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#### CORRECTIONS

No. 7, page 341, col. 2: Equation (2) should be " $B_1 = \dots\dots\dots$ "

page 350, col. 1, 2nd para., 2nd line should read "medium spaced  $\dots\dots\dots$ "





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## Microprocessor controls for limited-function robots

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G. P. C. CHARLES and R. H. WESTON (Loughborough University of  
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*Savings can be achieved in the application of special-purpose industrial robots if these  
are based on a common design which minimizes development time. As part of this  
programme, a microprocessor-based controller with modular hardware and software  
has been developed which has the flexibility for use with a wide range of devices but  
can be readily adapted for a particular role.*

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units for operation in the 18 to 170 GHz frequency range. These include switches and  
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end using these units is shown.*

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