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Automatic
Curtain Winder With add-on remote control

# Windicator Inexpensive l.e.d. readout Anemometer 

H.V.Capacitor Reformer For refurbishing valve equipment

The No. 1 Indepen
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$\&$ Computer Projects

ENERGY BANK KIT $1006^{\prime \prime} \times 6^{\prime \prime}$ 6V 100mA panels, 100 diodes, connection details etc. $£ 69.95$ ref EF112 CGTV CAMERA MODULES $46 \times 70 \times 29 \mathrm{~mm}, 30$ grams, 12 v 100 mA . auto electronic shutter, 3.6 mm F2 lens, CCIR, $512 \times 492$ pixels, video out ut is $1 v p-P$ ( 75 ohm). Works direcyy Into a scart or video input on a tv or video. IR sensitive. $£ 79.95$ ret EF13 IR LAMP KIr Sultable for the above camera
to be used in toral darkness! $\mathrm{E5} 59$ ref EF 138 . PASTEL ACCOUNTS SOFTWARE, does everything for all sizes of businesses, includes wordprocessor, report witer, windowing, networkable up to 10 stations, multiple cash books etc. 200 page comprehensive manuai. 90 days free technical support (0345-326009 try before you buy!) Current retail price is $£ 129$, ours just $£ 29$ ref EF 134 SAVE £100III
MINIMICRO FANS 12V $1.5^{\circ}$ sq just $£ 3.99$ each. Rel EF 199. C TTOH PRINTERS $80 \mathrm{col}, 9$ in matrix. serial/parallel, NLQ/draft. 3 mth warranty, good condition, £49 ref EF133
MICROSOFT TRACKBALL AND MOUSE Combined unit with 4 buttons and trackball, PS2 type connector. Complete with storage bracket Our price just $£ 11.99$ ref EF201. REUSEABLE HEAT PACKS. Ideal for fishermen, outdoor enthusiasts elderly or infim, waming food, drinks etc, defrosting
plpes etc. reuseable up to 10 times, lasts for up to 8 hours per go, plpes etc. reuseable up to 10 times, lasts for up to 8 hours per go,
2,000 , 1,44M B 3.5" DSC DRNES Returnsfromatop PC manufactuer 1.44 MB 3.6 D
so they may need attention. bargan price $£ 8.50$ ea ref EF 203 . 1.2MB6.26" DISC DRNES Again returns somay need attention, bargain price is $£ 8.50$ ref EF204. (1 of each 1.2+1.44 $£ 14.99$ refef205 A4 DTP MON ITORS Brand new, 300 DPI. Complete with diagram but no interface detaiks.(so you will have to work it out!) Bargain at just £7.99 eachll!! Ref EF186 OPD MONITORS $9^{\circ}$ mono monitor, fully cased complete with raster board, switched mode psuetc. CGATTLLinput ( 15 way D). IEC mains. $£ 15.99$ ref DEC23. Pnce including kitto convert to composite monitor for CCTV use etc is $£ 21.53$ ref DEC24
12V 2AMP LAPTOP psu's $110 \times 55 \times 40 \mathrm{~mm}$ (includes standard IEC socket) and 2 m lead with plug. $100-240 \mathrm{~V}$ IP. $£ 8.99$ rel EF200. PC CONTROLLED 4 CHANNEL TMER Control (onvof times etc) up to 4 items (8A 240v each) with this kit. Complete with Software, relays, PCB etc. £25.99 Ref 95/26
COMPLETE PC 300 WATT UPS SYSTEM Top of the range UPS system providing protection for your computer system and valuable software against mains power fuctuations and cuts. New and boxed, UK made Provides up to 5 mins running tme in the event of complete power failure to allow you
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RACAL MODEM BONANZAI 1 Racal MPS1223 $1200 / 75$ modem, telephone lead, mains lead, manual and comms software, the cheapest way onto the netl all this for just $£ 13$ ref DEC13 HOW LOW ARE YOUR FLOPPIES? $3.5^{\circ}(1.44)$ unbranded. We have sold $100,000+$ so ok! Pack of $50 £ 24.99$ ref DEC 16 6 mw LASER POINTER. Supplied in kit form, complete with power adjuster, $1-5 \mathrm{mw}$, and beam divergence adjuster. Runs on 2
AAA batteries. Produces thin red beam ideal for levels, gun sights, expenments etc. Cheapest in the UK! just $£ 39.95$ ref DEC49 SHOP WOBBLERS!Small assemblies designed to take D size batteries and 'wobble' signs about in shops! £3.99 Ref SEP4P2 RADIO PAG ERSBrand new. UK made pocket pagers clearance price is just $£ 4.99$ each $100 \times 40 \times 15 \mathrm{~mm}$ packed with bits! Rel SEP5. BULL TENS UNTT Fully built and tested TENS (Transcutaneous Electrical Nerve Stimulation) unit, complete whith electrodes and full Instructions. TENS is used for the relief of pain etc in up to $70 \%$ of sufferers. Drug free pain relief, safe and easy to
conjunction with analgesics etc. £49 Ref TEN/1
COMPUTER RS232 TERMINALS. (LIBERTY)Excellent quality modern units, (like wyse 50 , ) 2xRS232, 20 function keys, 50 thro to 38,400 baud, menu driven port, screen, cursor, and keyboard setup menus ( 18 menu's). £29 REF NOV4.
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ELECTRIC MOTOR BONANZA! $110 \times 60 \mathrm{~mm}$ Brand new precision, cap start (or spin to start), vitually silent and features a predision, cap start (or spin to start), vitualy slient and features a
moving outer case that acts as a fly wheel. Because of their unusual moving outer case that acts as a lly whee. Because of their unade fan
design we think that 2 of these in a tube with somemate design we think that 2 of these in a tube with some homemade fan
blades could form the basis for a wind turnel etc. Clearance price is blades could form the basis for a wind tunnel etc. Clearance price is
just£4.99 FOR APAIR! (note-these will have to be wired in series for 240 V operation Ref NOV1
MOTOR NO 2 BARGAIN $110 \times 90 \mathrm{~mm}$. Similar to the above motor but more suitable for mounting vertically (ie turntable etc). Again you will have to wire 2 in senes for 240 v use. Bargain price is just E4.99 FOR A PAIR!! Ref NOV3.
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TELEBOX ST for composite video input type
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& \text { TELEBOX MB Multiband VHF-UHF-Cable-Hyp }
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$1 \times$ Suck or Blow-Operated Pressure Switch. Or it can be operated by any low pressure variation such as water level in tanks. Order Ref. 67
$1 \times 6 \mathrm{~V} 750 \mathrm{~mA}$ Power Supply. Nicely cased wlth mains input and 6 V output lead. Order Ref: 103A.
$2 \times$ Stripper Boards. Each contains a 400V 2A bridge ectifier and 14 other diodes and rectifiers as well as dozens of capacitors, etc. Order Ref: 120
12 Very Fine Drills. For PCB boards etc. Normal cost bout 80p each. Order Ref: 128
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6 x Microphone Inserts. Magnetic 400 ohm, also act s speakers. Order Ref: 139
$6 \times$ Neon Indlcators. In panel mounting holders with ens. Order Ref: 180.
x In-Flex Simmerstat. Keeps your soldering iron etc always at the ready. Order Ref:196.
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$2 \times 6 \mathrm{~V}$ Operated Reed Relays. One normally on, other normally closed. Order Ref: 48
$1 \times$ Cabinet Lock. With two keys. Order Ref: 55
$61 / 2^{\prime \prime} 8 \Omega 5$ Watt Speaker. Order Ret: 824
$1 \times$ Shaded-Pole Mains Motor. ${ }^{4}{ }^{*}$ " stack, so quite powerful. Order Rel: 85.
an Blades. Could be fitted to the above motor. Order Ref: 86
$1 \times$ Case, $31 / 2^{\prime \prime} \times 21 / /^{\prime \prime} \times 1 \frac{3}{4} "^{\prime \prime}$ with $13 A$ socket pins. $4 \times$ Luminous Rocker Swliches. 10A mains. Order Ref: 793.
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of 100 , 1 , Prom Rets for insulation through panel. Packe Malns Trandermel.
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## More Information:

All listed items come with data and instructions. For more information, including reprints of the appropriate magazine articles, send an SAE + £1.00 per kit - or phone and use Mastercard/Visa etc.

## Mini-Lab \& Micro Lab Electronics Teach-In 7

As featured in EPE and now published as Teach-In 7. All parts are supplied by Magenta. Teach-In 7 is $£ 3.95$ from us or EPE Full Mini Lab Kit - £119.95-Power supply extra - £22.55 Full Micro Lab Kit - $£ 155.95$ Built Micro Lab - $£ 189.95$

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## DIVERSITY

One of the things which makes electronics such an interesting subject is the diversity of possible applications. Take this issue for instance; we have a very simple circuit with a rather unusual application - the Windicator and a fairly complex circuit for a sophisticated piece of test gear - the Ramp Generator.
The fascinating thing is that just about every hobbyist at any level of ability can find something to suit them and it's not always the simple items that interest only the beginners. The Windicator is quite simple to build but I guess there will be plenty of experienced hobbyists or professionals who will find it a worthwhile project - myself included.

There is one "simple" unit in this issue which is definitely not for the beginner - the H.V. Capacitor Reformer. This unit outputs a high d.c. voltage and needs to be treated with due respect. Items of this type, and that includes the EPE HiFi Valve Amplifier, can kill and should not even be considered as projects unless you are sure you know what you are doing. A similar message must go with any mains powered project, 230 V a.c. is dangerous so don't build a mains powered project, or experiment with circuits like those in our feature Bridge Rectification Enhanced until you have the necessary experience and always have a healthy respect for electricity.

## PLANNING

The chart we use to plan what will go into each issue of EPE has a dozen different project headings ranging from "Photographic" through "Test Gear", "Audio", "Car", etc., to "Features" and "PCs." The section with the most article titles in is often "Miscellaneous" where various items like the Windicator or next month's Solar Seeker get listed. So, even with all those categories, many projects defy a straightforward listing - it just goes to show how diverse the range is.


## SUBSCRIPTIONS

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# WINDICATOR 

## ALAN WINSTANLEY

## LED to the bar for a good measure gets you simply blowing in the wind!

0NE of the more entertaining and interesting requests which came the author's way recently was an appeal for a wind speed indicator which had to be reasonably accurate but above all, simple to build. Quite a tall order! A good deal of experimenting has resulted in this simple design - a project nicknamed the "Windicator" - which the designer hopes will fit the bill precisely. Having shown the design to many ordinary non-electronics folk, they have been quite fascinated to see this simple project in action, so it's sure to have a wide appeal and will be especially useful for its educational and interest value.
You will probably have seen a wind speed measuring device - an anemometer in use at one time or anfother, perhaps at an airport or a weather station. Those rotating cups whizzing round at a fair lick are propelled by gusts of wind from any direction and the rotating shaft drives a transducer to generate an electronic signal. This data has to be decoded ultimately to produce an intelligible measure of wind speed, which requires precision measuring equipment.
This Windicator design is not at all intended to be a precision device although the unit has been calibrated to give a surprisingly effective display of prevailing wind speeds. It is guaranteed to provide many hours of interest and entertainment for all ages, being simple and fun to build and you don't need a personal computer to use it!
Of great importance to mariners, the Beaufort Scale is a measure of wind speed. Named after the Royal Navy Admiral Francis Beaufort (1774-1857), it was accepted in the late 1800s and was further adjusted in the 1920s to its present scale. A scale of zero is classed as Calm whilst at the other extreme, a reading of 12 signifies Hurricane Force, something very rarely witnessed in the United Kingdom, mercifully!
The basic relationship between wind velocities and the effects that varying levels of wind have on the environment is shown later in Table 1.

## WINDICATOR CONSIDERATIONS

Having given the project some thought, it soon became apparent that the major problem likely to be encountered by constructors would be mechanical rather than electronic in nature. The idea of using rotating cups to detect velocity from any direction seemed the best approach, but
implied that a rotating shaft assembly would need to be used somewhere along the line, perhaps being guided in bearings to ensure smooth running.
It is certainly possible to purchase all the required materials - ball-bearing races and round bar in plastic - from several specialist engineering or modelmaker's sources but having priced up such a design, it was not in the least cost-effective and parts would not be readily available to most readers. Also the success of the finished unit would ultimately rely on one's ability to construct the rotating cup assembly to quite a high degree of workmanship and accuracy.

## SIMPLYCYCLING

A more economical and simple design was therefore called for. The final design is straightforward and does not require any complicated bearings or shafts, so that almost anybody can construct it. At the heart of the design is a good quality d.c. electric motor, used as a form of a wind-powered dynamo. As every schoolboy knows, when the shaft of an electric motor is rotated, this induces a voltage in the motor windings which can be used to power a load - just like a bicycle dynamo
The use of the specified motor will give very effective results, but most importantly of all, it means that no bearings or drive shafts are necessary since the motor takes care of all these aspects, which vastly simplifies the construction

An anemometer assembly can be made from four ordinary plastic measuring scoops, and these are used to spin the motor shaft directly. It is simple but highly effective. (Visions of ping-pong balls, cut in half, also sprang to mind but were quickly eliminated.)

## WINDY CIRCUIT

The circuit diagram for the Windicator is shown in Fig. 1. Component M1 is a quality 6 V d.c. electric motor. This is used as a wind-powered dynamo, which has a rotating cup assembly fitted directly to its drive shaft.
Tests during the early days of development showed that the output is relatively linear - although not perfectly so it is considered more than adequate in this application to produce an acceptable display. If the specified motor is used readers will be able to build this design and use the calibrations copied from the prototype, so absolutely no calibration is needed (later, you are shown how to test the circuit by comparing it against a car speedometer)

## GODD MOTOR

Earlier prototypes used a simple cheap d.c. model motor but the output characteristic was very poor - generating only about 100 mV at high wind speeds - and this necessitated further buffering and amplification. The arrival of a much better quality d.c. motor dispensed with the need for any initial amplification, since the d.c. output of the specified motor is so good that this can be used directly with very little



Fig. 1. Complete circuit diagram for the Windicator. See text regarding inset figure on the left
further processing. The final circuit was a simplified version of earlier attempts, and works extremely effectively.
The output voltage generated by the motor is proportional to the prevailing wind speed. A motor voltage of up to 6 V d.c. or more (as measured) is produced with varying levels of wind velocity. The back e.m.f. generated by the motor is shunted by rectifier D1 and noise spikes are filtered by capacitor Cl .

Diode D2 is a germanium diode which has a 0.2 V forward voltage drop (unlike a silicon type which is typically 0.6 V ). Again, the motor output voltage proved so high in use that the voltage drop across the diode had no particularly significant effect on the results. Resistor R1 and capacitor C 2 form a pump in which C 2 is progressively charged up by the voltage generated by the motor. Diode D2 prevents the capacitor (a tantalum type) from discharging anywhere except into resistors R2/R3.
The only drawback with the use of diode D 2 is that motor voltages lower than 0.2 V cannot cause C 2 to charge, since the diode's forward voltage has to be over-

come. In practical terms, this means that the minimum wind speed which the Windicator displays is approximately 10 miles per hour. It was thought there was little point in trying to make the circuit more sensitive in an effort to detect speeds under 10 m.p.h., though.
The result is that the potential across C2 rises when the motor rotates and decays again when the motor halts. The time constant here is quite low - well under half a second, so the circuit is quite responsive to changes in wind speed. Resistors R2/R3 actually form a voltage divider, with values selected for the motor, which steps down the generated voltage. Trials showed that the output voltage across R3 equated to an average of 200 mV at a speed of $10 \mathrm{~m} . \mathrm{p} . \mathrm{h}$., all the way up to roughly 1.5 V at $70 \mathrm{~m} . \mathrm{p} . \mathrm{h}$.

## BARGRAPH DRIVER

This varying d.c. voltage is directly coupled to IC1, an LM 3914 N bargraph driver. The Windicator display is in the form of a multi-coloured array of ten light-emitting diodes, representing average wind speeds from 10 to $75 \mathrm{~m} . \mathrm{p} . \mathrm{h}$. This popular i.c. will power ten l.e.d.s directly, using just one external resistor (R4) to set the current levels flowing through them. The i.c. has an input buffer amplifier which is quite robust - protected for inputs $\pm 35 \mathrm{~V}$ d.c - and so absolutely no further signal processing is needed in this very simple application.
The LM3914N offers an internal precision 1.25 V reference at its pin 7 , and this is connected across a series of ten comparators within the device. Pin 6 represents the "top end" of the comparator chain which is connected to the 1.25 V reference. the "bottom" of the chain is pin 4 which is connected to 0 V .
For each 125 mV rise ( $1.25 \mathrm{~V} / 10$ ) in input voltage at pin 5 , an internal comparator will switch on, causing the relevant output pin to go low. The outputs (pins 1 plus 10 to 18 , noting their order) are normally high and only when they go low do they sink current and enable the respective l.e.d.

## SELECTABLE DISPLAY

Another useful feature of which the Windicator takes advantage is the ability to produce either a bargraph or "moving dot" display. If ICl pin 9 is left open circuit, only one led will be on at a time. By linking it to the positive rail using TB2 (see later), a bargraph display will be produced. Capacitor $\mathbf{C} 2$ helps ensure that the display does not flicker too much.
To improve the display, the l.e.d.s on the prototype were colour-coded. The first three (D3 to D5) are green to indicate "normal" (up to 20 m.p.h.); D6 to D9 are yellow (up to roughly 55 m.p.h.) whilst the last three indicators, D10 to D12, are red (up to $75 \mathrm{~m} . \mathrm{p} . \mathrm{h} . / \mathrm{let}$ 's get out of here!).
At this point readers should be made aware that the calibrations shown on the prototype (see photographs) are the result of comparing various prototypes against a car speedometer when driving around deserted country lanes in calm weather. This was thought the most realistic and practicable way of simulating various speeds, since wind tunnels are a bit hard to come by. The calibrations are the averages taken from several test runs and are as



Fig. 2. Component layout and full size copper foil track master for the Windicator printed circuit board.
accurate as possible. The prototype was fitted to a car and the 1.e.d. display was calibrated against the Speedo across the entire range of velocities shown. Naturally, a co-pilot was employed to jot down the readings, and speed limits were strictly adhered to!
The results which readers will obtain depend on their choice of motor. If you follow the details of the prototype as closely as possible and use the specified components then there is no need to have to calibrate your own unit as the scale shown on the prototype unit should prove perfectly adequate.
Finally, rather than build a separate mains power supply, the prototype Windicator uses an ordinary cheap 6 V d.c. mains adaptor to run from the mains continuously. This is connected via the jack socket SK1. Capacitor C4 helps decouple the power supply, although the LM3914N is none too fussy about the quality of the d.c. rail. Correct polarity of the power supply is absolutely essential of course, or the bargraph chip will be permanently damaged. The supply voltage level is not critical and between 6 V and 12 V should be fine.
The unit could run directly from a 6 V d.c. battery pack but then a continuous display will not be feasible (the Windicator may draw over 100 mA maximum in bargraph mode) unless you use a set of NiCad rechargeable cells. As shown in the inset diagram of Fig. 1, a series pushswitch is the best option if using a battery, as is selecting "moving dot" mode (TB2 open circuit) to economise on battery life.

## CONSTRUCTION

Assembly is very straightforward. The circuit is built onto a small printed circuit board (p.c.b.) size $61 \mathrm{~mm} \times 51 \mathrm{~mm}$ avail able from the EPE PCB Service, Code No. 947. The Windicator was housed in an economical sloping-front case size $161 \mathrm{~mm} \times 96 \mathrm{~mm} \times 39 / 57 \mathrm{~mm}$, which had an l.e.d.s are connected.
aluminium front panel. There is plenty of room in the specified case to house the p.c.b., remembering that a power supply may be brought in from an external mains adaptor. Alternatively, the case will also house a battery (four $\times$ AA size) should you wish to run it from batteries.
Start by using the empty p.c.b. as a drilling template for the two 3 mm diameter mounting holes, which need drilling through the base of the enclosure. Continue construction by assembling the p.c.b. in accordance with Fig. 3.
First of all, solder in an 18-pin dual-inline (d.i.1.) i.c. socket to hold IC1, and continue with the rest of the discrete components, observing polarities for the tantalum and electrolytic capacitors.
The diodes require special mention: the polarisation of silicon rectifier D1 should be readily identifiable but the germanium glass diode D2 may be tricky to sort out. Look very closely at the glass body and there should be a band marked around the cathode end - this was extremely faint on the prototype. The germanium diode is also quite delicate: do not bend the leads too closely to the glass body and take care to solder it quickly into position without overheating it.
A two-way screw terminal block (TB1) was used to provide the connections for the twin-core motor wire (see motor details later). The bar/dot mode selector link (TB2) was a s.i.l. (single-in-line) header with push-on link. You might choose to hard-wire this with a link (bargraph display mode), or just use two short lengths of tinned copper wire - twist them together to produce a bargraph.

Lastly, fit ICl into place. The chip is a bipolar type and does not need any particular anti-static handling precautions. As always, one end of the i.c. is identified by a notch or a dimple next to pin 1 (or both). It must go in the right way round or it will be damaged on power-up.

The flying leads for the ten 1.e.d. cathodes (k) were formed with a short length of 10 -way ribbon cable which was soldered directly to the board, and all other flying leads are made with standard hook-up wire. For added interest, the l.e.d. display was multi-coloured, as


Interior view of the Windicator assembled electronic components. Note how the


Fig. 3. Interwiring details for the Windicator.

## COMPONEVTS

| Resistors |  | See |
| :--- | :--- | :--- |
| R1 | 22 k | SUOP |
| R2 | 150 k | RALK |
| R3 | 56 k | 1 k |
| R4 | TAL |  |
| All $0.25 \mathrm{~W} 5 \%$ carbon film | Page |  |

## Capacitor

| C1, C3 | 100nF polyester ( 2 off) |
| :--- | :--- |
| C 2 | $2 \mu 2$ tantalum bead 16 V |
| C 4 | $100 \mu \mathrm{~min}$. axial elect. 16 V |

## Semiconductors

## D1 1 N4148 silicon diode OA91 germanium diode D3 to D5 green l.e.d. (3 off) D6 to D9 yellow l.e.d. (4 off) D10 to <br> D12 red l.e.d. (3 off) <br> iC1 LM3914N bargraph driver

## Miscellaneous

M1 d.c. electric motor Matsushita MHN-5RG4E (see Shoptalk)
TB1 2-way p.c.b. terminal block
TB2 2-pin s.i.l. header with jumper (see text)
TB3 2-way electrical terminal block
SK1 $\quad 3.5 \mathrm{~mm}$ jack socket
Printed circuit board, available from the EPE PCB Service, code 947; sloping plastic housing, size 161 mm $\times 96 \mathrm{~mm} \times 39 \mathrm{~mm} / 57 \mathrm{~mm}$; M3 p.c.b. mounting hardware; 18 -pin d.i.l. socket; motor mounting hardware and plastic enclosure 35 mm dia. $\times 50 \mathrm{~mm}$; plastic scoops, 15 ml capacity approx. (4 off); plastic V-pulley 30 mm dia. with grub screw hub; 6 V to 12 V d.c. 300 mA unregulated mains adaptor; materials for mast; twin core zip wire, to suit; hook up wire, glue, grommet, solder etc
mentioned earlier. The author chose 2.5 mm diameter "flat top" types, for which a series of 2.5 mm diameter holes were drilled in a line through the front panel.
A keen, sharp twist drill is needed for this method though, and it's essential to centre-punch the drilling spot beforehand, to prevent the drill from wandering about.

After drilling the holes, they can be de-burred with a larger diameter twist drill or a special tool, before the display is marked with the calibrations shown in the photographs. Ordinary rub down lettering is used to number the display, followed by a coat or two of protective spray-on lacquer

On the prototype, the l.e.d.s were pushed through from behind, as a form of "invisible fixing". Small blobs of hot melt glue were also applied as an extra measure to secure them but the overall display is quite strong and appealing to look at. Needing no mounting clips, it's also cheap.

## INTERWIRING

The interwiring is very straightforward and is depicted in Fig. 3. The l.e.d. anodes (a) can all be hard-wired together simply by bending their lead-outs carefully to make contact with those of their neighbours, then they can be soldered. The display is "in effect a common anode arrangement and one separate wire connects the anode "rail" to the p.c.b.
It shouldn't be necessary to use any insulation as the hard-wired assembly should be relatively rigid and safe from short-circuits. The main point is of course to correctly orientate the l.e.d.s!
If in doubt, look through the translucent package: the "Cup" (reflector) is usually the Cathode. (One yellow 1.e.d. resolutely refused to work in an early prototype - the 1.e.d. had been moulded with the identification "flat" next to the anode!) Then solder the 10 -way ribbon cable from the p.c.b. to the appropriate l.e.d. cathodes (k).
The case is finished off with a 0.25 inch diameter hole for the jack socket SK1 (if used), and a suitable hole to accept the connecting lead from the motor, for which a grommet should also be used.


Fig. 4. Mechanical assembly of the wind cups and motor.

At this stage, the display can be quickly tested without using the motor. Link TB2 to select "bar" mode. Then ensuring that the power supply is of the correct polarity, apply a d.c. voltage ( 6 V to 12 V ) to the power supply inlet. The light-emitting diodes will all illuminate when the LM3914N input pin 5, or even D2 cathode, is temporarily hooked up to the positive supply rail using a jumper lead. If some glow but not others, you've probably reversed the l.e.d. connections somewhere With the main unit complete, attention turns to the anemometer section.

## MOTOR-HEAD

The high output d.c. electric motor tested and approved by the author (see Shoptalk page) measures 30 mm diameter $\times 25 \mathrm{~mm}$ deep, with a 1.5 mm diameter, 5 mm long drive shaft. It is smooth running and generates a usefully high voltage. Fig. 4 summarises the assembly details for the prototype motor and wind-cup unit. A round plastic container with screw-on lid was used as a housing; you could perhaps improvise with a large Aspirin container or something slightly larger than a 35 mm film container, to protect the motor from the elements.
Carefully drill the end of the container with three holes as shown - one 6 mm diameter for the shaft along with two 3 mm clearance fixing holes. The motor body can be secured end-on using two M3 $\times 6 \mathrm{~mm}$ screws. Do not overtighten them or the plastic housing will eventually crack. A little light lubricant (the author used a Teflon-based cycle lube) applied near the shaft is likely to repel water and improve the smooth running.
The anemometer cups were formed from four 15 ml plastic measuring scoops, with the "handles" slightly shortened. These were affixed to a plastic pulley ( 30 mm diameter) using plenty of hot-melt glue (which is virtually the only way to glue certain plastics such as nylon or polythene


The principle ingredients for the aneometer.
together). Ensure that the cups all face the right way round - see photos - and try to ensure they are all level in relation to the pulley, to avoid "wobble"
The overall diameter of the cup as sembly was about 120 mm diameter on the prototype. Also, the pulley must have a grub-screw type fixing so that it can be screwed onto the motor shaft. Although the length of the motor shaft is minimal, it proved adequate enough to produce a very secure assembly. Obviously you can test to see how the motor assembly runs by applying a d.c. voltage.
A two-way terminal block (TB3) terminates the motor leads, this also fits within the round plastic housing. At this point, it's necessary to determine the polarity of the motor output, given that this depends on which way round the motor has been wired and which direction the cups will move when they spin in the

Table 1. Measuring Wind Force

| Beaufort <br> Number | Wind <br> Description | Environmental <br> Indicators | Wind Speed <br> (m.p.h.) |
| :---: | :---: | :--- | :---: |
| 0 | Caim | Smoke rises vertically | $<1$ |
| 1 | Light air | Rising smoke deflected | $1-3$ |
| 2 | Light Breeze | Leaves rustle; wind felt on face | $4-7$ |
| 3 | Gentle Breeze | Leaves and twigs move | $8-12$ |
| 4 | Moderate Breeze | Litter, dust, small twigs move | $13-18$ |
| 5 | Fresh Breeze | Small leafy trees sway | $19-24$ |
| 6 | Strong Breeze | Overhead wires whistle; large branches <br> move | $25-31$ |
| 7 | Moderate Gale | Whole trees sway | $32-38$ |
| 8 | Fresh Gale | Twigs break off trees |  |
| 9 | Strong Gale | Chimney pots and roof tiles dislodged | $47-54$ |
| 10 | Whole Gale | Trees uprooted. Major structural <br> damage | $59-46$ |
| 11 | Storm | Serious structural and environmental <br> damage | $64-75$ |
| 12 | Hurricane | Catastrophic damage to the <br> environment | $75+$ |

wind. Save work: A quick practical test is simply to hook up a voltmeter and test the output when you blow on the (concave) scoops, then identify the polarity of the connecting wire.
You may wish to try the Windicator display by temporarily hooking up the motor to the p.c.b. (observe polarity). Blowing hard on the anemometer unit should cause probably four or five l.e.d.s to illuminate in bargraph mode; also try the dot mode. It will test your lung capacity if nothing else!

Lastly, ordinary cheap twin-core "zip" wire is all that's needed to hook up the motor once it has been sited in its rest ing place, and this wire could easily be 25 metres long or more. The connecting lead passes through a hole in the base of the housing, to the main Windicator unit.

The completed prototype motor assembly was fitted to a length of aluminium angle with a small L-shaped bracket screwed into the removable lid of the plastic housing, with insulation tape sealing the lid before the finished device was finally secured at the rear of the author's house. The unit shown in the photographs has been subjected to the most atrocious weather conditions (typical British weather, in fact!) over many months and is still operating perfectly.

## SITE SEEING

The final location of the motor head is quite important and may be the subject of trial and error. Fortunately, a convenient balcony was available at Chez Nous and the motor was fixed to the railings, much to the intrigue of the neighbours. Earlier efforts produced poor results, and this was attributed to the house actually sheltering the anemometer from prevailing winds in certain directions. An open aspect away from walls and buildings, is a must
It is probably a good idea to experiment with the finished project for a week or two, running it on a temporary basis before committing yourself to installing it permanently. The largest difficulty facing readers is the practicality of running a cable through into the house, or wherever the Windicator is to be used.
In the author's case, it was very easy to pass the twin-core wire through a wooden window frame, but others may not be so lucky (that's uPVC wind ows for you). Consider running the wire through door or
window frames, TV aerial inlet holes, air bricks, ventilator outlets, or up through the eaves. The twin-core cable is then screwed to TBl on the p.c.b. and the main unit can be closed up. Then, unless you have the powers of Thor, you have to wait for a windy day!
The finished prototype Windicator will generally. illuminate the $10 \mathrm{~m} . \mathrm{ph}$. and $15 \mathrm{~m} . \mathrm{p} . \mathrm{h}$. l.e.d.s when slight breezes are detected, and so far up to six 1.e.d.s (45 m.p.h. gusts) have glowed during rough weather, with the colour-coded display proving invaluable. The display also gives an idea of wind patterns, responding well to gusts before settling down again. So, the Windicator will give you an at-a-glance idea of how the wind's blowing - but its responsiveness is very much determined by the positioning of the motor unit and you might need to experiment with this to get the best out of the design.
If you use an alternative high-output motor, or want to calibrate your own constructed unit, then one practical way is to compare the Windicator against a car speedometer. A calm day and deserted roads are essential; a sun-roof and an assistant would be handy too! Power the unit from a fresh 6 V to 9 V battery pack (to avoid supply voltage droop

when all l.e.d.s. are on), or from a cigar lighter adapter. Starting at $10 \mathrm{~m} . \mathrm{p} . \mathrm{h}$., note the l.e.d. numbers ( 1 to 10 ) which illuminate as the car gradually increases speed towards a maximum of say $60-70$ m.p.h.; perhaps make half a dozen test runs or more, and then take the average of all readings and calibrate your l.e.d. display accordingly.
The Windicator should last many years, with perhaps the odd squirt of light

## ohm Sweet ohm Max Fidling <br> Eager to tackle this latest challenge, I'd

Cat Flapping

Rummaging around in the workshop the other day, I happened across a piece of white painted plywood propped up beside the bench, roughly two feet square and painted gloss white. It was no coincidence that there was a square hole of exactly the same dimensions in the kitchen door.
Although I'm an avid "Do-It-Yourself" fanatic, one thing I don't need, so I keep fooling myself, is exercise of any form. I'd much rather spend my spare hours beavering away in the workshop, constructing my latest brainchild or building a magazine project which might have caught my eye. Hence the eventual need to ensure that Piddles, my feline fun-filled assistant, was totally self sufficient so he could travel hither and thither unimpeded.

You see, I was forever having to open and close the kitchen door to allow Piddles back in after his daily round of mousing. By a perverse scheme of association behaviour the moggie had learned that if he sat by the door and whined loudly enough at a particularly nerve-shattering frequency, I would eventually tire of this racket and ouvre la porte for said cat, who would thien march through the door triumphantly, making a bee-line for his bow!
Such behaviour, he had learned, was remarkably effective if I happened to be in the middle of soldering up a board in the nearby workshop, well within earshot of his cringe-worthy din. It was no good, this shenanigans kept interrupting top priority domestic electronic research! Something would have to be done. But what?
Cycling to my local DIY store next day, I spotted a cat flap for sale. Perfect! This would stop the pesky puss from pestering me, and I could then solder on in peace!
soon marked out a square of suitable dimensions, using a felt-tip pen to outline where the cat flap would go on the back door. The thick black lines marked the route for me to tackle with the electric jigsaw.
As I started to slice through the woodwork, I had a brainstorm. Why not customise the cat flap so that Piddles could come and go as he pleased, but otherwise the flap would remain firmly shut? A plan formed, as I pondered the practicalities of another electronic labour-saving idea.

## Reed on . . .

I propped up the resultant square of wood against the bench in the workshop, and started to root around for inspiration. Recently I had taken an old speaker to pieces and thus I had acquired a nifty magnet
Stripped of the voice coil, it seemed to have pretty awesome pulling abilities. Now if I used this to operate a reed switch, and the reed switch drove a simple solenoid circuit, and the solenoid acted as a lock on the cat flap, we would be in business!
Thus was my reasoning as I returned to the scene of the crime and finished screwing the cat flap into place. The next week was spent in a futile effort to get Piddles accustomed to nosing his way through the cat flap - not one of my better moments.

In between times I developed a simple circuit which would respond munificently to the magnet. A surplus solenoid had been discovered on a shelf and I pressed it into service. Waving the rather large and powerful magnet near it, like Merlin casting a spell, the solenoid clicked over like a good'un, for a predetermined period derived from a 555 timer, before springing back into place.
lubricant helping to maintain performance. As the author has found, the most enjoyable aspect is probably when everyone asks, "What's that, then?" as they see the Windicator in full swing!


Just for good measure 1 added an l.e.d. and this blinked brightly whenever the solenoid was timing. If only it could speak, I mused, it would probably say "Quick, Moggie, Move It Or Else!" or words to that effect. Sadly, voice synthesis was beyond my abilities.

The cat flap then acquired some electronics which I don't think the manufacturers had quite anticipated when they designed it. D-Day came when at last I'd perfected the circuit and it was time for a trial run.
Piddles had just finished his breakfast and was feeling pretty content with life, i.e. he wouldn't know what had hit him until it was too late, I calculated. I'd fitted the magnet to a spare collar which I swiftly whisked around him, and then opened the kitchen door and encouraged him out with a gentle nudge or two.
Looking a bit like one of those Army-trained Dolphins carrying a homing beacon, I expected the magnetic moggie to trigger the timer and spring through the cat flap Mark Two any second now, accompanied by a flashing lie.d. and throbbing solenoid! Nothing happened, though, except that I heard a metallic "CLANG!" from outdoors.
Hmmm, not what I expected... Peering out, there was the moggie all right, the magnet on his collar pinning him firmly to the steel dustbin!

# Innovations $=$ Everyday News from the world of electronics 

## LASER CUTS THROUGH SURGERY <br> New laser cuts cleaner, improves healing and encourages new bone growth - by Hazel Cavendish

THE merging of physics with electronics has resulted in an exciting advance in laser technology at Manchester University, where the development of a remarkable new laser holds the promise of enhanced surgical achievements.
A team headed by Terry King, professor of physics at the University, has developed a laser called the Erbium-YAG which can cut through bone with an exactitude of positional accuracy as yet unachieved by conventional surgical saws. Research has proved that the new laser gives a cleaner cut and causes less secondary damage than other lasers with which it was compared.
The crystal heart of the ErbiumYAG laser is made from the chemical element erbium mixed with yttrium, aluminium and gallium and grown as a high purity garnet of very clear optical quality. This acts as the laser medium by absorbing light and emitting laser radiation.
Originally, researchers believed that healing was slowed down by laser surgery, but experiments in Manchester have shown that the new laser can actually promote faster healing.
Of great value to the surgeon is the potential for more precision in delicate brain surgery, and the repair of facial injuries caused by motor accidents. In surgery, particularly to the facial bones, the accurate positioning of bones is often achieved by fixing mini-bone plates. Laser techniques enable the surgeon to drill accurate


The Erbium- YAG laser which could increase the sophistica. tion of keyhole surgery.
holes which enhance the stability of plates and screws.

## FEARS DISPROVED

Surgeons had feared that in brain surgery, laser-cutting into the skull might damage the brain, but the new laser appears to disprove these fears. Professor Tony Freemont at the University explained that, since the new laser beam stops when it hits water, and as the brain is surrounded by water, damage to tissue is prevented.
"The greatest energy wavelength of the Erbium-YAG is concentrated in a very narrow band of 2.94 micrometres, which happens to be the peak energy absorption point for water", he explained.
In an experiment on anaesthetized rats, in which the laser was compared with a conventional water-cooled electric drill system, the laser was operated in free-running, fixed $Q$ mode and produced macro-pulses of 250 microseconds duration. Each macro-pulse consisted of a series of micro-pulses with a duration of a few microseconds.

## ARTICULATION

Operations will also be greatly aided by the mobility and reduced size of the laser. Its articulated arm is connected to a handpiece the size of a pen. Professor Freemont explained that the articulated arm was developed to enable a surgeon to direct the laser in areas of the body where it was particularly difficult to reach.
"There are two ways of delivering the laser: one by the articulated arm, which has a series of mirrors which bounce the beam round corners, and the other by use of a fibre-optic system. Unfortunately, the Erbium-YAG can only be directed down certain types of fibreoptic cable, such as Zirconium-


The business end of the articulated arm for the Erbium- YAG laser.
fluoride, which tends to break if it is repeatedly bent.
"The mirror system is better, except that energy is lost because there is a certain amount of light absorption by the mirror." Even so, the beam can be concentrated in a very localised fashion with less than 100 micrometres of damage. This is an important consideration when work ing in a constricted environment, such as in neuro-surgery.

## PAIN RELIEF

- Professor Freemont also commented: "Elderly people can experience pain due to the over-growth of bone causing compression of nerve roots. These outgrowths could be removed by the new laser as it can cut into bone to a clearly defined depth with such precision that it would neither damage the nerve nor cause more than minimal tissue damage."

In experiments with rats, the team also made the surprising discovery that they were able to stimulate the growth of new bone by using the laser. "That really is a discovery for Tomorrow's World", said Professor Freemont. "It has given us the signal that we may be able to stimulate bone marrow and turn it into new bone.
The new technology was unveiled at the Institute of Physics Annual Congress held at Telford this Spring.

# YOUNG ELECTRONIC DESIGNER AWARDS 

WENTY-one finalists, aged from 14 to 25 , gathered at the home of
scientific achievement at the Science Museum in London to display
their electronics based projects and to hear if they had been successful in their efforts to carry off the prize of 1995 Young Electronic Designer Award.
Co-sponsored this year by Texas Instruments and Mercury Communications, this annual competition has been running since 1985 and is open to all students, between the ages of 12 and 25, in secondary schools, colleges and universities. The competition aims to encourage and challenge young designers to invent and produce a novel electronic device that meets everyday needs.

Under the patronage of His Royal Highness The Duke of York, the competition is governed by The YEDA Trust, a registered charity. The Duke of York makes his own personal award to the contestant who he considers as "having the most innovative idea in the competition."

This year, the "Duke of York's Award for Creative Technology" was presented to Richard Earthrowl (16), of Ravens Wood School, Bromley for his "Sava-Siren" distress beacon for hikers, bikers, skiers and pot-holers. Richard received a crystal bowl trophy (held for one year) and, for his school, a TI Travel Mate notebook computer.
It was the view of the judges that Martin Johnstone (17), from Kingussie High School, Highland, should receive the Texas Instrument Prize of $£ 2,500$ for, in their opinion, the most commercially viable product. Martin's entry was the "MJ Switch" a device for indicating the turning and braking of a vehicle while carrying bicycles on the rear.

The judges could not decide on an outright winner for the Mercury Planet Award of $£ 2.500$, for the most socially or environmentally helpful project, so they made a "joint first" award to Sarah Preston (16) from Blyth Ridley High School for her "Poor Circulation Monitor", and to Steven Maher (17) of Cheltenham College for his "Asepsimeter", a digital expiratory-flow meter.

The use of ultrasonics won Lars Blackmore (14), Sevenoaks School, the first prize of $£ 500$ in the Junior category for his low-cost reversing and obstacle indicator for cars.

All finalists were presented with certificates and TI calculators, and their schools or colleges each received Mercury compatible telephones.

## AWARD WINNERS

The Duke of York's Award for Creative Technology:
Richard Earthrowl (16) - Ravens Wood School, Bromley, Kent "Sava-Siren" - a distress beacon for hikers, bikers, skiers and pot holers
The Texas instruments Prize $(£ 2,500)$ for the most commercially viable project: Martin Johnstone (17) - Kingussie High School, Highland
The "MJ Switch
The Mercury 'Planet' Ward $(\mathbf{~} 2,500)$ for the most soclally or environmentally aware project:

Sarah Preston (16) - Blyth Ridley High School, Blyth, Northumberland - "PCM" - Poor Circulation Monitor

Steven Maher (17) - Cheltenham College, Cheltenham
"Asepsimeter" - an improved electronic digital peak expiratory flow-meter

## Senior Category (18-25 years inclusive)

1st ( $£ 1,000$ ) Martin Foley (22) - Brunel University, Egham, Surrey "Freeboard" - a multi-access computer keyboard emulator for disabled PC users
2nd (£500) Christopher Kirkham (24) - Brunel University, Egham, Surrey
"Nautilus" - a sailboat race starting aid for race officials
3rd (£250) Alison Chappell (24) - Brunel University, Egham, Surrey A card operated street condom vending machine
Intermediate Category (15-17 years inclusive)
1st ( $£ 750$ ) Steven Maher (17) - Cheltenham College, Cheltenham "Asepsimeter" - an improved electronic digital peak expiratory flow-meter
2nd ( $£ 400) \quad$ David Wilson (16) - Merchiston Castle School, Edinburgh "RAPP" - Remotely Activated Power Points
Joint 3rd (£200) Mark Edgerton (16)-Colston's Collegiate School, Bristol, Avon
"Peak-Charge" - a new design NiCad battery charger Timothy Munn (16) - Sandown High School, Sandown, Isle of Wight
A foghorn operation system for small boats
Junior Category (under 15 years)
1st ( $\mathbf{2 5 0 0}$ ) Lars Blackmore (14) - Sevenoaks School, Sevenoaks, Kent A low-cost reversing indicator for cars using ultrasound Ross Adams (14) - Coleraine Boys' School, Coleraine, Northern Ireland
A device which deters able-bodied drivers parking in spaces allocated for disabled drivers
3rd (£150) Colm Miskelly (14) - St Mac Nissis College, Carnlough. Northern Ireland
"Velcrouse" - an electronic board game based on house building


The 1995 Young Electronic Designer Award category winners (from left to right): Martin Foley, Sarah Preston, Steven Maher, Richard Earthrowl, Lars Blackmore and Martin Johnstone.


Ravens Wood School student Richard Earthrowl who won The Duke of York's Award for Creative Technology is seen here receiving his prize from His Royal Highness.


Martin Foley of Brunel University winner of the Senior Category with his keyboard emulator for the seriously disabled.

# New Technology Upiate with photolithography techniques of producing and manufacturing i.c.s for the future. 

Photolithography is one of the key processes in i.c. manufacture. It enables the complicated shapes and patterns generated by the designers to be transferred to the silicon or other semiconductor surface. In turn this allows the individual components to be fabricated on the i.c. by the other processes used in the manufacturing cycle
It is possible to produce feature sizes of less than one micron, and very small levels of defects in the photographic processes.

## Basic Process

The basic idea of the process is quite simple. First the patterns which need to be transferred to the i.c. surface are generated by the designers. Today this will obviously be accomplished by computers, but in the early days of i.c.s, the shapes were produced manually.
Once the required shapes have been produced they are reduced in size many times and also repeated so that many i.c.s can be produced from the same wafer. This stage requires the use of very high grade photographic equipment, costing very large sums of money. The resultant "mask" is then ready for use in manufacture.
During manufacture of the i.c. a silicon oxide layer (or other semiconductor oxide layer) is first built up onto the substrate. Once this has been completed the substrate is covered with a very thin layer of a light sensitive material called photoresist.
To ensure a thin but even layer of the resist, the wafer is spun at a high speed and some resist is dropped onto the centre of the wafer. The centrifugal force pushes the resist out from the centre, covering the whole of the wafer in a uniform even layer.

## Good Exposure

When the resist has hardened the next stage is for it to be exposed. A glass photographic mask containing the required pattern is brought into contact with the wafer. Light is then made to shine onto the wafer through the mask so that areas of the photoresist are exposed to the light as shown in Fig. 1.
Having exposed the photoresist, it is developed to remove the relevant areas of resist. With some resists the exposed areas are removed during developing whereas with others the non-exposed areas are removed
The next stage in the process can be to etch away the areas of exposed silicon oxide to expose the basic silicon underneath. A variety of etches can be used, but it must not etch the photoresist of the silicon to any degree. When this has been completed, areas


Fig. 1. Stages used in photolithograptiy: (a) silicon oxide layer grown on to wafer, (b) photoresist added, (c) mask positioned, (d) photoresist exposed, (e) photoresist developed, (f) oxide etched and photoresist removed.
of silicon are then exposed for diffusion of $n$-type or $p$-type impurities.

This series of process outlines has to be repeated a number of times to build up the required areas to make an i.c.. Often as many as twenty stages or more are required to complete the circuit.

## Limitations

However, there are a number of limitations to the process. One of the major ones is the size of the features which can be produced. Today sizes of just less than a micron can be produced. To achieve this special collimators are required for the light used in the photolithographic stages. The quality of the mask also needs to be exceedingly high.
Unfortunately, the ultimate definition is limited by the wavelength of the light which is used. It is for this reason that ultraviolet light is normally used because it has a shorter wavelength than visible light.
With the ever increasing demand for more complicated and smaller i.c.s, sizes need to become even smaller. This puts the pressure on researchers to devise methods of improving the processes.

## Deep UV Light

One of the methods of improving the definition attainable is to shorten the wavelength of the light used even further and use what is called "deep ultra-violet light". Using this approach it is expected that feature sizes of $0 \cdot 1$ micron can be achieved, although much work still remains to be done.
To be able to work with deep ultraviolet light a number of modifications need to be made to existing processes First, it is necessary to develop a new range of photoresist materials. Currently there are a number of materials which respond to ultra-violet light beyond that normally used. However those for the projected wavelength are still being developed.

New optical arrangements are also needed. The collimators used for ordinary ultra-violet light use a series of lenses. With deep ultra-violet light lenses do not work.
As a result specially fabricated mirrors are needed. These have to be finished to an exceedingly high degree of accuracy. It is necessary for the surfaces to be accurate to within $5 \AA$ Ångstoms ( $5 \AA$ ); five hundred-millionths of a centimetre.

Fortunately some work has already been performed into making mirrors of this nature. This came out of the "Star Wars" or Strategic Defense Initiative inaugurated by President Reagan in the 1980s.

As the i.c.s manufactured with this process are likely to be much more complicated, there are going to be more manufacturing stages which also multiplies the wafer alignment problems. To help overcome this alignment problem a special frictionless mount is being developed. This involves the use of magnetic levitation techniques which will give full freedom of movement whilst still retaining complete control of the position.

## Into The Next Century

As a result timescales well into the next century have been set for the final completion of the work, and the availability of a usable system for mass manufacture of small feature i.c.s.
In fact, the first prototype system is expected to be working by 1998. This will only be experimental, and used for making limited numbers of circuits for evaluation.
After this the correct semiconductor technology to use has to be selected and experiments performed. This work is likely to take a number of years and it is not expected that volume production will commence until about 2006

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## Constructional Project

## AUTOMATIC CURTAIN

 WINDER
## MAX HORSEY

> Automatically opens and closes curtains at dawn and dusk at preset light levels. Can be added to almost any existing "corded" system. A single-button Infra-Red Remote Control is also included (next month] which will enable disabled people to control the system.

> The Remote Control produces a coded infra-red signal which makes it ideal for additional applications, such as alarm systems, door openers, light controllers etc.

MANY readers will have seen the advertisements on TV featuring automatic curtain winders. They are particularly valuable during holiday periods, since open curtains at night and closed curtains during the day are sure indicators that the occupants are away from home.
The curtains winding system to be described here can be added to any existing corded system, providing it runs freely; there is no need to purchase expensive curtain tracks, as required for some commercially available systems.

## AUTOMAT/C CONTAOL

The trigger for opening/closing of the curtains is the level of "daylight". A timing system was considered, but it is surprising how quickly the point at which the curtains should be closed or opened changes during Autumn and Spring. A daylight triggered system also allows for overcast or sunny weather.
Both the opening point and the closing point can be independently set, and a Schmitt trigger circuit ensures that the

The Automatic Curtain Winder System showing the Control Unit, Motor housing and the Infra-Red Remote Control hand-set (next month).

curtains will not react to slight changes of daylight caused by passing clouds. Full manual override is included, and the curtains stop automatically at the ends of their travel without the need for awkward sensing switches.

## REMOTE <br> CONTRDL

Systems which are available in the shops make much of being able to operate the curtains by remote control. An Infra-Red Remote Control Transmitter and Receiver system will be described in Part Two (next month), and this will allow the curtains to be opened/closed or stopped in any position by means of a single pushbutton switch.
To sum up, the system includes the following:

1. Uses an l.d.r. (light dependent resistor), fixed to the inside of a window to detect the level of light outside. At dusk and dawn the curtains will close/open. The motor will switch off at the end of the travel.
2. Although there is provision for stop switches to detect when the curtains are fully open or fully closed, the circuit also features an automatic "current sense" stop system so that stop switches are unnecessary.
3. Manual override is provided which will: (a) Stop the curtains in any position (b) Close or open from any position.
4. The circuit is powered by means of a 12 V 1 A regulated mains adaptor.
5. Provision for adding a Remote Control Unit, (featured next month).
6. The circuit can be easily interfaced to any controlling system, such as computer control.

## LIGHT SENSOR AND SENSOR PROCESSING MODULE

The system block diagram is shown in Fig. 1. An l.d.r. is used for sensing the daylight; it is inexpensive and very sensitive, and its sluggish performance (compared with a photo diode) is of no consequence when dealing with changing daylight.

This is followed by a 741 op.amp comparator, complete with Schmitt trigger action to avoid hesitation at the changeover points between day and night. In fact, two 741 comparators are used, one for sensing the falling degree of light in the evening, the other for the morning. This enables completely independent control of the open/close points.

The circuit diagram showing the input sensor and amplifier section appears in Fig. 2. Employing two l.d.r.s (one for each comparator) would be inconvenient and cumbersome and so both comparators are connected to the same l.d.r. circuit. Of course, one comparator is inverting, and the other non-inverting.


Fig. 2. Circuit diagram for the light level input sensior and amplifier section. The use of two comparators (741s) enables independent control of the curtain open/close points.


Fig. 1. System block diagram for the Automatic Curtain Winder.

Resistor R1 prevents damage caused by excessive current if the l.d.r. is exposed to bright sunlight (making its resistance very low), and if preset VR1 is set to a low resistance. The variable resistor VRI provides overall control of both open/close points.

The voltage at the junction between the I.d.r. R2 and VR1 rises as the level of daylight increases. This voltage is used to control the non-inverting input of ICl and the inverting input of IC2.

These i.c.s are connected as comparators In other words they compare the voltages at their inverting (pin 2) and non-inverting (pin 3) inputs. Note that in this instance the + and - signs indicate non-inverting and inverting respectively, not positive and negative.

## CURTAINS OPEN CIRCUIT

The preset potentiometer VR2 (wired as a variable resistor) together with resistor R4 forms a potential divider which sets the point at which ICl reacts to the changing level of light. The output (pin 6) from IC1 switches to positive when the amount of daylight increases sufficiently to make the voltage at pin 3 (IC1) rise above the voltage at pin 2 which is set by VR2. The change of

voltage at pin 6 triggers the logic circuit, as described later.
Feedback resistor R7 together with R3 cause the circuit to act as a Schmitt trigger. This makes the i.c. less sensitive to changes in light level, and less prone to trigger the curtains due to passing clouds etc. The ratio of R7 to R3 sets the degree of hysteresis - or in this context, and in plain English, the degree of insensitivity.

## CURTA/NS CLOSE

There is a similar circuit around IC2 except that the output switches to positive when the light level falls beyond a point set by preset VR3. The use of a completely separate circuit to detect the falling level of light enables considerable flexibility in setting the points at which the curtains are set to open and close.

## LOGIC PROCESSOR

Since pushbutton operation is required in addition to daylight control and possibly, remote control, the maximum flexibility is achieved by means of a bistable circuit. That is, a circuit which can be "set" by means of a single pulse, and "reset" by means of a pulse at a separate point.
A double R-S bistable circuit, comprised of four NOR gates, with pins 1 to 6 forming one bistable, and pins 8 to 13 the other is shown in Fig. 3. When the "Open" switch S 2 is pressed, pin 1 is forced to logic 1 (positive), and this causes the output pin 4 to switch and latch at logic 1.

Pressing the "Stop" switch S1 causes pin 6 to switch to logic 1, and this resets the bistable, with output pin 4 returning to 0 V .
A similar arrangement surrounds the second bistable, with the "Close" switch S3 making pin 8 switch to logic 1, and causing the bistable to latch with output pin 11 positive, until the "Stop" switch Sl is pressed.

## DA YLIGHT CONTROL

Since the processor latches in the appropriate state until a reset pulse is received there is no need to hold down any controlling switch. In fact, a switch which remained on would prevent the bistable resetting. So the processor needs a positive pulse rather than a constant logic 1. Such pulses are easily obtained by briefly pressing a push-to-make switch.

However, the daylight sensor of the input module is likely to remain at logic 1 throughout the day, and likewise the darkness sensor will remain at logic I throughout the night. We need a circuit which will convert this steady state into a short pulse at the moment when the logic level changes from 0 to logic 1 .

A series capacitor achieves this; hence the output from the daylight rising sensing circuit ( ICl ) is connected to the bistable via capacitor C 2 . The daylight falling circuit (IC2) is connected to the other bistable in a similar manner via C3.
This method of connection provides considerable flexibility in the control of the Logic Processor. It is possible to use the manual control switches to override the daylight control circuit at any time, but at the appropriate time the daylight control circuit will automatically resume control of the curtains. A Remote Control Receiver (next month) can also be added without affecting the existing controls, and any other interface idea is possible, such as opening the bedroom curtains automatically at a signal from the alarm clock!

## MANUAL STOP

The "Manual Stop" button S1 is wired to both bistables, the diodes D5 and D4 preventing accidental resetting. It is possible to use curtain rail stop switches, although the current sensing stop system described later is a better alternative.
If curtain rail stop switches are used, they must be connected individually to each bistable as shown in the final circuit diagram, since one or other will be held closed when the curtains are fully open or fully closed. Clearly we could not allow both bistables to be locked into a "eset" state.
The two curtain rail stop switches could be connected, via a coupling capacitor, to provide a pulse; however, if the curtains were fully open when the "Open" button


Fig. 3. Dual RS-bistable Logic Processing circuit and Manual switching arrangement.
was pressed, they would try to open further, resulting in damage to the motor etc. The same danger would exist in the fully closed position.

## CURRENT SENSING <br> AUTO-STOP

Using the "current sensing" method of detecting when the curtains are at the end of their travel is mechanically much simpler than using curtain rail switches, and is strongly recommended. It also has the advantage that if the curtains meet an obstacle or become tangled the motor will automatically cut out before causing damage.

When a motor runs at its normal speed the current used is much smaller than if the motor is forced to slow down. If a resistor of about 10 ohms is connected in series with the motor (see Fig. 4), the voltage across it will depend upon the current flowing.

A 10 ohm resistor will have little effect on the speed of the motor (although this will depend upon the type of motor employed experiment if necessary), but the rise in voltage across the resistor caused by the


Fig. 4. Basic current sensing or motor stalling circuit diagram.
motor being forced to slow down is sufficient to trigger an op.amp comparator. The output from the op.amp can in turn be used to reset the bistables.
The basic circuit diagram for the "current sensing" arrangement is shown in Fig. 4. The potentiometer (a small preset on the p.c.b.) is used to set the voltage at which the output from the op.amp changes state. The rise in voltage at pin 3 (non-inverting input) caused by the motor stalling, results in the output from the op.amp switching to logic 1 .


The completed "Controller" showing the Open, Stop and Close manual switches.

Note the addition of a capacitor C needed to smooth out fluctuations in the voltage across the resistor as the motor spins.
In trials, this system worked so well that curtain rail switches were not used, although provision for both stopping methods has been made on the p.c.b. Note however that the value of the resistor may need to be modified according to the type of motor used and if the behaviour of the system is different under load (i.e. when driving the curtains) than when on the workbench.
The motor used in the prototype (details later) worked well with a series resistor of value 8.2 ohms . Also an f.e.t. input op.amp such as CA3140E offers better results than a 741.

## MOTOR CONTROL

The motor control circuit is shown in Fig. 5 (the main circuit diagram) and has two inputs, via resistors R21 and R22. When a positive signal is applied to R21 transistor TR4 is turned on, and causes TR5 to switch off and TR6 to switch on.
Assuming that TR3 is turned off, the voltage at " $B$ " will be positive, and hence TR7 will be on, and TR8 off. With power transistors TR6 and TR7 both on, current will flow from the positive rail, through TR7, to the motor, and to 0 V via TR6 (and R27).
A similar sequence of events will occur if a positive signal is applied to R22, except that TR5 and TR8 will switch on, resulting in the motor rotating in the opposite direction. When the inputs at resistors R21 and R22 are both at around $0 \mathrm{~V}, \mathrm{TR} 3$ and TR4 will both be turned off, and all four power transistors will switch off, hence stopping the motor.
If a positive signal were to be applied to R21 and R22 at the same time, all four power transistors would turn on and a short circuit would occur. The diodes D8 and D9 should ensure that both outputs (i.e. from pin 4 and pin 11 of IC4) can never be positive at the same time, making this situation impossible.
Indicator D16 is a bi-colour I.e.d. which glows red when the current flows in one direction, and green when the current is reversed. Two separate l.e.d.s could be employed if preferred. Capacitor C11 suppresses voltage spikes produced by the motor, and the four diodes D12 to D15 remove voltage spikes which may damage the transistors.
Current from the motor reversing circuit must pass through resistor R27 on its way to 0 V . If the motor stalls, the voltage across R27 will rise and this rise in voltage is fed through R25 to trigger the "current sense stop circuit" built around IC3.
When the voltage at the non-inverting input (pin 3) of IC3 rises above the voltage determined by the setting of preset VR4, the output pin 6 switches from $0 V$ to positive. This causes an effect similar to pressing S1, the Stop switch. Diode D3 prevents current flowing back to pin 6 , if $S 1$ is pressed whilst pin 6 is at 0 V .
Capacitor Cl delays the stopping action a little, to allow the motor to start up initially. Once the motor has stopped, pin 6 switches back to about 0 V .
Note that capacitor Cl determines the speed with which the circuit reacts to the stalling motor; the circuit must be sensitive enough to detect the fully wound curtains, but not be so sensitive that the motor cannot be started initially. Fine control is provided by preset VR4.


Fig. 5. Complete circuit diagram for the Automatic Curtain Winder.

In practice VR4 controls the ease with which the curtains are brought to rest. Since opening requires more force than closing, and the force required increases as the curtains open, VR4 actually controls how far the curtains are pulled open.

## FINAL CIRCUIT

How the modules described slot together to form the complete circuit diagram for the Automatic Curtain Winder is shown in Fig. 5. Most of the components have already been described, but certain additions have been made to assist the reliability of the system
Capacitors C4 and C6 remove any interference which may be picked up if long wires are used to link switches S4 and S5the optional switches which may be fixed to the curtain track if this method of stopping the curtains is preferred to the automatic "current sense" system already described.
It is helpful, particularly when adjusting the variable resistors (presets) to know whether the circuit is in "day" or "night" mode. Hence, l.e.d. indicators (D1, D2) are driven from pin 6 of IC1 and IC2. The output of a 741 op.amp will not drive a normal l.e.d. directly, and so transistors (TR1 and TR2) are used to increase the available current.
When the output from ICl is positive, the voltage at the bases of TR1 is sufficient the switch on TRI and hence DI. When the output from a 741 switches to "low" the voltage is unfortunately too high to switch off a transistor. The task of resistors R9 and R10 is to reduce the voltage at the base of TR1 so that it can be switched off when required. A similar arrangement applies for IC2 and TR2

## POWER CUTS

Since the circuit is likely to be left unattended for long periods some provision must be made in the event of a power failure, to prevent the bistables assuming a random state when power is restored. At "power up" capacitor C5 supplies a
positive pulse via diode D6 to force both bistables into their reset state. D7 is necessary to allow the capacitor to discharge properly when power is removed.
The Logic Processor could be linked directly to the motor control circuit. However, instead of using a single base resistor for TR4, two 4.7 kilohms resistors in series (R19 and R21) are employed, together with a capacitor C10 and diode D10. Transistor TR3 is given similar treatment.

The reason for this additional circuitry is to prevent rapid reversal of the motor if say, the Close button is pressed immediately after pressing Stop whilst the curtains are opening, and visa-versa. The capacitor delays the rate at which its associated transistor can turn on, but the diode causes the capacitor to be rapidly discharged when the associated logic output switches to logic 0 . The result is that the current through the motor can be rapidly stopped, but there is a short delay before the motor can be turned on again.

## THERMAL FUSE

The circuit is likely to be left on and unattended for long periods. A 500 mA thermal fuse was therefore included on the p.c.b. to cover any eventuality e.g. curtains becoming tangled, current sense stop system failing, major short circuit etc. This particular fuse resets when it cools down, and is in addition to a standard 1A fuse which may be fitted in the case of the unit
It is assumed that the system will be powered by a 12 V 1 A regulated supply. Even so, there are likely to be voltage fluctuations throughout the circuit, and overall decoupling is provided by capacitors C7 and C8.

## CONSTRUCTION

Details of the Curtain Winder printed circuit board (p.c.b.) component layout and full size underside copper foil master pattern are provided in Fig. 6. This board is available from the EPE PCB Service, code 946.

Begin work by inserting the i.c. sockets, followed by the smaller components, checking that the diodes are fitted with their bands. facing the correct way. The resistors and small $0 \cdot 1 \mu \mathrm{~F} \quad(100 \mathrm{nF})$ capacitors can be fitted either way round, but the electrolytic capacitors and transistors must be the way shown. The negative end of the electrolytic capacitor is normally indicated by arrows and a shorter lead.

Fit terminal pins for the external connections. When soldering leads to the terminal pins the simplest and most reliable method is to place a little solder on each pin, then strip and tin (i.e. coat with a little solder) the end of each connecting lead, finally trimming with cutters so that only about a millimetre or two bare tinned lead are exposed. Now place the exposed end against the terminal pin whilst applying the soldering iron.
Decide at this stage if the project is to be housed in its case (described later) before the final test, so that all the external connections can be made; alternatively make temporary connections to the terminal pins to enable testing.

Finally, insert the i.c.s into their sockets, taking special care with IC3 and IC4 (since they are static sensitive) to "earth" your fingers (by touching an earthed metal object) before removing them from their protective package or foam. Ensure that all the i.c.s are fitted with their notches as indicated in Fig. 6.
Heatsinks were not found to be necessary in the prototype; however if a much larger motor is used, check that the power transistor tabs do not become excessively hot (they are allowed to feel too hot for comfort but should not be hot enough to cause a serious burn!).

## TEST/NE

The circuit is best tested by connecting it to a regulated and current limited 12 V supply. A maximum of 100 mA is ideal, assuming that the motor is NOT connected.

The Curtain Winder p.c.b. mounted in the control unit.



The use of a regulated 12 V 100 mA supply will ensure that no damage can be done to the circuit, regardless of mistakes. If such a supply is not available, take extra care, and switch off immediately if any component becomes excessively hot.
Set preset VR4 (bottom left on p.c.b.) fully anti-clockwise to cancel the auto stop. Set the other presets to about midway Switch on. It is likely that the Open I.e.d DI will light.
Twist preset VR1 fully clockwise. You should find that D1 switches off and D2 switches on. Carefully adjust VR1 until it is possible to make the l.e.d.s change over by shading or unshading the l.d.r., R2. Failure at this stage should be investigated before proceeding.

Assuming all is well check the behaviour of the bi-colour l.e.d. D16. It will probably be on, and could be red or green. Try pressing SI (Manual Stop), D16 should turn off.

Shade the I.d.r. to make D16 switch on again. Keep shading the l.d.r. whilst pressing SI again so that D16 is again turned off. Now unshade the I.d.r. This should cause D16 to change colour. The colour of D16 indicates the direction of the motor.
Try the manual switches S2 and S3 to check that D16 can be controlled as expected. Remember to press S1 to switch off D16 after each test. If SI is held on the circuit cannot be triggered.
If you intend using curtain rail stop switches the inputs for switches S4 and S5 could be tested by touching them briefly to positive supply. Note that S4 will only cancel D16 if the circuit is in "opening" mode, and S5 will only cancel D16 if the circuit is in "closing" mode. Keeping input S5 positive (as it will be when the curtains are fully open) will still allow the circuit to enter its closing mode, and vice versa.

## FINE TUNING

Presets VR2 and VR3 allow precise and independent control over when the curtains open or close. For example, it is possible to set the curtains to close at an early (bright) point in the evening, but open at an early (dim) point in the morning or vice versa.
This flexibility may be observed by adjusting presets VR2 and VR3 and noting that it is possible at the changeover point to make l.e.d. D1 switch off before D2 switches on, or make DI switch on after D2 switches off. Remember that D16 will not change colour unless you first trigger the Manual Stop switch SI.


Fig. 7. Positioning the printed circuit board "off-centre" allows space for the l.e.d.s, switches and sockets.

## FAULT FINDING

If the circuit fails to work as expected, check the board carefully for bridged pads (i.e. adjacent pads accidentally joined by solder) and dry joints which are caused by applying insufficient heat. Check also that the correct components are fitted, and have been inserted the correct way round.
Once the visual checks are complete, use a voltmeter to check each stage of the circuit. Connect the negative lead of the voltmeter to 0 V on the p.c.b. Use the positive lead of the voltmeter to check the output voltage from each module in turn to narrow the fault to a particular area. If necessary read the descriptions about each module to check that your readings are correct.
When using a voltmeter around a CMOS i.c. (IC4) be aware that the voltmeter may affect the readings, and may cause the circuit to latch or unlatch. This can be very frustrating, but if readings are taken at the outputs of the gates rather than the inputs the problem should be reduced. It will be very difficult to check the pulse arriving via capacitors C 2 or C 3 .
If the voltage from pin 6 of the op.amps is changing correctly, press and hold S2 and check that pin 1 of IC4 becomes positive. Likewise, holding down S 3 should make pin 8 positive.


The motor reverse circuit can be tested by disconnecting the side of resistor R22 which joins R20, and touching the disconnected side of R22 to positive. This should make the motor turn. Disconnect R22 from positive, and try the same method with R21.
Failure of the motor reverse module may well be due to a mix up between the pnp and $n p n$ transistors. Check their codes carefully, and check that all the transistors are fitted the correct way round.

## CASE DETA/LS

The p.c.b. may be housed in a plastic PX3 type case, size $109.5 \mathrm{~mm} \times 179.5 \mathrm{~mm}$ 60 mm (internal), as shown in Fig. 7. However, it is best to decide at this stage if the Remote Control p.c.b. (next month) is to be housed in the same case, since this affects the drilling requirements.
The p.c.b. is mounted off-centre to allow space for the l.e.d.s, switches and sockets. Begin by drilling holes for the three pushswitches, three l.e.d.s, and sockets. The l.d.r., power supply, and motor supply may be linked via plugs and sockets to promote easy installation.
The p.c.b. may be mounted using selfadhesive p.c.b. supports. Note again that the Remote Control p.c.b. affects the arrangement and will eventually be fitted below the Curtain Winder p.c.b. so that the winder presets may be easily adjusted.

## CHOOSIVG THE MOTOR

Clearly the motor is a key component in this project and will probably cost as much as the rest of the system put together. Remember that if you are using the current sense stop system, resistor R27 will remove several volts and should be rated at 3 W minimum. In the prototype a 6 V motor was chosen rather than a more obvious 12 V type.
A good quality motor will use a conservative amount of current. The prototype used less than 100 mA when under no load, peaking at 500 mA . just before being switched of by the current sense circuit.
The specified motor used in the prototype model was a 60 r.p.m. 6 V type, complete with gearbox (see Shoptalk). Its most useful feature is an output shaft compatible with Meccano shafts - ideal for those with low mechanical competence like the author!


Fig. 8. The motor drive-shaft assembly and housing. The motor is bolted outside the case and the motor spindle linked to the winding shaft using Mecanno parts.

## TESTING THE MOTOR

Assuming that the circuit works, and the bi-colour l.e.d. D16 functions properly, the motor may be connected. If you have been using a regulated 100 mA supply, connect instead a supply capable of delivering 12 V with enough current to drive the motor (say 1A). Repeat the previous tests, checking that the motor starts, stops and reverses when it should.
It will be difficult - probably impossible to test the current sense stop circuit. Wait until the motor is driving the curtains, or substitute another non-geared motor which can be easily stopped.
If you think the motor current sense circuit is not working, check the voltage at pin 3 of IC3. There should be a noticeable voltage rise when the motor is forced to stall, and this should cause the voltage at pin 6 to switch from below 2 V to around 10 V . The voltage at pin 2 of IC3 should change from 0 V to 12 V as preset VR4 is turned.

## MECHAN/CS

The motor discussed earlier, and used in the prototype closed the curtains in about 10 seconds, creating the effect of cinema screen curtains. Higher speed operation would demand a more powerful - and current hungry - motor.
Very heavy curtains might require slower operation. However, much depends upon the efficiency of the curtain tracks. The curtains have to run smoothly, with as little friction as possible. Clearly the tracks must be corded, and if cords are already fitted and run smoothly - there is little more to do at this end.
The shaft of the motor was identical in diameter to Meccano axle rods, and a short Meccano coupling was used to extend the motor shaft as shown in Fig. 8. The shaft runs quite slowly and unless the curtains are very heavy, more couplers may be employed to create a fatter shaft.
This is, however, a very expensive way of making the shaft thicker and cruder methods may be preferred. For example, the cords could be cut longer than required and the surplus used to wind round the shaft. The motor shaft in the prototype tended to slip inside the coupling, and it is well worth filing a flat area to enable the coupling screw to grip the shaft tightly.

The curtain drive motor is bolted onto one end of a ABS plastic case, with the
curtain cord drive-shaft housed inside the case (see photographs). The case specified is a type PX2 and has external dimensions of $54.5 \mathrm{~mm} \times 104.5 \times 42 \mathrm{~mm}$. The case appeared to be made to measure, the Meccano couplers and motor fitting perfectly.
Begin by drilling the holes required noting that the motor already has holes suitable for small nuts and bolts. The motor shaft appears to require quite a small hole, but a much larger one is needed to allow the motor to be bolted properly against the case.
Drill a smaller hole opposite the motor shaft to locate the Meccano shaft. Two holes are required for the winding cords, and one or two mounting holes to allow the case to be mounted on the window sill or wall.
Having mounted the motor assembly, pull the curtains fully open, then cut the "pull to close" cord so that it can be wrapped around the shaft two or three times before being tied to the bush wheel. The motor may now be switched on to wind the curtains fully closed. Stop the motor manually at this stage.
Now attach the "pull to open" cord in the same manner, slackening the shaft retaining screw if necessary to twist the
coupler until both cords are tight. Press the Open switch to wind the curtains open, then press Stop.
Close and open the curtains several times, then re-tighten the cords if necessary. Some slackness when the motor first starts to wind is acceptable providing the cord cannot become tangled.

## AUTO-STOP ALIGNMENT

To set up the auto-stop position, turn VR4 (in the corner of the p.c.b.) almost fully clockwise, and check that the motor has difficulty in driving the curtains. If the motor does not readily switch off, check for faults (see the guide above) before proceeding.
If all is well adjust VR4 anti-clockwise until the curtains will wind fully, but stop when fully wound. Now make fine adjustments to VR4 to set how far you wish the curtains to be opened.

## LIGHT SENSOR

The light dependent resistor R2 should be positioned using glue or tape to fasten its wires so that the body of the I.d.r. is against the inside of a window. Try to select a position away from direct sunlight and hidden from car headlights and spotlights.

## REMDTE <br> CONTAOL

This circuit can be easily interfaced to other control circuits, the nature of the logic is to allow independent operation from a variety of sources. For example, when switch $\mathbf{S} 2$ is pressed a pulse is applied to pin 1 of IC4 and the curtains open. A positive pulse from any other source will achieve the same result. The same applies to S1 and S3.
The Remote Control Unit, described next month, applies pulses at these points, and includes a logic control circuit to convert a single command into the sequence: Open, Stop, Close, Stop etc. This logic control circuit can be extracted if single command operation is required from any other source.
Next Month: Drive your curtains with an Infra-Red Remote Control.


The motor coupling and bush wheels bolted on the curtain drive-shaft.


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Morse Tone Decoder Driver

- unscramble dots amd dashes

THE circuit diagram depicted in Fig. 1 uses a decoder i.c. to act as an interface between an audible Morse code signal and an external logic circuit or relay, so that the user can start to decode Morse code heard on a radio receiver. It was decided from the start that the unit would have its own built-in microphone for ease of use and to avoid having to make connections to the circuit board within the radio receiver. Hence, this circuit is completely self-contained and enables you to synchronise a logic circuit or relay with the audio Morse code.

## Circuit

In the circuit diagram Fig. $1, \mathrm{MICl}$ is an electret microphone which feeds the selected audio tones to a simple transistor amplifier based around TR1 and associated components. Resistor R1, R2 and capacitor Cl provide a supply for the electret microphone. Potentiometer VRI is a Sensitivity control and the signal is coupled to ICl input (pin 3), via capacitor C5.

The NE567 i.c. is a tone decoder phaselocked loop device which drives a load whenever a particular signal frequency is present at its input for a given length of time. Resistor R6, potentiometer VR2 and capacitor C 8 set the operating frequency of the NE567 internal oscillator.

With the values shown, the circuit has a frequency range of 850 Hz to 1340 Hz . Within this range, the circuit will "lock" and cause the l.e.d. Dl connected at the output, to illuminate. Capacitors C6 and C7 are the output and loop filter components which were chosen to give optimum results over a wide range of Morse transmission speeds.

As quite a lot of Morse is transmitted in continuous wave (CW) it will be necessary to use the receiver's BFO to hear the Morse tones. Set the BFO to produce an audio tone of about 1 kHz , then position the microphone next to the loudspeaker and adjust VR1 and VR2 until the "signal" l.e.d. flashes. in unison with the Morse tones.


Fig. 1. Circuit diagram for the Morse Tone Decoder Driver.


Fig. 2a. C,ircuit diagram for a simple logic interface.

## Add-on Circuits

The output of the decoder is available at point " X ". A simple logic interface is given in Fig. 2a which generates a Logic 1 when a Morse tone is detected. The relay driver also shown in Fig. 2b could be adapted to drive ticker-tape or solenoid marking

Fig. 2b. Add-on circuit diagram for driving a relay.
devices, provided that the Morse speed is not too high.

A +5 V supply is necessary for correct operation and a standard 7805 regulator can be used to provide this from higher d.c. voltages.

Neil Dobson,
Chopwell, Newcastle-upon-Tyne.

Metal Detector

- strilke if lucky

When tuned correctly, the Metal Detector illustrated in Fig. 3 will detect an old Victorian Penny at a depth of 10 cm , although for practical purposes 5 cm may be more realistic. It will detect large objects at 25 cm and more. It is extremely simple and cheap to build and has minimal ground effect.
The metal detector is based on the BFO (Beat Frequency Oscillator) principle and incorporates two high frequency oscillators both running at approximately 300 kHz . In Fig. 3, ICla and IC1b oscillate at a fixed frequency whilst IClc is a variable frequency oscillator whose frequency is highly dependent on the inductance of coil L1. The outputs of both oscillators are mixed through ICld, producing an audible beat frequency.

Two coils were tested, one of 50 turns of 33s.w.g. enamelled copper wire 22 cms in diameter, the other of 40 turns of 30 s.w.g. 24 cms in diameter. It was found that the winding technique for the coils was not critical. Although the circuit is stable in operation, ceramic capacitors were found to introduce instability and are therefore not suitable. Polyester types may be best.


Fig. 3. Circuit diagram for the low cost Metal Detector.

The output is connected between ICld pin 11 and the 0 V rail, and may drive a set of headphones, a crystal earpiece or an amplifier. If an unclear note is heard, experiment with the values of the capacitors Cl to C 3 .
In order to tune the Metal Detector, adjust potentiometer VRI to a zero beat setting (i.e. silent output) between the loudest frequency peaks. Then tune a little either way to find a low tone. A 10 ohm poten-
tiometer in series with VR1 may simplify adjustment.
In use, a change of tone will indicate the presence of metal. With a smaller coil, this Metal Detector may also be used as a pipe or cable locator. It draws less than 10 mA current from a 9V PP3 battery.

Rev. Thomas Scarborough,
Cape Town, South Africa.

## Infra-Red Repeater

- TMP (VCR Rrom ofous

My CIRCUIT diagram shown in Fig. 4 is an Infra-Red Repeater Unit which allows equipment such as VCRs or satellite receivers etc. to be controlled from more than one room. All the work is done by IC1, a Sharp ISIU60 integrated circuit (from Electromail, Stock Code 577897). This three-terminal device detects the 40 kHz signals emitted by infra-red remote controllers, and provides a clean demodulated signal.

In the absence of any infra-red signal the output of ICl is high. This drives transistor TR1 on which resets IC2, a 555 astable oscillator. When infra-red pulses are received, IC2 will oscillate at 40 kHz or so.
The timer i.c. drives transistor TR2, which drives the two light-emitting diodes D1 and D2. D1 acts as a "pilot" indicator and illuminates to confirm that infra-red pulses are being received.
The infra-red diode D2 is placed in the same room as the equipment to be controlled, and placed as close as possible (I suggest within one metre) to the item of equipment. It can be connected to the


Fig. 4. Circuit diagram for the Infra-Red Repeater.

Repeater circuit with twin-core wire of suitable length.
I found that sometimes it was better to replace the 18 kilohm resistor with a 22 kilohm preset and adjust this for the most
reliable operation. The supply rail to the circuit is best regulated at 5 V . A cheap 7805 voltage regulator i.c. could be used, which will not need a heatsink.

Mark Skeete, London, E10.

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# BEBOP TO THE BOOLEAN BOOGIE 

Author Clive Maxfield<br>Size $\quad 471$ pages $256 \times 220 \mathrm{~mm}$<br>Price<br>Publisher HighText Publications Inc. ISBN 1-878707-22-1

"An Unconventional Guide to Electronics Fundamentals, Components and Processes." Clive (call me "Max") Maxfield

0PEN many text books on electronics and they commence with the same very dry theory of the physics pertaining to the electron, gradually becoming even more desiccated. Just out in the UK, Bebop is an American text book which is very different, not least because of Max's dry (British) sense of humour - starting with a series of wry footnotes which brought forth many a chuckle! Off to a flying start, then, this book is not a circuit cook-book per se but a thoroughly researched and highly readable reference on general electronics principles, prevailing techniques and future technologies.

Max has fired a well-aimed scatter-gun at electronics basics, progressing into digital techniques, logic systems, Boolean algebra of course, memories, programmable integrated circuits and more complex digital chips, dealing with the manufacturing methods of current-technology devices as well. A good proportion of Bebop then considers printed circuit board technology, sprinkled liberally with well presented illustrations of commendable clarity. This will appeal to those becoming involved with p.c.b. CAD systems for the first time, for instance, since the technology behind various board fabrication methods is discussed in some depth.

The author analyses cutting edge technology including superconductors, protein switches and nano-technology - not just in passing, either, but again in a well researched, interesting and authoritative manner that's bang up to date. Still the humour keeps coming but it isn't over-done and doesn't detract from a highly informative and buoyant style.

It's hard to pigeon-hole Bebop because it covers many disciplines such that there's something for anyone involved in any
way in electronics, whether as a mild interest or as a serious technician. Supported by a glossary, various appendices and a thorough and comprehensive index, I think the book is an excellent and invaluable resource for anyone who's ever held a soldering iron and wants to know what makes current electronics technology tick, and where it's going in the future.

The price seems a bit steep though, at $£ 30.99$ which might put it out of reach of those who would probably benefit from Bebop most of all. An excellent buy otherwise, and uniquely enjoyable. If you're not hooked after reading it you probably never will be.
A.W.

## THE MODEM REFERENCE (Third Edition)

Author
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Telecommunications technology is bounding ahead, leaving even this latest Edition of The Modem Reference a bit out of breath. Little if any mention of increasingly demanded 28.8 K bps (V.34) technology or currently popular 14.4 K (V.32bis) standards, this book is nonetheless a good introduction to modem technology and communications by computer. Aimed at both the beginner or professional modem user, it de-mystifies much of the jargon which anyone setting up and using a modem will undoubtedly encounter sooner or later - probably sooner!

Of American bias, there is still more than enough data to enable the UK reader to tackle his new modem with a lot more confidence, though you'll probably still need your modem instruction book to sort out any actual initialisation problems - at least you'll understand what much of the Hayes AT Command Set ąctually means and what's really going on, so that you can ftp and email with more confidence. Quite a proportion is given over to American on-line services and is less relevant here.

Let down by scrappy bitmap thumbnail graphics at times but includes a floppy disk with several useful utilities and Windows Terminal front ends. Generally worth having.
A.W.


## Automatic Curtain Winder

Clearly, the motor is a key component in the Automatic Curtain Winder and will probably cost as much as the rest of the system put together. In the prototype a 6 V motor was chosen rather than a more obvious 12 V type.

The specified, motor used in the model, is an RS type and was purchased through Electromail ( 01536 204555), code 336-337. This is a 60 r.p.m. 6 V type, complete with gearbox.

If you are unable to obtain the Meccano parts locally, they are available, mail order, from MW Models, Dept EPE, 4 Greys Road, Henley, Oxon. Tel: 01491572436.

The printed circuit board is available from the EPE PCB Service, code 946. Remember, if you are using the "current sense" stop system, resistor R27 should be rated at 3 W minimum.

## Windicator

The author of the Windicator project overcame the problem of the need for special mechanical parts by using a d.c. motor as a sensor. The specified d.c motor, made by Matsushita (MHN-5RG4E), is supplied by Magenta Electronics and is similar to a cassette-player motor.

A motor different from the one specified could be used but it must be a good quality, high output type. However, the output may
not be linear and you will then, of course, need to calibrate the design yourself - not so easyl

We understand that a full kit of parts for the Windicator is available from Magenta. The kit (code 856) comes complete with sensor motor and sensor cups, but excludes any twin-core "zip" wire. The cost of the kit is $£ 28$ and the motor is available separately for the sum of $f 4.80$. A post and packing charge of $£ 3$ per order must also be added to the cost. Magenta Electronics, Dept EPE, 135 Hunter Street, Burton-on-Trent, Staffs, DE14 2ST.

The small Windicator printed circuit board is available from the EPE.PCB Service, code 947.

## Ramp Generator

Some of the items called up for the Ramp Generator need to be specially purchased if the constructor is to adhere to the published design. Other componehts may be used but they may not fit on the p.c.b.s and may not produce such good results.

Most of the components used in this design are RS components and were purchased through Electromail (is 01536 204555). Particular parts which shouid be as specified are as follows: potentiometers, codes 173-631 and 18.7-220; crystal oscillator module $(16.384 \mathrm{MHz})$, code 658 845; AD7845 12-bit DAC, code 263-295;
mains transformer, code 208-945 and the $22,000 \mu \mathrm{~F}$ electrolytic, code 127-486.

The printed circuit boards for this project are available as a pair from the EPE PCB Service, code $944 / 5$. The choice of case has been left to the individual as the one used adds $£ 52.28$ to the cost!

## HV Capacitor Reformer

The majority of components for the HV Capacitor Reformer should be readily available from your local supplier. The high voltage electrolytic (C1) maybe a little more difficult to come by, but a few phone calls to advertisers should soon provide the answer.
The small printed circuit board is available from the EPE PCB Service, code 943.
EPE HiFi Valve Amplifier
It is most important that constructors undertaking the EPE HiFi Valve Amplifier adhere to the correct ratings of the resistors listed in the components box. Brimistors are now considered obsolete technology and are not now generally available. However, Brian J. Reed (4 0181393 9055) can, we understand, supply them at a surplus price.

Due to their weight, the mains and valve output transformers are best ordered/purchased from your nearest Maplin shop to save on the postage costs. Suppliers for the rest of the components were covered in last month's Shoptalk.

Note: If the amplifier is used to feed 4 ohm loudspeakers the valves will over-dissipate and their working life will be shortened. The output transformer is designed to drive 8 ohm speakers.

The Phase-splitter p.c.b. (last month) is available from the EPE PCB Service, code 941.


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On one glorious occasion an Indian newspaper got itself sued for stealing an article l'd written. I didn't sue. Neither did the British magazine from which it had been stolen. Someone mentioned in the stolen article sued, claiming that they had been libelled by the words the paper had stolen!

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As more and more picture material is distributed as digital code, this problem can only get worse.

## FBI INTERVENES

One solution may be a system called FBI, developed by a British company, MOR of Sutton in Surrey. Fingerprinted Bitmapped Identification buries a digitally encoded fingerprint inside any photographic image when it is stored in a computer or on a CD-ROM. The fingerprint is a string of letters, for instance someone's name or password, and there is no visible effect on the picture (except for black and white monochrome images, if they are very much enlarged).

The FBI software scans the image to bury the fingerprint and then at a later
date scans it to recognise the fingerprint. If the image has been manipulated the fingerprint shows breaks in the text string. The fingerprint also shows breaks if the image has been cropped.

FBI withstands conversion from one computer file format to another. It also survives copying any number of times.

If an A-4 picture of a tiger is converted into a 30 megabyte image file, and the file fingerprinted, then even taking the eye out of the tiger will still show up on print analysis.

## VIDEO VALIDATION

Early demonstrations of the software (at a seminar on CD-ROM piracy held in London recently) show that FBI works. Full trials begin this summer. Especially interesting is the claim that the same technique can be used to insert fingerprints into moving video material. It can also be used to fingerprint material sent down telephone lines, e.g. on the Internet.

Once inserted, the fingerprint cannot be stripped out, or masked, without damaging the picture. So if copyright owners mark their images, they can subsequently prove the true origin. This could help photo libraries which would like to distribute digital images by disc or line to magazines round the world, but fear their pictures will then be manipulated to disguise origin and avoid payment of copyright fees.

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# RAMP GENERATOR 

## NEIL JOHNSON BEng(Hons) AMIEE $\overline{\underline{\underline{\underline{~}}}}$ Part $1 \equiv$

## A professional quality ramp generator aimed at the intermediate to advanced constructor.

THIS Ramp Generator project evolved from a need to expand and improve the author's range of test equipment with a versatile unit which could be used for a wide range of tasks. Some suggestions as to what the Ramp Generator can be used for are covered later; just to whet your appetite: oscilloscope calibrator, plotter timebase, curve tracer, spectrum analyser, etc.

## DVERVIEW

Let us begin by looking at the system block diagram, shown in Fig. 1. The heart of the Ramp Generator is a precision master crystal oscillator module whose output is 16.384 MHz , within $\pm 0.01 \%$; this level of precision is easily attainable from off-the-shelf crystal modules.
The next stage is a presettable divider. This divides the master frequency $(16.384 \mathrm{MHz})$ by four to get 4.096 MHz , and then sixteen further division stages of one, two, five and their decades to produce the clock signal for the rest of the Ramp Generator.
The Gate and Trigger block, together with External Trigger Input and Output, provides the main ramp controls. The main function of this block is to gate the clock signal to the next stage. Control functions include glitch-free pause and single sweep triggering - both requiring devious circuit design!


The 12-bit counter and digital-toanalogue converter (DAC) are responsible for converting the stream of digital pulses into a smooth ramping analogue waveform. The gated clock signal increments, or decrements, the counter, with the resulting 12 -bit binary value being converted to an analogue voltage by the


Fig. 1. System block diagram for the Ramp Generator.

DAC. Being 12 -bit there are 4096 steps for one complete cycle, so the required clock frequency for a ramp of 1 ms duration is 4.096 MHz .

Following the DAC are the Level, Offset and Output Buffering circuits. The summing junction is an op.amp, combining a proportion of the converter output signal with a variable constant.d.c. offset voltage. The buffer amplifier provides plenty of signal for the ramp generator to drive a standard 50 ohm load

Finally, running the whole show is the Power Supply Unit (PSU), transforming 240 V a.c. to clean, regulated +5 V and $\pm 15 \mathrm{~V}$ d.c.

## CIRCUIT DESCRIPTION

Having taken a broad look at the Ramp Generator let's take a deeper look inside those blocks.

The Ramp Generator circuits are split into four main sections: Clock and Divider, Gate/Trigger and Counter, Converter and Buffer, and PSU.
The circuit diagram for the Clock and Divider is shown in Fig. 2. It follows a clockwise path starting at the top left with 1C32, a readily-available crystal oscillator module. It is worth noting here the merits of these modules: they offer crystal controlled TTL-compatible clock signals in a sealed metal package with a standard 14 pin d.i.l. layout.


Fig. 2. Circuit diagram for the Clock and Divider sub-section of the Ramp Generator.

Some of you may be thinking "Cheat" but consider: this module saves board space, around twenty holes, several other components and considerable design time, compared to building a crystal oscillator from individual components. Surely a better engineering solution?
The output of IC32 is divided by IClb and ICla down to 4.096 MHz , the first clock frequency. This feeds the start of the main divider chain, IC2 to IC9a, to provide the other 15 clock frequencies listed in Table 1.
Frequency selection is made by the 8 input multiplexers IC10 and IC11. These

TABLE 1

| Clock <br> Frequency | Ramp <br> Period |
| :---: | :---: |
| $4 \cdot 096 \mathrm{MHz}$ | 1 ms |
| $2 \cdot 048 \mathrm{MHz}$ | 2 ms |
| $819 \cdot 2 \mathrm{kHz}$ | 5 ms |
| $409 \cdot 6 \mathrm{kHz}$ | 10 ms |
| $204 \cdot 8 \mathrm{kHz}$ | 20 ms |
| 81.92 kHz | 50 ms |
| 40.96 kHz | 100 ms |
| 20.48 kHz | 200 ms |
| $8 \cdot 192 \mathrm{kHz}$ | 500 ms |
| $4 \cdot 096 \mathrm{kHz}$ | 1 s |
| $2 \cdot 048 \mathrm{kHz}$ | 2 s |
| $819 \cdot 2 \mathrm{~Hz}$ | 5 s |
| $409 \cdot 6 \mathrm{~Hz}$ | 10 s |
| $204 \cdot 8 \mathrm{~Hz}$ | 20 s |
| $81 \cdot 92 \mathrm{~Hz}$ | 50 s |
| $40 \cdot 96 \mathrm{~Hz}$ | 100 s |
|  |  |

are controlled by hexadecimal switch S1 via inverter IC12a, with IC10 selecting the first eight frequencies and IC11 the remainder. This double-selection system rotary switch and multiplexers - may seem a bit extravagant (instead of a simple rotary switch alone) but it has at least two advantages: IC10 and IC11 can be placed on the circuit board where appropriate, and, more importantly, critical signals are kept to relatively short circuit paths, well away from the front panel.
The outputs of the two multiplexers are combined by OR gate IC13c before sending on to the next stage.

## GATE/TRIGGER AND COUNTER

Looking at the Gate/Trigger and Counter circuit diagram in Fig. 3, the clock signal first passes through AND gate IC19b, the Pause gate. This gate is controlled by switch S2, flip-flop IC9b and friends. A $\mathrm{J}-\mathrm{K}$ flip-flop is used here for three reasons: being clocked from the input to the gate prevents any spurious runt pulses getting through; it provides a simple debounce circuit for switch S2 at no extra cost; and offers an extra output pin to operate an indicator circuit, based around transistor TR1 and I.e.d. D1.
The second AND gate, IC19a, is the main control gate. It is operated by the trigger circuitry, or can be held permanently open by switch S5 - with S5 open, IC19d pin 13 is pulled low through
resistor R10 and, via inverter IC12b, resulting in IC19a pin 1 being set high.
The trigger circuitry is based around an SR flip-flop (AND gates IC15b and IC15c). In the reset state, ICl9d pin 12 is set high and, together with switch S 5 being closed, opens the clock gate and clears the counters (more on this later). The reset input is connected to the output of a rising-edge detector based on inverters IC14a, IC14b, IC14c and NAND gate ICl5d.
This edge detector works on the finite propagation delay of the inverters, as shown by the timing diagram in Fig. 4. The input to the detector is a combination of the Reset push-switch S3 and the output of the zero-detector (yet to be described).
Setting the flip-flop is a bit more complicated. This time a falling-edge detector is used, consisting of inverters IC14d, IC14e, IC14f and OR gate IC13d. The two trigger inputs, manual and external, are combined by AND gate IC19c. The manual trigger, switch S4, is properly debounced by inverters IC12d, IC12e, and resistor R16, in order to avoid any spurious triggering, especially on the faster sweep times. The External Trigger Input is derived from a later part in the circuit.
Next along is the 12 -bit counter, made up of three 4 -bit counters in series - IC20, IC21 and IC22. Direction of count - up or down - is controlled by switch S6, the Ramp Mode control. For optimum performance the counters are operated synchronously from the common clock signal, to ensure that all 12 data bits


Fig. 3. Gate/Trigger and Counter circuit diagram details.
change at the same time. The three counters are linked together by NAND gates IC17c and IC17d.

Resetting all the counters to zero is accomplished with the Parallel Load function, loading a value of zero into all three counters at the same time. The 12 -bit output of the complete counter passes on to a zero detector, based on NOR gates IC16a, ICl6b, OR gate ICI3a, NAND gate ICI7b; and AND gates IC18a and IC18d. This circuit detects when all the counter outputs are zeroes, setting its own output, at IC18d
pin 11, high during this condition.
The "zero" signal is used for three purposes: to reset the trigger flip-flop via the path commencing with OR gate ICl 3 b ; to operate the Sweeping l.e.d. D2 via inverter IC12c and transistor TR2; and to provide the control signal for the External Trigger Output stage, accessed via inverter ICI7a and connector PL1.

Moving on to the next circuit section we jump via the 20 -way IDC connector PLI to the analogue circuit, whose details are shown in Fig. 5.

## CONVERTERAND BLFFER

The first port of call in Fig. 5, is the DAC. This takes the 12 -bit digital data and converts it into an analogue output voltage, which can be calculated from the following equation:

Vout $=-V_{\text {ref }} \times D / 4096$
where $\mathrm{V}_{\text {out }}=$ output voltage
$V_{\text {ref }}=$ reference voltage
$D=$ digital input code, 0 to 4095


Fig. 5. Circuit diagram for the Analogue portion of the Ramp Generator.

The reference voltage is provided by a precision +5 V reference device, IC24. Potentiometer VR1, the Level control, feeds a portion of the converter's output signal to the inverting input, pin 2 , of the summing amplifier based around op.amp IC25. A further signal to this input is provided by VR2, the Offset control. Resistors R20 and R21 set the maximum and minimum settings, while capacitors C26 and C27 filter out any unwanted noise. The Offset Null adjustment preset VR5 is provided should you decide not to include VR2.

The last stage of the main signal path is the output buffer. This is built around op.amp IC26, National Semiconductor's LM6181. This device is able to directly drive a 50 ohm terminated load up to 10 V peak without complaining, with a bandwidth extending up to 100 MHz . The buffered ramp waveform then reaches the outside world via connector SK2.
The External Trigger Output signal from the zero detector is buffered by IC27, all four AND gate sections being wired in parallel. The buffer output is

## $t_{\text {PD }}=$ Propagation delay of inverter



Fig. 4. Rising edge detector timing diagram.
protected from short circuits by resistor R28 and is brought to the front panel via socket SK 1 .
The External Trigger Input circuit based around comparator IC28 is accessed via socket SK3, resistor R32 and diode D3. Zener diode D4 is the input limiter which starts to work above 5 V and handles input voltages up to 30 V - exceed this and resistor R32 will turn into a little black'n'crispy ex-resistor!

## POWER SUPPLY UNIT

The Power Supply is a fairly simple transformer-rectifier-regulator linear unit. Its circuit diagram is shown in Fig. 6. Transformer T 1 reduces the mains voltage down to about 30 V a.c., rectified by bridge rectifier RECl to produce $\pm 20 \mathrm{~V}$ d.c. This is smoothed by capacitors C39 and C40 before being regulated at +15 V , -15 V and +5 V by IC 29 , IC30 and IC31, respectively. The positive supply smoothing capacitor, C39, has a larger capacity than C40 to provide smooth current for both +15 V and +5 V regulators. Poweron indication is provided byl.e.d. D5.
Supply decoupling is performed at a local level to each chip. Details are given in the respective circuit diagrams. In all cases the decoupling capacitors are physically located as close to the devices as possible

## COMPONFVIS

## Resistors

R1 to R4, R7, R8, R12; R13, R32

1k (9 off)
R5, R6, R10, R11, R15
R9, R14
R16, R28
R17 to R19
R21, R23, R24, R31 10k (5 off)
R22 33k
R25, R26 820 (2 off)
R27 47
R29, R30, R33, R34 1k5 (4 off)
All $0.5 \mathrm{~W} 5 \%$ carbon/metal film
Potentiometers


## Semiconductors

| D1 | l.e.d. 5 mm yellow plus clip |
| :---: | :---: |
| D2 | I.e.d. 5 mm green plus clip |
| D3 | 1 N4148 signal diode |
| D4 | BZX79C4V7 4V7 Zener diode 500 mW |
| D5 | l.e.d. 5 mm red plus clip |
| TR1, TR2 | BC109 npm transistor (2 off) |
| IC1, IC3, IC6, IC9 | 74LS73 dual J-K flip-flop (4 off) |
| IC2, IC4, IC5, IC7, |  |
| IC9 | $74 \mathrm{LS90}$ decade counter (5 off) |
| IC10, IC11 | 74LS151 8-input multiplexer (2 off) |
| IC12, IC14 | 74LS04 hex inverter (2 off) |
| IC13 | 74 LS 32 quad 2 -input OR |
| IC15, IC17 | 74LS00 quad 2 -input NAND (2 off) |
| IC16 | 74LS260 dual 5 -input NOR |
| IC18, IC19 | $74 \mathrm{LS08}$ quad 2 -input AND (2 off) |
| IC20 to IC22 | 74LS191 binary up/down counter (3 off) |
| IC23 | AD7845 12 -bit digital to analogue converter |
| IC24 | REF-02 +5 V precision voltage reference |
| IC25 | AD711 single high speed op.amp |
| 1 C 26 | LM6181 single 100 kHz op.amp |
| IC27 | 74 HCT08 quad 2 -input AND |
| 1 C 28 | LM311 voltage comparator op amp |
| IC29 | $7815+15 \mathrm{~V} 1$ A regulator |
| 1 C 30 | 7915 -15V 1 A regulator |
| 1C31 | $7805+5 \mathrm{~V} 1 \mathrm{~A}$ regulator |
| IC32 | 16.384 MHz crystal oscillator module |
| REC1 | W005 50V 1 A bridge rectifier |

## Miscellaneous

S1
hexdecimal rotary switch, with mounting bracket 2-pole changeover interlocking push-switch (5 off)
S2 to S6
s.p.s.t. 4A mains-rated latching push-switch, with mounting bracket
PL1, PL2
SK1 to SK3
SK4
T1 d.i.l. header plug and socket 20-way ( 2 off each) panel mounting BNC socket (3 off) panel mounting mains input connector mains transformer, $2 \times 15 \mathrm{~V} 1 \mathrm{~A}$ secondary windings, p.c.b. mounting
Printed circuit boards available from the EPE PCB Service, codes 944 (logic), 945 (analogue); 6-switch latching assembly bracket for S2 to S6; knob for S1 to S7 (7 off); knob for VR1, VR2 (2 off); s.p. push-make switch (optional -see text); 8-pin d.i,l. socket (4 off); 14-pin d.i.l. socket (18 off); 16 -pin d.i.I. socket ( 5 off); 20-pin d.i.I. socket; mica hardware for IC29 to IC31 ( 3 sets) plus silicone heatsink grease; panel mounting clips for I.e.d.s. (3 off); 20-way IDC connector socket ( 2 off); 20 -way IDC ribbon cable ( 15 cm minimum); metal case $290 \mathrm{~mm} \times 150 \mathrm{~mm} \times 260 \mathrm{~mm}$ ( $\mathrm{L} \times \mathrm{H} \times \mathrm{W}$ ) type RS 581-082; aluminium sheet $2 \mathrm{~mm} \times 74 \mathrm{~mm} \times 30 \mathrm{~mm}$; cable; connecting wire; solder, etc.

Fig. 6. Power supply circuit diagram.

## SAFETY ADVICE

Before discussing construction it is worth mentioning a couple of important points. As the Ramp Generator has its own built-in mains PSU, part of the construction process will involve mains wiring. ONLY ATTEMPT MAINS WIRING IF YOU KNOW WHAT YOU ARE DOING. IF YOU ARE UNSURE, GET THE UNIT CHECKED BY AN ELECTRICIAN BEFORE PLUGGING IT INTO THE MAINS.
You will also need access to workshop facilities for drilling the front and rear panels and making a bracket for the two panel potentiometers. If you are using someone else's workshop, or a workshop at work, school, college, etc., ask for permission first and never work alone - if there is an accident you may need to rely on someone else to help you.

## BDARDS DETA/LS

The printed circuit board (p.c.b.) for the Ramp Generator Logic circuit is a double-sided board with plated-through-holes (PTH). The Analogue board is single-sided p.c.b. These boards are available from the EPE PCB Service, as a pair, code 944/945.

However, the full-size copper foil track layouts for the boards are too large to publish. Full-size photocopies of the layouts, though, and full size legend details for the recommended case, can be obtained FREE from the Editorial Office address.

Readers who use the ready-made Logic board, which is PTH, do not need to use additional through-board link pins. Readers making their own board, though, will need to insert and solder link pins at the points where tracks are taken from one side of the board to the other. There are 78 of these points. With non-PTH boards, it is essential that component leads are soldered on both sides of the board in order to link tracks where appropriate. The use of turned-pin di.i.l i.c. sockets in this application is vital.
Next Month: Construction of the Logic and Analogue boards, case details and final testing.


As the PRO but also includes *Advanced Schematic Capture (Busses, Power rails,etc) *Larger Schematic \& PCB Designs *Gerber file IMPORT for File Exchange *Extended libraries (CMOS,SMT,etc) *SPICE Export *SpiceAge DDE link.
*Prices exc/ude P+P and V.A.T. VISA/MasterCard Accepted *Network versions available.
POWERware, 14 Ley Lane, Marple Bridge, Stockport, SK6 5DD, U.K.

# INTER FACE Robert Penfold 

USING a personal computer as the basis for a weather monitoring system is quite fashionable amongst electronics and computer enthusiasts. It is possible to undertake most of the normal types of monitoring using a PC plus some home constructed sensors. In some cases the fully computerised method could be regarded as doing things the hard way. With something like rainfall measurement for example, using the traditional method of measurement and typing the data into the computer's data base is likely to be the simplest and most accurate method.
Measurements such as temperature and wind speed, where frequent readings are required and accurate electronic sensing is reasonably simple, are a different matter. The all-electronic method is a more attractive proposition. Temperature measurement using an LM35 sensor and an analogue-to-digital converter based on the ZN 448 E is quite easy, and has been covered in previous articles. For the amateur meteorologist the only problem is in obtaining a suitable temperature range for his or her purposes.

## Scaling

The LM35CZ covers a range of 0 to 100 degrees Celcius, and the LM35DZ covers -40 to +110 degrees Celcius. Both devices have three terminals and a standard TO92 style plastic encapsulation. Leadout details are shown in Fig. 1 (which is a base view).
For both devices the output voltage is a straightforward $10 \mathrm{mV} /{ }^{\circ} \mathrm{C}$, with no offset voltage to contend with. On the face of it, this matches up very well with the 10 millivolt resolution of the ZN 448 E .


Fig. 1. Pinouts for the LM35CZ/DZ.
In practice this is not really the case, because the maximum output voltage of the LM35DZ is only $1 \cdot 1$ volts, which compares with a full scale value of 2.55 volts for the ZN448E. Directly interfacing these two devices does not even give full seven bit resolution. In the current context, temperatures of more than about 40 degrees are of no interest. Even with the rather erratic weather we get in the UK these days, it seems unlikely that a temperature
of $40^{\circ} \mathrm{C}$ (104 degrees Fahrenheit) will be reached in the near future.

Amplifying the output from the LM35 gives a more restricted temperature coverage, but also provides much better resolution. Amplifying the output voltage by a factor of five gives a voltage change of $50 \mathrm{mV} /{ }^{\circ} \mathrm{C}$. When fed to the input of a ZN 448 E this gives a temperature range of 0 to $51^{\circ} \mathrm{C}$, and a resolution of 0.2 degrees Centigrade. This compares to a resolution of $1^{\circ} \mathrm{C}$ if no amplification is used.

## Temperature <br> Interface

The circuit for a simple temperature interface that covers a range of 0 to $51^{\circ} \mathrm{C}$ is shown in Fig. 2. Dual balanced 12 V supplies were used to power the prototype, but dual 5 V supplies should just about suffice. IC1 is the temperature sensor. 1 used an LM35DZ, but over this range of temperatures the LM35CZ should work just as well.
The output from

IC1 feeds into a non-inverting mode amplifier based on IC2. The closed loop voltage gain of the amplifier is set by resistors R1, R2, and preset VR1. The latter is adjusted to give a voltage gain of five times.
In practice, VR1 is given the correct setting by first subjecting the sensor to a temperature which is equal to about half to one hundred percent of the full scale value (i.e. about 20 to 51 degrees). In most cases the room temperature will be about 20 to 25 degrees Celcius, and this will suffice. An accurate thermometer is used to accurately measure the room temperature, and then VR1 is adjusted for the appropriate reading.

This interface can be used with the PC Analogue Input Port described in the April 1995 issue of EPE (Fig. 2 on page 317). Resistors R2, R3, R4, and VR1 are omitted from the analogue port, and the output of the temperature interface connects direct to pin 6 of IC1. The interface should work equally well with other analogue inputs that are based on a ZN 448 E series converter, or the earlier ZN427E, provided the output of the interface can be connected direct to the input pin of the converter chip.

## Negative Thoughts

There is an obvious drawback to this temperature interface in that it does not handle negative temperatures. Even in the mild part of the UK where I live, the night-time air temperature occasionally dips below zero. Using an LM35DZ sensor it is possible to measure temperatures that go well below zero. However, negative temperatures produce negative output voltages from the LM35DZ, and the ZN488E cannot handle these.


Fig. 2. A temperature interface which covers a range of $O$ to 51 degrees Celcius.

The solution to the problem is to provide a positive offset voltage to the output signal of the LM35DZ, so that negative output voltages are brought within the input voltage range of the ZN448E. Fig. 3 shows the circuit for a modified version of the temperature interface that can provide this offset voltage.
This is basically the same as before, with IC2 being used to amplify the output of IC1 by a factor of five. The difference is that the lower end of R2 is not connected to the 0 volt rail, but is instead connected to the output of a variable voltage source. This uses VR2 and R4 to provide the variable voltage, and IC3 to act as a buffer stage so that R2 is fed from a low impedance source. This prevents the offset circuit from significantly affecting the closed loop voltage gain of IC2.

IC3 provides a small negative output voltage. The voltages at IC2's inputs are maintained at the same potential by the standard negative feedback action. With the lower end of R2 taken negative, the output of IC2 has to go more positive in order to maintain this balance. The positive offset at the output of IC2 is equal to the voltage set on VR1 multiplied by the closed loop voltage gain of IC2. For example, a negative potential of


Fig. 3. An interface circuit which covers the range $-11^{\circ} \mathrm{C}$ to $+40^{\circ} \mathrm{C}$.
100 mV from VR2 will produce a positive offset of 500 mV at the output of IC2.
The circuit can handle a wide range of offset voltages, but an offset of 110 mV at IC2's output is a good choice. An output potential of -110 mV from the sensor then gives zero volts at the output of IC2. This provides a temperature range of $-11^{\circ} \mathrm{C}$ to $+40^{\circ} \mathrm{C}$. In colder parts of the country it might be better to use an offset of 160 mV , which would give a temperature range of $-16^{\circ} \mathrm{C}$ to $+35^{\circ} \mathrm{C}$.
Precision operational amplifiers are specified for IC2 and IC3, but as large voltage gains are not involved, most 741C compatible operational amplifiers will give good results in this circuit. The supply regulation is probably a more important factor, particularly the negative supply as this is used to provide the offset voltage. The circuit should work with dual 5 V supplies if the value of R1 is reduced to 100 k , and R4 is reduced to 39k. Ideally, VR1 and VR2 should both be multi-turn "trimpots".

## Adjustment

Start with VRI at a roughly middle setting, and then subject the sensor to a low and accurately known temperature. This can be zero degrees provided by some iced water. Note though, that the sensor's leadouts must be electrically insulated from the water, or the sensor must be held so that the leadout wires are just clear of the liquid. VR2 is then adjusted for a reading of zero.
Next the sensor is subjected to a higher and accurately known temperature. This can simply be the room temperature. Give the sensor plenty of time to adjust to the change in temperature. Then adjust VRI for the correct reading. This whole process is repeated a few times until no further adjustment is required.

## Software

The following GW BASIC or Q BASIC program reads the temperature sensor and prints the temperature on the screen:

10 REM GW BASIC TEMPERATURE PROGRAM
20 CLS
30 OUT \& $337 \mathrm{~A}, 1$
40 OUT \& $337 \mathrm{~A}, 0$
$50 \mathrm{X}=\mathrm{INP}(\& \mathrm{H} 379)$ AND 120
$60 \mathrm{X}=\mathrm{X} / 8$
70 OUT \&H37A, 4
$80 \mathrm{Y}=\mathrm{INP}(\& \mathrm{H} 379)$ AND 120
$90 Y=Y^{*} 2$
$100 Z=X+Y$
$110 Z=Z / 5$
$120 \mathrm{Z}=\mathrm{Z}-11$
130 PRINT Z " Degrees C."
140 FOR DELAY = 1 TO 20000
150 NEXT DELAY
100 A $\$=$ INKEY $\$$
170 IF LEN $($ A $\$)=1$ THEN END
180 CLS
190 GOTO 30
It is assumed that the temperature interface is used in conjunction with the printer port analogue interface circuit mentioned previously. Lines 30 to 100 read the port and place the returned value in variable $Z$. If the interface is used with a different analogue input port, these lines must be changed to suit the particular port used.
Line 110 divides the returned value by five, and line 120 then deducts 11 from this value. The 0 to 255 range of values from the converter is thus converted to the required range of -11 to +40 . If a temperature range of -16 to +35 degrees is required, 16 must be deducted at line 120. The temperature is printed on the screen at line 130, and after a delay the program is looped back to line 30 where another reading is taken. Lines 160 and 170 enable the program to be broken out of the loop and halted by pressing any character key.
This program can also be used with the temperature interface of Fig. 2, but line 120 should be omitted. The software will then cover the same 0 to 51 degree range as the hardware.

## RING BINDERS FOR EPE

This ring binder uses a special system to allow the issues to be easily removed and reinserted without any damage. A nylon strip slips over each issue and this passes over the four rings in the binder, thus holding the magazine in place (see photo).

The binders are finished in hard wearing royal blue p.v.c. with the magazine logo in gold on the spine. They will keep your issues neat and tidy but allow you to remove them for use easily.
The price is $£ 5.95$ plus $£ 3.50$ post and packing. If you order more than one binder add $£ 1$ postage for each binder after the initial $£ 3.50$ postage charge, (for overseas readers the postage is $£ 6.00$ each to everywhere except Australia and Papua New Guinea which costs $£ 10.50$ each).
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## Constructional Project

# hich voltage CAPACITOR REFORMER 

## PAUL STENNING

## In the name of economy and antiquity, revitalise the capacitors of ancient radio sets.

WHEN not designing magazine projects, the author enjoys repairing and restoring valve radios. Often these sets will previously have been stored for a few years in somebody's loft. Electrolytic capacitors within sets of this age are prone to deterioration if they are not used for some time. This normally results in low capacitance and high leakage current. It is not unknown for one of these components to explode if a set is powered up after being left unused for years.

The easy approach could be taken and all the electrolytics replaced by modern components. However, from an antiquecollector's point of view, this would be regarded as cheating. The correct way to go about antique restoration is to use as many of the original parts as possible. Additionally, even if antiquity is not a relevant factor, high voltage electrolytics are not cheap, so restoring the capacitors rather than replacing them has obvious cost benefits.

Be warned, though, that this capacitor reformer is intended to be used in a workshop situation, by persons who know what they are doing. Those who are familiar with working on valve equipment should be used to dealing with high voltages, and should therefore able to treat this unit with due respect.
This project is definitely not suitable for beginners.

## DESIGNCONCEPT

This High Voltage Capacitor Reformer is designed for use with electrolytic capacitors rated at 350 V d.c. or greater. It is possible, though, for components rated at lower voltages $(275 \mathrm{~V}$ or greater) to be handled with the addition of an external resistor or Zener diode, as described later.

The unit applies a high d.c. voltage ( 340 V ) via a current limiting resistor to the elderly capacitor. This causes the chemical composition of the component to reform - thereby gradually restoring normal operation. The limited current prevents the component from getting too hot (minimising the risk of explosion or leakage), and allows the reforming to take place gradually. A small meter shows the actual voltage across the capacitor being

reformed, thereby indicating its state of health.
The time taken to reform a capacitor depends on its initial state. In most cases an hour or two will be sufficient, but some components will need to be left connected to the unit overnight. If a capacitor is not reformed within about ten hours, it never will be.

Obviously the unit is not guaranteed to work in every case. Of ten capacitors reformed so far using the prototype, nine were successful. The tenth remained almost short-circuit, and would probably have exploded if the radio set had been powered up. Even though the unit didn't fix the tenth capacitor, it did prevent a most horrible mess!


Fig. 1. Circuit diagram for the heart of the HV Capacitor Reformer.

## CIRCUIT <br> OPERATION

The circuit diagram for the heart of the Capacitor Reformer is shown in Fig.I. Diode Dl acts as a half-wave rectifier allowing capacitor Cl to charge to the mains peak voltage ( $240 \mathrm{~V} \times 1 \cdot 414=340 \mathrm{~V}$ d.c.) with no load present. On load, there will be some ripple present as the current drawn increases, but this seems to help the reforming operation.

Resistor R1 limits the surge current at switch-on, when Cl is in a discharged condition. A wirewound resistor is used because carbon and metal film resistors are prone to failure when subjected to surges (as the author found out the hard way!).
A discharge path for Cl and the capacitor being reformed when the unit is switched off is provided by resistor R2. It should be rated at 0.5 W or greater, and must be capable of operating at 350 V d.c.
Resistors R3 and R4 limit the current through the capacitor being reformed. Switch Sl allows them to be connected either in series or parallel, giving a resistance of either 20 kilohms or 5 kilohms. These resistors should be rated at a minimum of 4 W . They will get quite hot in the early stages of reforming when they have to drop a higher voltage.
The unit should be switched to the $20 k$ setting initially, and then switched over to $5 k$ once the voltage has risen to about 80 per cent of maximum. As the voltage across the capacitor rises, so the voltage across the resistors reduces, as does the current through them. The $5 k$ setting is intended to compensate for this. The use of a constant current circuit in this application did not seem justified.
Meter M1 indicates the voltage across the capacitor being reformed. It is a small $100 \mu \mathrm{~A}$ edge meter, resistor RS and preset VR1 being arranged to give a full scale reading at about 350 V . Alternatively, the normal workshop multimeter could be used instead of an integral meter.
The voltage across the reforming capacitor gives a fair indication of its state of health, since it will rise as the leakage current drops. The resistor values can be changed if a different integral meter is used. Suggested values for other common meter movements are given in Table 1.

| Table 1. Scaling component values for |  |  |
| :--- | :--- | :--- |
| different meters. |  |  | ( R5 $\quad$ VRI | Meter Current | 2 M 7 | 1 M |
| :--- | :--- | :--- |
| (F.S.D.) | 1 M 2 | 470 k |
| $100 \mu \mathrm{~A}$ | 20 k | 220 k |
| $200 \mu \mathrm{~A}$ or $250 \mu \mathrm{~A}$ | 100 k |  |
| $500 \mu \mathrm{~A}$ | 270 k | 1 mA |

## SAFETY <br> INTERFACE

With his own unit, the author chose not to isolate the circuit from the mains since he felt that it inherently produces dangerous high voltages. It is strongly recommended, however, that the circuit should be connected to the mains via the circuit shown in Fig. 2.
The circuit of Fig. 2 provides isolation from the mains by transformer T1. This has a $1: 1$ winding, so a 240 V a.c. input will result in a 240 V a.c. output. Since the current drawn by the reformer circuit is only small, a 25 VA transformer, delivering a maximum of about 100 mA , will probably suffice. (A small transformer may buzz


Fig. 3. Component layout and wiring diagram for the HV Capacitor Reformer complete with safety interface. The p.c.b. copper foil track master is shown full size.
when the unit is loaded, due to the half-wave rectification).

If an isolation transformer is not used, the mains neutral must go to the circuit's negative ( N ) power rail as shown on Fig. 1.

It is also strongly recommended that an RCCB (Residual Current Circuit Breaker) device is also used between the mains supply and the unit.

## CONSTRUCTION

Take great care with the construction of this unit. Mistakes on mains powered equipment can be potentially lethal.
The components of the main part of the unit are mounted on a small single-sided p.c.b. (printed circuit board), whose constructional and wiring details are shown in Fig.3. This board is available from the EPE PCB Service, code 943.

Stripboard is not a suitable substitute for the recommended p.c.b. since the gaps between the tracks on stripboard are too close to withstand high voltages.

Resistors R3 and R4 will get warm in use, and should be mounted about 4 mm above the p.c.b. Drill out a hole below preset VR1 so that it can be adjusted from below the board. Switch Sl should be raised above the board by soldering short lengths of thick tinned copper wire to its pins. Do not solder this until you have positioned the board in the case.

## BOXING UP

The prototype was fitted in a small diecast box. Such boxes are cheap and durable, making them ideal for this type of application. A plastic case should not be


Fig. 2. Safety interface circuit diagram.
used because of the heat generated by resistors R3 and R4, and because it cannot be earthed. The required dimensions of the box will depend upon the size of the transformer selected. (The photograph of the interior of the author's prototype unit excludes a transformer.)
A rectangular hole is required at one end of the box lid for the meter. This may be cut by drilling a series of holes then breaking out the centre part and filing the edges smooth. Diecast aluminum is very easy to work with. The task can be done just using a simple hand drill and a small flat file. A vice or similar can be used to hold thé case in position and make the job easier.
The p.c.b. is mounted in the box via the bush of switch SI. Once the switch is mounted, move the board by bending the switch wires so that the edges are at least 3 mm from the case. Now solder the switch wires to the board and check that this holds the board fairly firmly.
Two 4 mm sockets are used for the output connectors. These should be fitted towards the bottom of the box so that they do not foul on the meter. A hole at the other end is used for the mains input - again make sure this does not foul on anything. Use a cable clamp to prevent damage to the cable and to secure it in position. Drill a small hole near the mains input, and screw a solder tag to it for Earthing purposes.
Mark the positions of the toggle switch with " 20 k " and " 5 k " in the appropriate places. It is advisable to also mark the unit with "DANGER HIGH VOLTAGE" or something similar, in case it finds its way into the hands of someone who doesn't know what it is.
You will also need to make up two short test leads (about 300 mm long) with 4 mm plugs on one end and small insulated crocodile clips on the other end. To avoid polarity confusion, use red wire and connectors for one and black for the other.


## TESTING

Screw the case together. Set a multimeter on its lowest resistance range and check for a direct connection between the mains plug Earth pin and the case.
Now switch to the highest resistance range and measure between the earth pin of the plug and the following points: mains plug live, mains plug neutral, positive output terminal, and negative output terminal. In all cases the meter should read open circuit.
Remove the case lid again. Set the multimeter to a suitable resistance range, and connect it between the positive end of capacitor Cl and the positive output terminal. Switch Sl between its two positions to produce readings of 20 k and 5 k . Check that the case markings are the right way round!
Set VRI to the mid-way position. Set the multimeter to a high d.c. voltage range and connect it to the output terminals. Connect the unit to the mains via an RCCB as previously recommended, and switch on. The multimeter should read about 340 V d.c. (depending on the actual value of the mains voltage), and meter M1 should indicate somewhere near full scale.
Adjust VR1 to give exactly full scale on meter M1. Ideally, you should switch the unit off and wait for capacitor C1 to discharge before making any adjustments. BE EXTREMELY CAREFUL if you (inadvisably!) choose to adjust VRI with an insulated tool when the mains power supply is switched on.

Disconnect the multimeter. Switch the unit to $20 k$ and momentarily short circuit the output. The meter should read zero, and return immediately to full scale when the short circuit is removed. Switch the unit off, and the meter reading should slowly drop to zero. This should take about 15 seconds.
For the next test connect a 22 k resistor, rated at 4 W or greater, across the output. switch the unit to $20 k$ and switch on. Assuming the meter is scaled zero to ten, it should read about four or five. Switch to $5 k$ and the reading should rise to about eight.
If the unit has passed the above tests, then it is working satisfactorily. This level of testing may seem excessive for a simple circuit, but with high voltages it's better to be safe than sorry.

## INUSE

Regardless of what the previous owner of an old set may have told you about its condition, ideally its capacitors should be removed and tested one at a time.

Make sure the capacitor is rated at 350 V or higher. Connect the unit to the capacitor, making sure you have the polarity correct. If there is more than one capacitor in a single can, each should be tested individually. You will need to use a capacitor mounting clip, a metal Terry clip, Jubilee clip or something similar, to connect the unit to the case of the capacitor if this is the only negative terminal. Place the capacitor on an insulated surface, and do not allow it to come into contact with anything, including the case of the Reformer.
Set switch S1 to $20 k$ and switch on the unit. DO NOT TOUCH THE CAPACITOR OR OUTPUT LEADS WHEN THE UNIT IS SWITCHED ON. Observe the reading on the unit's meter. If the capacitor is good, the reading will steadily climb to full scale within about 30 seconds or so.
If the capacitor is not so healthy the meter will show a lower reading and climb very slowly. Check the reading about every 15 minutes. It should be a bit higher each time you look. If the reading is below about four, SWITCH OFF and feel the temperature of the capacitor. If it is warm, leave the unit switched off to let the capacitor cool down before continuing.
Once the reading has reached about seven or eight, switch $\mathrm{S} \mid$ to $5 k$. The reading
will probably go up a bit immediately, and should then continue to rise slowly. With luck the unit should read full scale after a couple of hours, but leave it for up to about ten hours before giving up.

If the reading rises to about nine or higher and then stops, the capacitor may still be usable as long as it is not the main h.t. smoothing component (connected directly to the cathode of the rectifier valve). In this case, re-install the capacitor in its original piece of equipment, and feel its temperature after the equipment has been powered up for about 10 or 15 minutes. If it is significantly warmer than the chassis, it should not be used further.

When the capacitor has been reformed, switch the unit off at the mains and wait for the capacitor to discharge and the meter to read zero. This could take a minute or more, depending on the value of the capacitor.

## ALTERNATIVE TECHNIQUES

To reform a 275 V capacitor, connect a 22 k 4 W resistor in parallel with it. With switch SI on the $20 k$ setting, the meter will only read up to four or five. When this value is reached, switch to the $5 k$ setting. The maximum reading will now be eight. If a more elegant method is preferred, make up a chained series of Zener diodes that total about 260 V to 270 V (e.g. a 120 V Zener in series with a 150 V one). Connect this in place of the resistor.

A quick check can be made on the main h.t. capacitors in a set without going through the hassle of removing them first. With the set disconnected from the mains, connect the Reformer unit between the h.t. rail (cathode of rectifier valve) and chassis, switch SI to $20 k$ and switch on. If the circuit diagram for the set is available, check for potential divider circuits across the supply rails - these will affect the readings and may be worth disconnecting.
Switch S1 to the $5 k$ setting once the reading is above about eight. If the unit's meter reads above nine on the $5 k$ setting within about ten minutes, it can be assumed that the capacitors are reasonably OK. If not, they will have to be removed and reformed individually.

If you have a dud capacitor that cannot be reformed, don't throw it away. The tidy (and "antique value") solution is to fit it back onto the chassis so that it looks

right, but don't connect it. Fit a modern electrolytic tidily below the chassis, and no-one will ever know! If you're really enthusiastic you could dig out the innards of the old capacitor and fit the modern replacement inside the can - if you have this much patience!

## UNKNOWN SET TESTS

When initially testing an unknown receiver, it is often advised that the set should be powered from a lower than normal mains voltage via a variac (variable auto-transformer). This is intended to give a lower voltage h.t. supply which is also at a higher impedance due to the valve heaters being underun. This will also show up leaky capacitors and many other problems without causing additional damage.
For those who do not have access to a variac (they are fairly expensive), the HV Capacitor Reformer will enable similar tests to be carried out. The unit is simply connected across the main h.t. smoothing capacitor (with the receiver disconnected from the mains) as described previously
Any leaky low-value non-polarised decoupling capacitors (and other capacitors which have a high voltage across them in use) will show up after a few minutes by the wax bubbling at one end. If any resistors are getting warm, the reason should be investigated. In the majority of receivers there are no potential dividers or other resistive circuits across the h.t. supply, so the h.t. rail should reach about 350 V . If anything is dragging this down, it should be investigated (remember that at this time valves have no power across their heaters and therefore will not be drawing current from the h.t. supply).


Measure the voltage at the grid of the output valve, relative to the chassis. If this is at all positive, the grid coupling capacitor is leaky and should be replaced. Also check the voltage at the anode of the output valve. If this is not at the full h.t. level (about 350 V ) the output transformer primary may be open circuit. If you have the service sheet for the receiver you can carry out a number of similar checks all before the mains supply has been applied.

## SAFETY ADVICE

To reiterate and expand on the warnings given earlier:
This unit produces potentially lethal voltages. Even though a mains isolating transformer is recommended, the unit should still be regarded as being connected directly to the a.c. mains. Do not touch the output leads or anything connected to them
while the unit is switched on. Wait for the meter to read zero after switching off. Keep this unit out of the reach of children, pets and anyone who does not appreciate the danger.

When working on live equipment, always keep one hand in your pocket or behind your back - this will reduce the chances of current passing through your heart if you accidentally touch something electrically live

The use of an RCCB (Residual Current Circuit Breaker) should be regarded as a "must", but is no substitule for safe working practices. A large capacitor can give a fatal shock without the circuit breaker responding.

Never work on live equipment alone always make sure there is someone present who knows how to administer the appropriate first aid.

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LAST month we looked at comparisions between valve and solid-state amplifiers and introduced circuits which combined both technologies. We also covered the p.c.b. construction of the single i.c. phase-splitter stage of the amplifier.
This month we conclude with the final wiring, testing and setting-up. We also offer some circuit ideas for possible further development.

## HEATER"WIRING

With all valve circuits wired in the traditional manner, the heater wiring is put down first so that it can be laid close to the chassis. It is also twisted and kept clear of the grid pins and by using these techniques hum pick-up from the heater a.c. power is minimised.
The heater, power wiring and other wiring that needs to be completed before the tag strips are dropped into place, on the underside of the chassis, is shown in Fig. 11.

The phase-splitter (last month) printed circuit board should also be mounted in position at this intermediate stage.

## TAG STRIPS

There are two tag strip assemblies in the design which can be conveniently constructed outside of the chassis before they are installed. Fig. 12 shows how the two tag strips should be cut from standard lengths before use. Note that some of the "earth" tags on the driver strip have been cut to increase the number of "floating" tags.
The component layout on the tag strip for the Driver stage is shown in Fig. 13. Note how the grid stopper resistors are positioned so as to slide straight through the grid tags on the valveholders.
Another point to watch is the possibility. of shorts and these are prevented by use of silicone sleeving over component leads. Also, if uninsulated metal-cased capacitors are used for C15 and C17, mount them so


EE65820

Fig. 14. Cathode tag strip assembly and wiring.
that their case is connected to the grids otherwise they will be floating at 200 V . Before bolting and soidering the tag strip into place make sure the output transformer wiring is in place.

The second, smailer, tag strip is for the cathode components for the power valves. The anti-surge resistor R39 is also mounted on the same tag strip and the whole assembly is shown in Fig. 14.

It is essential to use a hot thermostatically controlled soldering iron such as a Weller W60 for traditional hard wiring. That old 15 W iron will not do!
The final complete interwiring of the chassis is shown in Fig. 15. Note that the connections to the p.c.b. are made by Molex connectors. These need a special crimp tool to do the job properly. Fig. 16 shows how to complete a Molex connector.


Fig. 13. Driver stage tag strip assembly.


Fig. 11. First stage of the chassis "hard wiring", prior to dropping the tag strips in place. The heater wiring should be completed first and be kept away from the valve grid pins.
ORIVER STAGE TAG STRIP
Fig. 12. Preparation of the two tag strips from
standard lengths.


Fig. 15. Final complete chassis interwiring. Connections to the Phase-splitter p.c.b: are made using p.c.b. header connectors.


Layout of components on the topside of the chassis.

## TESTING

This amplifier is quite difficult to test with the normal test gear set-up of signal generator and oscilloscope because of the balanced inputs and outputs. The balanced input is not a problem since it can easily be converted to unbalanced by the simple expedient of grounding one of the input terminals.

Putting a 'scope on the output is problematic because if either terminal of the floating output is grounded the feedback is unbalanced and the amp will operate incorrectly giving a greatly reduced output swing. The unsafe method of getting round this is to remove the mains earth on the 'scope. The safer recommended method is to use a differential probe or a balancing transformer.
As with all valve power-amps it is not happy without a load, since there may be damaging flashovers in the output valves due to high back e.m.f.s being generated by the output transformer.
Valve amps are generally much more tolerant of wiring errors than solid-state amps, because there are no ready paths for chains of destruction, as there are with direct-coupled semiconductors.

However, it is logical to test the unit in a sensible sequence rather than just firing it up. The first stage is to check the mains and heater wiring by powering-up with the h.t. fuse FS2 removed. All the valves should light up. Listen out for unusual noises such as stressed power transformer hum, but do not be alarmed by the tinkling noises valves normally make as they warm up.
The next stage is to power-up with the h.t. fuse in place, with the driver valve V1 removed (this reduces the chance of oscillation). An 8 ohm 25 W load resistor should be connected at this stage. If the h.t. fuse does not blow, measure the h.t. (which should be around 430 V ) and the voltage across the cathode resistors which should be 29 V to 34 V .

The next stage is to check the op.amp power supply voltage at pin 8 of ICl which should be 32 V to 36 V . The offset voltage at the outputs of ICl should be measured and should be half the rail voltage at around 16.5 V .

If all is well, plug in the driver valve V1. If the amplifier oscillates it will be generally
be audible as a high pitched buzz from the output transformer. The normal cause of oscillation is the feedback being the wrong phase. If this is the case it can be cured by reversing the feedback Molex connector on the Phase-splitter board. Finally check the voltage on the driver valve anodes (pins 1 and 6) which should be 205 V
A final check should be made with a 1 kHz sine wave applied to the input looking for distortion. The level should be increased to check for symmetrical clean clipping. The amplifier should be able to swing 40 V peak-to-peak into the 8 ohm load resistor just before clipping. This equates to 24 W r.m.s. ( 20 V peak $\times 0.707=$ 14 V r.m.s. $P=V^{2} / R=196 / 8=24.5 \mathrm{~W}$.

## PUSH-PULL BALANCE

Here is an old dodge to check that each half of the amplifier is operating with equal gain so that the push-pull operation is fully balanced. Simply wire a pair of matched 100 kilohms, one per cent, resistors across the anodes of the output valves as shown in Fig. 17 and hook up to the 'scope.


Fig. 17. Using two close tolerance, 100 kilohm resistors to check "push-pull" balance.


Layout of components on the completed Phase-splitter p.c.b. (last month). Notice the ceramic bead spacers on the "dropper" resistors (to help keep heat away from the board), and the p.c.b. header pin connectors.

If the amp is in balance the two signals should cancel out. It is worth trying this at a few different levels and frequencies.
If there is an imbalance in level it can be corrected by tweaking one of the anode resistors in the driver stage. Imbalances at the high frequency end are best corrected by adjusting the feedback capacitors in the phase-splitter.

## IN USE

Since the amplifiers are monoblocks and have a low impedance balanced input, they
can be placed near the loudspeakers, minimising the need for expensive loudspeaker cables.
With a 10 k input impedance, the valve amplifier is only suitable for use with preamps that can drive low impedance loads. Usually the amp will be used with a passive pre-amp of the type shown in Fig. 18 with a CD player.
The output is only 24 W but because of the soft clipping it will sound as loud as a 40 W solid-state amp. To get high levels it is necessary to use high sensitivity loudspeakers.

## SAFETYWARNING

Not only is there mains in this amplifier, there is also 450 V h.t. which is even more dangerous because it is d.c., which means that muscles may freeze. Such shocks across the heart may result in ventricular fibrillation or breathing paralysis leading to death within a few minutes without resuscitation.
Always use well insulated probes when testing and always check the h.t. capacitors for residual charge when working on the unit
if switched off. To prevent the across the chest shocks, work with "one hand in the pocket" if possible.
It should be pointed out that the l.e.d. D6 is extinguished when the h.t. fuse has blown, this means that the bleeding function is also disabled and the capacitors could still be holding a lethal charge. The same applies if the amplifier is operated with the Phasesplitter board removed.
 speakers set at reasonable domestic levels. One way of increasing the maximum level and retain the quality, is to use valve driven LS3/5a speakers along with an active crossover driven sub-woofer powered by a solid-state amp
Valve amps can get quite hot so it is essential the units get plenty of ventilation. It is not a good idea to put them in an enclosed box - use a perforated steel cage if they need to be cased.

Here are some suggested possible circuit improvements that should be of interest to experimenters.

## Standby Switch

If the amp is to be left running for a long time, such as in a studio, it is worth putting a switch in the h.t. line. This enables the heaters to be left running without the h.t. When the amp is needed it can be switched on instantly with the Standby switch.

A Standby switch also prolongs the life of the valves since it is the electron emission that fails long before the heaters. Cathode stripping is also eliminated if the standby switch is turned on after the valves have warmed up.


The compact chassis underside component layout and interwiring of the completed EPE HiFi Valve Amplifier. The twisted heater winding leads run along the bottom and the screened signal lead across the top (as seen).

## Output

## Trensformers

The output transformers are the heart of any valve power-amplifier and they basically determine the low frequency performance of the amplifier. The recommended transformers are perfectly functional and at around $£ 26$ are one of the cheapest. It is possible to get better transformers which give more bass power below 40 Hz from companies like Sowter's and Audio Note, but expect to pay at least double.

The reason for the high cost of valve output transformers is that the windings are much more complex than a power transformer. They have to be, to minimise distributed capacitance and leakage inductance which are the main factors in obtaining a flat frequency response.
The winding configuration used in the specified transformer is shown in Fig. 19. This configuration is called a five-section winding, where the primary is divided into three layers and the secondary into two.
, Cheap output transformers use a threesection winding which generally results in a resonance in the 25 kHz area, whereas the one above has a damped resonance of around 80 kHz , well out of the audio band. Some very expensive types use up to ten sections, but after five sections the onset of diminishing returns is very rapid.

## Choke Smoothing

To reduce the hum further, a choke filter could be tried since a 10 Henry valve smoothing choke is now available from Maplin (order code ST28F). It is only officially rated at 100 mA but this is not a thermal rating and on this basis, the choke can handle the full 140 mA current of the valve amplifier.
The problem is that the core saturates reducing the inductance to some extent. The remaining inductance still seems to offer much improved smoothing however. The circuit for installing the choke is shown in Fig. 20.

## Cathode Current Regulation

The anode currents of both output valves must be equal to ensure complete cancellation of hum and residual magnetic field in the output transformer. Of course, the signal voltages do not cancel since they are out of phase, while the steady-state anode current does, because it flows through the valves in the same direction
If the currents are unequal the result is 100 Hz hum. This can be trimmed out by tweaking the cathode resistors, although there should not normally be a problem since valve tolerances are generally very good.


Fig. 19. Five-section output transformer construction and d.c. resistances.


Fig. 21. Constant current cathode biasing.


Fig. 24. Heater derived dual-rail op.amp power supply.

## Solid-state Ripple Suppression

To obtain the lowest supply ripple, a solid-state regulator could be used. However, semiconductors are not very reliable in such high voltage conditions and the circuit given in Fig. 22 is unlikely to be short circuit proof. However a regulated h.t. rail will make an improvement for valve pre-amps.

## Heater-derived Op.amp P.S.L.

The simple Zener supply in the amplifier is only suitable for powering a couple of op.amps in single rail mode. If extra power
is needed, for a preamplifier for example, it would be better to derive it from the heater supply.

A voltage tripler circuit such as that shown in Fig. 23 which provides dual rails, could be used.

## Cathode-derived Op.amp PSU

If it is desired to remove the dissipation of the dropper resistors it should be possible to derive op.amp power from the cathode resistors as shown in Fig. 24. The maximum voltage available is limited but there is sufficient gain in the driver stage to make up for any lost headroom.

Fig. 25. Cathode derived op. amp power supply

27 V TO PIN 8
IC



## PLAMEN PETKOV

## Ancient and modern rectifying techniques are combined to facilitate multi-voltage supply line derivation.

THE CLASSICAL bridge rectifier circuit, as shown in Fig. 1, is one of the most widely used types of a.c. to d.c. rectifying circuit. Conventionally, it is powered from a single secondary winding of a mains transformer.

When additional voltage supply lines are required from the same transformer, this secondary winding is either centre tapped, or additional secondary windings are employed, each having its own rectifying circuit.


Fig. 1. Classical bridge rectifier circuit.

## COSTFACTORS

In many commercial manufacturing situations, it may be cost-effective to have transformers specially wound to meet the voltage requirements of new equipment designs. In other cases, though, cost demands may make it preferable to use an off-the-shelf transformer rather than a custom designed one. Regrettably, however, the available transformers may not have the number of windings needed to supply the required variety of voltage levels.

Also, the need sometimes arises for additional voltage levels to be supplied to existing equipment if it is being upgraded. For example, the addition of op.amps, where previously none had been used, may require a negative voltage line to be added. It could even be the case that voltages higher than those already existing might need to be added.

Rather than use an additional trans former to supply the extra voltage levels, it is possible in a variety of instances to derive the voltages from an existing secondary winding of a transformer, by using conventional voltage multiplying, inverting or regulating circuits.

## BRIDGE PROBLEMS

However, not all situations can be catered for in this manner because of an inherent problem with bridge rectifier circuits, caused by their lack of a common connection between the input and the output.

Although it may be tempting to try using an additional rectifying circuit connected between one of the a.c. leads and the ground line, for example the voltage inverter/doubler circuit shown in Fig. 2a, the attempt will be likely to fail due to the uni-directional conductivity of the voltage source. Unfortunately, the input connections to this circuit require both charge and discharge current paths.

The reason for this is that the transformer secondary winding, grounded via the diodes of the bridge rectifier, provides only a charge path. A discharge path does not exist, as will be seen in the equivalent circuit in Fig. 2b.

In other words, the problem is that the diodes conduct only in one direction, which
is, of course, an essential feature for the correct operation of the classical bridge rectifier circuit.

## SYNCHRONOUS RECTIFIER

What is needed in this situation is a switching component which is capable of conducting during the appropriate halfwave period of the a.c. supply, irrespective of its polarity.

Historically, such a switching circuit was invented long before valves or semiconductor diodes became available. It was known as the synchronous rectifier and was based on a polarised relay circuit, schematically shown in Fig. 2c.

It is possible to upgrade this concept for modern applications by using semiconduc tor devices. Indeed, the functionally equivalent circuit shown in Fig. 3a offers vast opportunities for multi-voltage supply requirements.
The idea of the circuit illustrated in Fig. 3 a is to complement the "grounding diodes" of the bridge rectifier with bypassing transistors, switched on simultaneously with the corresponding diode during the appropriate a.c. half wave.

The operation of this modified bridge rectifier is similar to the historical synchronous rectifier configuration due to the fact that the respective transistors are on or off simultaneously with their diodes. The only difference from the historical circuit is the ability of this modern equivalent to provide a discharge path through transistors in addition to a charge path through diodes.

It should be noted that the transistors are protected from "wrong polarity" by the diodes, which inhibit the "reverse voltage".


Fig. 2(a) Voltage inverter, (b) and its equivalent circuit; (c) relay-driven synchronous rectifier.


Fig. 3(a) Modified bridge rectifier circuit and (b) its symbol.


Fig. 4. Bipolar rectifier, full-wave addition indicated by dotted line.
series capacitors must be sufficiently great to provide current charge transfer to the output, in other words, to pass the amount of a.c. current required. The value of the parallel (output) capacitors should be chosen to provide acceptable ripple levels. This proviso applies to all the nominal voltage relationships quoted in the ensuing circuit diagrams.

## SCALING VOLTAGES

The circuits of Fig. 5 and Fig. 6 demonstrate an additional refinement. respectively dividing the nominal output negative voltage by two and by three.
A negative voltage which is nominally half that of the equivalent positive voltage can be produced by the circuit shown in 'Fig. 5 . That is, if " +V " $=+12 \mathrm{~V}$ then $\cdots-\mathrm{V} / 2^{"}=-6 \mathrm{~V}$.
Similarly, a negative voltage nominally one third that of the equivalent positive voltage çan be produced by the circuit shown in Fig. 6. Thus, if " +V " $=+12 \mathrm{~V}$ then " $-\mathrm{V} / 3$ " $=-4 \mathrm{~V}$. Obviously, further voltage division in a similar fashion to less than one third is theoretically possible, but is rarely practical.
The idea of these circuits, which the author calls "scaling inverting rectifiers", is to alternately charge a number of serially connected capacitors, and to discharge them to the load in parallel connection. Accordingly, each capacitor is "equipped" with a charge diode and

The inclusion of the resistors ensures that the transistors are controlled by "safe" voltages and currents.

For the sake of illustrative convenience in later circuit diagrams, the circuit of Fig.3a has been given the schematic symbol shown in Fig.3b. The letter "E" denotes the common emitter ( 0 V ) point.

## CIRCUIT EXAMPLES

The circuits shown in Fig. 4 to Fig. 9 illustrate how the circuit of Fig. 3a can be used in conjunction with other rectifying circuits to produce a variety of "integer" and "non-integer" conversion ratios of the output voltage levels, both positive and negative, with respect to the input voltage level.
The circuit diagram in Fig. 4, for example, illustrates how an additional negative voltage can be derived from a transformer secondary winding which is already engaged in bridge-rectifying a positive voltage. As will be seen in the upper section of the circuit diagram, the positive voltage is produced by a sircuit identical to that shown in Fig. 3a.

The circuit configured around diodes D5 and D6, and capacitors C2 and C3, forms a standard half-wave voltage-inverting rectifier. Full-wave voltage-inverting rectification is a chieved when the circuit configured around capacitor C4 and diodes D7 and D8 is included as well (shown as dotted line. connections).
Nominally, the negative voltage is equal to the positive voltage. For example, if " $+V$ " equals +12 V , then " -V " will be -12 V . Note, though, that the exact voltage relationship may be different due to component tolerances and the actual currents drawn. In this context, note that there is a voltage drop of about 0.7 V across the series diodes, and that the value of the



Fig. 7. This circuit delivers $+V,+3 / 2 V$ and $-V$.
a pair of discharge diodes. The first capacitor, from the input, has only one discharge diode to the output.
Referring to Fig. 5, these capacitors (C2 and C3) are charged during the positive half-wave along the path: lower a.c. connection, capacitor C2, diode D6, capacitor C3, diode D8, OV (ground), diode D1, upper a.c. connection. Given that capacitors C2 and C3 are of equal capacitance, they charge to approximately half of the input voltage level.
During the "zero" half-wave, capacitors C2 and C3 are connected in parallel to the output: their positively charged leads (C3 via diode D5, and C2 directly) through transistor TR2 to 0 V (ground), and their negative leads to the output via diodes D7 and D9, respectively.
The discharge paths for capacitors C2 and C3 start from their positive leads, either directly, or via diode D5 and transistor TR2. and then 0 V (ground) through the load and capacitor C4 to the output, and then finally to their negative leads, via diodes D7 and D9 respectively. In this stage, charge transfer takes place to output capacitor C4.
The circuit of Fig. 6. operates in a similar way, the only difference being that three, rather than two, capacitors share the input voltage, so dividing the voltage accordingly.

The "scaled" voltages can be made positive and added to the main positive voltage in order to produce "non-integer" multiplying. For example, the circuit in Fig. 7 illustrates a " $+3 / 2 \mathrm{~V}$ " multiplier in addition to " $+V$ " and " $-V$ " supply lines.

Indeed, there is practically no limit to the number of rectifying circuits that can be driven in association with the modified bridge circuit of Fig. 3a. A further example is shown in Fig. 8. This circuit illustrates how full-wave " $+2 \mathrm{~V},+\mathrm{V},-\mathrm{V}$ and $-\mathrm{V} / 2$ " voltage supply lines can be derived from a single winding of a transformer.
It should be noted that in Fig. 8 only one of the bridge rectifiers is the modified (Fig. 3a) type. The others are auxiliary and associated with their respective voltages.

## DESIGN CONSIDEAATIONS

It should be noted that general considerations in respect of half-wave or full wave rectifiers should be applied as usual. The type of rectifier configuration chosen affects the currents through the transistors, diodes and capacitance values in the normal way. If only a half-wave rectifier circuit is required, the unrequired transistor and its associated resistor may be omitted.


Fig. 8. Four voltage levels are output from this circuit: $+V,+2 V,-V$ and $-V / 2$.

## CAUTION

Readers will undoubtedly wish to bread-board and experiment with these enhanced rectifiers It must be stressed, though that mains voltages will be present at the transformer and that the utmost care must be exercised at all times. Experimentation with the circuits is not recommended for electronics beginners.

When choosing which component types and values to use, the following parameters should be considered:
Transistor Maximum Collector Current: average current to match the output current; peak current at least three times higher to take into account the capacitive load.
Transistor Maximum Collector Voltage: to match the peak value of the input voltage ( 1.41 times nominal input voltage), plus some safety margin, i.e. at least twice the input voltage.

Transistor Base Resistance: less than Vin $\times \mathrm{h}_{\mathrm{f}} / \mathrm{I}_{\text {out }}$, where $\mathrm{V}_{\mathrm{in}}$ is the input voltage, $h_{\mathrm{fe}}$ is the transistor's minimal current gain (common emitter), and $\mathrm{I}_{\text {out }}$ is the output current. A resistance value lower than this is required to provide saturation when in the on state. A resistance value of about one fifth of that calculated would be a good choice. Too low a value, though, may jeopardise the self protection against short circuits, resulting from the current limitation of the transistor's base (and therefore collector current).

Output Filter Capacitors: these are required to reduce ripple voltages, consequently the optimum capacitance value is both load current and ripple voltage dependent. A rough rule is $2 \mu \mathrm{~F} / \mathrm{mA}$.

Charge Pump Capacitors: these transfer the charge to the output. Insufficient capacitance leads to a voltage drop when the load increases. A general rule is again $2 \mu \mathrm{~F} / \mathrm{mA}$. When dividing circuits are used, the capacitance can be reduced proportionally to the division ratio.

## POTENTIAL BENEFITS

The example circuits shown in this article actually deal with two independent matters, the modified bridge rectifier circuit, and various diode/capacitor rectifier circuits. There are instances, of course, where the latter may be used independently in other circuits without the modified bridge circuit.

Any one or more of the circuits could be of benefit where several voltage levels need to be supplied from a single transformer winding, provided that the output current requirements are not too great to be readily supplied via capacitive coupling.
It is acknowledged, though, that in some instances conventional voltage derivation techniques may provide better power line stabilisation. However, when next considering how best to derive several different supply line voltages from a single transformer winding, give thought to the versatility offered by the examples shown here.


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## SATELLITES LOST

Two amateur radio satellites were lost when their launch vehicle, a Russian START rocket, exploded on March 28. Two Russian satellites (for studying meteorite particles) were also lost.
One of the amateur satellites was the GURWIN-1 Techsat, built at the Tech-nion-Israel Institute of Technology in Haifa. The other was the UNAMSAT, assembled by students at the Universidad Nacional Autonoma de Mexico (UNAM) in Mexico City. Both were designed for packet radio repeater use and UNAMSAT also carried a unique "meteor" radar" experiment.
The START rocket is based on the SS-25 inter-continental balistic missile and the launch was to have. demonstrated that refurbished military rockets could be used for civilian purposes.

In November 1993, the first test launch of a converted SS- 25 was successful, but with a lighter load. As a result, radio amateurs, particularly in Europe, had hoped that the Russian rockets could provide an inexpensive way to launch amateur radio satellites.
The loss is a very great disappointment, not only to those who worked so hard to design and construct the spacecraft but to all radio amateurs around the world who participate in satellite operation.
The Israelis will, apparently, rebuild and could have another unit ready in a matter of months, but it is not known if the Mexicans are able to do this. There was no insurance. (Information from W5Y/ Report).

## FIRST RADIO AMATEUR

The international Amateur Radio Union has designated the third Saturday in September as World Amateur Radio Day. This, it says, will be an opportunity to focus public attention on the benefits derived from Amateur Radio; and the theme for 1995 will be " 100 Years of Radio"
This year is of course being celebrated as the 100th anniversary of the invention of wireless by Guglielmo Marconi in 1895. Marconi's name has been so wellknown since that time that it is hard to realise how ill-equipped he was when he began the experiments which gave him his place in history. In later years he was described as "the first radio amateur".
He was not particularly well educated, although an aptitude for physics was encouraged by a neighbour, Prof. Augusto Righi, who arranged library facilities for him at Bologna University. He obtained no qualifications, and spent much of his time at home undertaking minor scientific experiments.
In 1894, he read a commemorative article by Righi about Heinrich Hertz'
work with radio waves. Fired with enthusiasm he repeated Hertz' experiments, quite indifferent to the fact that previously only experienced scientists had sought to repeat, and improve on, the great man's work.
Hertz had found that waves radiated from an electric spark induced another, feebler, spark in a receiving circuit a few metres away. Marconi experimented with a coherer (detector), discovered by Edouard Branly and aiready used by others, including Oliver Lodge, in similar experiments. By trial and error Marconi produced an improved version, enabling his signals to be detected outside the house.

In 1895, he connected sheet iron to each side of his transmitter spark gap to obtain a longer wavelength. By chance he held one sheet in the air whilst the other lay on the ground. This primitive antenna radiated a much stronger signal. He modified the receiver in the same way and increased the range to about a kitiometre.

## FIRST INTERNATIONAL CONTACT

The receiver was carried further into the surrounding countryside by Marconi's brother, helped by his father's employees. A handkerchief waved on a stick acknowledged reception of a signal, and a rifle shot told Marconi that his waves had successfully reached over two kilometres, with a hill between transmitter and receiver
He now tried to interest the Italian authorities in his work, but without success. In February 1896 he went to London where, on June 2, he applied for the first ever wireless patent. He was introduced to William Preece. Engineer-in-Chief of the Post Office who, impressed by Marconi's equipment, arranged demonstrations before Post Office and military observers.
At a püblic demonstration, Preece lectured whilst Marconi, moving among the audience, carried a receiver which rang a bell every time Preece pressed a switch on the platform. Marconi, the amateur experimenter from Italy, was now a 22 yearold celebrity.

Only eighteen months after leaving home, he returned by official invitation and was presented to the King and Queen of Italy. In a demonstration for the Italian navy he established contact with a ship below the horizon.
On 27 March 1899 he achieved the first international radio contact, between England and France, a distance of some 50 km . Later that year the range was increased to about 130 km .
The earliest transmitters were untuned and during demonstrations for the US navy Marconi was unable to communicate between two warships whilst a shore-based station was operating. In

1901, however, he patented a system enabling a transmitter to radiate on a particular radio frequency and a receiver to be tuned to that frequency.
In that year he carried out his famous transatlantic tests. High-powered spark transmitters were installed at Poldhu in Cornwall. After various mishaps, with the vast antennas 'specially erected for the purpose blown down by gales, oneway contact was finally established from Cornwall to Newfoundland, where Marconi used a 183 metres long kite antenna coupled to an untuned receiver.

## TRANSATLANTIC SUCCESS

Poldhu sent the Morse letter " S " for three hours a day. At 12.30 on December 12, Marconi passed the earphone to his assistant, asking, "Can you hear anything Mr Kemp?'" The prearranged signal was there, and was heard three times that day.

A company was formed in 1900 to provide communications with ships at sea carrying Marconi apparatus. Seventy ships were equipped by the end of 1902, and there were twenty-five shore stations, including several in America
He died on July 20, 1937. The next day radio transmitters rourd the world shut down for two minutes in tribute to him. For that brief period the ether was as quiet as it had been in 1894

From modest beginnings had grown a great commercial empire but Marconi was always aware of the value of the amateur approach. In 1919, when there was pressure on the British government to re-introduce amateur radio after WW1, he wrote:
'In my opinion it would be a mistake to introduce legislation to prevent amateurs experimenting with wireless telegraphy. Had it not been for amateurs, wireless telegraphy as a great world-fact might not have existed at all. A great deal of the development and progress of wireless telegraphy is due to the efforts of amateurs.

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