification of power intent used throughout design, implementation and verification

## THE COMMON POWER FORMAT

Common Power Format (CPF), managed under the auspices of the Silicon Integration Initiative (Si2) consortium's Low-Power Coalition, provides a mechanism to capture architects' and designers' intent for power management, enables the automation of advanced low-power design techniques and allows "what if" exploration to take place without RTL changes.

The benefit of using CPF within a low-power kit is the ability to drive the design, verification and implementation from a single "golden" power intent description (**Figure 1**). A high level of automation within the tools around this central description eliminates many of the error prone tasks typically associated with low-power design.

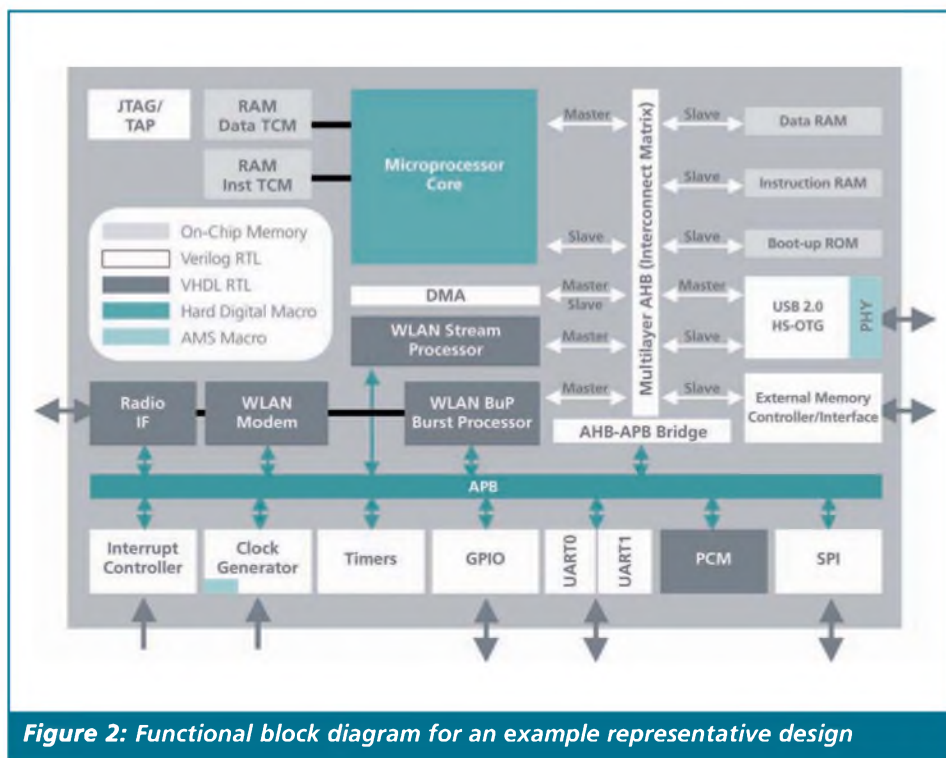
## A REPRESENTATIVE DESIGN

A variety of different considerations must be taken into account when creating a low-power kit. First and foremost, it is necessary to create a representative design that embraces all the low-power aspects of the typical designs you will be working on. This allows the different aspects of the kit to be proven out and demonstrated, and provides adopters with a well defined sandbox in which to experiment and learn. Additionally, this design can act as a pipe-cleaner whenever tool or silicon vendor changes are made.

As an example, consider an IEEE 802.11-based wireless access device comprising various interfaces and peripherals. At the core of this device will be a SoC containing a variety of functional blocks. A block diagram of the functions comprising such a representative design is shown in **Figure 2**. This will typically include some hard macros such as a microprocessor core, as well as a variety of first and third-party IP (both Verilog and VHDL) – many of which may utilise power-saving techniques.

In addition to all of the purely digital logic, there will likely be a number of analogue/mixed-signal (AMS) blocks that must be accommodated by our design environment, such as a phase-locked loop (PLL) in the clock generator and any physical-layer (PHY) interfaces.

To facilitate understanding, the kit should be partitioned into a number of



**Figure 2: Functional block diagram for an example representative design**

main categories; for example: Design Environment, Low-Power Techniques, Design Creation, Physical Implementation, Verification and Management. In turn, each of these categories should comprise a number of discrete modules and flows (**Figure 3**). Design and verification teams then need to use only those modules appropriate for their particular design.

Where applicable, each module should include background information pertaining to this aspect of the design, best practices, checklists, recommended flows, scripts to demonstrate the flows, training material and documentation.

## DESIGN ENVIRONMENT

This category should cover everything required to establish a complete low-power design environment for a new project, including infrastructure, tools, IP components and detailed checklists and dependencies.

Some example modules are:

**Library** Ensures the necessary view and databases

**Qualification** are available for successful low-power flows

**Process** Defines how low-power affects process selection

**Selection** and what is needed based on design requirements

**Infrastructure** Provides data

management and system infrastructure to ensure a smooth low-power implementation.

## LOW-POWER TECHNIQUES

This category should cover the various low-power techniques that may be employed in a design and that are supported by the design environment. Tradeoff analysis should also be performed to determine the most appropriate techniques to apply.

Some example modules are:

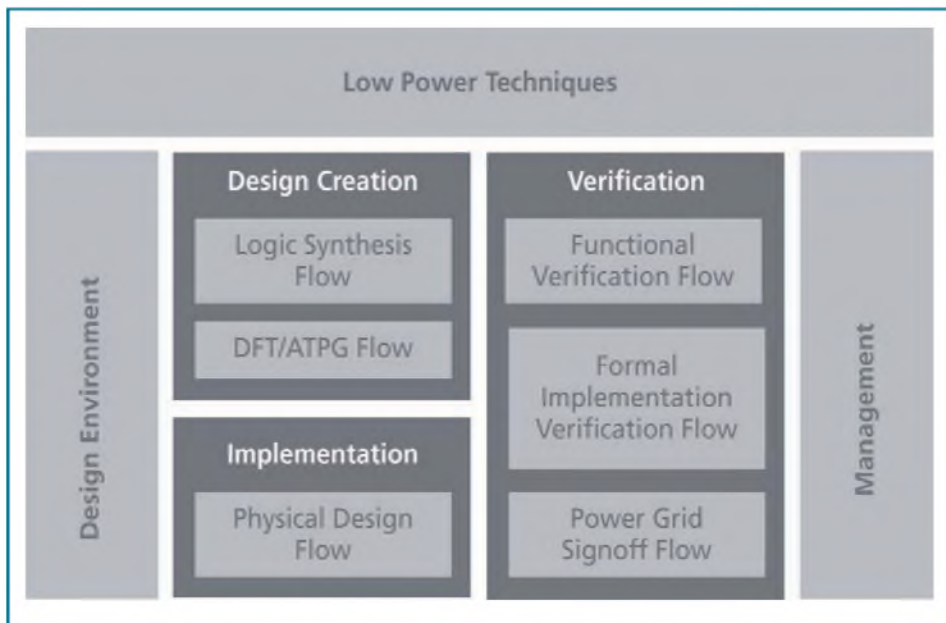
**Multi-Threshold Voltages** When and how to use this highly automated technique effectively.

**Low-Power Clocking** As a major contributor to power consumption, managing clocks effectively is key to a low-power implementation.

**Multi-Supply Voltages** Defines the benefits and pitfalls of MSV and what is needed to implement it in a design.

**Power Shut-Off (PSO)** PSO has substantial power benefits, but it needs to be applied appropriately as it affects all areas of the design process.

**Dynamic Voltage and Frequency Scaling (DVFS)** techniques may also have substantial power benefits, but ensuring that the performance-voltage-frequency feedback mechanism works correctly can be a challenge.



**Figure 3:** The low-power kit should feature a number of categories, modules and flows

## MANAGEMENT

This category should cover the various facets of managing a low-power design, from planning a verification strategy, defining metrics and estimation techniques, to implementing a low-power engineering change order (ECO) methodology.

Some example modules are:

**Low-Power ECO** Track all data and flow dependencies to ensure that late-stage changes do not cause problems.

**Methodology, Planning, Metrics and Analysis** Predictability is ensured through proper metrics and planning, and must be considered throughout the design process.

## DESIGN CREATION

This category should cover all design creation aspects of the flow, including performing architectural tradeoffs among power, timing and area, along with best practices for success with designs employing MSV and/or PSO techniques.

The modules included in this category might be as follows:

**Architecture Tradeoff** Compare different techniques and how they affect total power within your class of designs.

**RTL Design** Covers what can be done in RTL to affect power consumption, as well as how the different techniques are codified.

**CPF Creation** Effective power intent representation using the Common Power

Format including templates for your design styles.

**Low-Power Synthesis** How synthesis affects the power process and how to implement the most effective synthesis for a low-power design.

**Power-Aware DFT** Power affects both normal modes of operation and test and must be considered throughout.

The flows covering these modules should utilise the golden RTL and CPF files together with simultaneous optimisation of all constraints (timing, area and power) to create an optimised netlist that includes all of the relevant low-power structures including level-shifters, isolation cells and retention logic.

## PHYSICAL IMPLEMENTATION

This category should cover all the aspects of physical design from netlist through design signoff. As with Design Creation, the golden CPF file should be used to communicate power intent throughout the flow.

Some example modules are:

**Prototyping and Parasitic Correlation** Many iterations of floorplan optimisation may be needed on the road to timing closure. Accurate parasitic scaling between detailed extraction and prototyping extraction speeds this up.

**Power Planning** Proper selection of a power distribution scheme (grid or ring) must be taken into account for low- and

non-low-power blocks.

## Low-Power Floorplanning

Determine the best location for sensitive blocks. Rules may govern that blocks with the same voltage are located in close proximity or closer to pad I/Os, for example.

## Timing and Signal Integrity Closure

Even if power intent is considered to be the most important, timing and SI specifications must be met to obtain a functional design.

## VERIFICATION

The importance of verification within a low-power flow can best be illustrated by considering just a few of the challenges when utilising the PSO technique.

At the functional level we need to ensure that powered-down logic does not cause invalid data to propagate, that any necessary state is retained during power down and that power sequencing ensures successful power-up.

During implementation we need to verify that the appropriate isolation cells and other power structures are in place.

Finally, during power grid signoff, we need to make sure that any in-rush current during power-on of the PSO block does not corrupt surrounding logic.

Some example modules are:

## Low-Power Functional Verification

Power intent can directly affect functional intent, so functionality must be verified in the context of the final power implementation using techniques such as simulation and assertion-based verification.

## Low-Power Formal Implementation

**Verification** Defines a process to ensure that the low-power implementation chosen is correct and consistent through all design transformations.

**Power-Grid Signoff** Prior to signoff, verify that the static and dynamic behaviour of the power grid meets all requirements for correct operation.

## AN EFFECTIVE WAY

Utilising a kit-based approach to low-power design as described here, together with a common power format such as CPF, is a highly effective way to capture and communicate low-power knowledge throughout an organisation, allowing designers of different experience levels to effectively and efficiently adopt advanced low-power techniques. ■

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# POWER MANAGEMENT ICs OPTIMISE BEST-IN-CLASS CIRCUIT BLOCKS

**STEVE KNOTH**, PRODUCT MARKETING ENGINEER AT LINEAR TECHNOLOGY CORPORATION, LOOKS AT POWER MANAGEMENT INTEGRATED CIRCUITS (PMICS) OPTIONS AVAILABLE TO DESIGNERS TODAY

Unprecedented challenges face designers of today's battery-powered portable electronic products. Among these are the demands for high performance power management systems to accommodate growing system complexity and higher power budgets. These systems strive for an optimum balance among long battery run-time, compatibility with multiple power sources, high power density, small size and effective thermal management.

A new breed of power management integrated circuits (PMIC) is available to efficiently power these systems – much smaller in footprint and much higher in performance than the “traditional” PMIC. This is changing the way product designers can configure and partition their systems.

The PMIC arose primarily from the need to save PC board space via higher levels of integration of multiple discrete power IC functions, such as low dropout regulators, switching regulators, interface circuits and, in some cases, even battery chargers. Over the past five to ten years, these “system on a chip” (SOC) type ICs have become commonplace. However, they are quite large and many come with “hidden” costs and performance limitations for the designer.

However, there are now more optimised solutions – a new generation of PMICs that consolidate the “hard to do” functional circuit blocks such as power path management, high efficiency synchronous switching regulators, USB On-the-Go, over-voltage protection, high voltage input capability and full-featured battery chargers, while at the same time raising the overall performance bar. Their small form-factor, low-profile packaging and minimal external

components allow for simple, compact and cost-effective solutions for handheld electronic devices, especially those utilising USB power.

## DESIGNING AROUND “OVER-INTEGRATION”

Let the “buyer beware!”: some PMICs may save board space, but many come with hidden costs, additional required design time and performance limitations for the designer. The industry standard PMIC has been relatively large in form-factor, generates lots of localised heat and contains a number of functions that are not necessarily needed by the application, thus adding complexity and causing the need to “design around them”.

In many design cases, even if integration was absolutely necessary, designers had no choice but to pay for the extra functionality, even though they would use only a subset of the total chip's functionality. Many customers comment that they spend more time designing around what they do not need, rather than what they do want. The alternative has been to use multiple ICs plus a discrete component approach, which in turn takes more board space, adds cost, increases manufacturing complexity and grows the bill of materials.

## REDUCING HEAT

Many industry-standard PMICs come with a variety of linear regulators onboard. However, linear regulators, if not managed

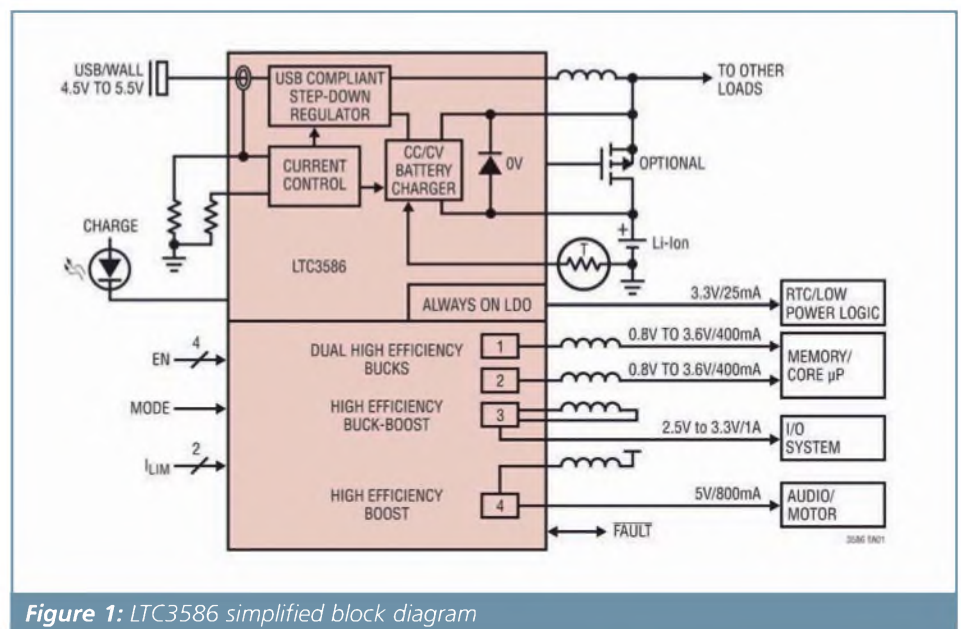


Figure 1: LTC3586 simplified block diagram



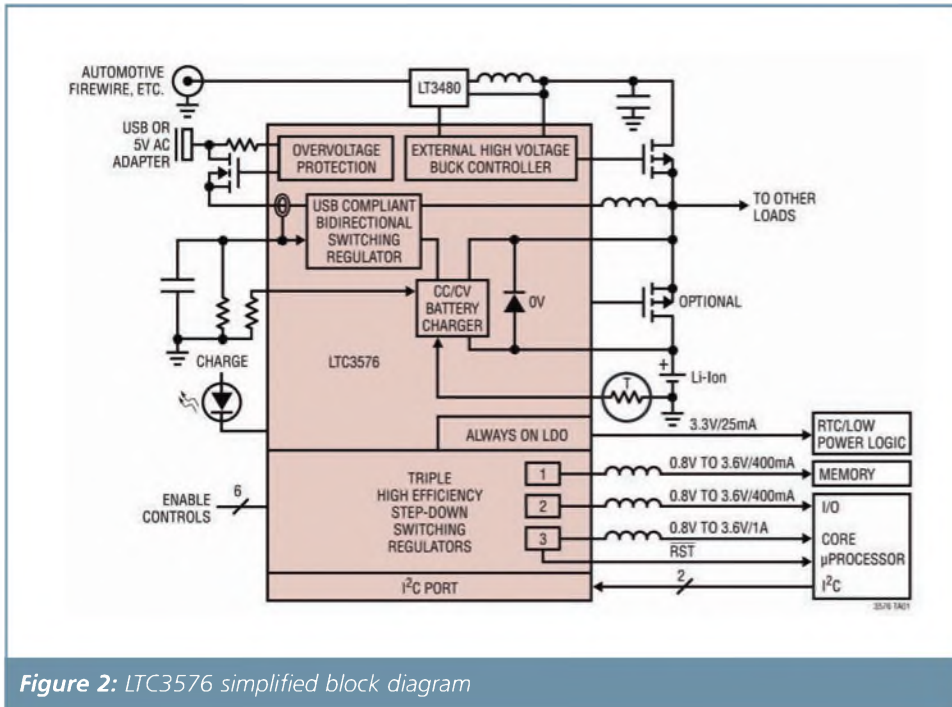


Figure 2: LTC3576 simplified block diagram

properly with sufficient copper trace routing, heat sinks, or well-designed input/output voltage and output current levels, can generate a lot of localised heat or “hot spots” on the PC board.

Alternatively, switching regulators provide a more efficient way to step down and convert voltages when the differential between input and output voltage is high and/or if the output current is high. This is commonplace in today's feature-rich devices with low-voltage microprocessors on board. So implementing switchmode power supplies for the majority of voltage rails is increasingly necessary.

Additionally, linear battery chargers may be another source of heat, depending on the input voltage to battery voltage differential and charging current. In principle, linear chargers act like a linear regulator in terms of power dissipation. So, LDOs combined with linear chargers on the same chip may present a real thermal issue to contend with.

### GENERATING INTERMEDIATE VOLTAGE RAILS FROM A LITHIUM BATTERY

Many of today's modern feature-rich portable electronics still require voltage rails around +3.3V, to power I/O or an HDD, for example. LDOs alone are clearly not sufficient to generate these system voltages from a Li battery input, as they may only

step voltages down. Even the usage of buck switching regulators may not be sufficient (bucks are no better than LDOs for dropout – and sometimes worse) depending on the input supply, i.e. if the rail is powered off a Lithium battery (which has a typical voltage range from 4.2V at full charge, down to ~3.0V when depleted).

Applications that take advantage of the entire Li battery range may require a buck-boost regulator, which can efficiently provide a fixed output voltage, regardless of the input being above, below, or equal to this output. This is also true for systems that have high pulsed current requirements – the buck or LDO can lose output regulation without a large input capacitor present to prevent droop on  $V_{IN}$ .

### MANAGEMENT OF MULTIPLE INPUT POWER SOURCES

Managing power flow, while minimising heat generation in a portable handheld product, presents a significant design challenge. An increasing number of portable battery-powered products can be powered from low voltage sources such as a 5V wall adapter, a USB port or Li-Ion/Polymer battery, and also high-voltage sources such as automotive adapters and Firewire ports.

Autonomous management of the power flow between these input sources and the battery while efficiently providing power to the load presents significant technical

obstacles. Traditionally, designers have performed this function discretely, using a handful of MOSFETs, op-amps and other components, but have faced difficult problems with hot plugging, excessive heat generation, large inrush currents and large voltage transients to the load, which can cause system reliability problems.

### EFFICIENTLY EXTRACTING POWER FROM USB

USB technology has increased the convenience of electronic devices. It is convenient to be able to charge the device from this same USB port that performs the data transfer, eliminating the need for a separate wall adapter. However, there are power limitations (2.5W max) when the USB is used for charging the device's battery. USB-capable battery charging in many cases means more convenience to the user, but it poses the constraint of USB current limits (500mA max). Thus, a battery charger must efficiently extract power from the USB port without exceeding the thermal limitations of the end product.

Key challenges for the system designer include:

- Designing around unnecessary PMIC functions
- Minimising power dissipated as heat
- Maximising battery run-time
- Generating low and intermediate voltage rails
- Managing power flow between multiple input sources, the battery and the load
- Maximising current delivered from the USB port (2.5W available)
- Minimising solution footprint and profile.

### SIMPLE SOLUTION

There is no longer the need to work around the performance deficiencies of the traditional “large PMIC”. Linear Technology's PMICs with PowerPath management and other best-in-class integrated functional blocks solve these problems simply and easily. In fact, in many systems one such PMIC is sufficient to power the entire system. This is possible because Linear Technology has taken a different approach to its PMIC development, utilising a more selective integration level that offers a compact solution without any performance compromises.

A key feature of these PMICs is the so-called PowerPath control. This automatic load prioritisation offers the ability to autonomously and seamlessly manage

power flow between multiple input sources such as USB ports, wall adapters and the battery, all while preferentially providing power to the system load.

In a traditional battery-fed charging system, the user must wait until there is sufficient battery charge and voltage level to obtain system power. Conversely, PowerPath control allows the end product to operate immediately when plugged in, regardless of the battery's state of charge, commonly referred to as "instant-on" operation. PowerPath control circuits may be found in both linear and switching topologies. Benefits of the linear PowerPath topology include Bat-Track adaptive output control capability with an external high-voltage buck and improved thermal performance with power flowing to the system load.

Switchmode PowerPath technology preserves these advantages while improving power delivery efficiency to the load/system and to the battery. It eliminates the power lost in the linear battery charger element, especially critical when the battery voltage is low and/or input power is limited (i.e. USB), giving it excellent thermal properties.

A second big advantage is its ability to extract up to 700mA battery charge current from a standard USB port (~ 2.3W) when battery voltages are low. In **Table 1** is a summary and comparison of the three different USB charging system topologies.

## INTEGRATED BUCK-BOOST AND BOOST REGULATOR CAPABILITY

Low voltage rails with moderate to high

output current, for instance down to 0.8V to power uP cores, may be efficiently generated from synchronous buck regulators. However, many of today's modern feature-rich portable electronics still require an intermediate voltage rail of either +3V or +3.3V.

Integrating synchronous buck-boost switching capability into the PMIC allows 3.3V (for example) regulation across the entire Li-ion/Polymer input battery range (sometimes as wide as 2.7V to 4.2V), with high efficiency, resulting in increased operating margin. So, at 3.3V a buck-boost regulator can "ride through" battery voltage or load current transients that would cause a step-down buck to lose regulation.

In addition, synchronous boost regulators allow "step-up" conversion to rails above the Lithium battery voltage range with good efficiency > 80%. Further, high switching frequencies reduce the size of external components and stability with ceramic capacitors reduces output ripple.

## LONGER BATTERY LIFE AND RUN TIMES

Accurately charging a Lithium Ion/Polymer battery to its final float voltage has a heavy influence on battery life. This is managed by selecting an appropriate battery-charging IC with tight float voltage accuracy and accurate termination algorithms, all of which maximise battery runtime while not over-charging the cell. Furthermore, low system standby (quiescent) current and high switching regulator conversion efficiencies via synchronous rectification allow small

system current consumption, further increasing battery run-time. Burst Mode operation, for example, automatically reduces switching regulator quiescent current (Iq) at light loads to help reduce device current consumption.

## THE LTC3586 PMIC

The LTC3586 PMIC integrates a switching PowerPath manager, a stand-alone battery charger, four high-efficiency synchronous switching regulators (1 buck-boost, 1 boost, and 2 buck regulators) and an always-on LDO, all in a low-profile 38-pin 4mm x 6mm QFN package (see **Figure 1**).

For fast charging, the LTC3586's switching input stage converts nearly all of the 2.5W available from the USB port to charging current, enabling up to 700mA from a 500mA limited USB supply or up to 1.5A when wall powered.

The LTC3586's buck-boost regulator can deliver up to 1A continuously and is ideal for efficiently regulating a 3.3V output over the full Lithium battery voltage range, down to 2.75V input. The LTC3586's two buck regulators feature 100% duty cycle operation and are capable of delivering output currents of 400mA each, with adjustable output voltages down to 0.8V. The boost regulator is capable of at least 800mA output current and is programmable up to a 5V output.

The LTC3586's internal low  $R_{DS(ON)}$  switches enable switching buck and buck-boost efficiencies as high as 94%, maximising battery run-time. In addition, Burst Mode operation optimises efficiency at

Attribute	Battery-Fed	Linear PowerPath	Switching PowerPath
Size	Small	Moderate	Larger
Complexity	Simple	Moderate	More complex
Solution Cost	Low	Moderate	Higher
USB Charge Current	Limited to 500mA	Limited to 500mA	NOT limited to 500mA (~ 2.3W)
Autonomous Control of			
Input Power Sources	No	Yes	Yes
Instant-ON Operation	No	Yes	Yes
System Load Efficiency (I <sub>bus</sub> <USB limit)		Poor (VBAT/VBUS)	Excellent (>90%) Very Good (~ 90%)
System Load Efficiency (I <sub>bus</sub> =USB limit)		Poor (VBAT/VBUS)	Poor (VBAT/VBUS) Very Good (~ 90%)
Battery Charger Efficiency	Poor (VBAT/VBUS)	Poor (VBAT/VBUS)	Very Good (~ 90%)
Thermal Dissipation	High	Moderate	Low
Bat-Track Adaptive Output			
Control/Interface to HV Buck	No	Yes	Yes

**Table 1:** Comparison of USB battery charging system topologies

Power Management ICs with Li-Ion/Polymer Battery Chargers							
Part Number	PowerPath Topology™	Interface	Buck(s)	Buck-Boost	Boost	LDO	Package (mm <sup>2</sup> )
LTC3576	switching	I <sup>2</sup> C	1A, 400mA x 2	-	-	25mA	4x6 QFN-38
LTC3586	switching	-	400mA x 2	1A	0.8A	25mA	4x6 QFN-38
LTC3555/-1/-3	switching	I <sup>2</sup> C	1A, 400mA x 2	-	-	25mA	4x5 QFN-24
LTC3556	switching	I <sup>2</sup> C	400mA x 2	1A	-	25mA	4x5 QFN-28
LTC3567	switching	I <sup>2</sup> C	-	1A	-	25mA	4x4 QFN-24
LTC3566	switching	-	-	1A	-	25mA	4x4 QFN-24
LTC3577 *	linear	I <sup>2</sup> C	600mA, 400mA x 2	-	-	150mA x 2	4x7 QFN-44
LTC3455	linear	-	600mA, 400mA	-	-	controller	4x4 QFN-24
LTC3557/-1	linear	-	600mA, 400mA x 2	-	-	25mA	4x4 QFN-28
LTC3558	-	-	400mA	0.4A	-	-	3x3 QFN-20
LTC3559/-1	-	-	400mA x 2	-	-	-	3x3 QFN-16

\* future product - contact LTC Marketing for information.

Table 2: Linear Technology's PMIC family

light loads with a quiescent current of only 25uA for the buck-boost regulator and only 35uA for each buck regulator (< 1uA each in shutdown for all).

The high 2.25MHz switching frequency allows the use of tiny low-cost capacitors and inductors less than 1mm in height while achieving very low output voltage ripple. Furthermore, all regulators are stable with ceramic output capacitors enabling a small footprint without thermal problems.

## THE LTC3576 PMIC WITH USB OTG SUPPORT

The LTC3576 features a bidirectional switching power manager with input overvoltage protection and USB On-The-Go (OTG) functionality, a stand-alone battery charger, three high efficiency synchronous buck regulators, an ideal diode, I<sup>2</sup>C control, plus an always-on LDO, all in a low-profile 38-pin 4mm x 6mm QFN package (see Figure 2).

The LTC3576's USB-compatible bidirectional switching regulator features programmable input current limits of 100mA and 500mA, as well as a 1A wall adapter input current limit. The IC can also take power from the battery to generate the 500mA at 5V needed for USB OTG applications, without any additional components, allowing the device to act as a host.

For fast charging, the LTC3576 converts nearly all of the 2.5W available from the USB port to charging current, enabling up to 700mA from a 500mA limited USB supply. Charging current may be as high as 1.5A from a wall adapter from a second external source. The IC provides an

overvoltage protection (OVP) control circuit that prevents damage to its input from the accidental application of voltages as high as 66V. The OVP circuit can protect the USB port even when the IC is providing power for USB OTG.

The LTC3576 provides Bat-Track control of a companion Linear Technology high voltage switching regulator for efficient charging from high voltage inputs, while minimising heat dissipation and providing a seamless transition between USB and the higher voltage power source.

The LTC3576's three integrated synchronous buck regulators are ceramic capacitor stable, feature 100% duty cycle operation and are capable of delivering output currents of 1A/400mA/400mA, respectively, with adjustable output voltages down to 0.8V. The internal low R<sub>DS(ON)</sub> switches enable efficiencies as high as 94%, maximising battery run time. In addition, Burst Mode operation optimises efficiency at light loads with a quiescent current of only 20uA per regulator (< 1uA in shutdown).

All three of the step down switching regulators can have their voltage adjusted "on-the-fly" via the I2C interface for voltage margining or optimising the performance/power tradeoff in micro-processors. Finally, the high 2.25MHz switching frequency allows the use of tiny low-cost capacitors and inductors less than 1mm in height.

## A MYRIAD OF END APPLICATIONS

The discussed PMIC family has been a great fit for consumer handheld USB-powered products such as personal media players

(PMPs), personal navigation devices (PNDs), electronic book readers and smart phones. However, the addition of new functional blocks and higher voltage and power capability has allowed these new PMICs to penetrate into other market spaces. For example, industrial portables such as tablet and rugged PCs or portable data entry terminals benefit from high input voltage capability and over-voltage protection from line transients of industrial system bus voltages. Medical devices benefit from a variety of voltage rail combinations and low quiescent currents. Portable automotive diagnostic and personal navigation device (PND) units benefit from high-voltage input capability to effectively power the unit from high voltage sources such as automotive adapters, in addition to USB. Even military applications such as vision systems and battlefield condition sensor systems benefit from the PMIC's rugged design and high voltage capabilities.

Table 2 highlights some of Linear Technology's high performance PMICs, ranging from lower-level integrated battery-fed topology ICs to linear PowerPath based ICs, to more sophisticated and higher level integrated switchmode PowerPath based PMICs.

## CHOICES

System designers now have new choices for their portable power needs. Instead of using discrete power IC components or traditional large PMICs, Linear Technology offers a new generation of compact PMICs that integrate key power management functions for a new level of performance and smaller, simpler solutions. This growing family of compact battery-fed, linear or switching PowerPath PMICs makes the product designer's job much easier.

The ICs feature the ability to extract more power from a USB port, seamlessly manage power flow between input sources, provide effective thermal management, increase efficiency via Bat-Track adaptive output control, provide low, intermediate and high voltage rails across the entire Lithium battery input range and simplify designs by utilising fewer and smaller external components.

Finally, these ICs also enable benefits for the product's end device as well, including USB charging and USB On-the-Go convenience, higher reliability, instantaneous system power with a dead battery, longer battery run-times and faster charge times. ■

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# PLC WITH PIC16F648A MICROCONTROLLER

## PART 2

The basic software of this programmable logic controller (PLC) called UZAM\_PLC makes use of general purpose 8-bit registers of RAM data memory of PIC16F648A. For the sake of simplicity, we restrict ourselves to use only BANK 0, i.e. all macros, including the basic definitions explained here, to be defined by means of 8-bit registers of BANK 0.

The file "definitions.inc" (all the files explained here including "definitions.inc" can be downloaded from <http://host.nigde.edu.tr/muzam/>). It contains all of the basic macros and definitions necessary for UZAM\_PLC. In this article we will explain the contents of this file. First of all, let's have a look at the file called "UZAM\_plc\_8i8o\_1.asm" shown in **Figure 1**. It is well-known that

ASSOCIATE PROFESSOR **DR MURAT UZAM** FROM NIGDE UNIVERSITY IN TURKEY PRESENTS A SERIES OF ARTICLES ON A PROJECT THAT FOCUSES ON A MICROCONTROLLER-BASED PLC. THIS IS THE SECOND ARTICLE OF THE SERIES AND IT COVERS THE BASIC SOFTWARE STRUCTURE OF THE UZAM\_PLC

the PLC's scan cycle includes the following: obtain the inputs, run the user program, update the outputs. This cycle repeats as long as the PLC runs.

Before getting into the endless PLC scan cycles, the initial conditions of the PLC are set up in the initialisation stage. These main steps can be seen from Figure 1, where "initialise" is a macro for setting up the initial conditions; "get\_inputs" is a macro for getting the inputs; and "send\_outputs" is a macro for updating the outputs. The "user PLC program" must be placed between

"get\_inputs" and "send\_outputs". The endless PLC scan cycles are obtained by means of the label "scan" and the instruction "goto scan".

UZAM\_PLC is fixed to run at 4MHz with PIC16F648A's internal oscillator. The watchdog timer is used to prevent user-program lock-ups. As will be explained later, the hardware timer TMR0 is utilised to obtain free-running reference timing signals.

### FILE DEFINITIONS

Next, let's consider the inside of the file "definitions.inc". The definition of 8-bit variables to be used for the basic software and their allocation in BANK 0 of RAM data memory are shown in **Figure 2a** and **2b** respectively. Although we can define as many inputs and outputs as we want, for the sake of simplicity we define four 8-bit input registers and four 8-bit output registers (Q0, Q1, Q2, Q3).

It is well-known that inputs taken from

```

-----
;
; Filename:  UZAM_plc_8i8o_1.asm
; Date:     28 January 2008
; Author:   Assoc. Prof. Dr. Murat UZAM
; Company:  Niğde Üniversitesi
;           Mühendislik-Mimarlık Fakültesi
;           Elektrik-Elektronik Mühendisliği Bölümü
;           Kampus, 51200, Niğde, TURKEY
;           http://host.nigde.edu.tr/muzam/
;           murat_uzam@nigde.edu.tr
;           murat_uzam@hotmail.com
;           Tel:  ++ 90 388 225 22 82
;           Fax:  ++ 90 388 225 01 12
;
; Notes:    This is the basic program
;           for PIC16F648 microcontroller
;           based UZAM PLC with
;           8 Inputs and 8 Outputs
;           and 32 Memory Bits (Internal Relays)
;
-----
list      p=16F648A           ;list directive to define processor
#include  <pl6f648a.inc>      ;processor specific variable definitions
#include  <definitions.inc>   ;basic PLC definitions, macros, etc.
CONFIG  CP_OFF& DATA_CP_OFF& LVP_OFF& BOREN_OFF& MCLR_OFF& WDT_ON
& PWRTE_ON& INTOSC_OSC_NOCLKOUT

org      0x00                ;Reset Vector
main
  initialize
scan
  get_inputs
;----- user program starts here -----
;----- user program ends here -----
  send_outputs
  goto   scan
end                          ;directive 'end of program'

```

Figure 1: The view of the file "UZAM\_plc\_8i8o\_1.asm"

It is also necessary to define and initialise all variables used within a PLC. Necessary functions are all described as PIC Assembly macros to be used in UZAM\_PLC. The macros described in this article could be summarised as follows: "HC165" (for handling the inputs), "HC595" (for sending the outputs), "dbncr" (for debouncing the inputs), "initialise", "get\_inputs", "send\_outputs".

```

----- VARIABLE DEFINITIONS -----
CBLOCK 0x20      ;Currently 4 Bytes are
bI0,bI1,bI2,bI3 ;reserved for 4 (bouncing)
endc            ;Input Registers (74HC165 ICs)
CBLOCK 0x24      ;Currently 4 Bytes are
I0,I1,I2,I3     ;reserved for 4 (debounced)
endc            ;Input Registers
CBLOCK 0x28      ;Currently 4 Bytes are
Q0,Q1,Q2,Q3     ;reserved for 4
endc            ;Output Registers (TPIC6B595 ICs)
CBLOCK 0x2C      ;4x8=32 Memory bits (Internal Relays)
M0,M1,M2,M3     ;
endc
CBLOCK 0x30      ;Currently 8 Bytes are
DBNCR           ;reserved for 8
endc            ;Debouncer Registers
CBLOCK 0x38      ;
DBNCRRED,Temp_1,Temp_2,Timer_2
endc
-----
    
```

**Figure 2:** (a) above – The definition of 8-bit variables to be used for the basic software, (b) below – Their allocation in BANK 0 of RAM data memory

20h	<b>bI0</b>
21h	<b>bI1</b>
22h	<b>bI2</b>
23h	<b>bI3</b>
24h	<b>I0</b>
25h	<b>I1</b>
26h	<b>I2</b>
27h	<b>I3</b>
28h	<b>Q0</b>
29h	<b>Q1</b>
2Ah	<b>Q2</b>
2Bh	<b>Q3</b>
2Ch	<b>M0</b>
2Dh	<b>M1</b>
2Eh	<b>M2</b>
2Fh	<b>M3</b>
30h	<b>DBNCR</b>
31h	<b>DBNCR+1</b>
32h	<b>DBNCR+2</b>
33h	<b>DBNCR+3</b>
34h	<b>DBNCR+4</b>
35h	<b>DBNCR+5</b>
36h	<b>DBNCR+6</b>
37h	<b>DBNCR+7</b>
38h	<b>Temp_1</b>
39h	<b>Temp_2</b>
3Ah	<b>Timer_2</b>
3Bh	<b>DBNCRRED</b>
	<b>BANK 0</b>

```

;----- BANK macros -----
BANK0 macro
    bcf STATUS,RP0
    bcf STATUS,RP1
endm
BANK1 macro
    bsf STATUS,RP0
    bcf STATUS,RP1
endm
BANK2 macro
    bcf STATUS,RP0
    bsf STATUS,RP1
endm
BANK3 macro
    bsf STATUS,RP0
    bsf STATUS,RP1
endm
;-----
    
```

**Figure 3:** BANK macros

contacts always suffer from “contact bouncing”. To circumvent this problem we will define a “debouncing” mechanism for the inputs and this will be explained later. In the “get\_inputs” stage of the PLC scan cycle, the input signals are serially taken from the related 74HC/LS165 registers and stored in the registers. As a result, bI0, bI1, bI2 and bI3 will hold these bouncing input signals. After applying the “debouncing” mechanism to the registers bI0, bI1, bI2 and bI3, we obtain “debounced” input signals and they are stored in registers I0, I1, I2 and I3 respectively.

We don’t have to use all of these registers. For example, if we use just the “main board”, then we have 8 inputs and therefore we can just use bI0 and I0. Similarly, if we use the “main board” with an “I/O extension board”, then we have 16 inputs and, therefore, we must use bI0, bI1 and I0, I1. Currently, for the sake of simplicity we restrict ourselves to the main board and, therefore, we need to use bI0 and I0.

In the “send\_outputs” stage of the PLC scan cycle, the output information stored in the 8-bit registers Q0, Q1, Q2, Q3 are serially sent out to and stored in the related TPIC6B595 registers. This means that Q0, Q1, Q2, Q3 registers will hold output information and they will be copied into the TPIC6B595 registers at the end of each PLC scan cycle. We don’t have use all of these output registers. For example, if we use just the “main board”, then we have 8 outputs and, therefore, we can use just Q0.

Similarly, if we use the “main board” with an “I/O extension board”, then we have 16 outputs and, so, we must use both Q0 and Q1. Currently, for the sake of simplicity we restrict ourselves to the main board and therefore we need to use only Q0. Four 8-bit registers, namely M0, M1, M2 and M3, are defined for obtaining 32 memory bits (internal relays, in PLC jargon).

To be used for the debouncer macro we define eight 8-bit registers (DBNCR, DBNCR+1, ..., DBNCR+7). In addition, the register DBNCRRED is also defined to be used for the debouncer macro. Temp\_1 is a general temporary register declared to be used in the macros. Temp\_2 is declared to be used especially for obtaining special memory bits as will be explained later. Timer\_2 is defined for storing high byte of the free-running timing signals.

```

;----- Definitions for 74HC165 -----
#define data_in PORTB,0
#define clock_in PORTB,6
#define shft_ld PORTB,7
;----- Definitions for TPIC6B595 -----
#define data_out PORTB,4
#define clock_out PORTB,3
#define latch_out PORTB,5
;----- LOGIC VALUES -----
#define LOGIC0 Temp_2,0
#define LOGIC1 Temp_2,1
;----- SPECIAL BITS -----
#define FRSTSCM Temp_2,2
#define SCNOSC Temp_2,3
;----- 8 INPUTS -----
#define bI0.0 bI0,0 ;b:bouncing
#define bI0.1 bI0,1
#define bI0.2 bI0,2
#define bI0.3 bI0,3
#define bI0.4 bI0,4
#define bI0.5 bI0,5
#define bI0.6 bI0,6
#define bI0.7 bI0,7

#define IO.0 IO,0 ;IO = debounced bI0
#define IO.1 IO,1
#define IO.2 IO,2
#define IO.3 IO,3
#define IO.4 IO,4
#define IO.5 IO,5
#define IO.6 IO,6
#define IO.7 IO,7
;----- 8 OUTPUTS -----
#define Q0.0 Q0,0
#define Q0.1 Q0,1
#define Q0.2 Q0,2
#define Q0.3 Q0,3
#define Q0.4 Q0,4
#define Q0.5 Q0,5
#define Q0.6 Q0,6
#define Q0.7 Q0,7

```

Figure 4: Definitions of one-bit variables

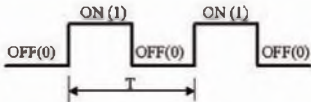


Figure 5: Timing diagram of the free-running reference timing signals (T = 0.512, 1.024... 16777.216ms)

The low byte of free-running timing signals is stored in TMRO (recalled as Timer\_1).

For accessing the RAM data memory easily, BANK macros are defined as shown in Figure 3. The definitions of one bit variables are depicted in Figure 4. The following definitions are self explanatory: 74HC165, TPIC6B595, 8 INPUTS, 8 OUTPUTS, 32 Memory Bits. Let us now have a look at the others.

```

;----- Macro HC165 -----
HC165 macro num,var0 ;This macro can be used for 74HC/HCT/LS165
local i=0,j=0 ;parallel to serial shift register ICs
bcf shft_ld ;latch
nop ;the inputs
nop ;of all 74HC165's
bsf shft_ld ;carry on while j < num
while j < num ;for each 74HC165, 8 times do the following
while i < 8 ;rotate the register "var0+j" one position left
rlf var0+j,f ;if the data_in is set then skip
btfss data_in ;if the data_in is reset then reset "var0+j,0"
bcf var0+j,0 ;if the data_in is set then skip
btfsc data_in ;if the data_in is set then set "var0+j,0"
bsf var0+j,0 ;generate
bcf clock_in ;a clock_in
nop ;pulse
bsf clock_in ;increment "i"
i += 1 ;after 8 iterations end the while loop for "i"
endw ;i=0 : get ready
i=0 ;increment "j" : for a new 74HC165
j += 1 ;after 'num' iterations end the while loop for "j"
endw
endm ;end macro HC165

```

Figure 6: The macro "HC165"

### OTHER VARIABLES

The variable "LOGIC0" is defined to hold logical "0" value throughout the PLC operation. At the initialisation stage it is deposited with this value. Similarly, the variable "LOGIC1" is defined to hold logical "1" value throughout the PLC operation. At the initialisation stage it is deposited with this value.

The special memory bit "FRSTSCN" is arranged to hold the value of "1" at the first PLC scan cycle only. In the other PLC scan cycles following the first one it is reset. The other special memory bit "SCNOSC" is arranged to work as a "scan oscillator". This means that in one PLC scan cycle this special bit will hold the value of "0", in the next one the value of "1", in the next one the value of "0" etc. This will keep on going for every PLC scan cycle. Let us now consider the 16 reference timing signals.

As seen later, TMRO of PIC16F648A is set up to count the 1/4 of 4MHz internal oscillator signal, i.e. 1MHz with a prescaler arranged to divide the signal to 256. As a result by means of TMRO bits (also called Timer\_1) we obtain eight free-running reference timing signals with the "T" timing periods starting from 0.512ms to 65.536ms. We'll see later that the register "Timer\_2" is incremented on Timer\_1 overflow. This also gives us (by means of Timer\_2 bits) eight more free-running reference timing signals with the "T" timing periods starting from 131.072ms to

16777.216ms.

Timing diagram of the free-running reference timing signals is depicted in Figure 5. Note that the evaluation of TMRO (Timer\_1) is independent from PLC scan cycles, but Timer\_2 is incremented within the "get\_inputs" stage of PLC scan cycle on Timer\_1 overflow. This is justified as long as the PLC scan cycle takes less than 65.536ms.

### THE MACROS

The macro "HC165" is shown in Figure 6. The input signals are serially taken from the related 74HC/LS165 registers and stored in the registers such as bI0, bI1, bI2 and bI3 by means of this macro. The "num" defines the number of 74HC/LS165 registers to be considered. This means that with this macro we can obtain inputs from as many 74HC/LS165 registers as we wish.

However, as explained before, we restrict this number to be 4 at most for the sake of simplicity; "var0" is the beginning of the registers to which the state of inputs taken from 74HC/LS165 registers will be stored. This implies that there should be enough RAM locations reserved after "var0" and, also, there should be enough 74HC/LS165 registers to get the inputs from. There are some explanations within the macro to describe how it works.

As can be seen, this macro makes use of previously defined "data\_in", "clock\_in" and "shft\_ld" bits to obtain the input

```

;----- Macro HC595 -----
HC595 macro num,var0 :This macro can be used for 74HC/ECT/LS595
local i=0,j=num-1 ;or TPIC6B595 serial to parallel shift register ICs
while j >= 0 ;carry on while j >= 0
while i < 8 ;for each TPIC6B595, 8 times do the following:
rlf var0+j,f ;rotate the register "var0+j" one position left
btfss STATUS,C ;if the Carry flag is set then skip
bcf data_out ;if the Carry flag is reset then reset data_out
btfsc STATUS,C ;if the Carry flag is reset then skip
bsf data_out ;if the Carry flag is set then set data_out
bsf clock_out ;generate
nop ;a clock_out
bcf clock_out ;pulse
i += 1 ;increment "i"
endw ;after 8 iterations end the while loop for "i"
rlf var0+j,f ;rotate the register "var0+j" one position left
i=0 ;i=0 : get ready
j-- 1 ;decrement "j" : for a new TPIC6B595
endw ;after 'num' iterations end the while loop for "j"
bsf latch_out ;Latch the serially shifted out data
nop ;on all
bcf latch_out ;TPIC6B595's
endm ;end macro HC595
;-----

```

Figure 7: The macro "HC595"

```

;----- macro: debouncer -----
dbncr macro num,regi,biti,t_reg,t_bit,tcnst_01,tcnst_10,rego,bito
local L1,L2,L3,L4
btfsc rego,bito
goto L4
btfsc regi,biti
goto L2
clr DBNCR+num
goto L1
L4 btfss rego,bito
goto L3
clr DBNCR+num
goto L1
L3 btfss t_reg,t_bit
bsf DBNCRRED,num
btfss t_reg,t_bit
goto L1
btfss DBNCRRED,num
goto L1
bcf DBNCRRED,num
incf DBNCR+num,f
movf DBNCR+num,w
xorlw tcnst_10
skpnz
bcf rego,bito
goto L1
L2 btfss t_reg,t_bit
bsf DBNCRRED,num
btfss t_reg,t_bit
goto L1
btfss DBNCRRED,num
goto L1
bcf DBNCRRED,num
incf DBNCR+num,f
movf DBNCR+num,w
xorlw tcnst_01
skpnz
bsf rego,bito
L1
endm
;-----

```

Figure 8: The macro "dbncr"

signals from 74HC/LS165 registers.

The macro "HC595" is shown in **Figure 7**. The output signals are stored in the 8-bit registers such as Q0, Q1, Q2 and Q3 in

RAM locations, and serially sent out to and stored in the related TPIC6B595 registers by means of this macro. The "num" defines the number of TPIC6B595 registers

to be used. This means that with this macro we can send output data serially to as many TPIC6B595 registers as we wish.

However, as explained before, we restrict this number to be 4 at most for the sake of simplicity; "var0" is the beginning of the 8-bit registers such as Q0 in RAM from which the state of outputs are taken and serially sent to TPIC6B595 registers. This implies that there should be enough RAM locations reserved after "var0" and, also, there should be enough TPIC6B595 registers to hold the outputs.

There are some explanations within the macro to describe how it works. As can be seen, this macro makes use of previously defined "data\_out", "clock\_out" and "latch\_out" bits to send the output signals serially to TPIC6B595 registers.

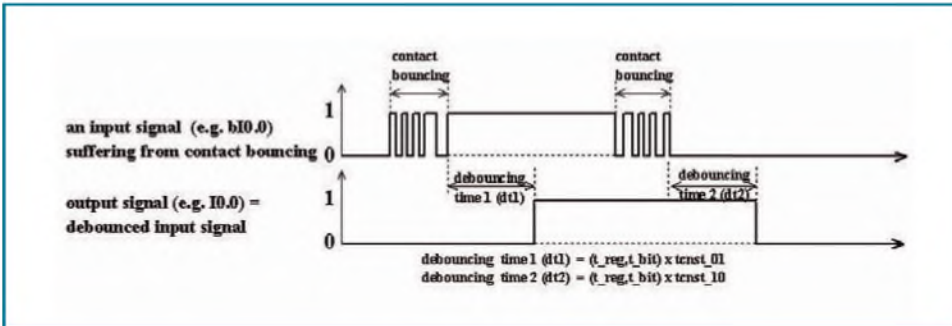
The macro "dbncr" is shown in **Figure 8**. It can be used for debouncing eight independent buttons, switches, relay or contactor contacts etc. The timing diagram of one channel of this debouncer is provided in **Figure 9**. It can be seen that the output changes its state only after the input becomes stable and waits in the stable state for the predefined debouncing time "dt1" or "dt2". The debouncing is applied to both rising and falling edges of the input signal.

In this macro, each channel is intended for a "normally open contact" connected to the PIC by means of a pull-down resistor, as this is the case with UZAM\_PLC. It can also be used without any problem for a "normally closed contact" connected to the PIC by means of a pull-up resistor.

The "debouncing times" such as 20ms, 50ms or 100ms can be selected as required depending on the application. It is possible to pick up different debouncing times for each channel. It is also possible to choose different debouncing times for rising and falling edges of the same input signal, if necessary. This gives a good deal of flexibility. This is simply done by changing the related time constant "tcnst\_01" or "tcnst\_10" defining the debouncing time delay for each channel and for both edges within the assembly program.

Note that if the state-change-of-the-contact is shorter than the predefined "debouncing time", this will also be regarded as bouncing and it will not be taken into account. Therefore, no state-





**Figure 9:** Timing diagram of one channel of the debouncer

change will be issued in this case. Each of the eight input channels of the debouncer may be used independently from other channels. The activity of one channel does not affect the other channels.

**THE MACRO “DBNCR”**

Let us now briefly consider how the macro “dbnrcr” works. First of all, one of the previously defined reference timing signals is chosen as “t\_reg,t\_bit” to be used

within this macro. Then, we can set up both debouncing times dt1 and dt2 by means of time constants “tcnst\_01” and “tcnst\_10” as  $dt1 = (t\_reg,t\_bit) \times tcnst\_01$  and  $dt2 = (t\_reg,t\_bit) \times tcnst\_10$  respectively.

If the input signal (regi,biti) = 0 and the output signal (rego,bito) = 0 or the input signal (regi,biti) = 1 and the output signal (rego,bito) = 1, then the related counter “DBNCR+num” is loaded with “00h” and

no state-change is issued. If the output signal (rego,bito) = 0 and the input signal (regi,biti) = 1, then with each “rising edge” of the reference timing signal “t\_reg,t\_bit” the related counter “DBNCR+num” is incremented by one. In this case, when the count value of “DBNCR+num” is equal to the number “tcnst\_01”, this means that the input signal is debounced properly and then state-change from 0 to 1 is issued for the output signal (rego,bito).

Similarly, if the output signal (rego,bito) = 1 and the input signal (regi,biti) = 0, then with each “rising edge” of the reference timing signal “t\_reg,t\_bit” the related counter “DBNCR+num” is incremented by one. In this case, when the count value of “DBNCR+num” is equal to the number “tcnst\_10”, this means that the input signal is debounced properly and then state-change from 1 to 0 is issued for the output signal (rego,bito). For this macro it is necessary to define the following 8-bit variables in RAM: Temp\_1, and DBNCRRED. In addition, it is also necessary to define eight 8-bit variables in successive RAM locations, the first of which is to be defined as “DBNCR”. It is not necessary to name the other seven variables. Each bit of the variable DBNCRRED is used to detect the “rising edge” of the reference timing signal “t\_reg,t\_bit” for the related channel.

**THE MACRO “INITIALISE”**

The macro “initialise” is shown in **Figure 10**. There are mainly two tasks carried out within this macro. In the former, first TMRO is set up as a free-running hardware timer with the 1/4 of 4MHz internal oscillator signal, i.e. 1MHz, and with a prescaler arranged to divide the signal to 256. In addition, PORTB is initialised to make RB0 (data in) as input and the following as outputs: RB3 (clock out), RB4 (data out), RB5 (latch out), RB6 (clock in), RB7 (shift/load). In the latter, all utilised RAM registers are loaded with initial “safe values”. In other words, all utilised RAM registers are cleared (loaded with 00h) except for Temp\_2, which is loaded with 06h. As explained before, Temp\_2 holds some special memory bits, therefore, the initial values of these special memory bits are put into Temp\_2 within this macro. As a result, these special memory bits are

```

;----- macro: initialize -----
initialize macro
    BANK1                ;goto BANK1
    movlw b'00000111' ;W <-- b'00000111' : Fosc/4 --> TMRO, PS=256
    movwf OPTION_REG ;pull-up on PORTB, OPTION_REG <-- W
    movlw b'00000001' ;PORTB is both input and output port
    movwf TRISB ;TRISB <-- b'00000001'
    BANK0                ;goto BANK0
    clrf PORTA ;Clear PortA
    clrf PORTB ;Clear PortB
    clrf bI0 ;Clear bI0
    clrf bI1 ;Clear bI1
    clrf bI2 ;Clear bI2
    clrf bI3 ;Clear bI3
    clrf I0 ;Clear I0
    clrf I1 ;Clear I1
    clrf I2 ;Clear I2
    clrf I3 ;Clear I3
    clrf Q0 ;Clear Q0
    clrf Q1 ;Clear Q1
    clrf Q2 ;Clear Q2
    clrf Q3 ;Clear Q3
    clrf M0 ;Clear M0
    clrf M1 ;Clear M1
    clrf M2 ;Clear M2
    clrf M3 ;Clear M3
    clrf DBNCR ;Clear DBNCR
    clrf DBNCR+1 ;Clear DBNCR+1
    clrf DBNCR+2 ;Clear DBNCR+2
    clrf DBNCR+3 ;Clear DBNCR+3
    clrf DBNCR+4 ;Clear DBNCR+4
    clrf DBNCR+5 ;Clear DBNCR+5
    clrf DBNCR+6 ;Clear DBNCR+6
    clrf DBNCR+7 ;Clear DBNCR+7
    clrf DBNCRRED ;Clear DBNCRRED
    clrf Timer_1 ;Clear Timer_1
    clrf Timer_2 ;Clear Timer_2
    clrf Temp_1 ;Clear Temp_1
    movlw 06h ;W <--- 06h
    movwf Temp_2 ;Temp_2 <--- W(06h)
    enda
;-----

```

**Figure 10:** The macro “initialise”

```

;----- macro: get_inputs -----
get_inputs macro
  local Nzero
  HC165 .1,bI0 ;obtain the 8 inputs from input
  dbncr 0,bI0.0,T00,.40,.40,I0.0 ;register (74HC165) and
  dbncr 1,bI0.1,T00,.40,.40,I0.1 ;put them into bI0
  dbncr 2,bI0.2,T00,.40,.40,I0.2 ;register within PIC16F648A.
  dbncr 3,bI0.3,T00,.40,.40,I0.3 ;Then debounce all bits of
  dbncr 4,bI0.4,T00,.40,.40,I0.4 ;bI0.
  dbncr 5,bI0.5,T00,.40,.40,I0.5 ;The debounced input signals
  dbncr 6,bI0.6,T00,.40,.40,I0.6 ;are stored in the register
  dbncr 7,bI0.7,T00,.40,.40,I0.7 ;I0

  btfsc Timer_1,7 ;
  bsf Temp_2,4 ;Increment Timer_2 on Timer_1 overflow
  btfsc Timer_1,7 ;
  goto Nzero ;
  btfsc Temp_2,4 ;
  goto Nzero ;
  incf Timer_2,f ;
  bcf Temp_2,4 ;

Nzero
  endm
;-----

```

Figure 11: The macro "get\_inputs"

```

;----- macro: send_outputs -----
send_outputs macro
  local L1,L2
  HC595 .1,Q0 ;take the 8 bits from Q0 register within PIC16F648A
  ;and put them into output register Q0 (TPIC6B595)

  clrwdt ;clear the watchdog timer

  bcf FRSTSCN ;reset the FRSTSCN bit

  btfsc SCNOSC ;toggle
  goto L2 ;the SCNOSC bit
  bcf SCNOSC ;after a program
  goto L1 ;scan
L2 bsf SCNOSC ;
L1
  endm
;-----

```

Figure 12: The macro "send\_outputs"

```

;----- user program starts here -----
movfw I0
movwf Q0
;----- user program ends here -----

```

Figure 13: A fraction of the first example program "UZAM\_plc\_8i8o\_ex1.asm"

```

;----- user program starts here -----
movfw Timer_2
movwf Q0
;----- user program ends here -----

```

Figure 14: A fraction of the second example program "UZAM\_plc\_8i8o\_ex2.asm"

loaded with the following initial values: LOGIC0 (Temp\_2,0) = 0, LOGIC1 (Temp\_2,1) = 1, FRSTSCN (Temp\_2,2) = 1, SCNOSC (Temp\_2,3) = 0.

### THE MACRO "GET\_INPUTS"

The macro "get\_inputs" is shown in Figure 11. There are mainly three tasks carried out within this macro. In the first one, the macro "HC165" is called with the parameters ".1" and "bI0". This means that we will use only the "main board" and, therefore, the macro "HC165" is called with the parameter ".1". As explained before, the input information taken from the macro is rated as "bouncing" information and, therefore, this information is stored in "bI0" register. For example if we decide to use the "main board" connected to three of the "I/O extension board" then we must call the macro "HC165" as follows: "HC165 .4,bI0". This will take four 8-bit bouncing input information from the 74HC/LS165 ICs and will put them to the four successive registers starting with the register bI0.

In the second task within this macro, each bit of bI0,  $i$  ( $i = 0, 1 \dots 7$ ) is debounced by the macro "dbncr" and each debounced input signal is stored in the related bit I0,  $i$  ( $i = 0, 1 \dots 7$ ). In general, 20ms time delay is enough for debouncing both rising and falling edges of an input signal. Therefore, to achieve these time delays, the reference timing signal, obtained from Timer\_1, is chosen as T00 (0.512ms period) and both "tcnst\_01" and "tcnst\_10" are chosen to be "40". Then we obtain the following:  $dt1 = T00 \times tcnst\_01 = (0.512ms) \times 40 = 20.48ms$ ,  $dt2 = T00 \times tcnst\_10 = (0.512ms) \times 40 = 20.48ms$ .

Note that in this series of articles for the sake of simplicity we use just 8 inputs and 8 outputs. If we want to add more inputs and to debounce these inputs, then we must organise the macro "dbncr" and locate necessary number of registers within the RAM.

The last task is about incrementing the Timer\_2 on overflow of Timer\_1. In this task, "Timer\_2" is incremented by one when the falling edge of the bit "Timer\_1,7" is detected. In order to detect the falling edge of the bit "Timer\_1,7", "Temp\_2,4" bit is utilised.

### THE MACRO "GET\_OUTPUTS"

The macro "send\_outputs" is shown in **Figure 12**. There are mainly four tasks carried out within this macro. In the first one, the macro "HC595" is called with the parameters ".1" and "Q0". This means that we will use only the "main board" and, therefore, the macro "HC595" is called with the parameter ".1".

As explained before, the output information is taken from the register Q0 and this macro sends the bits of Q0 serially to TPIC6B595 register. For example, if we decide to use the "main board" connected to three of the "I/O extension board" then we must call the macro "HC595" as follows: "HC595 .4,Q0". Then, the macro "HC595" will take four 8-bit output information stored in Q3, Q2, Q1 and Q0 and send them serially to the four TPIC6B595 register ICs respectively.

In the second task within this macro, the watchdog timer is cleared. In the third task, the "FRSTSCN" special memory bit is reset. As the final task, within this macro the "SCNOSC" special memory bit is toggled after a program scan, i.e. when it is "1" it is reset, when it is "0" it is set.

### EXAMPLES

Up to now we have seen the hardware and basic software necessary for UZAM\_PLC. It is now time to consider a few examples. Before you can run the two simple examples considered here, you are expected to construct your own UZAM\_PLC hardware by using the necessary PCB files and producing PCBs with its components.

For the first example, include the user program shown in **Figure 13** within the "UZAM\_PLC\_8i8o\_1.asm" and then save it as "UZAM\_PLC\_8i8o\_ex1.asm". The next thing to do is to open it by MPLAB IDE and to compile it. After that, by using the PIC programmer software take the compiled file "UZAM\_PLC\_8i8o\_ex1.hex" and by your PIC programmer hardware, send it to the program memory of PIC16F648A microcontroller within the UZAM\_PLC.

After loading the "UZAM\_PLC\_8i8o\_ex1.hex", switch the 4PDT in "RUN" and the power switch in "ON" position. Now, you are ready to test the first example program. You can see that all the inputs are transferred to the

respected outputs. That is to say that if  $I0.0 = 0$  then  $Q0.0 = 0$  and, similarly, if  $I0.0 = 1$  then  $Q0.0 = 1$ . This applies to all 8 inputs and 8 outputs.

For the second example, please include the user program shown in **Figure 14** within the "UZAM\_PLC\_8i8o\_1.asm" and then save it as "UZAM\_PLC\_8i8o\_ex2.asm". Next open it by MPLAB IDE and compile it. After that by using the PIC programmer software take the compiled file "UZAM\_PLC\_8i8o\_ex2.hex" and by your PIC programmer hardware send it to the program memory of PIC16F648A microcontroller within the UZAM\_PLC.

After loading the "UZAM\_PLC\_8i8o\_ex2.hex", switch the 4PDT in "RUN" and the power switch in "ON" position. Now, you are ready to test the second example program. In this case the contents of "Timer\_2" register are transferred to 8 outputs.

Of course, in these two examples the user programs include only PIC Assembly instructions, but we will start using our own macro-based PLC instructions in the next article. ■

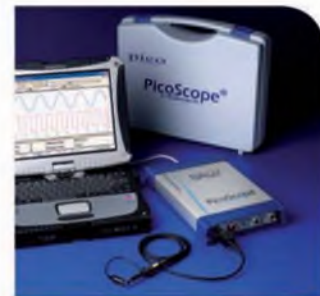
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The company is also exhibiting examples of products from its wide portfolio of frequency control devices including the latest SST (spread spectrum technology) oscillators offering low EMI emissions.

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represent a breakthrough in configurable frequency control solutions, featuring proprietary ASICs designed and developed with a key focus on noise reduction techniques.

New Statek CXOMHT surface mount oscillators are high temperature versions of the CXOM range and offer high stability and fast start up.

The T1220 is a new surface mount TCXO from Greenray Industries that offers temperature stabilities more usually associated with oven controlled temperature compensated (OCXO) devices.

Euroquartz's EQHM range is a cost-effective solution for clock oscillator generated EMI problems without the need for expensive and time consuming PCB redesign phases.

[www.euroquartz.co.uk](http://www.euroquartz.co.uk)

**Electronica Location B6.156**

## Industrial, Railway and Military Connectors Display



PEI-Genesis will be featuring a comprehensive line-up of leading manufacturers' industrial, railway and military connectors, all of which are available with the company's 48-hour connector assembly service.

For industrial applications, PEI-Genesis will be showing the Amphenol 62IP range of miniature bayonet-lock

connectors, which offer IP67 environmental protection and a moulded thermoplastic construction with a smooth, low-lustre black finish that requires no additional plating. Neoprene rubber is used for the insert material and the connectors are supplied with gold-plated solder-bucket contacts.

Demonstrating PEI's rail-industry capability will be ITT's

versatile CIR series multi-pin connectors, which can be configured with a wide variety of inserts and contacts to provide electrical, fibre-optic or pneumatic interconnections. Designed specifically for the hostile environment of railway applications, the VEAM CIR connectors feature a positive-lock/quick-disconnect bayonet coupling mechanism and achieve high shock and vibration resistance without the need for lock wires.

The display of military connectors on the PEI-Genesis stand will be spearheaded by ITT's VEAM PT (Pattern 105) range of military audio connectors, which are widely used in fighting vehicles and ground-based military communications equipment such as the MoD's Clansman and Bowman radio systems.

[www.peigenesis.co.uk](http://www.peigenesis.co.uk)

**Electronica Location B3.133**

## New Commercial Digital Media Player



Digital View's new ViewStream 400 is a digital video player designed for use with High Definition (HD) LCD and Plasma displays for various environments. Applications include, but are not limited to, point-of-purchase (POP) messaging and

promotions, product demonstration videos, digital menu boards, customer information kiosks, employee training role playing and museum information displays.

The ViewStream 400 is designed to be used as a standalone player without network connectivity. Content is updated via the USB port and a USB memory stick. Standard configuration will

allow the ViewStream 400 to store more than 50 hours of content via a SATA hard drive. Content scheduling and play list management is handled using DV Studio Plus, which is supplied free of charge.

Supported media formats include, MPEG-1, MPEG-2 and MPEG-4 video in standard definition and MPEG-2 in high-definition resolution. MP3 audio and JPEG file formats are also supported.

The ViewStream 400 is compact, measuring 180mm x 235mm x 60mm, and weighs only 1.2kg. Video output is through the ARGB port. Audio Output is via a 3.5mm stereo audio jack.

An OEM version of the ViewStream 400 is also available.

[www.digitalview.com](http://www.digitalview.com)

**Electronica Location A3.120**

## New Range of Vandal-Proof Keypads



Lorlin Electronics will be previewing their new range of vandal-proof keypads at Electronica 2008. The new KP range offers 1, 2, 3, 4, 12 and 16 button versions for

applications requiring a simple push button control to complex alpha numeric security entry systems. The keypads are available in black or chrome finishes to meet system design requirements and may be LED illuminated with a wide range of colour options. The weather and dust resistant IP rated keypads may be front or rear mounted and the keys feature an anti-pull design for improved security.

Lorlin's vandal-proof metal keypads are ideal for security switching or access control in public and industrial environments, environmental controls and service access.

Also on display will be Lorlin's wide range of spring return key switches commonly used for security gates and shutters for commercial and industrial premises. Single and double impulsion versions are available to suit individual requirements.

On show also will be a wide range IP67 rated key switches for secure access to electrical control boxes and panels, telecoms street furniture, electrical machinery and industrial equipment, as well as some of Lorlin's customisable push-rotate potentiometers.

[www.lorlinelectronics.com](http://www.lorlinelectronics.com)  
**Electronica Location B4.643**

## Extended Intelligent Colour Display Platform



Anders Electronics is announcing an extension to its UMR (User Machine Relationship) family of intelligent colour display platforms. The latest platform will significantly extend the range of functionality and price points for designers and integrators looking to incorporate colour TFT-LCD and enhanced features into embedded applications.

The Anders UMR family of intelligent colour display platforms has been developed to help designers and system integrators deliver the ultimate

user experience in a wide variety of display-based applications. The range currently includes the UMR-X10-70 and UMR-X10-35, both of which will also be on display at Electronica 2008.

UMR display platforms easily 'plug' into developers' application hardware, as a ready-to-use, highly optimised embedded display interface on which to run a dedicated Graphical User Interface (GUI) that brings the product to life for the end user. Through adopting a UMR display platform, developers can avoid the common integration challenges that they must usually solve independently and can free up resources to focus on their core domain expertise and specific application development. The end result is a shorter time to market, a more cost-effective solution and an easy-to-use product.

[www.anders.co.uk](http://www.anders.co.uk)  
**Electronica Location A3.431**

## CleanTech 100 Award for Nanotecture

Nanotecture, the energy technology company, has been named as one of the CleanTech 100 companies by The Guardian/Library House.



The CleanTech 100 is an award which aims to highlight a group of the most promising private companies in Europe focusing on clean technology, with – companies selected on the basis of their potential for future growth and – beneficial environmental impact. With climate change and energy use nudging the top of political and commercial agendas, these are companies that have a stake in how the world develops, states CleanTech 100 literature.

Nanotecture was awarded the CleanTech 100 status in the Energy Storage sector for its ground-breaking work to produce next generation energy storage products utilising Nanotecture's unique nanoporous materials.

Bill Campbell, Nanotecture's CEO said: "This award is strong endorsement of both the company's technology and its potential contribution to clean, highly efficient energy storage."

Nanotecture Ltd is a UK-based nanomaterials company, engaged in product development of innovative energy storage products for the automotive and portable electronics industries.

[www.nanotecture.co.uk](http://www.nanotecture.co.uk)  
**Electronica Location B2.133**

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# CIRCUIT PROVIDING A SAFE SHUTDOWN FOR A BACK-TO-BACK PWM CONVERTER

In a variable speed wind energy system, two back-to-back PWM converters are usually connected between the induction generator (IG) and the three-phase grid, as shown in **Figure 1** (right). In this configuration, the power flow of CONVERTER 2 is controlled in order to keep the dc-link voltage constant, while CONVERTER 1 is set to meet the magnetisation demand of the IG and the fixed reference speed.

During the disconnection of the grid, or if there is a fault in the power system, both converters are disconnected. Should this occur, the energy stored in the stator of the IG cannot be supplied to the grid and the current can only flow through the rectifier diodes of CONVERTER 1 to the dc-link capacitor, making the voltage rise to a dangerous level. To avoid this problem, a shutdown block that discharges the dc-link capacitor is required.

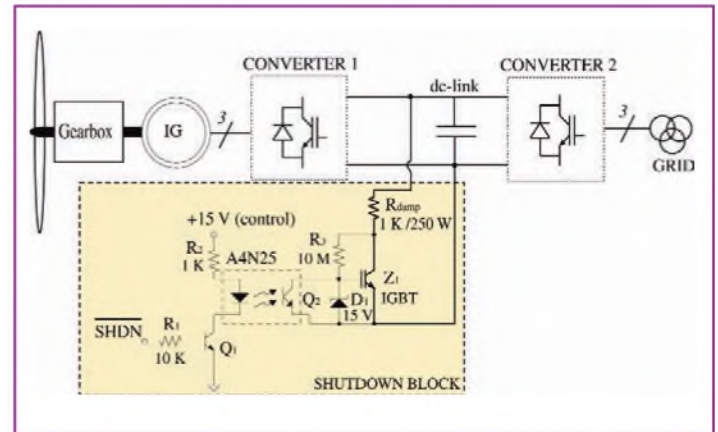
The circuit in Figure 1 implements this shutdown with few components, with a command signal generated by the control card which is isolated from the power system. Some of these circuits are implemented using a thyristor as a switching element. By using a thyristor the activation can only be controlled in the case of a shutdown, but this would not be so in the case of de-activation. The proposed shutdown block uses an IGBT to control both the activation (shutdown mode) and de-activation (normal mode).

In normal mode, the command is set,  $Q_1$  is on and the optocoupler turns off the IGBT ( $Z_1$ ). In shutdown mode, a low logic level is applied to the command,  $Q_1$  is switched off, the optocoupler output goes to a high-impedance state and the pull-up resistor  $R_3$  turns on the IGBT by pulling the gate high.

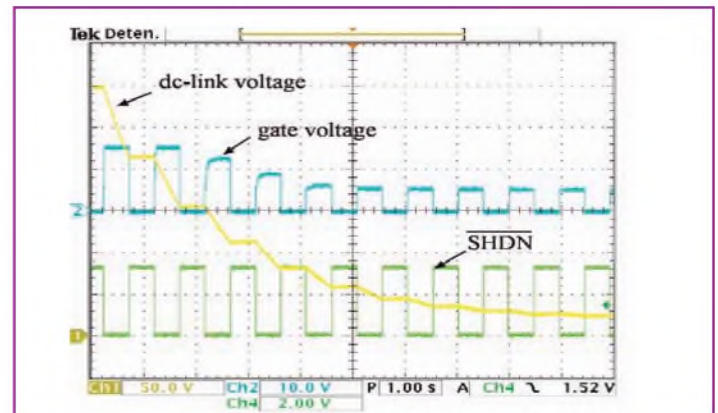
The  $R_{ON}$  of the IGBT, together with the  $R_{damp}$  resistor, acts as a voltage divider at the collector of the IGBT ( $V_{CE}$ ). This voltage  $V_{CE}$  is used to charge the equivalent gate-capacitor of the IGBT through  $R_3$ . Once the steady-state is reached and the gate-capacitor is charged, the current through  $R_3$  goes to zero and  $V_{GE}$  equals to  $V_{CE}$ .

The voltage  $V_{CE}$  is designed to be higher than the IGBT gate threshold voltage and, thus, to keep the IGBT activated. This imposes a maximum value of  $R_{damp}$  for a given value of the dc-link voltage and the  $R_{ON}$  of the IGBT. Moreover, the  $R_{damp}$  value fixes the discharge time constant of the dc-link capacitor.

In this particular case, the dc-link voltage is regulated to 300V, the dc-link capacitor value is 5mF and the  $R_{damp}$  resistor is selected of 1k $\Omega$ . This provides an initial collector current of approximately 0.3A, which gives a  $R_{ON}$  of tens of ohms for the selected IGBT (IRG4PC50KD), which increases as the dc-link capacitor discharges. If the  $R_{ON}$  of the selected IGBT is too big and/or a fast discharge of the dc-link capacitor is needed (small  $R_{damp}$ ), the resultant gate-voltage can overcome the maximum rating. For this reason, a zener diode ( $D_1$ ) of 15V has been



**Figure 1:** This circuit provides safe shutdown when grid disconnection is required, or if there is a fault in the power system



**Figure 2:** These curves show the discharge voltage of the dc-link capacitor and the gate-voltage of the IGBT when a sequence of pulses is applied in the command

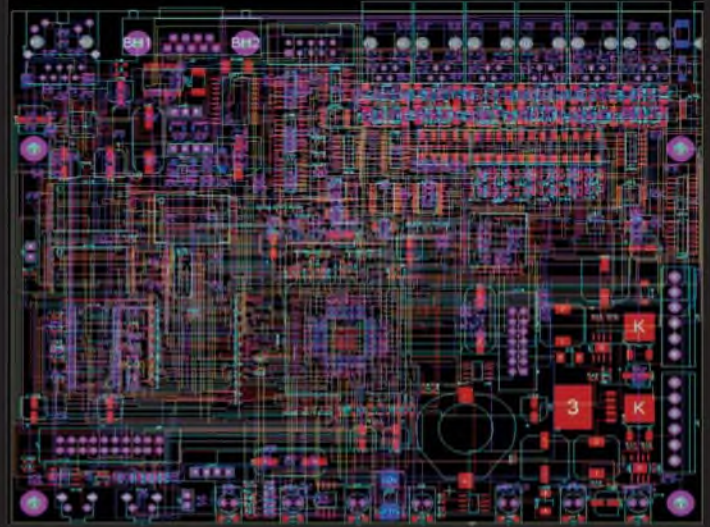
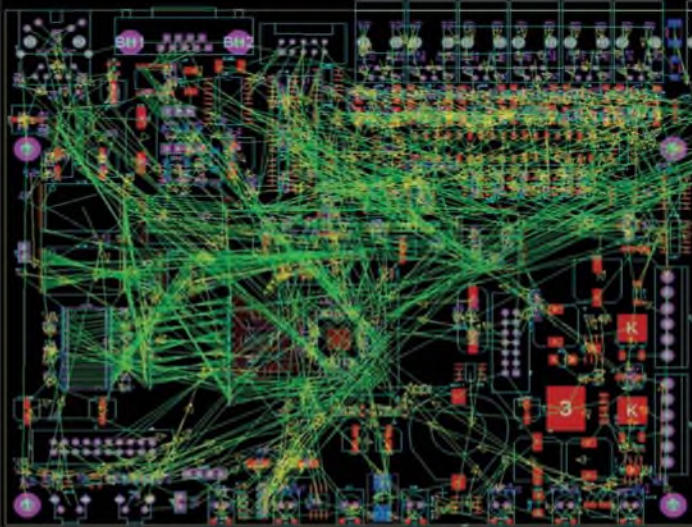
included at the gate of the IGBT.

A value of 10M $\Omega$  has been selected for  $R_3$ , so that in normal mode ( $Q_2$  on and  $Z_1$  off) the dc-link capacitor has in parallel a very high resistor. On the other hand, in shutdown mode, the  $R_3$  value, together with the equivalent gate-emitter capacitor of the IGBT, gives a slow switching-on but adequate for this application.

**Figure 2** shows the experimental waveforms when successive changes are applied between normal mode and shutdown mode.

**J. Castelló, R. García-Gil and J. M. Espí**  
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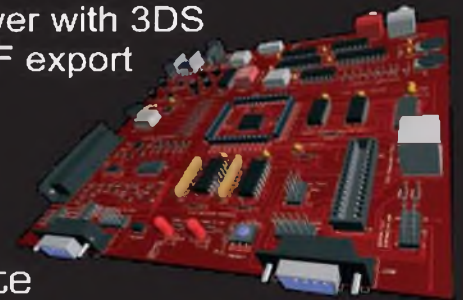


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## TIP: CMRR NOT CREATED EQUAL FOR ALL INAS

By Bonnie C. Baker, Senior Applications Engineer, Texas Instruments

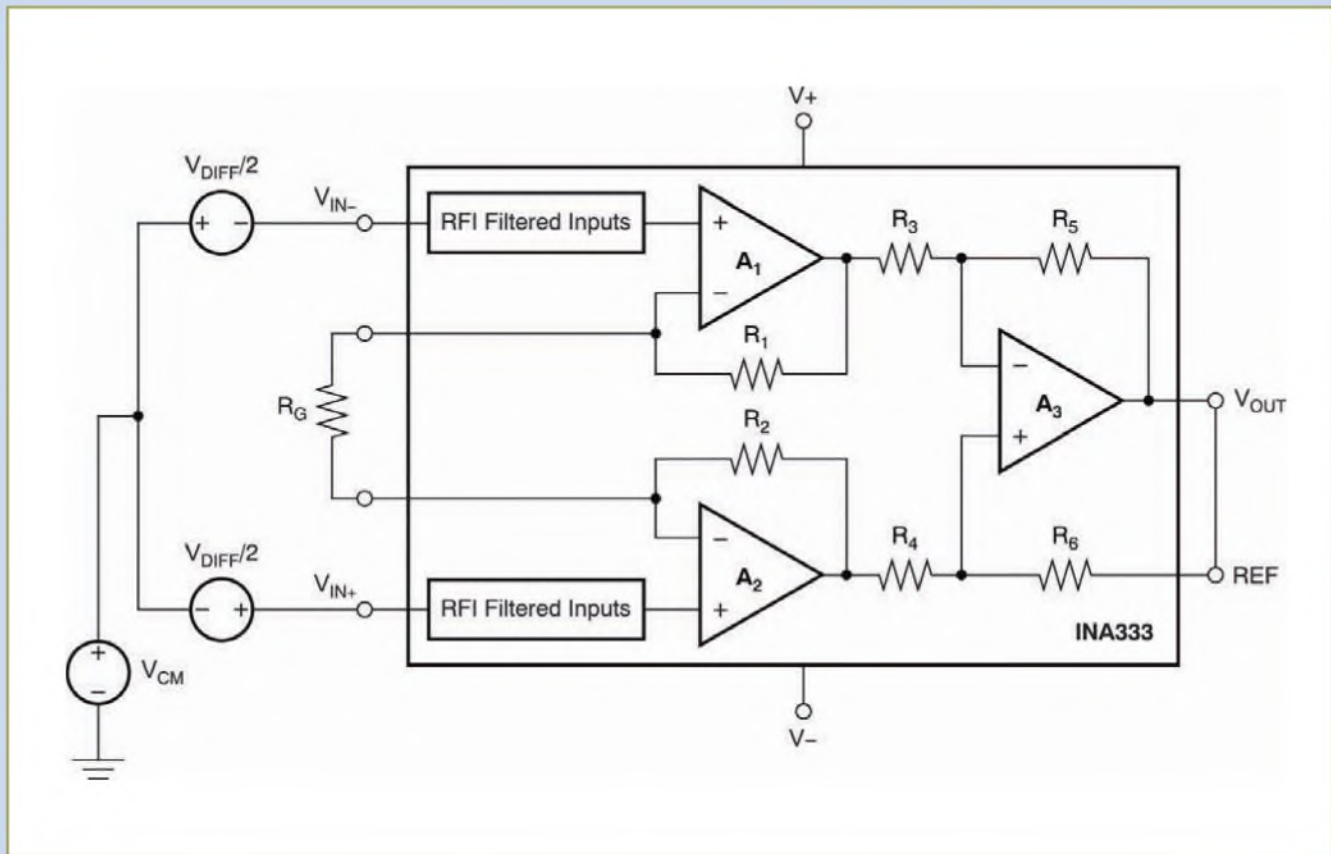


Figure 1: Classical 3-operational amplifier style instrumentation amplifier

### DOES CMRR CHANGE WITH GAIN?

With each type of INA, is the common mode rejection ratio (CMRR) independent of gain? CMRR compares a change in common-mode input voltage to a change in system offset (decibels):

$$CMRR = 20 \times \log_{10} \frac{\Delta V_{CM}}{\Delta V_{OFFSET}} \quad (1)$$

Manufacturers usually specify CMRR with an INA gain of one. This provides a good point for comparison from INA-to-INA. Don't assume CMRR is independent of gain. While CMRR in **Figure 1** is independent of gain, the CMRR in **Figure 2** is dependent on gain.

### NO SHORT ANSWER

Consider the INA design in Figure 1 as it lends itself to a more straightforward analysis. With this circuit the two input signals see the high-impedance, non-inverting inputs of the amplifiers (A<sub>1</sub> and

A<sub>2</sub>). The first stage also gains the two incoming signals. Adjust the gain with the gain resistor, R<sub>G</sub>. Following the first stage of this circuit is a difference amplifier (A<sub>3</sub>). This portion of the circuit rejects the common-mode voltage of the two input signals, as well as subtracts them.

The majority of the common-mode error for this type of topology at lower gains comes from a resistor mismatch in the back-end, difference-amplifier. Any mismatch between the ratios of R<sub>3</sub>:R<sub>4</sub> to R<sub>5</sub>:R<sub>6</sub> will generate a common-mode rejection error. For instance, let's assume the CMRR of the device in Figure 1 is 80dB. If a one-volt, common-mode input (V<sub>CM</sub>) change occurs, the output voltage changes by 100μV (per **Equation 1**). If you put the INA333 in a gain of 10V/V (R<sub>G</sub> = 11.11kΩ, R<sub>1</sub>R<sub>2</sub> = 50kΩ), the difference-amplifier resistors still contribute the same fixed error and produce an output error of 100μV.

If you refer this error to the input of the device, the change is equal to the output change divided by the gain or 10μV. Since the

CMRR specification is input-referred, the CMRR of this circuit in a gain of 10V/V is 100dB.

This theory works until the common-mode rejection of the front gain stage begins to dominate the system CMRR. For the INA333, at a gain of 100V/V the CMRR is 106dB, versus 120dB. This is because at higher gains, the mismatch of the difference-amplifier resistors ( $A_3$ ) no longer dominates the error term. The error term becomes more a function of the CMRR of the individual front-end op-amps ( $A_1$  and  $A_2$ ).

The INA configuration in Figure 2 has a different CMRR behaviour. The gain of this circuit is equal to:

$$GAIN = \left(1 + \frac{R_F}{R_{IN}}\right) + \left(1 + \frac{R_F}{R_{IN}}\right)\left(\frac{R_2}{R_1}\right) \quad (2)$$

By following the series path of the input signal, you can see that the gain is set with the back-end amplifier ( $A_3$ ). With this configuration, the change in offset of  $A_1$  and  $A_2$  will be gained by  $(1 + R_F/R_{IN})$  and summed to the offset change of  $A_3$ . This combined offset voltage from  $A_1$ ,  $A_2$  and  $A_3$  scales directly to the output by  $[1 + (R_2/R_1)]$ . Regardless of the gain set by  $R_1$  and  $R_2$ , the resistor mismatch around  $A_1$  dominates the common-mode error.

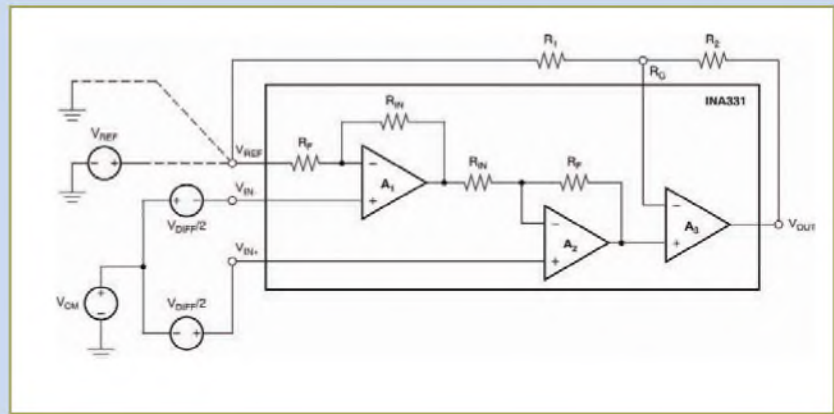


Figure 2: Baseband PR-ASK pulses at 64kbps

For instance, let's say we configure the INA in Figure 2 in a gain of five (i.e.  $R_1 = \text{open}$ ;  $R_2 = \text{short}$ ) and we apply a 1V common-mode ( $\Delta V_{CM}$ ) change at inputs of  $A_1$  and  $A_2$ . If this one volt common-mode input change creates a change of  $500\mu\text{V}$  at  $V_{OUT}$ , the corresponding referred to the input offset change is  $100\mu\text{V}$ . This is equivalent to a CMRR of 80dB.

If we increase the gain, the offset scales linearly to the output. Dividing the output by gain to obtain the input-referred offset does not change CMRR.

[Special thanks to Matthew Hann for his INA insights]

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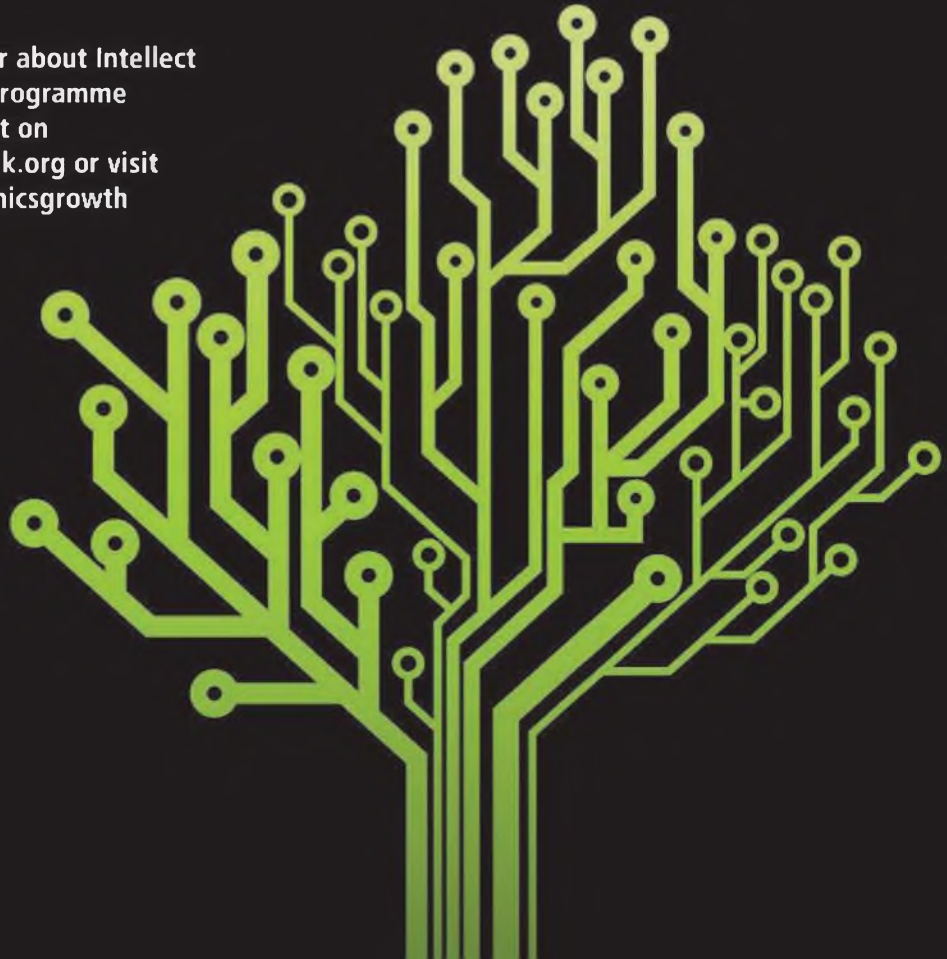
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As part of our efforts to promote and develop the UK electronics sector, we will be leading a delegation of British companies to electronica, the leading trade fair for the electronics industry, which takes place in Munich, between 11-14 November 2008. Visit Intellect on stand A5.175/2.

For more information on the delegation or about Intellect in general, please contact Henry Parker, programme manager - technology markets, at Intellect on 020 7331 2000, E [henry.parker@intellectuk.org](mailto:henry.parker@intellectuk.org) or visit our website, [www.intellectuk.org/electronicsgrowth](http://www.intellectuk.org/electronicsgrowth)



## COM Express Family Module Based On Intel Atom Processor N270

German-based congatec AG has enhanced its highly successful COM Express product family with the unveiling of the economically priced conga CA945 module. The new module features the Intel Atom processor N270 and the full-featured Mobile Intel 945GSE Express chipset in conjunction with the Intel I/O Controller Hub 7-M.



The complete design of this compact (95x95mm) COM Express module delivers excellent performance-per-watt at optimised price levels. The total thermal design power (TDP) of the processor/chipset combination is only 8 Watts, making applications that typically require less than 5 Watts ideal for this module. Combining this low power consumption with ACPI 3.0 battery management also provides the ability to create fully-featured mobile embedded applications.

The conga-CA945 supports three PCI Express Lanes, eight USB 2.0 ports, two serial ATA, two Express Cards, one IDE Interface and Intel High Definition Audio. Additionally, it features a 32-bit PCI bus, multi-master I<sup>2</sup>C bus, LPC bus, fan control and Gigabit Ethernet. A DDR2 SODIMM socket allows for flexible memory configuration up to 2 GBytes in size.

The conga-CA945 is equipped with 512 kByte L2 cache. It operates at 1.6GHz clock speed and utilises a 533MHz front-side bus.

[www.congatec.com](http://www.congatec.com)

## Smallest GPS Antenna Around

Alpha Micro Components announced that it has added Taoglas's smallest ever GPS Patch Antenna to its portfolio of embedded technologies. The new AP10 antenna patch, designed for use in smartphones, PDAs, personal tracking, navigation devices and mobiles phones, is one of the most compactly designed GPS receivers around.



Originally, developed for use in a touch-screen Smartphone device, this compact GPS antennae needed to be small, efficient and specifically tuned to the embedded GPS receiver, enabling location-based services and navigation capabilities to be added to the handset. Demand for such functionality in similar handsets is now rising, with requirement for all components including the antenna to be as small as possible, to sit comfortably within ever shrinking devices. In response, Taoglas has designed this miniature antenna and further ensured compatibility with all GPS receivers on the market by making the patch available in two formats: high-gain 2-stage LNA (Low Noise Amplifier) and low-gain 1-stage LNA.

The GPS patch antenna is available with a cable and connector which can be used for direct connection to a module or an onboard connector. Users requiring on-board integration have the chance to opt for the Surface Mountable (SMT) format.

[www.alphamicro.net](http://www.alphamicro.net)

## Naked Z-Foil Resistor Virtually Eliminates Distortion in Audio Applications



Charcroft announces the immediate availability of a new, naked ultra-high-precision resistor for high-end audio, multimedia and broadcast applications. Based on Vishay's Bulk Metal Z Foil resistor technology, the Charcroft CAR resistor is supplied with a protective coating, rather than

moulding or encapsulation, to deliver virtually distortion-free signal processing for the highest level of perceived sound clarity.

The resistors are built on the performance achieved by the previous generation of foil resistors to establish a new benchmark

for clarity and purity. They have been designed to improve signal processing integrity when replacing conventional resistors in differential amplifiers or power supplies for high-end audio products. CAR resistors can also be used in the feedback, loading and gain stages of audio circuits.

In addition to a low current noise of less than -40dB, CAR resistors achieve an excellent temperature coefficient of resistance (TCR) and power coefficient of resistance (PCR), whilst offering a fast rise time of 1ns without ringing. They also feature a non-inductive non-hot-spot design and withstand electrostatic discharges of over 25kV.

CAR resistors can be trimmed to any tolerance and any value within the resistance range of 10Ω to 100kΩ and are available now. [www.charcroft.com](http://www.charcroft.com)

## Expanded Offering of Next Generation Half-Brick DC/DCs



Murata Power Solutions has added two new ranges of single output, half-brick, isolated DC/DC converters to its product portfolio. The HPH series is a family of ultra-high output converters with different models capable of

delivering up to 360W of power and 70A output current. The UCH series comprises modules that deliver between 50W and 150W of output power and a maximum output current of 40A – at a very low cost.

Both the HPH and UCH series are isolated to 2250VDC with an open-frame construction and are designed for PCB mounting. Both series are in compliance with RoHS legislation and have UL60950-1 and EN60950-1 safety approvals.

HPH DC/DC converters offer a choice of fully regulated single outputs, ranging from 3.3VDC to 12VDC. A wide input voltage range of 36VDC to 75VDC, combined with an industry standard pinout and package measuring 61mm x 58.4mm x 10.2mm, simplifies the use of the modules in low-voltage/high-current OEM applications. The new converters utilise a full-bridge, fixed-frequency topology along with synchronous output rectification that enables levels of efficiency up to 91% to be achieved. Operating temperature range is -40°C to +85°C. An optional baseplate further enhances thermal performance.

[www.murata-ps.com](http://www.murata-ps.com)

## New UM Series Ultra-Compact PCB Mountable Supplies



Spellman High Voltage Electronics Corporation has announced the extension of its modular product line with the introduction of the UM Series. These printed circuit board mountable, high voltage modules offer easy form, fit and functional replacement for units presently available on the market. Utilising proprietary power conversion technology and high voltage packaging techniques, and aided by Spellman's advanced encapsulation techniques, the SMT-based UM series provides additional features compared to competitive models, at reduced cost.

The UM Series spans the output voltage range of 62 volts to 6kV in three power offerings of 4, 20 and 30 watts. An optional enhanced interface provides current programming capability and positive polarity, buffered, low output impedance voltage and current monitor signals. A second voltage programming input is also provided for negative polarity units, eliminating the programming inversion on the standard interface.

Current programming allows the user to set the unit's current limit, anywhere from 0 to 103% of maximum rated current. The UM can be used with confidence in demanding applications as these robust modules are fully arc and short-circuit protected.

[www.spellmanhv.com/um](http://www.spellmanhv.com/um)

## Cable Configurator For Ethernet Cabling

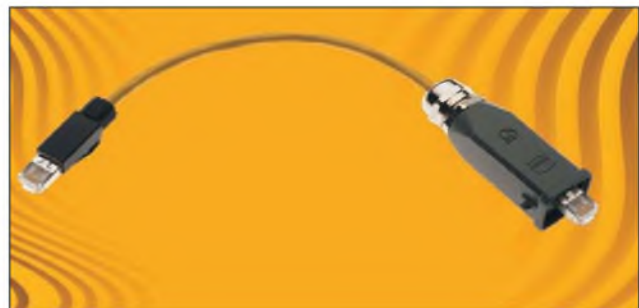
Harting has added a new cable configurator for Ethernet cabling to its Harkis catalogue information system.

With the new system, users can access and select the appropriate configuration of Ethernet cables and cable assemblies with only a few clicks. It also allows users to send an inquiry about the selected products directly to the company's sales department.

The cable configurator includes products for four poles (Category 5) and eight poles (Categories 5 and 6), as well as hybrid applications. The product portfolio comprises system cables in IP20 and IP65/IP 67 versions.

The new cable configurator can be found at [www.harkis.harting.com/harkisng/en/series/rji](http://www.harkis.harting.com/harkisng/en/series/rji).

The Harting Group develops, manufactures and distributes electrical and electronic connectors, network components, pre-assembled system cables and backplane assemblies. These products are capable of withstanding the harshest



demands in industrial environments and provide high data rates for electronic applications.

Harting connectors and network components are used in mechanical engineering and plant manufacturing, in automation systems, energy generation and distribution, and in electronic and telecommunication markets.

[www.harting.com](http://www.harting.com)

## Latching USB Cable Assemblies from GTK Ensure Secure Mating



Interconnect and opto-component manufacturer GTK has just announced the availability of latching USB cable assemblies that provide higher mating retention forces without having to

specify any different connector sockets. Featuring side-mounted squeeze latches that mate with any standard USB A socket, the assemblies are available in USB 1.1 and 2.0 with cable length and the opposite end connector to meet customer specifications.

The new cable assemblies deliver all the usual speed and size benefits of the USB standard interface yet suit applications where a more secure latch is required. For example, if the application is subject to shock or vibration latching is a real benefit. Similarly, with consumer items such as iPods leads are quite likely to be trodden on, so a more secure attaching mechanism is highly beneficial.

GTK's new secure matching USB cable assemblies are available in any configuration for volume requirements.

The company has ISO 9000-certified manufacturing facilities in China, and now delivers a comprehensive range of standard and custom interconnection components to European and American OEMs.

[www.gtk.co.uk](http://www.gtk.co.uk)

## Mixed-Signal Oscilloscope Family For Ease of Use

The new Yokogawa DLM2000 Series is a new family of mixed-signal oscilloscopes (MSOs) that represent a major step forward in terms of price/performance specification and ease of use.



With up to 500MHz bandwidth and 2GS/s sampling speed, the new

oscilloscopes have the longest memory (up to 125M points) and fastest update rate (up to 450,000 waveforms per second) in this class of instrument. In addition, the combination of flexible analogue and digital inputs, plus a large-screen display in a compact ergonomically-styled body, makes the instruments exceptionally easy to use.

In addition to the key performance specifications, the DLM2000 Series features a number of advanced measurement and analysis features, including histogram and trending functions, up to 20,000 history memories, digital filtering, zoom windows, user-defined mathematics and serial bus analysis.

The DLM2000 Series consists of six models: three with two channels and three with four, each covering the bandwidths 200, 350 and 500MHz, respectively. Mixed-signal oscilloscope operation is enabled on the 4-channel models by converting the fourth channel of analogue input to 8-bit logic, so that the instrument then functions as a 3-channel analogue plus 8-bit logic MSO. A high-resolution mode (up to 12-bit) is also available.

[www.yokogawa.com](http://www.yokogawa.com)

## Polyswitch RKEF Device Designed For Smaller Electronic Equipment

Tyco Electronics has introduced a new line of PolySwitch circuit protection devices. Designed for use in a wide variety of general electronic products, ranging from industrial controls to battery packs, the new PolySwitch RKEF devices are functionally equivalent to the company's existing RXEF overcurrent protection devices, but are available in a significantly smaller form-factor.

Key device parameters for the PolySwitch RKEF series include hold-current ratings of 0.5A to 5A and trip-current ratings of 1A to 10A. All devices have a maximum operating voltage rating of 60V and can operate at up to 85°C – the same maximum operating temperature as the RXEF series.

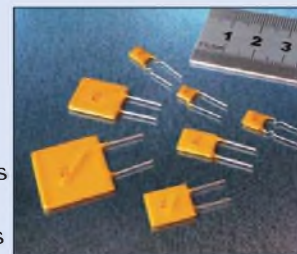
PolySwitch RKEF devices are of through-hole construction and

many of the radial-leaded devices have the same lead spacing as the RXEF devices. This facilitates easy replacement of RXEF

devices and can help designers optimise board space and improve thermal conditions. Lead spacing for the RKEF250 and RKEF300 devices is half that of the equivalent RXEF parts, yielding even more space.

PolySwitch RKEF devices are EU ROHS and ELV compliant, are compatible with industry standard installation procedures and are available in tape and reel packaging for compatibility with high-volume manufacturing.

[www.tycoelectronics.com](http://www.tycoelectronics.com)



## Flexible, High Performance 50MHz Arbitrary Waveform/Function Generator



Keithley Instruments has introduced the Model 3390 50MHz Arbitrary Waveform/Function Generator, featuring the highest waveform resolution and best price-to-performance value in its class. The Model 3390 is a flexible, easy-to-use programmable signal

generator with advanced function, pulse and arbitrary waveform capabilities. Superior signal integrity, faster rise and fall times, lower noise and greater waveform memory combine to provide high quality output signals.

Among its many useful features, the Model 3390 includes 50MHz maximum sine wave frequency; 25MHz pulse frequency with 10ns minimum width; arbitrary waveform generator with 256k-point, 14-bit resolution; built-in function generator capability including sine, square, triangle, noise, DC etc; precision pulses and square waves with fast (< 10ns) rise/fall times; built-in 10MHz external time base for multiple unit synchronisation; built-in AM, FM, PM, FSK, PWM modulation; frequency sweep and burst capability; LXI Class C-compliant Ethernet, TMC compliant USB and standard GPIB interfaces; digital pattern output port and control capabilities; and industry-leading sample speed and memory depth.

The Model 3390 can perform six different key functions in one package, saving valuable rack space and eliminating the need to purchase separate instruments.

Keithley is offering the Model 3390 for a special introductory price.

[www.keithley.com](http://www.keithley.com)

## High Density AC/DC Switching Power Supplies



The CF series from Murata Power Solutions is a new range of high density AC/DC switching power supplies. The single main output 200W and 350W open-frame units offer industry standard form-factor and high density. They

are ideal for use in distributed power architecture applications, redundant (N+1) operations, information technology equipment and industrial applications.

The series comprises a 200W model with a 12V (16.6A) main output and a choice of three 350W models, giving designers the choice of a 12V (29A), 24V (14.5A) or a 48V (7.2A) main output. All power supplies in the CF range offer a universal input (85 to 265VAC) with active power factor correction (PFC). They also feature an auxiliary 5V standby output to allow for system housekeeping and monitoring.

The 200W CF200-A12C has a high power density of 8W/in<sup>3</sup> that helps minimise the space required in customer applications. Synchronous rectification allows an efficiency level of over 80% to be achieved. Built to meet 1U height restrictions, the ruggedised open frame, U-channel package CF200-A12C has compact overall dimensions of 127mm x 84mm x 39.6mm.

350W models (CF350-A12C, A24C and A48C) achieve a power density of 9.5W/in<sup>3</sup> and similar levels of efficiency to 200W variants.

[www.murata-ps.com](http://www.murata-ps.com)

## Pressure Sensors in New SMT Housings



Sensortech's new HDO series is based on proven micromachined silicon elements to ensure highly stable and reliable pressure measurements. These sensors offer a wide selection of absolute, differential and gage pressure ranges from 10mbar up to 10 bar and feature an excellent price/performance ratio.

The HDO pressure sensors are precision calibrated and temperature compensated and intended to be used with air and non-corrosive gases. Innovative SMT housings allow for easy PCB-mounting and maximum OEM design flexibility. For all HDO sensors Sensortech can provide custom-specific pressure ranges and calibrations on request.

Due to its high accuracy and very wide measuring range Sensortech's new HDO series can be ideally used in many demanding OEM device applications like medical

devices, instrumentation, environmental controls and HVAC.

[www.sensortech.com](http://www.sensortech.com)

## World's First USB 3.0 Protocol Analyser Exerciser System

LeCroy Corporation announced its Voyager verification system, the world's first protocol analyser for USB 3.0, also known as SuperSpeed USB. Using custom front-end circuitry developed in conjunction with LeCroy's 5Gbps PCI-Express



platform, the Voyager analyser provides simultaneous protocol capture of both USB 2.0 and USB 3.0 signaling. Available with an integrated exerciser option, this sixth generation verification platform is LeCroy's complete solution for testing USB devices, systems and software.

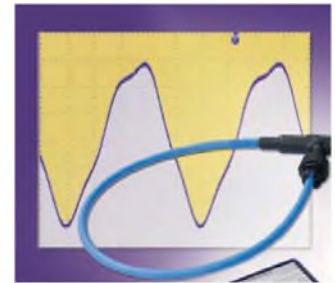
The USB 3.0 specification development was announced in September 2007 offering ten times the speed of USB 2.0 and backward compatibility with legacy devices. It features physical layer characteristics similar to PCI Express 2.0, including 5GHz signaling, that relies on link training to synchronise communication between devices. Aggressive power management represents an additional challenge for 3.0 validation teams as they contend with devices that frequently enter and exit low-power states.

To provide accurate data capture at 5GHz, the analyser must follow each link state transition and achieve bit lock in less than 1µs (when moving from idle to the active state). Any delay in signal lock can cause the analyser to miss data.

[www.lecroy.com/europe](http://www.lecroy.com/europe)

## New LFR Complements CWT From PEM

A new LFR AC current probe with market leading low frequency performance has been introduced by Power Electronic Measurements Ltd (PEM). This compact, low-cost, clip-around probe is both flexible and dual-range, while being



optimised to give minimal phase measurement error at frequencies from 45Hz to 20kHz. This is a Rogowski current probe, similar to PEM's highly successful CWT range, which covers 1Hz to 20MHz.

The LFR unit is ideal for use as a general purpose power frequency AC current probe and can be used with oscilloscopes, acquisition cards, data loggers, power analysers and meters. Other typical applications include power measurement, leakage current and power quality, where minimal phase error, low noise and good accuracy are key measurement criteria.

All Rogowski current probes generate noise, but the noise floor of the LFR is very small, and the LFR1/15 model is only 2.0mVrms on the 300A range. The rated output voltage is 6Vpeak for a 300A peak current, thus at 20% rated current the noise contributes less than 0.1deg additional uncertainty to the phase error. This is better than a measuring class 0.5 current transformer. The same unit with peak current rating 300A/3000A and coil length of 300mm has minimal phase measurement error at 50Hz of < 0.35deg and at 20kHz of < 1.8 deg.

[www.pemuk.com](http://www.pemuk.com)

## BestCap Series Addition for Wireless Applications

AVX Corporation has expanded its BestCap Series to include an ultra-low ESR double layer capacitors with an expanded temperature range from -40° to 75°C. Ideal for wireless applications, the capacitor series features high capacitance values and power pulse characteristics for high current, short pulse applications including GSM/GPRS wireless-based systems, USB modems, automatic meter reading systems, handheld scanners, battery chatter, dying gap and memory back-up systems.

The BestCap double layer capacitors are available in three different standard sizes with voltage ratings from 3V to 15V

and a capacitance range from 6.8 milli-Farad to 1 Farad.

The three standard sizes for the BestCap capacitor include BZ05 (20\*15 mm), BZ01 (28\*17 mm) and BZ02 (48\*30 mm). The BZ05 size offers the most aggressive capacitance value offering of 68 milli-Farads at 5.5V and 6.8 milli-Farads at 15V. The BZ02 has the largest capacitance value with 1 Farad at 5.5V and 68 milli-farads at 15V.

Typical pricing for the double layer capacitors start at \$2.90 each with delivery from stock to 10 weeks.

[www.avx.com](http://www.avx.com)



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### PHILLIPS

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## Increased Focus on Power Supplies and DC/DC Converters



Arrow Electronics has expanded its power technology portfolio by signing a distribution agreement with Recom, a leading global supplier of DC/DC and AC/DC converters. Arrow will sell and support Recom's complete power converter product range throughout Europe.

The new agreement is in line with Arrow's strategy to provide the widest possible range of power supply and converter technologies to designers across Europe. For

Recom, the agreement will expand the penetration of its product ranges into European markets and ensure that customers have access to products and support at a local level.

Available in single, dual, and triple rail outputs and a wide variety of input and output voltage configurations, power ratings, and isolation voltages, Recom converters are used in most industries requiring low- to medium-power voltage conversion in the 0.25W to 60W range. The company also offers the largest range of safety agency-approved converters from any manufacturer.

[www.arrowne.com](http://www.arrowne.com)

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## Harwin Names Abacus Pan-European "Distributor of the Year"



High-reliability interconnect company Harwin has named Abacus Group plc as Pan-European Distributor of the Year, citing "outstanding commitment" as the differentiating factor which resulted in the Newbury UK-headquartered company being given the award.

Abacus Group Plc is one of the leading distributors of electronic

components in Europe, with directly-owned group companies in every major European electronics market. "Abacus has been a vital part of our distribution network for many years, providing exemplary customer service through a wide

number of regional offices in the UK, Germany, Austria, France, Italy, Benelux and Scandinavia. They have demonstrated very high levels of focus in taking our new and existing product portfolio to market and we are delighted to name them Pan-European Distributor of the Year," said Harwin's MD, Andrew McQuilken.

"Harwin is a fine example of what you can achieve if you continue to manufacture in Europe. The company is quick to market with innovative new products and – because it retains all manufacturing processes in-house – is very quick to respond to requests for full custom or modified parts. We are honoured to receive this award," said Michelle Burns, Product Manager Emech at Abacus.

Harwin is a manufacturer of standard and custom interconnect components.  
[www.harwin.co.uk](http://www.harwin.co.uk)



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1.2GHz VIA Esther



## EPC-4853

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## 1GHz VIA Eden



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